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ON THE LIMIT-3 CLASSIFICATION OF THE SQUARE OF A SECOND-ORDER, LINEAR DIFFERENTIAL EXPRESSION

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1. Introduction. In recent years the work of several mathematicians has been directed towards a study of the formal powers of the symmetric, second-order differential expression M, where, for suitably differentiable complex-valued f, M is defined by

(1.1)
$$M[f] = -(pf')' + qf \quad on \quad I \quad (' \equiv d/dx).$$

Here *I* is an interval of the real line, and the coefficients *p* and *q* are real-valued, with p > 0, on *I*. The formal powers M^n , where n = 1, 2, 3, ..., of *M* are defined by $M^1 = M$ and $M^n = M[M^{n-1}]$ for n = 2, 3, ...; this definition requires certain differentiability properties of the coefficients *p* and *q* if M^n is also to be a differential expression.

The first result on the relationship between M and M^2 , as symmetric differential expressions, were given by Chaudhuri and Everitt in [1]. Since then there have been contributions to the properties of M^n , and more general polynomials in M, from Everitt and Giertz [3], [4] and [5], Kauffman [6], Kumar [7], Read [9] and Zettl [10]. In particular [5] is a survey article on the general powers M^n of M.

For the general definition of a real-valued formally symmetric (equivalently formally self-adjoint) differential expression see [2, Ch. XIII, 2.1] or [8, section 15]. When M is given by (1.1) and the power M^n exists then M^n is also formally symmetric. In the particular case of (1.1) with p = 1, i.e. p(x) = 1 ($x \in I$), we have

$$M[f] = -f'' + qf \quad \text{on} \quad I$$

and

(1.3)
$$M^{2}[f] = f^{(4)} - (2qf')' + (q^{2} - q'')f \text{ on } I.$$

Here derivatives of order greater than 2 are denoted by $f^{(3)}$ and $f^{(4)}$.

The results discussed in this paper are concerned with M and M^2 , as given by (1.2) and (1.3), in the case when the interval I is the half-line $[0, \infty)$. In particular one of the results, see Theorem 1 below, answers a previously unsolved problem posed by Chaudhuri and Everitt in 1969, see [1, section 12].

Since we deal only with the half-line $[0, \infty)$ we use the abbreviations L^2 for the Hilbert function space $L^2(0, \infty)$, and AC_{loc} for $AC_{loc}[0, \infty)$, i.e. those complex-valued functions defined on $[0, \infty)$ which are absolutely continuous on all compact sub-intervals of $[0, \infty)$.

Throughout the paper we assume that the coefficient q in (1.2) and (1.3) satisfies the following basic conditions:

(1.4) (i)
$$q$$
 is real-valued on $[0, \infty)$

(ii)
$$q' \in AC_{loc}$$
,

which ensure that both M and M^2 exist as formally symmetric differential expressions on $[0, \infty)$.

In these circumstances the minimal closed symmetric operator generated by M in L^2 has deficiency indices either (1,1) or (2,2), the limit-point and limit-circle classifications at ∞ , respectively, of Weyl; see [2, page 1306] or [8, section 17.5]. Similarly the deficiency indices corresponding to M^2 in L^2 are (2,2), (3,3) or (4,4) and we refer to M^2 as limit-r at ∞ when these are (r,r) for r=2,3 or 4, respectively.

The problem raised in [1, section 12] concerned the existence of coefficients q such that M, given by (1.2), is limit-point and M^2 is limit-3, both at ∞ . At the time of writing of [1] it was known that M^2 is limit-4 if and only if M is limit-circle and that M^2 is frequently limit-2 when M is limit-point, but the general theory and examples available left the above problem open. Since then, several mathematicians have tried to find an example of such a coefficient q or, conversely, to prove that M^2 is limit-2 if and only if M is limit-point at ∞ . The situation is further complicated by a recent result in [4] which states that if q satisfies (1.4) and, additionally, for some non-negative numbers k and X

$$(1.5) q(x) \ge -kx^2 (x \in [X, \infty))$$

then M is limit-point at ∞ (previously known, see [8, section 23]) and M^2 is limit-2 at ∞ . This shows that if there is a coefficient q for which M is limit-point at ∞ and M^2 is limit-3 at ∞ , then q will have to enjoy excursions through the $-kx^2$ barrier, for every positive number k, and yet do so in a way as to keep M in the limit-point case at ∞ .

