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# ON THE EXISTENCE OF PERIODIC BOUNDARY CONDITIONS FOR CERTAIN NONLINEAR VECTOR DIFFERENTIAL EQUATIONS 

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In [5], B. Mehri uses a special case of a theorem about contractions given in [3] (which, due to the finiteness of distance functions considered in [5], is in fact the usual theorem about contractions; see, e.g. [6]), and a result reported by D̆URIKovič [1], to establish the existence and uniqueness of solution of the nonlinear differential equation $x^{\prime \prime}+K x=f\left(t, x, x^{\prime}\right)$, satisfying the periodic boundary conditions $x(0)-$ $-x(\omega)=x^{\prime}(0)-x^{\prime}(\omega)=0$. Although Mehri's Theorem 1 covers both cases $K>0$ and $K<0$, his Theorems 2 and 3 are restricted only to the case $K>0$.

In this note, we first extend all the results in [5] to a system of nonlinear second order differential equations. Then we establish two theorems whose scalar cases give analogues of Theorems 2 and 3 of [5] for the case $K<0$.

Consider the vector boundary value problem

$$
\begin{equation*}
x^{\prime \prime}+A x=f\left(t, x, x^{\prime}\right), \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
x(0)-x(\omega)=x^{\prime}(0)-x^{\prime}(\omega)=0 \tag{2}
\end{equation*}
$$

where $x=\left(x_{1}, \ldots, x_{n}\right)$ is an $n$-dimensional vector; $A$ is a constant diagonal $n \times n$ matrix; and $f(t, x, y)=\left(f_{1}\left(t, x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{n}\right), \ldots, f_{n}\left(t, x_{1}, \ldots, x_{n}, y_{1}, \ldots, y_{n}\right)\right)$ is a vector valued function, defined for $(t, x, y) \in E=[0, \omega] \times R^{n} \times R^{n}$.

Throughout this paper, we take $\|x\|=\underset{i}{\operatorname{Max}}\left|x_{i}\right|$ and $\|A\|=\underset{i, k}{\operatorname{Max}}\left|a_{i k}\right|$ respectively as the norm of $x=\left(x_{1}, \ldots, x_{n}\right)$ and of $A={ }^{i}\left(a_{i k}\right)$.

Theorem 1. Suppose that the matrix $A=\left(a_{i} \delta_{i k}\right)_{1}^{n}\left(\delta_{i k}\right.$ is the Kronecker delta) is such that all the $a_{i}$ are nonzero and have the same sign. Suppose further that the vector function $f(t, x, y)$ is continuous, bounded in $E$ and satisfies the inequality

$$
\begin{equation*}
\left\|f\left(t, x_{1}, y_{1}\right)-f\left(t, x_{2}, y_{2}\right)\right\| \leqq C\left\{\left\|x_{1}-x_{2}\right\|+1 / b\left\|y_{1}-y_{2}\right\|\right\}, \tag{3}
\end{equation*}
$$

where $b=\operatorname{Min}_{i} \sqrt{ }\left|a_{i}\right|, C>0$ is a constant such that

$$
\begin{equation*}
\frac{2 C}{b^{2}}<1 \tag{4}
\end{equation*}
$$

Then in $[0, \omega] \subseteq[0, \pi / a]$, where $a=\operatorname{Max}_{i} \sqrt{ } a_{i}$ if

$$
\begin{equation*}
a_{i}>0, \quad i=1, \ldots, n \tag{5}
\end{equation*}
$$

and in $[0, \omega] \subseteq[0,+\infty)$, if

$$
\begin{equation*}
a_{i}<0, \quad i=1, \ldots, n \tag{6}
\end{equation*}
$$

the problem (1) (2) has a unique solution. Moreover, Picard's sequence of successive approximations defined by

$$
\begin{equation*}
x_{n}(t)=\int_{0}^{\omega} G(t, s) f\left(s, x_{n-1}(s), x_{n-1}^{\prime}(s)\right) \mathrm{d} s, \quad n=1,2, \ldots \tag{7}
\end{equation*}
$$

(where $G(t, s)$ is Green's matrix for the problem (1), (2)) for any vector function $x_{0}(t)$ specified below, converges in distance to this unique solution.

