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On a class of $\overline{\partial}$ -equations without solutions

Telemachos Hatziafratis

Abstract. In this note we construct $\overline{\partial}$ -equations (inhomogeneous Cauchy-Riemann equations) without solutions. The construction involves Bochner-Martinelli type kernels and differentiation with respect to certain parameters in appropriate directions.

Keywords: $\overline{\partial}$ -equation, Bochner-Martinelli type kernels Classification: 32A25

1. Introduction

If D is an open set in \mathbb{C}^n and f is a C^{∞} -function in D, one sets $\overline{\partial}f$ to be the (0,1)-form $\sum (\partial f/\partial \overline{z}_j) d\overline{z}_j$ where

$$\frac{\partial f}{\partial \overline{z}_j} = \frac{1}{2} \left(\frac{\partial f}{\partial x_j} + i \frac{\partial f}{\partial y_j} \right) \quad (z_j = x_j + i y_j, \ x_j, y_j \in \mathbb{R}, \ j = 1, \dots, n),$$

and, in general, if $u = \sum f_{j_1...j_q} d\overline{z}_{j_1} \wedge \ldots \wedge d\overline{z}_{j_q}$ is a (0,q)-form with C^{∞} coefficients in D then $\overline{\partial}u = \sum \overline{\partial}f_{j_1...j_q} \wedge d\overline{z}_{j_1} \wedge \ldots \wedge d\overline{z}_{j_q}$.

Several constructions in complex analysis are reduced to the $\overline{\partial}$ -equation, i.e., given a (0, q)-form v (in D) find a (0, q-1)-form u so that $\overline{\partial}u = v$; since $\overline{\partial}(\overline{\partial}u) = 0$, a necessary condition that the equation $\overline{\partial}u = v$ have a solution is that $\overline{\partial}v = 0$. It is usual to consider the quotient (the (0, q)- $\overline{\partial}$ -cohomology)

$$\begin{split} H^{(0,q)}_{\overline{\partial}}(D) &= \\ &= \{(0,q)\text{-forms } v \text{ in } D \text{ with } \overline{\partial}v = 0\}/\{\overline{\partial}u: u \text{ is a } (0,q-1)\text{-form in } D\} \end{split}$$

which measures the "insolvability" of the $\overline{\partial}$ -equation in D (for (0,q)-forms).

If $K \subset \mathbb{C}^n$ is a convex compact set then $H^{(0,n-1)}_{\overline{\partial}}(\mathbb{C}^n - K)$ is infinite dimensional (see for example [4, p. 156]). The proof is based on Martineau's theorem of the representation of the $\overline{\partial}$ -cohomology classes as holomorphic functions in an appropriate domain (depending on K). Here we will give a simple proof of this using the Bochner-Martinelli integral. In fact our proof works in more general settings, for example if we replace K by any compact set (not necessarily convex). We also cover the case of $(0, m - 1) - \overline{\partial}$ -cohomology if K is replaced by an appropriate closed neighborhood of some analytic varieties of codimension m.

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After this brief introduction we come to the main point of this note which is to construct some classes of $\overline{\partial}$ -equations without solution. The simplest such example is the one given in Rudin [6, p. 355]. As we pointed out, our construction involves Bochner-Martinelli type kernels and differentiation, in appropriate directions, with respect to certain parameters. We start by explaining this construction in a simple case and generalizing it gradually to more involved cases.

2. Examples of insolvable $\overline{\partial}$ -equations

For $z \neq \zeta$, let us consider the Bochner-Martinelli kernel with singularity at ζ :

$$k(z,\zeta) =: \frac{1}{|z-\zeta|^{2n}} \sum_{j=1}^{n} (-1)^{j-1} (\overline{z}_j - \overline{\zeta}_j) \, d\overline{z}_1 \wedge \dots (j) \dots \wedge d\overline{z}_n.$$

We recall its basic properties: it is a (0, n-1)-form in $z \in \mathbb{C}^n - \{\zeta\}, \overline{\partial}_z k(z, \zeta) = 0$ and reproduces holomorphic functions, i.e., for a holomorphic function f in neighborhood of \overline{D} (D is assumed to be a bounded domain in \mathbb{C}^n with smooth boundary) and $\zeta \in D$,

$$\int_{z\in\partial D} f(z)k(z,\zeta)\wedge\omega(z) = c_n f(\zeta)$$

where $\omega(z) = dz_1 \wedge \ldots \wedge dz_n$ and $c_n = (2\pi i)^n / (n-1)!$ (see Kytmanov [5, Chapter 1]).

