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### MATHEMATICA BOHEMICA

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## LINEAR STIELTJES INTEGRAL EQUATIONS IN BANACH SPACES II; OPERATOR VALUED SOLUTIONS

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Abstract. This paper is a continuation of [9]. In [9] results concerning equations of the form

$$x(t) = x(a) + \int_{a}^{t} d[A(s)]x(s) + f(t) - f(a)$$

were presented. The Kurzweil type Stieltjes integration in the setting of [6] for Banach space valued functions was used.

Here we consider operator valued solutions of the homogeneous problem

$$\Phi(t) = I + \int_d^t d[A(s)]\Phi(s)$$

as well as the variation-of-constants formula for the former equation.

 $Keywords\colon$  linear Stieltjes integral equations, generalized linear differential equation, equation in Banach space

MSC 1991: 34G10, 45N05

Assume that X is a Banach space and that L(X) is the Banach space of all bounded linear operators  $A \colon X \to X$  with the uniform operator topology. Defining the bilinear form  $B \colon L(X) \times X \to X$  by  $B(A, x) = Ax \in X$  for  $A \in L(X)$  and  $x \in X$ , we obtain in a natural way the bilinear triple  $\mathcal{B} = (L(X), X, X)$  (see [6]) because using the usual operator norm we have

# $||B(A,x)||_X \leq ||A||_{L(X)} ||x||_X.$

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Similarly, if we define the bilinear form  $B^*: L(X) \times L(X) \to L(X)$  by the relation  $B^*(A, C) = AC \in L(X)$  for  $A, C \in L(X)$  where AC is the composition of the linear operators A and C we get the bilinear triple  $B^* = (L(X), L(X), L(X))$  because we have

$$||B^*(A,C)||_{L(X)} \leq ||AC||_{L(X)} \leq ||A||_{L(X)} ||C||_{L(X)}$$

Assume that  $[a, b] \subset \mathbb{R}$  is a bounded interval.

Given  $A \colon [a, b] \to L(X)$ , the function A is of bounded variation on [a, b] if

$$\sup_{[a,b]} (A) = \sup \left\{ \sum_{j=1}^{k} \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)} \right\} < \infty$$

where the supremum is taken over all finite partitions

$$D: a = \alpha_0 < \alpha_1 < \ldots < \alpha_{k-1} < \alpha_k = b$$

of the interval [a, b]. The set of all functions  $A : [a, b] \to L(X)$  with  $\underset{[a, b]}{\operatorname{var}}(A) < \infty$  will be denoted by BV([a, b]; L(X)).

For  $A \colon [a, b] \to L(X)$  and a partition D of the interval [a, b] define

$$V_a^b(A,D) = \sup\left\{ \left\| \sum_{j=1}^k [A(\alpha_j) - A(\alpha_{j-1})] y_j \right\|_X \right\}$$

where the supremum is taken over all possible choices of  $y_j \in X, j=1,\dots,k$  with  $\|y_j\|\leqslant 1$  and similarly

$${}^{*}_{a}{}^{b}(A,D) = \sup\left\{ \left\| \sum_{j=1}^{k} [A(\alpha_{j}) - A(\alpha_{j-1})]C_{j} \right\|_{L(X)} \right\}$$

where the supremum is taken over all possible choices of  $C_j \in L(X), j=1,\dots,k$  with  $\|C_j\|_{L(X)} \leqslant 1.$ 

Define

$$(\mathcal{B})\operatorname{var}(A) = \sup V_a^b(A, D)$$

and

$$(\mathcal{B}^*) \operatorname{var}_{[a,b]}(A) = \sup \overset{*}{V}{}^b_a(A,D)$$

where the supremum is taken over all finite partitions

$$D: a = \alpha_0 < \alpha_1 < \ldots < \alpha_{k-1} < \alpha_k = b$$

of the interval [a, b].

The function  $A: [a, b] \to L(X)$  with  $(\mathcal{B}) \underset{[a, b]}{\operatorname{var}}(A) < \infty$  is called a function with bounded  $\mathcal{B}$ -variation on [a, b] and similarly if  $(\mathcal{B}^*) \underset{[a, b]}{\operatorname{var}}(A) < \infty$  then A is of bounded  $\mathcal{B}^*$ -variation on [a, b] ([3]).

We denote by  $(\mathcal{B})BV([a,b];L(X))$  the set of all functions  $A: [a,b] \to L(X)$  with  $(\mathcal{B}) \underset{[a,b]}{\operatorname{var}}(A) < \infty$  and by  $(\mathcal{B}^*)BV([a,b];L(X))$  the set of all functions  $A: [a,b] \to L(X)$  with  $(\mathcal{B}^*) \underset{[a,b]}{\operatorname{var}}(A) < \infty$ .

In [9, Prop. 1.1 and 1.2] it is shown that

$$BV([a,b];L(X)) \subset (\mathcal{B})BV([a,b];L(X)) = (\mathcal{B}^*)BV([a,b];L(X))$$

holds.

Given  $x: [a, b] \to X$ , the function x is called *regulated on* [a, b] if it has one-sided limits at every point of [a, b], i.e. if for every  $s \in [a, b)$  there is a value  $x(s+) \in X$  such that

$$\lim_{t \to s^+} \|x(t) - x(s^+)\|_X = 0$$

and if for every  $s \in (a, b]$  there is a value  $x(s-) \in X$  such that

$$\lim ||x(t) - x(s-)||_X = 0$$

The set of all regulated functions  $x: [a,b] \to X$  will be denoted by G([a,b];X)and similarly we denote the set of all regulated functions  $A: [a,b] \to L(X)$  by G([a,b];L(X)).

If  $\mathcal{B} = (L(X), X, X)$  is the bilinear triple of Banach spaces mentioned above then a function  $A : [a, b] \to L(X)$  is called  $\mathcal{B}$ -regulated on [a, b] if for every  $y \in X$ ,  $||y||_X \leq 1$ , the function  $Ay : [a, b] \to X$  given by  $t \in [a, b] \mapsto A(t)y \in X$  for  $t \in [a, b]$  is regulated, i.e.  $Ay \in G([a, b]; X)$  for every  $y \in X$ ,  $||y||_X \leq 1$ .

We denote by  $(\mathcal{B})G([a,b];L(X))$  the set of all  $\mathcal{B}\text{-regulated}$  functions  $A\colon [a,b]\to L(X).$ 

#### 1. EQUATIONS WITH OPERATOR VALUED SOLUTIONS

For [a, b] = [0, 1] we denote shortly

$$BV(L(X)) = BV([0,1]; L(X)), (\mathcal{B})BV(L(X)) = (\mathcal{B})BV([0,1]; L(X)),$$

 $G(L(X)) = G([0,1]; L(X)) \text{ and } (\mathcal{B})G(L(X)) = (\mathcal{B})G([0,1]; L(X)).$ 

Assume that  $A \colon [0,1] \to L(X)$  satisfies

(1.1) 
$$A \in (\mathcal{B})BV(L(X)) \cap (\mathcal{B})G(L(X))$$

and the following condition (E) (see [9]):

for every  $d \in [0,1]$  there are  $0 < \varrho = \varrho(d) < 1$  and  $\Delta = \Delta(d) > 0$  such that

(E+) 
$$(\mathcal{B}) \operatorname{var}_{(d,d+\Delta) \cap [0,1]}(A) < \varrho$$

and

(E–) 
$$(\mathcal{B}) \underset{[d-\Delta,d)\cap[0,1]}{\operatorname{var}} (A) < \varrho.$$

Taking the bilinear triple  $\mathcal{B}^* = (L(X), L(X), L(X)),$  by Proposition 1.1 in [9] we have

 $(\mathcal{B})BV(L(X))=(\mathcal{B}^*)BV(L(X))$ 

and

$$(\mathcal{B}) \operatorname{var}_{[a,b]}(A) = (\mathcal{B}^*) \operatorname{var}_{[a,b]}(A)$$

for every  $[a, b] \subset [0, 1]$ . Therefore condition (1.1) reads

(1.1) 
$$A \in (\mathcal{B}^*)BV(L(X)) \cap (\mathcal{B})G(L(X)),$$

and in condition (E) the symbol  $\beta$  can also be replaced by  $\beta^*$ , i.e. condition (E) reads for every  $d \in [0, 1]$  there are  $0 < \varrho = \varrho(d) < 1$  and  $\Delta = \Delta(d) > 0$  such that

$$(E+) \qquad \qquad (\mathcal{B}^*) \operatorname{var}_{(d \ d + \Delta) \cap [0, 1]}(A) < \varrho$$

and

(E–) 
$$(\mathcal{B}^*) \underset{[d-\Delta,d)\cap[0,1]}{\operatorname{var}} (A) < \varrho$$

Hence the results presented in Section 2 from  $\left[9\right]$  can be used for equations of the form

(1.2) 
$$Y(t) = \tilde{Y} + \int_{d}^{t} d[A(s)]Y(s) + F(t) - F(d)$$

for every  $t \in [0,1]$  where  $F \in G(L(X)), d \in [0,1]$  and  $\tilde{Y} \in L(X)$ .

