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# ON MEASURABLE SOLUTIONS OF A FUNCTIONAL EQUATION AND THEIR APPLICATION TO INFORMATION THEORY 

Gur Dial<br>(Received November 24, 1981)

## 1. INTRODUCTION

Let $\Gamma_{n}=\left\{P=\left(p_{1}, \ldots, p_{n}\right) ; p_{i} \geqq 0, i=1, \ldots, n ; \sum p_{i}=1\right\}$ for $n \geqq 1$ be a set of all $n$-complete probability distributions. Let $R$ be the set of all real numbers and let $I=[0,1]$.

Consider measurable functions $f, g, h, k: I \rightarrow R$ satisfying the system of functional equations

$$
\begin{equation*}
\sum_{i} \sum_{j} h\left(x_{i} y_{j}\right)=\sum_{j} \sum_{i} f\left(x_{i}\right) g\left(y_{t}\right)+\sum_{i} k\left(x_{i}\right), \tag{1.1}
\end{equation*}
$$

where $X=\left(x_{1}, \ldots, x_{n}\right) \in \Gamma_{n}, Y=\left(y_{1}, \ldots, y_{m}\right) \in \Gamma_{m}$.
The continuous solutions of (1.1) were given by Taneja [4].
The objective of this paper is to find the measurable solutions of (1.1). As an application, a joint characterization of Shannon's entropy and entropy of type $\beta$ is given.

## 2. MEASURABLE SOLUTIONS OF (1.1)

In this section we will find the measurable solutions of system (1.1). This is done in the following theorem.

Theorem 1. If $f, g, h$ and $k$ are measurable solutions of (1.1) for $X \in \Gamma_{n}, Y \in \Gamma_{m}$ where $n, m=2,3$, then they are given by one of the following set of solutions for $x \in[0,1]$. 1st set of solutions:

$$
\begin{equation*}
h(x)=B x+A x \log x, \quad f(x)=C x \tag{2.1}
\end{equation*}
$$

$2 n d$ set of solutions:

$$
\begin{gather*}
h(x)=B x+A\left(x^{\beta}-x\right), \quad f(x)=C x^{\beta}  \tag{2.3}\\
g(x)=D x+(A / C)\left(x^{\beta}-x\right), \quad k(x)=(B-A) x+(A-C D) x^{\beta} \tag{2.4}
\end{gather*}
$$

where $A, B, C$ and $D$ are arbitrary constants and $\beta>0(1 \neq \beta>0)$ is a parameter.

In addition to the above two sets of solutions, we also get the trivial solution:

$$
\begin{array}{cl}
h(\kappa)=B x, & f(x)=\operatorname{arbitrary}, \quad g(x)=D x \text { and } \\
& k(x)=B x-D f(x)
\end{array}
$$

Proof. Substituting $Y=(y, u, l-y-u) \in \Gamma_{3}$ and $Y=(y+u, l-y-u) \in \Gamma_{2}$ in (1.1), we get respectively

$$
\begin{gather*}
\quad \sum_{i}\left(h\left(x_{i} y\right)+h\left(x_{i} u\right)+h\left(x_{i}(1-y-u)\right)=\right.  \tag{2.5}\\
=\sum_{i} f\left(x_{i}\right)(g(y)+g(u)+g(1-y-u))+\sum_{i} k\left(x_{i}\right) \\
\sum_{i}\left(h\left(x_{i}(y+u)+h\left(x_{i}(1-y-u)\right)\right)=\sum_{i} f\left(x_{i}\right)(g(y+u)+\right.  \tag{2.6}\\
+g(1-y-u)+\sum_{i} k\left(x_{i}\right) .
\end{gather*}
$$

Subtracting (2.6) from (2.5), we obtain

$$
\begin{equation*}
\sum_{i}\left(h\left(x_{i} y\right)+h\left(x_{i} u\right)-h\left(x_{i}(y+u)\right)=\sum_{i} f\left(x_{i}\right)(g(y)+g(u)-g(y+u)) .\right. \tag{2.7}
\end{equation*}
$$

Let us define for $X \in \Gamma_{n}, n=2,3, t \in I=[0,1]$ :

$$
\begin{equation*}
A_{X}(t)=\sum_{i} h\left(x_{i} t\right)-\sum_{i} f\left(x_{i}\right) g(t) . \tag{2.8}
\end{equation*}
$$

By virtue of $(2.8)$ it is easy to see that $A_{X}(\cdot)$ is additive on $I$, i.e.

$$
\begin{equation*}
A_{X}(y+u)=A_{x}(y)+A_{x}(u) . \tag{2.9}
\end{equation*}
$$

It now follows from a result of Daroczy and Losonczi [3] that

$$
\begin{equation*}
A_{X}(t)=t A_{x}(1), \quad t \in I \tag{2.10}
\end{equation*}
$$

is a measurable solution.
In order to obtain the expression for $A_{x}(1)$, we will find the expression for the function

$$
\begin{equation*}
\sum_{i} h\left(x_{i}\right)-\sum_{i} f\left(x_{i}\right) g(1) . \tag{2.11}
\end{equation*}
$$

