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# CONGRUENCE RESTRICTIONS ON AXES 

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Summary. We give Mal'cev conditions for varieties $V$ whose congruences on the product $A \times B, A, B \in V$, are determined by their restrictions on the axes in $A \times B$.

Keywords: Congruence, axis in the product, variety of algebras, Mal'cev conditions
AMS classification: 08B05

The present paper is a contribution to the problem of restoration of a congruence from its given subset. Recall that any regular congruence is uniquely determined by any one of its blocks, see [1], [8], [11]. For weakly regular congruences it suffices to give up the congruence blocks at the nullary operations $c_{1}, \ldots, c_{n}$, see [6] and [8]. Subregular congruences are determined by their blocks on an arbitrary subalgebra, see [2] and [4]. The recent paper [5] investigates congruences on the square $A \times A$ which uniquely correspond to their blocks over the diagonal $\Delta_{A}$. Here we study congruences on the product $A \times B$ which are uniquely determined by their restrictions on axes in $A \times B$.

Definition 1. Let $A, B$ be similar algebras, $a \in A, b \in B$ arbitrary elements. The subsets $A \times\{b\},\{a\} \times B$ of $A \times B$ are called axes in the product $A \times B$.

## 1. Congruences determined by traces on axes

Let $\psi$ be a congruence on an algebra $A, S$ a subset of $A$. Then the trace $\psi \cap S \times S$ of $\psi$ on $S$ is denoted by $\psi \mid S$. The symbol $\theta\left(S_{1}, \ldots, S_{n}\right)$ denotes the least congruence on $A$ containing subsets $S_{1}, \ldots, S_{n}$ of $A \times A$.

Definition 2. A congruence $\psi$ on the product $A \times B$ of similar algebras $A, B$ is said to be determined by its traces $\psi|A \times\{b\}, \psi|\{a\} \times B$ on the axes $A \times\{b\}$, $\{a\} \times B$, respectively, whenever $\psi=\theta(\psi|A \times\{b\}, \psi|\{a\} \times B)$.

We say that a variety $V$ has congruences determined by traces on axes whenever each congruence on the product $A \times B$ of any $A, B \in V$ has this property.

Before stating the main theorem of this section we prove an auxiliary result.

Lemma 1. Let $a, b, c$ be elements of an algebra $A$. Then the traces $\Phi \mid A \times\{c\}$, $\Phi \upharpoonright\{c\} \times A$ of the principal congruence $\Phi=\theta(\langle a, a\rangle,(b, b\rangle) \in \operatorname{Con} A \times A$ on the axes $\mathbf{A} \times\{c\},\{c\} \times \mathbf{A}$, respectively, satisfy the symmetry law $\langle\langle f, c\rangle,\langle g, c\rangle\rangle \in \Phi \mid \mathbf{A} \times\{c\}$ iff $\langle\langle c, f\rangle,\langle c, g\rangle\rangle \in \Phi \mid\{c\} \times A$.

Proof. Let $\langle\langle f, c\rangle,\langle g, c\rangle\rangle \in \Phi \mid \mathrm{A} \times\{c\}$. From $\langle\langle f, c\rangle,\langle g, c\rangle\rangle \in \Phi=$ $\theta(\langle a, a\rangle,\langle b, b\rangle)$ we get that

$$
\begin{aligned}
f & =\varphi_{1}(a, b), \\
c & =\varphi_{1}(a, b), \\
\varphi_{i}(b, a) & =\varphi_{i+1}(a, b), \\
\varphi_{i}(b, a) & =\varphi_{i+1}(a, b), \quad 1 \leqslant i<n, \\
g & =\varphi_{n}(b, a), \\
c & =\varphi_{n}(b, a)
\end{aligned}
$$

for an integer $n \geqslant 1$ and suitable algebraic functions $\varphi_{1}, \ldots, \varphi_{n}$ over $A \times A$, see e.g. [3; Thm. 1]. Apparently the above equalities yield that also $\langle\langle c, f\rangle,\langle c, g\rangle\rangle \in \Phi$. Altogether, $\langle\langle c, f\rangle,\langle c, g\rangle\rangle \in \Phi \mid\{c\} \times A$ and the proof is complete.

The symbol $c$ stands for a finite sequence $c_{1}, \ldots, c_{k}$.

