## Commentationes Mathematicae Universitatis Caroline

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Commentationes Mathematicae Universitatis Carolinae, Vol. 28 (1987), No. 1, 95--102
Persistent URL: http://dml.cz/dmlcz/106512

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# COMMENTATIONES MATHEMATICAE UNIVERSITATIS CAROLINAE 

28.1 (1987)

## INTERIOR REGULARITY FOR THE QUASILINEAR ELLIPTIC SYSTEMS WITH NONSMOOTH COEFFICIENTS Jifi KOTTAS

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    Abstract: The interior C }\mp@subsup{C}{}{0,\alpha
on of the quasilinear second order elliptic system is investiga-
ted. The positive answer is obtained for systems which are "not
far" from the Laplace equations. This situation is described by
means of the dispersion of eigenvalues of the coefficients mat-
rix.
    Key words: Quasilinear elliptic systems, interior regula-
rity.
    Classification: 35B65, 35J60
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1. Introduction. The paper deals with $C^{0, \infty}$-regularity of solutions of second order quasilinear elliptic systems with nonsmooth coefficients satisfying certain conditions of the dispersion of eigenvalues, This condition was firstly established by A.I. Koshelev. (See [3] for references.) Our aim is to obtain a simpler proof and to this end we use a modification of the method of $J$. Nečas for smooth coefficients described in [2]. We consider a slightly more general condition of ellipticity than in [3] (which does not guarantee unicity of solutions of Dirichlet problem) and we prove that every weak solution is locally Höldercontinuous.
2. Notations and definitions. We consider the quasilinear system
(2.1) $\quad \sum_{1, \beta} \sum_{i=1}^{m} \sum_{j=1}^{m} D_{\alpha}\left(a_{i j}^{\alpha \beta}(x, u) D_{\beta} u^{j}\right)=0 \quad i=1, \ldots, m$, where $u=\left[u^{1}, \ldots, u^{m}\right]$ is a vector function defined on a bounded domain $\Omega \in \mathbb{R}^{n}$.

The coefficients $a_{i j}^{\alpha \beta}: \Omega \times \mathbb{R}^{m} \rightarrow \mathbb{R}$ are bounded Carathéodory functions, symmetric (i.e. $a_{i j}^{\alpha \beta}=a_{j i}^{\beta \alpha}$ ) and satisfying the following ellipticity condition:
(2.2) There are two positive numbers $\lambda_{0}, \lambda_{1}$ such that the inequalities

$$
\lambda_{0}|\xi|^{2} \leq\langle\mathbb{A}(x, p) \xi ; \xi\rangle \leq \lambda_{1}|\xi \cdot|^{2}
$$

hold for all $\xi \in \mathbb{R}^{m \times n}, p \in \mathbb{R}^{m}$ and a.e. $x \in \Omega$.
$\mathbb{A}$ denotes here the matrix of coefficients $\left(a_{i j}^{\alpha \beta}{ }_{i}^{\alpha, \beta=1, j=1, \ldots, n}, \ldots\right.$. $\left\langle\right.$; > is the inner product on the Euclidean space $\mathbb{R}^{k}(k=m \times n)$, $|\mid$ is the norm generated by this inner product.

In what follows, we shall suppose that $m \geq 2, n \geq 2$.
Definition 2.1. We say that the function $u \in W_{2,1 o c}^{1}(\Omega)$ (we shall write $W_{2,10 c}^{1}(\Omega)$ instead of $\left.\left[W_{2,10 c}^{1}(\Omega)\right]^{m}\right)$ is a weak solution of the system (2.1) if for each $\varphi \in \mathscr{D}(\Omega)$ we have

$$
\int_{\Omega}\langle A(x, u) D u ; D \varphi\rangle d x=0
$$

Definition 2.2. The system (2.1) is said to be regular if each weak solution of (2.1) is locally Hölder-continuous on $\Omega$.