Proof. If (5) holds, then problem (1), (2) is equivalent to the integral equation

$$
\begin{equation*}
x(t)=\int_{0}^{\omega} G(t, s) f\left(t, x(s), x^{\prime}(s)\right) \mathrm{d} s \tag{8}
\end{equation*}
$$

where $G(t, s)$ is Green's matrix for the problem (1), (2),

$$
G(t, s)=\left\{\begin{array}{l}
2^{-1}(\sqrt{ } A)^{-1}\left[\operatorname{Sin} \sqrt{ }(A) \frac{\omega}{2}\right]^{-1} \operatorname{Cos} \sqrt{ }(A)\left(\frac{\omega}{2}+s-t\right) \text { for }  \tag{9}\\
0 \leqq s \leqq t \leqq \omega \\
2^{-1}(\sqrt{ } A)^{-1}\left[\operatorname{Sin} \sqrt{ }(A) \frac{\omega}{2}\right]^{-1} \operatorname{Cos} \sqrt{ }(A)\left(\frac{\omega}{2}+t-s\right) \text { for } \\
0 \leqq t \leqq s \leqq \omega
\end{array}\right.
$$

and the matrix functions $\operatorname{Sin} \sqrt{ }(A) t$ and $\operatorname{Cos} \sqrt{ }(A) t$ are defined by the matrix series ([2], p. 118),

$$
\begin{aligned}
& \operatorname{Sin} \sqrt{ }(A) t=\sum_{p=0}^{\infty}(-1)^{p} \frac{(\sqrt{ } A)^{2 p+1}}{(2 p+1)!} t^{2 p+1} \\
& \operatorname{Cos} \sqrt{ }(A) t=\sum_{p=0}^{\infty}(-1)^{p} \frac{(\sqrt{ } A)^{2 p}}{(2 p)!} t^{2 p}
\end{aligned}
$$

If (6) holds, then problem (1), (2) is equivalent to (8) where

$$
G(t, s)=\left\{\begin{align*}
2^{-1}(\sqrt{ }|A|)^{-1}[E-\exp \sqrt{ }|A| \omega]^{-1} & \{\exp [-\sqrt{ }|A|(t-s)] \exp (\sqrt{ }|A| \omega)  \tag{10}\\
& +\exp [\sqrt{ }|A|(t-s)]\} \text { for } s \leqq t \\
2^{-1}(\sqrt{ }|A|)^{-1}[E-\exp \sqrt{ }|A| \omega]^{-1} & \{\exp [-\sqrt{ }|A|(s-t)] \exp (\sqrt{ }|A| \omega) \\
& +\exp [\sqrt{ }|A|(s-t)]\} \text { for } t \leqq s
\end{align*}\right.
$$

and the matrix functions $\exp [\sqrt{ }|A| t]$ and $\exp [-\sqrt{ }|A| t]$ are defined by the matrix series

$$
\exp [\sqrt{ }|A| t]=\sum_{p=0}^{\infty} \frac{(\sqrt{ }|A|)^{p}}{p!} t^{p}, \quad \exp [-\sqrt{ }|A| t]=\sum_{p=0}^{\infty}(-1)^{p} \frac{(\sqrt{ }|A|)^{p}}{p!} t^{p}
$$

Let $S$ be the set of all continuous vector functions $x(t)=\left(x_{1}(t), \ldots, x_{n}(t)\right)$ with continuous first derivatives $x^{\prime}(t)=\left(x_{1}^{\prime}(t), \ldots, x_{n}^{\prime}(t)\right)$ on $[0, \omega]$, and define the distance

$$
\begin{equation*}
d\left(x_{1}, x_{2}\right)=\operatorname{Max}_{t \in[0, \omega]}\left\{\left\|x_{1}(t)-x_{2}(t)\right\|+\frac{1}{b}\left\|x_{1}^{\prime}(t)-x_{2}^{\prime}(t)\right\|\right\} \tag{11}
\end{equation*}
$$

for an arbitrary pair of elements $x_{1}(t), x_{2}(t)$ of $S$. Then $X=(S, d)$ is a complete metric space. We define an operator $U$ on $X$ by

$$
\begin{equation*}
U x(t)=\int_{0}^{\omega} G(t, s) f\left(s, x(s), x^{\prime}(s)\right) \mathrm{d} s \tag{12}
\end{equation*}
$$

The operator $U$ maps the space $X$ into itself.
Let $x_{1}(t), x_{2}(t)$ be any two elements from $X$, then

$$
\left\|U x_{1}(t)-U x_{2}(t)\right\| \leqq C d\left(x_{1}, x_{2}\right) \operatorname{Max}_{i} \frac{1}{\left|a_{i}\right|} \leqq \frac{C}{b^{2}} d\left(x_{1}, x_{2}\right),
$$

and

$$
\frac{1}{b}\left\|\frac{\mathrm{~d}}{\mathrm{~d} t} U x_{1}(t)-\frac{\mathrm{d}}{\mathrm{~d} t} U x_{2}(t)\right\| \leqq \frac{C}{b} d\left(x_{1}, x_{2}\right) \operatorname{Max}_{i} \frac{1}{\sqrt{ }\left|a_{i}\right|} \leqq \frac{C}{b^{2}} d\left(x_{1}, x_{2}\right)
$$

Hence

$$
d\left(U x_{1}, U x_{2}\right) \leqq \frac{2 C}{b^{2}} d\left(x_{1}, x_{2}\right)
$$

Now (4) and the fact that any two elements of $X$ have a finite distance, complete the proof of the theorem.

