Ján Andres On stability and instability of the roots of the oscillatory function in a certain nonlinear differential equation of the third order

Časopis pro pěstování matematiky, Vol. 111 (1986), No. 3, 225--229

Persistent URL: http://dml.cz/dmlcz/108157

Terms of use:

© Institute of Mathematics AS CR, 1986

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* http://project.dml.cz

ČASOPIS PRO PĚSTOVÁNÍ MATEMATIKY

Vydává Matematický ústav ČSAV, Praha SVAZEK 111 * PRAHA 18. 7. 1986 * ČÍSLO 3

ON STABILITY AND INSTABILITY OF THE ROOTS OF THE OSCILLATORY FUNCTION IN A CERTAIN NONLINEAR DIFFERENTIAL EQUATION OF THE THIRD ORDER

JAN ANDRES, Olomouc (Received March 7, 1983)

1.

Our article deals with the analysis of (in)stability of the roots \bar{x} of the oscillatory function h(x) in the equation

(1)
$$x''' + ax'' + g(x) x' + h(x) = 0,$$

where a > 0 is a constant, g(x), $h(x) \in \mathscr{C}^1(-\infty, \infty)$ and the function h(x) has infinite number of isolated zero points \bar{x} on the interval $(-\infty, \infty)$.

We will apply the well-known *Liapunov's second method* represented by the following

Theorem 0. a) If there exists such a continuous positive definite function V(X) that the relation

 $V' := (\operatorname{grad} V(X), F(X)) = \frac{\mathrm{d}V(X)}{\mathrm{d}t_{(0)}} \leq 0$

holds with respect to the system

(0) $X' = F(X) \quad (F(0) = 0)$

and the set V' = 0 contains no trajectory except 0, then the trivial solution of the system (0) is asymptotically stable.

b) If there exists such a continuous function V(X) which is not negative definite in any neighbourhood of the origin, V' > 0 and the set V' = 0 contains no trajectory except 0, then the trivial solution of the system (0) is unstable.

For the proof see e.g. [1, pp. 19-23].

Theorem 1. If there exists such an h-neighbourhood of the root \bar{x} of h(x) in (1) that the conditions

1)
$$h'(x) > 0$$
,
2) $a g(x) - h'(x) \ge \delta > 0$ (δ -const.),
3) $g'(\bar{x}) = 0$

are satisfied for $0 < |x - \bar{x}| < h$, then \bar{x} is asymptotically stable.

Proof. It is obvious that the root \bar{x} of h(x) in (1) is asymptotically stable if and only if the same is true for the trivial solution of the equation

(2)
$$x''' + ax'' + g^*(x) x' + h^*(x) = 0$$
,

where $g^*(x) := g(x + \bar{x}), h^*(x) := h(x + \bar{x}).$

Let us transform (2) to the equivalent system

(2')
$$x' = y, \quad y' = z, \quad z' = -h^*(x) - g^*(x) y - az.$$

Since it is a well-known fact (see e.g. [2]) that the asymptotic stability of the trivial solution of (2') can be reached under the assumptions 1), 2) and 3'): $g^{*'}(x) \operatorname{sgn} x \ge 0$ holding for the functions g^* , h^* in an *h*-neighbourhood of the solution mentioned, we have to prove that the same holds also under a more general assumption than 3'), namely $g^{*'}(0) = 0$.

Applying the Liapunov function (cf. [2])

$$V(x, y, z) = a \int_0^x h^*(s) \, ds + h^*(x) \, y + \frac{1}{2} [g^*(x) \, y^2 + (ay + z)^2] \, ,$$

which for $x \neq 0$ can be rewritten as

$$V(x, y, z) = W(x) + \frac{1}{2} \left\{ g^*(x) \left[\frac{h^*(x)}{g^*(x)} + y \right]^2 + (ay + z)^2 \right\},$$

where

$$W(x) = \int_{0}^{x} \frac{h^{*}(s)}{g^{*}(s)} \left[\frac{1}{2} \frac{h^{*}(s)}{g^{*}(s)} g^{*'}(s) + a g^{*}(s) - h^{*'}(s) \right] ds \ge$$
$$\ge \int_{0}^{x} \frac{h^{*}(s)}{g^{*}(s)} \left[\frac{1}{2} \frac{h^{*}(s)}{g^{*}(s)} g^{*'}(s) + \delta \right] ds ,$$

we can see that such a number $h \ge h_1 > 0$ must exist that the relation

$$\lim_{x \to 0} \left[\frac{h^*(x)}{g^*(x)} g^{*'}(x) \right] = 0 \quad |x| \leq h_1$$

implied by 1 - 3 yields

$$\frac{1}{2}\frac{h^{*}(x)}{g^{*}(x)}g^{*'}(x) + \delta > 0,$$

and consequently V(x, y, z) is positive definite.

226

Since the derivative of V(x, y, z) with respect to (2') satisfies

$$\frac{\mathrm{d}V(x, y, z)}{\mathrm{d}t_{(2')}} = -\left[a g^*(x) - h^{*'}(x) - \frac{1}{2}g^{*'}(x) y\right] y^2 \leq -\frac{1}{2}\delta y^2$$

for $|g^{*'}(x) y| \leq \delta$ when $|x| \leq h_2 \leq h_1$, $|y| \leq k$ (h_2 , k-suitable constants), and the set $V'_{(2')} = 0$ contains no trajectory except (0, 0, 0), the trivial solution of (2') (and consequently also the root \bar{x} of h(x) in (1)) is, according to Theorem 0, a), asymptotically stable. Q.E.D.

3.

Let us proceed to the examination of unstable roots.

Lemma 1. If there exists such an h-neighbourhood of the origin that the condition

1')
$$h(x) \operatorname{sgn} x < 0$$

is satisfied for 0 < |x| < h, then the trivial solution of (1) is unstable.