We shall use so called Campanato spaces (denoted by $\mathscr{L}_{2, \lambda}(\Omega)$ or $L_{2, \lambda}^{c}(\Omega)$ - see [4]) which are for $\left.\lambda_{\epsilon} \in n, n+2\right]$ isomorphic to the spaces $c^{0, \alpha}(\bar{\Omega})$ with $\alpha=\frac{\lambda-n}{2}$

Introduce now in $\mathbb{R}^{n}$ the polar coordinates with the origin at the point $y$ :

$$
\begin{aligned}
& x_{1}-y_{1}=r \cos \varphi_{1}, x_{2}-y_{2}=r \sin \varphi_{1} \cos \varphi_{2}, \ldots, \\
& x_{n-1}-y_{n-1}=r \sin \varphi_{1} \cdots \sin \varphi_{n-2} \cos \varphi_{n-1} \\
& x_{n}-y_{n}=r \sin \varphi_{1} \ldots \sin \varphi_{n-1}
\end{aligned}
$$

and define the symbols $\partial_{1} v, \ldots, \partial_{n} v$ as

$$
\begin{aligned}
& \partial_{1} v=\frac{\partial v}{\partial r}, \quad \partial_{2} v=\frac{1}{r} \frac{\partial v}{\partial \varphi^{I}}, \quad \partial_{3} v=\frac{1}{r \sin \varphi_{1}} \frac{\partial v}{\partial \varphi_{2}}, \\
& \partial_{n} v=\frac{1}{r \sin \varphi_{1} \ldots \sin \varphi_{n-2}} \frac{\partial v}{\partial \varphi_{n-1}} .
\end{aligned}
$$

Denote further $D_{B} v=\left[\partial_{2} v, \ldots, \partial_{n} v.\right]$,

$$
\begin{aligned}
& B(y, R)=\left\{x \in \mathbb{R}^{n} ;|x-y|<R\right\} \\
& S(y, R)=\left\{x \in \mathbb{R}^{n} ;|x-y|=R\right\}
\end{aligned}
$$

It is clear that for $x \in S(y, R),\left(D_{B} v\right)(x)$ is the vector of derivatives of $v$ in tangent directions to the sphere $S(y, R)$. Put $u_{y, R}=\frac{1}{\mu(B(y, R)} \int_{B(n, R)} u d x$ ( $\mu$ is the Lebesgue measure on $\mathbb{R}^{n}$ )

$$
K(n)=\frac{\sqrt{1+\frac{(n-2)^{2}}{n-1}}-1}{\sqrt{1+\frac{(n-2)^{2}}{n-1}+1}}
$$

3. Soft theorem. We present here Theorem 3.1 which is weaker than Theorem 4.1, because it can be proved in a transparent way.

Theorem 3.1. Let $\frac{\lambda_{0}}{\lambda_{1}}>\frac{n-2}{n}$. Then the system (2.1) is regular
Remark 3.2. Each solution of the quasilinear system (2.1) is also the solution of the linear system with bounded measurable coefficients $\left(b_{i j}^{\alpha \beta}(x)=a_{i j}^{\alpha \beta}(x, u(x))\right.$, which satisfies the conditions (2.2) with the same constants $\lambda_{0}, \lambda_{1}$, hence it is sufficient to prove the theorem only for linear systems.

Proof: Let $u$ be a weak solution of the system (2.1) and let $\Omega_{1} \subset \subset \Omega$. In order to prove that $u \in C^{0, \alpha}\left(\bar{\Omega}_{1}\right)$ we have to show that for some $\beta>n$ the function $g\left(x_{0}, R\right)=R^{-\beta} \int_{B\left(x_{0}, R\right)}\left|u-u_{x_{0}, R}\right|^{2} d x$ is bounded on the set $\left.M=\Omega_{1} \times\right] 0$; $d\left[\right.$, where $d=\frac{1}{2} \operatorname{dist}\left(\Omega_{1}, \partial \Omega\right)$. Using Poincaré inequality

$$
\int_{B\left(x_{0}, R\right)}\left|u-u_{x_{0}}, R\right|^{2} d x \leqslant c R^{2} \int_{B\left(x_{0}, R\right)}|D u|^{2} d x
$$

we can see that it suffices for some $\gamma>n-2$ to show the boundedness of the function

$$
f\left(x_{0}, R\right)=R^{-\gamma} \int_{B\left(x_{0}, R\right)}|D u|^{2} d x \text { on } M .
$$

The function $f$ is bounded on the set $\Omega_{i} \times\{d\}$, hence it suffices to prove that $\frac{\partial f}{\partial R}\left(x_{0}, R\right) \geq 0$ for all $x_{0} \in \Omega_{1}$ and a.e. $\left.R \in\right] 0, d[$. The derivative $\frac{\partial f}{\partial R}$ exists for all $x_{0} \in \Omega_{1}$ and a.e. $\left.R \in\right] 0, d[$ and $\frac{\partial f}{\partial R}=-\gamma^{R^{-\gamma-1}} \int_{B\left(x_{0}, R\right)}|D u|^{2} d x+R^{-\gamma} \int_{B\left(x_{0}, R\right)}|D u|^{2} d S$.

