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# REGULARITY OF PRESSURE IN THE NEIGHBOURHOOD OF REGULAR POINTS OF WEAK SOLUTIONS OF THE NAVIER-STOKES EQUATIONS* 

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Abstract. In the context of the weak solutions of the Navier-Stokes equations we study the regularity of the pressure and its derivatives in the space-time neighbourhood of regular points. We present some global and local conditions under which the regularity is further improved.

Keywords: Navier-Stokes equations, regularity of weak solutions, regular and singular points

MSC 2000: 35Q35, 35Q30

## Introduction

Let $\Omega$ be either $\mathbb{R}^{3}$ or a bounded domain in $\mathbb{R}^{3}$ with $\mathcal{C}^{2+\mu}$ boundary $\partial \Omega(\mu>0)$, $T>0$ and $Q_{T}=\Omega \times(0, T)$. In $Q_{T}$ we deal with the Navier-Stokes equations

$$
\begin{gather*}
\frac{\partial u}{\partial t}-\nu \cdot \Delta u+(u \cdot \nabla) u+\nabla \mathcal{P}=0  \tag{1}\\
\nabla \cdot u=0  \tag{2}\\
u(x, 0)=u_{0} \tag{3}
\end{gather*}
$$

and (if $\Omega$ is a bounded domain)

$$
\begin{equation*}
u=0 \quad \text { on } \partial \Omega \times(0, T), \tag{4}
\end{equation*}
$$

where $u=\left(u_{1}, u_{2}, u_{3}\right)$ and $\mathcal{P}$ denote the velocity and pressure and $\nu>0$ is the viscosity coefficient.

[^0]As is usual in the standard theory of the Navier-Stokes equations, define $D(\Omega)=$ $\left\{\psi \in C_{0}^{\infty}(\Omega)^{3} ; \nabla \cdot \psi=0\right.$ in $\left.\Omega\right\}$ and let $H(\Omega)$ and $V(\Omega)$ be the completion of $D(\Omega)$ in $L^{2}(\Omega)^{3}$ and $W^{1,2}(\Omega)^{3}$, respectively. Define also $D_{T}=\left\{\eta \in C_{0}^{\infty}(\Omega \times[0, T))^{3} ; \nabla \cdot \eta=\right.$ 0 in $\Omega \times[0, T)\}$.

Definition 1. Let $u_{0} \in H(\Omega)$. A measurable function $u: Q_{T} \rightarrow \mathbb{R}^{3}$ is called a weak solution of the problem (1)-(4) if $u \in L^{2}(0, T, V(\Omega)) \cap L^{\infty}(0, T, H(\Omega))$ and

$$
\int_{0}^{T} \int_{\Omega}\left[u \cdot \frac{\partial \eta}{\partial t}-\nu \nabla u \cdot \nabla \eta-u \cdot \nabla u \cdot \eta\right] \mathrm{d} x \mathrm{~d} t=-\int_{\Omega} u_{0} \cdot \eta(\cdot, 0) \mathrm{d} x
$$

for all $\eta \in D_{T}$.
The existence of a weak solution of (1)-(4) was proved in many articles (see e.g. [1], [3] or [9]). However, the problem of regularity and uniqueness of weak solutions has not yet been solved. It is not known whether weak solutions obtained by different methods coincide or not. Let us point out that if not stated explicitly we do not consider any concrete weak solution (constructed, for example, by the Faedo-Galerkin method-see [9]) in this chapter but all the conclusions hold for any weak solution from Definition 1.

We say that a point $\left(x_{0}, t_{0}\right) \in Q_{T}$ is a regular point of $u$ if there exists a neighbourhood $\mathcal{U}$ of $\left(x_{0}, t_{0}\right)$ in $Q_{T}$ such that $u \in L^{\infty}(\mathcal{U})^{3}$.

Let $\left(x_{0}, t_{0}\right) \in Q_{T}$ be a regular point. In this paper we are mainly interested in the smoothness of the time derivative $\partial u / \partial t$ in a neighbourhood of $\left(x_{0}, t_{0}\right)$. More precisely, we ask whether $\partial u / \partial t \in C\left(Q^{\prime}\right)^{3}$, where $Q^{\prime}=B_{\delta}\left(x_{0}\right) \times\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ and $\delta, \varepsilon$ are some positive numbers. The problem was already studied in [5] where it was concluded (among other) that

$$
\begin{equation*}
\frac{\partial u}{\partial t} \in C\left(Q^{\prime}\right)^{3} \tag{5}
\end{equation*}
$$

To prove this result (see Theorem 7 in [5]) the author used the second part of the Main Theorem from [7]. He verified all the necessary assumptions, particularly $\partial u / \partial t \in L^{4 / 3}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{2}\left(B_{\delta}\left(x_{0}\right)\right)^{3}\right)$ for some $\varepsilon, \delta>0$ and concluded finally that (5) is an immediate consequence of the Main Theorem. Unfortunately, in our opinion, it is not the case. In fact, Serrin's theorem does not yield such a strong regularity of $\partial u / \partial t$ in $Q^{\prime}$ and therefore, we still consider the question mentioned above an open problem. Its solution would be useful in the study of the local regularity of solutions of the Navier-Stokes equations.

We begin the next chapter with the presentation of a few observations concerning the regularity of $\partial u / \partial t$ and $\mathcal{P}$ near regular points-Theorem 2 and Theorem 4. We stress that due to the non-existence of the boundary the results for $\Omega=\mathbb{R}^{3}$ are
stronger than those for a bounded $\Omega$. Next, we present some simple (global and local) additional conditions on $u$ and $\mathcal{P}$ under which the regularity of $\partial u / \partial t$ and $\mathcal{P}$ in the neighbourhood of a regular point of $u$ can be improved.

## 1. Discussion of known results

Let us start with some obvious properties of weak solutions of (1)-(4) in a spacetime neighbourhood of regular points which follow from [7] and [5].

