## Mathematic Slovaca

# Ondřej Došlý <br> The multiplicity criteria for zero points of second order differential equations 

Mathematica Slovaca, Vol. 42 (1992), No. 2, 181--193

Persistent URL: http://dml.cz/dmlcz/131731

## Terms of use:

© Mathematical Institute of the Slovak Academy of Sciences, 1992

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.


This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project DML-CZ: The Czech Digital Mathematics Library http://project.dml.cz

# THE MULTIPLICITY CRITERIA FOR ZERO POINTS <br> <br> OF SECOND ORDER DIFFERENTIAL EQUATIONS 

 <br> <br> OF SECOND ORDER DIFFERENTIAL EQUATIONS}

ONDŘEJ DOŠLÝ


#### Abstract

Sufficient conditions on the function $p(x)$ are given which guarantee the existence of a nontrivial solution of the equation $y^{\prime \prime}+p(x) y=0$ having at least $(n+1)$ zeros, $n \geq 1$, on a given interval.


## 1. Introduction

The aim of the present paper is to investigate the oscillation behaviour of the second order differential equation

$$
\begin{equation*}
\left(r(x) y^{\prime}\right)^{\prime}+p(x) y=0 \tag{1.1}
\end{equation*}
$$

where $r(x) \in C^{1}(I), r(x)>0$ on $I, p(x) \in C(I), x \in I=(a, b),-\infty \leq a<$ $b \leq \infty$. Particularly, we give conditions on the functions $r, p$ which guarantee the existence of a nontrivial solution of (1.1) having at least $(n+1)$ zeros on $I$.

Recall briefly the history of the problem. Hawking and Penrose [7] showed that the equation

$$
\begin{equation*}
y^{\prime \prime}+p(x) y=0 \tag{1.2}
\end{equation*}
$$

is conjugate on $\mathbb{R}=(-\infty, \infty)$ (i.e., there exists a nontrivial solution of (1.2) having at least 2 zeros - the so-called conjugate points - on $\mathbb{R}$ ) whenever $p(x) \geq 0$ and $p(x) \not \equiv 0$. This result was generalized by Tipler who proved that (1.2) is conjugate on $\mathbb{R}$ whenever

$$
\begin{equation*}
\liminf _{\left.t_{1} \downarrow-\infty, t_{2}\right\rceil \infty} \int_{t_{1}}^{t_{2}} p(x) \mathrm{d} x>0 \tag{1.3}
\end{equation*}
$$

[^0]Concerning equation (1.1), M üller-Pfeiffer [11] proved that this equation is conjugate on $I=(a, b)$ if

$$
\begin{gather*}
\int_{a} r^{-1}(x) \mathrm{d} x=\infty=\int^{b} r^{-1}(x) \mathrm{d} x  \tag{1.4}\\
\liminf _{t_{1}\left\lfloor a, t_{2} \dagger b\right.} \int_{i_{1}}^{t_{2}} p(x) \mathrm{d} x \geq 0 \tag{1.5}
\end{gather*}
$$

and $p(x) \not \equiv 0$ on $I$. The results of.[7] and [12] are based on the Riccati technique, the criterion of Müller-Pfeiffer is proved via the variational principle.

Recently the author proved (using a combination of the Riccati technique and the transformation method) that (1.2) is conjugate on $I$ if there exist $\varepsilon_{1}, \varepsilon_{2}>0$, $c \in I$ such that

$$
\begin{align*}
& \varepsilon_{1} \int_{c}^{b} \exp \left\{\int_{c}^{x}\left[\int_{c}^{t} p(s) \mathrm{d} s-\varepsilon_{1}\right] \mathrm{d} t\right\} \mathrm{d} x>\pi / 2  \tag{1.6}\\
& \varepsilon_{2} \int_{a}^{c} \exp \left\{\int_{c}^{x}\left[\int_{c}^{t} p(s) \mathrm{d} s+\varepsilon_{2}\right] \mathrm{d} t\right\} \mathrm{d} x>\pi / 2 \tag{1.6}
\end{align*}
$$

These conditions were proved to be less restrictive than (1.3).
Note that the transformation of the independent variable $t=t(x)=$ $\int^{x} r^{-1}(s) \mathrm{d} s$ transforms (1.1) into an equation of the form (1.2). Hence, in the sequel, we consider only the second order equations in this form.

The paper is designed as follows. In the next section we introduce the criterion which guarantees the existence of a nontrivial solution of (1.2) having at least $(n+1)$ zeros on $I=\mathbb{R}$. We also discuss the situation when the interval $I$ is bounded or one-side bounded. In Section 3 we present an improved version of the conjugacy criterion given by (1.6), which is shown to be more general than another conjugacy criterion of Tipler given in [12]. The last section is devoted to remarks concerning the extension of the results of Sections 2, 3 to partial differential equations and self-adjoint equations of higher orders.

## 2. The existence of $(n+1)$ zero points

Consider the equation (1.2) as a perturbation of the equation

$$
\begin{equation*}
y^{\prime \prime}=0 \tag{2.1}
\end{equation*}
$$

If $a=-\infty, b=\infty$, the latter equation is 1 -special according to the terminology introduced by B or u vk a [1], i.e., this equation is disconjugate on $I$ and there exists a unique (up to a multiple by a nonzero real constant) solution, namely $y_{0}=1$, which does not vanish on $I$. An equivalent formulation of this fact is that the principal solutions of (2.1) at $-\infty$ and $\infty$ are identical (recall that a solution $y_{b}$ of a second-order equation is said to be principal at a point $b$ if $\lim _{x \rightarrow b} y_{b}(x) / y(x)=0$ for any solution $y(x)$ linearly independent of $y_{b}(x)$ and $y_{b}(x) \neq 0$ in a neighbourhood of $\left.b\right)$.

