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ON A GENERALIZATION OF NETS

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This paper is concerned with the study of nets, where groupoids participate in an algebraical expression. These problems vere studied by M.A.Taylor, V.D.Belousov, N.I.Prodan, particularly for 3-nets. This paper studies the nets of an arbitrary degree. It appears that in general the apparatus of groupoids are not sufficient to this purpose and certain admissible relations are to be used. Under cartain conditions it becomes possible to pass from them over to the groupoids or even to quasi-groups with the help of homotopies. These problems were investigated by V.Havel, G.Čupona, J.Ušan, Z. Stojaković in general, and we are investigating them for the nets of dimension 2.

A (general) net is defined as a quadruplet (\mathcal{P}, \mathcal{L} , $(\mathcal{L}_{\iota})_{\iota \in \mathcal{Y}}, \mathbf{I}$), where \mathcal{P} is a non-empty set of elements called points, \mathcal{L} is a non-empty set of elements called lines and $(\mathcal{L}_{\iota})_{\iota \in \mathcal{Y}}$ a system of mutually disjoint subsets of \mathcal{L} (called

pencils), the union of which is $\mathcal{Z} \cdot \mathcal{J}$ is a set of indices $\#\mathcal{J} \ge 3$, Ic $\mathcal{P} \times \mathcal{L}$ is an incidence relation and the following conditions are satisfied:

- (i) ∀ℓ∈∠ ∃P∈∠ , PIℓ ,
- (ii) $\forall P \in \mathcal{P} \quad \forall_i \in \mathcal{I} \exists l \in \mathcal{L}_i$, PIl,
- (iii) $\forall_{l} \in \mathcal{Y} \quad \forall k, h \in \mathcal{X}_{l}; k \neq h \{ X \in \mathcal{P} | XIk, XIh \} = \emptyset,$
- (iiii) $\forall \alpha, \beta, \gamma \in \mathcal{I}; \ \alpha \neq \beta \neq \gamma \quad \forall l_1, l_2, l_3 \quad l_1 \in \mathcal{X}_{\alpha},$ $l_2 \in \mathcal{X}_{\beta}, \ l_3 \in \mathcal{X}_{\gamma}, \# \{ x \in \mathcal{P} \mid x \colon l_1, l_2, l_3 \} \notin 1.$

Lines of the same pencil (distinct pencils) are called parallel (non-parallel) and we write $a /\!/ b$ ($a /\!\!/ b$). The points A_1, A_2, \ldots are called collinear if there is e line a such that $A_1 I$, $A_2 I$, \ldots . We denote it by $\overline{A_1 A_2 \ldots}$. The lines a_1, a_2 , \ldots are called concurrent, if there is a point P such that $a_1 IP$, $a_2 IP$, \ldots . We denote it by $\overline{a_1, a_2, \ldots}$.

We denote by $[\ell]:= \{x \in \mathcal{P} \mid x \in \mathcal{P}\}$ for every $\ell \in \mathcal{L}$. By a degree of a net the cardinality of the set \mathcal{J} is meant.

Under a homomorphism of net $\mathscr{N} = (\mathcal{P}, \mathscr{L}, (\mathscr{L}_{l})_{l \in \mathcal{Y}}, I)$ onto a net $\mathscr{N}' = (\mathcal{P}, \mathscr{L}', (\mathscr{L}'_{l})_{l \in \mathcal{Y}}, I')$ we understand a couple $(\mathscr{P}, \mathcal{J})$ of surjective mappings $\mathscr{P} : \mathcal{P} \twoheadrightarrow \mathcal{P}', \ \mathcal{A} : \mathscr{L} \twoheadrightarrow \mathscr{L}'$ such that

(i) $PI\ell \implies \mathcal{T}(P)I'\lambda(\ell)$,

(ii) $(\ell \in \mathscr{L}_{l} \Longrightarrow \lambda(\ell) \in \mathscr{L}_{l}') \forall_{l} \in \mathcal{I}.$

If \mathcal{T} , \mathcal{X} are injections, then $(\mathcal{T}, \mathcal{X})$ is called an isomorphism.

