## Kybernetika

Mary Wynne Warner
Pseudomorphisms of automata

Kybernetika, Vol. 19 (1983), No. 1, 48--57
Persistent URL: http://dml.cz/dmlcz/124470

## Terms of use:

© Institute of Information Theory and Automation AS CR, 1983
Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.
This paper has been digitized, optimized for electronic delivery and stamped with
digital signature within the project DML-CZ: The Czech Digital Mathematics Library
http://project.dml.cz

# PSEUDOMORPHISMS OF AUTOMATA 

M. W. WARNER

A pseudomorphism between the automata $(X, Q)$ and $\left(X^{\prime}, Q^{\prime}\right)$ is defined as a class of pairs $\alpha: X \times Q \rightarrow X^{\prime}, \beta: Q \rightarrow Q^{\prime}$ which preserve the relation " $q_{2}$ may be obtained from $q_{1}$ by applying an elementary input". Pseudomorphisms provide simplicial maps between the complexes associated with this relation. They can be linked with the automata homomorphisms of the classical theory by means of cascade products.

Pseudo-isomorphisms are also discussed and an example given in which $\alpha$ is not surjective. Under some (pseudo-) homogeneity conditions an automaton is pseudo-isomorphic to a group quotient automaton.

## 1. INTRODUCTION

1.1. In general an automaton is defined as a quintuple $A=\{X, Y, Q, \delta, \lambda\}$ where $Q$ is the state set, $X$ the input set, $Y$ the output set, $\delta: X \times Q \rightarrow Q$ the next state function and $\lambda: X \times Q \rightarrow Y$ the output function (Ginzburg [3]). In this paper we need only $X, Q$ and $\delta$. Thus we have, according to Ginzburg, a semi-automaton. For convenience this will henceforth be called an automaton.
1.2. Our aim is to study the relationship between automata, and in particular to identify two automata whose "patterns of behaviour" are the same even if there is no functional relation between the inputs which cause the behaviour.
1.3. An automaton $A=(X, Q)$ with input set $X$ acting by right translation on the state space $Q, q \rightarrow q \cdot x$, defines the inertial relation $v, q_{1} v q_{2}$ iff there exists $x_{1} \in X$ such that $q_{2}=q_{1} \cdot x_{1} q_{1}, q_{2} \in Q$; i.e. $q_{1}$ is related to $q_{2}$ iff there exists an elementary input of $X$ which sends $q_{1}$ to $q_{2}$ (Warner [2]).
1.4. Muir and Warner [4], Warner [5] have used Dowker's [2] homology of relations to describe a homology theory appropriate to this automaton $A$. In [4] we observe that a simplicial map from the simplicial complex $|Q|$ of $A=(X, Q)$ to
the complex $\left|Q^{\prime}\right|$ of $A^{\prime}=\left(X^{\prime}, Q^{\prime}\right)$ is provided by a pseudomorphism $(\alpha, \beta)$, $\alpha: X \times Q \rightarrow X^{\prime}, \beta: Q \rightarrow Q^{\prime}$, satisfying for all $x \in X, q \in Q$

$$
\begin{equation*}
\beta(q) \cdot \alpha(x, q)=\beta(q \cdot x) \tag{1}
\end{equation*}
$$

