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# On a theorem of Fermi 

V.V. Slavskii


#### Abstract

Conformally flat metric $\bar{g}$ is said to be Ricci superosculating with $g$ at the point $x_{0}$ if $g_{i j}\left(x_{0}\right)=\bar{g}_{i j}\left(x_{0}\right), \Gamma_{i j}^{k}\left(x_{0}\right)=\bar{\Gamma}_{i j}^{k}\left(x_{0}\right), R_{i j}^{k}\left(x_{0}\right)=\bar{R}_{i j}^{k}\left(x_{0}\right)$, where $R_{i j}$ is the Ricci tensor. In this paper the following theorem is proved:

If $\gamma$ is a smooth curve of the Riemannian manifold $M$ (without self-crossing), then there is a neighbourhood of $\gamma$ and a conformally flat metric $\bar{g}$ which is the Ricci superosculating with $g$ along the curve $\gamma$.


Keywords: conformal connection, development
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Let $g=g_{i j} d x^{i} d x^{j}$ and $\bar{g}=\bar{g}_{i j} d x^{i} d x^{j}$ be two metrics on the $n$-dimensional manifold $M$. The metric $\bar{g}$ is said to be tangent, respectively osculating with the metric $g$ at the point $x_{0} \in M([1])$, if

$$
\begin{array}{ll}
g_{i j}\left(x_{0}\right)=\bar{g}_{i j}\left(x_{0}\right), & \text { respectively, } \\
g_{i j}\left(x_{0}\right)=\bar{g}_{i j}\left(x_{0}\right), & \frac{\partial g_{i j}}{\partial x^{k}}\left(x_{0}\right)=\frac{\partial \bar{g}_{i j}}{\partial x^{k}}\left(x_{0}\right)\left(\text { or } \quad \Gamma_{i j}^{k}\left(x_{0}\right)=\bar{\Gamma}_{i j}^{k}\left(x_{0}\right)\right)
\end{array}
$$

where $\Gamma_{i j}^{k}$ are the Cristoffel symbols.
If $\gamma$ is a smooth curve of the manifold $M$, then there is a local Euclidean metric $\bar{g}$ which is osculating with the $g$ along the curve (this theorem is due to Fermi [1]).

The Riemannian curvature tensor can be computed with the help of the first and second derivatives of the metric tensor $g_{i j}$; hence, there exists no localEuclidean metric which is superosculating of degree two with $g$. But if we consider a class of conformally flat metrics, there is a conformally flat metric which has some equal combinations of first and second derivatives.

Definition. Conformally flat metric $\bar{g}$ is said to be Ricci superosculating with $g$ at the point $x_{0}$ if

$$
g_{i j}\left(x_{0}\right)=\bar{g}_{i j}\left(x_{0}\right), \quad \Gamma_{i j}^{k}\left(x_{0}\right)=\bar{\Gamma}_{i j}^{k}\left(x_{0}\right), \quad R_{i j}\left(x_{0}\right)=\bar{R}_{i j}\left(x_{0}\right)
$$

where $R_{i j}$ is the Ricci tensor.

[^0]Theorem. If $\gamma$ is a smooth curve of the Riemannian manifold $M$ (without selfcrossing), then there is a neighbourhood of $\gamma$ and a conformally flat metric $\bar{g}$ which is the Ricci superosculating with $g$ along the curve $\gamma$.

To prove the theorem we use the conformal connection and a conformal development of the curve ([2]-[4]). Let $R^{n+2}=R^{n+1} \times R$ be a pseudo-Euclidean Minkowski space with a Lorentz inner product given by formula ([5]):

$$
\left\langle z_{1}, z_{2}\right\rangle=\left(x_{1}, x_{2}\right)-\zeta_{1} \zeta_{2}
$$

where $z_{i}=\left(x_{i}, \zeta_{i}\right) \in R^{n+2}, \quad i=1,2 ;\left(x_{1}, x_{2}\right)$ is an inner product for the Euclidean space $R^{n+1}$. Let $C^{+}=\{z=(x, \zeta):\langle z, z\rangle=0, \zeta>0\}$ denote the light cone of the Minkowski space. We consider the basis $F$ for the space $R^{n+2}$ as the column of vectors of $R^{n+2}$. Let $G L(n+1,1)$ be a manifold of all the basis of the kind:

$$
F^{t}=\left\{e_{1}, \ldots, e_{n}, z, z^{*}\right\}
$$

where $\left\{e_{1}, \ldots, e_{n}\right\}$ are spacelike vectors (i.e. $\left\|\bar{g}_{i j}\right\|=\left\|\left\langle e_{i}, e_{i}\right\rangle\right\|$ is a positively definite matrix),

$$
\begin{equation*}
\left\langle z, e_{i}\right\rangle=\left\langle z^{*}, e_{i}\right\rangle=0, \quad\left\langle z, z^{*}\right\rangle=-1, \quad\langle z\rangle^{2}=\left\langle z^{*}\right\rangle^{2}=0 \tag{1}
\end{equation*}
$$