As condition (1.3) shows, equation (2.1) is in a certain sense oscillatory unstable. A small perturbation of this equation by a term $p(x) y$ with $p(x) \not \equiv 0$ and $p(x)$ having essentially a non-negative mean value on $\mathbb{R}$ makes equation (1.2) conjugate on $\mathbb{R}$. This fact is not too surprising if we observe that $y_{0}(x)=1$ is the eigenfunction corresponding to the least eigenvalue $\lambda_{0}=0$ of the minimal closed symmetric operator $l_{0}$ generated by the differential expression

$$
\begin{equation*}
l(y)=\left(1+x^{2}\right)^{2} \frac{\mathrm{~d}^{2}}{\mathrm{~d} x^{2}} y, \quad x \in \mathbb{R} \tag{2.2}
\end{equation*}
$$

(see [13] for necessary terminology). This idea also suggests the method which we use in looking for conditions on $p(x)$ implying the existence of a nontrivial solution of (1.2) with at least $(n+1)$ zeros.

The main result of this section is based on the following variational lemma.
Lemma 1. Let $x_{0}, x_{1} \in \mathbb{R}, x_{0}<x_{1}$ and let $y_{1}, \ldots, y_{n} \in W^{1,2}\left(x_{0}, x_{1}\right)$ be linearly independent functions (as the members of the Hilbert space $W^{1,2}\left(x_{0}, x_{1}\right)$ ) such that $y_{k}\left(x_{0}\right)=y_{k}\left(x_{1}\right)=0$ and $y_{k}$ has exactly $(k-1)$ zeros on $\left(x_{0}, x_{1}\right)$, $k=1, \ldots, n$. If

$$
\begin{equation*}
I\left(y_{k} ; x_{0}, x_{1}\right)=\int_{x_{0}}^{x_{1}}\left[y_{k}^{\prime 2}(x)-p(x) y_{k}^{2}(x)\right] \mathrm{d} x<0 \tag{2.3}
\end{equation*}
$$

$k=1, \ldots, n$, then there exists a nontrivial solution of (1.2) having at least $(n+1)$ zeros on $\left[x_{0}, x_{1}\right]$.

Proof. By the Courant variational principle (see, e.g., [2]) (2.3) implies that the boundary value problem $y^{\prime \prime}+p(x) y=0, y\left(x_{0}\right)=y\left(x_{1}\right)=0$ has at least $n$ negative eigenvalues. The eigenfunction corresponding to the eigenvalue $\lambda_{n}<0$ (the eigenvalues are ordered by size, $\lambda_{1}<\lambda_{2}<\cdots<\lambda_{n}$ ) has $(n+1)$ zeros on $\left[x_{0}, x_{1}\right]$. Now, if the interval $\left[x_{0}, x_{1}\right]$ is shrinking, the eigenvalues increase and after some time $\lambda_{n}=0$. The standard regularity argument implies that the corresponding eigenfunction $y_{n}$ is of the class $C^{2}$, i.e., we have the solution of (1.2) having $(n+1)$ zeros on $\left[x_{0}, x_{1}\right]$.

## ONDŘEJ DOŠLÝ

Theorem 1. Suppose $p(x)-\left(k^{2}-1\right)\left(1+x^{2}\right)^{-2} \not \equiv 0$ on $\mathbb{R}$ and

$$
\begin{gather*}
\liminf _{t_{1} \downarrow-\infty, t_{2} \downarrow \infty} \int_{t_{1}}^{t_{2}}\left[p(x)-\left(k^{2}-1\right)\left(1+x^{2}\right)^{-2}\right]\left(1+x^{2}\right) \sin ^{2} k\left(\operatorname{arctg} x+\frac{\pi}{2}\right) \mathrm{d} x \geq 0 \\
k=1, \ldots, n . \tag{2.4}
\end{gather*}
$$

Then (1.2) possesses a nontrivial solution having at least $(n+1)$ zeros on $\mathbb{R}$.
Proof. Denote $y_{k}=\left(1+x^{2}\right)^{1 / 2} \sin k\left(\operatorname{arctg} x+\frac{\pi}{2}\right), f_{k}=\left(k^{2}-1\right)\left(1+x^{2}\right)^{-2}$, $p_{k}=p-f_{k}$. Since $p_{k} \not \equiv 0$ and (2.4) holds, there exists $t_{k} \in \mathbb{R}, d_{k}>0$ and $\varrho_{k}>0$ such that $p_{k}(x)>d_{k}$ for $x \in\left(t_{k}-\varrho_{k}, t_{k}+\varrho_{k}\right)$. According to (2.4) there exist $T_{k}, S_{k}$ such that $\int_{i_{1}}^{t_{2}} p_{k}(x) y_{k}^{2}(x) \mathrm{d} x>-\varepsilon, \varepsilon>0$ sufficiently small, whenever $t_{1}<T_{k}, t_{2}>S_{k}$. Choose $x_{1} \leq \min _{k}\left\{T_{k}\right\}, x_{2} \geq \max _{k}\left\{S_{k}\right\}$ such that all zero points of the functions $y_{k}$ and all $\varrho_{k}$-neighbourhoods of $t_{k}$ are in the interior of the interval $\left(x_{1}, x_{2}\right)$. Moreover, the numbers $t_{k}$ and $\varrho_{k}$ can be chosen in such a way that the interval $\left[t_{k}-\varrho_{k}, t_{k}-\varrho_{k}\right]$ does not contain zero points of the function $y_{k}(x)$. Define the function $h_{k}(x)$ and the test function $u_{k}(x)$ for (2.3) as follows:

$$
h_{k}(x)= \begin{cases}\delta_{k}\left(1-\varrho_{k}^{-1}\left|x-t_{k}\right|\right) & \text { if }\left|x-t_{k}\right| \leq \varrho_{k} \\ 0 & \text { if }\left|x-t_{k}\right|>\varrho_{k}\end{cases}
$$

the precise value of the constant $\delta_{k}$ will be determined latter,

$$
u_{k}(x)= \begin{cases}0, & x \leq x_{0} \\ y_{k}(x) \int_{x_{0}}^{x} y_{k}^{-2}(s) \mathrm{d} s\left(\int_{x_{0}}^{x_{1}} y_{k}^{-2}(s) \mathrm{d} s\right)^{-1}, & x \in\left[x_{0}, x_{1}\right] \\ y_{k}(x)\left(1+h_{k}(x) \cdot \operatorname{sgn} y_{k}(x)\right), & x \in\left[x_{1}, x_{2}\right] \\ y_{k}(x) \int_{x}^{x_{3}} y_{k}^{-2}(s) \mathrm{d} s\left(\int_{x_{2}}^{x_{3}} y_{k}^{-2}(s) \mathrm{d} s\right)^{-1}, & x \in\left[x_{2}, x_{3}\right] \\ 0, & x \geq x_{3}\end{cases}
$$

the values $r_{0}, r_{3}$ will be also determined later. Obviously $u_{k} \in \mathscr{O}^{-1,2}\left[r_{0}, x_{3}\right]$ $\left(\stackrel{o}{W}^{1,2}\left[x_{0}, x_{3}\right]=\left\{u \in W^{-1,2}\left(x_{0}, x_{3}\right), u\left(x_{0}\right)=0=u\left(x_{3}\right)\right\}\right)$. To simplify formally the computations which follow, we write $y, u, f, j, t, \underline{\varrho}, h, d, \delta$ instead of $y_{k}, u_{k}, f_{k}, p_{k}, t_{k}, \varrho_{k}, h_{k}, d_{k}, \delta_{k}$ respectively:

Using the fact that $y$ and $u$ are solutions of

$$
\begin{equation*}
y^{\prime \prime}+f(x) y=0 \tag{2.5}
\end{equation*}
$$

on $\left(x_{0}, t-\varrho\right) \cup\left(t+\varrho, x_{3}\right)$ and $y \neq 0$ on $\left(x_{0}, x_{1}\right) \cup\left(x_{2}, x_{3}\right)$, we have

$$
\begin{aligned}
& \int_{x_{0}}^{x_{1}}\left(u^{\prime 2}-f u^{2}\right) \\
= & \left.u^{\prime} u\right|_{x_{0}} ^{x_{1}}-\int_{x_{0}}^{x_{1}} u\left(u^{\prime \prime}+f u\right)=u^{\prime}\left(x_{1}\right) u\left(x_{1}\right)=y^{\prime}\left(x_{1}\right) y\left(x_{1}\right)+\left(\int_{x_{0}}^{x_{1}} y^{-2}(s) \mathrm{d} s\right)^{-1} .
\end{aligned}
$$

Similarly,

$$
\int_{x_{2}}^{x_{3}}\left(u^{\prime 2}-f u^{2}\right)=-y^{\prime}\left(x_{2}\right) y\left(x_{2}\right)+\left(\int_{x_{2}}^{x_{3}} y^{-2}(s) \mathrm{d} s\right)^{-1}
$$

Since $y$ is the principal solution of (2.5) both at $\infty$ and $-\infty$ (this may be verified by a direct computation), we have

$$
\lim _{x_{0} \downharpoonright-\infty}\left(\int_{x_{0}}^{x_{1}} y^{-2}(s) \mathrm{d} s\right)^{-1}=0=\lim _{x_{3} \uparrow \infty}\left(\int_{x_{2}}^{x_{3}} y^{-2}(s) \mathrm{d} s\right)^{-1}
$$

Further,

$$
\begin{aligned}
& \int_{x_{1}}^{x_{2}}\left(u^{\prime 2}-f u^{2}\right) \\
&=\left.y^{\prime} y\right|_{x_{1}} ^{t-\varrho}-\int_{x_{1}}^{t-\varrho} y\left(y^{\prime \prime}+f y\right)+\left.y^{\prime} y\right|_{t-\varrho} ^{t+\varrho}-\int_{t-\varrho}^{t+\varrho} u\left(u^{\prime \prime}+f u\right)+\left.y^{\prime} y\right|_{t+\varrho} ^{x_{2}}-\int_{t+\varrho}^{x_{2}} y\left(y^{\prime \prime}+f y\right) \\
&=\left.y^{\prime} y\right|_{x_{1}} ^{x_{2}}+\int_{t-\varrho}^{t+\varrho} y^{2}\left[(1+h \cdot \operatorname{sgn} y)^{\prime}\right]^{2}=\left.y^{\prime} y\right|_{x_{1}} ^{x_{2}}+\int_{t-\varrho}^{t+\varrho} y^{2} h^{\prime 2}
\end{aligned}
$$

Computing $\int_{x_{0}}^{x_{1}} \tilde{p} u^{2}$ and $\int_{x_{2}}^{x_{3}} \tilde{p} u^{2}$ observe that the function $u / y$ is monotonic on $\left(x_{0}, x_{1}\right)$ and $\left(x_{2}, x_{3}\right)$. Hence, using the second mean value theorem of integral

## ONDŘEJ DOŠLÝ

calculus, we have

$$
\begin{aligned}
\int_{x_{0}}^{x_{1}} \tilde{p} u^{2} & =\int_{x_{0}}^{x_{1}} \tilde{p} y^{2}(u / y)^{2}=\int_{\xi_{1}}^{x_{1}} \tilde{p} y^{2}, & \xi_{1} \in\left(x_{0}, x_{1}\right), \\
\int_{x_{2}}^{x_{3}} \tilde{p} u^{2} & =\int_{x_{2}}^{\xi_{2}} \tilde{p} y^{2}, & \xi_{2} \in\left(x_{2}, x_{3}\right) .
\end{aligned}
$$