We say $\mathcal{N} = (\mathcal{P}, \mathcal{Z}, (\mathcal{Z}_{l})_{l \in \mathcal{Y}}, I)$ is solvable if for every two lines a,b from distinct pencils $[a] \cap [b] \neq \emptyset$. \mathcal{N} is uniquely solvable if there exists one uniquely determined point P = $[a] \cap [b]$. The uniquely solvable nets are called as classical nets.

We say \mathscr{N} is a Cartesian net if there exist two significant pencils denote \mathscr{K}_1 , \mathscr{K}_2 1,2 $\not\in \mathscr{I}$ such that

 $a \in \mathcal{X}_1$, $b \in \mathcal{X}_2 \Longrightarrow (\exists ! P \in \mathcal{P} P I a, P I b)$.

Let $(S_{\iota})_{\iota \in \mathcal{Y}}$ be a family of non-empty sets with the index set \mathcal{J} , $\#\mathcal{J} \cong 3$. A subset $\mathcal{G} \subset \mathcal{X} S_{\iota}$ is called an admissible relation if

- (1) $\operatorname{proj}_{\iota} \sigma = S_{\iota}$ for every $\iota \in \mathcal{J}$,
- (2) for every $(s_l)_{l \in \mathcal{Y}}$, $(z_l)_{l \in \mathcal{Y}} \in \mathfrak{S}$ if there exist α , $\beta_i, \gamma_{l}; \alpha \neq \beta \neq \gamma_{l} \neq \alpha$ such that $s_{\alpha} = z_{\alpha}, s_{\beta} = z_{\beta},$ $s_{\gamma_l} = z_{\gamma_l},$ then $(s_l)_{l \in \mathcal{Y}} = (z_l)_{l \in \mathcal{Y}}.$

<u>Theorem 1</u>. For every admissible relation $\mathcal{C}_{\mathcal{L}}$ (where S_i are mutually disjoint) there exists a net $\mathscr{N} = (\mathcal{P}, \mathcal{Z}, (\mathcal{Z}_{i})_{i \in \mathcal{Y}}, \mathcal{I})$, such that $\mathcal{P} = \mathcal{O}$,

$$\begin{aligned} &\mathcal{L} = \bigcup_{\substack{u \in \mathcal{Y} \\ u \in \mathcal{Y}}} & \mathcal{L}_{i} = S_{i} & \forall_{i} \in \mathcal{Y}, \\ (s_{i})_{i} \in \mathcal{Y} & \text{Iy} \leq = > y \in \{s_{i}\}_{i} \in \mathcal{Y}. \end{aligned}$$

(Notation: $\mathcal N$ is a net over $\mathcal C$).

To the proof. The condition (i) from the definition of net is satisfied since $\operatorname{proj}_{\iota} \mathfrak{S} = S_{\iota}$ for every $\iota \in \mathcal{J}$. The conditions (ii) and (iii) folow from the fact that $\mathfrak{S} \subset \mathfrak{X} S_{\iota}$ and if(1) holds. The condition (iiii) follows from (2) of the definition of \mathfrak{S} .

<u>Theorem 2</u>. For every net $\mathcal{N} = (\mathcal{P}, \mathcal{L}, (\mathcal{L}_{l})_{l \in \mathcal{Y}}, I)$ there exists an admissible relation $\mathcal{OC} \times \mathcal{L}$ such that $(a_{l})_{l \in \mathcal{Y}} \in \mathcal{O}$ iff all lines of the set $\{a_{l}\}$ are concurrent. (Notation : \mathfrak{O} is associated to \mathcal{N}).

To the proof. Property (1) of the admissible relation follows from condition (i) of the definition of a net. Property (2) follows from condition (iiii).

Under a homotopy (an isotopy) of an admissible relation $\mathfrak{S}' \subset \underset{\substack{\iota \in \mathcal{Y} \\ \iota \in \mathcal{Y}}}{\mathsf{S}_{\iota}}$ onto an admissible relation $\mathfrak{S}' \subset \underset{\substack{\iota \in \mathcal{Y} \\ \iota \in \mathcal{Y}}}{\mathsf{S}_{\iota}}$ we mean a system of surjective (bijective) mappings $\overset{\iota e \, \mathcal{Y}}{\mathcal{Y}_{\iota}}$: $S_{\iota} \longrightarrow S_{\iota}'$ such that

 $(s_{\iota})_{\iota \in \mathcal{Y}} \in \mathcal{O} \Longrightarrow (\varphi_{\iota}(s_{\iota}))_{\iota \in \mathcal{Y}} \in \mathcal{O}'.$

The isotopy of admissible relations with the same index set is an equivalence relation; two admissible relations from the same equivalence class are said to be isotopic.

