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# COMMENTATIONES MATHEMATICAE UNVERSITATIS CAROLINAE 

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## ON AFFINE KAC-MOODY LIE ALGEBRAS Thomas N. VOUGIOUKLIS

Abstract: In this paper we deal with affine Kac-Moody Lie algebras of type $D_{n}^{(1)}, n \geq 4$. We give a method of computation of the eigenvalues needed for the realization of the basic representation that appeared in [3].<br>Key wordg: Affine Kac-Moody Lie algebras, graded Lie algebras.<br>Classification: 17B65, 17B70

1. Introduction. In the paper [3] there is given a construction of the basic representation of Euclidean algebras. This is a generalization of the construotion in [5]. In the main result of the paper [3] Theorem 4.1 one needs some constants $\lambda_{i j}$. The aim of this paper is to give a method to compute those constants for the affine Kac-Moody Lie algebras $D_{n}^{(1)}, n \geq 4$. Also we give an appropriate gradation of Lie algebras of type $D_{n}$.
2. Fix $n \geq 4$. Let $\left\{E_{i j}\right\}_{i, j=1, \ldots, 2 n}$ be the standard basis of the space of $2 n \times 2 n$ complex matrices, so that the matrix $E_{i j}$ is 1 in the ij-entry and 0 in all the other entries.

We focus our attention on the basic representation of the affine Kac-Moody Lie algebra $g(A)$ of type $D_{n}^{(1)}(n \geq 4)$, see KAC [2] and MOODY [6]. In this case we have
(1) $\quad g=o(2 n, c), \quad(x \mid y)=t r x y$.

So from the classical Lie algebras with symmetric Cartan matrices, see [2], we consider the Lie algebras of type $D_{n}(n \geq 4)$. We know that $g^{f}$ consists of all $2 n \times 2 n$ complex matrices $x$ such that $x: J+J^{t} \cdot x=0 \quad$ where

$$
J=\left(\begin{array}{llll}
0 & & 1 \\
& & 1 & \\
1 & \cdot & & 0
\end{array}\right) \quad, \quad \operatorname{see}[1]
$$

We take in $g$ the elements


It is easy to see that the above elements satisfy the following relations

$$
\left.\begin{array}{ll}
{\left[e_{i}, f_{j}\right]=\delta_{i j} h_{i}} & {\left[h_{i}, h_{j}\right]=0} \\
{\left[h_{i}, e_{j}\right]=a_{i j} e_{j}} & {\left[h_{i}, f_{j}\right]=-a_{i j} f_{j}}
\end{array}\right\}(i, j=0, \ldots, n)
$$

where the $(n+1) \times(n+1)$ matrix

be the generalized Cartan matrix corresponding to the Dynkin diagram

of $D_{n}^{(1)}$, see [2].
We know [2], that a Lie algebra $g$ is said to be a graded modh Lie algebra if it can be written in the form
with the property
(3)

$$
\left[g_{i}, g_{j}\right] \subset g_{(i+j) \text { modh }} .
$$

From now on for $i \in \mathbb{Z}$ we set $\mathscr{g}_{i+h} \mathbb{Z}=\mathscr{g}_{i}$ so we have

An element $x$ of $g_{i}$ is said to be of degree $i$.
In our case we take the Coxeter number [3] for $g$ as $h$ i.e. $h=2(n-1)$.

Let's denote by $\underline{x}$ the number defined in the following way

$$
\left.\begin{array}{lll}
\underline{x}=x & \therefore \text { ff } & x \leq n \\
\underline{x}=x-1 & \text { if } & x>n
\end{array}\right\} \quad x \in \mathbb{Z}
$$

PROPOSITION 1
A Lie algebra $g$ of type $D_{n}$ is a graded mod where the 1-principal $z / h z$-gradation of $g$ is given by setting
(4) $\quad \operatorname{deg} E_{i j}=(i-\underline{i}) \operatorname{modh}$

## PROOF

It is a simple calculation, observing that all the elements $e_{o}, e_{1}, \ldots, e_{n}$ have degrees 1.

So the elements $e_{i}, f_{i}, h_{i}, i=0,1, \ldots, n$, defined by (2), are the Chevalley generators for a complex Lie algebra $\mathbb{G}^{-( }(A)$, which we quotient by its largest $\mathbf{z}^{\mathrm{n}+1}$-graded ideal intersecting trivially the span of $h_{0}, \ldots, h_{n}$ and we take the Kac-Moody Lie algebra $g^{(A)}$ of type $D_{n}^{(1)}(n \geq 4)$. The images of $e_{i}, f_{i}, h_{i}$ $(i=0,1, \ldots, n)$ in $g(A)$ will be denoted by the same letters.

