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ON CONTINUITY OF LINEAR TRANSFORMATIONS COMMUTING WITH GENERALIZED SCALAR OPERATORS IN BANACH SPACE

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## 1. INTRODUCTION

In the present paper we give a modification of methods having been presented in the paper of B. E. Johnson and A. M. Sinclair [5]. The question is, under which condition a linear transformation $S$ commuting with a linear continuous operator $T$ in a (complex) Banach space $X$ is continuous. Similarly as in the paper mentioned above we shall deal with operator $T$ having a suitable spectral decomposition. More exactly: suppose that there exists, for every closed subset $F$ of the complex plane $\mathbf{C}$, a closed linear subspace $\mathscr{E}(F)$ in $X$ such that the following conditions are fulfilled:

$$
\begin{equation*}
\mathscr{E}(\emptyset)=\{0\}, \quad \mathscr{E}(\mathbf{C})=X ; \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\bigcap_{n=1}^{\infty} \mathscr{E}\left(F_{n}\right)=\mathscr{E}\left(\bigcap_{n=1}^{\infty} F_{n}\right) \tag{2}
\end{equation*}
$$

if $\left\{G_{j}\right\}_{j=1}^{m}$ is a finite open covering of the complex plane, then

$$
\begin{gather*}
X=\mathscr{E}\left(\bar{G}_{1}\right)+\ldots+\mathscr{E}\left(\bar{G}_{m}\right)  \tag{3}\\
T \mathscr{E}(F) \subset \mathscr{E}(F) \quad \text { and } \quad \sigma(T \mid \mathscr{E}(F)) \subset F . \tag{4}
\end{gather*}
$$

For the sake of completness we recall now some definitions.

Definition. Let $x \in X$. A complex number $\lambda$ is an element of $\varrho_{T}(x)$ if there is a vectorvalued analytic function $x($.$) defined in a neighbourhood G_{\lambda}$ of $\lambda$ such that ( $\mu I-$ $-T) x(\mu)=x$ for all $\mu \in G_{\lambda}$. The spectrum $\sigma_{T}(x)$ is the complement of $\varrho_{T}(x)$.

Obviously $\sigma_{T}(x) \subset \sigma(T)$.
Definition. An operator $T \in \mathscr{L}(X)$ (the algebra of all linear continuous operators of $X$ ) is said to have the single-valued extension property if for every open subset $G$
of the complex plane and for any vector valued analytic function $f: G \rightarrow X$ the equality $(\lambda I-T) f(\lambda) \equiv 0$ on $G$ implies $f \equiv 0$.

For every operator $T$ having the single-valued extension property $\sigma_{T}(x)=\emptyset$ if and only if $x=0$.
It has been shown in [2] that each operator of the present class has the singlevalued extension property and that the present class of operators is nothing else than the class of decomposable operators (in sense of [2]) with

$$
\begin{equation*}
\mathscr{E}(F)=\left\{x: \sigma_{T}(x) \subset F\right\} \tag{5}
\end{equation*}
$$

We shall use the usual notation $X_{T}(F)=\mathscr{E}(F)$. Let $L \in \mathscr{L}(X)$ be such that $T L=$ $=L T$. Then it is easy to prove that $L X_{T}(F) \subset X_{T}(F)$ for every $F$ closed.
Hence, consider now a linear transformation $S$ commuting with our operator $T$ and such that $S X_{T}(F) \subset X_{T}(F)$ for every $F$ closed.
Denote by $\sigma_{S}$ the linear subspace of $X$ consisting of all elements $x$ such that there exists a sequence $x_{n} \rightarrow 0$ with $S x_{n} \rightarrow x$. The subspace $\sigma_{S}$ is closed. According to the closed graph theorem the transformation $S$ is continuous if and only if $\sigma_{S}=0$.
Since we have, for an arbitrary finite open covering, the decomposition of $X$, it is natural to take into account only the subspaces on which $S$ is not continuous. It is easy to see that each such subspace must have a non-trivial intersection with $\sigma_{s}$. We shall consider, therefore, the subspace $X_{T}(F)$ such that $\sigma_{S} \subset X_{T}(F)$. If $\lambda$ is not an element of $F$, then there exists a closed neighbourhood $G$ of $\lambda$ with $G \cap F=\emptyset$ and $S \mid X_{T}(G)$ is continuous by the closed graph theorem. This fact leads quite naturally to the following

Definition. We shall call a number $\lambda$ a discontinuity value if the operator $S \mid X_{T}(F)$ is discontinuous for every closed neighbourhood $F$ of $\lambda$.

