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Commentationes Mathematicae Universitatis Carolinae, Vol. 36 (1995), No. 2, 395--400

Persistent URL: http://dml.cz/dmlcz/118765

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# Linear transforms supporting circular convolution over a commutative ring with identity

#### M.M. Nessibi

Abstract. We consider a commutative ring R with identity and a positive integer N. We characterize all the 3-tuples  $(L_1, L_2, L_3)$  of linear transforms over  $\mathbb{R}^N$ , having the "circular convolution" property, i.e. such that  $x * y = L_3(L_1(x) \otimes L_2(y))$  for all  $x, y \in \mathbb{R}^N$ .

Keywords: circular convolution property Classification: 15A04

#### 1. Introduction

Let R be a commutative ring with identity, N a positive integer and  $A = (a_{ij})$  $(0 \le i, j \le N - 1)$  a square matrix of order N over R. The linear transform  $L_A: R^N \to R^N$  defined by

$$L_A(x_0, x_1, \cdots, x_{N-1}) = (y_0, y_1, \cdots, y_{N-1}),$$

where  $y_k = a_{k0}x_0 + a_{k1}x_1 + \dots + a_{kN-1}x_{N-1}$   $(0 \le k \le N-1)$  is the linear transform over  $\mathbb{R}^N$  with matrix A.

For the case R being the field  $\mathbb{C}$  of complex numbers and  $A = (a_{kl})$  the square matrix defined by

$$a_{kl} = (e^{-2i\pi \frac{kl}{N}}) \quad (0 \le k, l \le N-1),$$

the linear transform  $L_A$  is the discrete Fourier transform D. This transform is often used to compute the circular convolution product of two elements  $x = (x_0, x_1, \dots, x_{N-1})$  and  $y = (y_0, y_1, \dots, y_{N-1})$  of  $\mathbb{C}^N$  as follows:

(1) 
$$x * y = D^{-1}(D(x) \otimes D(y)),$$

where  $D^{-1} = (\frac{1}{N}e^{+2i\pi\frac{kl}{N}})$  is the inverse discrete Fourier transform and

(2) 
$$x \otimes y = (x_0 y_0, x_1 y_1, \cdots, x_{N-1} y_{N-1}),$$

(3) 
$$x * y = (z_0, z_1, \cdots, z_{N-1}),$$

where  $z_k = \sum_{j=0}^{N-1} x_j y_{k-j}$   $(0 \le k \le N-1)$  and  $y_{k-j} = y_m$  for the integer *m* such that  $m \equiv k-j \pmod{N}$  and  $0 \le m \le N-1$ . The discrete Fourier transform plays

a key role in physics because it can be used as a mathematical tool to describe the relationship between the time domain and frequency domain representation of a discrete signal (see [5, p. 211]). In this paper, we characterize all 3-tuples  $(L_1, L_2, L_3)$  of linear transforms over  $\mathbb{R}^N$ , having the "circular convolution" property, i.e. such that  $x * y = L_3(L_1(x) \otimes L_2(y))$  for all  $x, y \in \mathbb{R}^N$ , where \* and  $\otimes$  are defined as in (2) and (3).

This question for an integral domain and for the case N = 2 was completely solved by L. Skula in [3]. For the case  $N \ge 3$ , L. Skula gave in [3] a sufficient condition for linear transforms over a commutative ring with identity to have the "circular convolution" property. The converse direction (necessary condition) was established by P. Cikánek ([1, p. 74]). This gives another characterization of the linear transforms supporting circular convolution over a commutative ring R with identity.

In this work, by applying Theorem 2.2 we characterize all linear transforms supporting circular convolution over a residue class ring  $\mathbb{Z}/m\mathbb{Z}$  for any integer  $m \geq 2$ .

In [4], L. Skula, by means of *p*-adic integers, described all linear transforms supporting circular convolution over a residue class ring  $\mathbb{Z}/m\mathbb{Z}$ , for any integer  $m \geq 2$ .

# 2. Characterization of linear transforms supporting circular convolution over *R*.

**Definition 2.1.** Let  $A = (a_{kl})$ ,  $B = (b_{kl})$  and  $C = (c_{kl})$   $(0 \le k, l \le N-1)$  be square matrices over the ring R. We say that the matrices A, B, C support circular convolution or briefly are SCC-matrices if for each u, v and w in  $\{0, 1, \dots, N-1\}$  the following relation holds:

 $\sum_{k=0}^{N-1} a_{ku} b_{kv} c_{kw} = \begin{cases} 1 & \text{for } u+v \equiv w \pmod{N} \\ 0 & \text{otherwise.} \end{cases}$ 

**Theorem 2.1.** The matrices A, B, C support circular convolution if and only if the 3-tuple  $(L_A, L_B, L_{C^*})$  supports circular convolution, where  $C^* = (c_{kl}^*)$  is the square matrix of order N over R defined by

$$c_{kl}^* = c_{lj} \quad (0 \le k, l \le N - 1)$$

with  $0 \le j \le N - 1$  and  $j \equiv -k \pmod{N}$ . (See [3, p. 12–14]).