Thus, let $\left(x_{0}, t_{0}\right) \in Q_{T}$ be a regular point of $u$. Then there exist $\varepsilon, \delta>0, Q^{\prime}=$ $B_{\delta}\left(x_{0}\right) \times\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ such that
(i) $u(\cdot, t) \in C^{\infty}\left(B_{\delta}\left(x_{0}\right)\right)^{3}$ for almost every $t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ and every space derivative of $u$ is bounded in compact subregions of $Q^{\prime}$ (see [7]);
(ii) $\partial u / \partial t \in L^{4 / 3}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{2}\left(B_{\delta}\left(x_{0}\right)\right)^{3}\right)($ see [5]);
(iii) $D_{x}^{\gamma} u(x, \cdot)$ are absolutely continuous functions of time in $\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ for almost every $x \in B_{\delta}\left(x_{0}\right)$ and every multi-index $\gamma=\left(\gamma_{1}, \gamma_{2}, \gamma_{3}\right)$, where $D_{x}^{\gamma}=$ $\partial^{|\gamma|} /\left(\partial x_{1}^{\gamma_{1}} \ldots \partial x_{3}^{\gamma_{3}}\right),|\gamma|=\gamma_{1}+\gamma_{2}+\gamma_{3}($ see $[7])$.
It follows from (i) that the functions $D_{x}^{\gamma} u(\cdot, t), t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right) \backslash \mathcal{A}$, where $\mathcal{A}$ is a subset of $\mathbb{R}$ of Lebesgue measure 0 , are uniformly bounded and uniformly continuous in $\left(\overline{B_{\delta_{1}}\left(x_{0}\right)}\right)^{3}$ for every $\delta_{1} \in(0, \delta)$. Using the Arzelà-Ascoli theorem and the weak continuity of $u$ as a function from $\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ into $L^{2}\left(B_{\delta}\left(x_{0}\right)\right)$, we get that

$$
\begin{equation*}
u(\cdot, t) \in C^{\infty}\left(B_{\delta}\left(x_{0}\right)\right)^{3} \text { for every } t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right) \tag{6}
\end{equation*}
$$

and $D_{x}^{\gamma} u$ are continuous functions in $B_{\delta}\left(x_{0}\right) \times\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ for every $\gamma$.
In the following two theorems we present further results on regularity of space derivatives of pressure and space derivatives of the time derivative of velocity. Since we have no information concerning the behavior of the pressure derivatives on $\partial \Omega$, we use the cut-off function technique (see e.g. [5]). Therefore, the results are determined by the initial global regularity of pressure as presented in [8] or [6]. The second theorem is stated exclusively for $\Omega=\mathbb{R}^{3}$. In this case we use the integral representation of $\mathcal{P}$ (see [1]) which holds for any weak solution. It is interesting that due to the non-existence of the boundary $\partial \Omega$, Theorem 4 gives stronger results than Theorem 2.

Theorem 2. Let $\Omega \subset \mathbb{R}^{3}$ be a bounded domain with a smooth boundary or $\Omega=R^{3}$, let $u$ be a weak solution of (1)-(4) and $\mathcal{P}$ the associated pressure. Let further $\left(x_{0}, t_{0}\right) \in Q_{T}$ be a regular point of $u$ and $\varepsilon, \delta$ the numbers from (i), (ii) and (iii). Then $D_{x}^{\gamma} \partial u / \partial t, D_{x}^{\gamma} \mathcal{P} \in L^{\alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)$ for every multi-index $\gamma,|\gamma| \geqslant 0, \delta_{1} \in(0, \delta)$ and $\alpha \in(1,2)$.

Proof. Let $\delta_{1} \in(0, \delta)$ and $\alpha \in(1,2)$. As follows from [8] or [6] we can suppose that $\mathcal{P} \in L^{r}\left(\xi, T, L^{s}\left(\Omega_{1}\right)\right)$ for every $\xi>0$ provided $\Omega_{1} \subset \Omega$ is a bounded domain, $2 / r+3 / s=3, r \in(1,2)$ and $s \in(3 / 2,3)$. Thus, we have

$$
\begin{equation*}
\mathcal{P} \in L^{\alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{1}\left(B_{\delta}\left(x_{0}\right)\right)\right) . \tag{7}
\end{equation*}
$$

Let $\varphi \in C^{\infty}\left(\mathbb{R}^{3}\right)$,
(8) $\varphi \in\langle 0,1\rangle$ in $\mathbb{R}^{3}, \varphi \equiv 1$ in $B_{\left(2 \delta_{1}+\delta\right) / 3}\left(x_{0}\right)$ and $\varphi \equiv 0$ in $\mathbb{R}^{3} \backslash B_{\left(2 \delta+\delta_{1}\right) / 3}\left(x_{0}\right)$.

For almost every $t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right.$ and for every $x \in B_{\delta_{1}}\left(x_{0}\right)$ it is possible to write

$$
\begin{align*}
\mathcal{P}(x, t)= & (\varphi \mathcal{P})(x, t)=\frac{1}{4 \pi} \int_{\Omega} \frac{1}{|x-y|} \varphi(y) \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y  \tag{9}\\
& +\frac{1}{4 \pi} \int_{\Omega} \frac{1}{|x-y|} \mathcal{P}(y, t) \Delta \varphi(y) \mathrm{d} y+\frac{1}{2 \pi} \int_{\Omega} \frac{x-y}{|x-y|^{3}} \nabla \varphi(y) \mathcal{P}(y, t) \mathrm{d} y \\
= & p_{1}(x, t)+p_{2}(x, t)+p_{3}(x, t)
\end{align*}
$$

Using (i), (8) and the equality

$$
\frac{\partial}{\partial x_{k}} \frac{1}{|x-y|}=-\frac{\partial}{\partial y_{k}} \frac{1}{|x-y|},
$$

we see that

$$
\begin{equation*}
\frac{\partial p_{1}}{\partial x_{k}}(x, t)=\frac{1}{4 \pi} \int_{\Omega} \frac{1}{|x-y|} \frac{\partial}{\partial y_{k}}\left(\varphi(y) \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t)\right) \mathrm{d} y, \quad k=1,2,3 \tag{10}
\end{equation*}
$$

and the following conclusion can be derived from (10) and (i):

$$
\begin{equation*}
\nabla p_{1} \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right) \tag{11}
\end{equation*}
$$

Differentiating further (10), we obtain

$$
\begin{equation*}
D_{x}^{\gamma} p_{1} \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right) \tag{12}
\end{equation*}
$$

for every $\gamma$. Using (7), (8) and the facts that

$$
\nabla \varphi \equiv 0 \text { on } B_{\left(2 \delta_{1}+\delta\right) / 3}\left(x_{0}\right) \cup\left(\mathbb{R}^{3} \backslash B_{\left(2 \delta+\delta_{1}\right) / 3}\left(x_{0}\right)\right)
$$

and

$$
\frac{1}{|x-y|} \in C^{\infty}\left(\mathbb{R}^{3} \backslash\{x\}\right),
$$

we get by differentiating the last two integrals in (9) that

$$
\begin{equation*}
D_{x}^{\gamma} p_{2}, D_{x}^{\gamma} p_{3} \in L^{\alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right) . \tag{13}
\end{equation*}
$$