The operator valued function  $Y : [\alpha, \beta] \to L(X)$  is called a solution of (1.2) on an interval  $[\alpha, \beta] \subset [0, 1]$  if Y satisfies (1.2) for every  $t \in [\alpha, \beta]$ . If  $d \in [\alpha, \beta]$  then of course we have  $Y(d) = \tilde{Y}$  for this solution.

With regard to the above mentioned facts we obtain by a simple reformulation of Proposition 2.4 and Theorem 2.10 from [9] the following

**1.1. Theorem.** Assume that  $A: [0,1] \to L(X)$  satisfies (1.1) and condition (E). Then for every  $d \in [0,1]$ ,  $\tilde{Y} \in X$ ,  $F \in G(L(X))$  there is a  $\Delta > 0$  such that for the interval  $J_d = [d - \Delta, d + \Delta] \cap [0,1]$  there is a unique function  $Y \in G(J_d; L(X))$  such that

$$Y(t) = \widetilde{Y} + \int_d^t d[A(s)]Y(s) + F(t) - F(d), \ t \in J_d,$$

i.e. Y(t) is a local solution of the operator valued equation (1.2) on  $J_d = [d - \Delta, d + \Delta] \cap [0, 1].$  If

(1.3)  $A \in (\mathcal{B})BV(L(X)) \cap G(L(X)),$ 

condition (U):

(U+) 
$$[I + \Delta^+ A(t)]^{-1} \in L(X)$$
 exists for every  $t \in [0, 1)$ 

and

(U-) 
$$[I - \Delta^{-}A(t)]^{-1} \in L(X) \text{ exists for every } t \in (0, 1]$$

and (E) hold, then for every choice of  $d \in [0,1]$ ,  $\tilde{Y} \in L(X)$ ,  $F \in G([0,1]; L(X))$  there exists a unique  $Y \in G([0,1]; X)$  which is a (global) solution of (1.2) on [0,1].

Let us consider the special case of the equation (1.2) with  ${\cal F}$  a constant, i.e. the so called homogeneous equation

(1.4) 
$$Y(t) = \widetilde{Y} + \int_d^t \mathbf{d}[A(s)]Y(s).$$

Theorem 1.1 applies to this equation and therefore there is a unique (global) solution to this equation and this operator valued solution is regulated provided  $A: [0,1] \rightarrow L(X)$  satisfies (1.3), (E) and (U).

Together with (1.4) let us consider the equation

(1.5) 
$$\Phi(t) = I + \int_d^t \mathbf{d}[A(s)]\Phi(s)$$

where  $I \in L(X)$  is the identity operator.

Clearly every solution  $Y: [0,1] \to L(X)$  of (1.4) can be written in the form

$$Y(t) = \Phi(t)\widetilde{Y}, \quad t \in [0, 1].$$

Let us now consider the properties of the solution  $\Phi: [0,1] \to L(X)$  of (1.5).

**1.2. Lemma.** Assume that  $A: [0,1] \to L(X)$  satisfies (1.3), (E) and (U). Then for the solution  $\Phi: [0,1] \to L(X)$  of (1.5) we have

 $\Phi \in (\mathcal{B})BV(L(X)) \cap G(L(X))$ 

and there is a constant K > 0 such that  $\|\Phi(t)\| \leq K$  for every  $t \in [0, 1]$ .

Proof. By Theorem 1.1  $\Phi \in G([0,1]; L(X))$  and therefore there exists a K > 0 such that  $\|\Phi(t)\| \leq K$  for every  $t \in [0,1]$ . It remains to show that  $\Phi \in (\mathcal{B})BV([0,1]; L(X))$ .

Assume that

$$D: 0 = \alpha_0 < \alpha_1 < \ldots < \alpha_{k-1} < \alpha_k = 1$$

is an arbitrary partition of the interval [0, 1].

For any  $y_j \in X, j = 1, ..., k$  with  $||y_j|| \leq 1$  we have

$$\sum_{j=1}^{k} [\Phi(\alpha_j) - \Phi(\alpha_{j-1})] y_j \Big\|_X = \Big\| \sum_{j=1}^{k} \int_{\alpha_{j-1}}^{\alpha_j} \mathrm{d}[A(s)] \Phi(s) y_j \Big\|_X$$

Define

$$\varphi(s) = \Phi(s)y_j \text{ for } s \in (\alpha_{j-1}, \alpha_j) \text{ and } \varphi(s) = 0 \text{ for } s = \alpha_j$$

Evidently  $\|\varphi(s)\| \leq K$ . Then by 1.18 from [9] we get

$$\int_{\alpha_{j-1}}^{\alpha_j} \mathrm{d}[A(s)]\Phi(s)y_j = \int_{\alpha_{j-1}}^{\alpha_j} \mathrm{d}[A(s)]\varphi(s)$$

+ 
$$[A(\alpha_{j-1}+) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_j + [A(\alpha_j) - A(\alpha_j-)]\Phi(\alpha_j)y_j$$

and  

$$\begin{split} &\left\|\sum_{j=1}^{k} \int_{\alpha_{j-1}}^{\alpha_{j}} d[A(s)\Phi(s)y_{j}\|_{X} = \left\|\sum_{j=1}^{k} \int_{\alpha_{j-1}}^{\alpha_{j}} d[A(s)]\varphi(s) + [A(\alpha_{j-1}+) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_{j} + [A(\alpha_{j}) - A(\alpha_{j}-)]\Phi(\alpha_{j})y_{j}\right\|_{X} \\ &= \left\|\int_{0}^{1} d[A(s)]\varphi(s) + \sum_{j=1}^{k} [A(\alpha_{j-1}+) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_{j} + \sum_{j=1}^{k} [A(\alpha_{j}) - A(\alpha_{j}-)]\Phi(\alpha_{j})y_{j}\right\|_{X} \le \left\|\int_{0}^{1} d[A(s)]\varphi(s)\right\|_{X} \\ &+ \left\|\sum_{j=1}^{k} [A(\alpha_{j-1}+) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_{j}\right\|_{X} + \left\|\sum_{j=1}^{k} [A(\alpha_{j}) - A(\alpha_{j}-)]\Phi(\alpha_{j})y_{j}\right\|_{X}. \end{split}$$
 For a given  $\eta > 0$  let us choose a  $\theta > 0$  such that

$$\|A(\alpha_{j-1}+\theta) - A(\alpha_{j-1}+)\|_{L(X)} < \frac{\eta}{k+1}$$

and

$$\|A(\alpha_j - \theta) - A(\alpha_j - \eta)\|_{L(X)} < \frac{\eta}{k+1}$$

for all  $j = 1, \ldots, k$ . Then

$$\begin{split} \left\| \sum_{j=1}^{k} [A(\alpha_{j-1}+) - A(\alpha_{j-1})] \Phi(\alpha_{j-1}) y_j \right\|_X \\ &= \left\| \sum_{j=1}^{k} [A(\alpha_{j-1}+) - A(\alpha_{j-1}+\theta) + A(\alpha_{j-1}+\theta) - A(\alpha_{j-1})] \Phi(\alpha_{j-1}) y_j \right\|_X \\ &\leqslant \left\| \sum_{j=1}^{k} [A(\alpha_{j-1}+) - A(\alpha_{j-1}+\theta)] \Phi(\alpha_{j-1}) y_j \right\|_X \\ &+ \left\| \sum_{j=1}^{k} [A(\alpha_{j-1}+\theta) - A(\alpha_{j-1})] \Phi(\alpha_{j-1}) y_j \right\|_X \\ &< \sum_{j=1}^{k} \frac{K\eta}{k+1} + \left\| \sum_{j=1}^{k} [A(\alpha_{j-1}+\theta) - A(\alpha_{j-1})] \Phi(\alpha_{j-1}) y_j \right\|_X \\ &< K\eta + K(\mathcal{B}) \operatorname{var}(\mathcal{A}) \end{split}$$

and similarly also

$$\sum_{j=1}^{\kappa} [A(\alpha_j) - A(\alpha_j - )] \Phi(\alpha_j) y_j \Big\|_X < K\eta + K(\mathcal{B}) \operatorname{var}_{[0,1]}(A).$$

