## Archivum Mathematicum

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Archivum Mathematicum, Vol. 36 (2000), No. 5, 499--505

Persistent URL: http://dml.cz/dmlcz/107764

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# STURM-LIOUVILLE DIFFERENCE EQUATIONS AND BANDED MATRICES 

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Abstract. In this paper we consider discrete Sturm-Liouville eigenvalue problems of the form

$$
L(y)_{k}:=\sum_{\mu=0}^{n}(-\Delta)^{\mu}\left\{r_{\mu}(k) \Delta^{\mu} y_{k+1-\mu}\right\}=\lambda \rho(k) y_{k+1}
$$

for $0 \leq k \leq N-n$ with $y_{1-n}=\cdots=y_{0}=y_{N+2-n}=\cdots=y_{N+1}=0$,
where $N$ and $n$ are integers with $1 \leq n \leq N$ and with the assumptions that $r_{n}(k) \neq 0, \rho(k)>0$ for all $k$. These problems correspond to eigenvalue problems for symmetric, banded matrices $\mathcal{A} \in \mathbb{R}^{(N+1-n) \times(N+1-n)}$ with band-width $2 n+1$. We present the following results: - a formula for the chracteristic polynomial of $\mathcal{A}$, which yields a recursion for its calculation - an oscillation theorem, which generalizes Sturm's well-known theorem on Sturmian chains, and - an inversion formula, which shows that every symmetric, banded matrix corresponds uniquely to a Sturm-Liouville eigenvalue problem of the above form.

AMS Subject Classification. 39A10, 39A12, 65F15, 15A18

Keywords. Sturm-Liouville equations, banded matrices, eigenvalue problems; Sturmian chains.

## 1. Introduction

We consider discrete Sturm-Liouville eigenvalue problems (with eigenvalue parameter $\lambda$ ) of the form

$$
\begin{equation*}
L(y)_{k}:=\sum_{\mu=0}^{n}(-\Delta)^{\mu}\left\{r_{\mu}(k) \Delta^{\mu} y_{k+1-\mu}\right\}=\lambda \rho(k) y_{k+1} \tag{1}
\end{equation*}
$$

for $0 \leq k \leq N-n$, where $\Delta y_{k}=y_{k+1}-y_{k}$, and with the boundary conditions

$$
\begin{equation*}
y_{1-n}=\cdots=y_{0}=y_{N+2-n}=\cdots=y_{N+1}=0 \tag{2}
\end{equation*}
$$

where $N$ and $n$ are fixed integers with $1 \leq n \leq N$ and where we always assume that

$$
\begin{equation*}
r_{n}(k) \neq 0 \quad \text { for all } k \tag{3}
\end{equation*}
$$

These problems correspond to eigenvalue problems for symmetric, banded matrices $\mathcal{A}$ of size $(N+1-n) \times(N+1-n)$ with band-width $2 n+1$. In particular, $\mathcal{A}$ is tridiagonal in the case $n=1$.

In this paper we essentially formulate and discuss our results while detailed proofs will be given in a forthcoming paper. The following theorems will be presented:

- a formula for the characteristic polynomial of $\mathcal{A}$ (Theorem 1). This result yields also a recursion for its calculation. In the case $n=1$ we obtain the well-known algorithm, which is commonly used in numerical analysis to handle eigenvalue problems for tridiagonal matrices (cf. [[4], pp. 305; [8], pp. 134; [9], pp. 299]).
- an oscillation theorem (Theorem 2). This result generalizes Sturm's well-known theorem on Sturmian chains (cf. e.g. [[4], Theorem 8.5-1 or [8], Sätze 4.8 and 4.9]).
- an inversion formula (Theorem 3). This identity can be used to calculate the matrix $\mathcal{A}$ when the discrete Sturm-Liouville operator from equation (1) is given and vice versa. Hence, every symmetric, banded matrix with bandwidth $2 n+1$ corresponds uniquely to such a Sturm-Liouville operator.

Our method and most of our results have continuous counterparts along the lines of the book [6] (cf. also [7]).

## 2. Discrete Sturm-Liouville equations and Associated Hamiltonian systems

In this section we give the connection between discrete Sturm-Liouville equations and Hamiltonian difference systems (cf. [[1], Proposition 5]), and we introduce the important notions of conjoined bases and focal points of it (cf. [[1], Definitions 1 and 3]). Moreover, the multiplicity of focal points is defined according to [3]. It will turn out that these multiplicities always equal one for Hamiltonian systems, which we treat here, i.e. which originate from Sturm-Liouville equations.