For $\left(x_{0}, R\right) \in M$ we denote $v=v\left(x, x_{0}, R\right)$
the veotor function which is a weak solution in $W_{2}^{1}\left(B\left(x_{0}, R\right)\right.$ ) of the system

$$
\Delta v^{j}=0 \quad j=1, \ldots, m
$$

and satisfies the stable boundary condition $u-v \in \mathbb{W}_{2}^{l}\left(B\left(x_{0}, R\right)\right)$.
Now we shall prove two lemmas to finish the proof of the theorem.

Lemma 3.3. For all $\left(x_{0}, R\right) \in M$ the inequality
(3.1) $\quad \int_{B\left(x_{0}, R\right)}|D u|^{2} d x \leqslant \frac{\lambda_{1}+\lambda_{0}}{2 \lambda_{0}} \int_{B\left(x_{0}, R\right)}|D v|^{2} d x$
holds.
Lemma 3.4. Let for some a $\in] 1, \frac{n-1}{n-2}$ [and for all $\left(x_{0}, R\right) \in M$ $\int_{B\left(x_{0}, R\right)}|B u|^{2} d x \leq a \quad \int_{B\left(x_{0}, R\right)}|D v|^{2} d x$.
Then
$u \in C^{0, \alpha}\left(\bar{\Omega}_{1}\right)$ with $\alpha=\frac{1}{2}\left(\frac{n-1}{2}-n+2\right)$.
Proof of Lemma 3.3. It is easy to see that
and $\int_{B\left(x_{0}, R\right)}\langle\mathbb{A} D u ; D(v-u)\rangle d x=0$
$\int_{B\left(x_{0}, R\right)}\langle D v ; D(v-u)\rangle d x=0$; hence
$\int_{B\left(x_{0}, R\right)}|D v|^{2} d x=\int_{B\left(x_{0}, R\right)}\langle D v ; D u\rangle d x$.
Now using the condition (2.2) and the symmetry of $\mathbb{A}$ we obtain $\int_{B\left(x_{0}, R\right)}|D u|^{2} d x \leq \frac{1}{\lambda_{0}} \int_{B\left(x_{0}, R\right)}\langle\mathbb{A} D \dot{u}, D u\rangle d x=$
$=\frac{1}{\lambda_{0}} \int_{B\left(x_{0}, R\right)}\langle\mathbb{A} D v ; D v\rangle d x-\frac{1}{\lambda_{0}} \int_{B\left(x_{0}, R\right)}\langle\mathbb{A} D(v-u), D(v-u)\rangle d x \leq$
$\leqslant \frac{\lambda_{1}}{\lambda_{0}} \int_{B\left(x_{0}, R\right)}|D v|^{2} d x-\int_{B\left(x_{0}, R\right)}|D(v-u)|^{2} d x=$
$=\frac{\lambda_{1}}{\lambda_{0}} \int_{B\left(x_{0}, R\right)}|D v|^{2} d x-\int_{B\left(x_{0}, R\right)}|D v|^{2} d x+2 \quad \int_{B\left(x_{0}, R\right)}\langle D v ; D u\rangle d x-$
$-\int_{B\left(x_{0}, R\right)}|D u|^{2} d x=\left(1+\frac{\lambda_{1}}{\lambda_{0}}\right) \int_{B\left(x_{0}, R\right)}|D v|^{2} d x-\int_{B\left(x_{0}, R\right)}|D u|^{2} d x$.
An easy calculation gives (3.1).
Proof of Lemma 3.4. For a weak solution $w \in W_{2}^{1}\left(B\left(x_{0}, R\right)\right)$ of
the system $\Delta w^{j}=0 \quad j=1, \ldots, m$ the estimate

$$
\int_{B\left(x_{0}, R\right)}|O w|^{2} d x \neq \frac{R}{n-1} \int_{S\left(x_{0}, R\right)}\left|D_{B} w\right|^{2} d S
$$

holds. See [2].
As $D_{B} u=D_{B} v$ on $S\left(x_{0}, R\right)$ and $\left|D_{B} u\right|^{2} \leqslant|D u|^{2}$, we get from here
$\int_{B\left(x_{0}, R\right)}|D u|^{2} d x \notin a \int_{B\left(x_{0}, R\right)}|D v|^{2} d x \in \frac{a R}{n-1} \int_{S\left(x_{0}, R\right)}\left|D_{B} v\right|^{2} d S=$
$=\frac{a R}{n-I} \int_{S\left(x_{0}, R\right)}\left|D_{B} u\right|^{2} d S \leqslant \frac{a R}{n-I} \int_{S\left(x_{0}, R\right)}|O u|^{2} d S$.
It easily follows that

$$
R \int_{S\left(x_{0}, R\right)}|D u|^{2} d S-\frac{n-1}{B} \int_{B\left(x_{0}, R\right)}|D u|^{2} d x \geq 0 .
$$