Let I be the set of n-tuples $a = (a_1, \ldots, a_n)$ where a_1, \ldots, a_n are non-negative integers. For every $a \in I$ let us define the differential form η_a by setting

$$\eta_a(z) = \left. \frac{\partial^{a_1 + \dots + a_n} k(z, \zeta)}{\partial \zeta_1^{a_1} \dots \partial \zeta_n^{a_n}} \right|_{\zeta = 0}$$

Then η_a is a (0, n-1)-form with C^{∞} -coefficients in $\mathbb{C}^n - \{0\}$ where it is $\overline{\partial}$ -closed, i.e., $\overline{\partial}\eta_a = 0$; this follows from the fact that $\overline{\partial}_z k(z, \zeta) = 0$.

We claim that for each finite subset $A \subset I$ and any $\lambda_a \in \mathbb{C}$, $a \in A$, the $\overline{\partial}$ -equation $\overline{\partial}u = \sum_{a \in A} \lambda_a \eta_a$ has no solution in $\mathbb{C}^n - \{0\}$ unless $\lambda_a = 0$ for all $a \in A$ (of course now we assume that $n \geq 2$). To prove this let us assume that this equation has a solution u; then

(1)
$$\sum_{a \in A} \lambda_a \eta_a \wedge \omega = \overline{\partial} u \wedge \omega = d[u \wedge \omega].$$

On the other hand

(2)
$$\int_{z\in\partial B(0,1)} f(z)\eta_a(z)\wedge\omega(z) = c_n \frac{\partial^{a_1+\ldots+a_n}f}{\partial z_1^{a_1}\ldots\partial z_n^{a_n}}(0)$$

for every holomorphic function f in a neighborhood of $\overline{B(0,1)}$, where $B(0,1) = \{z \in \mathbb{C}^n : |z| < 1\}$. Indeed for $\zeta \in B(0,1)$,

$$\int_{z \in \partial B(0,1)} f(z)k(z,\zeta) \wedge \omega(z) = c_n f(\zeta),$$

and applying the differential operator $\partial^{a_1+\ldots+a_n}/\partial\zeta_1^{a_1}\ldots\partial_n^{a_n}$ and evaluating at $\zeta = 0$ we obtain (2).

Next applying (2) with $f = f_{\beta}(z) = z_1^{\beta_1} \dots z_n^{\beta_n}$, for each $\beta = (\beta_1, \dots, \beta_n) \in A$, we obtain

(3)
$$\int_{z\in\partial B(0,1)} f_{\beta}(z)\eta_{a}(z)\wedge\omega(z) = \begin{cases} 0 & \text{if } a\neq\beta\\ c_{n}\beta_{1}!\dots\beta_{n}! & \text{if } a=\beta. \end{cases}$$

But (1) and Stokes's theorem give

$$\int_{\partial B(0,1)} \sum_{a \in A} \lambda_a f_\beta \eta_a \wedge \omega = \int_{\partial B(0,1)} d[f_\beta u \wedge \omega] = 0.$$

The above equation, taking into consideration (3), gives that $\lambda_{\beta} = 0$, and the claim follows.

It follows from what we have just proved that the set $\{[\eta_a] : a \in I\}$ is linearly independent in $H^{(0,n-1)}_{\overline{\partial}}(\mathbb{C}^n - \{0\})$; it follows that these vector spaces are infinite dimensional: dim $H^{(0,n-1)}_{\overline{\partial}}(\mathbb{C}^n - \{0\}) = \infty$. More generally if $K \subset \mathbb{C}^n$ is a compact set with $0 \in K$ then the cohomology classes $\{[\eta_a] : a \in I\}$ are linearly independent in $H^{(0,n-1)}_{\overline{\partial}}(\mathbb{C}^n - K)$. This can be proved in the same exactly way replacing the sphere S(0,1) by a sufficiently large sphere surrounding the compact set K. In particular dim $H^{(0,n-1)}_{\overline{\partial}}(\mathbb{C}^n - K) = \infty$; as we said in the introduction, in the case K is a convex compact set in \mathbb{C}^n , this is proved (by a different method) in Henkin-Leiterer [4, p. 156].