<u>Theorem 3</u>. Let $\mathcal{N} = (\mathcal{P}, \mathcal{Z}, (\mathcal{Z}_i)_{i \in \mathcal{Y}}, I)$ be a net. Then the net \mathcal{N}' over the admissible relation associated to \mathcal{N} is isomorphic to \mathcal{N} . Let $\mathcal{C} \subset \underset{i \in \mathcal{Y}}{\times} S_i$ be an admissible relation. Then the admissible relation \mathcal{O}' associated to the net over \mathcal{O} is isotopic to \mathcal{O}' .

To the proof. The isomorphism of nets is $(\mathcal{T}, \mathrm{id}_{\mathcal{Y}})$, where \mathcal{T} maps every point $A \in \mathcal{P}$ onto the point $(a_{\iota})_{\iota \in \mathcal{Y}}$, where AIa_{ι} for every $\iota \in \mathcal{J}$. The isotopy of admissible relations is $(\mathrm{id}_{S},)_{\iota} \in \mathcal{J}$.

Let $\mathcal{G} \subset X \subseteq$ be an admissible relation. We say \mathcal{G} is solvable (uniquely solvable) if for every two elements $s_{\mathcal{K}}$, $s_{\mathcal{K}} \in S_{\mathcal{K}}$, $s_{\mathcal{K}} \in S_{\mathcal{K}}$ there exist (uniquely determined) elements $s_{\iota} \iota \in \mathcal{I} \setminus \{\alpha_{, \ell}\}$ such that $(s_{\iota})_{\iota \in \mathcal{I}} \in \mathcal{G}$.

Clearly the solvable (uniquely solvable) admissible relation is associated to a solvable (uniquely solvable) net. And coversely: every solvable (uniquely solvable) net is a net over a solvable (uniquely solvable) admissible relation.

Let $\mathfrak{S} \subset \underset{\iota \in \mathcal{I}}{\times} S_{\iota}$ be an admissible relation, \sim_{ι} an equivalence relation on $S_{\iota} \iota \in \mathcal{I}$. We denote $S_{\iota} / \sim_{\iota} = \overline{S}_{\iota}$ and define the relation $\overline{\mathfrak{S}} \subset \underset{\iota}{\times} \overline{S}_{\iota}$ as follows:

 $\forall X_{i} \in \overline{S}, (X_{i})_{i \in \mathcal{Y}} \in \overline{\sigma} < \Rightarrow \forall_{i \in \mathcal{Y}} \exists s_{i} \in X_{i} \in \overline{S}, (s_{i})_{i \in \mathcal{Y}} \in \overline{\mathcal{O}}.$

Then $\overline{\sigma}$ is an admissible relation called a factor relation, written as $\overline{\sigma} = \overline{\sigma}/(\sim_l)_{l \in \mathcal{Y}}$.

One example of the equivalence relation: Let $\mathfrak{S} \subset \underset{\substack{\ell \in \mathcal{Y}\\ \ell \in \mathcal{Y}}}{\mathfrak{S}_{\ell}}$ be an admissible relation. For every $\not \in \mathcal{J}$ we define the relation $\sim_{\mathcal{X}}$ on $S_{\mathcal{X}}$ as : a $\sim_{\mathcal{X}}$ b means that for every β , $\gamma \in \mathcal{J}$ $\not \prec \neq \beta \neq \gamma \neq \not \prec (x_{\iota})_{\iota \in \mathcal{Y}} \in \mathfrak{S}$, where $x_{\iota} = a$, $x_{\beta} = x$, $x_{\gamma} = y$ if

and only if $(y_i)_{i \in Y} \in \mathfrak{S}$, where $y_{\mathfrak{A}} = \mathfrak{b}$, $y_{\mathfrak{A}} = \mathfrak{X}$, $y_{\mathfrak{P}} = \mathfrak{Y}$.