Put $\gamma=\frac{n-1}{a}$. Then

$$
\frac{\partial}{\partial r}\left(x_{0}, R\right)=R^{-\gamma} \int_{S\left(x_{0}, R\right)}|D u|^{2} d S-\gamma^{-\gamma-1} \int_{B\left(x_{0}, R\right)}|D u|^{2} d x \geq 0 .
$$

Q.E.D.

## 4. Hard theorem

Theorem 4.1. Let $\frac{\lambda_{0}}{\lambda_{1}}>K(n)$. Then the system"(2.1) is regular.
Proof: Let us introduce the function space (see [3])
$H_{2, \lambda}(\Omega)=\left\{u \in W_{2}^{1}(\Omega) ; \sup _{x_{0} \in \Omega} \int_{\Omega}|D u|^{2}\left|x-x_{0}\right|^{-\lambda} d x<\infty\right\}$ equipped with the norm

$$
|u|_{H_{2, \lambda}}(\Omega)=\left(\int_{\Omega}|u|^{2} d x+\sup _{x_{0} \in \Omega} \int_{\Omega}|D u|^{2}\left|x-x_{0}\right|^{-\lambda} d x\right)^{\frac{1}{2}} \text {. }
$$

This space is for $\lambda>n-2$ imbedded into the space $C^{0, \infty}(\Omega)$ with $\alpha=\frac{1}{2}(\lambda-n+2)$.
Let $h$ be a non-zero element of $D\left(R_{n}\right)$, supp $h \subset B(0,1), h \geq 0$.
Denote $h_{k}(x)=c_{k} h(k x), k \in \mathbb{N}$, where $c_{k}$ are constants such that

$$
\int_{\mathbb{R}^{n}} h_{k}(x) d x=1
$$

let $\Omega_{2} \subset \subset \Omega_{1} \subset \subset \Omega, \partial \Omega_{1}$ is sufficiently smooth.
Put $R=\frac{1}{4} \operatorname{dist}\left(\Omega_{2}, \partial \Omega_{1}\right), a_{i j}^{\alpha \beta}=0$ on $\mathbb{R}^{n} \backslash \Omega$ and $k_{a_{i j}}^{\alpha \beta}=h_{k} * a_{i j}^{\alpha \beta}$. Then $\lim _{k \rightarrow \infty} k_{a_{i j}}^{\alpha \beta}(x)=a_{i j}^{\alpha} \beta_{j}(x)$ a.e. on $\Omega$ and matrices ${ }^{k} \mathbb{A}$ satisfy (for $k \geq k_{0}$ ) on $\Omega_{1}$ the condition (2.2) with the same constants $\lambda_{0}, \lambda_{1}$. The boundary value problem

$$
\int_{\Omega_{1}}\left\langle{ }^{k} A D u_{k}, D \varphi\right\rangle=0 \quad \forall \varphi \in W_{2}^{1}\left(\Omega_{1}\right), u_{k}-u \in W_{2}^{1}\left(\Omega_{1}\right)
$$

has a uniquely determined solution $u_{k} \in W_{2}^{1}\left(\Omega_{1}\right)$ for each $k>k_{0}$. Obviously

$$
\left|u_{k}\right|_{W}^{1}(\Omega) \leqslant c\left(\lambda_{0}!\lambda_{1}\right)|u|_{W_{2}^{1 / 2}}\left(\partial \Omega_{1}\right) .
$$

The space $w_{2}^{1}\left(\Omega_{1}\right)$ is reflexive and so we can suppose that $u_{k}$ is weakly convergent to some $v \in W_{2}^{1}\left(\Omega_{1}\right)$.
The set $V=\left\{w \in W_{2}^{1}\left(\Omega_{1}\right)\right.$, $\left.w-u \in \mathscr{W}_{2}^{1}\right\}$ is convex and closed, hence it is weakly closed and $v-u \in \hat{W}_{2}^{1}\left(\Omega_{1}\right)$. Now we can apply the well known convergence lemma (see [1], chapt. 4) to see that $v$ is a weak solution of the system (2.1) and hence - because of the uniqueness - $v=u$.