Obviously every discontinuity value is an element of the set $F$ such that $\sigma_{S} \subset X_{T}(F)$.
Further, from the definition it follows immediately that the set of all discontinuity values is closed and contained in $\sigma(T)$.

Lemma. $\sigma_{S} \subset X_{T}(K)$ where $K$ is the set of all discontinuity values.
Proof. Let $\lambda \notin K$, let $F_{0}$ be a closed neighbourhood of $\lambda$ such that $S \mid X_{T}\left(F_{0}\right)$ is continuous. Let $\left\{G_{0}, G_{1}\right\}$ be an open covering of the complex plane, $\bar{G}_{0} \subset F_{0}$, $\lambda \notin \bar{G}_{1}$. Take an $x \in X$, let $x_{n} \rightarrow 0$ with $S x_{n} \rightarrow x$. Since we have, for every $x \in X$, the decomposition $x=x_{1}+x_{2}$ where $x_{1} \in X_{T}\left(\bar{G}_{0}\right), x_{2} \in X_{T}\left(\bar{G}_{1}\right)$, we can find sequences $x_{n}^{1} \rightarrow 0, x_{n}^{2} \rightarrow 0$ such that $x_{n}=x_{n}^{1}+x_{n}^{2}, x_{n}^{1} \in X_{T}\left(\bar{G}_{0}\right), x_{n}^{2} \in X_{T}\left(\bar{G}_{1}\right)$. We have $S x_{n}=$ $=S x_{n}^{1}+S x_{n}^{2}$. Since $S \mid X_{T}\left(\bar{G}_{0}\right)$ is continuous it follows $S x_{n}^{1} \rightarrow 0, S x_{n}^{2} \rightarrow x$ and $x \in X_{T}\left(\bar{G}_{1}\right)$, i.e. $\sigma_{S} \subset X_{T}\left(\bar{G}_{1}\right)$. We have obtained the following implication: if $\lambda \notin K$ then there is a closed $F_{\lambda}$ such that $\lambda \notin F_{\lambda}$ and $\sigma_{S} \subset X_{T}\left(F_{\lambda}\right)$. By (5) the family of subspaces $X_{T}(F)$ is closed with respect to the intersection and we have

$$
\sigma_{S} \subset \bigcap_{\lambda \notin K} X_{T}\left(F_{\lambda}\right)=X_{T}\left(\bigcap_{\lambda \notin K} F_{\lambda}\right) \subseteq X_{T}(K) .
$$

However, for the proof of the main theorem we have taken generalized scalar operators for which it is easy to characterize the structure of spaces $X_{T}(\{\lambda\})$.

## 2. PRELIMINARIES

2.1. Definition. Denote by $\left(C^{\infty}\left(R_{2}\right), \tau\right)$ the Fréchet space of all infinitely differentiable complex functions $\varphi\left(x_{1}, x_{2}\right)$ defined on $R_{2}$ with the family of pseudonorms

$$
|\varphi|_{k, m}=\sum_{p_{1}+p_{2}=0}^{m} \sup _{\left(x_{1}, x_{2}\right) \in K}\left|\frac{\partial^{p_{1}+p_{2}} \varphi\left(x_{1}, x_{2}\right)}{\partial^{p_{1}} x_{1} \partial^{p_{2}} x_{2}}\right|
$$

for every compact set $K$ and $p_{1}, p_{2}, m \geqq 0$.
2.2. Definition. A continuous linear operator $T$ in a Banach space $X$ is said to be a generalized scalar operator if there exists a continuous linear mapping $\mathscr{U}$ : $:\left(C^{\infty}\left(R_{2}\right), \tau\right) \rightarrow \mathscr{L}(X)$ such that

$$
\begin{gathered}
\mathscr{U}_{\varphi \psi}=\mathscr{U}_{\varphi} \mathscr{U}_{\psi} \text { for } \varphi, \psi \in C^{\infty}\left(R_{2}\right), \\
\mathscr{U}_{1}=I, \quad \mathscr{U}_{a}=T \quad \text { where } a(\lambda)=\lambda .
\end{gathered}
$$