Let us fix the basis $F_{e} \in G L(n+1,1)$, then any other basis $F \in G L(n+1,1)$ can be identified with the linear transformation $\mathcal{F}$ such that $F=\mathcal{F} \cdot F_{e}$. The matrix-valued 1-form $\Phi$ is defined by

$$
\Phi=d \mathcal{F} \cdot \mathcal{F}^{-1}=\left\|\omega_{i .}^{j}\right\|, \quad i, j=1, \ldots, n+2
$$

or

$$
\begin{equation*}
d F=d\left(\mathcal{F} \cdot F_{e}\right)=d \mathcal{F} \cdot \mathcal{F}^{-1} \cdot \mathcal{F} \cdot F_{e}=\Phi \cdot F \tag{2}
\end{equation*}
$$

Now (1) implies

$$
\begin{gathered}
d \bar{g}_{i j}=\omega_{i .}^{. k} \bar{g}_{k j}+\omega_{j .}^{. k} \bar{g}_{k i} \\
\omega_{n+1 .}^{. n+2}=\omega_{n+2 .}^{. n+1}=0, \quad \omega_{n+1 .}^{. n+1}+\omega_{n+2 .}^{n+2}=0 \\
\omega_{n+1 .}^{. k} \bar{g}_{k i}-\omega_{i .}^{. n+2}=0, \quad \omega_{n+2 .}^{. k} \bar{g}_{k i}-\omega_{i .}^{. n+1}=0
\end{gathered}
$$

Let us set

$$
\omega_{n+1 .}^{. i}=\omega^{i}, \quad \omega_{i .}^{n+2}=\omega_{i}, \quad \omega_{n+2 .}^{i}=\omega^{* i}, \quad \omega_{i .}^{n+1}=\omega_{i}^{*}, \quad \alpha=\omega_{n+1}^{. n+1}
$$

The equation of Cartan-Maurera $d \Phi+\frac{1}{2}[\Phi, \Phi]=0$ for $\Phi$ is written

$$
\begin{aligned}
& d \omega_{i .}^{. j}=\sum_{k=1}^{n} \omega_{i .}^{. k} \wedge \omega_{k .}^{. j}+\omega_{i .}^{*} \wedge \omega^{j}+\omega_{i} \wedge \omega^{* j}, \quad d \alpha=\omega_{i} \wedge \omega^{* i} \\
& d \omega^{i}=\omega^{k} \wedge \omega_{k .}^{i}+\alpha \wedge \omega^{i}, \quad d \omega^{* i}=\omega^{* k} \wedge \omega_{k .}^{i}-\alpha \wedge \omega^{* i}
\end{aligned}
$$

We now give a construction of the conformal Cartan connection. Let $g=$ $g_{i j} d t^{i} d t^{j}$ be the Riemannian metric on the manifold $M$. Let $\Phi$ be the differential matrix 1 -forms defined by the formulas:
$\omega^{i}=d t^{i}, \quad \omega_{i .}^{\cdot j}=\Gamma_{i k}^{j} d t^{k}, \quad \omega_{i}^{*}=\frac{1}{n-2}\left(R_{i k} d t^{k}-\frac{R g_{i k} d t^{k}}{2(n-1)}\right)=A_{i k} d t^{k}, \quad \alpha=0$,
where $\Gamma_{i k}^{j}$ are the Cristoffel symbols, $R_{i k}$ is the Ricci tensor, $A_{i k}$ is the reduced Ricci tensor, $R$ is the scalar curvature. The form $\Phi$ is called the normal conformal Cartan connection of the Riemannian manifold $M$ ([2]-[4]). We denote this matrix of differential 1-forms by $\Phi=\left\{\omega^{i}, \omega_{i .}^{\cdot j}, \omega_{i}^{*}, 0\right\}$.
Definition. Let $\{M, g\}$ be the Riemannian manifold; and let $\alpha$ be a differential 1-form on $M$. The extended conformal Cartan connection matrix $\widetilde{\Phi}=$ $\left\{\omega^{i}, \widetilde{\omega}_{i .}^{j}, \widetilde{\omega}_{i .}^{*}, \alpha\right\}$ on the manifold $M$, associated with $\alpha$, is the matrix defined by the formulas:

$$
\begin{aligned}
& \widetilde{\omega}_{i .}^{j}=\omega_{i .}^{\cdot j}-\alpha_{i} \omega^{j}+\alpha^{j} \omega_{i}=\left(\Gamma_{i k}^{j}-\alpha_{i} \delta_{k}^{j}+\alpha^{j} g_{i k}\right) d t^{k} \\
& \widetilde{\omega}_{i}^{*}=\omega_{i}^{*}-\alpha_{i} \alpha-D \alpha_{i}+\frac{|\alpha|^{2}}{2} \omega_{i}=\left(A_{i j}-\alpha_{i} \alpha_{j}-\alpha_{i, j}+\frac{|\alpha|^{2}}{2} g_{i j}\right) d t^{j}
\end{aligned}
$$

where $\alpha=\alpha^{i} \omega_{i}=\alpha_{i} \omega^{i}, D \alpha_{i}$ is the covariant derivative, $|\alpha|^{2}=\alpha^{i} \alpha_{i}$.
The curvature matrix of the extended Cartan connection is defined by the formula:

$$
d \widetilde{\Phi}+\frac{1}{2}[\widetilde{\Phi}, \widetilde{\Phi}]=\left(\begin{array}{ccccc}
\widetilde{W}_{i \cdot}^{\cdot j} & \mid & \widetilde{S}_{i} & 0 \\
\overline{0} & \mid & 0 & \overline{0} \\
\overline{\widetilde{S}^{j}} & \mid & \overline{0} & \overline{0}
\end{array}\right)
$$

where $\widetilde{W}_{i .}^{j}=W_{i .}^{j}$ are the forms of the Weyl tensor (it is independent of the choice of $\alpha$ ), $\widetilde{S}^{i}=S^{i}+\alpha^{s} W_{s}^{. j}$. are the forms of the Schouten-Weyl tensor ([6]).
Definition. Let $\gamma=\left\{x^{i}(t): a \leq t \leq b\right\}$ be a smooth curve of the manifold $\{M, g, \alpha\}$ and $F_{0}=\left\{e_{1}^{0}, \ldots, e_{n}^{0}, z^{0}, z^{0 *}\right\} \in G L(n+1,1)$ be a starting basis such that:

$$
g_{i j}(\gamma(a))=\left\langle e_{i}^{0}, e_{j}^{0}\right\rangle
$$

The lifting $F:[a, b] \rightarrow G L(n+1,1)$ is the solution of the differential matrix equation $\dot{F}=\Phi(\dot{\gamma}) F, \quad F(a)=F_{0}$. The vector function $z:[a, b] \rightarrow C^{+}$(the component of F ) is called the conformal development of $\gamma$.

Remark 1. The development $z$ does not depend on the choice of the local basis $\left\{e_{1}, \ldots, e_{n}\right\}$ and the form $\alpha$ on the manifold $M$ (for the proof see [3]).
Remark 2. In the case of the continuous curve $\gamma$, the lifting of the curve, for an arbitrary connection, was defined in [7].

Lemma. Let $Z: D \rightarrow C^{+}$be an immersion of the domain $D \subset R^{n}$ into the light cone $C^{+} \subset R^{n+2}$ of the Minkowski space $R^{n+2}$, and let $\bar{g}=\langle d Z, d Z\rangle=\bar{g}_{i j} d x^{i} d x^{j}$ denote the conformally flat metric ([5]), then

$$
d^{2} Z=Z_{i j} d x^{i} d x^{j}=Z_{k} \bar{\Gamma}_{i j}^{k} d x^{i} d x^{j}+Z^{*} \bar{g}_{i j} d x^{i} d x^{j}+Z \bar{A}_{i j} d x^{i} d x^{j}
$$

where $\bar{\Gamma}_{i j}^{k}$ are the Cristoffel symbols, $\bar{A}_{i k}$ is the reduced Ricci tensor of the metric $\bar{g}$, the vector $Z^{*}$ is defined by the formulas:

$$
\left\langle Z^{*}, Z_{i}\right\rangle=0, \quad\left\langle Z, Z^{*}\right\rangle=-1, \quad\left\langle Z^{*}, Z^{*}\right\rangle=0
$$

where $Z_{i}=\frac{d Z}{d x^{i}}, \quad Z_{i j}=\frac{\partial^{2} Z}{d x^{i} d x^{j}}$.
Proof: The vectors $\left\{Z_{1}, \ldots, Z_{n}, Z, Z^{*}\right\}$ form a basis, hence

$$
\begin{equation*}
Z_{i j}=Z_{k} M_{i j}^{k}+Z^{*} N_{i j}+Z P_{i j} \tag{3}
\end{equation*}
$$

It is easy to see, from (1), that

$$
M_{i j}^{k}=\bar{\Gamma}_{i j}^{k}, \quad N_{i j}=\bar{g}_{i j} .
$$

If we differentiate (3) with respect to $x^{s}$ and equate the mixed partial derivatives $Z_{i j s}$ and $Z_{i s j}$, we obtain $P_{i j}=\bar{A}_{i j}$.

