# Acta Universitatis Palackianae Olomucensis. Facultas Rerum Naturalium. Mathematica 

## Lubomír Kubáček; Eva Tesaříková Weakly nonlinear constraints in regression models

Acta Universitatis Palackianae Olomucensis. Facultas Rerum Naturalium. Mathematica, Vol. 41 (2002), No. 1, 67--81

Persistent URL: http://dml.cz/dmlcz/120456

## Terms of use:

© Palacký University Olomouc, Faculty of Science, 2002

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.


This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project DML-CZ: The Czech Digital Mathematics Library http://project.dml.cz

# Weakly Nonlinear Constraints in Regression Models 

Lubomír KUBÃCEK ${ }^{1}$, Eva TESAŘíkOVA ${ }^{2}$<br>${ }^{1}$ Department of Mathematical Analysis and Applications of Mathematics<br>Faculty of Science, Palacký University<br>Tomkova 40, 77900 Olomouc, Czech Republic<br>e-mail: kubacekl@risc.upol.cz<br>${ }^{2}$ Department of Algebra and Geometry, Faculty of Science, Palacky University<br>Tomkova 40, 77900 Olomouc, Czech Republic<br>e-mail: tesariko@risc.upol.cz

(Received January 31, 2002)


#### Abstract

Linear estimators in nonlinear regression models with nonlinear constraints can suffer more or less mainly by bias. The quadratic corrections can help however not in every situation. Some numerical studies of the problem are presented in the paper.


Key words: Nonlinear regression model, nonlinear constraints, linearization, quadratization.
2000 Mathematics Subject Classification: 62J05, 62F10

## 0 Introduction

Nonlinear regression models with nonlinear constraints create problems in a construction of estimators. Standard method of a linearization can lead to nonnegligible bias and can also worsen other properties of estimators. It seems that quadratic corrections should make estimators better. It is really so as far as the bias is concerned. However a quadratic term can produce a large dispersion

[^0]such that the mean square error characterization of the linear estimator can be better than the mean square error of the quadratic estimator. A theoretical basis for such an investigation is given in [3], however no numerical results are given there. Therefore a follow-up to that paper from the numerical viewpoint is presented here. ${ }^{1}$

## 1 Notation

The considered model is given in the form

$$
\begin{equation*}
\mathbf{Y} \sim N_{n}(\mathbf{f}(\boldsymbol{\beta}), \boldsymbol{\Sigma}), \quad \beta \in \mathcal{V}=\{\beta: \mathbf{g}(\beta)=\mathbf{0}\} \tag{1}
\end{equation*}
$$

Here $\mathbf{Y}$ is a normally distributed $n$-dimensional random vector with the mean value equal to $\mathbf{f}(\boldsymbol{\beta})=\left(f_{1}(\boldsymbol{\beta}), \ldots, f_{n}(\boldsymbol{\beta})\right)^{\prime}$ and with the covariance matrix $\boldsymbol{\Sigma}$. The $k$-dimensional vector $\beta$ is unknown and the parameter space is $\mathcal{V}$. The $q$-dimensional function $\mathbf{g}(\cdot)$ can be expressed as $\mathbf{g}\left(\boldsymbol{\beta}^{(0)}\right)+\mathbf{G} \delta \boldsymbol{\beta}+\frac{1}{2} \gamma(\delta \beta)$, where $\beta^{(0)}$ is an approximate value of the actual value $\beta^{*}$ of the vector $\beta$ and $\delta \beta=\beta-$ $\boldsymbol{\beta}^{(0)}$. The $q \times k$ matrix $\mathbf{G}$ is $\partial \mathbf{g}(\mathbf{u}) /\left.\partial \mathbf{u}^{\prime}\right|_{u=\beta^{(0)}}, \gamma(\delta \boldsymbol{\beta})=\left(\delta \beta^{\prime} \mathbf{G}_{1} \delta \beta \ldots, \delta \boldsymbol{\beta}^{\prime} \mathbf{G}_{q} \delta \boldsymbol{\beta}\right)^{\prime}$, $\mathbf{G}_{i}=\partial^{2} g_{i}(\mathbf{u}) /\left.\partial \mathbf{u} \partial \mathbf{u}^{\prime}\right|_{u=\beta^{(0)}}, i=1, \ldots, q$. Further it is assumed that the function $\mathbf{f}(\cdot)$ can be expressed analogously, i.e.

$$
\mathbf{f}(\boldsymbol{\beta})=\mathbf{f}\left(\boldsymbol{\beta}^{(0)}\right)+\mathbf{F} \delta \boldsymbol{\beta}+\frac{1}{2} \kappa(\delta \boldsymbol{\beta}), \quad \kappa(\delta \boldsymbol{\beta})=\left(\delta \boldsymbol{\beta}^{\prime} \mathbf{F}_{1} \delta \boldsymbol{\beta}, \ldots, \delta \boldsymbol{\beta}^{\prime} \mathbf{F}_{n} \delta \boldsymbol{\beta}\right)^{\prime}
$$

Here

$$
\mathbf{F}=\partial \mathbf{f}(\mathbf{u}) /\left.\partial \mathbf{u}^{\prime}\right|_{u=\beta^{(0)}}, \quad \mathbf{F}_{i}=\partial^{2} f_{i}(\mathbf{u}) /\left.\partial \mathbf{u} \partial \mathbf{u}^{\prime}\right|_{u=\beta^{(0)}}, \quad i=1, \ldots, n
$$

In the following the vector $\mathbf{g}\left(\beta^{(0)}\right)$ is assumed to be zero vector (in more detail cf. [2]).

The linearized version of the model (1) is

$$
\begin{equation*}
\mathbf{Y}-\mathbf{f}_{0} \sim N_{n}(\mathbf{F} \delta \beta, \boldsymbol{\Sigma}), \quad \mathbf{G} \delta \beta=0 \tag{2}
\end{equation*}
$$

where $\mathbf{f}_{0}=\mathbf{f}\left(\boldsymbol{\beta}^{(0)}\right)$ and the quadratized version of the model (1) is

$$
\begin{equation*}
\mathbf{Y}-\mathbf{f}_{0} \sim N_{n}\left(\mathbf{F} \delta \beta+\frac{1}{2} \kappa(\delta \beta), \boldsymbol{\Sigma}\right), \quad \mathbf{G} \delta \boldsymbol{\beta}+\frac{1}{2} \gamma(\delta \boldsymbol{\beta})=\mathbf{0} . \tag{3}
\end{equation*}
$$

## 2 Linear estimator and its bias

In what follows it is assumed that the rank $r(\mathbf{F})$ of the matrix $\mathbf{F}$ is $k<n$, $r(\mathbf{G})=q<k$ and the matrix $\boldsymbol{\Sigma}$ is positive definite. Under these assumptions the following statements are valid.

[^1]Statement 2.1 The best linear unbiased estimator $\delta \hat{\hat{\beta}}$ in (2) is

$$
\begin{align*}
\delta \hat{\hat{\boldsymbol{\beta}}} & =\left[\mathbf{I}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G}\right] \delta \hat{\boldsymbol{\beta}} \\
& \sim N_{k}\left(\delta \boldsymbol{\beta}, \mathbf{C}^{-1}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G C}^{-1}\right) \tag{4}
\end{align*}
$$

where $\mathbf{C}=\mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1} \mathbf{F}, \quad \delta \hat{\boldsymbol{\beta}}=\mathbf{C}^{-1} \mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1}\left(\mathbf{Y}-\mathbf{f}_{0}\right)$ (the best linear unbiased estimator in the model (2) when the constraints $\mathbf{G} \delta \boldsymbol{\beta}=\mathbf{0}$ are neglected).
Proof cf. [2].
Statement 2.2 The bias of the estimator (4) in the model (3) is

$$
\begin{align*}
E(\delta \hat{\tilde{\boldsymbol{\beta}}})-\delta \beta & =\mathbf{b}=\frac{1}{2} \mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \gamma(\delta \beta) \\
& +\frac{1}{2}\left[\mathbf{I}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G}\right] \mathbf{C}^{-1} \mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1} \kappa(\delta \boldsymbol{\beta}) \tag{5}
\end{align*}
$$

Proof cf. [2].
It is quite clear from the relationship (5) how the nonlinearity of the constraints influences the bias of the linear estimator.

