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STURM-LIOUVILLE DIFFERENCE EQUATIONS AND BANDED MATRICES

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ABSTRACT. In this paper we consider *discrete* Sturm-Liouville eigenvalue problems of the form

$$L(y)_{k} := \sum_{\mu=0}^{n} (-\Delta)^{\mu} \{ r_{\mu}(k) \Delta^{\mu} y_{k+1-\mu} \} = \lambda \rho(k) y_{k+1}$$

for $0 \le k \le N - n$ with $y_{1-n} = \dots = y_0 = y_{N+2-n} = \dots = y_{N+1} = 0$,

where N and n are integers with $1 \leq n \leq N$ and with the assumptions that $r_n(k) \neq 0$, $\rho(k) > 0$ for all k. These problems correspond to eigenvalue problems for symmetric, banded matrices $\mathcal{A} \in \mathbb{R}^{(N+1-n)\times(N+1-n)}$ with band-width 2n + 1. We present the following results: - a formula for the chracteristic polynomial of \mathcal{A} , which yields a *recursion* for its calculation - an *oscillation theorem*, which generalizes Sturm's well-known theorem on Sturmian chains, and - an inversion formula, which shows that *every* symmetric, banded matrix corresponds uniquely to a Sturm-Liouville eigenvalue problem of the above form.

AMS SUBJECT CLASSIFICATION. 39A10, 39A12, 65F15, 15A18

KEYWORDS. Sturm-Liouville equations, banded matrices, eigenvalue problems; Sturmian chains.

1. INTRODUCTION

We consider *discrete* Sturm-Liouville eigenvalue problems (with eigenvalue parameter λ) of the form

(1)
$$L(y)_k := \sum_{\mu=0}^n (-\Delta)^{\mu} \{ r_{\mu}(k) \Delta^{\mu} y_{k+1-\mu} \} = \lambda \rho(k) y_{k+1}$$

for $0 \le k \le N - n$, where $\Delta y_k = y_{k+1} - y_k$, and with the boundary conditions

(2)
$$y_{1-n} = \dots = y_0 = y_{N+2-n} = \dots = y_{N+1} = 0,$$

where N and n are fixed integers with $1 \leq n \leq N$ and where we always assume that

(3)
$$r_n(k) \neq 0$$
 for all k.

These problems correspond to eigenvalue problems for symmetric, banded matrices \mathcal{A} of size $(N + 1 - n) \times (N + 1 - n)$ with band-width 2n + 1. In particular, \mathcal{A} is *tridiagonal* in the case n = 1.

In this paper we essentially formulate and discuss our results while detailed proofs will be given in a forthcoming paper. The following theorems will be presented:

- a formula for the characteristic polynomial of \mathcal{A} (Theorem 1). This result yields also a *recursion* for its calculation. In the case n = 1 we obtain the well-known algorithm, which is commonly used in numerical analysis to handle eigenvalue problems for tridiagonal matrices (cf. [[4], pp. 305; [8], pp. 134; [9], pp. 299]).
- an oscillation theorem (Theorem 2). This result generalizes Sturm's well-known theorem on Sturmian chains (cf. e.g. [[4], Theorem 8.5-1 or [8], Sätze 4.8 and 4.9]).
- an inversion formula (Theorem 3). This identity can be used to calculate the matrix \mathcal{A} when the discrete Sturm-Liouville operator from equation (1) is given and vice versa. Hence, every symmetric, banded matrix with bandwidth 2n+1 corresponds uniquely to such a Sturm-Liouville operator.

Our method and most of our results have continuous counterparts along the lines of the book [6] (cf. also [7]).