Now we are going to generalize the above construction by replacing the set $\mathbb{C}^n - \{0\} = \mathbb{C}^n - \{z_1 = z_2 = \ldots = z_n = 0\}$ by a more general set of the form $\mathbb{C}^n - \{z \in \mathbb{C}^n : h_1(z) = \ldots = h_m(z) = 0\}$ (with $h_j \in O(\mathbb{C}^n)$ and $m \leq n$) and the set $\mathbb{C}^n - K$ by a set of the form D - A, where $D \subset \mathbb{C}^n$ is open and A is an appropriate closed set of D and satisfying a simple geometric condition; moreover we will construct explicitly an infinite set of linearly independent cohomology classes in $H^{(0,m-1)}_{\overline{\partial}}(D-A)$ (thus giving a large class of $\overline{\partial}$ -equations without solutions). More precisely we will prove the following

Theorem 1. Let *D* be a domain in \mathbb{C}^n , $h_1, \ldots, h_m \in O(D)$ holomorphic functions on *D* and $V = \{z \in D : h_1(z) = \ldots = h_m(z) = 0\}$. Suppose $A \subset D$ is a closed (in *D*) subset, containing *V*, such that there exist a point $p \in V$ which

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is a regular point of V (in the sense that $dh_1 \wedge \ldots \wedge dh_m \neq 0$ at the point p) and a complex submanifold X of D of dimension m, meeting V only at p and transversally, so that $A \cap X$ is a compact set. Then dim $H^{(0,m-1)}_{\overline{\partial}}(D-A) = \infty$.

PROOF: Let us consider the (0, m - 1)-form:

$$\theta(z,\zeta) = \frac{\sum_{j=1}^{m} (-1)^{j-1} (\overline{h}_j(z) - \overline{h}_j(\zeta)) \overline{\partial h_1}(z) \wedge \dots (j) \dots \wedge \overline{\partial h_m}(z)}{\left[\sum_{j=1}^{m} |h_j(z) - h_j(\zeta)|^2\right]^m};$$

this is a (0, m-1)-form in z defined for $z \in D - \{z \in D : h_j(z) = h_j(\zeta), 1 \le j \le m\}$; its coefficients depend on the parameter $\zeta \in D$.

Also let us consider a holomorphic vector field $w(\zeta)$ tangent to X in a neighborhood of p with $w(p) \neq 0$. Then express $w(\zeta)$ in terms of the basic fields $\partial/\partial\zeta_1, \ldots, \partial/\partial\zeta_n$ to obtain

$$w(\zeta) = \sum_{j=1}^{n} c_j(\zeta) \left(\frac{\partial}{\partial \zeta_j}\right)_{\zeta}$$

for some holomorphic functions $c_j(\zeta)$ in a neighborhood of p. Since $w(p) \neq 0$ we may assume that $c_1(p) \neq 0$ and hence $c_1(\zeta) \neq 0$ in a neighborhood U of p; in U define

$$\xi(\zeta) = \left(\frac{\partial}{\partial\zeta_1}\right)_{\zeta} + \sum_{j=2}^n \frac{c_j(\zeta)}{c_1(\zeta)} \left(\frac{\partial}{\partial\zeta_j}\right)_{\zeta}.$$

Now for $k = 0, 1, 2, \ldots$, define η_k by the formula

$$\eta_k(z) = \xi_{\zeta}^k \theta(z,\zeta)|_{\zeta=p};$$

here ξ_{ζ}^k acts in the variable ζ on each coefficient of the form $\theta(z,\zeta)$. It is clear that η_k is a (0, m-1)-form with C^{∞} coefficients on $D-V \supset D-A$. Moreover $\overline{\partial}_z \theta(z,\zeta) = 0$ for each fixed ζ ; this is a straightforward computation. Therefore $\overline{\partial}\eta_k = 0$ in D-A for every k and consequently the (0, m-1)-forms η_k define cohomology classes in $H_{\overline{\partial}}^{(0,m-1)}(D-A)$, denoted by $[\eta_k]$.