Lemma 1. A vector $y=\left(y_{k}\right)_{1-n}^{N+1} \in \mathbb{R}^{N+1-n}$ solves the Sturm-Liouville difference equation (1) for $0 \leq k \leq N-n$ if and only if $(x, u)$ solves the Hamiltonian difference system

$$
\begin{equation*}
\Delta x_{k}=A x_{k+1}+B_{k} u_{k}, \Delta u_{k}=\left(C_{k}-\lambda \tilde{C}_{k}\right) x_{k+1}-A^{T} u_{k} \tag{4}
\end{equation*}
$$

for $0 \leq k \leq N$, where we use the following notation:
$A, B_{k}, C_{k}, \tilde{C}_{k}$ are $n \times n$-matrices defined by

$$
\begin{gathered}
A=\left(\begin{array}{cccc}
0 & 1 & \cdots & 0 \\
\vdots & \ddots & \ddots & \vdots \\
0 & \cdots & 0 & 1 \\
0 & \cdots & 0 & 0
\end{array}\right), B_{k}=\frac{1}{r_{n}(k)} B \text { with } B=\operatorname{diag}(0, \ldots, 0,1), \\
C_{k}=\operatorname{diag}\left(r_{0}(k), \ldots, r_{n-1}(k)\right), \tilde{C}_{k}=\rho(k) \tilde{C} \text { with } \tilde{C}=\operatorname{diag}(1,0, \ldots, 0),
\end{gathered}
$$

for $0 \leq k \leq N$, and $x_{k}=\left(x_{k}^{(\nu)}\right)_{\nu=0}^{n-1}, u_{k}=\left(u_{k}^{(\nu)}\right)_{\nu=0}^{n-1} \in \mathbb{R}^{n}$ are defined by

$$
x_{k}^{(\nu)}=\Delta^{\nu} y_{k-\nu}, u_{k}^{(\nu)}=\sum_{\mu=\nu+1}^{n}(-\Delta)^{\mu-\nu-1}\left\{r_{\mu}(k) \Delta^{\mu} y_{k+1-\mu}\right\}
$$

for $0 \leq \nu \leq n-1,0 \leq k \leq N+1$ with suitably chosen $y_{N+2}, \ldots, y_{N+n+1}$ (which are used for $\left.u_{N+2-n}, \ldots, u_{N+1}\right)$.

Definition 1. Assume that (3) holds.
(i) A pair $(X, U)=\left(X_{k}, U_{k}\right)_{k=0}^{N+1}$ is called a conjoined basis of (4), if the real $n \times n$-matrices $X_{k}, U_{k}$ solve (4) for $0 \leq k \leq N$, and if

$$
X_{0}^{T} U_{0}=U_{0}^{T} X_{0} \text { and } \operatorname{rank}\left(X_{0}^{T}, U_{0}^{T}\right)=n \text { holds. }
$$

(ii) Suppose that $(X, U)$ is a conjoined basis of (4) and let $0 \leq k \leq N$. We say that $X$ has no focal point in the interval $(k, k+1]$ if
$\operatorname{Ker} X_{k+1} \subset \operatorname{Ker} X_{k}$ and $D_{k}:=X_{k} X_{k+1}^{\dagger} \tilde{A} B_{k} \geq 0$ holds, where $\tilde{A}:=(I-A)^{-1}$. Moreover, if $\operatorname{Ker} X_{k+1} \subset \operatorname{Ker} X_{k}$ and $D_{k} \nsupseteq 0$, then ind $D_{k}$ is called the multiplicity of the focal point of $X$ in the interval $(k, k+1)$.

## Remark 1.

(i) For a matrix $M$ we denote by $\operatorname{Ker} M$ the kernel of $M$, ind $M$ denotes the index of $M$, i.e., the number of negative eigenvalues of $M$, provided $M$ is symmetric (and real), and $M^{\dagger}$ denotes the Moore-Penrose inverse of $M$. Moreover, $M \geq 0$ means that $M$ is symmetric (and real) and non-negative definite. Observe that $D_{k}$ is symmetric, if $\operatorname{Ker} X_{k+1} \subset \operatorname{Ker} X_{k}$ (cf. [[1], Proposition 1]).
(ii) For our Sturm-Liouville difference equations the multiplicity of focal points, which we defined only in case $\operatorname{Ker} X_{k+1} \subset \operatorname{Ker} X_{k}$, always equals 1, because $\operatorname{rank} D_{k} \leq \operatorname{rank} B=1$.