The solvable relation \mathcal{O} is called regular if for every triple $(\alpha, \beta, \gamma) \in \mathcal{J}^3$ the set $\{\mathcal{O}_{\mathbf{x}, \beta, \mathbf{p}}(\mathbf{x}_{\mathbf{x}}, \mathbf{x}_{\beta}) \mid \mathbf{x}_{\mathbf{x}} \in S_{\alpha}, \mathbf{x}_{\beta} \in S_{\beta}\}$ is a decomposition of the set S_{γ} , (corresponding to some equivalence relation $\sim \gamma_{\mathbf{p}}$ on $S_{\gamma \mathbf{p}}$).

<u>Theorem 4</u>. Let $\mathfrak{S} \subset \underset{\substack{i \in \mathcal{Y} \\ i \in \mathcal{I}}}{\times S_i}$ be a regular admissible relation. Then $\mathfrak{S}/(\sim_i)_{i \in \mathcal{I}}$ is a uniquely solvable admissible relation. To the proof. Since \mathfrak{S} is a solvable admissible relation, then with respect to the definition of regularity, $\overline{\mathfrak{S}} = \mathfrak{S}/(\sim_i)_{i \in \mathcal{I}}$ is solvable, too.

Analogously to the set $\widetilde{\mathcal{O}}_{\alpha,\beta,\gamma}(x_{\alpha},x_{\beta})$ for $\widetilde{\mathcal{O}}$ we now define the sets $\overline{\mathcal{O}}_{\alpha,\beta,\gamma}(x_{\alpha},x_{\beta})$ for the relation $\overline{\mathfrak{O}} = \mathfrak{O}/(\sim_{\iota})_{\iota \in \mathcal{Y}}$. With regard to the definition of a regular relation it becomes evident that $\# \ \overline{\mathcal{O}}_{\alpha,\beta,\gamma}(x_{\alpha},x_{\beta}) = 1$ for every $(\alpha,\beta,\gamma) \in \mathcal{Y}^{3}$ and for every $x_{\alpha} \in \overline{S}_{\alpha}$, $x_{\beta} \in \overline{S}_{\beta}$.

Hence it follows that the relation $\overline{\sigma}$ is uniquely solvable.

<u>Corollary</u> : Any regular admissible relation can be mapped onto a uniquely solvable admissible relation by a homotopy.

To the proof. We define a system of surjections $\varphi_l: \, \mathbf{S}_l \to \overline{\mathbf{S}}_l \quad \text{such that}$

 $\varphi^{(\times_{l_o})} = X_{l_o} \qquad \qquad \times_{l_o} \in X_{l_o}$ $\times_{l_o} \in S_l \qquad \qquad X_{l_o} \in \overline{S}_l .$

There may be found to all properties of the admissible relation corresponding properties and corresponding theorems for nets. The most important of them are considered below. <u>Theorem 5</u>. Let $\mathcal{N} = (\mathcal{P}, \mathcal{L}, (\mathcal{L}_l)_{l \in \mathcal{Y}}, I)$ be a regular net. Then there exists a homomorphism which maps the net to a classical net.

Under a three-basic groupoid we understand a quadruplet $(A_1, A_2, A_3, .)$, where A_1, A_2, A_3 are non-empty sets and \bullet is a mapping $\bullet : A_1 \times A_2 \longrightarrow A_3$ (a,b) \longmapsto a.b.

<u>Theorem 6</u>. Let \mathscr{N} be a Cartesian net, \mathscr{O} an admissible relation associated to \mathscr{N} . Then there exists a system of three-basic groupoids $((S_1, S_2, S_4, \mathcal{A})_{\alpha} \in \mathcal{J} \setminus \{1, 2\})$ canonically determined by \mathfrak{O} .

and the mappings J_{α} : $S_1 \times S_2 \longrightarrow S_{\alpha} \propto \epsilon \mathcal{J}$ are given.