2. DISCRETE STURM-LIOUVILLE EQUATIONS AND ASSOCIATED HAMILTONIAN SYSTEMS

In this section we give the connection between discrete Sturm-Liouville equations and Hamiltonian difference systems (cf. [[1], Proposition 5]), and we introduce the important notions of *conjoined bases* and *focal points* of it (cf. [[1], Definitions 1 and 3]). Moreover, the *multiplicity* of focal points is defined according to [3]. It will turn out that these multiplicities always equal one for Hamiltonian systems, which we treat here, i.e. which originate from Sturm-Liouville equations. **Lemma 1.** A vector $y = (y_k)_{1-n}^{N+1} \in \mathbb{R}^{N+1-n}$ solves the Sturm-Liouville difference equation (1) for $0 \leq k \leq N-n$ if and only if (x, u) solves the Hamiltonian difference system

(4)
$$\Delta x_k = Ax_{k+1} + B_k u_k, \ \Delta u_k = (C_k - \lambda \tilde{C}_k)x_{k+1} - A^T u_k$$

for $0 \le k \le N$, where we use the following **notation**: A, B_k , C_k , \tilde{C}_k are $n \times n$ -matrices defined by

$$A = \begin{pmatrix} 0 & 1 & \cdots & 0 \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & 1 \\ 0 & \cdots & 0 & 0 \end{pmatrix}, B_k = \frac{1}{r_n(k)} B \quad with \ B = diag(0, \dots, 0, 1),$$

$$C_k = diag(r_0(k), \dots, r_{n-1}(k)), \ \tilde{C}_k = \rho(k)\tilde{C} \ with \ \tilde{C} = diag(1, 0, \dots, 0)$$

for $0 \le k \le N$, and $x_k = (x_k^{(\nu)})_{\nu=0}^{n-1}$, $u_k = (u_k^{(\nu)})_{\nu=0}^{n-1} \in \mathbb{R}^n$ are defined by

$$x_k^{(\nu)} = \Delta^{\nu} y_{k-\nu}, \ u_k^{(\nu)} = \sum_{\mu=\nu+1}^n (-\Delta)^{\mu-\nu-1} \{ r_{\mu}(k) \Delta^{\mu} y_{k+1-\mu} \}$$

for $0 \le \nu \le n-1, 0 \le k \le N+1$ with suitably chosen $y_{N+2}, \ldots, y_{N+n+1}$ (which are used for $u_{N+2-n}, \ldots, u_{N+1}$).

Definition 1. Assume that (3) holds.

(i) A pair $(X, U) = (X_k, U_k)_{k=0}^{N+1}$ is called a conjoined basis of (4), if the real $n \times n$ -matrices X_k, U_k solve (4) for $0 \le k \le N$, and if

 $X_0^T U_0 = U_0^T X_0$ and rank $(X_0^T, U_0^T) = n$ holds.

(ii) Suppose that (X, U) is a conjoined basis of (4) and let $0 \le k \le N$. We say that X has no focal point in the interval (k, k+1] if

Ker
$$X_{k+1} \subset$$
 Ker X_k and $D_k := X_k X_{k+1}^{\dagger} \tilde{A} B_k \ge 0$ holds,

where $\tilde{A} := (I - A)^{-1}$. Moreover, if Ker $X_{k+1} \subset$ Ker X_k and $D_k \not\geq 0$, then ind D_k is called the multiplicity of the focal point of X in the interval (k, k+1).

Remark 1.

- (i) For a matrix M we denote by Ker M the kernel of M, ind M denotes the index of M, i.e., the number of negative eigenvalues of M, provided M is symmetric (and real), and M[†] denotes the Moore-Penrose inverse of M. Moreover, M ≥ 0 means that M is symmetric (and real) and non-negative definite. Observe that D_k is symmetric, if Ker X_{k+1} ⊂ Ker X_k (cf. [[1], Proposition 1]).
- (ii) For our Sturm-Liouville difference equations the multiplicity of focal points, which we defined only in case $\operatorname{Ker} X_{k+1} \subset \operatorname{Ker} X_k$, always equals 1, because $\operatorname{rank} D_k \leq \operatorname{rank} B = 1$.