An answer to this problem has now been obtained and is given in

Theorem 1. There exist coefficients q which satisfy the basic conditions (1.4) such that when the differential expressions M and M^2 on $[0, \infty)$ are defined by (1.2) and (1.3) then

- (a) M is limit-point at ∞
- (b) M^2 is limit-3 at ∞ .

Proof. This is given in sections 2 and 3 below.

In the proof of Theorem 1 two particular results are used which are themselves of interest and these are stated here separately since they throw some light on the nature of the integrable-square solutions of the differential equations associated with M and M^2 . These equations are

(1.6)
$$M[y] = 0$$
 on $[0, \infty)$ and $M^2[y] = 0$ on $[0, \infty)$;

both regular at all points of $[0, \infty)$ but with singular points at ∞ .

Theorem 2. Assume that (1.4) holds and that the equation $M^2[y] = 0$ on $[0, \infty)$ has exactly 3 linearly independent solutions which are of integrable-square on $[0, \infty)$, i.e. solutions in $L^2(0, \infty)$; then M^2 is limit-3 at ∞ , M is limit-point at ∞ and the equation M[y] = 0 on $[0, \infty)$ has exactly one linearly independent solution in $L^2(0, \infty)$.

Theorem 3. Assume that (1.4) holds; then the following two statements are equivalent:

- (1) The equation $M^2[y] = 0$ on $[0, \infty)$ has exactly three linearly independent solutions in $L^2(0, \infty)$.
- (2) The equation M[y] = 0 on $[0, \infty)$ has real-valued solutions φ and $\psi \neq 0$ such that

$$\varphi \notin L^2(0,\infty)$$
, $\psi F \in L^2(0,\infty)$

where
$$F(x) = \int_0^x \varphi^2 \quad (x \in [0, \infty)).$$

We outline the contents of the paper. Section 2 contains proofs of Theorems 2 and 3 and associated results. The proof of Theorem 1 is given in section 3. In section 4 there are some remarks about the extent of the oscillations in such coefficients q as determined by the construction in the proof of Theorem 1. There is a list of references.

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2. Proof of Theorem 2 and Theorem 3. From now on we assume that q satisfies the basic conditions (1.4). It is then a standard result that the number of linearly independent solutions in L^2 of the eigenvalue problem

(2.1)
$$M^{2}[y] = \lambda y \quad \text{on} \quad [0, \infty)$$

does not depend on λ as long as λ is a complex but non-real number, and also that this number is r if and only if M^2 is limit-r. The situation is more complicated when λ is real. However, the following statements are known to hold true, see e.g. [5]:

- (a) When M^2 is limit-r and λ is real, then (2.1) has at most r linearly independent solutions which are of integrable square on $[0, \infty)$, that is in L^2 .
- (b) M^2 is limit-4 if and only if M is limit-2 (that is, in the limit-circle condition) in which case all solutions of (2.1) are in L^2 , also for every real λ .

Theorem 2 is an almost direct consequence of (a) and (b). In fact assume, as in Theorem 2, that the equation $M^2[y] = 0$ on $[0, \infty)$ has exactly 3 linearly independent solutions in L^2 . Then M^2 can not be limit-2 according to (a), and it can not be limit-4 in view of (b). Thus M^2 must be limit-3 and, again from (b), M must be limit-1 so that the equation M[y] = 0 may have at most one linearly independent solution in L^2 according to (a). But if it has no such solution, then $M^2[y] = 0$ can have at most two linearly independent solutions in L^2 , since every solution of M[y] = 0 is also a solution of $M^2[y] = 0$. This completes the proof of Theorem 2.