We shall use some properties of generalized scalar operators contained in [1] (Theorem 2, Propositions 1, 2, 3) which we mention without proving them.
2.3. Proposition. Every generalized scalar operator $T$ has the single valued extension property. If we denote $X_{T}(F)=\left\{x: \sigma_{T}(x) \subset F\right\}$ for $F=\bar{F}$, then $X_{T}(F)$ is a closed invariant subspace with respect to $T$ such that $\sigma\left(T \mid X_{T}(F)\right) \subset F$.
2.4. Proposition. Let $x \in X$, let $\varphi_{1}, \varphi_{2}$ be two functions from $C^{\infty}\left(R_{2}\right)$ such that $\varphi_{1} \equiv$ $\equiv 1$ in a neighbourhood of $\sigma_{T}(x)$ and $\operatorname{supp} \varphi_{2} \cap \sigma_{T}(x)=\emptyset$. Then $\mathscr{U}_{\varphi_{1}} x=x$ and $\mathscr{U}_{\varphi_{2}} x=0$.
2.5. Proposition. Let $x \in X$. Then $\mathscr{U}_{\varphi} x \in X_{T}(\operatorname{supp} \varphi)$ for every $\varphi \in C^{\infty}\left(R_{2}\right)$. Further $\operatorname{supp} \mathscr{G}=\sigma(T)$.

Remark. Every generalized scalar operator $T$ is an element of the class of operators having been considered in the introduction.

Indeed, proposition 2.3 asserts that (1) and (4) is satisfied for each $X_{T}(F)$. (2) is obviously satisfied and to prove (3) take an open covering $\left\{G_{j}\right\}_{j=1}^{m}$ of the complex plane. There exist functions $\varphi_{j} \in C^{\infty}\left(R_{2}\right)$ such that $0 \leqq \varphi_{j} \leqq 1$, $\operatorname{supp} \varphi_{j} \subset \bar{G}_{j}$ $(j=1,2, \ldots, m)$ and $\sum_{j=1}^{m} \varphi_{j} \equiv 1$ in a neighbourhood of $\sigma(T)$. Since supp $\mathscr{m}=\sigma(T)$ we may write, for every $x$, that $x=\sum_{j=1}^{m} \mathscr{U}_{\varphi_{j}} x$ where $\mathscr{U}_{\varphi_{j}} x \in X_{T}\left(\operatorname{supp} \varphi_{j}\right) \subset X_{T}\left(\bar{G}_{j}\right)$
for $j=1,2, \ldots, m$ and (3) holds.

Every linear operator in the finite dimensional space as well as every spectral operator of the finite type are generalized scalar operators. For other examples see [1].

It will be useful to characterize the spaces $X_{T}(\{\lambda\})$.
2.6. Proposition. Let $Q$ be a polynomial with the roots $\mu_{1}, \ldots, \mu_{n}$. Then $\{x$ : $: Q(T) x=0\} \subset X_{T}\left(\left\{\mu_{1}, \ldots, \mu_{n}\right\}\right)$.

Proof. Let $\lambda$ be a complex number and let $x, y \in X$ be such that $x=(\lambda I-T) y$. Obviously $\sigma_{T}(x) \subset \sigma_{T}(y)$. We shall show that $\sigma_{T}(y) \subset \sigma_{T}(x) \cup\{\lambda\}$ or equivalently $\varrho_{T}(x) \cap\{\mathbf{C} \backslash \lambda\} \subset \varrho_{T}(y)$. Take a $\mu \neq \lambda$ and $\mu \in \varrho_{T}(x)$. There exists an analytic function $x(\gamma)$ defined in a neighbourhood $G_{\mu}$ of $\mu\left(\lambda \notin G_{\mu}\right)$ with $x=(\gamma I-T) x(\gamma)$ for $\gamma \in G_{\mu}$. Put $y(\gamma)=[1 /(\gamma-\lambda)](y-x(\gamma))$. The function $y(\gamma)$ is analytic in $G_{\mu}$ and $(\gamma I-T) y(\gamma)=y$. This means of course that $\mu \in \varrho_{T}(y)$.