Using the previous computations we get

$$
\begin{aligned}
& \int_{x_{0}}^{x_{3}}\left(u^{\prime 2}-p u^{2}\right)=\int_{x_{0}}^{x_{3}}\left(u^{\prime 2}-f u^{2}\right)-\int_{x_{0}}^{x_{3}} \tilde{p} u^{2} \\
= & \left(\int_{x_{0}}^{x_{1}} y^{-2}\right)^{-1}+\left(\int_{x_{2}}^{x_{3}} y^{-2}\right)^{-1}-\int_{\xi_{1}}^{\xi_{2}} \tilde{p} y^{2}+\int_{t-\varrho}^{t+\varrho} y^{2} h^{\prime 2}-2 \int_{t-\varrho}^{t+\varrho} \tilde{p} y h \cdot \operatorname{sgn} y-\int_{t-\varrho}^{t+\varrho} \tilde{p} y^{2} h^{2} .
\end{aligned}
$$

The last term is negative since $\tilde{p}>0$ and if $x_{0}$ and $x_{3}$ are sufficiently close to $-\infty$ and $\infty$, the sum of first two terms is less than $\varepsilon$. Moreover, since $\xi_{1}<\min _{k}\left\{T_{k}\right\}, \xi_{2}>\max _{k}\left\{S_{k}\right\}$, we have $-\int_{\xi_{1}}^{\xi_{2}} \tilde{p} y^{2} \leq \varepsilon$. Consequently,

$$
\int_{x_{0}}^{x_{3}}\left(u^{\prime 2}-p u^{2}\right) \leq 2 \varepsilon+\int_{t-\varrho}^{t+\varrho} y^{2} h^{\prime 2}-2 \int_{t-\varrho}^{t+\varrho} \tilde{p} y h \cdot \operatorname{sgn} y
$$

Denote $y_{0}=\max \{|y(x)|, x \in[t-\varrho, t+\varrho]\}, y_{1}=\min \{|y(x)|, x \in[t-\varrho, t+\varrho]\}$. Then $\int_{t-\varrho}^{t+\varrho} y^{2} h^{\prime 2}-2 \int_{t-\varrho}^{t+\varrho} \tilde{p} y h \cdot \operatorname{sgn} y \leq y_{0} \delta^{2} \varrho^{-2}-2 d y_{1} \varrho \delta$ since by our assumption $y$ does not change its sign on $[t-\varrho, t+\varrho]$ and $y h \cdot \operatorname{sgn} y \geq 0$ on this interval. By setting $\delta=\varepsilon^{1 / 2}$ we get $\int_{x_{0}}^{x_{3}}\left(u^{\prime 2}-p u^{2}\right) \leq \varepsilon^{1 / 2}\left(\left(2+y_{0}^{2} \varrho^{-2}\right) \varepsilon^{1 / 2}-2 d y_{1} \varrho\right)$, hence $I\left(u ; x_{0}, x_{3}\right)<0$ if $\varepsilon$ is sufficiently small. It is clear that the same values $x_{0}, x_{3}$ can be chosen for each $k \in\{1, \ldots, n\}$, hence by Lemma 1 the equation (1.2) possesses a nontrivial solution having at least $(n+1)$ zeros on $\left[x_{0}, x_{3}\right] \subset \mathbb{R}$. The proof is complete.

In the theorem we have just proved we suppose that $I=(a, b)=(-\infty, \infty)$. If both $a$ and $b$ are finite, to find a condition which guarantees the existence of
a nontrivial solution of (1.2) with at least $n+1$ zeros is simple since in this case one can directly compute the eigenvalues and eigenfunctions of the operator $-y^{\prime \prime}$ on $W^{1,2}[a, b]$. Particularly, $\lambda_{k}=(k \pi)^{2} /(b-a)^{2}, y_{k}=\sin \lambda_{k}^{1 / 2}(x-a)$. If one of $a, b$, is infinite, say $b$, we need to compute the eigenfunctions and cigenvalues of the minimal closed symmetric extension of $(2.2)$ on $(a, \infty)$. To this end we use the transformation $y(x)=\left(1+x^{2}\right)^{1 / 2} u(t), t=\operatorname{arctg} x$, which transforms (2.2), considered on $[a, \infty)$, into the operator $\tilde{l}(u)=\ddot{u}+u(\cdot=\mathrm{d} / \mathrm{d} t)$, considered on $[\operatorname{arctg} a, \pi / 2)$. Now, it suffices to compute the eigenvalues and eigenfunctions of $\tilde{l}(u)$ on $W^{1,2}[\operatorname{arctg} a, \pi / 2]$ and to transform them "back" into $(2.2)$ on $[a, \infty)$. As a result we get the following reformulation of Theorem 1.

THEOREM 1'. Suppose that $p(x)-\lambda_{k}\left(1+x^{2}\right)^{-1} \not \equiv \equiv 0$ on $I=(a, \infty)$ and

$$
\liminf _{t_{2} \mid \infty} \int_{a}^{t_{2}}\left(p(x)-\lambda_{k}\left(1+x^{2}\right)^{-1}\right) y_{k}(x) \mathrm{d} x \geq 0, \quad k=1, \ldots, n,
$$

where $\lambda_{k}=4 \pi^{2} k^{2}(\pi-2 \operatorname{arctg} a)^{-2}-1, y_{k}=\left(1+x^{2}\right)^{1 / 2} \sin \frac{2 k \pi}{\pi-2 \operatorname{arctg} a}$. $(\operatorname{arctg} x-\operatorname{arctg} a)$. Then (1.2) has a nontrivial solution with at least $(n+1)$ zeros on $(a, \infty)$.