To prove Theorem 3 we begin by considering certain solutions of $M^2[y] = 0$ given in terms of solutions of M[y] = 0. Let f_1 and f_2 be any two linearly independent real-valued functions which satisfy M[y] = 0, and are normalised so that $f_1f'_2 - f'_1f_2 = 1$. Define f_3 and f_4 by

$$f_3(x) = f_1(x) \int_0^x f_1 f_2 - f_2(x) \int_0^x f_1^2 \quad (x \in [0, \infty)),$$

and

$$f_4(x) = f_1(x) \int_0^x f_2^2 - f_2(x) \int_0^x f_1 f_2 \quad (x \in [0, \infty)).$$

A direct calculation verifies that

$$M[f_3] = f_1$$
 and $M[f_4] = f_2$,

and it follows that f_i (i = 1, 2, 3, 4) are all solutions of $M^2[y] = 0$. They are linearly independent, since if

$$f = a_1 f_1 + a_2 f_2 + a_3 f_3 + a_4 f_4 = 0$$

then

$$M[f] = a_3 f_1 + a_4 f_2 = 0,$$

which shows that $a_3 = a_4 = 0$ and thus also $a_1 = a_2 = 0$.

In one direction, the proof is now essentially contained in the following lemma concerning properties of certain pairs of functions in L^2_{loc} .

Lemma 1. Let f and g be two functions which are defined and locally of integrable-square on $[0, \infty)$. Assume that

$$f \notin L^2$$
 and $gF \in L^2$ where $F(x) = \int_0^x |f|^2$ $(x \in [0, \infty))$;

then

$$g \in L^2$$
 and $fG \in L^2$ where $G(x) = \int_x^\infty |g|^2 \ (x \in [0, \infty)),$

$$fg \in L$$
 and $fH \in L^2$ where $H(x) = \int_x^{\infty} |fg| \ (x \in [0, \infty))$.

Proof. Let f and g satisfy the conditions of the lemma. The assumption that f is not in L^2 implies that $F(x) = \int_0^x |f|^2$ tends to infinity with x and thus that there exists a y in $(0, \infty)$ for which F(y) = 1 and $F(x) \ge 1$ (x > y). The assumption $gF \in L^2$ then implies $g \in L^2$ and $g \sqrt{F} \in L^2$, and it follows that also $f \sqrt{G}$ is in L^2 , where $G(x) = \int_x^\infty |g|^2$, since a partial integration and the fact that F is increasing give

$$\int_{0}^{x} |f^{2}G| = F(x) \int_{x}^{\infty} |g|^{2} + \int_{0}^{x} |g^{2}F| \leq \int_{0}^{\infty} |g\sqrt{F}|^{2} < \infty.$$

Since G is continuous and bounded this proves that fG is in L^2 .

The inequality, valid for $0 \le y < x < \infty$,

$$\left[\int_{y}^{x} |fg|\right]^{2} = \left[\int_{y}^{x} |gFf/F|\right]^{2} \le \int_{y}^{x} |gF|^{2} \int_{y}^{x} \{F'/F^{2}\} = \left[1 - 1/F(x)\right] \int_{y}^{x} |gF|^{2}$$

proves that fg is in L.

The analogous inequality

$$H^{2}(x) = \left[\int_{x}^{\infty} |fg|\right]^{2} \leq \left[1/F(x)\right] \int_{x}^{\infty} |gF|^{2}$$

shows that $FH^2(x) \to 0 \ (x \to \infty)$ and since

$$\int_{0}^{x} |fH|^{2} = (FH^{2})(x) + 2 \int_{0}^{x} |fgFH| \le (FH^{2})(x) + 2 \left\{ \int_{0}^{x} |gF|^{2} \int_{0}^{x} |fH|^{2} \right\}^{1/2}$$

also that $fH \in L^2$. This completes the proof of Lemma 1.