Remark. The tensors $\bar{g}_{i j}$ and $\bar{A}_{i j}$ completely define the second fundamental form of the surface $\{Z(x)\}$ in the Minkowski space.
Proof of the theorem: Let $\left\{x^{1}, x^{2}, \ldots, x^{n}\right\}$ be the Fermi co-ordinate system ([8]) in the tube about the curve

$$
\gamma=\left\{x: x^{2}=\cdots=x^{n}=0, a \leq x^{1} \leq b\right\}
$$

that is:
(a) the tangent vectors $\frac{\partial}{\partial x^{1}}, \ldots, \frac{\partial}{\partial x^{n}}$ form the orthonormal frame field along the curve $\gamma$,
(b) the curves $\left\{x^{1}=\right.$ const, $\left.x^{i}=c^{i} s: s>0, i \geq 2\right\}$ are geodesics, where $\left\{c^{i}\right\}_{i=2}^{n}$ are constants.
Let $B_{\varepsilon}(\gamma)=\left\{x: \sum_{i=2}^{n}\left(x^{i}\right)^{2}<\varepsilon^{2}, a \leq x^{1} \leq b\right\}$ denote the (solid) tube of the radius $\varepsilon$ about $\gamma$. We will determine the immersion

$$
Z: B_{\varepsilon}(\gamma) \rightarrow C^{+}
$$

such that $\bar{g}=\langle d Z, d Z\rangle$ will be the required conformally flat metric.

Let $x_{0}=(a, 0, \ldots, 0) \in B_{\varepsilon}(\gamma)$ be the starting point. Any point $x=\left(x^{1}, \ldots, x^{n}\right)$ $\in B_{\varepsilon}(\gamma)$ can be connected with $x_{0}$ by the curve (open polygon) $l_{x}$ consisting of the two arcs. The first arc is a line segment along the axis of $B_{\varepsilon}(\gamma)$ :

$$
x(t)=\left\{a(1-t)+t x^{1}, 0, \ldots, 0\right\}, \quad 0 \leq t \leq 1
$$

the second arc is the geodesic segment which is orthogonal to the axis

$$
x(t)=\left\{x^{1},(t-1) x^{2}, \ldots,(t-1) x^{n}\right\}, \quad 1 \leq t \leq 2
$$

The curve $l_{x}:[0,2] \rightarrow B_{\varepsilon}(\gamma)$ depends smoothly on the terminal point $x$. Let $\mathcal{L}$ denote the family of all such curves $l_{x}$.

Let us fix the basis $F_{0} \in G L(n+1,1)$ and associate $l_{x}$ with the lifting

$$
F_{x}(t)=\left\{e_{1}(t)_{x}, \ldots, e_{n}(t)_{x}, z(t)_{x}, z^{*}(t)_{x}\right\}
$$

into the group $G L(n+1,1)$. Then we may consider the map

$$
\mathbf{F}: x \in B_{\varepsilon}(\gamma) \rightarrow F_{x}(2) \in G L(n+1,1)
$$

Let $\bar{\Phi}=\left\{\bar{\omega}^{i}, \bar{\omega}_{i .}^{j}, \bar{\omega}_{i .}^{*}, \alpha\right\}$ be a matrix 1 -forms corresponding to the map $\mathbf{F}$ by the formula (2). Let $Z(x)=z(2)_{x}$ be a component of the map $\mathbf{F}$, that is the terminal point of the development $l_{x}$.

Since $\bar{\Phi}=\left.\Phi\right|_{\mathcal{L}}$, then the forms $\bar{\Phi}$ and $\Phi$ are equal along the axis $B_{\varepsilon}(\gamma)$ (on the tangent space of the manifold $M$ ). We have

$$
\begin{aligned}
& d Z=Z_{i} \bar{\omega}^{i}=Z_{i} d x^{i} \\
& d Z_{i}=\bar{\omega}_{i .}^{j} Z_{j}+\bar{\omega}_{i} Z^{*}+\bar{\omega}_{i}^{*} Z
\end{aligned}
$$

for any point of $\gamma$. Then

$$
d^{2} Z=\bar{\omega}_{i .}^{j} d x^{i} Z_{j}+\bar{\omega}_{i} d x^{i} Z^{*}+\bar{\omega}_{i}^{*} d x^{i} Z=\omega_{i .}^{\cdot j} d x^{i} Z_{j}+\omega_{i} d x^{i} Z^{*}+\omega_{i}^{*} d x^{i} Z
$$

for any point of $\gamma$. The application of the Lemma gives us the required result.
Other applications of the conformal development curves can be find in [3].

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