3. Associated quadratic functionals and banded matrices

For $y = (y_k)_{k=1}^{N+1-n} \in \mathbb{R}^{N+1-n}$ we define a quadratic functional \mathcal{F} , which corresponds to the Sturm-Liouville operator L(y) from equation (1), by

$$\mathcal{F}(y) := \sum_{k=0}^{N} \sum_{\mu=0}^{n} r_{\mu}(k) (\Delta^{\mu} y_{k+1-\mu})^2 ,$$

where we assume (2), i.e., $y_{1-n} = \cdots = y_0 = y_{N+2-n} = \cdots = y_{N+1} = 0$.

Lemma 2. The following formulas hold.

(i) $\mathcal{F}(y) = y^T \mathcal{A}y$, where $\mathcal{A} \in \mathbb{R}^{(N+1-n) \times (N+1-n)}$ is a symmetric, banded matrix with band-width 2n + 1, which is defined by

$$a_{k+1,k+1+t} = (-1)^t \sum_{\mu=t}^n \sum_{\nu=t}^\mu \binom{\mu}{\nu} \binom{\mu}{\nu-t} r_\mu(k+\nu)$$

for $0 \le t \le n$ and $0 \le k \le N - n - t$. (ii) $(\mathcal{A}y)_{k+1} = L(y)_k$ for $0 \le k \le N - n$ with $L(y)_k$ given by (1).

Observe that \mathcal{A} is a tridiagonal $N \times N$ -matrix in the case n = 1. In the sequel we use the **notation**:

 $\mathcal{A}_{N+1} = \mathcal{A} \in \mathbb{R}^{(N+1-n)\times(N+1-n)}$ is the symmetric, banded matrix as defined in Lemma 2, and $\mathcal{A}_k \in \mathbb{R}^{(k-n)\times(k-n)}$ is defined correspondingly for $n+1 \leq k \leq N+1$. Moreover, let $\mathcal{A}(\lambda) := \mathcal{A} - \lambda \mathcal{D}$ with $\mathcal{D} := \text{diag}(\rho(0), \ldots, \rho(N-1))$, and as before, $\mathcal{A}_k(\lambda)$ is defined accordingly.

The following statement follows directly from Lemma 2.

Corollary 1. The discrete Sturm-Liouville eigenvalue problem (1) and (2) from Section 1 is equivalent with the algebraic eigenvalue problem (matrix pencil)

$$\mathcal{A}y = \lambda \mathcal{D}y \text{ or } \mathcal{A}(\lambda)y = 0.$$

4. Results

We assume throughout that (X, U) is the so-called *principal solution* of (4), i.e., $X = X_k(\lambda), U_k = U_k(\lambda)$ satisfy (4) with

(5)
$$X_0 \equiv 0, \ U_0 \equiv I.$$

Moreover, as in the previous sections, $y = (y_k)_{k=1}^{N+1-n} \in \mathbb{R}^{N+1-n}$ satisfies (2), i.e., $y_{1-n} = \cdots = y_0 = y_{N+2-n} = \cdots = y_{N+1} = 0$, and

$$\mathcal{F}(y) = \sum_{k=0}^{N} \sum_{\mu=0}^{n} r_{\mu}(k) (\Delta^{\mu} y_{k+1-\mu})^2 , \ D_k = X_k X_{k+1}^{\dagger} \tilde{A} B_k (= D_k(\lambda)).$$

First, we cite some auxiliary results mainly from [1].

4.1. AUXILIARY RESULTS

Lemma 3. The following assertions hold, provided (3) and (5) are fulfilled.

- (i) X_0, \ldots, X_n are independent of λ .
- (*ii*) $det X_k = 0, D_k = 0, Ker X_{k+1} \subset Ker X_k \text{ for } k = 0, \dots, n-1.$
- (*iii*) det $X_n = \{r_n(0) \cdots r_n(n-1)\}^{-1} \neq 0$.
- (iv) $\det X_k(\lambda) \neq 0$ for $n \leq k \leq N+1$, if λ is sufficiently small, provided $\rho(k) > 0$ for $0 \leq k \leq N-n$.