The bias from Statement 2.2, i.e. the nonlinear terms in (3) can be neglected, if it is known that the shift $\delta \beta^{*}=\beta^{*}-\beta^{(0)}\left(\boldsymbol{\beta}^{*}\right.$ is an actual value of the parameter $\beta$ in the experiment) is so small that it leads to the inequality $\sqrt{\mathbf{b}^{\prime} \mathbf{C b}}<\varepsilon$ for sufficiently small $\varepsilon>0$.
Statement 2.3 The set

$$
\left\{\beta \in R^{k}:\left\|\mathbf{P}_{F(\beta)}^{\Sigma^{-1}}[\mathbf{Y}-\mathbf{f}(\beta)]\right\|_{\Sigma^{-1}}^{2} \leq \chi_{k}^{2}(1-\alpha)\right\}
$$

is a $(1-\alpha)$-confidence region in the model $\mathbf{Y} \sim N_{n}\left[\mathbf{f}(\boldsymbol{\beta}), \boldsymbol{\Sigma}^{-1}\right]$. Here $\mathbf{P}_{F(\boldsymbol{\beta})}^{\Sigma^{-1}}$ is the projection matrix in the Mahalanobis norm $\|\mathbf{x}\|_{\Sigma^{-1}}=\sqrt{\mathbf{x}^{\prime} \boldsymbol{\Sigma}^{-1} \mathbf{x}}, \mathbf{x} \in R^{n}$, on the column space of the matrix $\mathbf{F}(\boldsymbol{\beta})=\partial \mathbf{f}(\mathbf{u}) /\left.\partial \mathbf{u}\right|_{u=\beta}$.
Proof cf. Proposition 2.6.1 in [4].
Statement 2.4 in the model

$$
\begin{equation*}
\mathbf{Y} \sim N_{n}(\mathbf{f}(\boldsymbol{\beta}), \boldsymbol{\Sigma}), \quad \mathbf{g}(\boldsymbol{\beta})=\mathbf{0} \tag{6}
\end{equation*}
$$

the $(1-\alpha)$-confidence region is

$$
\left\{\beta: \mathbf{g}(\boldsymbol{\beta})=\mathbf{0},[\mathbf{Y}-\mathbf{f}(\boldsymbol{\beta})]^{\prime} \mathbf{U}[\mathbf{Y}-\mathbf{f}(\beta)] \leq \chi_{k-q}^{2}(1-\alpha)\right\}
$$

where

$$
\begin{aligned}
\mathbf{U} & =\boldsymbol{\Sigma}^{-1} \mathbf{F}(\boldsymbol{\beta}) \operatorname{Var}(\hat{\hat{\boldsymbol{\beta}}}) \mathbf{F}^{\prime}(\boldsymbol{\beta}) \boldsymbol{\Sigma}^{-1} \\
\mathbf{F}(\boldsymbol{\beta}) & =\partial \mathbf{f}(\boldsymbol{\beta}) / \partial \boldsymbol{\beta}^{\prime} \\
\mathbf{C}(\boldsymbol{\beta}) & =\mathbf{F}^{\prime}(\boldsymbol{\beta}) \boldsymbol{\Sigma}^{-1} \mathbf{F}(\boldsymbol{\beta}), \\
\operatorname{Var}(\hat{\tilde{\boldsymbol{\beta}}}) & =\mathbf{C}^{-1}(\boldsymbol{\beta})-\mathbf{C}^{-1}(\boldsymbol{\beta}) \mathbf{G}^{\prime}(\boldsymbol{\beta})\left[\mathbf{G}(\boldsymbol{\beta}) \mathbf{C}^{-1}(\boldsymbol{\beta}) \mathbf{G}^{\prime}(\boldsymbol{\beta})\right]^{-1} \mathbf{G}(\boldsymbol{\beta}) \mathbf{C}^{-1}(\boldsymbol{\beta}), \\
\mathbf{G}(\boldsymbol{\beta}) & =\partial \mathbf{g}(\boldsymbol{\beta}) / \partial \boldsymbol{\beta}^{\prime}
\end{aligned}
$$

Proof The projection matrix on the tangential space at the point $\mathbf{f}(\boldsymbol{\beta})$ of the mean value manifold $\{\mathbf{f}(\beta): \mathbf{g}(\beta)=\mathbf{0}\}$ of the model (6) is

$$
\begin{aligned}
\mathbf{P}_{F(\beta) M_{G^{\prime}(\beta)}}^{\Sigma^{-1}} & =\mathbf{F}(\beta) \mathbf{M}_{G^{\prime}(\beta)}\left[\mathbf{M}_{G^{\prime}(\beta)} \mathbf{C}(\beta) \mathbf{M}_{G^{\prime}(\beta)}\right]^{+} \mathbf{M}_{G^{\prime}(\beta)} \mathbf{F}^{\prime}(\boldsymbol{\beta}) \Sigma^{-1} \\
& =\mathbf{F}(\boldsymbol{\beta}) \operatorname{Var}(\hat{\hat{\boldsymbol{\beta}}}) \mathbf{F}^{\prime}(\boldsymbol{\beta}) \Sigma^{-1}
\end{aligned}
$$

where $\mathbf{M}_{G^{\prime}(\beta)}=\mathbf{I}-\mathbf{P}_{G^{\prime}(\beta)}$ and $\mathbf{P}_{G^{\prime}(\beta)}$ is the projection matrix in the Euclidean norm on the column space of the matrix $\mathbf{G}^{\prime}(\boldsymbol{\beta})$ and $\left[\mathbf{M}_{G^{\prime}(\beta)} \mathbf{C}(\boldsymbol{\beta}) \mathbf{M}_{G^{\prime}(\beta)}\right]^{+}$is the Moore-Penrose generalized inverse of the matrix $\mathbf{M}_{G^{\prime}(\beta)} \mathbf{C}(\beta) \mathrm{M}_{G^{\prime}(\beta)}$ (cf. [5]). Now it is sufficient to use Statement 2.3.

Thus if

$$
\begin{equation*}
\left[\mathbf{Y}-\mathbf{f}\left(\boldsymbol{\beta}^{(0)}\right)\right]^{\prime} \boldsymbol{\Sigma}^{-1} \mathbf{F} \operatorname{Var}(\hat{\boldsymbol{\beta}}) \mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1}\left[\mathbf{Y}-\mathbf{f}\left(\boldsymbol{\beta}^{(0)}\right)\right] \leq \chi_{k-q}^{2}(1-\alpha) \tag{7}
\end{equation*}
$$

then $\boldsymbol{\beta}^{(0)}$ is covered by the $(1-\alpha)$-confidence region for $\boldsymbol{\beta}^{*}$. The actual value $\boldsymbol{\beta}^{*}$ is covered by the $(1-\alpha)$-confidence ellipsoid

$$
\mathcal{E}=\left\{\mathbf{u}:(\mathbf{u}-\hat{\hat{\boldsymbol{\beta}}})^{\prime}[\operatorname{Var}(\hat{\hat{\boldsymbol{\beta}}})]^{-}(\mathbf{u}-\hat{\hat{\boldsymbol{\beta}}}) \leq \chi_{r[\operatorname{Var}(\hat{\hat{\boldsymbol{\beta}}})]}^{2}(1-\alpha)\right\}
$$

