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## Ján Andres

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# ON STABILITY AND INSTABILITY OF THE ROOTS OF THE OSCILLATORY FUNCTION IN A CERTAIN NONLINEAR DIFFERENTIAL EQUATION OF THE THIRD ORDER 

Jan Andres, Olomouc<br>(Received March 7, 1983)

## 1.

Our article deals with the analysis of (in)stability of the roots $\bar{x}$ of the oscillatory function $h(x)$ in the equation

$$
\begin{equation*}
x^{\prime \prime \prime}+a x^{\prime \prime}+g(x) x^{\prime}+h(x)=0 \tag{1}
\end{equation*}
$$

where $a>0$ is a constant, $g(x), h(x) \in \mathscr{C}^{1}(-\infty, \infty)$ and the function $h(x)$ has infinite number of isolated zero points $\bar{x}$ on the interval $(-\infty, \infty)$.

We will apply the well-known Liapunov's second method represented by the following

Theorem 0. a) If there exists such a continuous positive definite function $V(X)$ that the relation

$$
V^{\prime}:=(\operatorname{grad} V(X), F(X))=\frac{\mathrm{d} V(X)}{\mathrm{d} t_{(0)}} \leqq 0
$$

holds with respect to the system

$$
\begin{equation*}
X^{\prime}=F(X) \quad(F(0)=0) \tag{0}
\end{equation*}
$$

and the set $V^{\prime}=0$ contains no trajectory except 0 , then the trivial solution of the system (0) is asymptotically stable.
b) If there exists such a continuous function $V(X)$ which is not negative definite in any neighbourhood of the origin, $V^{\prime}>0$ and the set $V^{\prime}=0$ contains no trajectory except 0 , then the trivial solution of the system ( 0 ) is unstable.

For the proof see e.g. [1, pp. 19-23].

## 2.

Theorem 1. If there exists such an h-neighbourhood of the root $\bar{x}$ of $h(x)$ in (1) that the conditions

1) $h^{\prime}(x)>0$
2) $a g(x)-h^{\prime}(x) \geqq \delta>0$ ( $\delta$-const.),
3) $g^{\prime}(\bar{x})=0$
are satisfied for $0<|x-\bar{x}|<h$, then $\bar{x}$ is asymptotically stable.
Proof. It is obvious that the root $\bar{x}$ of $h(x)$ in (1) is asymptotically stable if and only if the same is true for the trivial solution of the equation

$$
\begin{equation*}
x^{\prime \prime \prime}+a x^{\prime \prime}+g^{*}(x) x^{\prime}+h^{*}(x)=0 \tag{2}
\end{equation*}
$$

where $g^{*}(x):=g(x+\bar{x}), h^{*}(x):=h(x+\bar{x})$.
Let us transform (2) to the equivalent system

$$
x^{\prime}=y, \quad y^{\prime}=z, \quad z^{\prime}=-h^{*}(x)-g^{*}(x) y-a z
$$

Since it is a well-known fact (see e.g. [2]) that the asymptotic stability of the trivial solution of ( $2^{\prime}$ ) can be reached under the assumptions 1), 2) and $\left.3^{\prime}\right): g^{*^{\prime}}(x) \operatorname{sgn} x \geqq 0$ holding for the functions $g^{*}, h^{*}$ in an $h$-neighbourhood of the solution mentioned, we have to prove that the same holds also under a more general assumption than $3^{\prime}$ ), namely $g^{* \prime}(0)=0$.

Applying the Liapunov function (cf. [2])

$$
V(x, y, z)=a \int_{0}^{x} h^{*}(s) \mathrm{d} s+h^{*}(x) y+\frac{1}{2}\left[g^{*}(x) y^{2}+(a y+z)^{2}\right],
$$

which for $x \neq 0$ can be rewritten as

$$
V(x, y, z)=W(x)+\frac{1}{2}\left\{g^{*}(x)\left[\frac{h^{*}(x)}{g^{*}(x)}+y\right]^{2}+(a y+z)^{2}\right\}
$$

where

$$
\begin{gathered}
W(x)=\int_{0}^{x} \frac{h^{*}(s)}{g^{*}(s)}\left[\frac{1}{2} \frac{h^{*}(s)}{g^{*}(s)} g^{*^{\prime}}(s)+a g^{*}(s)-h^{*^{\prime}}(s)\right] \mathrm{d} s \geqq \\
\geqq \int_{0}^{x} \frac{h^{*}(s)}{g^{*}(s)}\left[\frac{1}{2} \frac{h^{*}(s)}{g^{*}(s)} g^{*^{\prime}}(s)+\delta\right] \mathrm{d} s,
\end{gathered}
$$