Substituting $Y=(1,0)$ and $Y=(1,0,0)$ in (1.1) we get respectively

$$
\begin{align*}
\sum_{i} h\left(x_{i}\right)+n h(0) & =\sum_{i} f\left(x_{i}\right)(g(1)+g(0))+\sum_{i} k\left(x_{i}\right)  \tag{2.12}\\
\sum_{i} h\left(x_{i}\right)+2 n h(0) & =\sum_{i} f\left(x_{i}\right)(g(1)+2 g(0))+\sum_{i} k\left(x_{i}\right) .
\end{align*}
$$

Subtracting (2.12) from (2.13) we obtain

$$
\begin{equation*}
n h(0)=\sum_{i} f\left(x_{i}\right) g(0) \tag{2.14}
\end{equation*}
$$

Using (2.14), we transform (2.12) into

$$
\begin{equation*}
\sum_{i} h\left(x_{i}\right)=\sum_{i} f\left(x_{i}\right) g(1)+\sum_{i} k\left(x_{i}\right) \tag{2.15}
\end{equation*}
$$

From (2.15) and (2.10) we get

$$
\begin{equation*}
\sum_{i} h\left(x_{i} t\right)-\sum_{i} f\left(x_{i}\right) g(t)=t \sum_{i} k\left(x_{i}\right) \tag{2.16}
\end{equation*}
$$

for all $X \in \Gamma_{n}, n=2,3$ and $t \in I$.
Let us substitute $X=(x, v, 1-x-v) \in \Gamma_{3}$ and $X=(x+v, 1-x-v) \in \Gamma_{2}$ in (2.16). We obtain respectively

$$
\begin{align*}
h(x t)+h(v t)+ & h((1-x-v) t)-(f(x)+f(v)+f(1-x-v)) g(t)=  \tag{2.17}\\
& =t(k(x)+k(v)-k(1-x-v))
\end{align*}
$$

$$
\begin{gather*}
h((x+v) t)+h((1-x-v) t)-(f(x+v)+f(1-x-v)) g(t)=  \tag{2.18}\\
=t(k(x+v)-k(1-x-v))
\end{gather*}
$$

From (2.18) and (2.17), we get

$$
\begin{gather*}
h(x t)+h(v t)-h((x+v) t)=(f(x)+f(v)-f(x+v)) g(t)+  \tag{2.19}\\
+t(k(x)+k(v)-k(x+v)) .
\end{gather*}
$$

For $t \in I$, let us define

$$
\begin{equation*}
B_{t}(w)=h(w t)-f(w) g(t)-t h(w) . \tag{2.20}
\end{equation*}
$$

Then using (2.20), we can write (2.19) in the form

$$
\begin{equation*}
B_{t}(x+v)=B_{t}(x)+B_{t}(v), \text { for } x, v, x+v \in[0,1] . \tag{2.21}
\end{equation*}
$$

Again using the result of Daroczy and Losonczi [3], we have

$$
\begin{equation*}
B_{\imath}(x)=x B_{t}(1) \tag{2.22}
\end{equation*}
$$

By substituting $X=(1,0)$ and $X=(1,0,0)$ in (2.16) we get the relation

$$
\begin{equation*}
h(t)=f(1) g(t)+t k(1) . \tag{2.23}
\end{equation*}
$$

Using (2.23), (2.22) becomes

$$
\begin{equation*}
h(x t)=f(x) g(t)+t k(x), \text { for all } \quad x, t \in I . \tag{2.24}
\end{equation*}
$$

Dividing (2.24) by $x t(x \neq 0, t \neq 0)$, we get

$$
\frac{h(x t)}{x t}=\frac{f(x)}{x} \frac{g(t)}{t}+\frac{k(x)}{x} .
$$

Let $h_{1}(x)=h(x) / x, f_{1}(x)=f(x) / x, g_{1}(t)=g(t) / t$ and $k_{1}(x)=k(x) / x$.