**Proposition 2.1.** Let A, B, C be SCC-matrices over R. Then the determinants of A, B, C are not zero-divisors in R.

**Corollary 2.1.** Let A, B, C be SCC-matrices over R. We suppose that each non zero-divisor element of R is invertible. Then for each k  $(0 \le k \le N-1)$  there exists  $g_k \in R$  such that

- (1)  $g_k^N = 1$ .
- (1)  $g_k^{(1)} = g_k^u a_{k0}, b_{ku} = g_k^u b_{k0}, c_{ku} = g_k^u c_{k0}$  for each  $u \in \{0, \dots, N-1\}$ . (3) For each  $i, j \in \{0, \dots, N-1\}$  such that  $i \neq j, g_i g_j$  is not a zero-divisor in R.

**Corollary 2.2.** If N.1 is invertible in R and if there exist  $g_0, \dots, g_{N-1} \in R$  such that

(1)  $g_k^{N} = 1$  for each  $k \in \{0, \dots, N-1\}$ . (2) $\sum_{k=0}^{\mathbf{N}-1} g_k^m = \begin{cases} \mathbf{N} & \text{ for } m \equiv 0 \pmod{\mathbf{N}}, \\ \mathbf{0} & \text{ otherwise.} \end{cases}$ 

Then for each  $i, j \in \{0, \dots, N-1\}$  such that  $i \neq j$ ,  $(g_i - g_j)$  is not a zero-divisor in R.

**Proposition 2.2.** Let  $g_0, \dots, g_{N-1} \in R$  satisfying

- (1)  $g_k^N = 1$  for each  $k \in \{0, \dots, N-1\}$ . (2)  $g_i g_j$  is not a zero-divisor in R for each  $i, j \in \{0, \dots, N-1\}$  such that  $i \neq j$ .

Then we have

$$g_0 g_1 \cdots g_{N-1} = (-1)^{N-1}$$

PROOF: We denote by  $D(g_0, \dots, g_{N-1})$  the Vandermonde determinant defined as follows: 1 4 N - 1

$$D(g_0, \cdots, g_{N-1}) = \begin{vmatrix} 1 & g_0 & \cdots & g_0^{N-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & g_{N-1} & \cdots & g_{N-1}^{N-1} \end{vmatrix}.$$

Using the assertion (1) we obtain

$$D(g_0, \cdots, g_{N-1}) = \begin{vmatrix} g_0 & \cdots & g_0^{N-1} & g_0^N \\ \vdots & \ddots & \vdots & \vdots \\ g_{N-1} & \cdots & g_{N-1}^{N-1} & g_{N-1}^N \end{vmatrix}.$$

We deduce that

$$D(g_0, \cdots, g_{N-1}) = (-1)^{N-1} g_0 g_1 \cdots g_{N-1} D(g_0, \cdots, g_{N-1}).$$

The result follows from the last relation, the assertion (2) and the following equality:

$$D(g_0, \cdots, g_{N-1}) = \prod_{0 \le i < j \le N-1} (g_i - g_j).$$

 $\square$ 

**Corollary 2.3.** Under the same hypothesis as in Proposition 2.2 we have

- (1)  $D(g_0, \dots, g_{N-1}) = Ng_r^s D_{rs}^*$   $(0 \le r, s \le N-1)$ , where  $D_{rs}^*$  means the cofactor of the  $r^{th}$  row and the  $s^{th}$  column of the determinant D. (2)
  - $\sum_{k=0}^{\mathbf{N}-1} g_k^m = \begin{cases} \mathbf{N} & \text{if } m \equiv 0 \pmod{\mathbf{N}}, \\ 0 & \text{otherwise.} \end{cases}$

Using Corollaries 2.1–2.3 and considering the total quotient ring of R (see [6, p. 221) we deduce the following theorem:

**Theorem 2.2.** Let A, B, C be square matrices of order N over R. Then the following statements are equivalent:

- (1) The matrices A, B, C support circular convolution.
- (2)  $N a_{k0} b_{k0} c_{k0} = 1 \ (0 \le k \le N-1)$  and there exist  $g_0, \dots, g_{N-1}$  in R satisfying

  - (i)  $g_k^N = 1$  for  $k \in \{0, \dots, N-1\}$ . (ii)  $a_{ku} = g_k^u a_{k0}, b_{ku} = g_k^u b_{k0}, c_{ku} = g_k^u c_{k0} \quad (0 \le k, u \le N-1)$ . (iii) For each i, j in  $\{0, \dots, N-1\}$  such that  $i \ne j, (g_i g_j)$  is not a zero-divisor in R.

**Remark.** For the case R being an integer domain, the condition (2) (iii) of Theorem 2.2 becomes  $g_i \neq g_j$  for  $i \neq j$  and we find the result of L. Skula [3, p. 20].

