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# BILINEAR MULTIPLIERS ON LORENTZ SPACES 

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Abstract. We give one sufficient and two necessary conditions for boundedness between Lebesgue or Lorentz spaces of several classes of bilinear multiplier operators closely connected with the bilinear Hilbert transform.

Keywords: bilinear Hilbert transform, bilinear multipliers, Lorentz spaces
MSC 2010: 42B10, 42B15, 42B35, 47H60

## 1. Introduction

The bilinear Hilbert transform with parameter $\alpha \in \mathbb{R}$ is the operator given by

$$
H_{\alpha}(f, g)(x)=\frac{1}{\pi} p \cdot v \cdot \int f(x-t) g(x-\alpha t) \frac{\mathrm{d} t}{t}
$$

initially defined for functions in the Schwartz class. Notice that $H_{0}(f, g)=H(f) g$ and $H_{1}(f, g)=H(f g)$ where $H(f)$ is the classical Hilbert transform. So $H_{\alpha}$ can be seen as an intermediate step between both operators.

The bilinear Hilbert transform has been extensively studied since 1965 when A. Calderón set the conjecture of its boundedness from $L^{2} \times L^{\infty}$ into $L^{2}$ while he was working on the Hilbert transform defined over Lipschitz curves (see [2]). After several years of research and using original ideas of C. Fefferman [3], M. Lacey and C. Thiele finally answered this question when they proved the following

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Theorem 1.1. For each triple ( $p_{1}, p_{2}, p_{3}$ ) such that $1<p_{1}, p_{2} \leqslant \infty, 1 / p_{1}+1 / p_{2}=$ $1 / p_{3}$ and $p_{3}>2 / 3$ and each $\alpha \in \mathbb{R} \backslash\{0,1\}$ there exists $C\left(\alpha, p_{1}, p_{2}\right)>0$ for which

$$
\left\|H_{\alpha}(f, g)\right\|_{p_{3}} \leqslant C\left(\alpha, p_{1}, p_{2}\right)\|f\|_{p_{1}}\|g\|_{p_{2}}
$$

for all $f, g$ in the Schwartz class.
In two papers ([8], [9]) published in 1997 and 1999 respectively. See also [14] for a unified proof.

Since then a great deal of generalizations and extensions of this seminal work have appeared such as: [4], [5] and [12] related to the modification of the kernel of the operator, [6] related to uniform estimates in the same inequality, [10] related to maximal results, and [13] to uniform estimates with generalized kernels.

The present paper shows two sufficient and one necessary conditions for boundedness of different types of bilinear multipliers some of which include the bilinear Hilbert transform.

## 2. Preliminaries, notation and definitions

Given a measurable function $f$ we denote its distribution function by $m_{f}(\lambda)=$ $m(\{x \in \mathbb{R}:|f(x)|>\lambda\})$ and its nonincreasing rearrangement by $f^{*}(t)=\inf \{\lambda>$ 0 : $\left.m_{f}(\lambda) \leqslant t\right\}$. The Lorentz space $L^{p, q}$ consists of those measurable functions $f$ such that $\|f\|_{p, q}^{*}<\infty$, where

$$
\|f\|_{p, q}^{*}= \begin{cases}\left\{\frac{q}{p} \int_{0}^{\infty} t^{q / p} f^{*}(t)^{q} \frac{\mathrm{~d} t}{t}\right\}^{1 / q}, & 0<p<\infty, 0<q<\infty \\ \sup _{t>0} t^{1 / p} f^{*}(t) & 0<p \leqslant \infty, q=\infty\end{cases}
$$

The reader is referred to [1] for basic information on Lorentz spaces.
The interpolation result we are going to use is a trilinear version of the RieszThorin interpolation theorem for tuples of spaces. Since we will use it for positive integral operators

$$
\int_{\mathbb{R}} f(x-t) g(x-\alpha t) K(t) \mathrm{d} t
$$

where $K$ is a positive function, we state the theorem in this setting.

Theorem 2.1. Let $0<p_{i, j} \leqslant \infty$ for $i=1, \ldots, n, j=0,1,2,3$. Let $T$ a positive trilinear integral operator such that $T: L^{p_{i, 0}} \times L^{p_{i, 1}} \times L^{p_{i, 2}} \rightarrow L^{p_{i, 3}}$ is bounded for $i=1, \ldots, n$ with $\|T\|_{i} \leqslant M_{i}$.

Then $T: L^{p_{0}} \times L^{p_{1}} \times L^{p_{2}} \rightarrow L^{p_{3}}$ is bounded for $1 / p_{j}=\sum_{i=1}^{n} \theta_{i} / p_{i, j}$, for $j=0,1,2,3$ where $0 \leqslant \theta_{i} \leqslant 1$ and $\sum_{i=1}^{n} \theta_{i}=1$. Moreover, $\|T\| \leqslant \prod_{i=1}^{n} M_{i}^{\theta_{i}}$.

A proof of this theorem for a pair of spaces can be found in [1] page 185 for the linear case and 202 for the multilinear case. The extension to tuples of spaces is trivial from that result.

We set some frequently used notations. For every $x, y \in \mathbb{R}$ we denote the translation operator by $T_{y} f(x)=f(x-y)$ and the modulation operator by $M_{y} f(x)=$ $f(x) \mathrm{e}^{2 \pi \mathrm{i} y x}$, while for all $p \in \mathbb{R}$ and $t \neq 0$ we denote the dilation operators by $D_{t}^{p} f(x)=t^{-1 / p} f\left(t^{-1} x\right)$ and $D_{t} f(x)=D_{t}^{\infty} f(x)=f\left(t^{-1} x\right)$. These operators show certain symmetries when the Fourier transform acts on them. In particular, the transform of a translation is a modulation, $\left(T_{y} f\right)^{\wedge}=M_{-y} \hat{f}$, the transform of a modulation is a translation, $\left(M_{y} f\right)^{\wedge}=T_{y} \hat{f}$, and the transform of a dilation is its dual dilation, $\left(D_{t}^{p} f\right)^{\wedge}=\operatorname{sign}(t) D_{t^{-1}}^{p^{\prime}} \hat{f}$.

For the dilation operator we trivially have that $\left\|D_{t}^{r} f\right\|_{p, q}=|t|^{1 / p-1 / r}\|f\|_{p, q}$. Sometimes we will also use the notation $K_{\varepsilon}$ for the change of scale normalized to the $L^{1}$ norm, that is, $K_{\varepsilon}(x)=\varepsilon^{-1} K\left(\varepsilon^{-1} x\right)=D_{\varepsilon}^{1} K(x)$.

