Štefan Schwabik Note on Volterra-Stieltjes integral equations

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NOTE ON VOLTERRA-STIELTJES INTEGRAL EQUATIONS

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This note is a supplement to the paper [2] which is devoted to the Volterra-Stieltjes integral equation in the space $BV_n[0, 1]$ of *n*-vector functions of bounded variation on the interval [0, 1].

Assume that K(t, s) is an $n \times n$ -matrix valued function defined on the square $[0, 1] \times [0, 1] = J$ such that

 $v(\mathbf{K}) < \infty$

and

(2)
$$\operatorname{var}_0^1 \mathbf{K}(0, \cdot) < \infty$$

where $v(\mathbf{K})$ denotes the two dimensional Vitali variation of \mathbf{K} on the square J and $\operatorname{var}_0^1 \mathbf{K}(0, \cdot)$ is the variation of $\mathbf{K}(0, s)$ in the second variable on the interval [0, 1]. The notions of variation are defined in the usual way by the norm in the space $L(R_n)$ of all $n \times n$ -matrices which is the operator norm for linear operators on R_n (see [1], [2], [3]).

In [2], Theorem 3.1 asserts the following:

If $\mathbf{K} : J \to L(\mathbf{R}_n)$ satisfies (1), (2) and for any $t \in (0, 1]$ the inverse matrix $[I - (\mathbf{K}(t, t) - \mathbf{K}(t, t-))]^{-1}$ exists then the homogeneous Volterra-Stieltjes integral equation

(3)
$$\mathbf{x}(t) - \int_{0}^{t} \mathbf{d}_{s} [\mathbf{K}(t, s)] \mathbf{x}(s) = \mathbf{0}$$

possesses only the trivial solution $\mathbf{x} = \mathbf{0}$ in $BV_n[0, 1]$.

This states that the condition

(4) I - (K(t, t) - K(t, t-)) is a regular matrix for all $t \in (0, 1]$

is sufficient for the equation (3) to have only the trivial solution $\mathbf{x} = \mathbf{0} \in BV_n$. Our aim is to prove that (4) is also a necessary condition for the equation (3) to have this property.

Note that the limit $\lim_{\tau \to t^-} \mathbf{K}(t, \tau) = \mathbf{K}(t, t^-)$ exists since (1) and (2) hold (see [1]).

1. Theorem. If $K : J \to L(R_n)$ satisfies (1) and (2) then the homogeneous Volterra-Stieltjes integral equation (3) has only the trivial solution $\mathbf{x} = \mathbf{0}$ in BV_n if and only if the condition (4) is satisfied.

Proof. The sufficiency of (4) is stated in the above quoted theorem from [2]. It remains to prove the necessity. We show in the sequel that if (4) is not satisfied then (3) has a nonzero solution in the space BV_n .

It was shown in [2] that for the operator

$$\mathbf{x} \in BV_n \to \int_0^t \mathbf{d}_s [\mathbf{K}(t, s)] \ \mathbf{x}(s) \in BV_n$$

we have

(5)
$$\int_{0}^{t} \mathbf{d}_{s} [\mathbf{K}(t, s)] \mathbf{x}(s) = \int_{0}^{1} \mathbf{d}_{s} [\mathbf{K}^{\Delta}(t, s)] \mathbf{x}(s)$$

where

(6) $K^{\Delta}(t, s) = K(t, s) - K(t, 0)$ if $0 \le s \le t \le 1$,

$$\mathbf{K}^{\Delta}(t, s) = \mathbf{K}(t, t) - \mathbf{K}(t, 0) = \mathbf{K}^{\Delta}(t, t) \text{ if } 0 \leq t < s \leq 1.$$

For the new "triangular" kernel \mathbf{K}^{Δ} we have $\operatorname{var}_{0}^{1} \mathbf{K}^{\Delta}(0, \cdot) < \infty$, $v(\mathbf{K}^{\Delta}) < \infty$, $\mathbf{K}^{\Delta}(t, 0) = 0$ for $t \in [0, 1]$ if (1) and (2) is satisfied for the kernel \mathbf{K} . Hence the equation (3) can be written in the Fredholm-Stieltjes form

$$\mathbf{x}(t) - \int_0^1 \mathbf{d}_s [\mathbf{K}^{\Delta}(t, s)] \mathbf{x}(s) = \mathbf{0}$$