## 3. We set

$$
e=\sum_{i=0}^{n} e_{i}
$$

This is a 1-cyclic element of $g$ studied by KOSTANT in [4]. Note that [3] a cyclic element is conjugate to a multiple of any other cyclic element by an automorphism of $g(A)$ defined by

$$
e_{i} \longmapsto \beta_{i} e_{i}, f_{i} \longmapsto \beta_{i}^{-1} f_{i}, i=0,1, \ldots, n
$$

Although there is not known any natural normalization of the cyclic element in general, we give the following normalization . in case $D_{n}^{(1)}$ :
Note that

$$
\left(\beta_{i} e_{i}\right)^{h+1}=(-1)^{n} 4 \beta_{o} \beta_{1} \beta_{n-1} \beta_{n} \prod_{j=2}^{n-2} \beta_{j}^{2}\left(\beta_{i} e_{i}\right)
$$

so putting $\beta_{j}=1, j=2, \ldots, n-2$ and $\beta_{0}=\beta_{1}=\beta_{n-1}=\beta_{n}=1 / \sqrt{2}$ we obtain the simplest, for real $\beta_{i}{ }^{-} s$, relation

$$
\left(\beta_{i} e_{i}\right)^{h+1}=(-1)^{n}\left(\beta_{i} e_{i}\right)
$$

Froin now on we take the normalized 1 -cyclic element
(5) $E=\beta_{i} e_{i}$ where $\beta_{0}=\beta_{1}=\beta_{n-1}=\beta_{n}=1 / \sqrt{2}, \beta_{j}=1, j=2, \ldots, n-2$

Remark The 1 -cyclic element $E$ satisfies the following obvious relations:
(6) $E^{h+1}=(-1)^{n} E$
(7) $E^{2 x-1}=(-1)^{n} E^{2(n-x)-1}$ for $x \in N$; $x \leq \frac{n}{2}$

Let $S$ be the centralizer of $E$ in $\mathcal{G}$. Then, see Lemme 6.4B in [4], S is a Cartan subalgebra of $\mathbb{g}$. It is clear that in our case a basis for $S$ is the set

$$
\left\{E, E^{3}, \ldots, E^{2 n-3}, E_{O}\right\}
$$

where $\quad E_{0}=E_{1 n}-E_{n, n+1}+E_{n 1}+E_{n, 2 n}-E_{n+1,1}-E_{n+1,2 n}+E_{2 n, n}-E_{2 n, n+1}$

The element $E_{0}$ has $\operatorname{deg}_{0}=n-1$ and satisfies the relation

$$
E_{0}^{2}=4 I+(-1)^{n-1} 4 E^{h}
$$

We need a basis $T_{i}, i=1, \ldots, n$ such that

$$
\left(T_{i} \mid T_{n-j}\right)=\delta_{i j}
$$

By virtue of (7) such a basis is the following one :

For $n=2 \boldsymbol{n}$

$$
\left\{\begin{array}{l}
T_{i}=\frac{1}{\sqrt{h}} E^{2 i-1}, T_{x+i+1}=t_{T_{x-i}}, i=1, \ldots, x-1 \\
T_{x}=\frac{1}{2 \sqrt{2}} E_{0}, T_{x+1}=\frac{1}{2 \sqrt{2}} E_{0}+\frac{1}{\sqrt{h}} E^{2 x-1}
\end{array}\right.
$$

For $n=2 x+1$

$$
\left\{\begin{array}{l}
T_{i}=\frac{1}{\sqrt{h}} E^{2 i-1}, T_{n+i+1}=-t_{T_{n-i+1}}, i=1, \ldots, x \\
T_{x+1}=\frac{1}{2 \sqrt{2}} E_{0}
\end{array}\right.
$$