It follows from (12) and (13) that

$$
\begin{equation*}
D_{x}^{\gamma} \mathcal{P} \in L^{\alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right) \tag{14}
\end{equation*}
$$

Finally, using (i), (1) and (14), we conclude that

$$
D_{x}^{\gamma} \frac{\partial u}{\partial t} \in L^{\alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)
$$

and the proof is complete.
Remark 3. Suppose that the assumptions of Theorem 2 are satisfied and $\mathcal{P} \in$ $L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{1}\left(B_{\delta}\left(x_{0}\right)\right)\right), \beta \in\langle 2, \infty\rangle$. Then the proof of Theorem 2 gives that $D_{x}^{\gamma} p_{2}, D_{x}^{\gamma} p_{3} \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)$ and consequently $D_{x}^{\gamma} \partial u / \partial t, D_{x}^{\gamma} \mathcal{P} \in$ $L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)$.

Since $D_{x}^{\gamma} \partial u / \partial t \in L^{\alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)$, we have

$$
\begin{align*}
& \int_{t_{0}-\varepsilon}^{t_{0}+\varepsilon} \underset{x \in B_{\delta_{1}}\left(x_{0}\right)}{\operatorname{ess} \sup _{x}}\left|D_{x}^{\gamma} \frac{\partial u}{\partial t}(x, t)\right|^{\alpha} \mathrm{d} t  \tag{15}\\
& \quad=\left\|D_{x}^{\gamma} \frac{\partial u}{\partial t}\right\|_{L^{\alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)}^{\alpha}=c^{\alpha}<\infty .
\end{align*}
$$

It follows from (15), (i) and (iii) that

$$
\underset{x \in B_{\delta_{1}}\left(x_{0}\right)}{\operatorname{ess} \sup _{x}}\left\{\left\|D_{x}^{\gamma} u(x, \cdot)\right\|_{W^{1, \alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)}\right\} \leqslant c<\infty .
$$

Therefore, using also the continuity of $D_{x}^{\gamma} u$ in $Q^{\prime}$ and the reflexivity of the space $W^{1, \alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$, we get that

$$
\begin{equation*}
D_{x}^{\gamma} u(x, \cdot) \in W^{1, \alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right) \text { for every } x \in B_{\delta_{1}}\left(x_{0}\right) \tag{16}
\end{equation*}
$$

and

$$
\sup _{x \in B_{\delta_{1}}\left(x_{0}\right)}\left\{\left\|D_{x}^{\gamma} u(x, \cdot)\right\|_{W^{1, \alpha}\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)}\right\} \leqslant c<\infty .
$$

Using (6) and (16), we obtain that $D_{x}^{\gamma} u \in C^{0,1-1 / \alpha}\left(B_{\delta_{1}}\left(x_{0}\right) \times\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)\right)^{3}$, $\alpha \in(1,2)$, where the distance in the space-time is defined as $d\left((x, t),\left(x^{\prime}, t^{\prime}\right)\right)=$ $\left|x-x^{\prime}\right|+\left|t-t^{\prime}\right|$. Note that Ladyzhenskaya and Seregin proved a similar result in [6].

Theorem 4. Let $\Omega=R^{3}$ and let the assumptions of Theorem 2 be satisfied. Then $D_{x}^{\gamma} \partial u / \partial t, D_{x}^{\gamma} \mathcal{P} \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)$ for every multi-index $\gamma$, $|\gamma| \geqslant 0$ and $\delta_{1} \in(0, \delta)$.

Proof. Let $\delta_{1}<\delta_{2}<\delta$. It is known (see e.g. [1]) that for almost every $t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ and every $x \in B_{\delta_{1}}\left(x_{0}\right)$,

$$
\begin{align*}
\mathcal{P}(x, t)= & \frac{1}{4 \pi} \int_{R^{3}} \frac{1}{|x-y|} \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y  \tag{17}\\
= & \frac{1}{4 \pi} \int_{B_{\delta_{2}\left(x_{0}\right)}} \frac{1}{|x-y|} \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y \\
& +\frac{1}{4 \pi} \int_{\mathbb{R}^{3} \backslash B_{\delta_{2}}\left(x_{0}\right)} \frac{1}{|x-y|} \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y \\
= & \hat{p}_{1}(x, t)+\hat{p}_{2}(x, t) .
\end{align*}
$$

It follows from (i) that $\hat{p}_{1} \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)$. If we use twice integration by parts and take into consideration that $u \nabla u,|u|^{2} \in L^{1}\left(R^{3}\right)$ we get

$$
\begin{align*}
\hat{p}_{2}(x, t)= & \frac{1}{4 \pi} \int_{\partial B_{\delta_{2}}\left(x_{0}\right)} \frac{1}{|x-y|} \frac{\partial u_{i}}{\partial y_{j}}(y, t) u_{j}(y, t) n_{i}(y) \mathrm{d}_{y} S  \tag{18}\\
& -\frac{1}{4 \pi} \int_{\partial B_{\delta_{2}}\left(x_{0}\right)} \frac{\partial}{\partial y_{i}}\left(\frac{1}{|x-y|}\right) u_{i}(y, t) u_{j}(y, t) n_{j}(y) \mathrm{d}_{y} S \\
& +\frac{1}{4 \pi} \int_{R^{3} \backslash B_{\delta_{2}}\left(x_{0}\right)} \frac{\partial^{2}}{\partial y_{i} \partial y_{j}}\left(\frac{1}{|x-y|}\right) u_{i}(y, t) u_{j}(y, t) \mathrm{d} y,
\end{align*}
$$

where $n=\left(n_{1}, n_{2}, n_{3}\right)$ is the outer normal vector. Using (18), (i) and the facts that $u_{i} u_{j} \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{1}\left(\mathbb{R}^{3}\right)\right)$ and the functions $\psi(y)=1 /|x-y|, x \in B_{\delta_{1}}\left(x_{0}\right)$ and all their first and second space derivatives in $y$ are uniformly bounded in $\mathbb{R}^{3} \backslash B_{\delta_{2}}\left(x_{0}\right)$, we see that $\hat{p}_{2} \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)$. From this and (17) one can conclude

$$
\begin{equation*}
\mathcal{P} \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right) \tag{19}
\end{equation*}
$$

Now the proof follows immediately from Theorem 2 and Remark 3.
Let us remark that since $D_{x}^{\gamma} \partial u / \partial t \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)$, we have

$$
\underset{x \in B_{\delta_{1}}\left(x_{0}\right)}{ }\left\{\left\|D_{x}^{\gamma} u(x, \cdot)\right\|_{W^{1, \beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)}\right\} \leqslant c<\infty
$$

for every $\beta \in\langle 1, \infty\rangle$ and

$$
\begin{equation*}
D_{x}^{\gamma} u(x, \cdot) \in W^{1, \beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right) \text { holds for every } x \in B_{\delta_{1}}\left(x_{0}\right) \tag{20}
\end{equation*}
$$

provided $\beta \in\langle 1, \infty)$. Moreover, we also have $u \in C^{0, \lambda}\left(B_{\delta_{1}}\left(x_{0}\right) \times\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)\right)^{3}$ for every $\lambda \in(0,1)$.