(if the linearization is possible)). Since the matrix $\mathbf{C}$ is one version of the $g$-inverse of the matrix $\operatorname{Var}(\hat{\hat{\boldsymbol{\beta}}})$ and $r[\operatorname{Var}(\hat{\hat{\boldsymbol{\beta}}})]=k-q$,

$$
\mathcal{E}=\left\{\mathbf{u}:(\mathbf{u}-\hat{\hat{\boldsymbol{\beta}}})^{\prime} \mathbf{C}(\mathbf{u}-\hat{\hat{\boldsymbol{\beta}}}) \leq \chi_{k-q}^{2}(1-\alpha)\right\} .
$$

In an addition the following statement is valid.
Statement 2.5 Let $\mathbf{K}_{G}$ be a $k \times(k-q)$ matrix with the property

$$
\mathcal{M}\left(\mathbf{K}_{G}\right)=\left\{\mathbf{K}_{G} \mathbf{u}: \mathbf{u} \in R^{k-q}\right\}=\operatorname{Ker}(\mathbf{G})=\{\mathbf{v}: \mathbf{G} \mathbf{v}=\mathbf{0}\}
$$

and let

$$
C_{I, \delta \beta}^{(p a r)}=\sup \left\{\frac{\sqrt{A+B}}{\mathbf{u}^{\prime} \mathbf{K}_{G}^{\prime} \mathbf{C K}_{G} \mathbf{u}}: \mathbf{u} \in R^{k-q}\right\}
$$

where

$$
\begin{aligned}
A= & \boldsymbol{\kappa}^{\prime}\left(\mathbf{K}_{G} \mathbf{u}\right) \boldsymbol{\Sigma}^{-1} \mathbf{P}_{F K_{G}}^{\Sigma^{-1}} \kappa\left(\mathbf{K}_{G} \mathbf{u}\right), \\
B= & \gamma^{\prime}\left(\mathbf{K}_{G} \mathbf{u}\right)\left(\mathbf{G C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \gamma\left(\mathbf{K}_{G} \mathbf{u}\right), \\
\mathbf{P}_{F K_{G}}^{\Sigma^{-1}}= & \mathbf{F K}_{G}\left(\mathbf{K}_{G}^{\prime} \mathbf{C K}_{G}\right)^{-1} \mathbf{K}_{G}^{\prime} \mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1} \quad \text { (projection matrix on } \\
& \left.\mathcal{M}\left(\mathbf{F} \mathbf{K}_{G}\right) \text { in the norm }\|\mathbf{u}\|_{\Sigma^{-1}}=\sqrt{\mathbf{u}^{\prime} \mathbf{\Sigma}^{-1} \mathbf{u}}\right) .
\end{aligned}
$$

If

$$
\delta \boldsymbol{\beta} \in\left\{\mathbf{K}_{G} \mathbf{u}: \mathbf{u}^{\prime} \mathbf{K}_{G}^{\prime} \mathbf{C K}_{G} \mathbf{u} \leq \frac{2 \varepsilon}{\mathrm{C}_{I, \delta \beta}^{(p a r)}}\right\}
$$

then

$$
\forall\left\{\mathbf{h} \in R^{k}\right\}\left|\mathbf{h}^{\prime} \mathbf{b}\right| \leq \varepsilon \sqrt{\mathbf{h}^{\prime} \mathbf{C}^{-1} \mathbf{h}}
$$

Proof cf. in [2].
Now if $\chi_{k-q}^{2}(1-\alpha) \ll 2 \varepsilon / C_{I, \delta \beta}^{(p a r)}$, the model (6) can be linearized (with respect to the bias) at the point $\boldsymbol{\beta}^{(0)}$. However we need the linearization at the point $\beta^{*}$ which is unknown. If $\beta^{(0)}$ is chosen in such a way that (7) is satisfied, then $\boldsymbol{\beta}^{*}$ is in the neighbourhood of the point $\boldsymbol{\beta}^{(0}$. It can be assumed that the property "can be linearized" does not change in a small neighbourhood of a point of the parametric space $\mathcal{V}$. It would be better to investigate such a neighbourhood in more detail, however in practice it is sufficient to fulfil two conditions

$$
\begin{equation*}
\chi_{k-q}^{2}(1-\alpha) \ll \frac{2 \varepsilon}{C_{I, \delta \beta}^{(p a r)}} \text { and } \tag{7}
\end{equation*}
$$

Since $\mathbf{h}^{\prime} \mathbf{b}=E\left(\mathbf{h}^{\prime} \delta \hat{\tilde{\boldsymbol{\beta}}}\right)-\mathbf{h}^{\prime} \delta \boldsymbol{\beta}$ and

$$
\operatorname{Var}\left(\mathbf{h}^{\prime} \delta \hat{\tilde{\boldsymbol{\beta}}}\right)=\mathbf{h}^{\prime}\left[\mathbf{C}^{-1}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G} \mathbf{C}^{-1}\right] \mathbf{h} \leq \mathbf{h}^{\prime} \mathbf{C}^{-1} \mathbf{h}
$$

Statement 2.3 enables us to choose for a given vector

$$
\mathbf{h} \in \mathcal{M}\left(\mathbf{C}^{-1}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G C}^{-1}\right)
$$

the value of $\varepsilon$ in such a way that

$$
\left|\mathbf{h}^{\prime} \mathbf{b}\right| \leq \varepsilon_{1} \sqrt{\mathbf{h}^{\prime}\left[\mathbf{C}^{-1}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G C ^ { - 1 }} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G C ^ { - 1 } ] \mathbf { h }}\right.}
$$

i.e. $\varepsilon=\varepsilon_{1} \sqrt{\mathbf{h}^{\prime}\left[\mathbf{C}^{-1}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G C} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G C} \mathbf{C}^{-1}\right] \mathbf{h}} / \sqrt{\mathbf{h}^{\prime} \mathbf{C}^{-1} \mathbf{h}}$. A comparison of the bias with the standard deviation is of no sense in the case

$$
\mathbf{h} \perp \mathcal{M}\left(\mathbf{C}^{-1}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G C}^{-1}\right)
$$

since in this case $\mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{h}=0$. Thus, for practical purposes, a comparison with $\sqrt{\mathbf{h}^{\prime} \mathbf{C}^{-1} \mathbf{h}}$ seems to be reasonable.

Remark 2.6 The model (3) can be, in some sense, represented by the model without constraints

$$
\mathbf{Y}-\mathbf{f}_{0} \sim N_{n}\left(\mathbf{F K}_{G} \delta \mathbf{u}+\frac{1}{2}\left[\boldsymbol{\kappa}\left(\mathbf{K}_{g} \delta \mathbf{u}\right)-\mathbf{F G}_{m(C)}^{-} \gamma\left(\mathbf{K}_{G} \delta \mathbf{u}\right)\right], \boldsymbol{\Sigma}\right), \quad \delta \mathbf{u} \in R^{k-q} .
$$