The function $u$ is the weak limit of the sequence $\left\{u_{k}\right\}_{k>k_{0}}$
in $W_{2}^{1}\left(\Omega_{1}\right)$ and hence it is the strong limit in $L_{2}\left(\Omega_{1}\right)$ so we can suppose that
$\lim _{k \rightarrow \infty} u_{k}(x)=u(x)$ a.e. on $\Omega$.
All functions $u_{k}$ are of the class $C_{l o c}^{\infty}\left(\Omega_{1}\right)$. Choose $x_{0} \in \Omega_{2}$, $\eta \in D\left(B\left(x_{0}, 2 R\right)\right), \eta=1$ on $B\left(x_{0}, R\right),|D \eta|<\frac{c}{R}$, and $\psi=\left[\psi_{1}, \ldots, \psi_{m}\right] \epsilon$ $\in \mathbb{D}\left(\mathbb{R}^{n}\right)$. Then

$$
\int_{\mathbb{R}^{n}}\left\langle{ }^{k} \mathbb{A} D\left(u_{k} \eta\right), D \psi\right\rangle d x=
$$

$=\int_{\mathbb{R}^{m}}\left\langle{ }^{k} \mathbb{A} u_{k} D \eta, D \psi\right\rangle d x-\int_{\mathbb{R}^{m}}\left\langle{ }^{k} A D u_{k}, D \eta \psi\right\rangle d x$.
Putting $\gamma=\frac{2}{\lambda_{0}+\lambda_{1}}$, we can rewrite the last equality as
(4.1) $\int_{\mathbb{R}^{n}}\left\langle D\left(u_{k} \eta\right) ; D \psi\right\rangle d x=\int_{\mathbb{R}^{n}}\left\langle\left(I-\gamma^{k} A\right)\left(D\left(u_{k} \eta\right)+\gamma^{k} A u_{k} D \eta ; D \psi\right\rangle d x-\right.$ $-\gamma \int_{\mathbb{R}^{n}}\left\langle{ }^{k} \mathbb{A} D u_{k}, D \eta \psi\right\rangle d x$.
Now we can apply
Lemma 4.3. Let $v, g, f$ be from $D\left(\mathbb{R}_{n}\right), x_{0} \in \mathbb{R}^{n}, n \geq 3$, and let for all $\psi \in D\left(\mathbb{R}^{n}\right)$

$$
\int_{\mathbb{R}^{n}}\langle D v, D \psi\rangle d x=\int_{\mathbb{R}^{n}}\langle f, D \psi\rangle d x+\int_{\mathbb{R}^{n}} g \psi d x .
$$

Then for $\lambda \in(n-2, n)$ and $\varepsilon>0$ exist $k=k(\varepsilon, \lambda)>0$ and $a=a(\lambda)>0$

$$
\begin{aligned}
& \text { such that } \\
& \int_{\mathbb{R}^{2 n}}|D v|^{2}\left|x-x_{0}\right|^{-\lambda} d x \leqslant(1+\varepsilon) a(\lambda)\left(1+\frac{(n-2)^{2}}{n-1}\right) \int_{\mathbb{R}^{n}}|f|^{2}\left|x-x_{0}\right|^{-\lambda} d x+ \\
&+k \int_{\mathbb{R}^{n}}|g|^{2}\left|x-x_{0}\right|^{-\lambda+2} d x
\end{aligned}
$$

and $\lim _{\lambda \rightarrow(m-2)_{+}} a(\lambda)=1$.
We omit the proof of this lemma. It can be found in a slightly modified form in [2].

Note that we are to prove this theorem only for $n \geq 3$. In the case $n=2$, every system (2.1) is regular. (It follows e.g. from Theorem 3.1.)