Remark 5. Let $u$ be a weak solution of (1)-(4) and let $\mathcal{P}$ be the associated pressure. Then $\mathcal{P} \in L^{5 / 3}\left(Q_{T}\right)$.

Proof. We use the integral representation of $\mathcal{P}$ (the first equation in (17)) and apply twice integration by parts. We get for almost every $t \in(0, T)$ that

$$
\mathcal{P}(x, t)=-\frac{1}{3}|u(x, t)|^{2}+\lim _{\varepsilon \rightarrow 0_{+}} \frac{1}{4 \pi} \int_{R_{\varepsilon}^{3}(x)} \frac{\partial^{2}}{\partial y_{i} \partial y_{j}}\left(\frac{1}{|x-y|}\right) u_{i}(y, t) u_{j}(y, t) \mathrm{d} y
$$

for almost every $x \in \mathbb{R}^{3}$, where $\mathbb{R}_{\varepsilon}^{3}(x)=\mathbb{R}^{3} \backslash \overline{B_{\varepsilon}(x)}$. The conclusion of Remark 5 is obtained by using the Calderón-Zygmund theorem (see [2] or [4]) and the fact that $u \in L^{10 / 3}\left(Q_{T}\right)$.

## 2. Application of additional conditions

From now on till the end of the chapter suppose that $\Omega$ is a bounded domain. Our intention is to prove Theorem 2 for $\alpha \geqslant 2$. Unfortunately, we are not able to prove it generally. At first, we present a few global additional conditions on $u$ and $p$, under which Theorem 2 holds for $\alpha \geqslant 2$. Thus, let the assumptions of Theorem 2 be satisfied and $\delta_{1} \in(0, \delta)$. Moreover, we suppose that it is possible to write

$$
\begin{equation*}
\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)=\bigcup_{\alpha \in \Gamma} I_{\alpha} \cup G \tag{21}
\end{equation*}
$$

where $\Gamma$ is at most countable, $I_{\alpha}$ are open disjoint intervals, one-dimensional Lebesgue measure of $G$ is zero and $u, \mathcal{P}$ are smooth functions in $\Omega \times I_{\alpha}$. These assumptions hold, for example, for the weak solution of (1)-(4) constructed by the Faedo-Galerkin method (see [9]) or for the weak solutions of (1)-(4) satisfying the strong energy inequality (see [4]).

There exists an orthogonal decomposition of $L^{2}(\Omega)^{3}$ (see [9]),

$$
\begin{equation*}
L^{2}(\Omega)^{3}=H_{1} \oplus H_{2} \oplus H_{3}, \tag{22}
\end{equation*}
$$

where

$$
\begin{aligned}
& H_{1}=\left\{v \in L^{2}(\Omega)^{3}, \operatorname{div} v=0, \gamma_{\nu} v=0\right\} \\
& H_{2}=\left\{v=\nabla p, p \in W_{0}^{1,2}(\Omega)\right\}
\end{aligned}
$$

and

$$
H_{3}=\left\{v=\nabla q, q \in W^{1.2}(\Omega), \Delta q=0\right\}
$$

where $\gamma_{\nu} v$ is the restriction of $v \cdot \nu$ to $\partial \Omega$ for every $v \in C^{\infty}(\bar{\Omega})$ and $\nu$ is the normal vector to $\partial \Omega$ (see [9]). Coming back to the equation (1), we can decompose all terms in (1) on the intervals $I_{\alpha}$. Denote by $P_{1}, P_{2}, P_{3}, P_{12}, P_{13}, P_{23}$, respectively, the projections from $\left(L^{2}(\Omega)\right)^{3}$ onto the spaces $H_{1}, H_{2}, H_{3}, H_{1} \oplus H_{2}, H_{1} \oplus H_{3}, H_{2} \oplus H_{3}$. Then

$$
\begin{gather*}
\nu \cdot \Delta u=P_{1}(\nu \cdot \Delta u)+P_{3}(\nu \cdot \Delta u) \in H_{1} \oplus H_{3},  \tag{24}\\
\nabla \mathcal{P}=P_{2}(\nabla \mathcal{P})+P_{3}(\nabla \mathcal{P}) \in H_{2} \oplus H_{3}
\end{gather*}
$$

and

$$
\begin{equation*}
u \nabla u=P_{1}(u \nabla u)+P_{2}(u \nabla u)+P_{3}(u \nabla u) \in H_{1} \oplus H_{2} \oplus H_{3} . \tag{26}
\end{equation*}
$$

Lemma 6. If $u$ is a weak solution of the system (1)-(4) and $\mathcal{P}$ is an associated pressure then

$$
\begin{gather*}
(u \cdot \nabla) u \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ;\left(W^{3,2}(\Omega)^{3}\right)^{*}\right),  \tag{27}\\
\Delta \mathcal{P}=-\frac{\partial u_{i}}{\partial y_{j}} \cdot \frac{\partial u_{j}}{\partial y_{i}} \in L^{2}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ;\left(W^{3,2}(\Omega)\right)^{*}\right) . \tag{28}
\end{gather*}
$$

Proof. Let $\psi \in W^{3,2}(\Omega)^{3}$. Then

$$
\int_{\Omega}(u \cdot \nabla) u \cdot \psi \mathrm{~d} y=-\int_{\Omega} u_{j} u_{i} \frac{\partial \psi_{i}}{\partial y_{j}} \mathrm{~d} y .
$$