Theorem 1. For a variety $V$ the following conditions are equivalent:
(1) $V$ has congruences determined by traces on axes;
(2) there exist ternary terms $p_{1}, \ldots, p_{m}, q_{1}, \ldots, q_{m}, c_{1}, \ldots, c_{k}, d_{1}, \ldots, d_{k}, f_{1}$, $\ldots, f_{l}, g_{1}, \ldots, g_{1},(4+k)$-ary terms $t_{1}, \ldots, t_{m}$, and $(2+1)$-ary terms $s_{1}^{i}, \ldots, s_{n}^{i}$, $1 \leqslant i \leqslant m$, such that

$$
\begin{aligned}
& x=t_{1}\left(p_{1}(x, y, z), q_{1}(x, y, z), z, z, c(x, y, z)\right) \\
& x=t_{1}\left(z, z, p_{1}(x, y, z), q_{1}(x, y, z), d(x, y, z)\right)
\end{aligned}
$$

$$
\begin{align*}
& t_{i}\left(q_{i}(x, y, z), p_{i}(x, y, z), z, z, c(x, y, z)\right)= \\
& =t_{i+1}\left(p_{i+1}(x, y, z), q_{i+1}(x, y, z), z, z, c(x, y, z)\right), \\
& t_{i}\left(z, z, q_{i}(x, y, z), p_{i}(x, y, z), d(x, y, z)\right)=  \tag{i}\\
& =t_{i+1}\left(z, z, p_{i+1}(x, y, z), q_{i+1}(x, y, z), d(x, y, z)\right), \quad 1 \leqslant i<m, \\
& y=t_{m}\left(q_{m}(x, y, z), p_{m}(x, y, z), z, z, c(x, y, z)\right) \text {, } \\
& y=t_{m}\left(z, z, q_{m}(x, y, z), p_{m}(x, y, z), d(x, y, z)\right)
\end{align*}
$$

and

$$
\begin{align*}
p_{i}(x, y, z) & =s_{1}^{i}(x, y, f(x, y, z)), \\
z & =s_{1}^{i}(x, y, g(x, y, z)), \\
s_{j}^{i}(y, x, f(x, y, z)) & =s_{j+1}^{i}(x, y, f(x, y, z)),  \tag{ii}\\
s_{j}^{i}(y, x, g(x, y, z)) & =s_{j+1}^{i}(x, y, g(x, y, z)), \quad 1 \leqslant j<n, \\
q_{i}(x, y, z) & =s_{n}^{i}(y, x, f(x, y, z)), \\
z & =s_{n}^{i}(y, x, g(x, y, z)), \quad 1 \leqslant i \leqslant m,
\end{align*}
$$

are identities in $V$.
Proof. (1) $\Rightarrow(2)$ : Denote by $\Phi$ the principal congruence $\theta(\langle x, x\rangle,\langle y, y\rangle)$ on the square $A \times A=F_{v}(x, y, z) \times F_{v}(x, y, z)$. Consider the axes $A \times\{z\}$ and $\{z\} \times A$ in $A \times A$. By hypothesis is determined by its traces on the axes, so $\Phi=\theta(\Phi)$ $A \times\{z\}, \Phi\lceil\{z\} \times A)$. Since $\Phi$ is finitely generated we infer that the above equality holds true for some finite subsets of $\Phi|A \times\{z\}, \Phi|\{z\} \times A$. Furthermore, using Lemma 1 we can state that

$$
\Phi=\bigvee_{1 \leqslant i \leqslant h} \theta\left(\left\langle\left\langle p_{i}, z\right\rangle,\left\langle q_{i}, z\right\rangle\right\rangle,\left\langle\left\langle z, p_{i}\right\rangle,\left\langle z, q_{i}\right\rangle\right\rangle\right)
$$

for some $p_{1}, \ldots, p_{h}, q_{1}, \ldots, q_{h} \in A$. Now the relation

$$
\langle\langle x, x\rangle,\langle y, y\rangle\rangle \in \bigvee_{1 \leqslant i \leqslant h} \theta\left(\left\langle\left\langle p_{i}, z\right\rangle,\left\langle q_{i}, z\right\rangle\right\rangle,\left\langle\left\langle z, p_{i}\right\rangle,\left\langle z, q_{i}\right\rangle\right\rangle\right)
$$

yields the identities (2) (i) where $\left\{p_{1}, \ldots, p_{m}\right\}=\left\{p_{1}, \ldots, p_{h}\right\}$ and $\left\{q_{1}, \ldots, q_{m}\right\}=$ $\left\{q_{1}, \ldots, q_{h}\right\}$, see [2; Thm. 1]. Similarly from $\left\langle\left\langle p_{i}, z\right\rangle,\left\langle q_{i}, z\right\rangle\right\rangle \in \theta(\langle x, x\rangle,\langle y, y\rangle)$, $1 \leqslant i \leqslant m$, we obtain the other identities (2) (ii).