By 1.11 from [9] we have further

$$\Big\|\int_0^1\,\mathrm{d}[A(s)]\varphi(s)\Big\|_X\leqslant K(\mathcal{B}) \mathop{\mathrm{var}}_{[0,1]}(A)$$

and finally we obtain

$$\Big\|\sum_{j=1}^{k} [\Phi(\alpha_{j}) - \Phi(\alpha_{j-1})y_{j}\Big\|_{X} = \Big\|\sum_{j=1}^{k} \int_{\alpha_{j-1}}^{\alpha_{j}} d[A(s)]\Phi(s)y_{j}\Big\|_{X} < 2K\eta + 3K(\mathcal{B}) \max_{[0,1]}(A).$$

Passing to the corresponding suprema we arrive easily at

$$(\mathcal{B}) \operatorname{var}_{[0,1]}(\Phi) \leq 3K(\mathcal{B}) \operatorname{var}_{[0,1]}(A) < \infty,$$

i.e.  $\Phi \in (\mathcal{B})BV([0,1]; L(X)).$ 

**1.3. Lemma.** Assume that  $A: [0,1] \rightarrow L(X)$  satisfies (1.3), (E) and (U).

Then the solution  $\Phi\colon [0,1]\to L(X)$  of (1.5) has an inverse  $[\Phi(t)]^{-1}\in L(X)$  for every  $t\in [0,1].$ 

Proof. For t = d we have  $\Phi(t) = \Phi(d) = I$  and the inverse  $[\Phi(t)]^{-1}$  evidently exists for this value.

Assume that there is a point  $t^* \in [0, 1]$  such that the inverse  $[\Phi(t^*)]^{-1}$  does not exist. Then there exists  $y \in X$  such that the equation

 $\Phi(t^*)z = y$ 

has no solution in X. Assume that  $\Psi\colon [0,1]\to L(X)$  is a solution of the operator valued equation

$$\Psi(t) = I + \int_{t^*}^t \mathbf{d}[A(s)]\Psi(s)$$

this solution exists and is uniquely determined by the second part of Theorem 1.1. Let us set  $z = \Psi(d)y$ . The function  $x \colon [0,1] \to X$  given by  $x(t) = \Psi(t)y$  is a solution of the equation

$$\mathbf{r}(t) = y + \int_{t^*}^t \mathbf{d}[A(s)]\mathbf{x}(s)$$

with  $x(t^*) = y$  and  $x(d) = \Psi(d)y$ . On the other hand,  $\varphi(t) = \Phi(t)z$  is a solution of

$$\varphi(t) = z + \int_d^t \mathbf{d}[A(s)]\varphi(s)$$

where  $\varphi(d) = z = \Psi(d)y = x(d)$  and

$$x(t) = x(d) + \int_d^t \mathrm{d}[A(s)]x(s).$$

Hence by the uniqueness of a solution stated in Theorem 2.10 from [9] we have  $x(t)=\varphi(t)$  for all  $t\in[0,1].$  Therefore

$$x(t^*) = y = \varphi(t^*) = \Phi(t^*)z = \Phi(t^*)\Psi(d)y,$$

i.e.  $z = \Psi(d)y \in X$  is a solution of the equation  $\Phi(t^*)z = y$ . This contradicts the assumption and proves that the operator  $\Phi(t) \in L(X)$  has an inverse for every  $t \in [0, 1]$ .

**1.4. Lemma.** Assume that  $A: [0, 1] \to L(X)$  satisfies (1.3), (E) and (U). Then the inverse  $[\Phi(t)]^{-1} = \Phi^{-1}(t)$  to the solution  $\Phi: [0, 1] \to L(X)$  of (1.5) belongs to G(L(X)) and there is a constant L > 0 such that

$$\|\Phi^{-1}(t)\|_{L(X)} \leq L$$

for every  $t \in [0, 1]$ .

Proof. By Theorem 1.1 we have  $\Phi \in G(L(X))$  and therefore the onesided limits of this function exist at every point of [0,1]. E. g., the limit  $\lim_{r \to t+} \Phi(r)$  exists for every  $t \in [0,1)$  and by 1.18 from [9] we have

$$\begin{split} \lim_{r \to t+} \Phi(r) &= I + \lim_{r \to t+} \int_d^r \mathbf{d}[A(s)] \Phi(s) = I + \int_d^t \mathbf{d}[A(s)] \Phi(s) \\ &+ \lim_{r \to t+} \int_t^r \mathbf{d}[A(s)] \Phi(s) = \Phi(t) + \lim_{r \to t+} \int_t^r \mathbf{d}[A(s)] \Phi(s) \\ &= \Phi(t) + [A(t+) - A(t)] \Phi(t) = [I + \Delta^+ A(t)] \Phi(t). \end{split}$$

Hence  $\Phi(t+) = [I + \Delta^+ A(t)]\Phi(t)$  and because  $\Phi^{-1}(t)$  exists by Lemma 1.3 and the inverse  $[I + \Delta^+ A(t)]^{-1}$  exists by (U+) from the assumption (U) the inverse  $[\Phi(t+)]^{-1} = \Phi^{-1}(t+)$  also exists and we have the relation

$$[\Phi(t+)]^{-1} = \Phi^{-1}(t+) = \Phi^{-1}(t) \cdot [I + \Delta^+ A(t)]^{-1}, \quad t \in [0,1).$$

Similarly we have also

$$\Phi^{-1}(t-) = \Phi^{-1}(t) \cdot [I - \Delta^{-}A(t)]^{-1}, \quad t \in (0,1]$$

where  $\Phi^{-1}(t-) = [\Phi(t-)]^{-1}$ .

Using the continuity of the operation of taking an inverse (see [2], p. 624) we obtain

$$\lim_{t \to 0} \Phi^{-1}(r) = \Phi^{-1}(t+) \text{ for } t \in [0,1)$$

and

$$\lim_{r \to t^{-}} \Phi^{-1}(r) = \Phi^{-1}(t^{-}) \text{ for } t \in (0,1]$$

because  $\lim_{r \to t^+} \Phi(r) = \Phi(t^+)$  for  $t \in [0, 1)$  and  $\lim_{r \to t^-} \Phi(r) = \Phi(t^-)$  for  $t \in (0, 1]$ .

Hence the operator valued function  $\Phi^{-1}: [0,1] \to L(X)$  belongs to the space G(L(X)) and it is therefore bounded, i.e. there is an  $L \ge 0$  such that

$$\|\Phi^{-1}(t)\|_{L(X)} \leq L$$

for every  $t \in [0, 1]$ .

**1.5. Lemma.** Assume that  $A: [0,1] \rightarrow L(X)$  satisfies (1.3), (E) and (U).

Assume that  $d \in [0,1]$  is fixed and that  $\Phi: [0,1] \to L(X)$  is the solution of (1.5). Then for every  $t_0 \in [0,1]$  and  $\tilde{x} \in X$ , the unique solution  $x: [0,1] \to X$  of the homogeneous equation

$$x(t) = \tilde{x} + \int_{t_0}^t d[A(s)]x(s)$$

is given by the relation

$$x(t) = \Phi(t)\Phi^{-1}(t_0)\tilde{x}, \quad t \in [0,1].$$

 $\mathbf{Proof.}$  The solution x exists and is unique by Theorem 2.11 in [9]. Using (1.1) we have

$$\begin{split} \mathbf{x}(t) &= \Phi(t)\Phi^{-1}(t_0)\widetilde{x} = \left[I + \int_d^t \mathbf{d}[A(s)]\Phi(s)\right]\Phi^{-1}(t_0)\widetilde{x} \\ &= \left[I + \int_d^{t_0} \mathbf{d}[A(s)]\Phi(s) + \int_{t_0}^t \mathbf{d}[A(s)]\Phi(s)\right]\Phi^{-1}(t_0)\widetilde{x} \\ &= \Phi(t_0)\Phi^{-1}(t_0)\widetilde{x} + \int_{t_0}^t \mathbf{d}[A(s)]\Phi(s)\Phi^{-1}(t_0)\widetilde{x} = \widetilde{x} + \int_{t_0}^t \mathbf{d}[A(s)]x(s) \end{split}$$

and the lemma is proved.