Now assume that the statement (2) in Theorem 3 holds true, with φ and ψ normalised so that $\varphi\psi' - \varphi'\psi = 1$. Then φ and ψ satisfy the conditions of Lemma 1 with $f = \varphi$ and $g = \psi$. Thus $\psi \in L^2$, $\varphi\psi \in L$ and the functions defined by

$$\varphi(x) \int_{x}^{\infty} \psi^{2}, \quad \varphi(x) \int_{x}^{\infty} \varphi \psi \quad \text{and} \quad \psi(x) \int_{0}^{x} \varphi \psi \quad (x \in [0, \infty))$$

are all in L^2 . With

(2.2)
$$f_3(x) = \varphi(x) \int_0^x \varphi \psi - \psi(x) \int_0^x \varphi^2$$

(2.3)
$$f_4(x) = \varphi(x) \int_0^x \psi^2 - \psi(x) \int_0^x \varphi \psi$$

it follows that ψ , $f_3 - \varphi \int_0^\infty \varphi \psi$ and $f_4 - \varphi \int_0^\infty \psi^2$ are three linearly independent L^2 -solutions of $M^2[y] = 0$. Since φ is a fourth solution which is not in L^2 , it is clear that (1) is satisfied.

Conversely, assume that the statement (1) holds true. Then, from Theorem 2, M must be in the limit-point condition at ∞ and M[y]=0 must have exactly one linearly independent L^2 -solution. Let φ and ψ be real-valued solutions of M[y]=0 which satisfy $\varphi \notin L^2$, $\psi \in L^2$ and $\varphi \psi' - \varphi' \psi = 1$, and let f_3 and f_4 be defined by (2.2) and (2.3) so that $\{\varphi, \psi, f_3, f_4\}$ is a basis for the solutions of $M^2[y]=0$. According to (1) there exist linearly independent vectors (a_2, a_3, a_4) and (b_2, b_3, b_4) in R^3 for which $a_2\varphi + a_3f_3 + a_4f_4$ and $b_2\varphi + b_3f_3 + b_4f_4$ are both in L^2 . It follows that $f_3 + a\varphi \in L^2$ for some unique real number a (eliminating f_4 above in case both $a_4 \neq 0$ and $b_4 \neq 0$). Put

$$F(x) = \int_0^x \varphi^2$$
 and $H(x) = a + \int_0^x \varphi \psi$ $(x \in [0, \infty))$.

Then $\varphi H - \psi F = f_3 + a\varphi \in L^2$, and the identity $(f_3 + a\varphi)^2 = (\varphi H)^2 + (\psi F)^2 - F(H^2)'$ gives

(2.4)
$$\int_0^x (f_3 + a\varphi)^2 = 2 \int_0^x (\varphi H)^2 + \int_0^x (\psi F)^2 - (FH^2)(x) \quad (x \in [0, \infty)),$$

after a partial integration of the last term.

We shall show that $\psi F \in L^2$, so that the statement (2) follows, by obtaining a contradiction from (2.4) in case ψF is not in L^2 .

If $\psi F \notin L^2$ it is clear from (2.4) that

(2.5)
$$U(x) = (FH^{2})(x) - 2 \int_{0}^{x} (\varphi H)^{2} \to +\infty \quad (x \to \infty),$$

and since the function V defined by

$$V(x) = F^{-2}(x) \int_{0}^{x} (\varphi H)^{2} \quad (x \in (0, \infty))$$

satisfies $V' = \varphi^2 F^{-3} U$ it follows from (2.5) and the definition of F that V' (as well

as V) is non-negative for sufficiently large x. Thus $V(x) > \frac{1}{2}C^2$, say, that is

$$\int_0^x (\varphi H)^2 > \frac{1}{2}C^2 F^2(x),$$

for some constant C > 0 and large x. Returning to (2.5) we obtain

$$0 < U(x) < (FH^2)(x) - C^2 F^2(x)$$
,

that is, $H(x) > C\sqrt{F(x)}$ for all large x. Now this inequality gives us the required contradiction. In fact, let X be so large that

$$\int_{Y}^{\infty} \psi^2 < C^2/4 .$$

Then for x > X,

$$H(x) = a + \int_0^x \varphi \psi \le a + \int_0^x |\varphi \psi| + \left[\int_x^x \psi^2 \int_x^x \varphi^2 \right]^{1/2} \le$$
$$\le \left(C/2 + \left(a + \int_0^x |\varphi \psi| \right) / \sqrt{F(x)} \right) \sqrt{F(x)}$$

where the term in () is < C when x is large enough, since $F(x) \to \infty$ ($x \to \infty$). Thus $\psi F \in L^2$ and the proof of Theorem 3 is complete.