## 3. The existence of two zero points

In this section we present an improved version of the conjugacy criterion given by (1.6). In the form given here it offers a unified approach to the investigation of the conjugacy of (1.2) on an arbitrary interval.

Theorem 2. Suppose that there exist $\varepsilon_{1}, \varepsilon_{2}>0$ and $c \in(a, b)$ such that

$$
\begin{align*}
& \varepsilon_{1} \int_{c}^{b} \exp \left\{2 \int_{c}^{x}\left[\int_{c}^{t} p(s) \mathrm{d} s-\varepsilon_{1}\right] \mathrm{d} t\right\} \mathrm{d} x>A  \tag{3.1}\\
& \varepsilon_{2} \int_{a}^{c} \exp \left\{2 \int_{c}^{x}\left[\int_{c}^{t} p(s) \mathrm{d} s+\varepsilon_{2}\right] \mathrm{d} t\right\} \mathrm{d} x>B .
\end{align*}
$$

If

$$
\begin{equation*}
\varepsilon_{1}+\varepsilon_{2}-\pi\left(\varepsilon_{1} B+\varepsilon_{2} A\right) / 2 A B \geq 0 \tag{3.2}
\end{equation*}
$$

then (1.2) is conjugate on $(a, b)$.
Proof. Denote $c_{R}=\varepsilon_{1}(1-\pi / 2 A), c_{L}=\varepsilon_{2}(\pi / 2 B-1)$. Let $y_{1}, z_{1}$ be the solutions of (1.2) given by the initial condition $y_{1}(c)=1=z_{1}(c), y_{1}^{\prime}(c)=c_{R}$,

## ONDŘEJ DOSLÝ

$z_{1}^{\prime}(c)=\varepsilon_{1}$. Suppose that the function $y_{1}(x)$ does not vanish on $(c, b)$. Then the function $\alpha(x)=\operatorname{arctg}\left(z_{1} / y_{1}\right)$ is well defined on $(c, b), \alpha(c)=\pi / 4, \alpha(b-) \leq \pi / 2$ and $\alpha^{\prime}=\varepsilon_{1} \pi / 2 A\left(y_{1}^{2}+z_{1}^{2}\right)$. For $x \in(c, b)$ we have $z_{1}(x)>y_{1}(x)>0$ and the function $w=z_{1}^{\prime} / z_{1}$ is a solution of the Riccati equation $w^{\prime}+w^{2}+p(x)=0$, i.e., $w(x)=w(c)-\int_{c}^{x} p(s) \mathrm{d} s-\int_{c}^{x} w^{2}(s) \mathrm{d} s$ and hence
$z_{1}(x)=\exp \left\{\int_{c}^{x}\left(\varepsilon_{1}-\int_{c}^{t}\left(p+w^{2}\right)\right) \mathrm{d} t\right\} \leq \exp \left\{\int_{c}^{x}\left(\varepsilon_{1}-\int_{c}^{t} p\right) \mathrm{d} t\right\} \quad$ for $x>c$.

It follows

$$
\begin{aligned}
\alpha(b-) & =\alpha(c)+\int_{c}^{b} \alpha^{\prime} \\
& =\pi / 4+\varepsilon_{1}(\pi / 2 A) \int_{c}^{b}\left(y_{1}^{2}+z_{1}^{2}\right)^{-1} \mathrm{~d} x \geq \pi / 4+\varepsilon_{1}(\pi / 2 A) \int_{c}^{b}\left(2 z_{1}^{2}\right)^{-1} \mathrm{~d} x \\
& >\pi / 4+\varepsilon_{1}(\pi / 4 A) \int_{c}^{b} \exp \left\{2 \int_{c}^{x}\left[\int_{c}^{t} p-\varepsilon_{1}\right] \mathrm{d} t\right\} \mathrm{d} x \geq \pi / 4+\pi / 4=\pi / 2
\end{aligned}
$$

a contradiction. Let $y_{2}, z_{2}$ be the solutions of (1.2) given by the initial condition $y_{2}(c)=1=z_{2}(c), y_{2}^{\prime}(c)=c_{L}, z_{2}^{\prime}(c)=-\varepsilon_{2}$. Similarly as above we get a contradiction supposing that $y_{2}(x)>0$ on $(a, c)$. Now, let $y(x)$ be a solution of (1.2) given by the initial condition $y(c)=1, y^{\prime}(c)=\gamma \in\left[c_{L}, c_{R}\right]$. According to the Sturm separation theorem for zeros of linearly independent solutions of (1.2), $y(x)$ has zero points in both intervals $(a, c)$ and $(c, b)$. This completes the proof.