The bilinear operators we are going to work with can be seen as generalizations of convolution operators. Thus, as in the case of the convolution of a distribution and a function, they can be defined functionally and distributionally. We will work only with the functional definition.

Definition 2.1. Let $u$ be a distribution. For every $\alpha \in \mathbb{R}$ and every $f, g \in C_{0}^{\infty}$ we define the function

$$
H_{u, \alpha}(f, g)(x)=\left(u, D_{-1} T_{-x} f \cdot D_{-\alpha^{-1}} T_{-x} g\right)
$$

for all $x \in \mathbb{R}$. We will say that $H_{u, \alpha}$ is a generalized bilinear Hilbert transform associated to $u$ and $\alpha$ or just a BHT for short.

In this way, if $K$ is a locally integrable function, for instance, this definition leads to the expression

$$
\begin{equation*}
H_{K, \alpha}(f, g)(x)=\int_{\mathbb{R}} f(x-t) g(x-\alpha t) K(t) \mathrm{d} t \tag{1}
\end{equation*}
$$

which is well defined for all $\alpha, x \in \mathbb{R}$ and for any bounded functions $f, g$ such that at least one of them has compact support if $\alpha \neq 0$ or $f$ has compact support if $\alpha=0$.

We give the following

Definition 2.2. Let $\alpha \in \mathbb{R}$ and $u$ be a distribution. Let $0<p_{i}<\infty, 0<$ $q_{i} \leqslant \infty, i=1,2,3$. We say that $H_{u, \alpha}$ is $\left(p_{i}, q_{i}\right)_{i=1,2,3}$ bounded if it can be extended to a bounded operator from $L^{p_{1}, q_{1}} \times L^{p_{2}, q_{2}}$ into $L^{p_{3}, q_{3}}$. This is possible if there exists a constant $C>0$ depending of $u, \alpha$ and $p_{i}, q_{i}$ such that $\left\|H_{u, \alpha}(f, g)\right\|_{p_{3}, q_{3}} \leqslant$ $C\|f\|_{p_{1}, q_{1}}\|g\|_{p_{2}, q_{2}}$, for all $f$ and $g$ in some appropriate dense subspaces.

In the same way that convolution and linear multiplier operators are intimately related, so are the operators previously defined and the following ones:

Definition 2.3. Let $m$ be a bounded measurable function in $\mathbb{R}^{2}$. For every $x \in \mathbb{R}$ and $f, g \in \mathcal{S}$ we define the operator

$$
B_{m}(f, g)(x)=\int_{\mathbb{R}^{2}} \hat{f}(\xi) \hat{g}(\eta) m(\xi, \eta) \mathrm{e}^{2 \pi \mathrm{i}(\xi+\eta) x} \mathrm{~d} \xi \mathrm{~d} \eta
$$

Let $p_{i}>0$.
We say that $m$ is a $\left(p_{1}, p_{2}, p_{3}\right)$ multiplier or just a bilinear multiplier if the operator can be extended to a bounded operator from $L^{p_{1}} \times L^{p_{2}}$ to $L^{p_{3}}$. We denote by $\|\cdot\|_{\mathscr{M}_{p_{p_{1}, p_{2}, p_{3}}}}$ the minimum constant that satisfies the inequality $\left\|B_{m}(f, g)\right\|_{p_{3}} \leqslant$ $C\|f\|_{p_{1}}\|g\|_{p_{2}}$ for all functions $f, g \in \mathcal{S}$.

The relationship between both kinds of operators is the following: if $K$ is, say, an integrable function then

$$
\int_{\mathbb{R}} f(x-t) g(x-\alpha t) K(t) \mathrm{d} t=\int_{\mathbb{R}^{2}} \hat{f}(\xi) \hat{g}(\eta) \widehat{K}(\xi+\alpha \eta) \mathrm{e}^{2 \pi \mathrm{i}(\xi+\eta) x} \mathrm{~d} \xi \mathrm{~d} \eta
$$

and so both operators can be regarded as generalizations of convolution operators or as generalizations of linear multiplier operators.

We finally state several of their properties related to invariance under traslation, commutativity and duality:

$$
\begin{align*}
H_{T_{y} u, \alpha}(f, g) & =H_{u, \alpha}\left(T_{y} f, T_{\alpha y} g\right),  \tag{2}\\
H_{u, \alpha}(f, g) & =\operatorname{sign}(\alpha) H_{D_{\alpha}^{1} u, \alpha^{-1}}(g, f),  \tag{3}\\
\left\langle h, H_{u, \alpha}(f, g)\right\rangle & =\left\langle H_{D_{-1} u, 1-\alpha}(h, g), f\right\rangle . \tag{4}
\end{align*}
$$

## 3. Three conditions for boundedness

We introduce three results on boundedness which can be summarized as follows. We first give a necessary condition obtained when we study the operator acting over Gaussian functions. Then we also give a sufficient condition which is the generalization of the Young inequality to this class of non-convolution operators. The third one is another sufficient condition for the second class of operators we have defined.
3.1. Gaussians looking for necessary conditions. We use the fact that the BHT over Gaussian functions has a particularly easy expression in order to get necessary conditions for its boundedness when the kernel is a temperate distribution. We get in this way two conditions for boundedness: one on the spaces between which the BHT can be bounded and another one on the kernel itself. We work with Lorentz spaces just for the sake of generality. We begin with a technical lemma.

Lemma 3.1. Let $G \in \mathcal{S}$ be such that $\widehat{G}(0)=1$. Let $\left(G_{\varepsilon}\right)_{\varepsilon>0}$ be an approximate identity with $G_{\varepsilon}=D_{\varepsilon}^{1} G$. Then for all $\varphi \in \mathcal{S},\left(G_{\varepsilon} * \varphi\right)_{\varepsilon>0}$ converges to $\varphi$ in the topology of the Schwartz class $\mathscr{T}_{\mathcal{S}}$.