In terms of the relation $v$ of 1.3 , iff $(\alpha, \beta)$ is such a pseudomorphism, then $q_{1} v q_{2} \Rightarrow$ $\Rightarrow \beta\left(q_{2}\right)=\beta\left(q_{1} \cdot x_{1}\right)=\beta\left(q_{1}\right) \cdot \alpha\left(x_{1}, q\right)$. Thus $\beta\left(q_{1}\right) \cup \beta\left(q_{2}\right)$ and $\beta$ is a morphism of $(Q, v)$ to ( $\left.Q^{\prime}, v^{\prime}\right)$. An alternative (cubical) chain complex is introduced in $\S 5$ and the effect of pseudomorphisms on this structure is discussed.
1.5. In § 2 we generalise the above definition of pseudomorphism to a class $[(\alpha, \beta)]$ of pairs $(\alpha, \beta)$ satisfying relation (1) of 1.4 for a given $\beta$. A pseudomorphism will henceforth be taken to be such a class. Pseudo-isomorphisms are then defined and some properties established, for example pseudo-isomorphism is an equivalence relation on the set of automata.
1.6. We observe in $\S 3$ that a pseudomorphism from $A$ to $A^{\prime}$ can be regarded as a homomorphism in the sense of Ginzburg (3) from $A$ to the cascade produce $A \alpha A^{\prime}$. In fact when $\beta$ is surjective the parallel product of $A$ with itself 'covers' (Ginzburg [3]), or simulates $A \alpha A^{\prime}$. Thus the state of $A$ at any moment governs the input to $A^{\prime}$, there being an on-line connection between them. With this proviso $A$ can be thought of a simulating $A^{\prime}$.
1.7. The foregoing concepts are used by the author in § 4 and (Warner [6]) to establish pseudo-isomorphisms between a class of automata described as pseudohomogeneous and group quotient automata.
1.8. In passing from the input actions to the relation some information is lost, but not too much. For an ordered pair of states $\left(q_{1}, q_{2}\right)$ we know whether there exists an elementary input taking $q_{1}$ to $q_{2}$. This is an improvement on Arbib's [1] inertial tolerance automaton in which it is known only that there exists either an input taking $q_{1}$ to $q_{2}$ or an input taking $q_{2}$ to $q_{1}$. The imposition of symmetry loses information without reaping any advantage since it is still possible to mimic continuity with respect to time by defining $t_{r} \nu t_{r+1}$ on the quantized time set $T=\{0,1,2, \ldots\}$. Then with each input sequence $x^{*}=\left\{x_{0}, x_{1}, x_{2}, \ldots\right\}$ associate the motion $m_{x^{*}}: T \rightarrow$ $\rightarrow Q$ by defining $m_{x^{*}}(0)=q_{0}$, an initial state, $m_{x^{*}}(t+1)=m_{x^{*}}(t) \cdot x_{t}$. Clearly $m_{x^{*}}$ is a morphism (preserves the relation $v$ ).
1.9. The appendix provides an example of a pseudoisomorphism $[(\alpha, \beta)]$ in which $\alpha$ is not surjective. If $\left[\left(\alpha^{\prime}, \beta^{-1}\right)\right]$ is the inverse of $[(\alpha, \beta)]$ then $\alpha^{\prime}$ is also not surjective and $\alpha^{\prime}(\alpha(x, q), \beta(q))$ does not coincide with $x$. Except when there is a possibility of confusion all relations will be written $v$.

## 2. PSEUDOMORPHISMS

2.1. Definition. A pseudomorphism $[(\alpha, \beta)]$ from the automaton $A=(X, Q)$ to $A^{\prime}=\left(X^{\prime}, Q^{\prime}\right)$ is an equivalence class of pairs of functions $\alpha: X \times Q \rightarrow X^{\prime}$, $\beta: Q \rightarrow Q^{\prime}$ such that

$$
\begin{equation*}
\beta(q) \cdot \alpha(x, q)=\beta(q \cdot x) \text { for all } q \in Q, x \in X \tag{1}
\end{equation*}
$$

The equivalence relation $\sim$ is defined by $(\alpha, \beta) \sim\left(\alpha_{1}, \beta\right)$ if $\alpha, \alpha_{1}$ both satisfy (1) with respect to $\beta$. We refer to $(\alpha, \beta)$ as a representative of $[(\alpha, \beta)]$.
2.2. If $A, A^{\prime}$ are given inertial tolerance (Arbib [1]), then $\beta$ is tolerance-preserving iff either $\beta(q) \cdot \alpha(x, q)=\beta(q \cdot x)$ or $\beta(q \cdot x) \cdot \alpha(x, q)=\beta(q)$. Thus pseudomorphisms preserve inertial tolerance.
2.3. If $\alpha$ does not depend on $q$ (the state arrived at), then $\beta(q) \cdot \alpha(x)=\beta(q \cdot x)$ where $\alpha: X \rightarrow X^{\prime}$. This is a homomorphism of automata (Ginzburg [3]). It is clearly not suitable in this case to pass to classes $[(\alpha, \beta)]$. If $\beta$ is bijective and its inverse is a homomorphism we have an isomorphism between $A$ and $A^{\prime}$.
2.4. Definition. The pseudomorphism $[(\alpha, \beta)]$ is a $p$ seudo-isomorphism represented by ( $\alpha, \beta, \alpha^{\prime}$ ) if $\beta$ is bijective and there exists $\alpha^{\prime}: X^{\prime} \times Q^{\prime} \rightarrow X$ such that