Let $Q(T) z=x$. The induction with respect to the degree of the polynomial $Q$ yields $\sigma_{T}(z) \subset \sigma_{T}(x) \cup\left\{\mu_{1}, \ldots, \mu_{n}\right\}$. Particularly if $x=0$ then we obtain the result desired.
2.7. Proposition. If $\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}$ is a finite set of complex numbers, then there is a polynomial $P($.$) with the roots \lambda_{1}, \ldots, \lambda_{k}$ such that

$$
P(T) \mid X_{T}\left(\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}\right)=0
$$

Proof. Denote $\mathscr{U}_{\varphi}^{\prime}=\mathscr{U}_{\varphi} \mid X_{T}\left(\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}\right)$. It is easy to see that $T^{\prime}=T \mid X_{T}\left(\left\{\lambda_{1}, \ldots\right.\right.$ $\left.\left.\ldots, \lambda_{k}\right\}\right)$ is a generalized scalar operator and $\mathscr{U}^{\prime}$ is its distribution. Let $n$ be the order of the distribution $\mathscr{U}$, let $f$ be a continuous linear functional defined on $\mathscr{L}(X)$. Put $P(\lambda)=\left[\left(\lambda-\lambda_{1}\right) \cdot\left(\lambda-\lambda_{2}\right) \ldots\left(\lambda-\lambda_{k}\right)\right]^{n+1}$. Then $\mathscr{V}_{\varphi}=f \mathscr{U}_{\varphi}^{\prime}$ is a continuous linear functional on $\left(C^{\infty}\left(R_{2}\right), \tau\right)$, supp $\mathscr{V} \subset \operatorname{supp} \mathscr{U}^{\prime} \subseteq\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}$ and the order of $\mathscr{V}$ does not exceed the order of $\mathscr{U}^{\prime}$. Since $P(\lambda)$ is zero on supp $\mathscr{V}$ and all derivatives up to $n$ are zero as well, it follows by [3], theorem 1.5.4. that $\mathscr{V}_{P}=f \mathscr{U}_{P}^{\prime}=0$ for each $f$ so that $P(T) \mid X_{T}\left(\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}\right)=\mathscr{U}_{P}^{\prime}=0$.

Remark. From 2.6 and 2.7 it follows that $X_{T}\left(\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}\right)=X_{T}\left(\left\{\mu_{1}, \ldots, \mu_{j}\right\}\right)$ $(j \leqq k)$ where $\mu_{j}$ are all eigenvalues of $T$ from the set $\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}$.

## 3. LINEAR TRANSFORMATIONS COMMUTING WITH GENERALIZED SCALAR OPERATORS

Let $T$ be a generalized scalar operator and let $S$ be a linear transformation such that $S X_{T}(F) \subset X_{T}(F)$ for $F=\bar{F}$.
3.1. Lemma. The set of discontinuity values is either empty or it has only a finite number of elements.

Proof. To prove the lemma, we shall suppose that there is a sequence of distinct discontinuity values $\left\{\lambda_{i}\right\}_{i=1}^{\infty}$ and a closed sets $F_{i}$ such that $\lambda_{i} \in \operatorname{Int} F_{i}$ and $F_{i} \cap \overline{\bigcup_{j \neq i} F_{j}}=$ $=\emptyset$ for every $i \in N$. Take further $\varphi_{i} \in C^{\infty}\left(R_{2}\right)$ with $\operatorname{supp} \varphi_{i} \cap \overline{\bigcup_{j \neq i} F_{j}}=\emptyset$ and $\varphi_{i} \equiv 1$ in a neighbourhood of $F_{i}$. The restriction of $S$ to each of $X_{T}\left(F_{i}\right)$ is a discontinuous operator so that there exists, for each $i \in N$, an element $\xi_{i} \in X_{T}\left(F_{i}\right)$ such that

$$
\begin{equation*}
\left|\xi_{i}\right|<\frac{1}{2^{i}}, \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\left|S \xi_{i}\right|>i\left|\mathscr{U}_{\varphi_{i}}\right| . \tag{2}
\end{equation*}
$$