Proof. We need to prove that for every $n, m \in \mathbb{N}, \lim _{\varepsilon \rightarrow 0^{+}}\left\|\left(G_{\varepsilon} * \varphi\right)_{n, m}-\varphi_{n, m}\right\|_{\infty}=$ 0 where we define $\varphi_{n, m}(x)=x^{n} \varphi^{(m)}(x)$. If $c_{n, k}$ denote the combinatorial number $n$ over $k$ then for $x \in \mathbb{R}$ and $\varepsilon>0$ we have

$$
\begin{aligned}
x^{n}\left(G_{\varepsilon} * \varphi\right)^{(m)}(x) & =x^{n}\left(G_{\varepsilon} * \varphi^{(m)}\right)(x)=\int_{\mathbb{R}}(x-t+t)^{n} G_{\varepsilon}(t) \varphi^{(m)}(x-t) \mathrm{d} t \\
& =\sum_{k=0}^{n} c_{n, k} \int_{\mathbb{R}} t^{k} D_{\varepsilon}^{1} G(t)(x-t)^{n-k} \varphi^{(m)}(x-t) \mathrm{d} t \\
& =\sum_{k=0}^{n} c_{n, k} \varepsilon^{k}\left(D_{\varepsilon}^{1}\left(G_{k, 0}\right) * \varphi_{n-k, m}\right)(x)
\end{aligned}
$$

Thus,

$$
\left|\left(G_{\varepsilon} * \varphi\right)_{n, m}(x)-\varphi_{n, m}(x)\right| \leqslant\left|\left(G_{\varepsilon} * \varphi_{n, m}\right)(x)-\varphi_{n, m}(x)\right|+\sum_{k=1}^{n} c_{n, k} \varepsilon^{k}\left\|G_{k, 0}\right\|_{1}\left\|\varphi_{n-k, m}\right\|_{\infty}
$$

$$
\text { and for } a=\max (n, m), \varrho_{r}(\varphi)=\sup _{m, n \leqslant r}\left\|\varphi_{n, m}\right\|_{\infty}
$$

$$
\left\|\left(G_{\varepsilon} * \varphi\right)_{n, m}-\varphi_{n, m}\right\|_{\infty} \leqslant\left\|G_{\varepsilon} * \varphi_{n, m}-\varphi_{n, m}\right\|_{\infty}+\left((\varepsilon+1)^{n}-1\right) \max _{0 \leqslant k \leqslant a}\left\|G_{k, 0}\right\|_{1} \varrho_{a}(\varphi)
$$

This proves the result by the main property of an approximate identity.

Proposition 3.1. Let $\alpha<0$ and $p_{i}, q_{i}>0$ for $i=1,2,3$. Let $u$ be a non null tempered distribution. If $H_{u, \alpha}$ is bounded from $L^{p_{1}, q_{1}} \times L^{p_{2}, q_{2}}$ into $L^{p_{3}, q_{3}}$ with norm $\left\|H_{u, \alpha}\right\|$ then $0 \leqslant 1 / p_{1}+1 / p_{2}-1 / p_{3} \leqslant 1$.

In this case, if $G(x)=\mathrm{e}^{-\pi x^{2}}$ and $1 / p=1 / p_{1}+1 / p_{2}-1 / p_{3}$ we have that $\hat{u} * D_{\lambda}^{p^{\prime}} G$ is a uniformly bounded family of functions with

$$
\sup _{\lambda>0}\left\|\hat{u} * D_{\lambda}^{p^{\prime}} G\right\|_{\infty} \leqslant C\left\|H_{u, \alpha}\right\|
$$

where $C$ is a constant that depends only of $\alpha, p_{i}$ and $q_{i}, i=1,2,3$.
Remark 3.1. When $1 / p_{1}+1 / p_{2}=1 / p_{3}$ the assertion says that $\hat{u}$ is a bounded function with $\|\hat{u}\|_{\infty} \leqslant C\left\|H_{u, \alpha}\right\|$ which is a known fact for linear multipliers (see [11]).

Proof. Let $\omega \in \mathbb{R}, \lambda>0, \alpha \in \mathbb{R} \backslash\{0,1\}$ and define $\lambda^{\prime}=(1+|\alpha|)^{-1} \lambda^{2}$. Let $f(t)=\mathrm{e}^{2 \pi \mathrm{i} \omega t} \mathrm{e}^{-\lambda^{\prime} \pi t^{2}}$ and $g(t)=\mathrm{e}^{-\left(\lambda^{\prime} /|\alpha|\right) \pi t^{2}}$. An easy computation shows that for $\alpha<0$ we have $f(x-t) g(x-\alpha t)=f(x) g(x) f(-t) g(-\alpha t)$. Thus

$$
H_{u, \alpha}(f, g)(x)=f(x) g(x) H_{u, \alpha}(f, g)(0)
$$

which says that the BHT of these Gaussian functions is the product of both functions times a constant. Since

$$
\left|H_{u, \alpha}(f, g)(0)\right|\|f g\|_{p_{3}, q_{3}}=\left\|H_{u, \alpha}(f, g)\right\|_{p_{3}, q_{3}} \leqslant\left\|H_{u, \alpha}\right\|\|f\|_{p_{1}, q_{1}}\|g\|_{p_{2}, q_{2}}
$$

we just need to compute norms in order to get the desired condition:

$$
\begin{aligned}
\|f\|_{p_{1}, q_{1}} & =\left\|M_{\omega} D_{\lambda^{\prime-1 / 2}} G\right\|_{p_{1}, q_{1}}=\lambda^{\prime-1 /\left(2 p_{1}\right)}\|G\|_{p_{1}, q_{1}} \\
\|g\|_{p_{2}, q_{2}} & =\left\|D_{\left(\lambda^{\prime} /|\alpha|\right)^{-1 / 2}} G\right\|_{p_{2}, q_{2}}=\lambda^{\prime-1 /\left(2 p_{2}\right)}|\alpha|^{1 /\left(2 p_{2}\right)}\|G\|_{p_{2}, q_{2}} \\
\|f g\|_{p_{3}, q_{3}} & =\left\|M_{\omega} D_{\lambda^{\prime-1 / 2}(1+1 /|\alpha|)^{-1 / 2}} G\right\|_{p_{3}, q_{3}}=\lambda^{\prime-1 /\left(2 p_{3}\right)}\left(1+\frac{1}{|\alpha|}\right)^{-1 /\left(2 p_{3}\right)}\|G\|_{p_{3}, q_{3}}
\end{aligned}
$$

with

$$
\|G\|_{p_{i}, q_{i}}=\left(\frac{q_{i}}{2 p_{i}}\right)^{1 / q_{i}} \Gamma\left(\frac{q_{i}}{2 p_{i}}\right)^{1 / q_{i}}\left(\frac{4}{q_{i} \pi}\right)^{1 /\left(2 p_{i}\right)}
$$