3. Proof of Theorem 1. To prove Theorem 1 it is sufficient, according to Theorem 2, to produce differential expressions M for which (1) of Theorem 3 holds true. To achieve this it is not only sufficient but also necessary for us to ensure that the equation M[y] = 0 on $[0, \infty)$ has solutions φ and ψ which satisfy (2). As it turns out, such solutions must necessarily be of an oscillatory nature on $[0, \infty)$, with an unbounded sequence of discrete and simple zeros. In the following lemma we give additional conditions on the zeros of the linearly independent L^2 -solution ψ which ensure that M^2 is, indeed, in the limit-3 case.

Lemma 2. Let φ and ψ be two real-valued functions in $C^4[0, \infty)$ which satisfy $\varphi\psi' - \varphi'\psi = 1$ on $[0, \infty)$. Assume that ψ has a denumerable increasing sequence $(x_n)_{n=0}^{\infty}$ of zeros, with $x_0 = 0$ and $x_n \to \infty$ $(n \to \infty)$, and that

(i)
$$\sum_{n=1}^{\infty} \{(x_n - x_{n-1})^3 x_n^2\} \quad converges ,$$

(ii) there exist positive numbers A, B and C such that

$$\int_{x_{n-1}}^{x_n} \psi^2 < A(x_n - x_{n-1})^3 \quad and \quad Bx_n < \int_{0}^{x_n} \varphi^2 < Cx_n$$

for all positive integers n.

Then $(\psi''/\psi)(x)$ tends to a finite limit as x tends to a zero of ψ ; the coefficient q defined by $q(x) = (\psi''/\psi)(x)$ $(x \in [0, \infty))$ is in $C^2[0, \infty)$ (where, of course, q is defined by continuity at the zeros of ψ); and φ and ψ satisfy (2) of Theorem 3 with M defined by M[f] = -f'' + qf.

Proof. Let φ and ψ satisfy the conditions of the lemma. The facts that $(\psi''/\psi)(x) = q(x)$ tends to a finite limit as x tends to a zero of ψ and that $q \in C^2[0, \infty)$ follow directly from the assumptions $\varphi, \psi \in C^4[0, \infty)$ and $\varphi\psi' - \varphi'\psi = 1$, which imply that $\varphi(x) \neq 0$ when $\psi(x) = 0$, and that $\varphi\psi'' = \varphi''\psi$. It is also clear from the last equality that $M[\varphi] = M[\psi] = 0$.

The lower bound in the assumption (ii) implies that φ is not in L^2 . On the other hand with $F(x) = \int_0^x \varphi^2(x \in [0, \infty))$ the upper bounds give, for x in $[x_{N-1}, x_N)$,

$$\int_0^x (\psi F)^2 < \sum_{n=1}^N \left\{ \int_{x_{n-1}}^{x_n} (\psi F)^2 \right\} < AC^2 \sum_{n=1}^N \left\{ (x_n - x_{n-1})^3 x_n^2 \right\}.$$

In view of the assumption (i) it follows that $\psi F \in L^2$, that is, φ and ψ satisfy (2) of Theorem 3. This completes the proof of Lemma 2.

We now prove Theorem 1 by displaying functions φ and ψ which satisfy the conditions of Lemma 2. We shall construct such functions in terms of a real-valued function f in $C^{\infty}[0, 1]$ with the properties that

(i) f is infinitely differentiable, positive and convex upwards with

$$f(0) = 0$$
, $f'(0) = k > 0$, $f(1) = B > 0$ and $f'(1) = 0$,

and that, for some number $r \in (0, \frac{1}{2})$,

(ii)
$$f(x) = kx \ (x \in [0, r]) \ and \ f(x) = B \ (x \in [1 - r, 1]),$$

(iii)
$$\int_{r}^{1} (1/f)^2 = 1/(k^2 r)$$
.

Then we shall show that functions f with the above properties do endeed exist, provided $k/B \in (1, 2)$ and r is small enough.

Assuming that f has the properties (i)-(iii), define g on [0, 1] by

$$g(x) = -f(x) \int_{x}^{1} (1/f)^{2} \quad (x \in [0, 1]),$$

where g(0) is defined by continuity.