In the following two theorems we shall assume that (5) holds. Since $\omega \in[0, \pi / a]$, it follows that $\sqrt{ }\left(a_{i}\right)(\omega / 2) \in[0, \pi / 2]$ for each $i$, and hence $\operatorname{Sin} \sqrt{ }\left(a_{i}\right)(\omega / 2) \geqq$ $\geqq(2 / \pi) \sqrt{ }\left(a_{i}\right)(\omega / 2)$ for each $i$ involving

$$
\|G(t, s)\| \leqq \frac{\pi}{2 b^{2} \omega}, \quad\left\|G_{t}(t, s)\right\| \leqq \frac{\pi}{2 b \omega} .
$$

Let $S$ and $U$ be as before, then $U S \subseteq S$. Let $\left(S^{*}, d\right)$ be the completion of $(U S, d)$ where $d$ is given by (11).

Theorem 2. Let $f(t, x, y)$ be a vector function defined and continuous on $E$, and satisfying the following conditions

$$
\begin{equation*}
\|f(t, x, y)\| \leqq \frac{b^{2}}{2 \pi} t^{p}, \quad p \geqq 0, \quad(t, x, y) \in E \tag{13}
\end{equation*}
$$

$$
\begin{equation*}
\left\|f\left(t, x_{1}, y_{1}\right)-f\left(t, x_{2}, y_{2}\right)\right\| \leqq \frac{b^{2}}{\pi t^{r}}\left\{\left\|x_{1}-x_{2}\right\|^{q}+\left[\frac{1}{b}\left\|y_{1}-y_{2}\right\|^{q}\right\}\right. \tag{14}
\end{equation*}
$$

for $\left(t, x_{i}, y_{i}\right) \in E, i=1,2$, where $q \geqq 1,0<r<1, r=p(q-1)$ and

$$
\frac{1}{(1-r)}\left(\frac{1}{p+1}\right)^{q-1}<1
$$

Then problem (1), (2) has a unique solution $x(t) \in S^{*}$, and the successive approximations defined by (7) for any $x_{0}(t) \in S$, converge in distance to this unique solution.

Proof. The space $X=\left(S^{*}, d\right)$ is a complete metric space, and $U$, defined by (12), maps $X$ into itself. Let $z_{1}(t), z_{2}(t)$ be any two elements of $X$, then from (12) and (13)

$$
\left\|z_{1}(t)-z_{2}(t)\right\| \leqq \frac{b^{2}}{\pi} \int_{0}^{\omega}\|G(t, s)\| s^{p} \mathrm{~d} s \leqq \frac{1}{2(p+1)} \omega^{p}
$$

and

$$
\frac{1}{b}\left\|z_{1}^{\prime}(t)-z_{2}^{\prime}(t)\right\| \leqq \frac{b^{2}}{\pi b} \int_{0}^{\omega}\left\|G_{t}(t, s)\right\| s^{p} \mathrm{~d} s \leqq \frac{1}{2(p+1)} \omega^{p} .
$$

From (14) and (11) we obtain

$$
\begin{aligned}
\left\|U z_{1}(t)-U z_{2}(t)\right\| & \leqq \frac{b^{2}}{\pi}\left(\frac{\omega^{p}}{p+1}\right)^{q-1} \cdot \frac{\pi}{2 b^{2} \omega} \cdot \frac{d\left(z_{1}, z_{2}\right)}{(1-r)} \omega^{1-r} \leqq \\
& \leqq \frac{1}{2} \cdot \frac{1}{(p+1)^{q-1}} \cdot \frac{d\left(z_{1}, z_{2}\right)}{(1-r)}
\end{aligned}
$$

and

$$
\frac{1}{b}\left\|\frac{\mathrm{~d}}{\mathrm{~d} t} U z_{1}(t)-\frac{\mathrm{d}}{\mathrm{~d} t} U z_{2}(t)\right\| \leqq \frac{1}{2} \cdot \frac{1}{(p+1)^{q-1}} \cdot \frac{d\left(z_{1}, z_{2}\right)}{(1-r)} .
$$

From the last two inequalities, it follows that

$$
\cdot d\left(U z_{1}, U z_{2}\right) \leqq \frac{1}{(p+1)^{q-1}} \cdot \frac{1}{1-r} d\left(z_{1}, z_{2}\right)
$$

which completes the proof.
Remark. In Theorem 2 it is assumed that $f(t, x, y)$ is bounded on $E$. The following theorem (whose proof is similar to that of Theorem 2) shows that this assumption is not necessary.