Notice that the identities (2) (ii) ensure also the relations $\left\langle\left\langle z, p_{i}\right\rangle,\left\langle z, q_{i}\right\rangle\right\rangle \in$ $\theta(\langle x, x\rangle,\langle y, y\rangle), 1 \leqslant i \leqslant m$.
$(2) \Rightarrow(1)$ : Let $\psi$ be a congruence on the product $A \times B$ of algebras $A, B \in V$. Choose arbitrary elements $a \in A, b \in B$. We have to verify the equality $\psi=\theta(\psi \upharpoonright A \times$
$\{b\}, \psi \mid\{a\} \times B)$. To this end take a pair $\langle\langle x, y\rangle,\langle u, v\rangle\rangle \in \psi$. Setting $z:=a, y:=u$ in the odd identities from (2) (ii) and $z:=b, y:=v, x:=y$ in the even identities from (2) (ii) we get that $\left\langle\left\langle p_{i}(x, u, a), b\right\rangle,\left\langle q_{i}(x, u, a), b\right\rangle\right\rangle \in \psi$ for $1 \leqslant i \leqslant m$. Similarly, setting $z:=a, y:=u$ in the even identities from (2) (ii) and $z:=b, y:=v, x:=y$ in the odd identities from (2) (ii) we obtain that $\left\langle\left\langle a, p_{i}(y, v, b)\right\rangle,\left\langle a, q_{i}(y, v, b)\right\rangle\right\rangle \in \psi$ for $1 \leqslant i \leqslant m$. Further, setting $z:=a, y:=u$ in the odd identities from (2) (i) and $z:=b, \dot{y}:=v, x:=y$ in the even identities from (2) (i) we find that $\langle\langle x, y\rangle,\langle u, v\rangle\rangle \in$ $\underset{1 \leqslant i \leqslant m}{V} \theta\left(\left\langle\left\langle p_{i}(x, u, a), b\right\rangle,\left\langle q_{i}(x, u, a), b\right\rangle\right\rangle,\left\langle\left\langle a, p_{i}(y, v, b)\right\rangle,\left\langle a, q_{i}(y, v, b)\right\rangle\right\rangle\right)$ and thus $\langle\langle x, y\rangle,\langle u, v\rangle\rangle \in \theta(\psi|\mathrm{A} \times\{b\}, \psi|\{a\} \times \mathrm{B})$. Since $\langle\langle x, y\rangle,\langle u, v\rangle\rangle$ is an arbitrary element from $\psi$ we conclude that $\psi \subseteq \theta(\psi|\mathrm{A} \times\{b\}, \psi|\{a\} \times \mathrm{B})$, which was to be proved.

Example 1. Let $V$ be a variety of rings with 1 . We propose the terms from Theorem 1 (2) as follows:

$$
\begin{aligned}
& p_{1}(x, y, z)=x \\
& q_{1}(x, y, z)=y \\
& t_{1}\left(a, b, u, v, c_{1}, c_{2}\right)=a \cdot c_{1}+u \cdot c_{2} \\
& c_{1}(x, y, z)=1, \quad c_{2}(x, y, z)=0 \\
& d_{1}(x, y, z)=0, \quad d_{2}(x, y, z)=1 \\
& s_{1}^{1}\left(a, b, f_{1}, f_{2}\right)=a \cdot f_{1}+f_{2} \\
& f_{1}(x, y, z)=1, \quad f_{2}(x, y, z)=0 \\
& g_{1}(x, y, z)=0, \quad g_{2}(x, y, z)=z
\end{aligned}
$$