Then the Bates and Watts measures of nonlinearity (cf. [1]) are

$$
\begin{aligned}
K_{I}^{(i n t)} & =\sup \left\{\frac{\sqrt{\mathbf{k}^{\prime} \mathbf{\Sigma}^{-1} \mathbf{M}_{F K_{G}}^{\Sigma-1} \mathbf{k}}}{\delta \mathbf{u}^{\prime} \mathbf{K}_{G}^{\prime} \mathbf{C K} \mathbf{K}_{G} \delta \mathbf{u}}: \delta \mathbf{u} \in R^{k-q}\right\} \\
& =\sup \left\{\frac{\sqrt{\mathbf{k}^{\prime} \mathbf{\Sigma}^{-1} \mathbf{k}-\boldsymbol{\kappa}^{\prime}\left(\mathbf{K}_{G} \delta \mathbf{u}\right) \boldsymbol{\Sigma}^{-1} \mathbf{P}_{F K_{G}}^{\Sigma-1} \kappa\left(\mathbf{K}_{G} \delta \mathbf{u}\right)}}{\delta \mathbf{u}^{\prime} \mathbf{K}_{G}^{\prime} \mathbf{C K}_{G} \delta \mathbf{u}}: \delta \mathbf{u} \in R^{k-q}\right\}
\end{aligned}
$$

and

$$
\begin{aligned}
K_{I}^{(p a r)} & =\sup \left\{\frac{\sqrt{\mathbf{k}^{\prime} \Sigma^{-1} \mathbf{P}_{F K_{G}}^{\Sigma^{-1}} \mathbf{k}}}{\delta \mathbf{u}^{\prime} \mathbf{K}_{G}^{\prime} \mathbf{C K}_{G} \delta \mathbf{u}}: \delta \mathbf{u} \in R^{k-q}\right\} \\
& =\sup \left\{\frac{\sqrt{\kappa^{\prime}\left(\mathbf{K}_{G} \delta \mathbf{u}\right) \Sigma^{-1} \mathbf{P}_{F K_{G}}^{\Sigma^{-1}} \boldsymbol{\kappa}\left(\mathbf{K}_{G} \delta \mathbf{u}\right)}}{\delta \mathbf{u}^{\prime} \mathbf{K}_{G}^{\prime} \mathbf{C K}_{G} \delta \mathbf{u}}: \delta \mathbf{u} \in R^{k-q}\right\},
\end{aligned}
$$

where $\mathbf{k}=\boldsymbol{\kappa}\left(\mathbf{K}_{G} \delta \mathbf{u}\right)-\mathbf{F G}_{m(C)}^{-} \gamma\left(\mathbf{K}_{G} \delta \mathbf{u}\right)$.
These measures can be used in an investigation of other statistical properties of the model (3). In more detail cf. [2].

## 3 A quadratic correction of the linear estimator

If the two conditions (8) from the end of the preceding section are not satisfied, the bias can be eliminated by a quadratic correction, i.e. the estimator

$$
\begin{align*}
\delta \tilde{\tilde{\boldsymbol{\beta}}}= & \delta \hat{\hat{\boldsymbol{\beta}}}-\frac{1}{2}\left[\mathbf{I}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G}\right] \mathbf{C}^{-1} \mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1} \boldsymbol{\kappa}(\delta \hat{\hat{\boldsymbol{\beta}}}) \\
& -\frac{1}{2} \mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \gamma(\delta \hat{\hat{\boldsymbol{\beta}}}) \\
& +\frac{1}{2}\left[\mathbf{I}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G}\right] \mathbf{C}^{-1} \mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1}\left(\begin{array}{c}
\operatorname{Tr}\left[\mathbf{F}_{1} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right] \\
\vdots \\
\operatorname{Tr}\left[\mathbf{F}_{n} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right]
\end{array}\right) \\
& +\frac{1}{2} \mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1}\left(\begin{array}{c}
\operatorname{Tr}\left[\mathbf{G}_{1} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right] \\
\vdots \\
\operatorname{Tr}\left[\mathbf{G}_{q} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right]
\end{array}\right) \tag{9}
\end{align*}
$$

can be used. Some caution is necessary, since quadratic terms in the estimator can produce a nonnegligible enlargement of the variance. Some comments to it are given in the following text.

Since

$$
\begin{aligned}
& \mathbf{G} \delta \tilde{\tilde{\boldsymbol{\beta}}}+\frac{1}{2} \gamma(\delta \tilde{\tilde{\boldsymbol{\beta}}})=-\frac{1}{2} \gamma(\delta \hat{\hat{\boldsymbol{\beta}}})+\frac{1}{2}\left(\begin{array}{c}
\operatorname{Tr}\left[\mathbf{G}_{1} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right] \\
\vdots \\
\operatorname{Tr}\left[\mathbf{G}_{q} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right]
\end{array}\right)+\frac{1}{2} \gamma(\delta \tilde{\tilde{\boldsymbol{\beta}}}) \\
& =\frac{1}{2}\left(\begin{array}{c}
\operatorname{Tr}\left[\mathbf{G}_{1} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right] \\
\vdots \\
\operatorname{Tr}\left[\mathbf{G}_{q} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right]
\end{array}\right)+\text { terms of the 3th and higher order, }
\end{aligned}
$$

the estimator $\delta \tilde{\tilde{\boldsymbol{\beta}}}$ does not satisfy the constraints as far as the terms

$$
\operatorname{Tr}\left[\mathbf{G}_{i} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right], \quad i=1, \ldots, q
$$

are concerned. (It is to be said that the mean value of the estimator $\delta \tilde{\tilde{\beta}}$ from (9) satisfies the constraints $\mathbf{G} \delta \boldsymbol{\beta}+\frac{1}{2} \gamma(\delta \boldsymbol{\beta})=\mathbf{0}$.)

Now it is to be decided whether satisfying the constraints is more important than the bias due to the terms $\operatorname{Tr}\left[\mathbf{G}_{i} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right], \quad i=1, \ldots, q$. In practice satisfying the constraints is preferred. Thus in the following, the estimator

$$
\begin{aligned}
\delta \overline{\overline{\boldsymbol{\beta}}}= & \delta \hat{\hat{\boldsymbol{\beta}}}-\frac{1}{2}\left[\mathbf{I}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G}\right] \mathbf{C}^{-1} \mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1} \boldsymbol{\kappa}(\delta \hat{\hat{\boldsymbol{\beta}}}) \\
& -\frac{1}{2} \mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \gamma(\delta \hat{\hat{\boldsymbol{\beta}}}) \\
& +\frac{1}{2}\left[\mathbf{I}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G}\right] \mathbf{C}^{-1} \mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1}\left(\begin{array}{c}
\operatorname{Tr}\left[\mathbf{F}_{1} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right] \\
\vdots \\
\operatorname{Tr}\left[\mathbf{F}_{n} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right]
\end{array}\right)
\end{aligned}
$$

will be also considered.
Let $h(\delta \boldsymbol{\beta})=\mathbf{h}^{\prime} \delta \boldsymbol{\beta}$, where $\mathbf{h} \in R^{k}$ be given vector. Then the notation

$$
\begin{aligned}
\mathbf{F}_{h(\cdot)} & =\sum_{i=1}^{n}\left\{\mathbf{h}^{\prime} \frac{1}{2}\left[\mathbf{I}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G}\right] \mathbf{C}^{-1} \mathbf{F}^{\prime} \boldsymbol{\Sigma}^{-1}\right\}_{i} \mathbf{F}_{i} \\
\mathbf{G}_{h(\cdot)} & =\sum_{i=1}^{q}\left\{\mathbf{h}^{\prime} \frac{1}{2} \mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1}\right\}_{i} \mathbf{G}_{i}
\end{aligned}
$$

will be used. Let $\mathbf{e}_{j} \in R^{k}$ and $\left\{\mathbf{e}_{j}\right\}_{i}=\delta_{i, j}$ (the Kronecker delta). Then

$$
E(\delta \hat{\hat{\boldsymbol{\beta}}})-\delta \boldsymbol{\beta}=\mathbf{b}=\left(\begin{array}{c}
\delta \boldsymbol{\beta}^{\prime} \mathbf{A}_{1} \delta \boldsymbol{\beta} \\
\vdots \\
\delta \beta^{\prime} \mathbf{A}_{k} \delta \beta
\end{array}\right)
$$

where

$$
\mathbf{A}_{i}=\mathbf{F}_{e_{i}(\cdot)}+\mathbf{G}_{e_{i}(\cdot)}, \quad i=1, \ldots, k
$$