Theorem 3. Let $f(t, x, y)$ be continuous on E and satisfy the following conditions

$$
\begin{gather*}
\|f(t, x, y)\| \leqq \frac{b^{2}}{2 \pi} t^{-p}, \quad 0<p<1, \quad(t, x, y) \in E  \tag{15}\\
\left\|f\left(t, x_{1}, y_{1}\right)-f\left(t, x_{2}, y_{2}\right)\right\| \leqq \frac{b^{2}}{\pi} t^{p(q-1)}\left\{\left\|x_{1}-x_{2}\right\|^{q}+\left[\frac{1}{b}\left\|y_{1}-y_{2}\right\|^{q}\right\}\right. \tag{16}
\end{gather*}
$$

where $q \geqq 1$ and

$$
\left(\frac{1}{1-p}\right)^{q-1} \cdot \frac{1}{p(q-1)+1}<1
$$

Then problem (1), (2) has a unique solution, and the successive approximations defined by (7) for any $x_{0}(t) \in S$, converge in distance to this unique solution.

In the following two theorems we shall assume that (6) holds. Then we have

$$
\|G(t, s)\| \leqq \frac{2+b \omega}{2 b^{2} \omega}, \quad\left\|G_{t}(t, s)\right\| \leqq \frac{2+b \omega}{2 b \omega} .
$$

Theorem 4. Let $f(t, x, y)$ be continuous on $E$, and let $C>0$ be a constant such that

$$
\begin{equation*}
\|f(t, x, y)\| \leqq \frac{b^{2} C}{2} t^{p}, \quad p \geqq 0, \quad(t, x, y) \in E \tag{17}
\end{equation*}
$$

$$
\begin{equation*}
\left\|f\left(t, x_{1}, y_{1}\right)-f\left(t, x_{2}, y_{2}\right)\right\| \leqq \frac{b^{2} C}{t^{r}}\left\{\left\|x_{1}-x_{2}\right\|^{q}+\left[\frac{1}{b}\left\|y_{1}-y_{2}\right\|\right]^{q}\right\} \tag{18}
\end{equation*}
$$

where $q \geqq 1,0<r<1, r=p(q-1)$ and

$$
\begin{equation*}
2 C\left(\frac{1}{1-r}\right)^{1 / q}\left(\frac{1}{p+1}\right)^{q-1 / q}<1 \tag{19}
\end{equation*}
$$

Then there exists an $\omega_{0}>0$ such that for every $\omega, 0<\omega \leqq \omega_{0}$, (1), (2) has a unique solution $x(t) \in S^{*}$, and the successive approximations defined by (7) for any $x_{0}(t) \in S$, converge in distance to this unique solution.

Proof. Let $X=\left(S^{*}, d\right)$, and let $z_{1}(t), z_{2}(t)$ be any two elements of $X$, then from (12) and (17)

$$
\left\|z_{1}(t)-z_{2}(t)\right\| \leqq b^{2} C \int_{0}^{\omega}\|G(t, s)\| s^{p} \mathrm{~d} s \leqq \frac{C(2+b \omega) \omega^{p}}{2(p+1)}
$$

and

$$
\frac{1}{b}\left\|z_{1}^{\prime}(t)-z_{2}^{\prime}(t)\right\| \leqq \frac{b^{2} C}{b} \int_{0}^{\omega}\left\|G_{t}(t, s)\right\| s^{p} \mathrm{~d} s \leqq \frac{C(2+b \omega) \omega^{p}}{2(p+1)}
$$