we can see that such a number $h \geqq h_{1}>0$ must exist that the relation

$$
\lim _{x \rightarrow 0}\left[\frac{h^{*}(x)}{g^{*}(x)} g^{*^{\prime}}(x)\right]=0 \quad|x| \leqq h_{1}
$$

implied by 1 ) -3 ) yields

$$
\frac{1}{2} \frac{h^{*}(x)}{g^{*}(x)} g^{*^{\prime}}(x)+\delta>0
$$

and consequently $V^{\prime}(x, y, z)$ is positive definite.

Since the derivative of $V(x, y, z)$ with respect to $\left(2^{\prime}\right)$ satisfies

$$
\frac{\mathrm{d} V(x, y, z)}{\mathrm{d} t_{\left(2^{\prime}\right)}}=-\left[a g^{*}(x)-h^{*^{\prime}}(x)-\frac{1}{2} g^{*^{\prime}}(x) y\right] y^{2} \leqq-\frac{1}{2} \delta y^{2}
$$

for $\left|g^{* \prime}(x) y\right| \leqq \delta$ when $|x| \leqq h_{2} \leqq h_{1},|y| \leqq k\left(h_{2}, k\right.$-suitable constants), and the set $V_{\left(2^{\prime}\right)}^{\prime}=0$ contains no trajectory except ( $0,0,0$ ), the trivial solution of ( $2^{\prime}$ ) (and consequently also the root $\bar{x}$ of $h(x)$ in (1)) is, according to Theorem 0 , a), asymptotically stable. Q.E.D.

## 3.

Let us proceed to the examination of unstable roots.

Lemma 1. If there exists such an h-neighbourhood of the origin that the condition

$$
\left.1^{\prime}\right) h(x) \operatorname{sgn} x<0
$$

is satisfied for $0<|x|<h$, then the trivial solution of $(1)$ is unstable.

## Proof. Let us transform (1) to the equivalent system

$$
x^{\prime}=y, \quad y^{\prime}=z, \quad z^{\prime}=-h(x)-g(x) y-a z
$$

Using the function $V(x, y, z)$ with suitable parameters $\alpha, \beta$ :
$V(x, y, z)=-\alpha \int_{0}^{x} g(s) s \mathrm{~d} s+\beta \int_{0}^{x} h(s) \mathrm{d} s-\alpha a x y+\frac{1}{2}(\beta a+\alpha) y^{2}-\alpha x z+\beta y z$,
we obtain the following identity:

$$
\frac{\mathrm{d} V(x, y, z)}{\mathrm{d} t_{\left(1^{\prime}\right)}}=\alpha h(x) x-y^{2}(\alpha a+\beta g(x))+\beta z^{2}
$$

Thus, denoting $K:=\max _{|x| \leqq h}|g(x)|$ and choosing $\beta:=1, \alpha:<-K \mid a$, we conclude that

$$
\frac{\mathrm{d} V}{\mathrm{~d} t_{\left(1^{\prime}\right)}}>0 \quad \text { for } \quad|x| \leqq h \quad((x, y, z) \neq(0,0,0))
$$

Since the function $V(x, y, z)$ is evidently idenfinite, the trivial solution of $(1)$ is, according to Theorem $0, \mathrm{~b}$ ), unstable. Q.E.D.

Lemma 2. If there exists such an h-neighbourhood of the origin that the conditions

$$
\begin{aligned}
& \text { 1) } h(x) \operatorname{sgn} x>0 \\
& \text { 2') } g(x) \leqq-\delta<0 \quad(\delta \text {-const. })
\end{aligned}
$$

are satisfied for $0<|x|<h$, then the trivial solution of $(1)$ is unstable.

Proof. Employing the same Liapunov function as in the proof of Lemma 1 and choosing the parameters $\alpha, \beta$ as follows:

$$
\alpha:=1, \quad \beta:=\frac{a}{K}, \quad \text { where } \inf _{0<|x|<h}|g(x)|:=K \geqq \delta
$$

we find that the relation

$$
\frac{\mathrm{d} V}{\mathrm{~d} t_{\left(1^{\prime}\right)}}>0
$$

is satisfied for $|x| \leqq h((x, y, z) \neq(0,0,0))$. Therefore the same argument as that used in Lemma 1 confirms the above assertion.