Since f is positive this function g is negative, and since, by a direct calculation,

(3.1)
$$fg' - f'g = 1$$
 and $fg'' = f''g$ on [0, 1],

we infer from (ii) that

(3.2)
$$g$$
 is convex downwards with $g(0) = -1/k$ and $g(1) = 0$.

Near the left end point of [0, 1] we obtain from (iii)

(3.3)
$$g(x) = -kx \left[\int_{x}^{r} (kt)^{-2} dt + \int_{r}^{1} f^{-2} \right] = -1/k \quad (x \in [0, r]),$$

and near the right end point we have

(3.4)
$$g(x) = -B \int_{x}^{1} B^{-2} = (x-1)/B \quad (x \in [1-r, 1]).$$

It is clear from (i) that f is increasing and satisfies $Bx \le f(x) \le B$ ($x \in [0, 1]$) and it follows from (3.2) and (3.3) that $|g(x)| \le 1/k$ on [0, 1]. Thus

(3.5)
$$B^2/3 < \int_0^1 f^2 < B^2 \text{ and } \int_0^1 g^2 < 1/k^2.$$

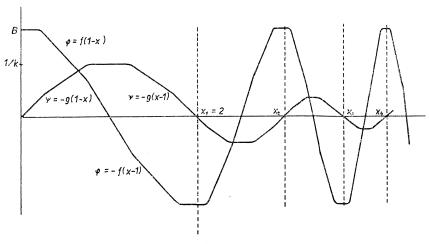


Fig. 1.

In the interval $[x_0, x_1] = [0, 2] \varphi(x) = -f_1(x)$ and $\psi(x) = -g_1(x)$. In the intervals $[x_{n-1}, x_n] \varphi(x) = (-1)^n f_1(2(x - x_{n-1})/(x_n - x_{n-1}))$, $\psi(x) = (-1)^n \frac{1}{2}(x_n - x_{n-1}) \quad g_1(2(x - x_{n-1}) : (x_n - x_{n-1}))$. In this particular example, $L_n = 2/n$ and B = 1, $k = \frac{5}{3}$, and $r = \frac{1}{5}$; as we shall see later the set of functions f satisfying (i)—(iii) is non-empty for these values of f, g, and g.

Let $(x_n)_{n=0}^{\infty}$ be a sequence of real numbers tending monotonically to infinity with n, with $x_0 = 0$ and $x_1 = 2$, and put $L_n = x_n - x_{n-1}$. Define, first f_1 and g_1 on $[0, L_1] = [0, 2]$ by $f_1(x) = -f(1-x)$, $g_1(x) = g(1-x)$ ($x \in [0, 1]$) and $f_1(x) = f(x-1)$, $g_1(x) = g(x-1)$ ($x \in [1, 2]$) and then, for each integer n > 1, f_n and g_n on $[0, L_n]$ by

(3.6)
$$f_n(x) = f_1(2x/L_n)$$
 and $g_n(x) = (L_n/2) g_1(2x/L_n)$ $(x \in [0, L_n])$.

The property (ii) of f ensures that f_1 is infinitely differentiable on its interval of definition and takes the constant value -B near the left end point and the value B near the right end point of this interval. Similarly, (3.3) shows that g_1 is also infinitely differentiable and (3.4) that g_1 vanishes linearly at the end points of its interval of definition, with slope -1/B near the left end point and slope 1/B near the right one. It follows from (3.1) that $f_1g_1' - f_1'g_1 = 1$ on this interval. Clearly, from the definition (3.6), the functions f_n and g_n inherit these properties for all integers n > 1. But this means that we may patch the f_n : s together, and also the g_n : s, to obtain two functions φ and ψ in $C^{\infty}[0,\infty)$ of the form shown in Fig. 1 by defining, for each interval $I_n = [x_{n-1}, x_n)$,

$$\varphi(x) = (-1)^n f_n(x - x_{n-1}) \quad \text{and} \quad \psi(x) = (-1)^n g_n(x - x_{n-1}) \quad (x \in I_n).$$