Since (1) and (2) hold we have $\operatorname{var}_0^1 H < \infty$ for the matrix valued function $H: [0, 1] \to L(R_n)$ defined by the relations

$$H(t) = K(t, t) - K(t, t-)$$
 for $t \in (0, 1]$, $H(0) = 0$

and there exists a sequence $\{t_i\}_{i=1}^{\infty}$, $t_i \in (0, 1]$ such that $\mathbf{H}(t) = \mathbf{0}$ for $t \in [0, 1]$, $t \neq t_i, i = 1, 2, ...$ (see Lemma 3.1 in [2]). Hence $\sum_{i=1}^{\infty} ||\mathbf{H}(t_i)|| < \infty$ because $\operatorname{var}_0^1 \mathbf{H} = 2\sum_{t_i \in (0, 1]} ||\mathbf{H}(t_i)|| + ||\mathbf{H}(1)||$. This implies that $||\mathbf{H}(t)|| < \frac{1}{2}$ for $t \in [0, 1]$ except for a finite set of points in (0, 1). Hence the matrix $\mathbf{I} - \mathbf{H}(t)$ can be singular only at a finite set of points $T_i, i = 1, ..., k, 0 < T_1 < T_2 < \ldots < T_k \leq 1$.

Let us assume that the condition (4) is not satisfied. Then by the facts shown above there is a point $T_1 \in (0, 1]$ such that I - H(t) = I - (K(t, t) - K(t, t-)) is a regular matrix for $t \in [0, T_1)$ but $I - H(T_1) = I - (K(T_1, T_1) - K(T_1, T_1-))$ is not regular. Hence there exists $z \in R_n$ such that the linear algebraic equation

(7)
$$[I - (K(T_1, T_1) - K(T_1, T_1 -))] \mathbf{x} = \mathbf{z}$$

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has no solution in R_n . If we define the function $\mathbf{y}^{\wedge} : [0, 1] \to R_n$ by the relations $\mathbf{y}^{\wedge}(t) = \mathbf{0}$ for $t \in [0, 1]$, $t \neq T_1$ and $\mathbf{y}^{\wedge}(T_1) = \mathbf{z}$ then $\mathbf{y}^{\wedge} \in BV_n$. Let us now consider the Volterra-Stieltjes integral equation

(8)
$$\mathbf{x}(t) - \int_0^t \mathbf{d}_s [\mathbf{K}(t, s)] \mathbf{x}(s) = \mathbf{y}^*(t)$$

Since I - (K(t, t) - K(t, t-)) is regular for $t \in [0, T_1)$, every solution x of (8) vanishes on the interval $[0, T_1)$ by the first part of the theorem and for $t = T_1$ we have

$$\mathbf{x}(T_1) - \int_0^{T_1} \mathrm{d}_s [\mathbf{K}(T_1, s)] \mathbf{x}(s) = \mathbf{z}.$$

Using the relation

$$\int_{0}^{T_{1}} d_{s}[K(T_{1}, s)] \mathbf{x}(s) = (K(T_{1}, T_{1}) - K(T_{1}, T_{1}-)) \mathbf{x}(T_{1})$$

(see [1]) we get

$$\mathbf{x}(T_1) - (\mathbf{K}(T_1, T_1) - \mathbf{K}(T_1, T_1-)) \mathbf{x}(T_1) = \mathbf{z}$$

but the value $\mathbf{x}(T_1)$ cannot be determined since the linear algebraic equation (7) has no solution. Hence there is no $\mathbf{x} \in BV_n[0, 1]$ satisfying the equation (8), i.e. the range of the operator

$$\mathbf{x} \in BV_n \to \mathbf{x}(t) - \int_0^t \mathbf{d}_s [\mathbf{K}(t, s)] \mathbf{x}(s) \in BV_n$$

is a proper subspace in $BV_n[0, 1]$.

Since the Volterra-Stieltjes integral equation is a special case of the Fredholm-Stieltjes integral equation we obtain by the Fredholm Theorem (see Theorem 6 in [3]) that there exists in BV_n a nonzero solution of the homogeneous equation (3) and our theorem is completely proved.

2. Corollary. Let $K: J \to L(R_n)$ satisfy (1) and (2). Then the nonhomogeneous Volterra-Stieltjes integral equation

(9)
$$\mathbf{x}(t) - \int_{0}^{t} \mathbf{d}_{s}[\mathbf{K}(t, s)] \mathbf{x}(s) = \mathbf{y}(t)$$

has a unique solution $\mathbf{x} \in BV_n[0, 1]$ for any $\mathbf{y} \in BV_n[0, 1]$ if and only if the condition (4) is satisfied.