['] Proof. Let us transform (1) to the equivalent system

(1')
$$x' = y, \quad y' = z, \quad z' = -h(x) - g(x) y - az.$$

Using the function V(x, y, z) with suitable parameters α, β :

$$V(x, y, z) = -\alpha \int_0^x g(s) s \, \mathrm{d}s + \beta \int_0^x h(s) \, \mathrm{d}s - \alpha a xy + \frac{1}{2}(\beta a + \alpha) y^2 - \alpha xz + \beta yz,$$

we obtain the following identity:

$$\frac{\mathrm{d}V(x, y, z)}{\mathrm{d}t_{(1')}} = \alpha h(x) x - y^2(\alpha a + \beta g(x)) + \beta z^2 \, .$$

Thus, denoting $K := \max_{|x| \le h} |g(x)|$ and choosing $\beta := 1$, $\alpha :< -K/a$, we conclude that

that

$$\frac{\mathrm{d}V}{\mathrm{d}t_{(1')}} > 0 \quad \text{for} \quad |x| \leq h \quad ((x, y, z) \neq (0, 0, 0)) \,.$$

Since the function V(x, y, z) is evidently idenfinite, the trivial solution of (1) is, according to Theorem 0, b), unstable. Q.E.D.

Lemma 2. If there exists such an h-neighbourhood of the origin that the conditions

1)
$$h(x) \operatorname{sgn} x > 0$$
,
2') $g(x) \leq -\delta < 0$ (δ -const.)

are satisfied for 0 < |x| < h, then the trivial solution of (1) is unstable.

Proof. Employing the same Liapunov function as in the proof of Lemma 1 and choosing the parameters α , β as follows:

$$\alpha := 1$$
, $\beta := \frac{a}{K}$, where $\inf_{0 < |x| < h} |g(x)| := K \ge \delta$,

we find that the relation

$$\frac{\mathrm{d}V}{\mathrm{d}t_{(1')}} > 0$$

is satisfied for $|x| \leq h$ ((x, y, z) \neq (0, 0, 0)). Therefore the same argument as that used in Lemma 1 confirms the above assertion.

Lemma 3. If there exists such an h-neighbourhood of the origin that the conditions

1)
$$h(0) = 0$$
,
2') $h'(x) - a g(x) \ge \delta > 0$ (δ -const.),
3') $g(x) > 0$

are satisfied for 0 < |x| < h, then the trivial solution of (1) is unstable.

Proof. It is useful to notice that the assumption 1)-3' imply the existence of such a constant $0 < h_1 \leq h$ that the relations

(3)
$$\frac{h(x)}{x} - a g(x) \ge \frac{\delta}{2}, \quad h(x) \operatorname{sgn} x > 0$$

hold for $0 < |x| < h_1$, because, by virtue of the L'Hospital rule,

(4)
$$\lim_{x \to 0} \left[\frac{h(x)}{x} - a g(x) \right] = h'(0) - a g(0) \ge \delta$$

is satisfied in view of 1), 2') and the function (h(x)|x - a g(x)) is assumed to be continuous for $0 < |x| < h_1$; the second relation follows immediately from 3').

If we transform (1) to (1') again and employ the Liapunov function of the form

$$-V(x, y, z) = a \int_0^x g(s) s \, ds - \alpha \int_0^x h(s) \, ds - a^2 xy + axz - (1 + \alpha) \, ay^2/2 - \alpha yz$$

with a positive parameter α , we come to

$$\frac{dV(x, y, z)}{dt_{(1')}} = -\frac{ax}{h(x)} \left[h(x) + az\right]^2 - y^2 \left[a^2 - \alpha g(x)\right] - z^2 \left[\alpha - \frac{a^3x}{h(x)}\right].$$

Hence, in order to satisfy

$$\frac{\mathrm{d}V}{\mathrm{d}t_{(1')}} > 0 \quad ((x, y, z) \equiv (0, 0, 0)),$$

228

the inequalities

(5)
$$a^2 > \alpha g(x), \quad \alpha > \frac{a^3 x}{h(x)},$$

i.e. $\frac{h(x)}{x} > \frac{a^3}{\alpha} > a g(x)$, must be fulfilled.

However, taking $\alpha := a^2/(g(0) + \delta a/4)$, (5) can be satisfied for $0 < |x| < h_2 \le h_1$, where h_2 is a certain suitable constant, as it follows immediately from (3), (4). Since the remaining assumptions of Theorem 0, b) can be easily verified and

V(x, y, z) is indefinite, the trivial solution of (1) is again unstable.

Theorem 2. If there exists such an h-neighbourhood of the root \bar{x} of h(x) in (1) that at least one of the following conditions is satisfied:

1)
$$h'(x) < 0$$
,
2) $h'(x) > 0$, $g(x) \le -\delta < 0$,
3) $h(\bar{x}) = 0$, $g(x) > 0$, $h'(x) - a g(x) \ge \delta > 0$

for $0 < |x - \bar{x}| < h$, then the root \bar{x} is unstable.

Proof follows immediately from Lemmas 1, 2, 3 by the same arguments as those used in the proof of Theorem 1.

4.

Although we have succeeded in obtaining information about unstable roots of h(x), by reversing the conditions 1), 2) of Theorem 1, neither of the two conditions can be said to be a necessary one.

References

- [1] E. A. Barbashin: Liapunov Functions (in Russian). Nauka, Moscow 1970.
- [2] V. Haas: A stability result for a third order nonlinear differential equation. J. London Math. Soc. 40 (1965), 31-33.

Author's address: 771 46 Olomouc, Gottwaldova 15 (Laboratoř optiky PU).