## 3. Associated quadratic functionals and banded matrices

For $y=\left(y_{k}\right)_{k=1}^{N+1-n} \in \mathbb{R}^{N+1-n}$ we define a quadratic functional $\mathcal{F}$, which corresponds to the Sturm-Liouville operator $L(y)$ from equation (1), by

$$
\mathcal{F}(y):=\sum_{k=0}^{N} \sum_{\mu=0}^{n} r_{\mu}(k)\left(\Delta^{\mu} y_{k+1-\mu}\right)^{2},
$$

where we assume (2), i.e., $y_{1-n}=\cdots=y_{0}=y_{N+2-n}=\cdots=y_{N+1}=0$.
Lemma 2. The following formulas hold.
(i) $\mathcal{F}(y)=y^{T} \mathcal{A} y$, where $\mathcal{A} \in \mathbb{R}^{(N+1-n) \times(N+1-n)}$ is a symmetric, banded matrix with band-width $2 n+1$, which is defined by

$$
a_{k+1, k+1+t}=(-1)^{t} \sum_{\mu=t}^{n} \sum_{\nu=t}^{\mu}\binom{\mu}{\nu}\binom{\mu}{\nu-t} r_{\mu}(k+\nu)
$$

for $0 \leq t \leq n$ and $0 \leq k \leq N-n-t$.
(ii) $(\mathcal{A} y)_{k+1}=L(y)_{k}$ for $0 \leq k \leq N-n$ with $L(y)_{k}$ given by (1).

Observe that $\mathcal{A}$ is a tridiagonal $N \times N$-matrix in the case $n=1$. In the sequel we use the notation:
$\mathcal{A}_{N+1}=\mathcal{A} \in \mathbb{R}^{(N+1-n) \times(N+1-n)}$ is the symmetric, banded matrix as defined in Lemma 2 , and $\mathcal{A}_{k} \in \mathbb{R}^{(k-n) \times(k-n)}$ is defined correspondingly for $n+1 \leq k \leq N+1$. Moreover, let $\mathcal{A}(\lambda):=\mathcal{A}-\lambda \mathcal{D}$ with
$\mathcal{D}:=\operatorname{diag}(\rho(0), \ldots, \rho(N-1))$, and as before, $\mathcal{A}_{k}(\lambda)$ is defined accordingly.
The following statement follows directly from Lemma 2.
Corollary 1. The discrete Sturm-Liouville eigenvalue problem (1) and (2) from Section 1 is equivalent with the algebraic eigenvalue problem (matrix pencil)

$$
\mathcal{A} y=\lambda \mathcal{D} y \text { or } \mathcal{A}(\lambda) y=0
$$

## 4. Results

We assume throughout that ( $X, U$ ) is the so-called principal solution of (4), i.e., $X=X_{k}(\lambda), U_{k}=U_{k}(\lambda)$ satisfy (4) with

$$
\begin{equation*}
X_{0} \equiv 0, U_{0} \equiv I \tag{5}
\end{equation*}
$$

Moreover, as in the previous sections, $y=\left(y_{k}\right)_{k=1}^{N+1-n} \in \mathbb{R}^{N+1-n}$ satisfies (2), i.e., $y_{1-n}=\cdots=y_{0}=y_{N+2-n}=\cdots=y_{N+1}=0$, and

$$
\mathcal{F}(y)=\sum_{k=0}^{N} \sum_{\mu=0}^{n} r_{\mu}(k)\left(\Delta^{\mu} y_{k+1-\mu}\right)^{2}, \quad D_{k}=X_{k} X_{k+1}^{\dagger} \tilde{A} B_{k}\left(=D_{k}(\lambda)\right) .
$$

First, we cite some auxiliary results mainly from [1].

### 4.1. Auxiliary results

Lemma 3. The following assertions hold, provided (3) and (5) are fulfilled.
(i) $X_{0}, \ldots, X_{n}$ are independent of $\lambda$.
(ii) $\operatorname{det} X_{k}=0, D_{k}=0, \operatorname{Ker} X_{k+1} \subset \operatorname{Ker} X_{k}$ for $k=0, \ldots, n-1$.
(iii) $\operatorname{det} X_{n}=\left\{r_{n}(0) \cdots r_{n}(n-1)\right\}^{-1} \neq 0$.
(iv) $\operatorname{det} X_{k}(\lambda) \neq 0$ for $n \leq k \leq N+1$, if $\lambda$ is sufficiently small, provided $\rho(k)>0$ for $0 \leq k \leq N-n$.
(v) $D_{k}(\lambda)=\frac{1}{r_{n}(k)} \frac{\operatorname{det} X_{k}(\lambda)}{\operatorname{det} X_{k+1}(\lambda)} B$, provided $\operatorname{det} X_{k+1}(\lambda) \neq 0$, for $n \leq k \leq N$.