Let us relate the result of Theorem 2 to some recent ones. First, if $A=$ $(\pi / 2)=B$, it is easy to see that (3.1) is more general than (1.6). Tipler proved in [12] that equation (1.2) is conjugate on an interval $\left[x_{0}, \infty\right)$ provided $p(x) \geq 0$ on $\left[x_{0}, \infty\right)$ and there exist $x_{1}, x_{2} \in\left(x_{0}, \infty\right), x_{1}<x_{2}$ such that $\int_{x_{1}}^{x_{2}} p(x) \mathrm{d} x>\left(x_{1}-x_{0}\right)^{-1}$. Next we show that this criterion can be obtained as a corollary of Theorem 2. Let $a=x_{0}, b=\infty$ and $c>x_{2}$ be arbitrary for a moment. Since $p(x) \geq 0$ on $\left[x_{0}, \infty\right)$, by the Sturm comparison theorem the statement will be proved to be a corollary of Theorem 2 if we prove it for a
function $\tilde{p}(x)$ such that $\tilde{p}(x)=p(x)$ for $x \in\left[x_{0}, x_{2}\right]$ and $\tilde{p}(x) \equiv 0$ for,$x \geq x_{2}$. Let $\varepsilon_{1}>0$ be arbitrary, we have

$$
\varepsilon_{1} \int_{c}^{\infty} \exp \left\{2 \int_{c}^{x}\left[\int_{c}^{t} \tilde{p}-\varepsilon_{1}\right] \mathrm{d} t\right\} \mathrm{d} x \geq \varepsilon_{1} \int_{c}^{\infty} \exp \left\{-2 \varepsilon_{1}(x-c)\right\} \mathrm{d} x=1 / 2
$$

For any $\varepsilon_{2}>0$ we have

$$
\begin{array}{r}
\varepsilon_{2} \int_{x_{0}}^{c} \exp \left\{2 \int_{c}^{x}\left[\int_{c}^{t} \tilde{p}+\varepsilon_{2}\right] \mathrm{d} t\right\} \mathrm{d} x \geq \varepsilon_{2} \int_{x_{0}}^{c} \exp \left\{2(x-c)\left[\int_{x_{1}}^{x_{2}} p-\varepsilon_{2}\right]\right\} \mathrm{d} x \\
=\varepsilon_{2}\left(\int_{x_{1}}^{x_{2}} p-\varepsilon_{2}\right)^{-1}\left[\exp \left\{2\left[\int_{x_{1}}^{x_{2}} p-\varepsilon_{2}\right]\left(c-x_{0}\right)\right\}-1\right]
\end{array}
$$

The inequality (3.2) can be written in the form $\varepsilon_{1}(1-\pi / 2 A)+\varepsilon_{2}(1-\pi / 2 B) \geq 0$. Since $A \geq 1 / 2$ independently of $\varepsilon_{1}$, letting $\varepsilon_{1} \rightarrow 0$ it suffices to show that the term $\varepsilon_{2}(1-\pi / 2 B)$ is positive for some $\varepsilon_{2}>0$. But this is the case if $\varepsilon_{2}=\left(x_{1}-x_{0}\right)^{-1}$ and $c \rightarrow \infty$, since then $B \rightarrow \infty$ and thus $(1-\pi / 2 B)$ is positive.

## Remarks

i) Consider the partial differential equation

$$
\begin{equation*}
\Delta_{n} u+q(x) u=0 \tag{4.1}
\end{equation*}
$$

where $\Delta_{n}=\sum_{i=1}^{n} \partial^{2} / \partial x_{i}^{2}$ is the $n$-dimensional Laplace operator, $x=\left(x_{1}, \ldots, x_{n}\right)$ and $q(x)$ is a locally Lipschitz continuous real-valued function defined on $\mathbb{R}^{n}$. A bounded domain $G \subset \mathbb{R}^{n}$ is said to be a nodal domain of (4.1) if there exists a nontrivial solution $u$ of (4.1) for which $u \in \stackrel{\circ}{W}^{1,2}(G) \cap W^{2,2}(G)$ (the Sobolev spaces $W^{1,2}(G), W^{2,2}(G)$ are defined similarly as in the one-dimensional case). It is known (see, e.g, [10]) that a ball $B_{R}=\left\{x \in \mathbb{R}^{n},|x|=\left(\sum x_{i}^{2}\right)^{1 / 2} \leq R\right\}$ contains a nodal domain of (4.1) if there exists a nontrivial function $v \in \stackrel{\circ}{W}^{1,2}\left(B_{R}\right)$ such that

$$
\begin{equation*}
\int_{B_{R}}\left(|\nabla v(x)|^{2}-q(x) v^{2}(x)\right) \mathrm{d} x \leq 0 \tag{4.2}
\end{equation*}
$$

## ONDŘEJ DOSLÝ

Denote $\tilde{q}(r)=\int_{|x|=r} q(x) \mathrm{d} \omega$, where $\omega$ is the surface of the sphere $S_{r}^{n-1}=$ $\left\{x \in \mathbb{R}^{n},|x|=r\right\}$, in $\mathbb{R}^{n}$. If the function $v=v(r)$ is radially symmetric, we have $\int_{B_{R}}\left(|\nabla v|^{2}+q v^{2}\right) \mathrm{d} x=\int_{0}^{R}\left(r^{n-1}\left(\frac{\mathrm{~d}}{\mathrm{~d} r} v\right)^{2}+\tilde{q}(r) v^{2}\right) \mathrm{d} r$. Using this substitution one can apply the results concerning the zero points of solutions of ordinary differential equations while investigating the problem of the existence of a nodal domain and negative eigenvalues of the Schrödinger partial differential operators. We hope to follow this idea in more detail elsewhere.
ii) Let us try to extend the method introduced in Section 2 to the higher order self-adjoint linear differential equation

$$
\begin{equation*}
(-1)^{n}\left(r(x) y^{(n)}\right)^{(n)}+p(x) y=0 \tag{4.3}
\end{equation*}
$$

where $r \in C^{n}, r>0, p \in C, x \in I=(a, b),-\infty \leq a<b \leq \infty$. For the sake of simplicity consider, as a model, the fourth order equation

$$
\begin{equation*}
y^{(i v)}+p(x) y=0 . \tag{4.4}
\end{equation*}
$$

It was proved in [9] that this equation possesses a nontrivial solution having at least two conjugate points on $\mathbb{R}$ (i.e., the points $x_{1}, x_{2} \in \mathbb{R}$ such that $y^{(i)}\left(x_{1}\right)=$ $0=y^{(i)}\left(x_{2}\right), i=0,1$, for some nontrivial solution $y$ of (4.4)), whenever there exist $c_{1}, c_{2} \in \mathbb{R}$ such that

$$
\begin{equation*}
\limsup _{t_{1} \downarrow-\infty, t_{2} \uparrow \infty} \int_{t_{1}}^{t_{2}} p(x)\left(c_{1} x+c_{2}\right)^{2} \mathrm{~d} x<0 \tag{4.5}
\end{equation*}
$$