Now put $\eta=\sum_{i=1}^{\infty} \xi_{i}$. We can write, for each $i \in N$,

$$
S \eta=S \xi_{i}+S \sum_{j \neq i} \xi_{j}
$$

If a $j \neq i$ is given, then $\xi_{j} \in X_{T}\left(F_{j}\right) \subset X_{T}\left(\overline{\bigcup_{j \neq i}} F_{j}\right)$ and $\sum_{j \neq i} \xi_{j} \in X_{T}\left(\overline{\bigcup_{j \neq i} F_{j}}\right)$.
By the assumption all $X_{T}(F)$ are invariant with respect to $S$ so that $S \xi_{i} \in X_{T}\left(F_{i}\right)$ and $S \sum_{j \neq i} \xi_{j} \in X_{T}\left(\bigcup_{j \neq i} \bar{F}_{j}\right)$. Using 2.4 we obtain

$$
\mathscr{U}_{\varphi_{i}} S \sum_{j \neq i} \xi_{j}=0, \quad \mathscr{U}_{\varphi_{i}} S \xi_{i}=S \xi_{i}
$$

We have, for any $i \in N$, the estimate

$$
\left|\mathscr{U}_{\varphi_{i}}\right| \cdot|S \eta| \geqq\left|\mathscr{U}_{\varphi_{i}} S \eta\right|=\left|S \xi_{i}\right|>i\left|\mathscr{U}_{\varphi_{i}}\right|
$$

and this is a contradiction.
We shall show now that the existence of the distribution $\mathscr{U}$ is not essential and we can prove the same result for wider class of operators.
3.2. Definition. A decomposable operator $T$ is said to be a strongly decomposable operator if the equality

$$
\mathscr{E}(F)=\mathscr{E}(F) \cap \mathscr{E}\left(\bar{G}_{1}\right)+\ldots+\mathscr{E}(F) \cap \mathscr{E}\left(\bar{G}_{m}\right)
$$

holds for every finite open covering $\left\{G_{j}\right\}_{j=1}^{m}$ of the complex plane and for every subspace $\mathscr{E}(F)$.

The problem if there exists a decomposable operator which is not a strongly decomposable one is still open.

We shall use again the notation $X_{T}(F)=\mathscr{E}(F)$.
Lemma 3.1.' Let $T$ be a strongly decomposable operator. Then the set of discontinuity values is empty or it has only a finite number of elements.

Proof. Take the same sequence of discontinuity values as in 3.1. Let $i$ be fixed. $\infty$
Since $T$ is strongly decomposable, we have, for every $x \in X_{T}\left(\bigcup_{i=1} F_{i}\right)$, a unique representation $x=x_{1}^{i}+x_{2}^{i}$ where $x_{1}^{i} \in X_{T}\left(F_{i}\right), x_{2}^{i} \in X_{T}\left(\overline{\bigcup_{j \neq i} F_{j}}\right)$. The operator $R_{1}^{i} x=x_{1}^{i}$ is linear, continuous and $R_{1}^{i} \neq 0$. The transformation $S \mid X_{T}\left(F_{i}\right)$ is a discontinuous operator and we can find a $\xi_{i} \in X_{T}\left(F_{i}\right)$ with $\left|\xi_{i}\right|<1 / 2^{i}$ and $\left|S \xi_{i}\right|>i\left|R_{1}^{i}\right|$. Put $\eta=$ $=\sum_{i=1}^{\infty} \xi_{i}$. Then

$$
R_{1}^{i} S \eta=R_{1}^{i} S \xi_{i}+R_{1}^{i} S \sum_{j \neq i} \xi_{j}=S \xi_{i}
$$

We have, for each $i \in N$,

$$
\left|R_{1}^{i}\right| \cdot|S \eta| \geqq i\left|R_{1}^{i}\right| .
$$

With regard to the properties of generalized scalar operators we can reformulate the lemma from the introduction as follows:
3.3. Lemma. Either $\sigma_{S}=\{0\}$ or there exists a finite set of eigenvalues $\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}$ of $T$ with the property

$$
\sigma_{S} \subset X_{T}\left(\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}\right)
$$