$$
\beta^{-1}\left(q^{\prime}\right) \cdot \alpha^{\prime}\left(x^{\prime}, q^{\prime}\right)=\beta^{-1}\left(q^{\prime} \cdot x^{\prime}\right)
$$

where $x^{\prime} \in X^{\prime}, q^{\prime} \in Q^{\prime}$. Thus $\left[\left(\alpha^{\prime}, \beta^{-1}\right)\right]$ is also a pseudo-isomorphism, and $q$. $\alpha^{\prime}(\alpha .(x, q), \beta(q))=q . x$. But $\alpha, \alpha^{\prime}$ are not necessarily surjective, and $\alpha^{\prime}(\alpha(x, q), \beta(q))$ need not be $x$. Both these claims are illustrated in the example of the appendix. We denote the above pseudo-isomorphism by $\left[\left(\alpha, \beta, \alpha^{\prime}\right)\right]$.
2.5. Lemma. Pseudo-isomorphism is an equivalence relation $\simeq$ on the set of automata.

Proof. (i) $A \sim A$ is represented by $(u, 1, u)$ where $q \cdot u(x, q)=q \cdot x$, e.g. $\alpha(x, q)=$ $=x$. Then $[(u, 1, u)]$ is the identity pseudo-isomorphism.
(ii) If $A \sim A^{\prime}$ is represented by $\left(\alpha, \beta, \alpha^{\prime}\right)$, then $\left(\alpha^{\prime}, \beta^{-1}, \alpha\right)$ represents $A^{\prime} \simeq A$.
(iii) If ( $\alpha, \beta, \alpha^{\prime}$ ) represents $A \simeq A^{\prime}$ and ( $\bar{\alpha}, \bar{\beta}, \bar{\alpha}^{\prime}$ ) represents $A^{\prime} \simeq A^{\prime \prime}$ then $A \simeq A^{\prime \prime}$ is represented by ( $\hat{\alpha}, \bar{\beta} \beta, \hat{\alpha}^{\prime}$ ) where

$$
\begin{gathered}
\hat{\alpha}(x, q)=\bar{\alpha}(\alpha(x, q), \beta(q)) \\
\hat{\alpha}^{\prime}\left(x^{\prime \prime}, q^{\prime \prime}\right)=\alpha^{\prime}\left(\bar{\alpha}^{\prime}\left(x^{\prime \prime}, q^{\prime \prime}\right), \quad \bar{\beta}^{-1}\left(q^{\prime \prime}\right)\right) \text { for } x \in X, \quad x^{\prime \prime} \in X^{\prime \prime},
\end{gathered}
$$

$q \in Q, q^{\prime \prime} \in Q^{\prime \prime}$. Verification that ( $\hat{\alpha}, \bar{\beta} \beta, \hat{\alpha}^{\prime}$ ) does represent a pseudo-isomorphism
follows without difficulty, e.g.,

$$
\begin{aligned}
\bar{\beta} \beta(q) \cdot \hat{\alpha}(x, q) & =\bar{\beta} \beta(q) \cdot \bar{\alpha}(\alpha(x, q), \beta(q)) \\
& =\bar{\beta}(\beta(q) \cdot \alpha(x, q)) \\
& =\bar{\beta} \beta(q \cdot x)
\end{aligned}
$$

Similarly, $\left(\hat{\alpha}^{\prime},(\bar{\beta} \beta)^{-1}\right)$ represents a pseudo-morphism.
2.6. Lemma. The set of pseudo-isomorphisms from $A$ to itself forms a group.

Proof. Closure follows from transitivity ( 2.5 (iii)). The identity is defined in 2.5 (i). The inverse of $\left[\left(\alpha, \beta, \alpha^{\prime}\right)\right]$ is represented by $\left(\alpha^{\prime}, \beta^{-1}, \alpha\right)$ since $\beta^{-1} \beta=1$, and in the notation of 2.5 (iii), $\hat{\alpha}(x, q)=\alpha^{\prime}(\alpha(x, q), \beta(q))$, so $q \cdot \hat{\alpha}(x, q)=q \cdot x$. Thus $\left[\left(\hat{\alpha}, \beta^{-1} \beta\right.\right.$, $\left.\left.\hat{\alpha}^{\prime}\right)\right]=[(u, 1, u)]=$ identity.