where $\Gamma$ denotes the Gamma function of Euler (see Remark 3.2 below). So

$$
\begin{aligned}
& \left|H_{u, \alpha}(f, g)(0)\right| \\
& \quad \leqslant\left\|H_{u, \alpha}\right\| \frac{\|G\|_{p_{1}, q_{1}}\|G\|_{p_{2}, q_{2}}|\alpha|^{1 /\left(2 p_{2}\right)}\left(1+\frac{1}{|\alpha|}\right)^{1 /\left(2 p_{3}\right)} \lambda^{\prime-\frac{1}{2}\left(1 / p_{1}+1 / p_{2}-1 / p_{3}\right)}}{\|G\|_{p_{3}, q_{3}}} \\
& \quad=\left\|H_{u, \alpha}\right\| \frac{\|G\|_{p_{1}, q_{1}}\|G\|_{p_{2}, q_{2}}}{\|G\|_{p_{3}, q_{3}}}|\alpha|^{\frac{1}{2}\left(1 / p_{2}-1 / p_{3}\right)}(1+|\alpha|)^{\frac{1}{2}\left(1 / p_{1}+1 / p_{2}\right)} \lambda^{-1 / p}=C \lambda^{-1 / p}
\end{aligned}
$$

for all $\lambda>0$ and $\omega \in \mathbb{R}$.

Now we work a little bit on the expression $H_{u, \alpha}(f, g)(0)$. Since

$$
f(-t) g(-\alpha t)=\mathrm{e}^{-2 \pi \mathrm{i} \omega t} \mathrm{e}^{-(1+|\alpha|) \lambda^{\prime} \pi t^{2}}=\mathrm{e}^{-2 \pi \mathrm{i} \omega t} \mathrm{e}^{-\lambda^{2} \pi t^{2}}=M_{-\omega} D_{\lambda^{-1}} G(t)
$$

we have, using the fact that $\widehat{G}=G$ and $D_{-1} G=G$, that

$$
\begin{equation*}
H_{u, \alpha}(f, g)(0)=\left(u, M_{-\omega} D_{\lambda^{-1}} G\right)=\left(\hat{u}, T_{\omega} D_{\lambda}^{1} G\right)=\left(\hat{u} * D_{\lambda}^{1} G\right)(\omega), \tag{5}
\end{equation*}
$$

and we can rewrite the previous result for all $\lambda>0$ and $\omega \in \mathbb{R}$ as

$$
\left|\left(\hat{u} * D_{\lambda}^{1} G\right)(\omega)\right| \leqslant C \lambda^{-1 / p} .
$$

a) If $1 / p<0$ we prove that $u \equiv 0$ by showing that the family of functions $m_{\lambda}(\omega)=$ $\left(\hat{u} * D_{\lambda}^{1} G\right)(\omega)$ converges pointwise to zero and distributionally to $\hat{u}$ when $\lambda$ tends to zero.

On the one hand, we see that $m_{\lambda}$ are bounded functions (and so locally integrable) with $\left\|m_{\lambda}\right\|_{\infty} \leqslant C \lambda^{-1 / p} \leqslant C$ for $\lambda<1$ and $\lim _{\lambda \rightarrow 0} m_{\lambda}(\omega)=0$ for all $\omega \in \mathbb{R}$.

On the other hand, since $\left(D_{\lambda}^{1} G\right)_{\lambda>0}$ is an approximate identity we have proven in Lemma 3.1 that $\left.\left\{D_{\lambda}^{1} G * \varphi\right)\right\}_{\lambda>0}$ converges to $\varphi$ in the topology $\mathscr{T}_{\mathcal{S}}$. Thus, by the continuity of $\hat{u}$ we have for all $\varphi \in \mathcal{S}$

$$
\lim _{\lambda \rightarrow 0}\left(u_{m_{\lambda}}, \varphi\right)=\lim _{\lambda \rightarrow 0}\left(\hat{u} * D_{\lambda}^{1} G, \varphi\right)=\lim _{\lambda \rightarrow 0}\left(\hat{u}, D_{\lambda}^{1} G * \varphi\right)=(\hat{u}, \varphi)
$$

With both facts and the Dominated Convergence Theorem of Lebesgue we have

$$
(\hat{u}, \varphi)=\lim _{\lambda \rightarrow 0}\left(u_{m_{\lambda}}, \varphi\right)=\lim _{\lambda \rightarrow 0} \int_{\mathbb{R}} m_{\lambda}(\omega) \varphi(\omega) \mathrm{d} \omega=0 .
$$

b) If $1 / p=0$ we still know that $m_{\lambda}$ define a family of bounded functions with $\left\|m_{\lambda}\right\|_{\infty} \leqslant C$ for all $\lambda>0$ that converge distributionally to $\hat{u}$ when $\lambda$ tends to zero. We use this fact to show that $\hat{u}$ must be a bounded function and that, actually, the convergence is also pointwise. From the above,

$$
|(\hat{u}, \varphi)|=\lim _{\lambda \rightarrow 0}\left|\int_{\mathbb{R}} m_{\lambda}(\omega) \varphi(\omega) \mathrm{d} \omega\right| \leqslant \varlimsup_{\lambda \rightarrow 0}\left\|m_{\lambda}\right\|_{\infty}\|\varphi\|_{1} \leqslant C\|\varphi\|_{1}
$$

for all $\varphi \in \mathcal{S}$ and thus $\hat{u}$ is a distribution associated to a bounded function. Moreover, by the property of approximate identity, we have that

$$
\lim _{\lambda \rightarrow 0} m_{\lambda}(\omega)=\lim _{\lambda \rightarrow 0}\left(\hat{u} * D_{\lambda}^{1} G\right)(\omega)=\hat{u}(\omega)
$$

almost everywhere (at all Lebesgue points of $\hat{u}$ ).
c) If $0<1 / p \leqslant 1$ our condition says that $\left|\left(\hat{u} * D_{\lambda}^{p^{\prime}} G\right)(\omega)\right| \leqslant C$ for all $\lambda>0$ and $\omega \in \mathbb{R}$ which is the main statement of the proposition.