### 2. VARIATION OF CONSTANTS

**2.1. Lemma.** Assume that  $A: [0,1] \to L(X)$  satisfies (1.3), (E) and (U). Let  $\Phi: [0,1] \to L(X)$  be the solution of (1.5) and assume that its inverse  $\Phi^{-1}: [0,1] \to L(X)$  given by Lemma 1.3 is such that  $\Phi^{-1} \in (\mathcal{B})BV(L(X))$ .

Then for every  $g \in G(X)$ ,  $t \in [0, 1]$  the equality

$$(2.1) \quad \int_{d}^{t} \mathbf{d}[A(r)]\Phi(r) \int_{d}^{r} \mathbf{d}[\Phi^{-1}(s)]g(s) = \Phi(t) \int_{d}^{t} \mathbf{d}[\Phi^{-1}(s)]g(s) + \int_{d}^{t} \mathbf{d}[A(s)]g(s)$$

holds.

Proof. Since  $g \in G(X)$  and  $\Phi^{-1} \in (\mathcal{B})BV(L(X))$ , the integrals on both sides of (2.1) exist by [6, Theorem 11] (see also [9, 1.12]).

To show that the equality (2.1) is valid for every regulated function  $g: [0, 1] \to X$ it is sufficient to prove it for an arbitrary finite step function, because the finite step functions are dense in the space G(X) (see [2]).

For a given  $\alpha \in [0, 1], c \in X$  and for  $s \in [0, 1]$  we define

$$\psi_{\alpha}^{+}(s) = 0 \text{ if } s \leq \alpha, \qquad \psi_{\alpha}^{+}(s) = c \text{ if } s > \alpha$$

and

$$\psi_{\alpha}^{-}(s) = 0$$
 if  $s < \alpha$ ,  $\psi_{\alpha}^{-}(s) = c$  if  $s \ge \alpha$ .

It is a matter of routine to verify that every finite step function can be expressed in the form of a finite sum of functions of the the type  $\psi_{\alpha}^+$  and  $\psi_{\alpha}^-$ . Hence by the linearity of the integral it suffices to show that (2.1) holds for functions of this type.

Let us prove e.g. that (2.1) is satisfied for the function  $\psi_{\alpha}^+.$ 

Assume that  $\alpha < d$ . Then

$$\int_{d}^{r} \mathbf{d}_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi^{-1}(r) - \Phi^{-1}(d)]c \text{ if } r > \alpha$$

and

(2.2) 
$$\int_{d}^{r} d_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c \text{ if } r \leq \alpha.$$

Hence for  $t > \alpha$  we have

(2.3) 
$$\int_{d}^{t} d[A(r)]\Phi(r) \int_{d}^{r} d_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s)$$

$$= \int_{d}^{t} d[A(r)]\Phi(r)[\Phi^{-1}(r) - \Phi^{-1}(d)]c = \int_{d}^{t} d[A(r)][I - \Phi(r)\Phi^{-1}(d)]c$$

$$= [A(t) - A(d)]c - [\Phi(t) - \Phi(d)]\Phi^{-1}(d)c = [A(t) - A(d)]c + c - \Phi(t)\Phi^{-1}(d)c.$$
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If 
$$t \leq \alpha$$
 then  

$$\int_{d}^{t} d[A(r)]\Phi(r) \int_{d}^{r} d_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = -\int_{t}^{d} d[A(r)]\Phi(r) \int_{d}^{r} d_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s)$$

$$= -\left(\int_{t}^{\alpha} d[A(r)]\Phi(r) \int_{d}^{r} d_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) + \int_{\alpha}^{d} d[A(r)]\Phi(r) \int_{d}^{r} d_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s)\right)$$
and

$$\begin{aligned} & \int_{\alpha}^{d} d[A(r)]\Phi(r) \int_{d}^{r} d_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) \\ &= [A(\alpha+) - A(\alpha)]\Phi(\alpha)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c \\ &+ \lim_{\delta \to 0+} \int_{\alpha+\delta}^{d} d[A(r)]\Phi(r)[\Phi^{-1}(r) - \Phi^{-1}(d)]c \\ &= [A(\alpha+) - A(\alpha)]\Phi(\alpha)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c \\ &+ \lim_{\delta \to 0+} \int_{\alpha+\delta}^{d} d[A(r)]c - \lim_{\delta \to 0+} \int_{\alpha+\delta}^{d} d[A(r)]\Phi(r)\Phi^{-1}(d)c \\ &= [A(\alpha+) - A(\alpha)]\Phi(\alpha)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c + [A(d) - A(\alpha+)]c \\ &- [\Phi(d) - \Phi(\alpha+)]\Phi^{-1}(d)c. \end{aligned}$$

Further we have

$$\int_{t}^{\alpha} d[A(r)]\Phi(r) \int_{d}^{r} d_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(\alpha + 1) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(\alpha + 1) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(\alpha + 1) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(\alpha + 1) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(\alpha + 1) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(\alpha + 1) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(\alpha + 1) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(\alpha + 1) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(\alpha + 1) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(s) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(s) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]e^{-1}(s) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi^{-1}(s)]e^{-1}(s) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi^{-1}(s)]e^{-1}(s) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi(\alpha) - \Phi^{-1}(s)]e^{-1}(s) + \frac{1}{2} \int_{0}^{t} ds [\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi^{-1}(s)$$

and

$$\begin{split} &\int_{d}^{t} \mathbf{d}[A(r)] \Phi(r) \int_{d}^{r} \mathbf{d}_{s}[\Phi^{-1}(s)] \psi_{\alpha}^{+}(s) \\ &= -\{[A(\alpha+) - A(\alpha)] \Phi(\alpha) [\Phi^{-1}(\alpha+) - \Phi^{-1}(d)] c + [A(d) - A(\alpha+)] \\ &- [\Phi(d) - \Phi(\alpha+)] \Phi^{-1}(d) c + [\Phi(\alpha) - \Phi(t)] [\Phi^{-1}(\alpha+) - \Phi^{-1}(d)] c \} \end{split}$$

Since  $[A(\alpha+) - A(\alpha)]\Phi(\alpha) = \Delta^+ A(\alpha)\Phi(\alpha) = \Phi(\alpha+) - \Phi(\alpha)$  we have  $\int_{-1}^{t} \frac{1}{A(-\alpha)\Phi(\alpha)} \int_{-1}^{t} \frac{1}{A(-\alpha)\Phi(\alpha)} \int_{-1}^{$ 

$$\int_{d}^{1} d[A(r)]\Phi(r) \int_{d}^{1} d_{s}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s)$$

$$= -\{[\Phi(\alpha+) - \Phi(\alpha)][\Phi^{-1}(\alpha+) - \Phi^{-1}(d)] + [A(d) - A(\alpha+)]$$

$$(2.4) \qquad -I + \Phi(\alpha+)\Phi^{-1}(d) + \Phi(\alpha)\Phi^{-1}(\alpha+) - \Phi(\alpha)\Phi^{-1}(d)$$

$$- \Phi(t)\Phi^{-1}(\alpha+) + \Phi(t)\Phi^{-1}(d)\}c$$

$$= -\{[A(d) - A(\alpha+)] - \Phi(t)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]\}c$$

$$= [A(\alpha+) - A(d)]c + \Phi(t)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c$$

for  $t \leq \alpha$ .