It remains to verify associativity. Let $\gamma, \bar{\gamma}, \dot{\gamma}: A \simeq A$ be represented by ( $\alpha, \beta, \alpha^{\prime}$ ), $\left(\bar{\alpha}, \bar{\beta}, \bar{\alpha}^{\prime}\right),\left(\dot{\alpha}, \dot{\beta}, \dot{\alpha}^{\prime}\right)$ respectively. Then, again using the notation of 2.5 (iii), $\gamma \bar{\gamma}=$ $=\left[\left(\alpha, \bar{\beta} \beta, \hat{\alpha}^{\prime}\right)\right]$, and $(\gamma \bar{\gamma}) \dot{\gamma}=\left[\left(\tilde{\alpha}, \dot{\beta} \bar{\beta} \beta, \tilde{\alpha}^{\prime}\right)\right]$ where

$$
\begin{aligned}
\tilde{\alpha}(x, q) & =\dot{\alpha}(\hat{\alpha}(x, q), \bar{\beta} \beta(q)) \\
& =\dot{\alpha}(\bar{\alpha}(\alpha(x, q), \beta(q)), \bar{\beta} \beta(q))
\end{aligned}
$$

And $\bar{\gamma} \dot{\gamma}=\left[\left(\alpha_{\wedge}, \vec{\beta} \bar{\beta}, \alpha_{\wedge}^{\prime}\right)\right]$ with $\alpha_{\wedge}(x, q)=\dot{\alpha}(\bar{\alpha}(x, q), \bar{\beta}(q))$
Thus $\gamma(\bar{\gamma} \dot{\gamma})=\left[\left(\alpha_{\sim}, \dot{\beta} \bar{\beta} \beta, \alpha_{\sim}^{\prime}\right)\right]$ where

$$
\begin{aligned}
\alpha_{\sim}(x, q) & =\alpha_{\wedge}(\alpha(x, q), \beta(q)) \\
& =\dot{\alpha}(\bar{\alpha}(\alpha(x, q), \beta(q)), \bar{\beta} \beta(q))
\end{aligned}
$$

Similariy $\tilde{\alpha}^{\prime}$ and $\alpha_{\sim}^{\prime}$ have the same action.

## 3. HOMOMORPHISMS

3.1. Let $[(\alpha, \beta)]$ be a pseudomorphism from $A=(X, Q)$ to $A^{\prime}=\left(X^{\prime}, Q^{\prime}\right)$. Let $\bar{Q} \subseteq Q \times Q$ be the diagonal $\{(q, q): q \in Q\}$, and let $\omega(x, q)=x$.

We recall that a function $\alpha: X \times Q \rightarrow X^{\prime}$ defines a cascade product $A \alpha A^{\prime}=$ $=\left(X, Q \times Q^{\prime}\right)$ with input action $\left(q, q^{\prime}\right) \cdot x=\left(q \cdot x, q^{\prime} \cdot \alpha(x, q)\right)$.
Define $f: \bar{Q} \rightarrow Q \times Q^{\prime}$ by $f(q, q)=(q, \beta(q))$.
Lemma. $(f, \zeta)$ is a homomorphism from $(X, \bar{Q} \subseteq A \omega A)$ to $A \alpha A^{\prime}=\left(X, Q \times Q^{\prime}\right)$, with $\zeta$ the identity on $X$.

Proof.

$$
\begin{aligned}
f(q, q) \cdot x & =(q, \beta(q)) \cdot x \\
& =(q \cdot x, \beta(q) \cdot \alpha(x, q)) \\
& =(q \cdot x, \beta(q \cdot x)) \\
& =f(q \cdot x, q \cdot x)
\end{aligned}
$$

Corollary. When $\beta$ is surjective $A \omega A$ covers or simulates $A \alpha A^{\prime}$ (Ginzburg [3]), i.e. $f$ maps a subset of $Q \times Q$ onto $Q \times Q^{\prime}$ and satisfies the relation established in the lemma.

Figure 1 illustrates the homomorphism $(f, 1)$


Fig. 1.
3.2. Lemma. A pseudo-isomorphism $\left[\left(\alpha, \beta, \alpha^{\prime}\right)\right]$ may be represented by an isomorphism $f$ from the diagonal of $A \omega A \omega A=(X, Q \times Q \times Q)$ to $A \alpha A^{\prime} \alpha^{\prime} A=$ $=\left(X, Q \times Q^{\prime} \times Q\right)$ given by $f(q, q, q)=(q, \beta(q), q)$.
Proof.