We still have that $m_{\lambda}=\hat{u} * D_{\lambda}^{1} G$ define a family of bounded functions that converges distributionally to $\hat{u}$ and satisfies $\left\|m_{\lambda}\right\|_{\infty} \leqslant C \lambda^{-1 / p}$ for all $\lambda>0$.
d) If $1<1 / p$ we prove directly that $u \equiv 0$. The previous condition can be written as
$\left|\left(\hat{u} * D_{\lambda} G\right)(\omega)\right| \leqslant C \lambda^{1 / p^{\prime}}$ with $p^{\prime}<0$. Moreover, since $H_{u, \alpha}$ is bounded and translation invariant by the property (2), we have that $H_{T_{y} u, \alpha}$ is also a bounded operator with the same constant and thus it satisfies $\left|\left(\widehat{T_{y} u} * D_{\lambda} G\right)(\omega)\right| \leqslant C \lambda^{1 / p^{\prime}}$ for every $y, \omega \in \mathbb{R}$. With this we can write

$$
\begin{aligned}
\lim _{\lambda \rightarrow 0}\left|\left(u, T_{y} D_{\lambda}^{1} G\right)\right| & \left.=\lim _{\lambda \rightarrow 0} \mid \widehat{T_{-y} u}, D_{\lambda^{-1}} G\right) \mid \\
& \left.=\lim _{\lambda \rightarrow 0} \mid \widehat{T_{-y} u} * D_{\lambda^{-1}} G\right)(0) \mid \leqslant \lim _{\lambda \rightarrow 0} C \lambda^{-1 / p^{\prime}}=0
\end{aligned}
$$

Thus for every $\varphi \in \mathcal{S}$ we have by the Dominated Convergence Theorem

$$
(u, \varphi)=\lim _{\lambda \rightarrow 0}\left(u, \varphi * D_{\lambda}^{1} G\right)=\lim _{\lambda \rightarrow 0} \int_{\mathbb{R}} \varphi(y)\left(u, T_{y} D_{\lambda}^{1} G\right) \mathrm{d} y=0
$$

Now we deal with the case of $\alpha>0$. If $\alpha>1$ and $p_{3} \geqslant 1$ the duality formula (4) with $1-\alpha<0$ allows us to apply the former result to $H_{D_{-1} u, 1-\alpha}$ in the following way: if $f, g, h$ are some properly chosen Gaussian functions then

$$
\left\langle h, H_{u, \alpha}(f, g)\right\rangle=\left\langle H_{D_{-1} u, 1-\alpha}(h, g), f\right\rangle=H_{D_{-1} u, 1-\alpha}(h, g)(0)\langle h g, f\rangle
$$

which, if we assume the operator to be bounded, implies

$$
\left|H_{D_{-1} u, 1-\alpha}(h, g)(0)\right| \leqslant\left\|H_{u, \alpha}\right\| \frac{\|f\|_{p_{1}, q_{1}}\|g\|_{p_{2}, q_{2}}\|h\|_{p_{3}^{\prime}, q_{3}^{\prime}}}{|\langle h g, f\rangle|}=C \lambda^{-1 / p} .
$$

Thus by (5) and using $D_{-1}(f * g)=D_{-1} f * D_{-1} g, D_{-1} \hat{u}=\widehat{D_{-1} u}$ we have

$$
\left|\left(\hat{u} * D_{\lambda}^{1} G\right)(-\omega)\right|=\left|\left(\widehat{D_{-1} u} * D_{\lambda}^{1} G\right)(\omega)\right|=\left|H_{D_{-1} u, 1-\alpha}(h, g)(0)\right| \leqslant C \lambda^{-1 / p}
$$

From here the same ideas lead to the same conclusion.
Finally, if $0<\alpha<1$ and $p_{3} \geqslant 1$, the commutativity formula (3) with $\alpha^{-1}>1$ and the duality formula (4) with $1-\alpha^{-1}<0$ allow us to apply the same ideas to $H_{D_{-1} D_{\alpha}^{1} u, 1-\alpha^{-1}}$ to get the same conclusion:

$$
\begin{aligned}
\left\langle h, H_{u, \alpha}(f, g)\right\rangle & =\left\langle h, H_{D_{\alpha}^{1} u, \alpha^{-1}}(g, f)\right\rangle \\
& =\left\langle H_{D_{-1} D_{\alpha}^{1} u, 1-\alpha^{-1}}(h, f), g\right\rangle=H_{D_{-1} D_{\alpha}^{1} u, 1-\alpha^{-1}}(h, f)(0)\langle h f, g\rangle,
\end{aligned}
$$

which implies

$$
\left|H_{D_{-1} D_{\alpha}^{1} u, 1-\alpha^{-1}}(h, f)(0)\right| \leqslant\left\|H_{u, \alpha}\right\| \frac{\|f\|_{p_{1}, q_{1}}\|g\|_{p_{2}, q_{2}}\|h\|_{p_{3}^{\prime}, q_{3}^{\prime}}}{|\langle h f, g\rangle|}=C \lambda^{-1 / p} .
$$

Now, using the fact that $D_{\alpha}(f * g)=D_{\alpha}^{q} f * D_{\alpha}^{q^{\prime}} g$ we get by (5)

$$
\begin{aligned}
\left|\left(\hat{u} * D_{\alpha \lambda}^{1} G\right)(-\alpha \omega)\right| & =\left|D_{\alpha^{-1}}\left(\hat{u} * D_{\alpha}^{1} D_{\lambda}^{1} G\right)(-\omega)\right|=\left|\left(D_{\alpha^{-1}} \hat{u} * D_{\lambda}^{1} G\right)(-\omega)\right| \\
& =\left|\left(\widehat{D_{-1} D_{\alpha}^{1}} u * D_{\lambda}^{1} G\right)(\omega)\right|=\left|H_{D_{-1} D_{\alpha}^{1} u, 1-\alpha^{-1}}(h, f)(0)\right| \leqslant C \lambda^{-1 / p}
\end{aligned}
$$

and we finish by the same ideas as before.
Remark 3.2. Since $G$ is even and non-increasing in $[0, \infty)$, we know that $G^{*}=$ $D_{2} G$ and so we can compute $\|G\|_{p_{1}, q_{1}}^{q_{1}}$ as follows

$$
\begin{aligned}
\frac{q_{1}}{p_{1}} \int_{0}^{\infty} t^{q_{1} / p_{1}} \mathrm{e}^{-\frac{1}{4} q_{1} \pi t^{2}} \frac{\mathrm{~d} t}{t} & =\frac{q_{1}}{2 p_{1}}\left(\frac{4}{q_{1} \pi}\right)^{q_{1} /\left(2 p_{1}\right)} \int_{0}^{\infty} t^{q_{1} /\left(2 p_{1}\right)} \mathrm{e}^{-t} \frac{\mathrm{~d} t}{t} \\
& =\frac{q_{1}}{2 p_{1}}\left(\frac{4}{q_{1} \pi}\right)^{q_{1} /\left(2 p_{1}\right)} \Gamma\left(\frac{q_{1}}{2 p_{1}}\right) .
\end{aligned}
$$

3.2. Bilinear Young inequality. The next result is the generalization of the Young inequality to our bilinear non-convolution operators. We pay now special attention to the dependence of the constants on the parameter $\alpha$. In order to deal with a more general and symmetric operator, we change a little bit its definition. For the next proposition we let BHT be the operator

$$
H_{K, \alpha, \beta}(f, g)(x)=\int_{\mathbb{R}} f(x-\alpha t) g(x-\beta t) K(t) \mathrm{d} t
$$

defined for all $\alpha, \beta, x \in \mathbb{R}$ and $f, g \in \mathcal{S}$.