For the right hand side of (2.1) we use (2.2) for obtaining

$$\Phi(t) \int_{d}^{t} d[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = \Phi(t)[\Phi^{-1}(t) - \Phi^{-1}(d)]c \text{ if } t > c$$

and

(2.5) 
$$\Phi(t) \int_{d}^{t} d[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) = [\Phi^{-1}(\alpha +) - \Phi^{-1}(d)]c \text{ if } t \leq \alpha$$

Now it is a matter of routine to show that

$$\int_{d}^{t} \mathbf{d}[A(s)]\psi_{\alpha}^{+}(s) = [A(t) - A(d)]c \text{ if } t > c$$

and

(2.6) 
$$\int_d^t \mathbf{d}[A(s)]\psi_\alpha^+(s) = [A(\alpha+) - A(d)]c \text{ if } t \leq \alpha.$$

Using (2.5) and (2.6) we obtain

$$\begin{split} \Phi(t) & \int_{d}^{t} \mathrm{d}[\Phi^{-1}(s)]\psi_{\alpha}^{+}(s) + \int_{d}^{t} \mathrm{d}[A(s)]\psi_{\alpha}^{+}(s) \\ &= -\Phi(t)[\Phi^{-1}(t) - \Phi^{-1}(d)]c + [A(t) - A(d)]c \text{ if } t > c \end{split}$$

and

$$\begin{split} \Phi(t) \int_d^t \mathrm{d}[\Phi^{-1}(s)]\psi_\alpha^+(s) + \int_d^t \mathrm{d}[A(s)]\psi_\alpha^+(s) \\ &= [\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c + [A(\alpha+) - A(d)]c \ \text{ if } \ t \leqslant \alpha. \end{split}$$

Looking at (2.3) and (2.4) we can see immediately that the equality (2.1) holds for the function  $\psi_\alpha^+$  if  $\alpha < d.$ 

For  $\alpha \ge d$  as well as for the case of the function  $\psi_{\alpha}^{-}$  the result can be proved similarly. The computations are straightforward but slightly tedious.

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Let us assume that  $A\colon [0,1]\to L(X)$  satisfies (1.3), (E) and (U). Let us consider the equation

(2.7) 
$$x(t) = \tilde{x} + \int_{t_0}^t d[A(s)]x(s) + f(t) - f(t_0).$$

By [9, Theorem 2.10] we obtain that for every choice of  $t_0 \in [0, 1]$ ,  $\tilde{x} \in X$ ,  $f \in G(X)$  there exists  $x \in G(X)$  such that

$$x(t) = \tilde{x} + \int_{t_0}^t d[A(s)]x(s) + f(t) - f(t_0)$$

for every  $t \in [0, 1]$ .

This solution of (2.7) is determined uniquely.

**2.2. Theorem.** Assume that  $A: [0,1] \to L(X)$  satisfies (1.3), (E) and (U). Let  $\Phi: [0,1] \to L(X)$  be the solution of (1.5) and assume that its inverse  $\Phi^{-1}: [0,1] \to L(X)$  given by Lemma 1.3 is such that  $\Phi^{-1} \in (B)BV(L(X))$ .

Then for every  $t_0 \in [0, 1]$ ,  $\tilde{x} \in X$  and  $f \in G(X)$  the formula

(2.8) 
$$x(t) = \Phi(t)\Phi^{-1}(t_0)\tilde{x} + f(t) - f(t_0) - \Phi(t)\int_{t_0}^t \mathrm{d}[\Phi^{-1}(s)](f(s) - f(t_0)),$$

 $t \in [0, 1]$ , represents a solution of (2.7).

Proof. Using (2.8) we have for  $t \in [0, 1]$ 

$$\begin{split} \int_{t_0}^t \mathrm{d}[A(r)]x(r) \\ &= \int_{t_0}^t \mathrm{d}[A(r)] \Big\{ \Phi(r) \Phi^{-1}(t_0) \widetilde{x} + f(r) - f(t_0) - \Phi(r) \int_{t_0}^r \mathrm{d}[\Phi^{-1}(s)](f(s) - f(t_0)) \Big\} \\ &= \int_{t_0}^t \mathrm{d}[A(r)] \Phi(r) \Phi^{-1}(t_0) \widetilde{x} + \int_{t_0}^t \mathrm{d}[A(r)](f(r) - f(t_0)) \\ &- \int_{t_0}^t \mathrm{d}[A(r)] \Phi(r) \int_{t_0}^r \mathrm{d}[\Phi^{-1}(s)](f(s) - f(t_0)). \end{split}$$

For a solution  $\Phi$  of (1.5) we have

$$\int_{t_0}^t \mathrm{d}[A(r)]\Phi(r) = \Phi(t) - \Phi(t_0)$$

and by Lemma  $2.1\ \rm we$  have

$$\int_{t_0}^t d[A(r)]\Phi(r) \int_{t_0}^r d[\Phi^{-1}(s)](f(s) - f(t_0))$$
  
=  $\Phi(t) \int_{t_0}^t d[\Phi^{-1}(s)](f(s) - f(t_0)) + \int_{t_0}^t d[A(s)](f(s) - f(t_0)).$ 

Therefore

$$\begin{split} \int_{t_0}^t \mathbf{d}[A(r)]x(r) \\ &= [\Phi(t) - \Phi(t_0)]\Phi^{-1}(t_0)\tilde{x} + \int_{t_0}^t \mathbf{d}[A(r)](f(r) - f(t_0)) \\ &- \Phi(t) \int_{t_0}^t \mathbf{d}[\Phi^{-1}(s)](f(s) - f(t_0)) - \int_{t_0}^t \mathbf{d}[A(s)](f(s) - f(t_0)) = \Phi(t)\Phi^{-1}(t_0)\tilde{x} - \tilde{x} \\ &- \Phi(t) \int_{t_0}^t \mathbf{d}[\Phi^{-1}(s)](f(s) - f(t_0)). \end{split}$$

Hence

$$\int_{t_0}^{t} d[A(r)]x(r) = x(t) - \tilde{x} - (f(s) - f(t_0))$$

for every  $t \in [0, 1]$  and this means that the function  $x: [0, 1] \to X$  given by (2.8) is a solution of the equation (2.7).

Remark. From the point of view of the variation-of-constants formula (2.8) presented in Theorem 2.2 the assumption that the inverse  $\Phi^{-1}: [0,1] \to L(X)$  to  $\Phi: [0,1] \to L(X)$  given by Lemma 1.3 is such that  $\Phi^{-1} \in (B)BV(L(X))$  is very unnatural. It would be nice if the property  $\Phi^{-1} \in (B)BV(L(X))$  could be derived from the general assumptions, i.e. from the fact that  $A: [0,1] \to L(X)$  satisfies (1.3), (E) and (U).

In the next section we will show that in the special situation of  $A \in BV(L(X))$ the variation-of-constants formula (2.8) holds without any further assumption.

3. The variation-of-constants formula for the case  $A \in BV(L(X))$ 

Assume throughout this section that  $A \in BV(L(X))$ .

First of all it should be mentioned that by [9, 1.5] we have  $A \in G(L(X))$  and therefore  $A: [0,1] \to L(X)$  evidently satisfies (1.3) because, as was already mentioned in the introductory part of this note, we have  $BV(L(X)) \subset (\mathcal{B})BV(L(X))$  by [9, Prop. 1.1 and 1.2].

As was mentioned in the last Remark in [9], if  $A \in BV(L(X))$  then A satisfies also condition (E).

Let us now prove the following proposition.

**3.1. Proposition.** Assume that  $A \colon [0,1] \to L(X)$ .

Then  $A \in BV(L(X))$  if and only if

(3.1) 
$$\sup_{P} \left\{ \sup_{C_j, D_j} \left\| \sum_{j=1}^{\kappa} D_j [A(\alpha_j - A(\alpha_{j-1})]C_j \right\|_{L(X)} \right\} < \infty$$

where  $P: 0 = \alpha_0 < \alpha_1 < \ldots < \alpha_{k-1} < \alpha_k = 1$  is a partition of [0, 1],  $C_j, D_j \in L(X)$  with  $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1, j = 1, \ldots, k$ , and

$$\sup_{[0,1]} (A) = \sup_{P} \left\{ \sup_{C_{j}, D_{j}} \left\| \sum_{j=1}^{k} D_{j} [A(\alpha_{j} - A(\alpha_{j-1})]C_{j} \right\|_{L(X)} \right\}$$

Proof. Assume that

 $P \colon 0 = \alpha_0 < \alpha_1 < \ldots < \alpha_{k-1} < \alpha_k = 1$ 

is an arbitrary partition of [0, 1].