Thus

$$
\begin{aligned}
& \left|E\left(\mathbf{h}^{\prime} \delta \hat{\hat{\boldsymbol{\beta}}}\right)-\mathbf{h}^{\prime} \delta \boldsymbol{\beta}\right|=\left|\delta \boldsymbol{\beta}^{\prime} \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta}\right|, \quad \mathbf{A}_{h(\cdot)}=\sum_{i=1}^{k}\{\mathbf{h}\}_{i} \mathbf{A}_{i}, \\
& \left|E\left(\mathbf{h}^{\prime} \delta \overline{\overline{\boldsymbol{\beta}}}\right)-\mathbf{h}^{\prime} \delta \boldsymbol{\beta}\right|=\left|\operatorname{Tr}\left[\mathbf{G}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right]+2 \mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta}+\mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \mathbf{b}\right|
\end{aligned}
$$

and

$$
M S E\left(\mathbf{h}^{\prime} \delta \hat{\hat{\boldsymbol{\beta}}}\right)=\mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{h}+\left[E\left(\mathbf{h}^{\prime} \delta \hat{\hat{\boldsymbol{\beta}}}\right)-\mathbf{h}^{\prime} \delta \boldsymbol{\beta}\right]^{2}
$$

$$
\begin{aligned}
M S E\left(\mathbf{h}^{\prime} \delta \overline{\overline{\boldsymbol{\beta}}}\right)= & \mathbf{h}^{\prime} \operatorname{Var}(\delta \overline{\overline{\boldsymbol{\beta}}}) \mathbf{h}+\left[E\left(\mathbf{h}^{\prime} \delta \overline{\overline{\boldsymbol{\beta}}}\right)-\mathbf{h}^{\prime} \delta \boldsymbol{\beta}\right]^{2} \\
\mathbf{h}^{\prime} \operatorname{Var}(\delta \overline{\overline{\boldsymbol{\beta}}}) \mathbf{h}= & \mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})+2 \operatorname{Tr}\left\{\left[\mathbf{A}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right]^{2}\right\} \\
& -4 \mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta}-4 \mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{A}_{h(\cdot)} \mathbf{b} \\
& +4 \delta \boldsymbol{\beta}^{\prime} \mathbf{A}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta} \\
& +8 \mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta} \\
& +4 \mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{A}_{h(\cdot)} \mathbf{b} .
\end{aligned}
$$

If the estimator $\mathbf{h}^{\prime} \delta \overline{\overline{\boldsymbol{\beta}}}$ is used, it is necessary to check whether the ratio

$$
\begin{equation*}
\operatorname{Tr}\left[\mathbf{G}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right] / \sqrt{\mathbf{h}^{\prime}\left[\mathbf{C}^{-1}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G} \mathbf{C}^{-1}\right] \mathbf{h}} \tag{10}
\end{equation*}
$$

is sufficiently small.

## 4 Numerical examples

Example 4.1 Let

$$
\begin{gathered}
f(x)= \begin{cases}l_{1}\left(x ; \beta_{1}, \beta_{2}\right)=\beta_{1}+\beta_{2} x, & x \leq 0 \\
l_{2}\left(x ; \beta_{1}, \beta_{3}\right)=\beta_{1} \exp \left(\beta_{3} x\right), & x \geq 0\end{cases} \\
g\left(\beta_{1}, \beta_{2}, \beta_{3}\right)=\partial l_{2}\left(x ; \beta_{1}, \beta_{3}\right) /\left.\partial x\right|_{x=0}-\partial l_{1}\left(x ; \beta_{1}, \beta_{2}\right) /\left.\partial x\right|_{x=0}=\beta_{1} \beta_{3}-\beta_{2}=0, \\
\beta_{1}=5, \quad \beta_{2}=-4, \quad \beta_{3}=-0.8
\end{gathered}
$$

The values $\beta_{1}, \beta_{2}$ and $\beta_{3}$ are chosen as $\beta_{1}^{(0)}, \beta_{2}^{(0)}$ and $\beta_{3}^{(0)}$, respectively.

| $x$ | -3 | -2 | -1 | 1 | 2 | 3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $l_{1}(x)$ | 17 | 13 | 9 |  |  |  |
| $l_{2}(x)$ |  |  |  | 2.247 | 1.009 | 0.454 |
| $y$ | 17.1 | 12.8 | 8.9 | 2.3 | 1.1 | 0.4 |

$$
\begin{gathered}
\operatorname{Var}(\mathbf{Y})=\sigma^{2} \mathbf{I}_{6,6}, \quad \beta_{1}^{(0)}=5, \quad \beta_{2}^{(0)}=-4, \quad \beta_{3}^{(0)}=-0.8 \\
\partial l_{1}\left(x, \beta_{1}, \beta_{2}, \beta_{3}\right) / \partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right)=(1, x, 0) \\
\partial l_{2}\left(x, \beta_{1}, \beta_{2}, \beta_{3}\right) / \partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right)=\left(\exp \left(\beta_{3} x\right), 0, \beta_{1} x \exp \left(\beta_{3} x\right)\right), \\
\partial g\left(\beta_{1}, \beta_{2}, \beta_{3}\right) / \partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right)=\left(\beta_{3},-1, \beta_{1}\right) .
\end{gathered}
$$

Let $\sigma=0.2, \mathbf{h}=(1,0,0)^{\prime}$. Then we obtain

$$
\mathbf{K}_{G}=\left(\begin{array}{r}
0.98791,0.00000 \\
-0.03040,0.98058 \\
0.15199,0.19612
\end{array}\right)
$$

$$
\begin{aligned}
\delta \hat{\boldsymbol{\beta}} & =(-0.23583,-0.086786,0.053987)^{\prime}, \\
\mathbf{C}^{-1} & =\left(\begin{array}{rr}
0.086383, & 0.037021,-0.012123 \\
0.037021, & 0.018723, \\
-0.012123, & -0.005196, \\
0.005345
\end{array}\right) \\
\delta \hat{\hat{\boldsymbol{\beta}}} & =(-0.01713,0.010692,-0.000602)^{\prime}, \\
\operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) & =\left(\begin{array}{c}
0.019518,0.007219,0.004567 \\
0.007219,0.005440,0.002243 \\
0.004567,0.002243,0.001178
\end{array}\right) \\
\mathbf{d} & =(0.1397,0.0738,0.0343)^{\prime}, \\
\delta \tilde{\tilde{\boldsymbol{\beta}}} & =(-0.01524,0.01154,0.00078)^{\prime} .
\end{aligned}
$$

Here

$$
\begin{equation*}
\left.\mathbf{d}=\left(\sqrt{\operatorname{Var}\left(\delta \hat{\hat{\beta}}_{1}\right.}\right), \sqrt{\operatorname{Var}\left(\delta \hat{\hat{\beta}}_{2}\right)}, \sqrt{\operatorname{Var}\left(\delta \hat{\hat{\beta}}_{3}\right)}\right)^{\prime} . \tag{11}
\end{equation*}
$$

Further

$$
K_{I}^{(p a r)}=0.104963, \quad C_{I, \delta \beta}^{(p a r)}=0.105101 .
$$

In this case

$$
\chi_{2}^{2}(0.95)=5.99<\frac{2 c}{C_{I, \delta \beta}^{(p a r)}}=\frac{1}{0.105101}=9.515 .
$$

Thus the linearization is possible.
The relationship (10) is
thus the term $\operatorname{Tr}\left[\mathbf{G}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right]$ can be neglected. Further

$$
\begin{array}{ll}
\mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{h}=0.019518, & M S E\left(\mathbf{h}^{\prime} \delta \hat{\hat{\beta}}\right)=0.019527 \\
\mathbf{h}^{\prime} \operatorname{Var}(\delta \tilde{\boldsymbol{\beta}}) \mathbf{h}=0.018197, & \operatorname{MSE}\left(\mathbf{h}^{\prime} \delta \tilde{\tilde{\beta}}\right)=0.018199
\end{array}
$$