Proof. Since (5) holds the equation (9) can be written in the Fredholm-Stieltjes form

$$\mathbf{x}(t) - \int_0^1 \mathbf{d}_s [\mathbf{K}^{\Delta}(t, s)] \mathbf{x}(s) = \mathbf{y}(t)$$

where $K^{\Delta}: J \to L(R_n)$ is given by (6). By Theorem 1 the corresponding homogeneous

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equation has only the trivial solution $\mathbf{x} = \mathbf{0}$ in BV_n and consequently by the Fredholm Theorem (see Theorem 6. in [3]) we obtain the statement of the corollary.

3. Theorem. Let $K : J \to L(R_n)$ satisfy (1) and (2). If the condition (4) is satisfied then for every $y \in BV_n[0, 1]$ the unique solution of the equation (9) is given by the formula

(10)
$$\mathbf{x}(t) = \mathbf{y}(t) + \int_0^t \mathbf{d}_s [\boldsymbol{\Gamma}(t,s)] \, \mathbf{y}(s) \quad t \in [0, 1]$$

where $\Gamma(t, s)$, $0 \leq s \leq t \leq 1$ is a uniquely determined $n \times n$ – matrix valued function such that

(11)
$$\Gamma(t, s) = \mathbf{K}(t, s) - \mathbf{K}(t, 0) + \int_0^t d_r [\mathbf{K}(t, r)] \Gamma(r, s)$$

if $0 \leq s \leq t \leq 1$. If we define $\Gamma(t, s) = \Gamma(t, t)$ for $0 \leq t < s \leq 1$ then $v(\Gamma) < \infty$ and $\operatorname{var}_0^1 \Gamma(t, \cdot) < \infty$ for every $t \in [0, 1]$.

Proof. Since the equation (9) can be rewritten in the form of a Fredholm-Stieltjes integral equation

$$\mathbf{x}(t) - \int_{0}^{1} \mathbf{d}_{s} [\mathbf{K}^{\Delta}(t, s)] \mathbf{x}(s) = \mathbf{y}(t)$$

we obtain by Theorem 8. from [3] that the unique solution of this equation can be given by the formula

(12)
$$\mathbf{x}(t) = \mathbf{y}(t) + \int_0^1 \mathbf{d}_s [\mathbf{\Gamma}(t, s)] \mathbf{y}(s)$$

where $\Gamma: J \to L(R_n)$ satisfies the equality

$$\boldsymbol{\Gamma}(t,s) = \boldsymbol{K}^{\Delta}(t,s) - \boldsymbol{K}^{\Delta}(t,0) + \int_{0}^{1} \mathrm{d}_{r} [\boldsymbol{K}^{\Delta}(t,r)] \boldsymbol{\Gamma}(r,s)$$

for all $t, s \in [0, 1]$, $\operatorname{var}_0^1 \Gamma(0, \cdot) < \infty$, $\Gamma(t, 0) = 0$ for all $t \in [0, 1]$, and $v(\Gamma) < \infty$. Using the definition (6) of the "triangular" kernel K^{Δ} and the relation (5) we obtain

$$\int_0^1 \mathrm{d}_r [\mathbf{K}^{\Delta}(t, r)] \ \boldsymbol{\Gamma}(r, s) = \int_0^t \mathrm{d}_r [\mathbf{K}(t, r)] \ \boldsymbol{\Gamma}(r, s)$$

and this yields the relation (11) for $0 \le s \le t \le 1$. Further, evidently $\Gamma(t, s) = \Gamma(t, t)$ for $0 \le t < s \le 1$ and also

$$\int_{0}^{1} \mathbf{d}_{s}[\boldsymbol{\Gamma}(t, s)] \boldsymbol{\gamma}(s) = \int_{0}^{t} \mathbf{d}_{s}[\boldsymbol{\Gamma}(t, s)] \boldsymbol{\gamma}(s)$$

for every $\mathbf{y} \in BV_n$. Hence by (12) we obtain the representation (10) for the solution of the equation (7). Let us finally mention that by Theorem 8. in [3] the matrix valued function $\Gamma(t, s)$ is uniquely determined on the square J.

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