From (4.1) and from the conclusion of Lemma 4.3 we obtain for $\varepsilon$ and $\sigma^{\sigma}$ positive

$$
\begin{gathered}
\int_{\mathbb{R}^{n}}\left|D\left(u_{k} \eta\right)\right|^{2}\left|x-x_{0}\right|^{-\lambda} d x \leq(1+\varepsilon) a(\lambda)\left(1+\frac{(n-2)^{2}}{n-1}\right) . \\
\cdot \int_{\mathbb{R}^{n}}\left|\left(I-\gamma^{k} \mathbb{A}\right) D\left(u_{k} \eta\right)+\gamma^{k} \mathbb{A} u_{k} D \eta\right|^{2}\left|x-x_{0}\right|^{-\lambda} d x+ \\
+\left.\left.K_{1} \int_{\mathbb{R}^{m}}\right|^{k} \mathbb{A} D u_{k} D \eta\right|^{2}\left|x-x_{0}\right|^{-\lambda+2} d x \leq \\
-100-
\end{gathered}
$$

$\leq(1+\varepsilon)(1+\delta) a(\lambda)\left(1+\frac{(n-2)^{2}}{n-1}\right) \int_{\mathbb{R}^{n}}\left|\left(I-\gamma^{k} \mathbb{A}\right) D\left(u_{k} \eta\right)\right|^{2}\left|x-x_{0}\right|^{-\lambda} d x+$ $+K_{2}\left[\left.\left.\int_{R^{n}}\right|^{k} \mathbb{A} u_{k} D \eta\right|^{2}\left|x-x_{0}\right|^{-\lambda} d x+\left.\left.\int_{\mathbb{R}^{n}}\right|^{k} A D u_{k} D \eta\right|^{2}\left|x-x_{0}\right|^{-\lambda+2} d x\right] \leqslant$ $\leq(1+\varepsilon)\left(1+\sigma^{\prime}\right) \mathrm{a}(\lambda)\left(1+\frac{(n-2)^{2}}{n-1}\right)\left(\frac{\lambda_{1}-\lambda_{0}}{\lambda_{1}+\lambda_{0}}\right)^{2} \int_{\mathbb{R}^{n}}\left|D\left(u_{k} \eta\right)\right|^{2}\left|x-x_{0}\right|^{-\lambda}+$ $+K_{3} \int_{\mathbb{R}^{n}}\left(\left|u_{k}\right|^{2}+\left|D u_{k}\right|^{2}\right) d x$
since supp $|D \eta| \subset P=B\left(x_{0}, 2 R\right) \backslash B\left(x_{0}, R\right)$ and the function $|D \eta|\left|x-x_{0}\right|^{-\lambda}$ is bounded on $P$.

Now we have $\frac{\lambda_{0}}{\lambda_{1}}>K(n)$ and so we can choose positive $\varepsilon ; \sigma^{\sigma}$ and $\lambda>n-2$ such that

$$
(1+\varepsilon)\left(1+\sigma^{\prime \prime}\right) a\left(\lambda^{\prime}\right)\left(\frac{\lambda_{1}-\lambda_{0}}{\lambda_{1}+\lambda_{0}}\right)^{2}\left(1+\frac{(n-2)^{2}}{n-1}\right)^{2}<1
$$

and hence

$$
\begin{aligned}
\int_{B\left(x_{0}, R\right)}\left|D u_{n}\right|^{2}\left|x-x_{0}\right|^{-\lambda} & \leq k_{4}\left|u_{k}\right|_{w_{2}^{1}\left(\Omega_{1}\right)} \leq c= \\
& =c\left(\Omega_{1}, \Omega_{2}, \frac{\lambda_{1}}{\lambda_{0}}, \lambda_{1}|u|_{w_{2}^{1 / 2}\left(\partial \Omega_{1}\right)}\right) .
\end{aligned}
$$

If we take into account the definition of the space $H_{2, \lambda}\left(\Omega_{2}\right)$ and its imbedding into $C^{0, \propto}\left(\bar{\Omega}_{2}\right)$ we have for $x, y \in \Omega_{2}$

$$
\left|\frac{u_{k}(x)-u_{k}(y)}{|x-y|^{\infty}}\right| \leq c,
$$

where $C$ does not depend on $k$. Letting $k \rightarrow \infty$ we obtain the conclusion of the theorem.
5. Open problems
a) Is the estimate $a<\frac{n-1}{n-2}$ in Lemma 3.4 sharp ?
b) It is a well known fact that in the case $n=2$ or $m=1$ is the system (2.1) regular. The case $n=2$ is the consequence of the theorem 3.1, but our condition on $\frac{\lambda_{0}}{\lambda_{1}}$ does not take into account the number of the equations $m$. It would be better to have conditions in the form

$$
\frac{\lambda_{0}}{\lambda_{1}}>K(m, n) .
$$

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