Proposition 3.2 (Bilinear Young inequality). Let $p_{0} \geqslant 1$. If $K \in L^{p_{0}}$ then $H_{K, \alpha, \beta}$ is a bounded operator from $L^{p_{1}} \times L^{p_{2}}$ to $L^{p_{3}}$ with $p_{i} \geqslant 1$ for $i=1,2,3$ and $p_{1}^{-1}+p_{2}^{-1}+p_{0}^{-1}=1+p_{3}^{-1}$, and all $\alpha, \beta \in \mathbb{R} \backslash\{0\}$ such that $\alpha \neq \beta$. Moreover,

$$
\left\|H_{K, \alpha, \beta}(f, g)\right\|_{p_{3}} \leqslant C_{\alpha, \beta, p_{0}, p_{1}, p_{2}}\|K\|_{p_{0}}\|f\|_{p_{1}}\|g\|_{p_{2}}
$$

Remark 3.3. Notice that $p_{1}^{-1}+p_{2}^{-1}-p_{3}^{-1}=p_{0}^{\prime-1} \in[0,1]$ as Proposition 3.1 says it must be. See also that this condition can be rewritten as $p_{1}^{-1}+p_{2}^{-1}+p_{3}^{\prime-1}=1+p_{0}^{\prime-1}$ and so the point $\left(p_{1}^{-1}, p_{2}^{-1}, p_{3}^{\prime-1}\right) \in \mathbb{R}^{3}$ belongs to the plane $x+y+z=1+p_{0}^{\prime-1}$ with $1+p_{0}^{\prime-1} \in[1,2]$.

Proof. Let $p \geqslant 1, f, g, h, K \in \mathcal{S}$ and

$$
I=\left|\int_{\mathbb{R}} h(x) \int_{\mathbb{R}} f(x-\alpha t) g(x-\beta t) K(t) \mathrm{d} t \mathrm{~d} x\right|
$$

We denote here $f_{a, b}(x, t)=f(a x+b t)$. By the Hölder inequality and some changes of variables $I \leqslant\left\|f_{1,-\alpha} g_{1,-\beta}\right\|_{L^{p}\left(\mathbb{R}^{2}\right)}\left\|K_{0,1} h_{1,0}\right\|_{L^{p^{\prime}\left(\mathbb{R}^{2}\right)}}=|\alpha-\beta|^{-1 / p}\|f\|_{p}\|g\|_{p}\|K\|_{p^{\prime}}\|h\|_{p^{\prime}}$, i.e.

$$
\begin{equation*}
\left\|H_{K, \alpha, \beta}(f, g)\right\|_{p} \leqslant|\alpha-\beta|^{-1 / p}\|f\|_{p}\|g\|_{p}\|K\|_{p^{\prime}} ; \tag{6}
\end{equation*}
$$

$I \leqslant\left\|K_{0,1} g_{1,-\beta}\right\|_{L^{p}\left(\mathbb{R}^{2}\right)}\left\|f_{1,-\alpha} h_{1,0}\right\|_{L^{p^{\prime}\left(\mathbb{R}^{2}\right)}}=|\alpha|^{-1 / p^{\prime}}\|f\|_{p^{\prime}}\|g\|_{p}\|K\|_{p}\|h\|_{p^{\prime}}$, i.e.

$$
\begin{equation*}
\left\|H_{K, \alpha, \beta}(f, g)\right\|_{p} \leqslant|\alpha|^{-1 / p^{\prime}}\|f\|_{p^{\prime}}\|g\|_{p}\|K\|_{p} \tag{7}
\end{equation*}
$$

$I \leqslant\left\|f_{1,-\alpha} K_{0,1}\right\|_{L^{p}\left(\mathbb{R}^{2}\right)}\left\|g_{1,-\beta} h_{1,0}\right\|_{L^{p^{\prime}}\left(\mathbb{R}^{2}\right)}=|\beta|^{-1 / p^{\prime}}\|f\|_{p}\|g\|_{p^{\prime}}\|K\|_{p}\|h\|_{p^{\prime}}$, i.e.

$$
\begin{equation*}
\left\|H_{K, \alpha, \beta}(f, g)\right\|_{p} \leqslant|\beta|^{-1 / p^{\prime}}\|f\|_{p}\|g\|_{p^{\prime}}\|K\|_{p} . \tag{8}
\end{equation*}
$$

We associate each bound of the operator from $L^{p_{1}} \times L^{p_{2}}$ to $L^{p_{3}}$ to the point $\left(p_{1}^{-1}, p_{2}^{-1}, p_{3}^{\prime-1}\right) \in \mathbb{R}^{3}$ in the plane $x+y+z=1+p^{-1}$. In this way and taking the values $p=1$ and $p=\infty$ in each of the three previous inequalities we consider the extremal points $(1,1,0),(0,0,1)$ (from the first one), $(0,1,0),(1,0,1)$ (from the second), $(1,0,0)$ and $(0,1,1)$ (from the third). In this way, by using trilinear interpolation between two spaces iteratively we get the bounds on the surface of the convex hull of the previous six points, that is, on the surface of the octahedron drawn in the following diagram

where we write the constants of boundedness in each vertex and each face. We show how to get one of them: from (7) and (8) we know that $\left\|H_{K, \alpha, \beta}(f, g)\right\|_{\infty} \leqslant$ $|\alpha|^{-1}\|f\|_{1}\|g\|_{\infty}\|K\|_{\infty}$, and $\left\|H_{K, \alpha, \beta}(f, g)\right\|_{\infty} \leqslant|\beta|^{-1}\|f\|_{\infty}\|g\|_{1}\|K\|_{\infty}$, so we have $\left\|H_{K, \alpha, \beta}(f, g)\right\|_{\infty} \leqslant|\alpha|^{-1 / p}|\beta|^{-1 / p^{\prime}}\|f\|_{p}\|g\|_{p^{\prime}}\|K\|_{\infty}$.