These functions satisfy $\varphi \psi' - \varphi' \psi = 1$ on $[0, \infty)$ and since

$$\int_{I_n} \varphi^2 = (L_n/2) \int_0^2 f_1^2 = L_n \int_0^1 f^2 \quad \text{and} \quad \int_{I_n} \psi^2 = (L_n^3/4) \int_0^1 g^2$$

it follows from (3.5) that

$$\int_{x_{n-1}}^{x_n} \psi^2 < L_n^3/(2k)^2 \quad \text{and} \quad B^2 L_n/3 < \int_{x_{n-1}}^{x_n} \varphi^2 < B^2 L_n.$$

Thus φ and ψ satisfy the conditions of Lemma 2 provided we select the sequence $(L_n)_{n=1}^{\infty}$ so that $L_1=2$ and

(3.7)
$$\sum_{n=1}^{\infty} \{L_n^3 x_n^2\} = \sum_{n=1}^{\infty} \{L_n^3 (\sum_{k=1}^n L_k)^2\} \quad \text{converges }.$$

To obtain examples of such sequences we may choose $L_n = 2n^{-\alpha}$ with $\alpha \in (\frac{3}{5}, 1]$; the fact that these satisfy (3.7) is easily verified on using

$$\sum_{k=1}^{n} L_k < 2\left(1 + \int_{1}^{n} t^{-\alpha} dt\right) < \begin{cases} 2(1-\alpha)^{-1} n^{1-\alpha} & (\alpha \in (\frac{3}{5}, 1)) \\ 2 + 2\log n & (\alpha = 1) \end{cases}.$$

It remains to verify that there exist functions f with the above properties (i)-(iii). Intuitively, it seems clear that there are functions which have the properties stated in (i) and (ii) when 1 < k/B < 2, but for lack of a suitable reference we sketch a proof of

Lemma 3. Let a, b, c and d be positive real numbers satisfying b < c/d < a. Then there are functions in $C^{\infty}[0,d]$ which are convex upwards and satisfy f(0) = 0, f'(0) = a, f(d) = c, f'(d) = b and $f^{(n)}(0) = f^{(n)}(d) = 0$ $(n \ge 2)$.

Proof. Define $P: [0, 1] \rightarrow [0, 1]$ by

(3.8)
$$P(x) = K \int_0^x \exp\left\{-\frac{1}{s} - \frac{1}{1-s}\right\} ds \quad (x \in [0, 1]),$$

where the constant K is determined by the requirement P(1) = 1. It is straightforward to verify that P is infinitely differentiable and increases monotonically from P(0) = 0 to P(1) = 1, with all derivatives vanishing at x = 0 and at x = 1, and satisfies P(x) + P(1 - x) = 1 ($0 \le x \le \frac{1}{2}$) so that $\int_0^1 P = \frac{1}{2}$.

Now the assumption bd < c < ad implies that l = (c - bd)/(ad - bd) satisfies 0 < l < 1, and thus in turn that in a (s-t)-plane, the line $t + \frac{1}{2}s = l$ has a non-empty intersection with the half-square determined by $0 \le t < t + s \le 1$. For each (s, t) in this intersection, define $Q_{st} : [0, d] \to [0, a - b]$ by

$$Q_{st}(x) = \begin{cases} 0 & (0 \le x \le td) \\ (a - b) P\left(\frac{x - td}{sd}\right) & (td < x < (t + s) d) \\ a - b & ((t + s) d \le x \le d) \end{cases}$$

Then Q_{st} is in $C^{\infty}[0, d]$ and

$$\int_{0}^{d} Q_{st} = (ad - bd) s \int_{0}^{1} P + (ad - bd) (1 - s - t) = (ad - bd) (1 - t - \frac{1}{2}s) =$$

$$= (ad - bd) (1 - l) = ad - c.$$

Thus each function $f: [0, d] \rightarrow [0, c]$ defined by

$$f(x) = ax - \int_0^x Q_{st} \quad (x \in [0, d])$$

satisfies f(d) = c. A direct computation shows that f has the other properties stated in the lemma as well.