We estimate

$$
\left|\int_{\Omega} u_{j} u_{i} \frac{\partial \psi_{i}}{\partial y_{j}} \mathrm{~d} y\right| \leqslant c\|u\|_{L^{2}(\Omega)^{3}}^{2}\|\psi\|_{W^{3,2}(\Omega)^{3}}
$$

and (27) follows. Similarly, if $\psi \in W^{3,2}(\Omega)$, then

$$
\int_{\Omega} \frac{\partial u_{i}}{\partial y_{j}} \frac{\partial u_{j}}{\partial y_{i}} \psi \mathrm{~d} y=-\int_{\Omega} u_{j} \frac{\partial u_{j}}{\partial y_{j}} \frac{\partial \psi}{\partial y_{i}} \mathrm{~d} y
$$

and

$$
\left|\int_{\Omega} u_{j} \frac{\partial u_{i}}{\partial y_{j}} \frac{\partial \psi}{\partial y_{i}} \mathrm{~d} y\right| \leqslant c\|u\|_{L^{2}(\Omega)^{3}}\|\nabla u\|_{L^{2}(\Omega)^{9}}\|\psi\|_{W^{3,2}(\Omega)}
$$

Therefore (28) holds. Lemma 6 is proved.

Let us show now that there exists a function $\eta_{x}=\eta_{x}(y)$ from $W^{3,2}(\Omega)^{3} \cap$ $W_{0}^{1,2}(\Omega)^{3} \cap \mathcal{C}^{\infty}(\bar{\Omega})^{3}$ for every $x \in B_{\delta_{1}}\left(x_{0}\right)$ such that for almost every $t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$

$$
\begin{equation*}
p_{2}(x, t)+p_{3}(x, t)=-\int_{\Omega} \nabla \mathcal{P}(y, t) \cdot \eta_{x}(y) \mathrm{d} y \tag{29}
\end{equation*}
$$

(the functions $p_{2}, p_{3}$ were defined in (9)) and therefore

$$
\begin{equation*}
\mathcal{P}(x, t)=\varphi \mathcal{P}(x, t)=p_{1}(x, t)-\int_{\Omega} \nabla \mathcal{P}(y, t) \cdot \eta_{x}(y) \mathrm{d} y \tag{30}
\end{equation*}
$$

Moreover, we will show that there exists $K>0$ such that

$$
\begin{equation*}
\left\|\eta_{x}\right\|_{W^{3,2}(\Omega)^{3}} \leqslant K \tag{31}
\end{equation*}
$$

for every $x \in B_{\delta_{1}}\left(x_{0}\right)$.
Let us recall the following lemma (see [9]).
Lemma 7. Let $D \subset \mathbb{R}^{3}$ be an open bounded domain, $\partial D \in C^{\beta}$, where $\beta=$ $\max (m+2,2)$ and assume that $m \geqslant-1$ is an integer. Let $\Phi \in W^{m+1,2}(D)$ and $\int_{D} \Phi \mathrm{~d} x=0$. Then there exist $\eta \in W^{m+2,2}(D)^{3}$ and $q \in W^{m+1,2}(D)$ such that

$$
\begin{align*}
&-\Delta \eta+\nabla q=0 \quad \text { in } \quad D,  \tag{32}\\
& \operatorname{div} \eta=\Phi \quad \text { in } \quad D, \\
& \eta=0 \quad \text { on } \quad \partial D .
\end{align*}
$$

Moreover,

$$
\|\eta\|_{W^{m+2,2}(D)} \leqslant c\|\Phi\|_{W^{m+1,2}(D)},
$$

where $c=c(D, m)$.
Take $\varphi$ defined in (8). Denote for every $x \in B_{\delta_{1}}\left(x_{0}\right)$

$$
\Psi_{x}(y)=\frac{1}{4 \pi} \frac{1}{|x-y|} \Delta \varphi(y)+\frac{1}{2 \pi} \nabla_{y} \frac{1}{|x-y|} \nabla \varphi(y)-m(\Omega)^{-1},
$$

where $m(\Omega)$ denotes the Lebesgue measure of $\Omega$. Then $\int_{\Omega} \Psi_{x}(y) \mathrm{d} y=0$ and $\left\|\Psi_{x}\right\|_{2,2} \leqslant K<\infty$ for every $x \in B_{\delta_{1}}\left(x_{0}\right)$ and for some $K>0$. Using Lemma 7 , we obtain a function $\eta_{x} \in W^{3,2}(\Omega)^{3} \cap W_{0}^{1,2}(\Omega)^{3}$, div $\eta_{x}=\Psi_{x}$ and $\left\|\eta_{x}\right\|_{W^{3,2}(\Omega)} \leqslant c K<\infty$ for every $x \in B_{\delta_{1}}\left(x_{0}\right)$. Obviously, $\eta_{x} \in C^{\infty}(\bar{\Omega})^{3}$, since $\Psi_{x} \in C^{\infty}(\bar{\Omega})^{3}$. Therefore, using the equality $\int_{\Omega} \mathcal{P}(y, t) \mathrm{d} y=0$, we can write

$$
\begin{equation*}
p_{2}(x, t)+p_{3}(x, t)=\int_{\Omega}\left(\Psi_{x}(y)+m(\Omega)^{-1}\right) \mathcal{P}(y, t) \mathrm{d} y=-\int_{\Omega} \nabla \mathcal{P}(y, t) \cdot \eta_{x}(y) \mathrm{d} y . \tag{33}
\end{equation*}
$$

Thus, (29)-(31) are verified. We know from the proof of Theorem 2 that $p_{1} \in$ $L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)\right)$. Due to (30) this means that to prove

$$
\begin{equation*}
\mathcal{P} \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)\right) \tag{34}
\end{equation*}
$$

for some $\beta \in\langle 2, \infty\rangle$, it is sufficient to show that $\int_{\Omega} \nabla \mathcal{P}(y, t) \cdot \eta_{x}(y) \mathrm{d} y$ as a function of $(x, t)$ is from the space $L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)\right)$. We use this idea in the the proof of the two next lemmas, where we present two examples of global conditions imposed on $u$ under which (34) is satisfied. Recall that (34) then implies (according to Remark 3) that Theorem 2 holds for $\alpha=\beta \geqslant 2$. For the sake of simplicity, we omit in the proof of Lemma 8 and Lemma 9 the dependence of functions on $y$ and $t$.

Lemma 8. Let $g$ be a function for which $\nabla g=P_{3}(\nu \Delta u)$ and suppose that $\left.g\right|_{\partial \Omega} \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{1}(\partial \Omega)\right), \beta \in\langle 2, \infty\rangle$. Then (34) holds.

