## Mathematic Bohemia

## Anton Augustynowicz <br> On the uniqueness of solutions of functional differential equations with nonincreasing right-hand sides

Mathematica Bohemica, Vol. 121 (1996), No. 2, 113-116

Persistent URL: http://dml.cz/dmlcz/126104

## Terms of use:

© Institute of Mathematics AS CR, 1996

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.


This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project DML-CZ: The Czech Digital Mathematics Library http://dml.cz

# ON THE UNIQUENESS OF SOLUTIONS OF FUNCTIONAL <br> DIFFERENTIAL EQUATIONS WITH NONINCREASING RIGHT-HAND SIDES 

Antoni Augustynowicz, Gdańsk
(Received October 12, 1994)

Dedicated to Professor Zygfryd Kucharski on the occasion of his 50th birthday

Summary. It is proved that nonincreasing and satisfying the Volterra condition righthand side of a functional differential equation does not guarantee the uniqueness of solutions.

Keywords: nonlinear functional differential equations
AMS classification: 34K05

Suppose that $I=[0, a], B$ is a Banach space, $f: I \times B \rightarrow B, g: I \times C(I, B) \rightarrow B$ are continuous functions satisfying the Volterra condition (it means that $g(t, x)=$ $g(t, y)$ if $x(s)=y(s)$ for $s \in[0, t]$, where $C(I, B)$ denotes the Banach space of all functions from $I$ into $B$. It is well known that the Cauchy problems

$$
\begin{align*}
x^{\prime}(t) & =f(t, x(t))  \tag{1}\\
x(0) & =x_{0}
\end{align*}
$$

and

$$
\begin{align*}
x^{\prime}(t) & =g(t, x) \\
x(0) & =x_{0} \tag{2}
\end{align*}
$$

have many fundamental properties in common. For instance, the Peano Theorem and the Picard Theorem are valid for both of them (see [3]). However, there are some differences. For example, graphs of each two solutions of (1) are tangent at
any common point, but this need not be true for every two solutions of problem (2) (see [3]). In this note we construct an example which illustrates another difference.

In the case of a Hilbert space $B$ with a scalar product $\langle\cdot, \cdot\rangle$ and a norm $|\cdot|_{*}$, some generalizations of Kamke type conditions for (1) of the form

$$
\operatorname{Re}\langle v-u, f(t, v)-f(t, u)\rangle \leqslant w\left(t,|v-u|_{*}\right)
$$

were considered in literature. For some classes of functions $w$ these conditions guarantee the existence and uniqueness of a solution of (1) (see, for instance, [1], [2], [4] and [5]). The strongest condition of the above type is

$$
\operatorname{Re}\langle v-u, f(t, v)-f(t, u)\rangle \leqslant 0
$$

If $B$ is the one-dimensional Euclidean space $\mathbb{R}$, the above condition means that $f$ is nonincreasing with respect to the second variable. The example we construct shows that even in the case $B=\mathbb{R}$ the condition " $g(t, \cdot)$ is a nonincreasing function for any $t \in I$ " is not sufficient for the uniqueness of solutions of (2).

First we prove

Lemma. Suppose that $y_{1}, y_{2}, z_{1}, z_{2} \in C=C(I, \mathbb{R}), z_{1}(0)=z_{2}(0)$ and for any $t \in(0, a]$ we have

$$
l_{1}(t)=\sup _{s \in[0, t]}\left(y_{1}(s)-y_{2}(s)\right)>0, \quad l_{2}(t)=\sup _{s \in[0, t]}\left(y_{2}(s)-y_{1}(s)\right)>0
$$

Then there exists a continuous function $g: I \times C \rightarrow \mathbb{R}$ such that

1. $z_{i}(t)=g\left(t, y_{i}\right)$ for $i=1,2, t \in I$;
2. $g$ satisfies the Volterra condition;
3. $g(t, \cdot)$ is a nonincreasing function;
4. $g$ is bounded.

Proof. Let us define an operator $r: C \rightarrow \mathrm{C}$ by the formula

$$
(r x)(t)= \begin{cases}m(t), & \text { if } x(t)<m(t) \\ x(t), & \text { if } m(t) \leqslant x(t) \leqslant M(t) \\ M(t), & \text { if } x(t)>M(t)\end{cases}
$$

where $m(t)=\min \left\{y_{1}(t), y_{2}(t)\right\}, M(t)=\max \left\{y_{1}(t), y_{2}(t)\right\}$.