Then we have

$$
\begin{equation*}
h_{1}(x t)=f_{1}(x) g_{1}(t)+k_{1}(x) . \tag{2.25}
\end{equation*}
$$

Putting first $x=1$ and then $t=1$ in (2.25) we get

$$
\begin{align*}
& h_{1}(t)=f_{1}(1) g_{1}^{\prime}(t)+k_{1}(1),  \tag{2.26}\\
& h_{1}(1)=f_{1}(1) g_{1}(1)+k_{1}(1) .
\end{align*}
$$

If $f_{1}(1)=0$ then (2.26) implies

$$
h_{1}(t)=h_{1}(1) \quad \text { or } \quad h(t)=t h_{1}(1)=A t \quad \text { where } A=h_{1}(1)=h(1) .
$$

In this case $h$ is a homogeneous linear function. Now suppose that $f_{1}(1) \neq 0$. Then from (2.25) and (2.26) we obtain

$$
h_{1}(x t)=\frac{f_{1}(x)}{f_{1}(1)} h_{1}(t)+k_{1}(x)-\frac{f_{1}(x)}{f_{1}(1)} k_{1}(1) .
$$

Define $f_{2}(x)=f_{1}(x) \mid f_{1}(1), k_{2}(x)=k_{1}(x)-f_{2}(x) k_{1}(1)$. Then we have from the above equation that

$$
\begin{equation*}
h_{1}(x t)=f_{2}(x) h_{1}(t)+k_{2}(x) . \tag{2.28}
\end{equation*}
$$

Since $f, g, h, k$ are measurable functions, hence $h_{1}, f_{2}, h_{1}$ and $k_{2}$ are also measurable.
The general measurable solution of $(2.28)$ with $h_{1}, f_{2}, k_{2}$ measurable is given by (see Aczel [1])

$$
\begin{equation*}
h_{1}(x)=h_{0}(x)+\alpha ; \quad f_{2}(x)=1 ; \quad k_{2}(x)=h_{0}(x) \tag{2.29}
\end{equation*}
$$

and

$$
\begin{equation*}
h_{1}(x)=\gamma \mathrm{e}^{h_{0}(x)}+\alpha, \quad f_{2}(x)=\mathrm{e}^{h_{0}(x)}, \quad k_{2}(x)=\alpha\left(1-\mathrm{e}^{h_{0}(x)}\right) \tag{2.30}
\end{equation*}
$$

with an additional trivial solution

$$
\begin{equation*}
h_{1}(x)=\alpha, \quad f_{2}(x) \quad \text { arbitrary }, \quad k_{2}(x)=\alpha\left(1-f_{2}(x)\right) \tag{2.31}
\end{equation*}
$$

where $\gamma \neq 0$ and $\alpha$ are arbitrary constants and $h_{0}$ is an arbitrary measurable solution of the equation

$$
\begin{equation*}
h_{0}(x t)=h_{0}(x)+h_{0}(t) . \tag{2.32}
\end{equation*}
$$

However the most general measurable solution of (2.32) is

$$
\begin{equation*}
h_{0}(x)=A \log x \tag{2.33}
\end{equation*}
$$

where $A$ is an arbitrary constant.
Thus the solutions (2.29), (2.30) and (2.31) together with (2.33), (2.28) and (2.25) give the required set of solutions.

## 3. APPLICATIONS TO INFORMATION THEORY

Shannon's measure of information is defined as

$$
\begin{equation*}
H(P)=-\sum_{i} p_{i} \log p_{i}, \quad P \in \Gamma_{n} . \tag{3.1}
\end{equation*}
$$

A well known generalization of (3.1) is covered by the entropy of type $\beta$ and is given as (see [2])

$$
\begin{equation*}
H^{\beta}(P)=\left(2^{1-\beta}-1\right)^{-1}\left(\sum_{i} p_{i}^{\beta}-1\right), \quad \beta \neq 1, \beta>0, \quad P \in \Gamma_{n} \tag{3.2}
\end{equation*}
$$

In terms of measurable solution of (1.1), we can define $H(P)$ or $H^{\beta}(P)$ as

$$
\begin{equation*}
H(P)=\sum_{i} h\left(p_{i}\right) \tag{3.3}
\end{equation*}
$$

under suitable boundary and normalization conditions.
In the following theorem a joint characterization of (3.1) and (3.2) is given.
Theorem 2. The entropies of distribution $P$ under the conditions $h(1)=h(0)$ and $h(1 / 2)=1 / 2$ corresponding to the measurable solutions are (3.1) and (3.2), respectively.

Proof. Putting $x=0$ in (2.1) and (2.3) we have $h(0)=h(1)=0$. Using $h(1 / 2)=$ $=1 / 2$, the constant $A$ becomes -1 and $\left(2^{1-\beta}-1\right)^{-1}$, respectively. The result follows from (3.3).

## References

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[2] J. Aczel, Z. Daroczy: On measures of information and their characterizations. Academic Press, New York, 1975.
[3] Z. Daroczy, Losonczi: Über die Erweiterung der auf einer Punktmenge additive Funktion. Publ. Math. Debrecen, 14 (1967) 239-245.
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## Souhrn

MĚŘITELNÁ ŘEŠENÍ JISTÉ FUNKCIONÁLNÍ ROVNICE A JEJICH APLIKACE V TEORII INFORMACE

Gur Dial
V článku jsou nalezena měřitelná řešení jisté funkcionální rovnice se čtyřmi neznámými funkcemi. Jako jejich aplikace je dána společná charakterizace Shannonovy entropie a entropie $\beta$.

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