$$
\begin{aligned}
f(q, q, q) \cdot x= & (q, \beta(q), q) \cdot x \\
= & (q \cdot x,(\beta(q), q) \cdot \alpha(x, q)) \\
= & (q \cdot x, \beta(q) \cdot \alpha(x, q), \\
& \left.q \cdot \alpha^{\prime}(\alpha(x, q), \beta(q))\right) \\
= & (q \cdot x, \beta(q \cdot x), q \cdot x) \\
= & f(q \cdot x, q \cdot x, q \cdot x) .
\end{aligned}
$$

## 4. PSEUDO-HOMOGENEITY

4.1. A permutation automaton $A=(X, Q)$ is defined in Warner [6] as having permutation inputs only. If $G$ is the group generated by $X$ then the above automaton is homogeneous if for all $q, q^{\prime} \in Q$ there exists $g \in G$ such that $g(q)=q^{\prime}$. Let $H$ be the subgroup of $G$ which fixes some $q_{0} \in Q$. It is proved in [6] that the homogeneous automaton $A$ is isomorphic to the group quotient automaton $(X, G / H)$ with action $[g] . x=[x g]$. Hence [ ] denotes equivalence class under the relation " $g \sim g^{\prime}$ iff $g\left(q_{0}\right)=g^{\prime}\left(q_{0}\right)^{\prime \prime}$. The isomorphism $\tilde{\Phi}: G / H \rightarrow Q$ is well-defined by $\tilde{\Phi}[g]=g\left(q_{0}\right)$.
4.2. If in addition the permutation inputs of $X$ in this homogeneous automaton and their inverses are inertia-preserving (1.3), i.e. $q_{1} v q_{2} \Rightarrow q_{1} \cdot x v q_{2} \cdot x, q_{1} \cdot x^{-1} v q_{2}$. .$x^{-1}$, for all $x \in X$, then the group $G$ above is a $v$-group in which $v$ is preserved by left and right translations by group elements ([6], Lemma 4). The elements of $G$ are isomorphisms of $A$ with $\alpha=1$.
4.3. A pseudo-homogeneous automaton is taken to be one which is indistinguishable in its $v$-structure from a homogeneous automaton. Formally, $A=(X, Q)$ is pseudopermutational if it is pseudo-isomorphic to a permutation automaton $\bar{A}=(\bar{X}, \bar{Q})$. Let $[(\alpha, \beta)]$ be such a pseudo-isomorphism. Without loss of generality we may take $\beta=1$ and identify $Q$ and $\bar{Q}$. Then if $q_{2}=q_{1} \cdot x$ for some $x \in X, \alpha\left(x, q_{1}\right)=\bar{x} \in \bar{X}$ such that $q_{2}=q_{1} \cdot \bar{x}$. Finally, such an automaton is pseudo-homogeneous if for all $q_{1}, q_{2} \in Q$ there exists $g \in G$ (the group generated by $\bar{X}$ ) such that $g\left(q_{1}\right)=q_{2}$.
4.4. Now let the permutation inputs of $\bar{X}$ generate pseudomorphisms $[(\alpha, \beta)]$ of $\bar{A}$ to itself. Then for $\bar{x} \in \bar{X}, \beta(q)=q \cdot \bar{x}$ and there exists $\alpha: \bar{X} \times \bar{Q} \rightarrow \bar{X}$ such that $(q \cdot \bar{x}) \cdot \alpha\left(\bar{x}_{1}, q\right)=q \cdot \bar{x}_{1} \bar{x}$. Define $\beta^{-1}(q)=q \cdot \bar{x}^{-1}$ even though $\bar{x}^{-1}$ may not be an element of $\bar{X}$. If there exists $\alpha^{\prime}: \bar{X} \times \bar{Q} \rightarrow \bar{X}$ such that $\left(q \cdot \bar{x}^{-1}\right) \cdot \alpha^{\prime}\left(x_{1}, q\right)=$ $=q \cdot \bar{x}_{1} \bar{x}$ then $[(\alpha, \beta)]$ is a pseudo-isomorphism. The group generated by such pseudo-isomorphisms is a subgroup of the gioup of all pseudo-isomorphisms of $A$ described in Lemma 2.6.
4.5. Theorem. If each permutation input associated with a pseudo-homogeneous automaton $A=(X, Q)$ generates a pseudo-isomorphism then the automaton $A$ is pseudo-isomorphic to a group quotient automaton whose group $G$ is a $v$-group.