(v)
$$D_k(\lambda) = \frac{1}{r_n(k)} \frac{\det X_k(\lambda)}{\det X_{k+1}(\lambda)} B$$
, provided $\det X_{k+1}(\lambda) \neq 0$, for $n \leq k \leq N$.

Proof. The assertions (i) and (iii) are derived in a forthcoming paper. The assertion (ii) is contained in [[1], Proposition 6], and (iv) follows from [[1], Satz 9], because

$$\mathcal{F}(y) - \lambda \sum_{k=0}^{N-n} \rho(k) y_{k+1}^2 > 0 \quad for \quad \lambda \le \lambda_0,$$

if $y \neq 0$ and $\rho(k) > 0$ for $0 \leq k \leq N - n$. Finally, the assertion (v) is shown in [[2], Lemma 4.1].

Observe that $X_k(\lambda)$, $U_k(\lambda)$ are matrix-polynomials in λ , so that $D_k(\lambda)$ is a rational function of λ as follows from Lemma 3 (v). Hence, if $\rho(k) > 0$ for all k, then det $X_k(\lambda) \neq 0$ for $n \leq k \leq N + 1$ and all $\lambda \in \mathbb{R} \setminus \mathcal{N}$ with a *finite* set \mathcal{N} . The next result follows from [[1], Proposition 1] and Lemma 3.

Lemma 4. (*Picone's identity*) Suppose (2), (3), and (5), and assume that $\det X_k(\lambda) \neq 0$ for $n \leq k \leq N+1$. Then

$$\mathcal{F}(y) - \lambda \sum_{k=0}^{N-n} \rho(k) y_{k+1}^2 = \sum_{k=n}^N z_k^T D_k z_k,$$

where $z_k = u_k - U_k(\lambda)X_k^{-1}(\lambda)x_k$ with x_k , u_k as in Lemma 1.

The next statement with the notation of Section 3 follows immediately from Lemma 3 and Lemma 4.

Corollary 2. Under the assumptions of Lemma 4

$$y^{T}(\mathcal{A}_{N+1} - \lambda \mathcal{D})y = \sum_{k=n}^{N} r_{n}(k) \frac{\det X_{k+1}(\lambda)}{\det X_{k}(\lambda)} w_{k+1-n}^{2},$$

where $w_{\nu} = y_{\nu} + \sum_{\mu=\nu+1}^{\nu+n} \alpha_{\mu} y_{\mu}$ with suitable coefficients $\alpha_{\mu} = \alpha_{\mu}(\nu, \lambda)$. Hence, w = Ty with $T = \begin{pmatrix} 1 & \star & \star \\ \vdots & \ddots & \star \\ 0 & \cdots & 1 \end{pmatrix}$, so that $\det T = 1$.

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4.2. Main results

First, the Lemmas 3 and 4 with Crollary 2 yield our first result, which states a formula for the characteristic polynomial of \mathcal{A} and its recursive calculation.

Theorem 1. (Recursion) Assume (3), (5), and suppose that

(6)
$$\rho(k) > 0 \quad for \quad 0 \le k \le N - n$$

holds. Then, with the notation of Section 3,

(7)
$$det(\mathcal{A} - \lambda \mathcal{D}) = r_n(0) \cdots r_n(N) det X_{N+1}(\lambda)$$

for all $\lambda \in \mathbb{R}$. Moreover, by (4) and (5), $X_{N+1}(\lambda)$ is given by the recursion

$$X_{k+1} = \tilde{A}(X_k + B_k U_k), \ U_{k+1} = (C_k - \lambda \tilde{C}_k) X_{k+1} + (I - A^T) U_k$$

for all $0 \le k \le N$ with $X_0 = 0, U_0 = I$.