From (18) and (11), it follows that

$$
\begin{aligned}
\left\|U z_{1}(t)-U z_{2}(t)\right\| & \leqq b^{2} C \cdot\left(\frac{C(2+b \omega) \omega^{p}}{p+1}\right)^{q-1} \cdot \frac{2+b \omega}{2 b^{2} \omega} \cdot \frac{d\left(z_{1}, z_{2}\right)}{1-r} \omega^{1-r} \leqq \\
& \leqq \frac{1}{2} \cdot \frac{(C(2+b \omega))^{q}}{(p+1)^{q-1}} \cdot \frac{1}{1-r} d\left(z_{1}, z_{2}\right)
\end{aligned}
$$

and

$$
\frac{1}{b}\left\|\frac{\mathrm{~d}}{\mathrm{~d} t} U z_{1}(t)-\frac{\mathrm{d}}{\mathrm{~d} t} U z_{2}(t)\right\| \leqq \frac{1}{2} \cdot \frac{(C(2+b \omega))^{q}}{(p+1)^{q-1}} \cdot \frac{1}{1-r} d\left(z_{1}, z_{2}\right)
$$

From the last two inequalities we obtain

$$
d\left(U z_{1}, U z_{2}\right) \leqq \frac{(C(2+b \omega))^{q}}{(p+1)^{q-1}} \cdot \frac{1}{1-r} d\left(z_{1}, z_{2}\right) .
$$

$U$ is a contraction map provided that

$$
\begin{equation*}
\frac{(C(2+b \omega))^{q}}{(p+1)^{q-1}} \cdot \frac{1}{1-r}<1 \tag{20}
\end{equation*}
$$

Clearly (20) is satisfied if

$$
\begin{equation*}
\omega<\frac{1}{b}\left\{\frac{1}{C}(p+1)^{q-1 / q}(1-r)^{1 / q}-2 .\right. \tag{21}
\end{equation*}
$$

Therefore, if $\omega>0$ is chosen so that (21) is satisfied, then problem (1), (2) has a unique solution with the desired property.

Theorem 5. Let $f(t, x, y)$ be continuous on $E$, and let $C>0$ be a constant such that
(22) $\quad\|f(t, x, y)\| \leqq \frac{b^{2} C}{2} t^{-p}, \quad 0<p<1, \quad(t, x, y) \in E$,
(23) $\left\|f\left(t, x_{1}, y_{1}\right)-f\left(t . x_{2}, y_{2}\right)\right\| \leqq b^{2} C t^{p(q-1)}\left\{\left\{\left\|x_{1}-x_{2}\right\|^{q}+\left[\frac{1}{b}\left\|y_{1}-y_{2}\right\|\right]^{q}\right\}\right.$
where $q \geqq 1$, and

$$
\begin{equation*}
2 C\left(\frac{1}{1-p}\right)^{q-1 / q}\left(\frac{1}{p(q-1)+1}\right)^{1 / q}<1 \tag{24}
\end{equation*}
$$

Then there exists an $\omega_{0}>0$ such that for every $\omega, 0<\omega \leqq \omega_{0}$, (1), (2) has a unique solution, and the successive approximations defined by (7) for any $x_{0}(t) \in S$, converge in distance to this unique solution.
Proof. Let $X=\left(S^{*}, d\right)$ and let $z_{1}(t)$ and $z_{2}(t)$ be any two elements in $X$, then

$$
\begin{aligned}
\left\|z_{1}(t)-z_{2}(t)\right\| & \frac{C(2+b \omega) \omega^{-p}}{2(1-p)} \\
\frac{1}{b}\left\|z_{1}^{\prime}(t)-z_{2}^{\prime}(t)\right\| & \leqq \frac{C(2+b \omega) \omega^{-p}}{2(1-p)}
\end{aligned}
$$

From (23) we obtain

$$
d\left(U z_{1}, U z_{2}\right) \leqq \frac{(C(2+b \omega))^{q}}{(1-p)^{q-1}} \cdot \frac{1}{p(q-1)+1} d\left(z_{1}, z_{2}\right)
$$

Again $U$ is a contraction map if

$$
\begin{equation*}
\omega<\frac{1}{b}\left\{\frac{1}{C}(1-p)^{q-1 / q}(p(q-1)+1)^{1 / q}-2\right\} \tag{25}
\end{equation*}
$$

Therefore, if $\omega>0$ is chosen so that (25) is satisfied, then problem (1), (2) has a unique solution with the desired property.

Remarks. (a) In case that equation (1) is a scalar equation, Theorems 4 and 5 are analogues of Theorems 2 and 3 of [5] for the case $K<0$. (b) In [5], Mehri defines four distance functions which are equivalent in the sense that if $S^{*}$ is complete with respect to one of them, it is also complete with respect to the three others, and the factors $1 /\left[\left.K\right|^{p}, 1 / \omega^{p}\right.$ or $1 / \omega^{-p}$ do not contribute anything as far as the proofs of theorems in [5] are concerned.

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