Proof. $A$ is pseudo-isomorphic to $\bar{A}$ which is homogeneous and therefore isomorphic to a group quotient automaton. The fact that the elements of $\bar{X}$ and their inverses are inertia-preserving follows immediately from 4.4. Let $\bar{x}, \bar{x}_{1} \in \bar{X}$ and $q_{2}=q_{1} \cdot \bar{x}_{1}$, so $q_{1} v q_{2}$. Then $q_{2} \cdot \bar{x}=q_{1} \cdot \bar{x}_{1} \bar{x}=\left(q_{1} \cdot \bar{x}\right) \cdot \alpha\left(\bar{x}_{1}, q\right)$, and $q_{1} \cdot \bar{x} v q_{2} \cdot \bar{x}$. Similarly for inverses $\vec{x}^{-1}$.

## 5. HOMOLOGY

5.1. It has already been pointed out (1.4) that a pseudo-morphism between automata provides a simplicial map between their associated Dowker simplicial complexes. In fact any homology theory based on the inertial relation $v$ is equally well served by pseudomorphisms.
5.2. Bearing in mind the definition of $v$, namely $q_{1} v q_{2}, q_{1}, q_{2} \in Q$, iff there exists $x_{1} \in X$ such that $q_{2}=q_{1} \cdot x_{1}$ we define a singular cubical homology theory on $Q$ (cf. a similar treatment for tolerance spaces in Warner [4]).
5.3. The standard n-cube $e_{n}$ is the subset of Hilbert space consisting of points $\left(u_{i}\right)=\left(u_{1}, u_{2}, \ldots, u_{p}, \ldots\right)$ such that $u_{i}=0, i>n$, each $u_{i}=0$ or $1, i \leqq n$. The cube $e_{n}$ has the relation $\left(u_{i}\right) v\left(u_{i}^{\prime}\right)$ iff the points $\left(u_{i}\right),\left(u_{i}^{\prime}\right)$ differ in at most one co-ordinate, say the $j$ th, and $u_{j}<u_{j}^{\prime}$.
5.4. The chain group $C_{n}(Q)$ is the free abelian group generated by the set of morphisms $f: e_{n} \rightarrow Q$, called singular $n$-cubes. The boundary $\partial: C_{n}(Q) \rightarrow C_{n-1}(Q)$ is defined as usual by $\partial f=\sum_{i=1}^{n}(-1)^{i}\left(f^{i 0}-f^{i 1}\right)$ where the face $f^{i j}: e_{n-1} \rightarrow Q$ is the composition of $f$ with $v_{i j}: e_{n-1} \rightarrow e_{n}, v_{i j}\left(u_{1}, u_{2}, \ldots, u_{n-1}, 0, \ldots\right)=\left(u_{1}, u_{2}, \ldots, u_{i-1}\right.$, $\left.j, u_{i}, \ldots, u_{n-1}, 0, \ldots\right)$. Then $\partial \partial=0$ and $(C(Q), \partial)$ is a chain complex. We normalise by factoring out degenerate cubes, viz. cubes which do not depend on all their coordinates. The normalised homology groups will be denoted by $H_{n}(Q)$. A brief résumé of the required terminology and concepts of classical homology theory is given in the appendix to [4].
5.5. Lemma. A pseudomorphism $[(\alpha, \beta)]$ between automata $A=(X, Q)$ and $A^{\prime}=\left(X^{\prime}, Q^{\prime}\right)$ induces a chain homomorphism $\bar{\beta}: C(Q) \rightarrow C\left(Q^{\prime}\right)$.

Proof. $\beta$ is a morphism from $(Q, v)$ to $\left(Q^{\prime}, v^{\prime}\right)$ by (1.4). Let $\bar{\beta}_{n}(f)=\beta f$ where $f \in C_{n}(Q)$. Then $\beta f \in C_{n}\left(Q^{\prime}\right)$. And

$$
\begin{gathered}
\partial \bar{\beta}_{n}(f) \overline{\bar{J}}=\partial \beta f=\sum_{i=1}^{n}(-1)^{i}\left((\beta f)^{i 0}-(\beta f)^{i 1}\right) \\
\bar{\beta}_{n-1}(\partial f)=\beta \partial f=\beta \sum_{i=1}^{n}(-1)^{i}\left(f^{i 0}-f^{i 1}\right)
\end{gathered}
$$

while $\beta f^{i j}\left(e_{n-1}\right)=\beta f v_{i j}\left(e_{n-1}\right)=(\beta f)^{i j}\left(e_{n-1}\right)$.
So $\bar{\beta}$ is a chain homomorphism.
5.6. In the function space $Q^{\prime Q}$ of morphisms from $Q$ to $Q^{\prime}$, let $\beta_{1} v \beta_{2}$ iff $\beta_{1}(q) \vee \beta_{2}(q)$ for all $q \in Q$.