Proof. Let $x \in B_{\delta_{1}}\left(x_{0}\right)$. Suppose that $\eta_{x}$ is the function from (29). Using (1) and (23)-(25) we get for almost every $t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ that

$$
\begin{aligned}
\int_{\Omega} \nabla \mathcal{P} \eta_{x} \mathrm{~d} y= & \int_{\Omega} \nabla \mathcal{P} P_{23}\left(\eta_{x}\right) \mathrm{d} y=-\int_{\Omega}(u \cdot \nabla) u P_{23}\left(\eta_{x}\right) \mathrm{d} y \\
& +\int_{\Omega} \nu \Delta u P_{23}\left(\eta_{x}\right) \mathrm{d} y-\int_{\Omega} \frac{\partial u}{\partial t} P_{23}\left(\eta_{x}\right) \mathrm{d} y
\end{aligned}
$$

Obviously, $\int_{\Omega} \partial u / \partial t P_{23}\left(\eta_{x}\right) \mathrm{d} y=0$ and $\int_{\Omega} \nu \Delta u P_{23}\left(\eta_{x}\right) \mathrm{d} y=\int_{\Omega} \nu P_{3}(\Delta u) P_{3}\left(\eta_{x}\right) \mathrm{d} y$. Thus,

$$
\begin{equation*}
\int_{\Omega} \nabla \mathcal{P} \eta_{x} \mathrm{~d} y=-\int_{\Omega}(u \cdot \nabla) u P_{23}\left(\eta_{x}\right) \mathrm{d} y+\int_{\Omega} \nu P_{3}(\Delta u) P_{3}\left(\eta_{x}\right) \mathrm{d} y \tag{35}
\end{equation*}
$$

It follows from Lemma $6,(31)$ and the fact that $\left\|P_{23} \varphi_{x}\right\|_{W^{3,2}(\Omega)^{3}} \leqslant c\left\|\varphi_{x}\right\|_{W^{3,2}(\Omega)^{3}}$ that

$$
\begin{equation*}
\int_{\Omega}(u \cdot \nabla) u P_{23}\left(\eta_{x}\right) \mathrm{d} y \leqslant C \tag{36}
\end{equation*}
$$

for some $C>0$, every $x \in B_{\delta_{1}}\left(x_{0}\right)$ and almost every $t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$.
Denote by $h$ the function for which $\nabla h=P_{3}\left(\eta_{x}\right)$. Then $\Delta h=0$ and

$$
\begin{align*}
\int_{\Omega} P_{3}(\nu \Delta u) \cdot P_{3}\left(\eta_{x}\right) \mathrm{d} y & =\int_{\Omega} \nabla g \cdot \nabla h \mathrm{~d} y  \tag{37}\\
& =\int_{\partial \Omega} g \frac{\partial h}{\partial n} \mathrm{~d}_{y} S-\int_{\Omega} g \Delta h \mathrm{~d} y=\int_{\partial \Omega} g \frac{\partial h}{\partial n} \mathrm{~d}_{y} S
\end{align*}
$$

From $\eta_{x} \in W_{0}^{1,2}(\Omega)^{3}$ we get that $\partial h / \partial n=-P_{2}\left(\eta_{x}\right) \cdot n$ on $\partial \Omega$ and this implies $\|\partial h / \partial n\|_{L^{\infty}(\partial \Omega)} \leqslant c\left\|\eta_{x}\right\|_{W^{3,2}(\Omega)^{3}}$. Therefore,

$$
\left|\int_{\partial \Omega} g \frac{\partial h}{\partial n} \mathrm{~d}_{y} S\right| \leqslant\|g\|_{L^{1}(\partial \Omega)}\left\|\frac{\partial h}{\partial n}\right\|_{L^{\infty}(\partial \Omega)} \leqslant c\|g\|_{L^{1}(\partial \Omega)}\left\|\eta_{x}\right\|_{W^{3,2}(\Omega)^{3}} \leqslant c K\|g\|_{L^{1}(\partial \Omega)}
$$

From this inequality and from (33), (35), (36) and (37) we get (34) and Lemma 8 is proved.

Lemma 9. Suppose that $\partial u / \partial n \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{1}(\partial \Omega)^{3}\right), \beta \in\langle 2, \infty\rangle$. Then (34) holds.

Proof. First, we proceed similarly as we did in Lemma 8. Instead of (37) we estimate $\left(\nabla h=P_{3}\left(\eta_{x}\right)\right)$

$$
\begin{aligned}
\nu \int_{\Omega} \Delta u \cdot P_{3}\left(\eta_{x}\right) \mathrm{d} y & =\int_{\partial \Omega} \frac{\partial u}{\partial n} \cdot \nabla h \mathrm{~d}_{y} S-\int_{\Omega} \frac{\partial u_{i}}{\partial x_{j}} \frac{\partial^{2} h}{\partial x_{i} \partial x_{j}} \mathrm{~d} y \\
& =\int_{\partial \Omega} \frac{\partial u}{\partial n} \cdot \nabla h \mathrm{~d}_{y} S-\int_{\partial \Omega} u_{i} n_{j} \frac{\partial^{2} h}{\partial x_{i} \partial x_{j}} \mathrm{~d}_{y} S+\int_{\Omega} u_{i} \frac{\partial}{\partial x_{i}}(\Delta h) \mathrm{d} y \\
& =\int_{\partial \Omega} \frac{\partial u}{\partial n} \cdot \nabla h \mathrm{~d}_{y} S
\end{aligned}
$$

By virtue of Lemma 6, we have

$$
\left|\int_{\partial \Omega} \frac{\partial u}{\partial n} \cdot \nabla h \mathrm{~d}_{y} S\right| \leqslant\left\|\frac{\partial u}{\partial n}\right\|_{L^{1}(\partial \Omega)^{3}}\left\|\eta_{x}\right\|_{W^{3,2}(\Omega)^{3}}
$$

and we obtain (34). Lemma 9 is proved.
Now let us formulate one local condition (see Theorem 10) under which (34) is satisfied. The following considerations can be done for an arbitrary weak solution of (1)-(4). Let $2 r<\delta$ and $x \in B_{r}\left(x_{0}\right)$. Let further $\zeta \in C^{\infty}(\langle 0, \infty)), \zeta \equiv 1$ in $\langle 0, r / 2\rangle$ and $\zeta \equiv 0$ in $\langle 3 r / 4, \infty)$. Thus, $\zeta$ is independent of $t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ and $x \in B_{r}\left(x_{0}\right)$. Put $\varphi_{x}(y)=\zeta(|x-y|)$ for every $x \in B_{r}\left(x_{0}\right)$ and every $y \in \mathbb{R}^{3}$. For almost every $t \in\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ and for every $x \in B_{r}\left(x_{0}\right)$ it is possible to write