Lemma 3. If there exists such an h-neighbourhood of the origin that the conditions

$$
\begin{aligned}
& \text { 1) } h^{\prime}(0)=0 \\
& \text { 2') }^{\prime} h^{\prime}(x)-a g(x) \geqq \delta>0 \quad \text { ( } \delta \text {-const.) } \\
& \text { 3') } g(x)>0
\end{aligned}
$$

are satisfied for $0<|x|<h$, then the trivial solution of (1) is unstable.
Proof. It is useful to notice that the assumption 1)- $3^{\prime}$ ) imply the existence of such a constant $0<h_{1} \leqq h$ that the relations

$$
\begin{equation*}
\frac{h(x)}{x}-a g(x) \geqq \frac{\delta}{2}, \quad h(x) \operatorname{sgn} x>0 \tag{3}
\end{equation*}
$$

hold for $0<|x|<h_{1}$, because, by virtue of the L'Hospital rule,

$$
\begin{equation*}
\lim _{x \rightarrow 0}\left[\frac{h^{\prime}(x)}{x}-a g^{\prime}(x)\right]=h^{\prime}(0)-a g^{\prime}(0) \geqq \delta \tag{4}
\end{equation*}
$$

is satisfied in view of 1 ), $2^{\prime}$ ) and the function $(h(x) \mid x-a g(x))$ is assumed to be continuous for $0<|x|<h_{1}$; the second relation follows immediately from $3^{\prime}$ ).

If we transform (1) to $\left(1^{\prime}\right)$ again and employ the Liapunov function of the form

$$
-V(x, y, z)=a \int_{0}^{x} g(s) s \mathrm{~d} s-\alpha \int_{0}^{x} h(s) \mathrm{d} s-a^{2} x y+a x z-(1+\alpha) a y^{2} / 2-\alpha y z
$$

with a positive parameter $\alpha$, we come to

$$
\frac{\mathrm{d} V(x, y, z)}{\mathrm{d} t_{\left(1^{\prime}\right)}}=-\frac{a x}{h^{\prime}(x)}[h(x)+a z]^{2}-y^{2}\left[a^{2}-\alpha g(x)\right]-z^{2}\left[\alpha-\frac{a^{3} x}{h(x)}\right]
$$

Hence, in order to satisfy

$$
\frac{\mathrm{d} V}{\mathrm{~d} t_{\left(1^{\prime}\right)}}>0 \quad((x, y, z) \neq(0,0,0))
$$

the inequalities

$$
\begin{equation*}
a^{2}>\alpha g(x), \quad \alpha>\frac{a^{3} x}{h(x)} \tag{5}
\end{equation*}
$$

i.e. $\frac{h(x)}{x}>\frac{a^{3}}{\alpha}>a g(x)$, must be fulfilled.

However, taking $\alpha:=a^{2} /(g(0)+\delta a / 4)$, (5) can be satisfied for $0<|x|<h_{2} \leqq$ $\leqq h_{1}$, where $h_{2}$ is a certain suitable constant, as it follows immediately from (3), (4).

Since the remaining assumptions of Theorem $0, b$ ) can be easily verified and $V(x, y, z)$ is indefinite, the trivial solution of (1) is again unstable.

Theorem 2. If there exists such an h-neighbourhood of the root $\bar{x}$ of $h(x)$ in (1) that at least one of the following conditions is satisfied:

1) $h^{\prime}(x)<0$,
2) $h^{\prime}(x)>0, g(x) \leqq-\delta<0$,
3) $h(\bar{x})=0, \quad g(x)>0, \quad h^{\prime}(x)-a g(x) \geqq \delta>0$
for $0<|x-\bar{x}|<h$, then the root $\bar{x}$ is unstable.
Proof follows immediately from Lemmas $1,2,3$ by the same arguments as those used in the proof of Theorem 1.

## 4.

Although we have succeeded in obtaining information about unstable roots of $h(x)$, by reversing the conditions 1 ), 2) of Theorem 1 , neither of the two conditions can be said to be a necessary one.

## References

[1] E. A. Barbashin: Liapunov Functions (in Russian). Nauka, Moscow 1970.
[2] V. Haas: A stability result for a third order nonlinear differential equation. J. London Math. Soc. 40 (1965), 31-33.

Author's address: 77146 Olomouc, Gottwaldova 15 (Laboratoř optiky PU).