**Theorem 2.3.** Let  $T = (t_{ij}) \ (0 \le i, j \le N - 1)$  be an invertible square matrix of order N over R. Then the following statements are equivalent:

- (1) The matrices  $T, T^{-1}$  support circular convolution.
- (2) N.1 is invertible in R and there exist  $g_0, \dots, g_{N-1}$  in R such that
  - (i)  $g_k^N = 1$  for  $k \in \{0, \cdots, N-1\}$ .

  - (ii)  $t_{ku} = g_k^u$   $(0 \le k, u \le N-1)$ . (iii)  $(g_i g_j)$  is not a zero-divisor in R for each i, j in  $\{0, \dots, N-1\}$  such that  $i \neq j$ .

Furthermore,  $T^{-1} = (T_{ij}) \ (0 \le i, j \le N-1)$  with  $T_{ij} = (N.1)^{-1} g_i^{-i} \quad (0 \le i, j \le N-1).$ 

### 3. Matrices supporting circular convolution over a residue class ring $\mathbb{Z}/m\mathbb{Z}$ , *m* integer $\geq 2$

First we suppose that  $m = p^n$ , where n is a positive integer and p is a prime. In [3], [4] L. Skula showed that there exist SCC-matrices A, B, C of order N over the ring  $\mathbb{Z}/p^n\mathbb{Z}$  if and only if N divides p-1. In [4] he described all the linear transforms supporting circular convolution over  $\mathbb{Z}/p^n \mathbb{Z}$  by means of p-adic integers.

Using another method we give in this section another characterization of all the linear transforms supporting circular convolution over  $\mathbb{Z}/p^n \mathbb{Z}$ .

**Theorem 3.1.** We suppose that N divides (p-1). Let A, B, C be square matrices of order N over  $\mathbb{Z}/p^n \mathbb{Z}$ . The following statements are equivalent:

- (1) The matrices A, B, C support circular convolution.
- (2)  $Na_{k0}b_{k0}c_{k0} = 1$  for  $k \in \{0, \dots, N-1\}$  and  $a_{ku} = g_k^u a_{k0}, b_{ku} = g_k^u b_{k0}$ ,  $c_{ku} = g_k^u c_{k0} \ (0 \le k, u \le N-1),$  where

$$\{g_0, \cdots, g_{N-1}\} = \{\alpha \in (\mathbb{Z}/p^n \mathbb{Z}) \mid \alpha^N = 1\}.$$

**PROOF:** By using the fact that the multiplicative group  $(\mathbb{Z}/p^n \mathbb{Z})^*$  is cyclic (see [2, p. 55–58]) and by applying the Hensel's lemma (see [2, p. 169]) we deduce that if N divides p-1 we have the two following results:

- The set  $H_n = \{x \in \mathbb{Z}/p^n \mathbb{Z} \mid x^N = 1\}$  contains exactly N elements.
- For each  $x, y \in H_n$  such that  $x \neq y, x y$  is not a zero-divisor in  $\mathbb{Z}/p^n \mathbb{Z}$ .

The result follows from these properties together with Theorem 2.2.

For general integer m;  $m \ge 2$  we write  $m = p_1^{\alpha_1} \cdots p_r^{\alpha_r}$ , where  $\alpha_1, \cdots, \alpha_r$  are positive integers and  $p_i$   $(1 \le i \le r)$  are primes such that  $p_i \ne p_j$  for  $i \ne j$ . Hence we have

 $\mathbb{Z}/m\mathbb{Z}\simeq(\mathbb{Z}/p_1^{\alpha_1}\mathbb{Z})\otimes\cdots\otimes(\mathbb{Z}/p_r^{\alpha_r}\mathbb{Z}).$ 

We denote by  $\Pi_i$   $(1 \le i \le r)$  the canonical homomorphism from the ring  $\mathbb{Z}/m\mathbb{Z}$ onto the ring  $(\mathbb{Z}/p_i^{\alpha_i}\mathbb{Z})$ .

By using Theorem 3.1 and Proposition 2.6 in [3, p. 14] we deduce the following theorem:

**Theorem 3.2.** Let A, B, C be square matrices of order N over  $\mathbb{Z}/m\mathbb{Z}$ . The following statements are equivalent:

- (1) The matrices A, B, C support circular convolution.
- (2)  $N a_{k0} b_{k0} c_{k0} = 1 \ (0 \le k \le N-1)$  and there exist  $g_0, \dots, g_{N-1} \in (\mathbb{Z}/m\mathbb{Z})$ such that

  - (i)  $g_k^{N} = 1$  for  $k \in \{0, \dots, N-1\}$ . (ii)  $a_{ku} = g_k^u a_{k0}, b_{ku} = g_k^u b_{k0}, c_{ku} = g_k^u c_{k0} \ (0 \le k, u \le N-1)$ . (iii)  $\Pi_i(g_k) \ne \Pi_i(g_l)$  for each k, l in  $\{0, \dots, N-1\}$  such that  $k \ne l$ .

Acknowledgments. I am grateful to Professor K. Trimèche for helpful comments. I thank the referee for his corrections and remarks.

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(Received May 27, 1994, revised November 21, 1994)