Let $\mathfrak{S} \subset \underset{\ell \in \mathscr{Y}}{\underset{\ell :}}}}}}}}}}}} nde so is description of the substant for every is description of the source is description of the$

If \mathscr{N} is a Cartesian net for which $\# \mathscr{L}_{l} = \text{constant}$ for every $l \in \mathcal{J}$, then the corresponding algebraical system is a family of groupoids. If the net \mathscr{N} is a solvable Cartesian net, then the equations $s_1 \cdot \mathscr{K} \times = s_{\mathscr{K}}$, $y \cdot \mathscr{K} \cdot s_2 = s_{\mathscr{K}}$ are solvable for every $s_1 \in S_1$, $s_2 \in S_2$, $s_{\mathscr{K}} \in S_{\mathscr{K}}$ for every $\mathscr{K} \in \mathcal{J} \setminus \{1,2\}$ and we obtain the family of D-groupoids (PRODAN) called also solvable groupoids, or groupoids with division. If the net \mathscr{N} is a uniquely solvable (obviously it is a Cartesian net and $\# \mathscr{L}_{\mathscr{L}} = \text{constant}$), i.e. a classical net, then all groupoids are uniquely solvable and we obtain the family of quasigroups. <u>Conclusion</u>: Let \mathscr{N} be a regular net and \mathfrak{S} an admissible relation associated to \mathscr{N} . Then the system of three-basic groupoids determined by \mathfrak{S} is homotopic to a system of quasigroups.

Thus we have found an important class of regular solvable nets. The fact that they can pass from the epimorphism to the classical nets guarantees that this generalization is reasonable and is worth of investigating their properties.

Example of a regular solvable admissible relation : Let S_k be the sets of complex numbers having absolute value equal to k for $k \in \{2,3,6,12,18,36,72,108,216,432,648,$ $1296,\ldots\} = \mathcal{Y}$ where $k = 2^m \cdot 3^n$, $|m-n| \leq 1$, $m, n \in \mathbb{N} \cup \{0\}$. (N is a set of natural numbers.)

We put $G' = \{(s_{\iota})_{\iota \in \mathbb{N}} | s_{\iota} = \dot{s}_{1}^{m} \cdot s_{2}^{n}, \iota = m+2n | m-n | \leq 1\} \subset$ $(s_{2} \times s_{3} \times s_{6} \times \dots \times s_{k} \times \dots$

Then \mathfrak{S} has all sequested properties. The corresponding equivalence relation $\sim_k \quad k \in \mathcal{J}$ are the relations of diametrally opposite points on S_k . The factor relation $\mathfrak{S} / (\sim_k)_{k \in \mathcal{Y}}$ is isotopic to

$$\left\{ (X_{l})_{l \in \mathbb{N}} \middle| |X_{1}| = 2 , |X_{2}| = 3, \dots, |X_{l}| = 2^{m} \cdot 3^{n} , \dots \right.$$

$$x_{l} = x_{1}^{m} \cdot x_{2}^{n} \quad \text{if} \quad l = m+2n \quad |m-n| \leq 1 \quad m, n \in \mathbb{N} \cup \left\{ 0 \right\} .$$

Now we make a system of three-basic groupoids. $((S_2, S_3, S_k, \cdot_k)_k \in \mathcal{Y}), \cdot k$ is defined the following way: $s_l = s_1 \cdot_k s_2 \iff s_l = s_1^m \cdot s_2^n, s_1 \in S_2, s_2 \in S_3, s_l \in S_k,$ $l = m+2n |m-n| \leq 1, \cdot is product of complex numbers.$

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O JEDNOM ZOBECNĚNÍ TKÁNÍ

Souhrn

V článku se zavádí pojem obecné tkáně a k ní příslušného algebraického protějšku – přípustné relace. Specielně kartézským tkáním odpovídají tzv. tříbázové grupoidy. Ukazuje se, že třída regulárních řešitelných tkání je významná tím, že každou její tkáň je možno epimorfně zobrazit na klasickou tkáň.

ОБ ОДНОМ ОБОБЩЕНИИ СЕТЕЙ

Резюме

Статья описывает понятие общей сети и соответствующего алгебраического выражения. Показывается класс сетей, которые отображаются помощью эпиморфизма на классические сети.

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