Our function $g: I \times C \rightarrow \mathbb{R}$ is defined by

$$
g(t, x)=\left\{\begin{array}{lc}
z_{1}(0), & \text { if } t=0, \\
l_{1}(t)^{-1} \sup _{s \in[0, t]}\left(y_{1}(s)-(r x)(s)\right)\left(z_{2}(t)-z_{1}(t)\right)+z_{1}(t), \\
& \text { if } t>0 \text { and } z_{1}(t) \leqslant z_{2}(t), \\
l_{2}(t)^{-1} \sup _{s \in[0, t]}\left(y_{2}(s)-(r x)(s)\right)\left(z_{1}(t)-z_{2}(t)\right)+z_{2}(t), \\
& \text { if } t>0 \text { and } z_{1}(t)>z_{2}(t) .
\end{array}\right.
$$

Since $r y_{i}=y_{i}, i=1,2$, condition 1 holds true. It is easy to verify that conditions 2 and 3 are also satisfied. Condition 4 holds true because

$$
\begin{equation*}
0 \leqslant l_{i}(t)^{-1} \sup _{s \in[0, t]}\left(y_{i}(s)-(r x)(s)\right) \leqslant 1 \tag{3}
\end{equation*}
$$

for $t \in(0, a]$, and

$$
\min \left\{z_{1}(t), z_{2}(t)\right\} \leqslant g(t, x) \leqslant \max \left\{z_{1}(t), z_{2}(t)\right\}
$$

## for $t \in I, x \in C$.

We prove that the function $g$ is continuous. For $t \in(0, a], x, y \in C$ we get

$$
\begin{gathered}
\left|\sup _{s \in[0, t]}\left(y_{i}(s)-(r x)(s)\right)-\sup _{s \in[0, t]}\left(y_{i}(s)-(r y)(s)\right)\right| \\
\leqslant \sup _{s \in[0, t]}|(r x)(s)-(r y)(s)| \leqslant \sup _{s \in[0, t]}|x(s)-y(s)| \leqslant\|x-y\|,
\end{gathered}
$$

where $\|\cdot\|$ denotes the norm of the uniform convergence. Hence

$$
|g(t, x)-g(t, y)| \leqslant l(t)\|x-y\|
$$

where $l(t)=\max \left\{l_{1}(t)^{-1}, l_{2}(t)^{-1}\right\}\left|z_{1}(t)-z_{2}(t)\right|$. It means that $g$ is a continuous function on $(0, a] \times C$, since $g(\cdot, x)$ is a continuous function on $(0, a]$ for each $x \in C$. Let us verify the continuity of $g$ at any point of $\{0\} \times C$. Suppose that $\left(t_{n}, x_{n}\right) \rightarrow$ $\left(0, x_{0}\right), n \rightarrow \infty$, for some $x_{0} \in C$. Then we get from (3)

$$
\left|g\left(t_{n}, x_{n}\right)-z_{1}\left(t_{n}\right)\right| \leqslant\left|z_{2}\left(t_{n}\right)-z_{1}\left(t_{n}\right)\right|
$$

Since $z_{1}(0)=z_{2}(0)$ we obtain $\lim _{n \rightarrow \infty} g\left(t_{n}, x_{n}\right)=z_{1}(0)=g\left(0, x_{0}\right)$. We conclude that the function $g$ is continuous on $\stackrel{n \rightarrow \infty}{I} \times C$ and the proof is complete.

## The main result is presented in

Theorem. There exists a continuous function $g$ satisfying conditions 2-4 of Lemma, such that for any $a>0$ the problem (2) has at least two different solutions on $[0, a]$.

Proof. Suppose that $y_{1}$ and $y_{2}$ satisfy the assumptions of Lemma and are continuously differentiable on $I$, and $y_{1}^{\prime}(0)=y_{2}^{\prime}(0)$ (we can take, for instance, $y_{1}(t)=$ $\left.x_{0}, y_{2}(t)=x_{0}+t^{3} \sin t^{-1}\right)$. Assume that $g$ is a function satisfying the assertion of Lemma for $z_{i}=y_{i}^{\prime}, i=1,2$. It follows from condition 1 that the Cauchy problem (2) has two different solutions $y_{1}$ and $y_{2}$.

Remark. It follows from the above proof that the graphs of two different solutions of the problem (2) may have infinitely many common points on any finite interval $(0, b), b>0$ and need not be tangent at any point.

## References

[1] F. E. Browder: Non-linear equations of evolution. Ann. Math. 80 (1964), 485-523.
[2] J. B. Diaz, R. J. Weinacht: On nonlinear differential equations in Hilbert spaces. Appl. Anal. 1 (1971), 31-41.
[3] J. K. Hale: Theory of Functional Differential Equations. Springer-Verlag, New York, 1977.
[4] S. Kato: On existence and uniqueness conditions for nonlinear ordinary differential equation in Banach space. Funkcial. Ekvac. 19 (1976), 239-245.
[5] L. A. Medeiros: On nonlinear differential equations in Hilbert spaces. Amer. Math. Monthly 76 (1969), 1024-1027.

Author's address: Antoni Augustynowicz, Institute of Mathematics, Gdańsk University, ul. Wita Stwosza 57, 80-952 Gdańsk, Poland.