Lemma. If $\beta_{1} v \beta_{2}$ then the induced chain homomorphisms are chain homotopic.

Proof. For all $n$, define $\Delta_{n}: C_{n}(Q) \rightarrow C_{n+1}\left(Q^{\prime}\right)$ as follows. Let $f: e_{n} \rightarrow Q$ be a singular $n$-cube of $Q$. Then $\Delta_{n} f=h$ where

$$
h\left(u_{1}, u_{2}, \ldots, u_{n+1}\right)= \begin{cases}\beta_{1} f\left(u, \ldots, u_{n+1}\right) & \text { when } u_{1}=0 \\ \beta_{2} f\left(u, \ldots, u_{n+1}\right) & \text { when } u_{1}=1\end{cases}
$$

And $h \in C_{n+1}\left(Q^{\prime}\right)$ since $h$ is a morphism.
This follows on the first co-ordinate from

$$
\beta_{1} f\left(u_{2}, \ldots, u_{n+1}\right) \cup \beta_{2}\left(f\left(u_{2}, \ldots, u_{n+1}\right)\right.
$$

and on the other co-ordinates from the fact that $\beta_{1}, \beta_{2}$ are morphisms

$$
\left\{\Delta_{n}\right\} \text { is the required chain homotopy, for if } f \in C_{n+1}
$$

$$
\begin{aligned}
\Delta_{n} \partial f & =\Delta_{n} \sum_{i=1}^{n+1}(-1)^{i}\left(f^{i 0}-f^{i 1}\right) \\
& =\Delta_{n} f^{11}-\Delta_{n} f^{10}+\sum_{i=2}^{n+1}(-1)^{i}\left(\Delta_{n} f^{i 0}-\Delta_{n} f^{i 1}\right) \\
& =\beta_{2} f-\beta_{1} f-\partial A_{n} f
\end{aligned}
$$

5.7. By classical homology theory, then, $\beta_{1}$ and $\beta_{2}$ induce the same homomorphism of homology groups. But the inertial relation requires each input $x \in X$ to satisfy the relation $1 v x$ since $q v q . x$ for all $q$. We therefore deduce the following lemmas.

Lemma. Inertia-preserving inputs to an automaton $A=(X, Q)$ induce the identity homology homomorphism on $H_{n}(Q)$ for all $n$.

Lemma. A pseudomorphism of $A$ to itself in which $1 \nu \beta$ induces the identity homology homomorphism on $H(Q)$.
5.8. $\alpha_{n}$ be the number of non-degenerate singular $n$-cubes of $Q$, and $\chi=\sum_{i}(-1)^{i} \alpha_{i}$. It follows immediately from the Hopf trace theorem (see [4], appendix) that if $\chi \neq 0$ every chain homomorphism chain homotopic to the identity maps a generator of some $C_{n}$ to itself. Thus we have the following theorems.

Theorem. If $\chi \neq 0$, every inertia-preserving input to the automaton $A=(X, Q)$ maps some cube of $Q$ to itself.

Theorem. Given an automaton $A=(X, Q)$ and the inertial normalised cubical singular chain complex $C(Q)$ of $Q$, then a pseudomorphism $[(\alpha, \beta)]$ of $A$ to itself in which $q v \beta(q)$ for all $q \in Q$ maps some cube of $C(Q)$ to itself whenever $\gamma \neq 0$.

## APPENDIX

Example. Let $A=(X, Q)$ where $X=\left\{x_{1}, x_{2}, x_{3}\right\}, Q=\left\{q, q \cdot x_{1}=q . x_{2}, q, x_{3}\right\}$. The rest of the action of $X$ on $Q$ is given by

|  | $q$ | $q \cdot x_{1}$ | $q \cdot x_{3}$ |
| :--- | :--- | :--- | :--- |
| $x_{1}$ | $q \cdot x_{1}$ | $q \cdot x_{1}$ | $q \cdot x_{3}$ |
| $x_{2}$ | $q \cdot x_{2}$ | $q$ | $q \cdot x_{3}$ |
| $x_{3}$ | $q \cdot x_{3}$ | $q$ | $q \cdot x_{3}$ |