If  $C_j, D_j \in L(X)$  with  $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1, j = 1, \dots, k$  then

$$\begin{split} \left\| \sum_{j=1}^{k} D_{j}[A(\alpha_{j}) - A(\alpha_{j-1})]C_{j} \right\|_{L(X)} \\ &\leqslant \sum_{j=1}^{k} \|D_{j}\|_{L(X)} \|A(\alpha_{j}) - A(\alpha_{j-1})\|_{L(X)} \|C_{j}\|_{L(X)} \\ &\leqslant \sum_{j=1}^{k} \|A(\alpha_{j}) - A(\alpha_{j-1})\|_{L(X)}. \end{split}$$

Hence

$$\sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)} \leqslant \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)}$$

where the supremum on the left hand side is taken over all  $C_j, D_j \in L(X)$  with  $\|C_j\|_{L(X)} \leq 1$ ,  $\|D_j\|_{L(X)} \leq 1$ . Consequently,

(3.2)  
$$\sup_{P} \left\{ \sup_{C_{j},D_{j}} \left\| \sum_{j=1}^{k} D_{j}[A(\alpha_{j}) - A(\alpha_{j-1})]C_{j} \right\|_{L(X)} \right\} \\ \leqslant \sup_{P} \sum_{j=1}^{k} \|A(\alpha_{j}) - A(\alpha_{j-1})\|_{L(X)} = \sup_{[0,1]} (A).$$

Assume that  $\widehat{D}_j \in L(X)$  with  $\|\widehat{D}_j\|_{L(X)} \leq 1$  and  $x_j \in X$  with  $\|x_j\|_X \leq 1, j = 1, \ldots, k$ . Let us take  $w \in X$  such that  $\|w\|_X = 1$ . Then for all  $j = 1, \ldots, k$  there exist  $\widehat{C}_j \in L(X)$  with  $\|\widehat{C}_j\|_{L(X)} \leq 1$  such that  $\widehat{C}_j w = x_j$ . Hence

$$\begin{split} \left\| \sum_{j=1}^{k} \widehat{D}_{j}[A(\alpha_{j}) - A(\alpha_{j-1})]x_{j} \right\|_{X} &= \left\| \sum_{j=1}^{k} \widehat{D}_{j}[A(\alpha_{j}) - A(\alpha_{j-1})]\widehat{C}_{j}w \right\|_{X} \\ &\leqslant \sup_{\|y\|_{X} \leqslant 1} \left\| \sum_{j=1}^{k} \widehat{D}_{j}[A(\alpha_{j}) - A(\alpha_{j-1})]\widehat{C}_{j}y \right\|_{X} \\ &= \left\| \sum_{j=1}^{k} \widehat{D}_{j}[A(\alpha_{j}) - A(\alpha_{j-1})]\widehat{C}_{j} \right\|_{L(X)} \\ &\leqslant \sup_{C_{j}, D_{j}} \left\| \sum_{j=1}^{k} D_{j}[A(\alpha_{j}) - A(\alpha_{j-1})]C_{j} \right\|_{L(X)} \end{split}$$

where the supremum on the right hand side is taken over all  $C_j, D_j \in L(X)$  with  $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1$ . Passing to the supremum over all  $\hat{D}_j \in L(X)$  with  $\|\hat{D}_j\|_{L(X)} \leq 1$  and  $x_j \in X$  with  $\|x_j\|_X \leq 1, j = 1, \ldots, k$  we get

(3.3)  
$$\sup_{x_j,D_j} \left\| \sum_{j=1}^k D_j[A(\alpha_j) - A(\alpha_{j-1})]x_j \right\|_X$$
$$\leqslant \sup_{C_j,D_j} \left\| \sum_{j=1}^k D_j[A(\alpha_j) - A(\alpha_{j-1})]C_j \right\|_{L(X)}$$

Assume that  $\varepsilon>0$  is given. Choose vectors  $x_j\in X$  with  $\|x_j\|_X\leqslant 1,\,j=1,\ldots,k$  such that

(3.4) 
$$\| [A(\alpha_j) - A(\alpha_{j-1})] x_j \|_X > \| [A(\alpha_j) - A(\alpha_{j-1})] \|_{L(X)} - \frac{\varepsilon}{k}.$$

Let us set

$$v_j = \frac{[A(\alpha_j) - A(\alpha_{j-1})]x_j}{\|[A(\alpha_j) - A(\alpha_{j-1})]x_j\|_X} \text{ if } [A(\alpha_j) - A(\alpha_{j-1})]x_j \neq 0$$

and

$$v_j = 0$$
 if  $[A(\alpha_j) - A(\alpha_{j-1})]x_j = 0.$ 

For  $v_j \neq 0$  let  $Y_j$  be the onedimensional subspace of X given by

$$Y_j = \{\lambda v_j; \lambda \in \mathbb{R}\}$$

and assume that  $\tilde{f}_j$  is a bounded linear functional on  $Y_j$  such that  $\tilde{f}_j(v_j) = 1$  and denote by  $f_j \in X^*$  its extension onto X with  $\|f_j\| = 1$ .

Assume that  $w \in X$  is fixed such that  $\|w\|_X = 1$  and define the linear operator  $D_j \in L(X)$  by the relation

$$D_j x = f_j(x)w, x \in X, j = 1, \dots, k.$$

Then certainly

$$||D_j||_{L(X)} = ||f_j|| ||w|| = 1$$

and

$$D_{j}[A(\alpha_{j}) - A(\alpha_{j-1})]x_{j} = \|A(\alpha_{j}) - A(\alpha_{j-1})]x_{j}\|_{X}D_{j}v_{j}$$
  
=  $\|A(\alpha_{j}) - A(\alpha_{j-1})]x_{j}\|_{X}f_{j}(v_{j})w = \|A(\alpha_{j}) - A(\alpha_{j-1})]x_{j}\|_{X}w.$ 

Hence by (3.4) we get

$$\begin{split} \left\| \sum_{j=1}^{k} D_{j}[A(\alpha_{j}) - A(\alpha_{j-1})] x_{j} \right\|_{X} &= \left\| \sum_{j=1}^{k} \left\| A(\alpha_{j}) - A(\alpha_{j-1}) \right\|_{X} w \|_{X} \\ &= \sum_{j=1}^{k} \|A(\alpha_{j}) - A(\alpha_{j-1})] x_{j} \|_{X} > \sum_{j=1}^{k} \left( \|A(\alpha_{j}) - A(\alpha_{j-1})\|_{L(X)} - \frac{\varepsilon}{k} \right) \\ &= \sum_{j=1}^{k} \|A(\alpha_{j}) - A(\alpha_{j-1})\|_{L(X)} - \varepsilon. \end{split}$$

Taking the supremum over all  $D_j \in L(X)$  with  $||D_j||_{L(X)} \leq 1$  and  $x_j \in X$  with  $||x_j||_X \leq 1, j = 1, \dots, k$  we get

$$\sup_{x_{j},D_{j}} \Big\| \sum_{j=1}^{k} D_{j}[A(\alpha_{j}) - A(\alpha_{j-1})]x_{j} \Big\|_{X} > \sum_{j=1}^{k} \|A(\alpha_{j}) - A(\alpha_{j-1})]\|_{L(X)} - \varepsilon$$

and using (3.3) we finally obtain

$$\sup_{C_j,D_j} \Big\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \Big\|_{L(X)} \ge \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})]\|_{L(X)} - \varepsilon.$$

Taking the supremum over all partitions P of [0,1] we obtain together with (3.2) for every  $\varepsilon>0$  the inequality

$$\operatorname{var}_{0,1}(A) - \varepsilon < \sup_{P} \left\{ \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)} \right\} \leq \operatorname{var}_{[0,1]}(A)$$

and therefore

$$\sup_{[0,1]} (A) = \sup_{P} \Big\{ \sup_{C_j, D_j} \Big\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \Big\|_{L(X)} \Big\}.$$

Remark. It has to be mentioned that the characterization of the space BV(L(X)) given by Proposition 3.1 is interesting independently of the context of the equations studied in this paper.

**3.2. Lemma.** Assume that  $A: [0,1] \to L(X)$  satisfies  $A \in BV(L(X))$  and (U). Then for the solution  $\Phi: [0,1] \to L(X)$  of (1.5) we have  $\Phi \in BV(L(X))$ .

Proof. Since  $BV(L(X)) \subset (\mathcal{B}^*)BV(L(X))$  the conclusion of Lemma 1.2 holds and there exists a K > 0 such that  $||\Phi(t)|| \leq K$  for every  $t \in [0,1]$ . It remains to show that the relation  $\Phi \in BV(L(X))$  holds.