Proof. First we shall find the minimal subspace $X_{T}(F)$ containing $\sigma_{S}$. Denote by $\mathfrak{A}$ the family of all closed $F$ such that $\sigma_{S} \subset X_{T}(F)$. Put $Y=\bigcap_{F \in \mathscr{U}} X_{T}(F)$. It follows immediately from 2.3 that $Y=X_{T}\left(\bigcap_{F \in \mathscr{A}} F\right)$ and $\sigma(T \mid Y) \subset F$ for each $F \in \mathfrak{A}$. To prove the lemma, it is sufficient to show that $\sigma(T \mid Y)$ consists of discontinuity values only. Indeed, if the set of discontinuity values is empty, then $\sigma_{S} \subset Y=X_{T}(\sigma(T \mid Y))=$ $=X_{T}(\emptyset)=\{0\}$. If the set of discontinuity values consists of elements $\lambda_{1}, \ldots, \lambda_{k}$, then $\sigma_{S} \subset X_{T}\left(\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}\right)$.
In view of the remark in the end of the preceding section we may assume that all $\lambda_{1}, \ldots, \lambda_{k}$ are eigenvalues of $T$.
Take a $\lambda$ which is not a discontinuity value. In such case there is a closed neighbourhood $F_{0}$ of $\lambda$ such that $S \mid X_{T}\left(F_{0}\right)$ is continuous. We can find functions $\varphi_{1}, \varphi_{2} \in$ $\in C^{\infty}\left(R_{2}\right)$ such that $\varphi_{1}+\varphi_{2} \equiv 1, \varphi_{1} \equiv 1$ in a neighbourhood of $\lambda$ and $\operatorname{supp} \varphi_{1} \subset F_{0}$.
We shall show that there exists a closed set $F$ for which $\lambda \notin F$ and $\sigma_{S} \subset X_{T}(F)$. To prove that, take an $x \in \sigma_{s}$. Let $\left\{x_{n}\right\}$ be a sequence such that $x_{n} \rightarrow 0$ and $S x_{n} \rightarrow x$.
We have

$$
S x_{n}=S \mathscr{U}_{\varphi_{1}} x_{n}+S \mathscr{U}_{\varphi_{2}} x_{n}
$$

Since $\operatorname{supp} \varphi_{1} \subset F_{0}$, it follows that $\mathscr{U}_{\varphi_{1}} x_{n} \in X_{T}\left(F_{0}\right)$ and $S \mathscr{U}_{\varphi_{1}} x_{n} \rightarrow 0$ by the assumption that $S \mid X_{T}\left(F_{0}\right)$ is continuous. From this fact $S \mathscr{U}_{\varphi_{2}} x_{n} \rightarrow x ; x$ being a limit of elements of $X_{T}\left(\operatorname{supp} \varphi_{2}\right)$, it is an element of $X_{T}\left(\operatorname{supp} \varphi_{2}\right)$ as well.
3.4. Definition. A complex number $\lambda$ is said to be a critical eigenvalue of $T$ if $\lambda$ is an element of the point spectrum of $T$ and the range $R(\lambda I-T)$ is of infinite codimension, i.e. a Hamel basis in the quotient space $X / R(\lambda I-T)$ is not a finite set.

Consider now a $T$ having a critical eigenvalue. Then there exists a discontinuous $S$ such that $T S=S T$ and $S X_{T}(F) \subset X_{T}(F)$ for every $F$ closed. To prove this we shall apply the example given in [4], lemma 2.1.

Let $\lambda$ be a critical eigenvalue, let $y \in X$ be a corresponding eigenvector $T y=$ $=\lambda y . R(\lambda I-T)$ has not a finite codimension. Using a Hamel basis in $X / R(\lambda I-T)$ we can construct a discontinuous linear functional $f$ defined on $X$ with the property $f(x)=0$ for $x \in R(\lambda I-T)$. The linear transformation $S$ defined by the formula

$$
S x=y f(x)
$$

is obviously discontinuous and from the equality $(\lambda I-T) S=S(\lambda I-T)=0$ it follows that $S$ commutes with $T$.

According to the definition we have, for every $x, \sigma_{T}(S x) \subset \sigma_{T}(y)=\{\lambda\}$. Providing that $\lambda \in \sigma_{T}(x)$ we have $\sigma_{T}(S x) \subset \sigma_{T}(x)$. If $\lambda \notin \sigma_{T}(x)$, then there is an $x_{\lambda}$ such that $x=(\lambda I-T) x_{\lambda} \in R(\lambda I-T)$ and $S x=y . f(x)=0$ so that $\sigma_{T}(S x)=\emptyset \subset \sigma_{T}(x)$. We have obtained $\sigma_{T}(S x) \subset \sigma_{T}(x)$ for every $x \in X$ and this is obviously equivalent to $S X_{T}(F) \subset X_{T}(F)$ for $F=\bar{F}$.