Now, find a condition on the function $p(x)$ which would guarantee the existence of a nontrivial solution of (4.4) with 3 or more conjugate points on $\mathbb{R}$. In the case of the second-order equation we proceeded as follows: The transformation $y=$ $\left(1+x^{2}\right)^{1 / 2} u$ transformed (1.2) into the equation $\left(\left(1+x^{2}\right) u^{\prime}\right)^{\prime}+\left(1+x^{2}\right)^{-1} u=0$. Then we took the equation $\left(k^{-1}\left(1+x^{2}\right) u^{\prime}\right)^{\prime}+k\left(1+x^{2}\right)^{-1} u=0, k=2,3, \ldots, n$, and transforming it "back" we got the equation $y^{\prime \prime}+\left(k^{2}-1\right)\left(1+x^{2}\right)^{-2} y=0$ which we used in Theorem_1.

Let us try to modify this method to be applicable to the equation (4.3). This equation can be written in the form of the linear Hamiltonian system

$$
\begin{equation*}
\boldsymbol{u}^{\prime}=\mathbf{A} \boldsymbol{u}+\mathbf{B}(x) \boldsymbol{v}, \quad \boldsymbol{v}^{\prime}=\mathbf{C}(x) \boldsymbol{u}-\mathbf{A}^{\top} \boldsymbol{v} \tag{4.6}
\end{equation*}
$$

where $\mathbf{A}, \mathbf{B}, \mathbf{C}$ are $n \times n$ matrices with entries $\mathbf{A}=\mathbf{A}_{i, j}=1$ if $j=i+1, i=$ $1, \ldots, n-1$, all the other entries of $\mathbf{A}$ equal $0, \mathbf{B}(x)=\operatorname{diag}\left\{0, \ldots, \dot{0}, r^{-1}(x)\right\}$, $\mathbf{C}(x)=\operatorname{diag}\{p(x), 0, \ldots, 0\}, \boldsymbol{u}=\operatorname{col}\left(y, \ldots, y^{(n-1)}\right), \quad v=\operatorname{col}\left((-1)^{n-1}\right.$. $\left.\left(r y^{(n)}\right)^{(n-1)},(-1)^{n-2}\left(r y^{(n)}\right)^{(n-2)}, \ldots, r y^{(n)}\right)$.

It was shown in [4] that there exist $n \times n$ matrices $\mathbf{H}(x), \mathbf{K}(x), \mathbf{H}(x)$ being nonsingular, such that the transformation

$$
\begin{equation*}
\mathbf{u}=\mathbf{H} \boldsymbol{s}, \quad \mathbf{v}=\mathbf{K} \boldsymbol{s}+\left(\mathbf{H}^{\top}\right)^{-1} \mathbf{c} \tag{4.7}
\end{equation*}
$$

transforms (4.6) into the so-called trigonometric system

$$
\begin{equation*}
\boldsymbol{s}^{\prime}=\mathbf{Q}(x) \mathbf{c}, \quad \boldsymbol{c}^{\prime}=-\mathbf{Q}(x) \boldsymbol{s} \tag{4.8}
\end{equation*}
$$

where $\mathbf{Q}=\mathbf{H}^{-1} \mathbf{B}\left(\mathbf{H}^{\top}\right)^{-1}, \mathbf{H} \mathbf{H}^{\top}=\mathbf{U}_{1} \mathbf{U}_{1}^{\top},+\mathbf{U}_{2} \mathbf{U}_{2}^{\top},\left(\mathbf{U}_{1}, \mathbf{V}_{1}\right),\left(\mathbf{U}_{2}, \mathbf{V}_{2}\right)$ are the $2 n \times n$ matrix solutions of (4.6) for which $\mathbf{U}_{\boldsymbol{i}}^{\top} \mathbf{V}_{\boldsymbol{i}}-\mathbf{V}_{i}^{\top} \mathbf{U}_{\boldsymbol{i}}=\mathbf{O}, i=1,2$ and $\mathbf{U}_{1}^{\top} \mathbf{V}_{2}-\mathbf{V}_{1}^{\top} \mathbf{U}_{2}=\mathbf{I}$ - the identity matrix.

If system (4.6) corresponds to the equation $y^{(i v)}=0$, i.e., $\mathbf{A}=\left(\begin{array}{ll}0 & 1 \\ 0 & 0\end{array}\right)$, $\mathbf{B}=\operatorname{diag}\{0,1\}, \mathbf{C}=\mathbf{O}$, the matrices $\mathbf{H}, \mathbf{K}, \mathbf{Q}$ can be computed explicitly, see [8] and also [5] for a more detailed comment concerning the computation of these matrices. Particularly, we have

$$
\mathbf{H H}^{\top}=\left(\begin{array}{cc}
1+x^{2}+x^{4} / 4+x^{6} / 36 & x+x^{3} / 2+x^{5} / 12 \\
x+x^{3} / 2+x^{5} / 12 & 1+x^{2}+x^{4} / 4
\end{array}\right) .
$$