Since $\hat{\hat{\boldsymbol{\beta}}}=(4.982870,-3.989308,-0.800602)^{\prime}$,

$$
\begin{aligned}
& l_{1}^{\prime}(0, \hat{\hat{\boldsymbol{\beta}}})=\partial l_{1}(x, \hat{\hat{\boldsymbol{\beta}}}) /\left.\partial x\right|_{x=0}=-3.989308 \\
& l_{2}^{\prime}(0, \hat{\hat{\boldsymbol{\beta}}})=\partial l_{2}(x, \hat{\hat{\beta}}) /\left.\partial x\right|_{x=0}=-3.989296
\end{aligned}
$$

and $\tilde{\tilde{\boldsymbol{\beta}}}=(4.984760,-3.988460,-0.799220)^{\prime}$,

$$
l_{1}^{\prime}(0, \tilde{\tilde{\beta}})=-3.988460, \quad l_{2}^{\prime}(0, \tilde{\tilde{\beta}})=-3.983920
$$

As far as the constraints are concerned the linear estimator seems to be a little better.

It can be of some interest to give the UBMSE (upper bounds for single terms of $M S E$ ). They are given in the following table for

$$
\delta \mathrm{s}_{1}=\binom{0.283}{0.000} \Rightarrow \delta \beta=\mathbf{K}_{G} \delta \mathrm{~s}_{1}=\left(\begin{array}{r}
0.280 \\
-0.009 \\
0.043
\end{array}\right)
$$

and

$$
\delta \mathbf{s}_{2}=\binom{0.000}{0.150} \Rightarrow \delta \beta=\mathbf{K}_{G} \delta \mathrm{~s}_{2}=\left(\begin{array}{c}
0.000 \\
0.147 \\
0.029
\end{array}\right)
$$

compare d (11).

| $\operatorname{term}$ | UBMSE $\left(\delta \mathbf{s}_{1}\right)$ | UBMSE $\left(\delta \mathbf{s}_{2}\right)$ |
| :---: | :---: | :---: |
| $\delta \boldsymbol{\beta}^{\prime} \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta}$ | 0.073296 | 0.067076 |
| $-4 \mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta}$ | 0.014021 | 0.013413 |
| $4 \delta \boldsymbol{\beta}^{\prime} \mathbf{A}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta}$ | 0.002518 | 0.002304 |
| $-4 \mathbf{h}^{\prime} \operatorname{Var}\left(\delta \hat{\hat{\boldsymbol{\beta}}} \mathbf{)} \mathbf{A}_{h(\cdot)} \mathbf{b}\right.$ | 0.002152 | 0.001970 |
| $8 \mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta}$ | 0.000773 | 0.000677 |
| $\left.4 \operatorname{Tr}^{[ } \mathbf{G}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right] \mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta}$ | 0.000168 | 0.000147 |
| $4 \mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) \mathbf{A}_{h(\cdot)} \mathbf{b}$ | 0.000059 | 0.000050 |
| $2 \operatorname{Tr}^{\prime}\left[\mathbf{G}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right] \mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \mathbf{b}$ | 0.000013 | 0.000011 |
| $4\left(\mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta}\right)^{2}$ | 0.000506 | 0.000388 |
| $4 \mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \delta \boldsymbol{\beta} \mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \mathbf{b}$ | 0.000078 | 0.000057 |
| $\left(\mathbf{b}^{\prime} \mathbf{A}_{h(\cdot)} \mathbf{b}\right)^{2}$ | 0.000003 | 0.000002 |

In the case $\sigma=0.2$ the linearization gives satisfactory results, even the quadratic estimator seems to be a little better. For $\mathbf{h}=(0,1,0)^{\prime}$ and $\mathbf{h}=$ $(0,0,1)^{\prime}$ we obtain similar results.

In the case $\sigma=0.5$

$$
K_{I}^{(p a r)}=0.262407 \text { and } C_{I, \delta \beta}^{(p a r)}=0.262752
$$

Thus

$$
\chi_{2}^{2}(0.95)=5.99>\frac{2 c}{C_{I, \delta \beta}^{(p a r)}}=\frac{1}{0.262752}=3.806
$$

and linearization cannot be recomended. Thus a decision must be made whether a more precise measurement can be organized or it is less tedious to investigate whether a utilization of quadratic corrections is reasonable with respect to $M S E$.

Example 4.2 Let

$$
\begin{aligned}
& f(x)=\left\{\begin{array}{ll}
l_{1}\left(x ; \beta_{1}\right)=\exp \left(\beta_{1} x\right), & x \leq 4, \\
l_{2}\left(x ; \beta_{2}, \beta_{3}\right)=\beta_{2} \exp \left[-\left(x-\beta_{3}\right)^{2}\right], & x \geq 4,
\end{array},\right. \\
& g_{1}\left(\beta_{1}, \beta_{2}, \beta_{3}\right)=l_{1}\left(4 ; \beta_{1}\right)-l_{2}\left(4 ; \beta_{2}, \beta_{3}\right)=\exp \left(4 \beta_{1}\right)-\beta_{2} \exp \left[-\left(4-\beta_{3}\right)^{2}\right]=0, \\
& g_{2}\left(\beta_{1}, \beta_{2}, \beta_{3}\right)=l_{1}^{\prime}\left(4 ; \beta_{1}\right)-l_{2}^{\prime}\left(4 ; \beta_{2}, \beta_{3}\right) \\
& =\partial l_{1}\left(x, \beta_{1}\right) /\left.\partial x\right|_{x=4}-\partial l_{2}\left(x, \beta_{2}, \beta_{3}\right) /\left.\partial x\right|_{x=4} \\
& =\beta_{1} \exp \left(4 \beta_{1}\right)+2 \beta_{2}\left(4-\beta_{3}\right) \exp \left[-\left(4-\beta_{3}\right)^{2}\right]=0, \\
& \beta_{1}=0.5, \quad \beta_{2}=7.865609, \quad \beta_{3}=4.25 .
\end{aligned}
$$

The values $\beta_{1}^{(0)}, \beta_{2}^{(0)}$ and $\beta_{3}^{(0)}$ are chosen as $\beta_{1}, \beta_{2}$ and $\beta_{3}$, respectively.

| $x$ | 1 | 2 | 3 | 5 | 6 | 7 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $l_{1}(x)$ | 1.649 | 2.718 | 4.482 |  |  |  |
| $l_{2}(x)$ |  |  |  | 4.482 | 0.368 | 0.004 |
| $y$ | 1.8 | 2.5 | 4.3 | 4.6 | 0.3 | 0 |

$$
\operatorname{Var}(\mathbf{Y})=\sigma^{2} \mathbf{I}_{6,6}, \quad \beta_{1}^{(0)}=0.5, \quad \beta_{2}^{(0)}=7.865609, \quad \beta_{3}^{(0)}=4.25
$$

$$
\begin{aligned}
\frac{\partial l_{1}\left(x, \beta_{1}\right)}{\partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right)}= & \left(x \exp \left(\beta_{1} x\right), 0,0\right), \\
\frac{\partial l_{2}\left(x, \beta_{2}, \beta_{3}\right)}{\partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right)}= & \left(0, \exp \left[-\left(x-\beta_{3}\right)^{2}\right], 2 \beta_{2}\left(x-\beta_{3}\right) \exp \left[-\left(x-\beta_{3}\right)^{2}\right]\right), \\
\frac{\partial g_{1}\left(\beta_{1}, \beta_{2}, \beta_{3}\right)}{\partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right)}= & \left(4 \exp \left(4 \beta_{1}\right),-\exp \left[-\left(4-\beta_{3}\right)^{2}\right],\right. \\
& \left.-2 \beta_{2}\left(4-\beta_{3}\right) \exp \left[-\left(4-\beta_{3}\right)^{2}\right]\right), \\
\frac{\partial g_{2}\left(\beta_{1}, \beta_{2}, \beta_{3}\right)}{\partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right)}= & \left(\left(1+4 \beta_{1}\right) \exp \left(4 \beta_{1}\right), 2\left(4-\beta_{3}\right) \exp \left[-\left(4-\beta_{3}\right)^{2}\right],\right. \\
& {\left.\left[-2 \beta_{2}+4 \beta_{2}\left(4-\beta_{3}\right)^{2}\right] \exp \left[-\left(4-\beta_{3}\right)^{2}\right]\right) . }
\end{aligned}
$$