$$
\begin{align*}
\mathcal{P}(x, t)= & \frac{1}{4 \pi} \int_{B_{r}(x)} \frac{1}{|x-y|} \varphi_{x}(y) \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y  \tag{38}\\
& +\frac{1}{4 \pi} \int_{B_{r}(x)} \frac{1}{|x-y|} \Delta_{y} \varphi_{x}(y) \mathcal{P}(y, t) \mathrm{d} y \\
& +\frac{1}{2 \pi} \int_{B_{r}(x)} \frac{(x-y)}{|x-y|^{3}} \cdot \nabla_{y} \varphi_{x}(y) \mathcal{P}(y, t) \mathrm{d} y
\end{align*}
$$

It is possible to show that

$$
\begin{equation*}
\int_{B_{r}(x)}\left[\frac{1}{|x-y|} \Delta_{y} \varphi_{x}(y)+2 \nabla_{y}\left(\frac{1}{|x-y|}\right) \cdot \nabla_{y} \varphi_{x}(y)-\frac{3}{r^{3}}\right] \mathrm{d} y=0 . \tag{39}
\end{equation*}
$$

Lemma 7 yields that there exist $\eta_{x} \in C^{\infty}\left(\overline{B_{r}(x)}\right)^{3} \cap W_{0}^{1,2}\left(B_{r}(x)\right)^{3}$ such that

$$
\begin{equation*}
\nabla \cdot \eta_{x}(y)=\frac{1}{|x-y|} \Delta_{y} \varphi_{x}(y)+2 \nabla_{y}\left(\frac{1}{|x-y|}\right) \cdot \nabla_{y} \varphi_{x}(y)-\frac{3}{r^{3}} \quad \text { on } B_{r}(x) \tag{40}
\end{equation*}
$$

and $\left\|\eta_{x}\right\|_{W^{m+1,2}\left(B_{r}(x)\right)^{3}}$ are bounded on $B_{r}\left(x_{0}\right)$ for every $m \in N$. Decompose $\eta_{x}$ on $L^{2}\left(B_{r}(x)\right)^{3}$ as $P_{1}\left(\eta_{x}\right)+P_{2}\left(\eta_{x}\right)+P_{3}\left(\eta_{x}\right)$ and let $\nabla \mathcal{Q}_{2, x}=P_{2}\left(\eta_{x}\right)$ and $\nabla \mathcal{Q}_{3, x}=P_{3}\left(\eta_{x}\right)$. Then $\left|\mathcal{Q}_{2, x}(y)\right| \leqslant c$, where $c$ is a positive constant independent of $x \in B_{r}\left(x_{0}\right)$ and $y \in B_{r}(x)$. This follows from (40) and the fact that $\mathcal{Q}_{2, x}$ is a solution of the system

$$
\begin{aligned}
\Delta \mathcal{Q}_{2, x} & =\nabla \cdot \eta_{x} & & \text { in } B_{r}(x) \\
\mathcal{Q}_{2, x} & =0 & & \text { on } \partial B_{r}(x) .
\end{aligned}
$$

We can see from (40) that $\nabla \cdot \eta_{x}$ is spherically symmetric around $x$ and the same must be true for $\mathcal{Q}_{2, x}$. Consequently, $\partial \mathcal{Q}_{2, x} / \partial n=$ const. on $\partial B_{r}(x)$ ( $n$ is a normal vector on $\left.\partial B_{r}(x)\right)$ and since

$$
\int_{\partial B_{r}(x)} \frac{\partial \mathcal{Q}_{2, x}}{\partial n} \mathrm{~d}_{y} S=\int_{B_{r}(x)} \Delta \mathcal{Q}_{2, x} \mathrm{~d} y=\int_{B_{r}(x)} \nabla \cdot \eta_{x} \mathrm{~d} y=\int_{\partial B_{r}(x)} \eta_{x} \cdot n \mathrm{~d}_{y} S=0
$$

one gets that $\partial \mathcal{Q}_{2, x} / \partial n=0$ on $\partial B_{r}(x)$. Further, $\mathcal{Q}_{3, x}$ is a solution of the system

$$
\begin{array}{ll}
\Delta Q_{3, x}=0 & \text { in } B_{r}(x) \\
\frac{\partial \mathcal{Q}_{3, x}}{\partial n}=-\frac{\partial \mathcal{Q}_{2, x}}{\partial n}=0 & \text { on } \partial B_{r}(x)
\end{array}
$$

which gives $\mathcal{Q}_{3, x}=$ const. and therefore $\nabla \mathcal{Q}_{3, x}=0$ on $B_{r}(x)$. Thus, we can write

$$
\begin{align*}
& \int_{B_{r}(x)} \nabla \cdot \eta_{x}(y) \mathcal{P}(y, t) \mathrm{d} y=-\int_{B_{r}(x)} P_{2}\left(y \eta_{x}\right)(y) \cdot \nabla \mathcal{P}(y, t) \mathrm{d} y  \tag{41}\\
= & \int_{B_{r}(x)} \mathcal{Q}_{2, x}(y) \Delta \mathcal{P}(y, t) \mathrm{d} y=-\int_{B_{r}(x)} \mathcal{Q}_{2, x}(y) \frac{\partial^{2}\left(u_{i} u_{j}\right)}{\partial y_{i} \partial y_{j}}(y, t) \mathrm{d} y .
\end{align*}
$$

Now it follows from (38), (40) and (41) that

$$
\begin{align*}
\mathcal{P}(x, t)= & \frac{1}{4 \pi} \int_{B_{r}(x)}\left[\frac{1}{|x-y|} \varphi_{x}(y)-\mathcal{Q}_{2, x}(y)\right] \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y  \tag{42}\\
& +\frac{3}{4 \pi r^{3}} \int_{B_{r}(x)} \mathcal{P}(y, t) \mathrm{d} y
\end{align*}
$$

which can be written as

$$
\begin{align*}
0= & \frac{1}{4 \pi} \int_{B_{r}(x)}\left[\frac{1}{|x-y|} \varphi_{x}(y)-\mathcal{Q}_{2, x}(y)\right] \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y  \tag{43}\\
& +\frac{3}{4 \pi r^{3}} \int_{B_{r}(x)}(\mathcal{P}(y, t)-\mathcal{P}(x, t)) \mathrm{d} y .
\end{align*}
$$