Now let S = S(B, k, r) be the subset of $C^{\infty}[0, 1]$ containing real-valued functions which satisfy (i) and (ii). According to Lemma 3, with a = k, b = 0, c = B and d = 1, this set is nonempty, and it follows from the convexity requirement in (i) that each f in S is bounded by $l(x) \le f(x) \le m(x)$ in the interval [r, 1 - r], where the graph of

$$l(x) = kr + \frac{B - kr}{1 - 2r}(x - r) \quad (x \in [r, 1 - r])$$

is the line segment connecting the points (r, kr) and (1 - r, B), and

$$m(x) = \begin{cases} kx & (x \in [0, B/k)) \\ B & (x \in [B/k, 1]) \end{cases}.$$

For each s in the open interval (r, B/k), let l_s be the line parallel to l which intersects the graph of m at the points (s, ks) and (t, B), say. On rounding off the corners following the recipe in Lemma 3 we obtain, for any sufficiently small positive number ε and all s in $(r + \varepsilon, Bk^{-1} - \varepsilon)$, functions in S with graphs coinciding with that of m in $(0, s - \varepsilon) \cup (t + \varepsilon, 1)$ and with l_s in $(s + \varepsilon, t - \varepsilon)$. A continuity argument shows that S contains functions for which $\int_r^1 (1/f)^2$ takes any prescribed value in the open interval

$$\left(\int_{r}^{1-r} (1/m)^2 + r/B^2, \int_{r}^{1-r} (1/l)^2 + r/B^2\right).$$

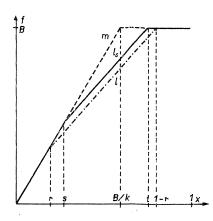


Fig. 2.

In particular, it contains functions which satisfy (iii) when $1/(k^2r)$ lies in this interval. Putting k/B = b we find after some elementary calculations that this condition takes the form

$$(1 + b^2r - 2br)/b^2r < 1/b^2r < (b + b^2r^2 - 2br)/b^2r,$$

or equivalently

$$b < 2 < b + (1 - br)^2,$$

which is satisfied for $b \in (1, 2)$ provided r is small enough - in the two figures above we have used B = 1, $k = \frac{5}{3}$ and $r = \frac{1}{5}$.

4. Comments on the above examples. All examples constructed by the method used in section 3 have the common property that there exist arbitrarily large x for which $q(x) = (\varphi''/\varphi)(x) < -x^3$. In fact, the property (i) for f implies that f''/f must be strictly negative at some points in (r, 1 - r). Let y be such a point with, say, $(f''/f)(y) = -c^2$. Then at the points $y_n = x_{n-1} + (L_n/2)y$ we have

$$q(y_n) = (2/L_n)^2 (f_1''/f_1)(y) = -(2c/L_n)^2$$
.

Thus if $q(y_n) \ge -y_n^3$ for $n > N_0$ then

$$(2c/L_n)^2 \le (x_{n-1} + (L_n/2) y)^3 < x_n^3 \quad (n > N_0),$$

so that for $N > N_0$

$$\sum_{n=N_0}^{N} \left\{ L_n^3 x_n^2 \right\} > 4c^2 \sum_{n=N_0}^{N} \left\{ L_n / x_n \right\} = 4c^2 \sum_{n=N_0}^{N} \left\{ L_n / \sum_{k=1}^{n} L_k \right\}.$$

Here the last sum diverges since $\sum L_k$ is divergent, just as $\int_{-\infty}^{\infty} \{h(x)/\int_{x}^{x} h\} dx$ diverges when $\int_{-\infty}^{\infty} h$ is divergent. This contradicts (3.7) and so $q(y_n) < -y_n^3$ for arbitrarily large n. On the other hand, given any positive number ε the method in section 3 yields coefficients which satisfy $q(x) \ge -x^{3+\varepsilon}$ ($x \in [0, \infty)$). These q: s result from functions φ and ψ constructed by means of functions f which hold close to $\sin(\pi x/2)$ on [0, 1], with very small intervals of linearity near the end-points.

Thus the results of this paper still leave open the question whether the condition (1.5) for M^2 to be limit-2 at ∞ is best possible or not in the case when M is limit-point at ∞ .

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