Fig. 2.
Let $A^{\prime}=\left(X^{\prime}, Q^{\prime}\right)$ where $X^{\prime}=\left\{x_{1}^{\prime}, x_{2}^{\prime}, x_{3}^{\prime}\right\}$ and $Q^{\prime}=\left\{\beta(q), \beta\left(q \cdot x_{1}\right), \beta\left(q \cdot x_{3}\right)\right\}$ with action

|  | $\beta(q)$ | $\beta\left(q \cdot x_{1}\right)$ | $\beta\left(q \cdot x_{3}\right)$ |
| :--- | :--- | :--- | :--- |
| $x_{1}^{\prime}$ | $\beta\left(q \cdot x_{1}\right)$ | $\beta\left(q \cdot x_{1}\right)$ | $\beta\left(q \cdot x_{3}\right)$ |
| $x_{2}^{\prime}$ | $\beta\left(q \cdot x_{3}\right)$ | $\beta(q)$ | $\beta\left(q \cdot x_{3}\right)$ |
| $x_{3}^{\prime}$ | $\beta\left(q \cdot x_{3}\right)$ | $\beta\left(q \cdot x_{1}\right)$ | $\beta\left(q \cdot x_{3}\right)$ |

Fig. 3.


With $\beta: Q \rightarrow Q^{\prime}$ the bijection given above, define $\alpha: X \times Q \rightarrow X^{\prime}$ by

$$
\begin{array}{lll}
\alpha\left(x_{1}, q\right)=x_{1}^{\prime} & \alpha\left(x_{1}, q \cdot x_{1}\right)=x_{1}^{\prime} & \alpha\left(x_{1}, q \cdot x_{3}\right)=x_{1}^{\prime} \\
\alpha\left(x_{2}, q\right)=x_{1}^{\prime} & \alpha\left(x_{2}, q \cdot x_{1}\right)=x_{2}^{\prime} & \alpha\left(x_{2}, q \cdot x_{3}\right)=x_{1}^{\prime} \\
\alpha\left(x_{3}, q\right)=x_{2}^{\prime} & \alpha\left(x_{3}, q \cdot x_{1}\right)=x_{2}^{\prime} & \alpha\left(x_{3}, q \cdot x_{3}\right)=x_{1}^{\prime}
\end{array}
$$

Then $[(\alpha, \beta)]$ is a pseudo-isomorphism. We can check that $\beta(q \cdot x)=\beta(q) \cdot \alpha(\in, q)$ $\forall x \in X, q \in Q$.

And we can construct $\alpha^{\prime}$ e.g. $\alpha^{\prime}\left(x_{1}^{\prime}, \beta(q)\right)=x_{1}, \alpha^{\prime}\left(x_{2}^{\prime}, \beta(q)\right)=x_{3}, \alpha^{\prime}\left(x_{3}^{\prime}, \beta(q)\right)=x_{3}$ etc. Then $\alpha$ is not surjective (every action $x_{3}^{\prime}$ can be obtained from $x_{1}^{\prime}$ or $x_{2}^{\prime}$ ). And $\alpha^{\prime}\left(\alpha\left(x_{2}, q\right), \quad \beta(q)\right)=\alpha^{\prime}\left(x_{1}^{\prime}, \beta(q)\right)=x_{1} \neq x_{2} \quad$ although $q \cdot x_{1}=q \cdot x_{2}$, so $q \cdot \alpha^{\prime}$. . $\left(\alpha\left(x_{2}, q\right), \beta(q)\right)=q \cdot x_{2}$.
(Received October 15, 1981.)
[1] M. A. Arbib: Tolerance automata. Kybernetika 3 (1967), 223-233.
[2] C. H. Dowker: Homology groups of relations. Ann. of Math. 56 (1952), 84-95.
[3] A. Ginzburg: Algebraic Theory of Automata. Academic Press, New York 1968.
[4] A. Muir and M. W. Warner: Homology theories and tolerance automata. Discrete Math. 33 (1981), 209-221.
[5] M. W. Warner: Fixed blots in tolerance automata. Kybernetes 9 (1980), 193-195.
[6] M. W. Warner: Semi-group, group quotient and homogeneous automata. Informat. and Control 47 (1980), 59-66.

Dr. M. W. Warner, Department of Mathematics, The City University, Northampton Square, London, E.C. I, V4PB, U.K.