Let $\boldsymbol{\Sigma}=\sigma^{2} \mathbf{I}, \sigma=0.2, \mathbf{h}=(1,0,0)^{\prime}$. Then we obtain

$$
\begin{aligned}
\mathbf{K}_{G} & =(0.029898,0.999440,0.014949)^{\prime} \\
K_{I}^{(p a r)} & =0.984855, \quad C_{I, \delta \beta}^{(p a r)}=1.945840 \\
\delta \mathbf{s} & =1 \quad \Rightarrow \quad \delta \beta=\mathbf{K}_{g} \delta \mathbf{s}=\left(\begin{array}{c}
0.029898 \\
0.999440 \\
0.014949
\end{array}\right), \\
\delta \hat{\boldsymbol{\beta}} & =(-0.015880,0.313440,-0.064269)^{\prime}
\end{aligned}
$$

$$
\left.\begin{array}{rl}
\mathbf{C}^{-1} & =\left(\begin{array}{rrr}
0.000188, & 0.000000, & 0.000000 \\
0.000000, & 0.495600, & -0.125430 \\
0.000000, & -0.125430, & 0.000916
\end{array}\right), \\
\delta \hat{\tilde{\beta}} & =(0.000931,0.031125,0.000466)^{\prime}, \\
\operatorname{Var}(\hat{\delta} \hat{\boldsymbol{\beta}}) & =\left(\begin{array}{l}
0.000009839, \\
0.000328900,000328900, \\
0.00000004919 \\
0.000004919,
\end{array}\right) 0.000164470,0.0000002458
\end{array}\right),
$$

In this case

$$
\chi_{1}^{2}(0.95)=3.84>\frac{2 c}{C_{I, \delta \beta}^{(p a r)}}=\frac{1}{1.945840}=0.5139
$$

Thus the linearization cannot be recomended.
Further

The term $\operatorname{Tr}\left[\mathbf{G}_{h(\cdot)} \operatorname{Var}(\delta \hat{\boldsymbol{\beta}})\right]$ can be neglected. Further

$$
\begin{aligned}
\mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\tilde{\boldsymbol{\beta}}}) \mathbf{h} & =0.000009839, \quad \operatorname{MSE}\left(\mathbf{h}^{\prime} \delta \hat{\tilde{\boldsymbol{\beta}}}\right)=0.000013894, \\
\mathbf{h}^{\prime} \operatorname{Var}(\delta \tilde{\tilde{\boldsymbol{\beta}}}) \mathbf{h} & =0.000007214, \quad \operatorname{MSE}\left(\mathbf{h}^{\prime} \delta \tilde{\tilde{\boldsymbol{\beta}}}\right)=0.000007304, \\
\mathbf{b} & =(0.002014,0.002061,0.001007)^{\prime} .
\end{aligned}
$$

Since $\hat{\hat{\boldsymbol{\beta}}}=(0.500931,7.896734,4.250476)^{\prime}$,

$$
\begin{array}{ll}
l_{1}(4, \hat{\hat{\boldsymbol{\beta}}})=7.416624, & l_{2}(4, \hat{\hat{\beta}})=7.400493 \\
l_{1}^{\prime}(4, \hat{\hat{\beta}})=3.715217, & l_{2}^{\prime}(4, \hat{\hat{\boldsymbol{\beta}}})=3.715325
\end{array}
$$

and $\tilde{\tilde{\beta}}=(0.500951,7.896755,4.250476)^{\prime}$,

$$
\begin{array}{ll}
l_{1}(4, \tilde{\tilde{\beta}})=7.417218, & l_{2}(4, \tilde{\tilde{\beta}})=7.416548 \\
l_{1}^{\prime}(4, \tilde{\tilde{\beta}})=3.715663, & l_{2}^{\prime}(4, \tilde{\tilde{\beta}})=3.715334
\end{array}
$$

In the cases $\mathbf{h}=(0,1,0)^{\prime}$ and $\mathbf{h}=(0,0,1)^{\prime}$ similar results are obtained. The model is nonlinear, however not weakly, mainly due to the constraints. The linearization is not suitable, however the quadratic estimation can be satisfactory. Also the constraints are satisfied a little better in the case of quadratic estimators than in the case of linear estimators.

## Example 4.3 Let

$$
\begin{aligned}
f(x) & = \begin{cases}l_{1}\left(x ; \beta_{1}\right)=\beta_{1} x, & x \leq 5, \\
l_{2}\left(x ; \beta_{2}, \beta_{3}\right)=\beta_{2} \exp \left(\beta_{3} x\right), & x \geq 5,\end{cases} \\
g\left(\beta_{1}, \beta_{2}, \beta_{3}\right) & =f_{1}\left(5 ; \beta_{1}\right)-f_{2}\left(5 ; \beta_{2}, \beta_{3}\right)=5 \beta_{1}-\beta_{2} \exp \left(\beta_{3} 5\right), \\
\beta_{1} & =1.473, \quad \beta_{2}=33, \quad \beta_{3}=-0.299954 .
\end{aligned}
$$

The values $\beta_{1}^{(0)}, \beta_{2}^{(0)}$ and $\beta_{3}^{(0)}$ are chosen as $\beta_{1}, \beta_{2}$ and $\beta_{3}$, respectively.

| $x$ | 1 | 2 | 3 | 6 | 7 | 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $l_{1}(x)$ | 1.473 | 2.945 | 4.418 |  |  |  |
| $l_{2}(x)$ |  |  |  | 5.455 | 4.041 | 2.994 |
| $y$ | 1.2 | 3.2 | 4.9 | 5.1 | 3.8 | 2.5 |

$\operatorname{Var}(\mathbf{Y})=\sigma^{2} \mathbf{I}_{6,6}, \quad \beta_{1}^{(0)}=1.473, \quad \beta_{2}^{(0)}=33, \quad \beta_{3}^{(0)}=-0.299954$,

$$
\begin{aligned}
\partial l_{1}\left(x, \beta_{1}\right) / \partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right) & =(x, 0,0) \\
\partial l_{2}\left(x, \beta_{2}, \beta_{3}\right) / \partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right) & =\left(0, \exp \left(\beta_{3} x\right), x \beta_{2} \exp \left(\beta_{3} x\right)\right. \\
\partial g\left(\beta_{1}, \beta_{2}, \beta_{3}\right) / \partial\left(\beta_{1}, \beta_{2}, \beta_{3}\right) & =\left(5,-\exp \left(5 \beta_{3}\right),-5 \beta_{2} \exp \left(5 \beta_{3}\right)\right) .
\end{aligned}
$$