One can verify directly that the transformation (4.7) with $k^{-1 / 2} \mathbf{H}, k^{-1 / 2} \mathbf{K}$, $k \in \mathbb{N}$, instead of $\mathbf{H}, \mathbf{K}$, transforms the trigonometric system (4.8), with $k \mathbf{Q}$ instead of $\mathbf{Q}$, into the Hamiltonian system

$$
\begin{equation*}
\boldsymbol{u}^{\prime}=\mathbf{A} \boldsymbol{u}+\mathbf{B} \boldsymbol{v}, \quad \boldsymbol{v}^{\prime}=\left(1-k^{2}\right)\left(\mathbf{H} \mathbf{H}^{\top}\right)^{-1} \mathbf{B}\left(\mathbf{H} \mathbf{H}^{\top}\right)^{-1} \boldsymbol{u}-\mathbf{A}^{\top} \boldsymbol{v} \tag{4.9}
\end{equation*}
$$

Denote $f(x)=\left(\mathbf{H H}^{\top}\right)_{12}, g(x)=\left(\mathbf{H H}^{\top}\right)_{22}$, then (4.9) is equivalent to the fourth order equation

$$
\begin{equation*}
y^{(i v)}+\left(k^{2}-1\right)\left[-\left(g^{2} y^{\prime}+f g y\right)+f g y^{\prime}+f^{2} y\right]=0 \tag{4.10}
\end{equation*}
$$

and the corresponding quadratic functional is of the form

$$
\int_{a}^{b}\left(y^{\prime \prime 2}+\left(k^{2}-1\right)\left(f y+g y^{\prime}\right)^{2}\right) \mathrm{d} x
$$

The main difficulty which prevents us to extend directly the "second-order method" to fourth order equations is the fact that we do not know solutions of (4.10), i.e., we do not know the eigenfunctions corresponding to higher eigenvalues of the operator associated with the operator $d^{4} / d x^{4}$. For second order equations we computed the eigenfunctions of (2.2) corresponding to the eigenvalues $\left(k^{2}-1\right)$ via the transformation $y=k^{-1 / 2}\left(1+x^{2}\right)^{1 / 2} u$ which transforms the equation $\left(k^{-1}\left(1+x^{2}\right) u^{\prime}\right)^{\prime}+k\left(1+x^{2}\right)^{-1} u=0$ into the equation $l(y)=\left(k^{2}-1\right) y$ (the operator $l$ is given by (2.2)). Here, even if we know the solution of the trigonometric system (4.8) corresponding to the equation $y^{(i v)}=0$ (this trigonometric system is a higher order analogy of the equation $\left.\left(\left(1+x^{2}\right) u^{\prime}\right)^{\prime}+\left(1+x^{2}\right)^{-1} u=0\right)$, we do not know the solution of this system with $k \mathbf{Q}$ instead of $\mathbf{Q}$, thus we cannot use this method in order to compute solutions of (4.10).

We may also formulate some further problems. For example, the linear Hamiltonian system corresponding to the equation $y^{(i v)}=0$ is 0 -general in the terminology introduced in [3] (i.e., the principal solutions of the corresponding linear Hamiltonian system at $-\infty$ and $\infty$ coincide). Since the transformation (4.7) transforms principal solutions into principal solutions, the associated trigonometric system (4.8) has the same property. Has the trigonometric system (4.8) with $k \mathbf{Q}, k=2,3, \ldots$ also this property? It is not difficult to verify that in the second order case the answer is affirmative.

The solution of these problems would be very useful in extending the knowledge of the oscillation and the spectral properties of higher order self-adjoint differential equations.

## REFERENCES

[1] BORU゚VKA, O.: Lineare Differentialtransformationen 2. Ordnung, VEB, Deutscher Verlag der Wissenschaften, Berlin, 1971.
[2] COURANT, R.-HILBERT, D.: Methods of Mathematical Physics. Vol. I, Interscience, New York, 1953.
[3] DOŠLÝ, O.: Riccati matrix differential equation and classification of disconjugate differcntial systems, Arch. Math. (Brno) 23 (1988), 231-242.
[4] D()ŠLY, O.: On transformation of self-adjoint differential systems and their reciprocals, Amn. Polon. Math. 50 (1990), 223--234.
[5] IOŠLY, O.: On some problems in oscillation theory of self-adjoint linear differential equations, Math. Slovaca 41 (1991), 101-111.
[6] DOŠL $\dot{Y}, \mathrm{O}$ : Conjugacy criteria for second order differential equations, Rocky Mountain J. Math., (To appear).
[7] HAWKIN(i, S. W.--PENROSE, R : The singularities of gravity collapse and insmology. Proc. Roy. Soc. London Ser A 314 1970 $\because \cdot 548$

## THE MULTIPLICITY CRITERIA FOR ZERO POINTS...

[8] MACHÁT, J.: Phase matrix of self-adjoint linear differcntial cquations. (Czech.), Thesis, Brno, 1989.
[9] MÜLLER-PFEIFFER, E.: Existence of conjugate points for second and fourth order differential equations, Proc. Roy. Soc. Edimburgh Sect. A 89 (1981), 281 291.
[10] MÜLLER-PFEIFFER, E.: On the existence of nodal domains for elliptic: duffcrential operators, Proc. Roy. Soc. Edinburgh Sect. A 94 (1983), 287-299.
[11] MÜLLER-PFEIFFER, E.: Nodal domains of one- or tuo-dimenszonal cllaptic: differential equations, Z. Anal. Anwendungen 7 (1988), 135-139.
[12] TIPLER, F. J.: General relativity and conjugate ordinary differential equatzons, J. Differential Equations 30 (1978), 165174.
[13] WEIDMAN, J.: Linear Operators in Hilbert Spaces, Springer-Verlag, New York-Berlin, 1982.


[^0]:    AMS Subject Classification (1991): Primary 34C10.
    Key words: Conjugate points, Principal solution, Linear Hamiltonian system.