Now, knowing the properties of space $X_{T}(\{\lambda\})$ in case of generalized scalar operators, we can prove the following
3.5. Theorem. Let $T$ be a generalized scalar operator in a Banach space $X$ which has no critical eigenvalue. Let $S$ be a linear transformation such that

1) $T S=S T$,
2) $S X_{T}(F) \subset X_{T}(F)$ for $F=\bar{F}$.

Then $S$ is continuous.
Proof. In the preceding lemma we showed that either $\sigma_{S}=\{0\}$ and $S$ is continuous or that there exists a $k \geqq 1$ and elements $\lambda_{1}, \ldots, \lambda_{k}$ of the point spectrum of $T$ such that $\sigma_{S} \subset X_{T}\left(\left\{\lambda_{1}, \ldots, \lambda_{k}\right\}\right)$. By 2.7 there exists a polynomial $P($.$) with P(T) \mid \sigma_{S}=0$. Denote by $q$ the quotient map from $X$ onto $X / \sigma_{s}$ and by $P(T)^{\prime}$ the corresponding operator to $P(T)$ from $X / \sigma_{S}$ into $X$ both being continuous. By the closed graph theorem we see that $q S$ is a continuous operator so that $P(T) S=P(T)^{\prime} q S$ is continuous as well.

Since each $R\left(\lambda_{i} I-T\right)(i=1,2, \ldots, k)$ has a finite codimension, it is easy to see that $P(T) X$ has also a finite codimension. In this case there exists a finite dimensional vector space $Z$ such that we can find, for each $x \in X$, a unique representation $x=$ $=x_{1}+x_{2}$ with $x_{1} \in P(T)$ and $x_{2} \in Z$. It is not difficult to prove that the maps
$R_{1} x=x_{1}, R_{2} x=x_{2}$ are continuous and the space $P(T) X$ is closed. See also [4]. Now we have

$$
S x=S R_{1} x+S R_{2} x
$$

Since $S \mid P(T) X$ and $S \mid Z$ are continuous, $S$ is a continuous operator on the whole $X$ as well.
We have obtained the above result by a slight modification of the methods in [5]. However, the assumption that $\{0\}$ is the only $T$-divisible subspace can be replaced by the assumption that all $X_{T}(F)$ are invariant with respect to $S$, which is weaker.
3.6. Definition. A subspace $Y$ is called $T$-divisible if for every complex number $\lambda$ there is $(\lambda I-T) Y=Y$.

Let $Z$ be a subspace of $X$ invariant with respect to $T$. Similarly as in [5] we denote by ${ }_{\cap}^{\infty}(\lambda \in M)(\lambda I-T) Z$ the constant value of the transfinite sequence $Z(\alpha)$ defined by

1) $Z(0)=Z$,
2) $Z(\alpha+1)=\bigcap_{\lambda \in M}(\lambda I-T) Z(\alpha)$,
3) $Z(\alpha)=\bigcap_{\beta<\alpha} Z(\beta)$ for limit ordinals.

We can always find such transfinite sequence with eventual constant value. If we put $Z=X$ and $M=\mathbf{C}$, then $\bigcap^{\infty}(\lambda \in \mathbf{C})(\lambda I-T) X$ is the largest $T$-divisible subspace in $X$. For other properties see also [5]. It is easy to see that every $\bigcap^{\infty}(\lambda \in M)(\lambda I-T) X$ is invariant with respect to any linear transformation commuting with $T$. Further, $X_{T}(F) \subset \bigcap^{\infty}(\lambda \notin F)(\lambda I-T) X$ and particularly $x \in \bigcap_{\left(\lambda \notin \sigma_{T}(x)\right)(\lambda I-T) X .}$
3.7. Proposition. Let $T$ be a generalized scalar operator for which $\{0\}$ is the only T-divisible subspace.
Then, for every closed $F$, the subspace $X_{T}(F)$ is invariant with respect to any linear transformation $S$ such that $S T=T S$.