We will prove that the set $\{[\eta_k] : k = 0, 1, 2, ...\}$ is \mathbb{C} -linearly independent in $H^{(0,m-1)}_{\overline{\partial}}(D-A)$. For this let $\lambda_0, \ldots, \lambda_N \in \mathbb{C}$ so that

$$\sum_{k=0}^{N} \lambda_k[\eta_k] = 0 \text{ in } H^{(0,m-1)}_{\overline{\partial}}(D-A);$$

this means that there is a (0, m - 2)-form u with C^{∞} coefficients in D - A such that

$$\sum_{k=0}^{N} \lambda_k \eta_k = \overline{\partial} u \text{ in } D - A \quad (\text{here we assume } m \ge 2).$$

Since $X \cap A$ is compact there is a domain $G \subset X$ with smooth boundary which contains $X \cap A$, i.e., $\partial G \subset X - A$.

Then, for every holomorphic function f on D, we have

$$\int_{\partial G} f \overline{\partial} u \wedge \omega(h) = \int_{\partial G} d \left[f u \wedge \omega(h) \right] = 0,$$

by Stokes's theorem, where $\omega(h) = \partial h_1 \wedge \ldots \wedge \partial h_m$. Therefore

(4)
$$\sum_{k=0}^{N} \lambda_k \int_{\partial G} f \eta_k \wedge \omega(h) = 0.$$

Since $d[f\eta_k \wedge \omega(h)] = 0$ (with differential forms restricted to X) we have

(5)
$$\int_{\partial G} f\eta_k \wedge \omega(h) = \int_{\partial B} f\eta_k \wedge \omega(h)$$

where $B \subset X$ is a small domain with smooth boundary containing the point p; here we used also our assumption that $X \cap V = \{p\}$. On the other hand

(6)
$$\int_{\partial B} f\eta_k \wedge \omega(h) = c_m \xi^k f(p)$$

where $c_m = (2\pi i)^m / (m-1)!$, provided that B is sufficiently small. Indeed since p is a regular point of V and X meets V at p and transversally it follows that B can be chosen sufficiently small so that for each $\zeta \in B$ the map:

$$B \ni z \to (h_1(z) - h_1(\zeta), \dots, h_m(z) - h_m(\zeta))$$

is one-to-one; hence the multiplicity of the zero ζ of this map is 1. Thus by $[1, \, \mathrm{p}, 25]$

$$\int_{z \in \partial B} f(z)\theta(\zeta, z) \wedge \omega(h)(z) = c_m f(\zeta) \text{ for } \zeta \in B.$$

Applying ξ_{ζ}^k to both sides of this equation (this can be done since ξ_{ζ} are tangent to X near the point p) and evaluating at $\zeta = p$ we obtain (3). Now apply (4) and (5) with $f = (x_1 - x_2)^{\beta}$ for s = 0, 1, 2 to obtain

Now apply (4) and (5) with $f = (z_1 - p_1)^s$ for s = 0, 1, 2, ... to obtain

(7)
$$\sum_{k=0}^{N} \lambda_k \int_{\partial B} (z_1 - p_1)^s \eta_k \wedge \omega(h) = 0, s = 0, 1, 2, \dots$$

But by (6)

(8)
$$\int_{\partial B} (z_1 - p_1)^s \eta_k \wedge \omega(h) = c_m \left(\xi^k (\zeta_1 - p_1)^s \right) \Big|_{\zeta = p}.$$

Also, as a simple computation shows,

$$\xi^k = \frac{\partial^k}{\partial \zeta_1^k} + L_k$$

where L_k is a differential operator with the property $L_k[(\zeta_1 - p_1)^s]|_{\zeta=p} = 0$ for all s. Hence

$$\left(\xi^k(\zeta_1-p_1)^s\right)\Big|_{\zeta=p} = \frac{\partial^k}{\partial\zeta_1^k} \left((\zeta_1-p_1)^s\right)|_{\zeta=p} = \begin{cases} k! & \text{if } k=s\\ 0 & \text{if } k\neq s. \end{cases}$$

This, combined with (7) and (8), gives that $\lambda_s = 0, s = 0, 1, \ldots, N$. Thus the linear independence of the classes $[\eta_k], k = 0, 1, 2, \ldots$ has been established and the proof is complete.