Let $\boldsymbol{\Sigma}=\sigma^{2} \mathbf{I}, \sigma=0.5, \mathbf{h}=(0,1,0)^{\prime}$. Then we obtain

$$
\begin{aligned}
\mathbf{K}_{G} & =\left(\begin{array}{lr}
0.990910, & 0 \\
0.000815, & -0.999980 \\
0.134540, & 0.006061
\end{array}\right), \\
K_{I}^{(p a r)} & =5.262598, \quad C_{I, \delta \beta}^{(p a r)}=5.5672, \\
\delta \mathbf{s} & =\binom{0}{10} \Rightarrow \delta \boldsymbol{\beta}=\mathbf{K}_{i} \delta \mathbf{s}=\left(\begin{array}{r}
0 \\
-9.9998 \\
0.0606
\end{array}\right), \\
\delta \hat{\boldsymbol{\beta}} & =(0.119860,5.86137,-0.0389)^{\prime}, \\
\mathbf{C}^{-1} & =\left(\begin{array}{ll}
0.017857, & 0.000000, \\
0.000000, & 391.52, \\
0.0000000 & -1.769 \\
0.1 .769, & 0.008095
\end{array}\right), \\
\delta \hat{\hat{\beta}} & =(0.084899,14.569,-0.076767)^{\prime}, \\
\operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}}) & =\left(\begin{array}{rr}
0.013544, & 1.0744, \\
1.0744, & 123.93, \\
-0.004672, & -0.6052 \\
-0.6052, & 0.003034
\end{array}\right), \\
\mathbf{d} & =(0.11638,11.132385,0.05508)^{\prime}, \\
\delta \tilde{\tilde{\boldsymbol{\beta}}} & =(0.086411,16.4085,-0.079310)^{\prime},
\end{aligned}
$$

In this case

$$
\chi_{2}^{2}(0.95)=5.99>\frac{2 c}{C_{I, \delta \beta}^{(p a r)}}=\frac{1}{5.5672}=0.17962
$$

Thus the linearization is impossible. The value $C_{I, \delta \beta}^{(p a r)}$ indicates an extremaly high nonlinearity, which is due to the large value of $\sigma$.

Further

$$
\frac{\operatorname{Tr}\left[\mathbf{G}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\beta}})\right]}{\sqrt{\mathbf{h}^{\prime}\left[\mathbf{C}^{-1}-\mathbf{C}^{-1} \mathbf{G}^{\prime}\left(\mathbf{G} \mathbf{C}^{-1} \mathbf{G}^{\prime}\right)^{-1} \mathbf{G} \mathbf{C}^{-1}\right] \mathbf{h}}}=-0.428117
$$

The term $\operatorname{Tr}\left[\mathbf{G}_{h(\cdot)} \operatorname{Var}(\delta \hat{\hat{\boldsymbol{\beta}}})\right]$ is not sufficiently small and also other characteristics of nonlinearity are bad. Further

$$
\begin{aligned}
\mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\tilde{\boldsymbol{\beta}}}) \mathbf{h} & =123.93, \quad M S E\left(\mathbf{h}^{\prime} \delta \hat{\tilde{\boldsymbol{\beta}}}\right)=129.511 \\
\mathbf{h}^{\prime} \operatorname{Var}(\delta \tilde{\tilde{\boldsymbol{\beta}}}) \mathbf{h} & =51.0987, \quad \operatorname{MSE}\left(\mathbf{h}^{\prime} \delta \tilde{\tilde{\boldsymbol{\beta}}}\right)=77.7384 \\
\mathbf{b} & =(-0.001942,-2.263,0.004875)^{\prime}
\end{aligned}
$$

Since $\delta \hat{\hat{\boldsymbol{\beta}}}=(0.084899,14.569,-0.076767)^{\prime}$,

$$
l_{1}(5, \hat{\hat{\boldsymbol{\beta}}})=7.789495, \quad l_{2}(5, \hat{\hat{\boldsymbol{\beta}}})=7.232
$$

and $\delta \tilde{\tilde{\boldsymbol{\beta}}}=(0.086411,16.4085,-0.079310)$,

$$
l_{1}(5, \tilde{\tilde{\beta}})=7.797055, \quad l_{2}(5, \tilde{\tilde{\beta}})=7.417206
$$

what is a terrible result and thus the calculation cannot be used.
Let in this example $\sigma=0.01, \delta \mathbf{s}=(0,0.1)^{\prime}$ and the measured data be

$$
1.5,2.95,4.4,5.46,4.03,2.98
$$

Then

$$
\begin{aligned}
& K_{I}^{(p a r)}=0.105251, \quad C_{I, \delta \beta}^{(p a r)}=0.107389, \\
& \delta \hat{\boldsymbol{\beta}}=(-0.001571,0.608090,-0.002987)^{\prime} \\
& \delta \hat{\hat{\boldsymbol{\beta}}}=(-0.000051,0.203970,-0.001229)^{\prime}, \\
& \mathbf{d}=(0.002328,0.222645,0.001102)^{\prime}, \\
& \delta \tilde{\tilde{\boldsymbol{\beta}}}=(0.000049,0.204640,-0.001233)^{\prime},
\end{aligned}
$$

In this case

$$
\chi_{2}^{2}(0.95)=5.99<\frac{2 c}{C_{I, \delta \beta}^{(p a r)}}=\frac{1}{0.107389}=9.312 .
$$

In this case the linearization is possible. However the value $\sigma=0.01$ is now essentially smaller than the preceding value 0.5 .

Further

$$
\begin{aligned}
\mathbf{h}^{\prime} \operatorname{Var}(\delta \hat{\tilde{\boldsymbol{\beta}}}) \mathbf{h} & =0.000001213 \quad \operatorname{MSE}\left(\mathbf{h}^{\prime} \delta \hat{\tilde{\boldsymbol{\beta}}}\right)=0.000001213 \\
\mathbf{h}^{\prime} \operatorname{Var}(\delta \tilde{\tilde{\boldsymbol{\beta}}}) \mathbf{h} & =0.000001237, \quad \operatorname{MSE}\left(\mathbf{h}^{\prime} \delta \tilde{\tilde{\boldsymbol{\beta}}}\right)=0.000001237 \\
\mathbf{b} & =(-0.00000258,0.00035817,-0.000002098)^{\prime}
\end{aligned}
$$

Since $\hat{\hat{\boldsymbol{\beta}}}=(1.473051,33.203970,-0.301183)^{\prime}$,

$$
l_{1}(5, \hat{\hat{\boldsymbol{\beta}}})=7.365255, \quad l_{2}(5, \hat{\widehat{\boldsymbol{\beta}}})=7.365113
$$

a $\tilde{\tilde{\beta}}=(1.473049,33.204640,-0.301187)^{\prime}$,

$$
l_{1}(5, \tilde{\tilde{\beta}})=7.365245, \quad l_{2}(5, \tilde{\tilde{\beta}})=7.365115
$$

In this case the linearization is sufficient.

## References

[1] Bates, D. M., Watts, D. G.: Relative curvature measures of nonlinearity. J. Roy. Stat Soc. B 42 (1980), 1-25.
[2] Kubáček, L., Kubáčková, L.: Statistics and Metrology. Vyd. Univ. Palackého, Olomouc, 2000 (in Czech).
[3] Kubáček, L.: Linearized models with constraints of the type I. Applications of Mathematics (to appear).
[4] Pázman, A.: Nonlinear Statistical Models. Kluwer Academic Publishers, Dordrecht--Boston-London and Ister Science Press, Bratislava, 1993.
[5] Rao, C. R., Mitra, S. K.: Generalized Inverse of the Matrix and Its Applications. J. Wiley, New York, 1971.


[^0]:    *Supported by the grant No. 201/99/0327 of the Grant Agency of the Czech Republic and by the Council of the Czech Government J 14/98: 153100011.

[^1]:    ${ }^{1}$ A special software Tesaříková, E. and Kubáček, L: Properties of estimators in models with constraints of the type I (in Czech), prepared for the purpose was utilized here.