According to [3] the subspace $g_{0}$ of the elements of $g$ of degree 0 is the linear span of the projections of all the root spaces of $g$ with respect to $S$. Our problem is to choose $n$ root vectors $A_{1}, \ldots, A_{n}$, with respect to $S$, corresponding to the roots $\beta_{1} \ldots, \beta_{n}$ such that their projections on $\mathscr{g}_{0}$ form a basis of this space, then to compute the constants $\lambda_{i j}$ defined by

$$
\lambda_{i j}=\beta_{i}\left(T_{j}\right) \quad, i, j=1, \ldots, n
$$

Note that if we decompose the vectors $A_{1}, \ldots, A_{n}$ with respect to the 1-principal gradation:

$$
A_{i}=\sum_{j} A_{i j}, i=1, \ldots, n, j \in z / h z
$$

then the elements

$$
A_{i j}, T_{x} \quad \text { where } \quad i, x=1, \ldots, n ; j=0, \ldots, h-1
$$

form a basis of $g$ -
Using the above notation we obtain the following proposition for $D_{n}^{(1)}$.
PROPOSITION 2
The constants $\lambda_{i j}$ belong to the $h$-roots of the real numbers $\tau_{v}, \tau_{\mu}$ such that
(8) $\left(\operatorname{adT}_{h-v}\right)\left(\operatorname{adT}_{v}\right) A_{\text {io }}=\tau_{v} A_{\text {io }},\left(\operatorname{adT}_{\mu}\right)^{2} A_{\text {io }}=\tau_{\mu} A_{\text {io }}$
where $v=1, \ldots, x-1$ and $\mu=x, x+1$ for $n=2 x$, $v=1, \ldots, x$ and $\mu=x+1$ for $n=2 x+1$.

## PROOF

From relation (7) we obtain that $\operatorname{adr}_{v}$ and $\operatorname{adT}_{h-v}$ have opposite eigenvalues with eigenvectors which are transpose to each other. That means that those eigenvectors have the same projections on $g_{0}$.
On the other hand from the relation

$$
\left(\operatorname{adT}_{v}\right) A_{i j}=B_{i}\left(T_{v}\right) A_{i, j+v}
$$

the transformation $a d T v$ shifts the gradation by $v$. Therefore
we have for the projection $A_{i o}$ on $\mathcal{E}_{0}$ the relation

$$
\left(a d T_{h-v}\right)\left(a d T_{v}\right) A_{i o}=\beta_{i}\left(T_{v}\right) \beta_{i}\left(T_{h-v}\right) A_{\text {io }}
$$

According to KAC [2] an automorphism o of order $h$ of the Lie algebra $g$ is given by $\sigma(x)=\varepsilon^{i} x, x \in g_{i}$, where $\varepsilon$ is a primitive h-root of unity. So we have

$$
\left(\beta_{i}\left(T_{v}\right)\right)^{h-v}=\left(\beta_{i}\left(T_{h-v}\right)\right)^{v}
$$

Therefore if $\varepsilon$ is a primitive h-root of $\quad \tau_{v}=\beta_{i}\left(T_{v}\right) \beta_{i}\left(T_{h-v}\right)$
then we can take

$$
\varepsilon^{\nu}=\beta_{i}\left(T_{\nu}\right), \varepsilon^{h-v}=\beta_{i}\left(T_{h-v}\right)
$$

Q.E.D.
4. In order to compute the $\lambda_{j . j} / s$ we can taike an integer $v<n$ such that $(v, h)=1$ and then we can try to find $n$ different $\tau_{v}{ }^{-s}$. The eigenvector $A_{i}$ corresponding to such an $\tau_{v}$ will be defined by
(9) $A_{i}=\sum_{j=0}^{h-1}\left(a d T_{v}\right)^{j_{A}}{ }_{i o}$

In the special case of $\quad v=1$ we have the following :
a) For $A_{10}=E_{11}-E_{2 n, 2 n}$ and $A_{n O}=E_{n n}-E_{n+1, n+1}$
we have $\tau=-1$. So

$$
A_{i}=\sum_{j=0}^{h-1}\left(\operatorname{adT}_{v}\right)^{j} A_{i o}, \quad \lambda_{i j}=\varepsilon^{j}
$$

where $i=1$ or $n$ and $\varepsilon$ be an $h$-primitive root of -1 .
b) For $i=2, \ldots, n-1$ we set
(10) $A_{i 0}=\operatorname{diag}\left(0, x_{i 2}, \ldots, x_{i, n-1}, 0,0,-x_{i, n-1} \ldots,-x_{i 2}, 0\right)$

Then from relation (8) we obtain that $\tau$-s are the eigenvalues of the matrix
and for some eigenvector $\quad x=\left(x_{i 2}, \ldots, x_{i, n-1}\right)$ we get the corresponding $A_{i o}$ from (10).

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