The first integral on the right-hand side of (43) is from $L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{r}\left(x_{0}\right)\right)\right)$. Let $a^{+}=\max (a, 0)$ and $a^{-}=\max (-a, 0)$ for every $a \in \mathbb{R}$. We can conclude:

Theorem 10. Let the assumptions of Theorem 2 be fulfilled. Let further $2 r<\delta$ and $x \in B_{r}\left(x_{0}\right)$. If $(\mathcal{P}-\mathcal{P}(x, t))^{+}$or $(\mathcal{P}-\mathcal{P}(x, t))^{-}$is from the space $L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\right.$ $\left.\varepsilon, L^{1}\left(B_{r}(x)\right)\right)$ for some $\beta \in\langle 2, \infty\rangle$, then $\mathcal{P}-\mathcal{P}(x, t) \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{1}\left(B_{r}(x)\right)\right)$. Consequently, there exists a sufficiently small $\theta$ such that $\mathcal{P}-\mathcal{P}(x, t) \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\right.$ $\left.\varepsilon, L^{1}\left(B_{\theta}\left(x_{0}\right)\right)\right)$. Considering now the pressure $\mathcal{P}-\mathcal{P}(x, t)$ instead of the pressure $\mathcal{P}$, we obtain, using Remark 3, that $D_{x}^{\gamma} \partial u / \partial t \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{\infty}\left(B_{\theta_{1}}\left(x_{0}\right)\right)^{3}\right)$ and $D_{x}^{\gamma} \mathcal{P} \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{\infty}\left(B_{\theta_{1}}\left(x_{0}\right)\right)\right)$ for every multi-index $\gamma,|\gamma| \geqslant 1$ and $\theta_{1} \in(0, \theta)$.

Let us now present two consequences of Theorem 10. First, let the assumptions of Theorem 2 be satisfied. If $2 r<\delta$ and there exists $x \in B_{r}\left(x_{0}\right)$ such that $\mathcal{P}-\mathcal{P}(x, t)$ is bounded from below (above) in $B_{r}(x) \times\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$ then $\mathcal{P}-\mathcal{P}(x, t)$ and all space derivatives of $\mathcal{P}$ are in the space $L^{\infty}$ in a space-time neighbourhood of ( $x_{0}, t_{0}$ ).

Secondly, suppose that $\Omega=B_{R}\left(x_{0}\right)$, where $x_{0} \in \mathbb{R}^{3}$ and $R>0$, and $x_{0}$ is a regular point of $u$. We will show that if $\mathcal{P}^{+}$or $\mathcal{P}^{-}$is from the space $L^{\beta}\left(t_{0}-\right.$ $\left.\varepsilon, t_{0}+\varepsilon, L^{1}\left(B_{\delta_{1}}\left(x_{0}\right)\right)\right)$ for some $\beta \in\langle 2, \infty\rangle, \delta_{1} \in(0, \delta)$, then $\mathcal{P} \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\right.$ $\left.\varepsilon ; L^{1}\left(B_{\delta_{1}}\left(x_{0}\right)\right)\right)$. We can suppose that $\int_{\Omega} \mathcal{P}(y, t) \mathrm{d} y=0$. It is possible to write

$$
\begin{aligned}
\mathcal{P}\left(x_{0}, t\right)= & \frac{1}{4 \pi} \int_{B_{r}\left(x_{0}\right)} \frac{1}{\left|x_{0}-y\right|} \varphi_{x_{0}}(y) \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y \\
& +\frac{1}{4 \pi} \int_{B_{r}\left(x_{0}\right)} \frac{1}{\left|x_{0}-y\right|} \Delta_{y} \varphi_{x_{0}}(y) \mathcal{P}(y, t) \mathrm{d} y \\
& +\frac{1}{2 \pi} \int_{B_{r}\left(x_{0}\right)} \frac{\left(x_{0}-y\right)}{\left|x_{0}-y\right|^{3}} \cdot \nabla_{y} \varphi_{x_{0}}(y) \mathcal{P}(y, t) \mathrm{d} y .
\end{aligned}
$$

Consequently,

$$
\begin{align*}
\mathcal{P}\left(x_{0}, t\right)= & \frac{1}{4 \pi} \int_{B_{r}\left(x_{0}\right)} \frac{1}{\left|x_{0}-y\right|} \varphi_{x_{0}}(y) \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y  \tag{44}\\
& -\frac{1}{4 \pi} \int_{\Omega} \mathcal{Q}_{2, x_{0}}(y) \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y,
\end{align*}
$$

where $\mathcal{Q}_{2, x_{0}} \in C^{\infty}(\bar{\Omega}) \cap W_{0}^{1,2}(\Omega)$ is constructed on $\Omega$ in the same way as in the paragraph preceding Theorem 10. Since

$$
\begin{equation*}
\frac{1}{4 \pi} \int_{\Omega} \mathcal{Q}_{2, x_{0}}(y) \frac{\partial u_{i}}{\partial y_{j}}(y, t) \frac{\partial u_{j}}{\partial y_{i}}(y, t) \mathrm{d} y=\frac{1}{4 \pi} \int_{\Omega} \frac{\partial^{2} \mathcal{Q}_{2, x_{0}}}{\partial y_{i} \partial y_{j}}(y) u_{i}(y, t) u_{j}(y, t) \mathrm{d} y \tag{45}
\end{equation*}
$$

(44) gives immediately that $\mathcal{P}\left(x_{0}, \cdot\right) \in L^{\infty}\left(t_{0}-\varepsilon, t_{0}+\varepsilon\right)$. Using now Theorem 10 we can conclude that if $\mathcal{P}^{+}$or $\mathcal{P}^{-}$is from the space $L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{1}\left(B_{\delta_{1}}\left(x_{0}\right)\right)\right)$ for some $\beta \in\langle 2, \infty\rangle$, then $\mathcal{P} \in L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon, L^{1}\left(B_{\delta_{1}}\left(x_{0}\right)\right)\right)$ and therefore $D_{x}^{\gamma} \mathcal{P}, D_{x}^{\gamma} \partial u / \partial t \in$ $L^{\beta}\left(t_{0}-\varepsilon, t_{0}+\varepsilon ; L^{\infty}\left(B_{\delta_{1}}\left(x_{0}\right)\right)^{3}\right)$ as follows from Remark 3.

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