Assume that

$$P: 0 = \alpha_0 < \alpha_1 < \ldots < \alpha_{k-1} < \alpha_k = 1$$

is an arbitrary partition of the interval [0,1] and that  $C_j, D_j \in L(X), j = 1, \ldots, k$ with  $\|C_j\|_{L(X)} \leq 1$ ,  $\|D_j\|_{L(X)} \leq 1$  are given.

The fact that  $\Phi \in G(L(X))$  yields by [6, Prop. 15] the existence of the integral  $\int_0^1 d[A(r)]\Phi(r)$  and therefore by definition for every  $\varepsilon > 0$  there is a gauge  $\delta \colon [0, 1] \to (0, \infty)$  such that

$$\Big\|\sum_{i=1}^{l} [A(\beta_i) - A(\beta_{i-1})] \Phi(\sigma_i) - \int_0^1 \mathbf{d} [A(r)] \Phi(r) \Big\|_{L(X)} < \frac{\varepsilon}{k+1}$$

for every  $\delta$ -fine P-partition

$$\{\beta_0, \sigma_1, \beta_1, \ldots, \beta_{l-1}, \sigma_l, \beta_l\}$$

of the interval [0, 1].

By the Saks-Henstock Lemma (see [6, Lemma 16]) we have

$$(3.5) \qquad \Big\|\sum_{i=1}^{l_j} [A(\beta_i^j) - A(\beta_{i-1}^j)] \Phi(\sigma_i^j) - \int_{\alpha_{j-1}}^{\alpha_j} \mathrm{d}[A(r)] \Phi(r) \Big\|_{L(X)} \leqslant \frac{\varepsilon}{k+1}$$

for every  $\delta$ -fine P-partition

$$\{\beta_0^j, \sigma_1^j, \beta_1^j, \ldots, \beta_{l_j-1}^j, \sigma_{l_j}^j, \beta_{l_j}^j\}$$

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of the interval  $[\alpha_{j-1}, \alpha_j], j = 1, \dots, k.$ Further, we have

$$\Phi(\alpha_j) - \Phi(\alpha_{j-1}) = \int_{\alpha_{j-1}}^{\alpha_j} \mathrm{d}[A(r)]\Phi(r)$$

for every  $j = 1, \ldots, k$  by the definition of a solution of (1.5) and therefore

$$\begin{split} \Big| \sum_{j=1}^{k} D_{j}[\Phi(\alpha_{j}) - \Phi(\alpha_{j-1})]C_{j} \Big\|_{L(X)} &= \Big\| \sum_{j=1}^{k} D_{j} \Big[ \int_{\alpha_{j-1}}^{\alpha_{j}} d[A(r)]\Phi(r) \Big]C_{j} \Big\|_{L(X)} \\ &= \Big\| \sum_{j=1}^{k} \Big\{ D_{j} \Big[ \int_{\alpha_{j-1}}^{\alpha_{j}} d[A(r)]\Phi(r) - \sum_{i=1}^{l_{j}} [A(\beta_{i}^{j}) - A(\beta_{i-1}^{j})]\Phi(\sigma_{i}^{j}) \Big]C_{j} \Big\}_{.} \\ &+ \sum_{j=1}^{k} \sum_{i=1}^{l_{j}} D_{j} [A(\beta_{i}^{j}) - A(\beta_{i-1}^{j})]\Phi(\sigma_{i}^{j})C_{j} \Big\|_{L(X)} \\ &\leq \Big\| \sum_{j=1}^{k} \Big\{ D_{j} \Big[ \int_{\alpha_{j-1}}^{\alpha_{j}} d[A(r)]\Phi(r) - \sum_{i=1}^{l_{j}} [A(\beta_{i}^{j}) - A(\beta_{i-1}^{j})]\Phi(\sigma_{i}^{j}) \Big]C_{j} \Big\} \Big\|_{L(X)} \\ &+ \Big\| \sum_{j=1}^{k} \sum_{i=1}^{l_{j}} D_{j} [A(\beta_{i}^{j}) - A(\beta_{i-1}^{j})]\Phi(\sigma_{i}^{j})C_{j} \Big\|_{L(X)} \\ &\leq \sum_{j=1}^{k} \Big\| \Big[ \int_{\alpha_{j-1}}^{\alpha_{j}} d[A(r)]\Phi(r) - \sum_{i=1}^{l_{j}} [A(\beta_{i}^{j}) - A(\beta_{i-1}^{j})]\Phi(\sigma_{i}^{j}) \Big] \Big\|_{L(X)} \\ &+ \Big\| \sum_{j=1}^{k} \sum_{i=1}^{l_{j}} D_{j} [A(\beta_{i}^{j}) - A(\beta_{i-1}^{j})]\Phi(\sigma_{i}^{j})C_{j} \Big\|_{L(X)} \\ \end{split}$$

provided

$$\{\beta_0^j, \sigma_1^j, \beta_1^j, \dots, \beta_{l_j-1}^j, \sigma_{l_j}^j, \beta_{l_j}^j\}$$

is a  $\delta$ -fine P-partition of the interval  $[\alpha_{j-1}, \alpha_j]$ ,  $j = 1, \ldots, k$ . Hence using (3.5) we obtain by the last inequalities

$$\begin{split} \Big\| \sum_{j=1}^{k} D_{j} [\Phi(\alpha_{j}) - \Phi(\alpha_{j-1})] C_{j} \Big\|_{L(X)} \\ &\leqslant \sum_{j=1}^{k} \frac{\varepsilon}{k+1} + \Big\| \sum_{j=1}^{k} \sum_{i=1}^{l_{j}} D_{j} [A(\beta_{i}^{j}) - A(\beta_{i-1}^{j})] \Phi(\sigma_{i}^{j}) C_{j} \Big\|_{L(X)} \\ &< \varepsilon + \Big\| \sum_{j=1}^{k} \sum_{i=1}^{l_{j}} D_{j} [A(\beta_{i}^{j}) - A(\beta_{i-1}^{j})] \Phi(\sigma_{i}^{j}) C_{j} \Big\|_{L(X)}. \end{split}$$

For the second term on the right hand side we have

$$\begin{split} \left\| \sum_{j=1}^{k} \sum_{i=1}^{l_{j}} D_{j} [A(\beta_{i}^{j}) - A(\beta_{i-1}^{j})] \Phi(\sigma_{i}^{j}) C_{j} \right\|_{L(X)} \\ & \leq \sum_{j=1}^{k} \sum_{i=1}^{l_{j}} \| D_{j} \|_{L(X)} \| A(\beta_{i}^{j}) - A(\beta_{i-1}^{j}) \|_{L(X)} \| \Phi(\sigma_{i}^{j}) \|_{L(X)} \| C_{j} \|_{L(X)} \\ & \leq K \cdot \sum_{j=1}^{k} \sum_{i=1}^{l_{j}} \| A(\beta_{i}^{j}) - A(\beta_{i-1}^{j}) \|_{L(X)} \leq K \cdot \sup_{[0,1]} (A). \end{split}$$

Hence

$$\left\|\sum_{j=1}^{\kappa} D_{j}[\Phi(\alpha_{j}) - \Phi(\alpha_{j-1})]C_{j}\right\|_{L(X)} \leq \varepsilon + K \cdot \underset{[0,1]}{\operatorname{var}}(A)$$

and since  $\varepsilon>0$  can be taken arbitrarily small, we get

$$\left\|\sum_{j=1}^{k} D_{j}[\Phi(\alpha_{j}) - \Phi(\alpha_{j-1})]C_{j}\right\|_{L(X)} \leqslant K \cdot \underset{[0,1]}{\operatorname{var}}(A)$$

for any partition

$$P: 0 = \alpha_0 < \alpha_1 < \ldots < \alpha_{k-1} < \alpha_k = 1$$

of the interval [0, 1] and any choice of  $C_j, D_j \in L(X), j = 1, \dots, k$  with  $\|C_j\|_{L(X)} \leq 1$ ,  $\|D_j\|_{L(X)} \leq 1$ .

Passing to the suprema over all  $C_j, D_j \in L(X), j = 1, ..., k$  with  $||C_j||_{L(X)} \leq 1$ ,  $||D_j||_{L(X)} \leq 1$  and all partitions P of [0, 1] we obtain

$$\sup_{P} \sup_{C_{j}, D_{j}} \left\| \sum_{j=1}^{\kappa} D_{j} [\Phi(\alpha_{j}) - \Phi(\alpha_{j-1})] C_{j} \right\|_{L(X)} \leqslant K \cdot \operatorname{var}_{[0,1]}(A)$$

and this together with Proposition 3.1 yields the result.