Proof. By Lemma 3 and Lemma 4 we have that

$$\det \mathcal{A}(\lambda) = r_n(n) \frac{\det X_{n+1}(\lambda)}{\det X_n(\lambda)} \cdots r_n(N) \frac{\det X_{N+1}(\lambda)}{\det X_N(\lambda)}$$
$$= r_n(0) \cdots r_n(N) \det X_{N+1}(\lambda).$$

Next, the general oscillation theorem for Hamiltonian systems from reference [3] implies a corresponding result here.

Theorem 2. (Oscillation) Under the assumptions of Theorem 1 let $\lambda \in \mathbb{R}$ with det $X_k(\lambda) \neq 0$ for $n \leq k \leq N + 1$. Then, the number of eigenvalues (including multiplicities) of the eigenvalue problem (1), (2) from Section 1, which are less than λ , equals the number of focal points of $X(\lambda)$ in the interval (0, N + 1].

Remark 2. Observe first, that the multiplicity of an eigenvalue λ is given by the rank of the kernel of $X_{N+1}(\lambda)$. Hence, it is an integer in $\{1, \ldots, n\}$. Moreover, by Remark 1, the focal points of $X(\lambda)$ are all simple, i.e., of multiplicity one, and their number in (0, N+1] equals the number of the elements of the set

$$\{k: n \le k \le N \text{ with } r_n(k) \frac{\det X_{k+1}(\lambda)}{\det X_k(\lambda)} < 0\}.$$

The next corollary is just another formulation of Theorem 2. It generalizes the well-known theorem of Sturm on "Sturmian chains" (cf. [[4], Theorem 8.5-1 and [8], Sätze 4.8 and 4.9). Moreover, it yields the Poincaré separation theorem for banded matrices (cf. [[5], 4.3.16 Corollary]).

Corollary 3. Under the assumptions of Theorem 2 and the previous notation define polynomials $f_k(t)$ by

(8)
$$f_k(t) := \det \mathcal{A}_k(t) \text{ for } n+1 \le k \le N+1 \text{ and } f_n(t) \equiv 1.$$

Then the number of zeros of $f_{N+1}(t)$ (including multiplicities), which are less than λ , equals the number of sign changes of $\{f_k(\lambda)\}$ for $n \leq k \leq N+1$, i.e., $\{f_k(\lambda)\}$ is a "Sturmian chain".

Proof. The assertion follows from Theorem 1 and Theorem 2, because

$$f_k(\lambda) = r_n(0) \cdots r_n(k-1) \det X_k(\lambda)$$

for $n \leq k \leq N+1$, so that

$$\frac{f_{k+1}(\lambda)}{f_k(\lambda)} = r_n(k) \frac{\det X_{k+1}(\lambda)}{\det X_k(\lambda)} .$$

Finally, we have the following inversion formula, where the "easy" part is the assertion (i) of Lemma 2, while the main formula will be proved in detail via generating functions in a forthcoming paper as already mentioned in the introduction.

Theorem 3. (Inversion) The following inversion formulas hold:

(9)
$$r_{\mu}(k+\mu) =$$

$$(-1)^{\mu} \sum_{s=\mu}^{n} \left\{ \binom{s}{\mu} a_{k+1,k+1+s} + \sum_{l=1}^{s-\mu} \frac{s}{l} \binom{\mu+l-1}{l-1} \binom{s-l-1}{s-\mu-l} a_{k+1-l,k+1-l+s} \right\},$$

for $0 \le \mu \le n$ and all k, if and only if the $a_{\mu\nu}$ are given by

(10)
$$a_{k+1,k+1+t} = (-1)^t \sum_{\mu=t}^n \sum_{\nu=t}^\mu \binom{\mu}{\nu} \binom{\mu}{\nu-t} r_\mu(k+\nu)$$

for $0 \le t \le n$ and all k.

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