Proof. The assertions (i) and (iii) are derived in a forthcoming paper. The assertion (ii) is contained in [[1], Proposition 6], and (iv) follows from [[1], Satz 9], because

$$
\mathcal{F}(y)-\lambda \sum_{k=0}^{N-n} \rho(k) y_{k+1}^{2}>0 \text { for } \lambda \leq \lambda_{0}
$$

if $y \neq 0$ and $\rho(k)>0$ for $0 \leq k \leq N-n$. Finally, the assertion (v) is shown in [[2], Lemma 4.1].

Observe that $X_{k}(\lambda), U_{k}(\lambda)$ are matrix-polynomials in $\lambda$, so that $D_{k}(\lambda)$ is a rational function of $\lambda$ as follows from Lemma 3 (v). Hence, if $\rho(k)>0$ for all $k$, then $\operatorname{det} X_{k}(\lambda) \neq 0$ for $n \leq k \leq N+1$ and all $\lambda \in \mathbb{R} \backslash \mathcal{N}$ with a finite set $\mathcal{N}$. The next result follows from [[1], Proposition 1] and Lemma 3.

Lemma 4. (Picone's identity) Suppose (2), (3), and (5), and assume that $\operatorname{det} X_{k}(\lambda) \neq 0$ for $n \leq k \leq N+1$. Then

$$
\mathcal{F}(y)-\lambda \sum_{k=0}^{N-n} \rho(k) y_{k+1}^{2}=\sum_{k=n}^{N} z_{k}^{T} D_{k} z_{k}
$$

where $z_{k}=u_{k}-U_{k}(\lambda) X_{k}^{-1}(\lambda) x_{k}$ with $x_{k}, u_{k}$ as in Lemma 1.
The next statement with the notation of Section 3 follows immediately from Lemma 3 and Lemma 4.

Corollary 2. Under the assumptions of Lemma 4

$$
y^{T}\left(\mathcal{A}_{N+1}-\lambda \mathcal{D}\right) y=\sum_{k=n}^{N} r_{n}(k) \frac{\operatorname{det} X_{k+1}(\lambda)}{\operatorname{det} X_{k}(\lambda)} w_{k+1-n}^{2}
$$

where $w_{\nu}=y_{\nu}+\sum_{\mu=\nu+1}^{\nu+n} \alpha_{\mu} y_{\mu}$ with suitable coefficients $\alpha_{\mu}=\alpha_{\mu}(\nu, \lambda)$. Hence, $w=T y$ with $T=\left(\begin{array}{ccc}1 & \star & \star \\ \vdots & \ddots & \star \\ 0 & \cdots & 1\end{array}\right)$, so that $\operatorname{det} T=1$.

### 4.2. Main Results

First, the Lemmas 3 and 4 with Crollary 2 yield our first result, which states a formula for the characteristic polynomial of $\mathcal{A}$ and its recursive calculation.
Theorem 1. (Recursion) Assume (3), (5), and suppose that

$$
\begin{equation*}
\rho(k)>0 \quad \text { for } \quad 0 \leq k \leq N-n \tag{6}
\end{equation*}
$$

holds. Then, with the notation of Section 3,

$$
\begin{equation*}
\operatorname{det}(\mathcal{A}-\lambda \mathcal{D})=r_{n}(0) \cdots r_{n}(N) \operatorname{det} X_{N+1}(\lambda) \tag{7}
\end{equation*}
$$

for all $\lambda \in \mathbb{R}$. Moreover, by (4) and (5), $X_{N+1}(\lambda)$ is given by the recursion

$$
X_{k+1}=\tilde{A}\left(X_{k}+B_{k} U_{k}\right), U_{k+1}=\left(C_{k}-\lambda \tilde{C}_{k}\right) X_{k+1}+\left(I-A^{T}\right) U_{k}
$$

for all $0 \leq k \leq N$ with $X_{0}=0, U_{0}=I$.
Proof. By Lemma 3 and Lemma 4 we have that

$$
\begin{aligned}
\operatorname{det} \mathcal{A}(\lambda) & =r_{n}(n) \frac{\operatorname{det} X_{n+1}(\lambda)}{\operatorname{det} X_{n}(\lambda)} \cdots r_{n}(N) \frac{\operatorname{det} X_{N+1}(\lambda)}{\operatorname{det} X_{N}(\lambda)} \\
& =r_{n}(0) \cdots r_{n}(N) \operatorname{det} X_{N+1}(\lambda)
\end{aligned}
$$