Then

$$
\begin{array}{r}
t_{1}\left(p_{1}(x, y, z), q_{1}(x, y, z), z, z, c_{1}(x, y, z), c_{2}(x, y, z)\right)=p_{1}(x, y, z)=x, \\
t_{1}\left(z, z, p_{1}(x, y, z), q_{1}(x, y, z), d_{1}(x, y, z), d_{2}(x, y, z)\right)=p_{1}(x, y, z)=x, \\
t_{1}\left(q_{1}(x, y, z), p_{1}(x, y, z), z, z, c_{1}(x, y, z), c_{2}(x, y, z)\right)=q_{1}(x, y, z)=y, \\
t_{1}\left(z, z, q_{1}(x, y, z), p_{1}(x, y, z), d_{1}(x, y, z), d_{2}(x, y, z)\right)=q_{1}(x, y, z)=y,
\end{array}
$$

and

$$
\begin{aligned}
& s_{1}^{1}\left(x, y, f_{1}(x, y, z), f_{2}(x, y, z)\right)=x \cdot 1+0=x=p_{1}(x, y, z) \\
& s_{1}^{1}\left(x, y, g_{1}(x, y, z), g_{2}(x, y, z)\right)=x \cdot 0+z=z \\
& s_{1}^{1}\left(y, x, f_{1}(x, y, z), f_{2}(x, y, z)\right)=y \cdot 1+0=y=q_{1}(x, y, z) \\
& s_{1}^{1}\left(y, x, g_{1}(x, y, z), g_{2}(x, y, z)\right)=y \cdot 0+z=z
\end{aligned}
$$

Other examples follow from our next observation.

Corollary 1. Any variety satisfying the Fraser-Horn property, see [7], has congruences determined by traces on the axes.

Proof. Immediate.

## 2. Congruences determined by pairs on different axes

Definition 3. A congruence $\psi$ on the product $A \times B$ of similar algebras $A, B$ is said to be determined by pairs on different axes whenever $\psi=\theta(\psi \cap A \times\{b\} \times\{a\} \times B)$ for any elements $a \in A, b \in B$.

We say that a variety $V$ has congruences determined by pairs on different axes whenever each congruence on the product $A \times B$ of any algebras $A, B \in V$ has this property.

Theorem 2. For a variety $V$ the following conditions are equivalent:
(1) $V$ has congruences determined by pairs on different axes;
(2) there exist ternary terms $p_{1}, \ldots, p_{m}, q_{1}, \ldots, q_{m}, c_{1}, \ldots, c_{k}, d_{1}, \ldots, d_{k}, f_{1}$, $\ldots, f_{l}, g_{1}, \ldots, g_{l}, \quad(1+k)$-ary terms $t_{1}, \ldots, t_{m}$ and $(1+l)$-ary terms $s_{1}^{i}, \ldots, s_{n}^{i}$, $1 \leqslant i \leqslant m$, such that

$$
\begin{align*}
& x=t_{1}\left(p_{1}(x, y, z), c(x, y, z)\right) \\
& x=t_{1}(z, d(x, y, z)) \\
& t_{i}(z, c(x, y, z))=t_{i+1}\left(p_{i+1}(x, y, z), c(x, y, z)\right),  \tag{i}\\
& t_{i}\left(q_{i}(x, y, z), d(x, y, z)\right)=t_{i+1}(z, d(x, y, z)), \quad 1 \leqslant i<m \\
& y=t_{m}(z, c(x, y, z)) \\
& y=t_{m}\left(q_{m}(x, y, z), d(x, y, z)\right)
\end{align*}
$$

and

$$
\begin{align*}
p_{i}(x, y, z) & =s_{1}^{i}(x, f(x, y, z)), \\
z & =s_{1}^{i}(x, g(x, y, z)), \\
s_{j}^{i}(y, f(x, y, z)) & =s_{j+1}^{i}(x, f(x, y, z)),  \tag{ii}\\
s_{j}^{i}(y, g(x, y, z)) & =s_{j+1}^{i}(x, g(x, y, z)), \quad 1 \leqslant j<n, \\
z & =s_{n}^{i}(y, f(x, y, z)), \\
q_{i}(x, y, z) & =s_{n}^{i}(y, g(x, y, z)), \quad 1 \leqslant i \leqslant m,
\end{align*}
$$