**3.3. Lemma.** Assume that  $A: [0,1] \to L(X)$  satisfies  $A \in BV(L(X))$  and (U). Then the inverse  $[\Phi(t)]^{-1} = \Phi^{-1}(t)$  to the solution  $\Phi: [0,1] \to L(X)$  of (1.5) exists for every  $t \in [0,1]$  and we have  $\Phi^{-1} \in BV(L(X))$ .

Proof. By the results given in Lemma 1.3 and 1.4 the inverse  $\Phi^{-1}$  exists and  $\Phi^{-1} \in G(L(X))$ . Hence there is a constant L > 0 such that

$$\|\Phi^{-1}(t)\|_{L(X)} \leq L$$

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for every  $t \in [0, 1]$ .

It remains to show that  $\Phi^{-1} \in BV(L(X))$ . Assume that

$$P: 0 = \alpha_0 < \alpha_1 < \ldots < \alpha_{k-1} < \alpha_k = 1$$

is an arbitrary partition of the interval [0,1] and that  $C_j, D_j \in L(X), j = 1, \ldots, k$  with  $\|C_j\|_{L(X)} \leq 1$ ,  $\|D_j\|_{L(X)} \leq 1$  are given.

We have

$$\begin{split} \left\| \sum_{j=1}^{k} D_{j} [\Phi^{-1}(\alpha_{j}) - \Phi^{-1}(\alpha_{j-1})] C_{j} \right\| &= \left\| \sum_{j=1}^{k} D_{j} \Phi^{-1}(\alpha_{j}) [I - \Phi(\alpha_{j}) \Phi^{-1}(\alpha_{j-1})] C_{j} \right\| \\ &= \left\| \sum_{j=1}^{k} D_{j} \Phi^{-1}(\alpha_{j}) [\Phi(\alpha_{j-1}) - \Phi(\alpha_{j})] \Phi^{-1}(\alpha_{j-1}) C_{j} \right\| \\ &= \left\| \sum_{j=1}^{k} D_{j} \Phi^{-1}(\alpha_{j}) [\Phi(\alpha_{j}) - \Phi(\alpha_{j-1})] \Phi^{-1}(\alpha_{j-1}) C_{j} \right\| \\ &\leq L^{2} \cdot \operatorname{var}(\Phi) \leq L^{2} \cdot K \cdot \operatorname{var}_{[0,1]}(A). \end{split}$$

Passing to the suprema over all  $C_j, D_j \in L(X), j = 1, \ldots, k$  with  $\|C_j\|_{L(X)} \leq 1$ ,  $\|D_j\|_{L(X)} \leq 1$  and all partitions P of [0, 1] we obtain

$$\sup_{P} \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [\Phi^{-1}(\alpha_j) - \Phi^{-1}(\alpha_{j-1})] C_j \right\|_{L(X)} \leqslant L^2 \cdot K \cdot \inf_{[0,1]} (A).$$

0

and this together with Proposition 3.1 yields  $\Phi^{-1} \in BV(L(X))$ .

**3.4. Theorem.** Assume that  $A: [0,1] \to L(X)$  satisfies  $A \in BV(L(X))$  and (U). Let  $\Phi: [0,1] \to L(X)$  be the solution of (1.5).

Then for every  $t_0 \in [0,1]$ ,  $\tilde{x} \in X$  and  $f \in G(X)$  the formula

(2.8) 
$$x(t) = \Phi(t)\Phi^{-1}(t_0)\tilde{x} + f(t) - f(t_0) - \Phi(t)\int_{t_0}^t \mathrm{d}[\Phi^{-1}(s)](f(s) - f(t_0)),$$

 $t \in [0, 1]$ , represents a solution of (2.7).

Proof. By Lemma 3.3 the inverse  $\Phi^{-1}: [0,1] \to L(X)$  given by Lemma 1.3 belongs to BV(L(X)) and therefore we have also  $\Phi^{-1} \in (\mathcal{B})BV(L(X))$ . All the assumptions of Theorem 2.2 being satisfied we obtain the result by this theorem.  $\Box$ 

3.5 Example. Let us consider the abstract linear differential equation

(3.6) 
$$\frac{\mathrm{d}x}{\mathrm{d}t} = a(t)x + \varphi(t)$$

on [0,1] where  $a: [0,1] \to L(X), \varphi: [0,1] \to X$  and both a and  $\varphi$  are Bochner integrable. For equations of this kind see e.g. [1].

A solution of (3.6) is understood to be a solution of the integral equation

(3.7) 
$$x(t) = x_0 + \int_d^t a(s)x(s)\,\mathrm{d}s + \int_a^t \varphi(s)\,\mathrm{d}s$$

where  $d \in [0, 1]$  and  $x_0 = x(d)$ .

More generally we can consider the integral equation of the form

(3.8) 
$$x(t) = \int_d^t a(s)x(s)\,\mathrm{d}s + g(t)$$

with  $g \in G(X)$ . Let us set

$$A(t) = \int_d^t a(s) \, \mathrm{d}s \text{ and } f(t) = \int_d^t \varphi(s) \, \mathrm{d}s, \quad t \in [0, 1]$$

Assume that  $D: 0 = \alpha_0 < \alpha_1 < \ldots < \alpha_{k-1} < \alpha_k = 1$  is an arbitrary partition of [0,1]. Then using the properties of the Bochner integral we get

$$\sum_{j=1}^{k} \|A(\alpha_{j}) - A(\alpha_{j-1})\| = \sum_{j=1}^{k} \left\| \int_{\alpha_{j-1}}^{\alpha_{j}} a(s) \, \mathrm{d}s \right\|$$
$$\leq \sum_{j=1}^{k} \int_{\alpha_{j-1}}^{\alpha_{j}} \|a(s)\| \, \mathrm{d}s = \int_{0}^{1} \|a(s)\| \, \mathrm{d}s < \infty$$

and therefore  $A \in BV(L(X))$ . Since the function ||a|| is Lebesgue integrable over [0,1] we have

$$||A(t) - A(r)|| \leq \left| \int_{r}^{t} ||a(s)|| \, \mathrm{d}s \right|$$

for  $t, r \in [0, 1]$  and this yields the continuity of A on [0, 1]. Hence  $\lim_{t \to r^{\perp}} A(t) = A(r)$  for  $r \in [0,1)$  and  $\lim_{t \to \infty} A(t) = A(r)$  for  $r \in (0,1]$  and consequently we have  $\Delta^+ A(r) = 0$ for  $r \in [0,1)$  and  $\Delta^- A(r) = 0$  for  $r \in (0,1]$  and the function  $A \colon [0,1] \to L(X)$  satisfies

the condition (U) given in Theorem 1.1. Similarly the function  $f \colon [0,1] \to X$  is also continuous and belongs trivially to G(X).

It is a matter of routine to show that

if  $x \in G(X)$  then the integrals  $\int_0^1 d[A(s)]x(s)$  and  $\int_0^1 a(s)x(s) ds$  both exist and

$$\int_0^1 d[A(s)]x(s) = \int_0^1 a(s)x(s) \, \mathrm{d}s.$$

Since g is assumed to belong to G(X), every solution of (3.8) also belongs to G(X)and therefore the equation (3.8) is equivalent to

$$x(t) = \int_{d}^{t} d[A(s)]x(s) + g(t) = g(d) + \int_{d}^{t} d[A(s)]x(s) + g(t) - g(d).$$

Hence by Theorem 2.10 in [9] there exists a unique solution  $x: [0,1] \to X, x \in G(X)$  of (3.8) and by Theorem 3.4 we get after a straightforward calculation

$$\begin{aligned} x(t) &= \Phi(t)\Phi^{-1}(t_0)g(d) + g(t) - g(d) - \Phi(t)\int_d^t d[\Phi^{-1}(s)](g(s) - g(d)) \\ &= g(t) - \Phi(t)\int_d^t d[\Phi^{-1}(s)]g(s) \end{aligned}$$

where the function  $\Phi: [0,1] \to L(X)$  is a solution of (1.5) with A given by  $A(t) = \int_{t}^{t} a(s) \, ds$  for  $t \in [0,1]$ .

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