 \square

Remarks. (i) With the notation of Theorem 1, suppose that the Jacobian $\partial(h_1, \ldots, h_m)/\partial(z_1, \ldots, z_m)$ is different from zero at the point p of V. Then $X = \{z \in D : z_{m+1} = p_{m+1}, \ldots, z_n = p_n\}$ meets V at p transversally and if the closed subset $A \subset D$, which contains V, is such that there is a neighborhood U of p and a compact subset $K \subset X \cap U$ so that $p \in K$ and $X \cap U - K \subset D - A$, then dim $H^{(0,m-1)}_{\overline{\partial}}(D-A) = \infty$. In fact a similar proof shows that the set $\{[\eta_a]:$ where $a = (a_1, \ldots, a_m)$ with a_1, \ldots, a_m being non-negative integers}, is linearly independent in $H^{(0,m-1)}_{\overline{\partial}}(D-A)$ where the (0, m-1)-forms η_a are defined as follows:

$$\eta_a(z) = \left. \frac{\partial^{a_1 + \dots + a_m} \theta(z, \zeta)}{\partial \zeta_1^{a_1} \dots \partial \zeta_m^{a_m}} \right|_{\zeta = p}$$

A special case of this is when A = V and we obtain, in particular, that $\dim H^{(0,m-1)}_{\overline{\partial}}(D-V) = \infty$; this is proved (by a different method) in Gunning [2, p. 163].

(ii) Notice that Theorem 1 holds even for m = 1; then it simply says that dim $O(D - A) = \infty$. Thus Theorem 1 may be considered as a generalization of this fact and the space $H_{\overline{\partial}}^{(0,m-1)}(D - A)$ plays, in a sense, the role of O(D - A). (iii) A similar construction can also be carried out with the Cauchy-Fantappie type kernels of [3].

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3. Replacing D by a complex manifold

Let M be an *n*-dimensional complex manifold on which global holomorphic functions give coordinates at any point of M, i.e., for any point p of M there exist holomorphic functions ζ_1, \ldots, ζ_n on M so that $(\zeta_1, \ldots, \zeta_n)$ restricted to a sufficiently small neighborhood of p define holomorphic coordinates for M at p. For example a Stein manifold (i.e., a closed submanifold of some \mathbb{C}^n) or any open subset of a Stein manifold satisfies this condition. For such manifolds we can prove the following

Theorem 2. Let M be an n-dimensional complex manifold on which global holomorphic functions give coordinates at any point of M. Let $h_1, \ldots, h_m \in O(M)$ be holomorphic functions on M and $V = \{z \in M : h_1(z) = \ldots = h_m(z) = 0\}$. Suppose $A \subset M$ is a closed subset, containing V, such that there exist a point $p \in V$ which is a regular point of V and a complex submanifold X of M of dimension m, meeting V only at p and transversally, so that $A \cap X$ is a compact set. Then dim $H^{(0,m-1)}_{\overline{\partial}}(M-A) = \infty$.

PROOF: Choose functions ζ_1, \ldots, ζ_n , holomorphic on M, which give coordinates at p and $\zeta_1(p) = \ldots = \zeta_n(p) = 0$. Then, as in the proof of Theorem 1, we may choose a holomorphic vector field of the form

$$\xi(\zeta) = \left(\frac{\partial}{\partial\zeta_1}\right)_{\zeta} + \sum_{j=2}^n \frac{c_j(\zeta)}{c_1(\zeta)} \left(\frac{\partial}{\partial\zeta_j}\right)_{\zeta}$$

in a neighborhood U (in M) of p which is tangential to X at any point of $X \cap U$. Then the proof can be continued as in the case of Theorem 1, using at the end the functions z_1^s , s = 0, 1, 2..., which are holomorphic functions on all of M. \Box

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DEPARTMENT OF MATHEMATICS, UNIVERSITY OF ATHENS, PANEPISTEMIOPOLIS, 157 84 ATHENS, GREECE

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