In the same way, from (7) and (6) $\left\|H_{K, \alpha, \beta}(f, g)\right\|_{\infty} \leqslant|\alpha|^{-1}\|f\|_{1}\|g\|_{\infty}\|K\|_{\infty}$ and $\left\|H_{K, \alpha, \beta}(f, g)\right\|_{\infty} \leqslant\|f\|_{\infty}\|g\|_{\infty}\|K\|_{1}$, we get

$$
\left\|H_{K, \alpha, \beta}(f, g)\right\|_{\infty} \leqslant|\alpha|^{-1 / p}\|f\|_{p}\|g\|_{\infty}\|K\|_{p^{\prime}}
$$

Interpolating both cases we get

$$
\left\|H_{K, \alpha, \beta}(f, g)\right\|_{\infty} \leqslant|\alpha|^{-1 / p}|\beta|^{-1 / q_{1}}\|f\|_{p}\|g\|_{q_{1}}\|K\|_{q_{2}}
$$

with $q_{1}^{-1}+q_{2}^{-1}={p^{\prime}}^{-1}$. Using again (6), $\left\|H_{K, \alpha, \beta}(f, g)\right\|_{1} \leqslant|\alpha-\beta|^{-1}\|f\|_{1}\|g\|_{1}\|K\|_{\infty}$, we finally have

$$
\left\|H_{K, \alpha, \beta}(f, g)\right\|_{p_{3}} \leqslant|\alpha|^{-1 / p_{1}}|\beta|^{-1 / p_{2}}|\alpha-\beta|^{-1 / p_{3}}\|f\|_{p_{1}}\|g\|_{p_{2}}\|K\|_{p_{0}}
$$

where $p_{3}^{-1}=\theta, p_{1}^{-1}=(1-\theta) p^{-1}+\theta, p_{2}^{-1}=(1-\theta) q_{1}^{-1}+\theta$ and $p_{0}^{-1}=(1-\theta) q_{2}^{-1}$, which is the stated result since $p_{1}^{-1}+p_{2}^{-1}+p_{0}^{-1}=1+p_{3}^{-1}$.

Now in order to get bounds in the interior of the octahedron we use interpolation between six spaces. In this way, each point $p=\left(p_{1}^{-1}, p_{2}^{-1}, p_{3}^{\prime-1}\right)$ can be written as the convex linear combination of the six vertices in the following way

$$
\begin{aligned}
p= & \left(\lambda_{2}+p_{3}^{-1}-p_{2}^{-1}\right)(1,0,0)+\left(\lambda_{1}+p_{3}^{-1}-p_{1}^{-1}\right)(0,1,0)+\left(p_{3}^{\prime-1}-\lambda_{1}-\lambda_{2}\right)(0,0,1) \\
& +\lambda_{1}(1,0,1)+\lambda_{2}(0,1,1)+\left(p_{1}^{-1}+p_{2}^{-1}-p_{3}^{-1}-\lambda_{1}-\lambda_{2}\right)(1,1,0),
\end{aligned}
$$

for every $\lambda_{1}, \lambda_{2} \in[0,1]$ such that $\max \left(p_{1}^{-1}-p_{3}^{-1}, 0\right) \leqslant \lambda_{1}, \max \left(p_{2}^{-1}-p_{3}^{-1}, 0\right) \leqslant \lambda_{2}$ and $\lambda_{1}+\lambda_{2} \leqslant \min \left(p_{3}^{\prime-1}, p_{0}^{\prime-1}\right)$. We denote by $D$ such non empty triangle (notice that $p_{i}^{-1}-p_{3}^{-1} \leqslant p_{1}^{-1}+p_{2}^{-1}-p_{3}^{-1}=p_{0}^{\prime-1} \leqslant 1$ and $\max \left(p_{1}^{-1}-p_{3}^{-1}, 0\right)+\max \left(p_{2}^{-1}-\right.$ $\left.\left.p_{3}^{-1}, 0\right) \leqslant \min \left(p_{3}^{\prime-1}, p_{0}^{\prime-1}\right)\right)$. Also notice that this decomposition implies this other one for $\tilde{p}=\left(p_{1}^{-1}, p_{2}^{-1}, p_{3}^{-1}\right)$

$$
\begin{aligned}
\tilde{p}= & \left(\lambda_{2}+p_{3}^{-1}-p_{2}^{-1}\right)(1,0,1)+\left(\lambda_{1}+p_{3}^{-1}-p_{1}^{-1}\right)(0,1,1) \\
& +\left(1-p_{3}^{\prime-1}+\lambda_{1}+\lambda_{2}\right)(0,0,0)+\lambda_{1}(1,0,0)+\lambda_{2}(0,1,0) \\
& +\left(p_{1}^{-1}+p_{2}^{-1}-p_{3}^{-1}-\lambda_{1}-\lambda_{2}\right)(1,1,1)
\end{aligned}
$$

in order to interpolate. So, using Theorem 2.1 we get

$$
\left\|H_{K, \alpha, \beta}(f, g)\right\|_{p_{3}} \leqslant|\alpha|^{-\lambda_{1}}|\beta|^{-\lambda_{2}}|\alpha-\beta|^{-\left(1 / p_{0}^{\prime}-\lambda_{1}-\lambda_{2}\right)}\|f\|_{p_{1}}\|g\|_{p_{2}}\|K\|_{p_{0}}
$$

for every $\lambda_{1}, \lambda_{2} \in D$, and we want now to minimize. Since $D$ is a convex domain and $F(x, y)=\left(|\alpha||\alpha-\beta|^{-1}\right)^{-x}\left(|\beta||\alpha-\beta|^{-1}\right)^{-y}$ is a convex function in $D$, the minimal constant is attained in one of the three vertices of the triangle:

$$
\begin{aligned}
& \left(\max \left(p_{1}^{-1}-p_{3}^{-1}, 0\right), \max \left(p_{2}^{-1}-p_{3}^{-1}, 0\right)\right), \\
& \left(\max \left(p_{1}^{-1}-p_{3}^{-1}, 0\right), \min \left(p_{1}^{\prime-1}, p_{2}^{-1}, p_{3}^{\prime-1}, p_{0}^{\prime-1}\right)\right), \\
& \left(\min \left(p_{1}^{-1}, p_{2}^{\prime-1}, p_{3}^{\prime-1}, p_{0}^{\prime-1}\right) ; \max \left(p_{2}^{-1}-p_{3}^{-1}, 0\right)\right)
\end{aligned}
$$