Proof. Take an $x \in X$ and a $\varphi \in C^{\infty}\left(R_{2}\right)$ with the properties $0 \leqq \varphi \leqq 1$ and $\varphi \equiv 1$ in a neighbourhood of $\sigma_{T}(x)$. We shall show that $\mathscr{U}_{1-\varphi} S x=0$. We have

$$
x \in \bigcap^{\infty}\left(\lambda \notin \sigma_{T}(x)\right)(\lambda I-T) X .
$$

Since the subspace on the right hand side is invariant with respect to $S$, we obtain

$$
S x \in \bigcap^{\infty}\left(\lambda \notin \sigma_{T}(x)\right)(\lambda I-T) X
$$

On the other hand we can easily show that

$$
\mathscr{U}_{1-\varphi}^{-} \bigcap^{\infty}\left(\lambda \notin \sigma_{T}(x)\right)(\lambda I-T) X \subset \bigcap^{\infty}\left(\lambda \notin \sigma_{T}(x)\right)(\lambda I-T) \mathscr{U}_{1-\varphi} X .
$$

Take a $\lambda \in \sigma_{T}(x)$. By 2.5 the subspace $\mathscr{U}_{1-\varphi} X \subset X_{T}(\operatorname{supp}(1-\varphi))$ and thus the operator $(\lambda I-T)$ is one-to-one on $\mathscr{U}_{1-\varphi} X$. Let us show that $(\lambda I-T)$ maps $\mathscr{U}_{1-\varphi} X$ onto itself.

Let $x=\mathscr{U}_{1-\varphi} z$, then there is a $y \in X_{T}(\operatorname{supp}(1-\varphi))$ such that $x=(\lambda I-T) y$. Put $\psi(\lambda)=0$ and $\psi(\mu)=(1-\varphi(\mu)) /(\lambda-a(\mu))$ for $\mu \neq \lambda$, so that $\psi \in C^{\infty}\left(R_{2}\right)$. Denote $u=\mathscr{U}_{\psi} z-y$. Since

$$
(\lambda I-T) u=\mathscr{U}_{1-\varphi} z-(\lambda I-T) y=0
$$

it is $\sigma_{T}(u) \subset\{\lambda\}$. On the other hand $\sigma_{T}(y) \subset \operatorname{supp}(1-\varphi), \sigma_{T}\left(\mathscr{U}_{\psi} z\right) \subset \operatorname{supp}(\psi)=$ $=\operatorname{supp}(1-\varphi)$ and thus $\sigma_{T}(u) \subset \operatorname{supp}(1-\varphi)$. But $\sigma_{T}(u) \subset \operatorname{supp}(1-\varphi) \cap$ $\cap\{\lambda\}=\emptyset$ and $u=0$. We have obtained $y=\mathscr{U}_{\psi} z$. Let $\varphi_{0} \in C^{\infty}\left(R_{2}\right), \varphi_{0} \equiv 1$ in a neighbourhood of $\sigma_{T}(y)$ such that $\operatorname{supp} \varphi_{0} \cap \sigma_{T}(x)=\emptyset$. Then $y=\mathscr{U}_{\varphi_{0}} y=$ $=\mathscr{U}_{1-\varphi} \mathscr{U}_{\varphi_{0} /(\lambda-a)} z \in \mathscr{U}_{1-\varphi} X$.

So we can write

$$
\bigcap_{\bigcap}^{\infty}\left(\lambda \notin \sigma_{T}(x)\right)(\lambda I-T) \mathscr{U}_{1-\varphi} X=\bigcap^{\infty}(\lambda \in \mathbf{C})(\lambda I-T) \mathscr{U}_{1-\varphi} X .
$$

Since $\{0\}$ is the only $T$-divisible subspace, we have $\mathscr{U}_{1-\varphi} S x=0$ and $S x=$ $=\mathscr{U}_{1-\varphi} S x+\mathscr{U}_{\varphi} S x=\mathscr{U}_{\varphi} S x \in X_{T}(\operatorname{supp} \varphi)$ for every $\varphi \in C^{\infty}\left(R_{2}\right)$ such that $\varphi \equiv 1$ in a neighbourhood of $\sigma_{T}(x)$. From this fact it follows obviously $\sigma_{T}(S x) \subset \sigma_{T}(x)$.

Open problem: Is there a generalized scalar operator or a spectral operator of the finite type having a non-trivial divisible subspace? ${ }^{1}$ )

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[^0]:    ${ }^{1}$ ) The problem was solved by the author and the results will be published.