Next, the general oscillation theorem for Hamiltonian systems from reference [3] implies a corresponding result here.
Theorem 2. (Oscillation) Under the assumptions of Theorem 1 let $\lambda \in \mathbb{R}$ with $\operatorname{det} X_{k}(\lambda) \neq 0$ for $n \leq k \leq N+1$. Then, the number of eigenvalues (including multiplicities) of the eigenvalue problem (1), (2) from Section 1, which are less than $\lambda$, equals the number of focal points of $X(\lambda)$ in the interval $(0, N+1]$.

Remark 2. Observe first, that the multiplicity of an eigenvalue $\lambda$ is given by the rank of the kernel of $X_{N+1}(\lambda)$. Hence, it is an integer in $\{1, \ldots, n\}$. Moreover, by Remark 1 , the focal points of $X(\lambda)$ are all simple, i.e., of multiplicity one, and their number in $(0, N+1$ ] equals the number of the elements of the set

$$
\left\{k: n \leq k \leq N \text { with } r_{n}(k) \frac{\operatorname{det} X_{k+1}(\lambda)}{\operatorname{det} X_{k}(\lambda)}<0\right\}
$$

The next corollary is just another formulation of Theorem 2. It generalizes the well-known theorem of Sturm on "Sturmian chains" (cf. [[4], Theorem 8.5-1 and [8], Sätze 4.8 and 4.9). Moreover, it yields the Poincaré separation theorem for banded matrices (cf. [[5], 4.3.16 Corollary]).
Corollary 3. Under the assumptions of Theorem 2 and the previous notation define polynomials $f_{k}(t)$ by

$$
\begin{equation*}
f_{k}(t):=\operatorname{det} \mathcal{A}_{k}(t) \quad \text { for } n+1 \leq k \leq N+1 \quad \text { and } \quad f_{n}(t) \equiv 1 \tag{8}
\end{equation*}
$$

Then the number of zeros of $f_{N+1}(t)$ (including multiplicities), which are less than $\lambda$, equals the number of sign changes of $\left\{f_{k}(\lambda)\right\}$ for $n \leq k \leq N+1$, i.e., $\left\{f_{k}(\lambda)\right\}$ is a "Sturmian chain".

Proof. The assertion follows from Theorem 1 and Theorem 2, because

$$
f_{k}(\lambda)=r_{n}(0) \cdots r_{n}(k-1) \operatorname{det} X_{k}(\lambda)
$$

for $n \leq k \leq N+1$, so that

$$
\frac{f_{k+1}(\lambda)}{f_{k}(\lambda)}=r_{n}(k) \frac{\operatorname{det} X_{k+1}(\lambda)}{\operatorname{det} X_{k}(\lambda)}
$$

Finally, we have the following inversion formula, where the "easy" part is the assertion (i) of Lemma 2, while the main formula will be proved in detail via generating functions in a forthcoming paper as already mentioned in the introduction.

Theorem 3. (Inversion) The following inversion formulas hold:

$$
\begin{equation*}
r_{\mu}(k+\mu)= \tag{9}
\end{equation*}
$$

$$
(-1)^{\mu} \sum_{s=\mu}^{n}\left\{\binom{s}{\mu} a_{k+1, k+1+s}+\sum_{l=1}^{s-\mu} \frac{s}{l}\binom{\mu+l-1}{l-1}\binom{s-l-1}{s-\mu-l} a_{k+1-l, k+1-l+s}\right\}
$$

for $0 \leq \mu \leq n$ and all $k$, if and only if the $a_{\mu \nu}$ are given by

$$
\begin{equation*}
a_{k+1, k+1+t}=(-1)^{t} \sum_{\mu=t}^{n} \sum_{\nu=t}^{\mu}\binom{\mu}{\nu}\binom{\mu}{\nu-t} r_{\mu}(k+\nu) \tag{10}
\end{equation*}
$$

for $0 \leq t \leq n$ and all $k$.

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