that is,

$$
\left\|H_{K, \alpha, \beta}(f, g)\right\|_{p_{3}} \leqslant C_{\alpha, \beta, p_{1}, p_{2}, p_{0}}\|f\|_{p_{1}}\|g\|_{p_{2}}\|K\|_{p_{0}}
$$

where $C_{\alpha, \beta, p_{1}, p_{2}, p_{0}}$ is the minimum of the three quantities:

$$
\begin{aligned}
& |\alpha|^{-\max \left(p_{1}^{-1}-p_{3}^{-1}, 0\right)}|\beta|^{-\max \left(p_{2}^{-1}-p_{3}^{-1}, 0\right)}|\alpha-\beta|^{-\min \left(p_{1}^{-1}, p_{2}^{-1}, p_{3}^{-1}, p_{0}^{\prime-1}\right)}, \\
& |\alpha|^{-\max \left(p_{1}^{-1}-p_{3}^{-1}, 0\right)}|\beta|^{-\min \left(p_{1}^{\prime}-1, p_{2}^{-1}, p_{3}^{\prime}-1, p_{0}^{\prime}-1\right)}|\alpha-\beta|^{-\max \left(p_{2}^{-1}-p_{1}^{\prime-1}, 0\right)}, \\
& \left.|\alpha|^{-\min \left(p_{1}^{-1}, p_{2}^{\prime}-1, p_{3}^{\prime}-1, p_{0}^{\prime}-1\right.}\right)|\beta|^{-\max \left(p_{2}^{-1}-p_{3}^{-1}, 0\right)}|\alpha-\beta|^{-\max \left(0, p_{1}^{-1}-p_{2}^{\prime}-1\right)},
\end{aligned}
$$

which, on the surface of the octahedron, are the same bounds as we already had (in fact, the three bounds coincide on each face).
3.3. The third condition. The last result gives a sufficient condition for boundedness of bilinear multipliers. It gives a condition on the symbol of the operator instead of the kernel.

Proposition 3.3. Let $m \in L^{q}\left(\mathbb{R}^{2}\right)$ with $1 \leqslant q \leqslant 4$. Then $m$ is $\left(p_{1}, p_{2}, p_{3}\right)$ multiplier for all exponents such that $1 \leqslant p_{1}, p_{2}, p_{3}^{\prime} \leqslant \min (2, q), q \notin\left\{p_{1}, p_{2}, p_{3}^{\prime}\right\}$ and $p_{1}^{-1}+p_{2}^{-1}+p_{3}^{\prime-1}=1+2 q^{-1}$. Moreover, $\|m\|_{\mathscr{M} B_{p_{1}, p_{2}, p_{3}}} \leqslant\|m\|_{q}$.

Proof. By duality it is enough to prove that for every $f, g, h \in \mathcal{S}$

$$
I=\left|\int_{\mathbb{R}^{2}} \hat{f}(\xi) \hat{g}(\eta) m(\xi, \eta) \hat{h}(-\xi-\eta) \mathrm{d} \xi \mathrm{~d} \eta\right| \leqslant C_{m}\|f\|_{p_{1}}\|g\|_{p_{2}}\|h\|_{p_{3}^{\prime}}
$$

If $q=1$ then $I \leqslant\|m\|_{1}\|\hat{f}\|_{\infty}\|\hat{g}\|_{\infty}\|\hat{h}\|_{\infty} \leqslant\|m\|_{1}\|f\|_{1}\|g\|_{1}\|h\|_{1}$.
If $q>1$, we define $\tilde{p}=\left(\tilde{p}_{1}, \tilde{p}_{2}, \tilde{p}_{3}^{\prime}\right)$ by

$$
\tilde{p}_{1}=\frac{p_{1}(q-1)}{q-p_{1}}, \quad \tilde{p}_{2}=\frac{p_{2}(q-1)}{q-p_{2}}, \quad \tilde{p}_{3}^{\prime}=\frac{p_{3}^{\prime}(q-1)}{q-p_{3}^{\prime}}
$$

which satisfy:

$$
1 \leqslant \tilde{p}_{1}, \tilde{p}_{2}, \tilde{p}_{3}^{\prime} \leqslant \infty, \quad \tilde{p}_{i}^{\prime}=\frac{p_{i}^{\prime}}{q^{\prime}}, i=1,2, \quad \tilde{p}_{3}=\frac{p_{3}}{q^{\prime}}, \quad \frac{1}{\tilde{p}_{1}^{\prime}}+\frac{1}{\tilde{p}_{2}^{\prime}}+\frac{1}{\tilde{p}_{3}}=2
$$

Then, by the Hölder, the Young and the Hausdorff-Young inequalities we have

$$
\left.\begin{array}{rl}
I & \leqslant\|m\|_{q}\left(\int_{\mathbb{R}^{2}}|\hat{f}(\xi)|^{q^{\prime}}|\hat{g}(\eta)|^{q^{\prime}}|\hat{h}(-\xi-\eta)|^{q^{\prime}} \mathrm{d} \xi \mathrm{~d} \eta\right)^{1 / q^{\prime}} \\
& =\|m\|_{q}\left(|\hat{f}|^{q^{\prime}} *|\hat{g}|^{q^{\prime}} *|\hat{h}|^{q^{\prime}}\right)(0)^{1 / q^{\prime}} \\
& \leqslant\|m\|_{q}\left\||\hat{f}|^{q^{\prime}} *|\hat{g}|^{q^{\prime}} *|\hat{h}|^{q^{\prime}}\right\|\left\|_{\infty}^{1 / q^{\prime}} \leqslant\right\| m \|_{q}\left(\||\hat{f}| q^{q^{\prime}}\right.
\end{array}\left\|_{\tilde{p}_{1}^{\prime}}\right\||\hat{g}|^{q^{\prime}}\left\|_{\tilde{p}_{2}^{\prime}}\right\| \hat{h}| |^{q^{\prime}} \|_{\tilde{p}_{3}}\right)^{1 / q^{\prime}} .
$$

Remark 3.4. Although $K \in L^{p}$ for some $1<p \leqslant 2$, none of the functions $m(\xi, \eta)=\hat{K}(\alpha \xi+\beta \eta)$ belongs to $L^{q}\left(\mathbb{R}^{2}\right)$ for $1 \leqslant q \leqslant 4$. So, this result is neither a generalization nor a special case of Proposition 3.2.

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