are identities in $\boldsymbol{V}$.
Proof. (1) $\Rightarrow$ (2): Choose algebras $A=B=F_{V}(x, y, z) \in V$, the principal congruence $\theta(\langle x, x\rangle,\langle y, y))$ on $\mathrm{A} \times \mathrm{B}$ and the axes $\mathrm{A} \times\{z\},\{z\} \times \mathrm{A}$ in $\mathrm{A} \times \mathrm{B}$. By hypothesis $\theta(\langle x, x\rangle,\langle y, y\rangle)$ is uniquely determined by pairs on the axes $A \times\{z\}$ and $\{z\} \times \mathrm{A}$, i.e. we have $\theta(\langle x, x\rangle,\langle y, y\rangle)=\underset{1 \leqslant i \leqslant h}{\bigvee} \theta\left(\left\langle p_{i}, z\right\rangle,\left\langle z, q_{i}\right\rangle\right)$ for some $p_{1}, \ldots, p_{h}, q_{1}$, $\ldots, q_{h} \in \mathrm{~A}$. The relation $\langle\langle x, x\rangle,\langle y, y\rangle\rangle \in \underset{1 \leqslant i \leqslant h}{\bigvee} \theta\left(\left\langle p_{i}, z\right\rangle,\left\langle z, q_{i}\right\rangle\right)$ yields the identities

$$
\begin{align*}
& x=t_{1}\left(p_{1}(x, y, z), z, c(x, y, z)\right), \\
& x=t_{1}\left(z, q_{1}(x, y, z), d(x, y, z)\right), \\
& t_{i}\left(z, p_{i}(x, y, z), c(x, y, z)\right)=t_{i+1}\left(p_{i+1}(x, y, z), z, c(x, y, z)\right),  \tag{II}\\
& t_{i}\left(q_{i}(x, y, z), z, d(x, y, z)\right)=t_{i+1}\left(z, q_{i+1}(x, y, z), d(x, y, z)\right), \quad 1 \leqslant i<m, \\
& y=t_{m}\left(z, p_{m}(x, y, z), c(x, y, z)\right), \\
& y=t_{m}\left(q_{m}(x, y, z), z, d(x, y, z)\right),
\end{align*}
$$

where $\left\{p_{1}, \ldots, p_{m}\right\}=\left\{p_{1}, \ldots, p_{h}\right\},\left\{q_{1}, \ldots, q_{m}\right\}=\left\{q_{1}, \ldots, q_{h}\right\}$, see [3] again, and similarly form $\left\langle\left\langle p_{i}, z\right\rangle,\left\langle z, q_{i}\right\rangle\right\rangle \in \theta(\langle x, x\rangle,\langle y, y\rangle), \quad 1 \leqslant i \leqslant m$, we obtain the identities

$$
\begin{align*}
p_{i}(x, y, z) & =s_{1}^{i}(x, y, f(x, y, z)), \\
z & =s_{1}^{i}(x, y, g(x, y, z)), \\
s_{j}^{i}(y, x, f(x, y, z)) & =s_{j+1}^{i}(x, y, f(x, y, z)),  \tag{I2}\\
s_{j}^{i}(y, x, g(x, y, z)) & =s_{j+1}^{i}(x, y, g(x, y, z)), \quad 1 \leqslant j<n, \\
z & =s_{n}^{i}(y, x, f(x, y, z)), \\
q_{i}(x, y, z) & =s_{n}^{i}(y, x, g(x, y, z)) \quad \text { for } 1 \leqslant i \leqslant m .
\end{align*}
$$

Now the implication $(p(x, y ; z)=z, 1 \leqslant i \leqslant m) \Rightarrow x=y$ is a consequence of the identities (I1), and $p(x, x, z)=z, 1 \leqslant i \leqslant m$, follow from the identities (I2). Altogether we find that $p_{1}, \ldots, p_{m}$ are Csákány terms ensuring the congruence regularity of $V$, see [1]. Hence by [9] $V$ has $n$-permutable congruences for some $n>1$, and we can state that the terms $t_{1}, \ldots, t_{m}$ as well as the terms $s_{1}^{i}, \ldots, s_{n}^{i}$, $1 \leqslant i \leqslant m$, do not depend on the second variable, see [3]. The identities (2) (i) and (2) (ii) follow.
(2) $\Rightarrow$ (1): Let $\psi$ be a congruence on $A \times B, A, B \in V, a \in A, b \in B$. Consider the axes $\mathrm{A} \times\{b\}$ and $\{a\} \times \mathbf{B}$ in $\mathbf{A} \times \mathrm{B}$. Take an element $\langle\langle x, y\rangle,\langle u, v\rangle\rangle \in \psi$. Setting $z:=a, y:=u$ in the odd identities from (2) (ii) and $z:=b, y:=v, x:=y$ in the even identities from (2) (ii) we obtain that also $\left\langle\left\langle p_{i}(x, u, a), b\right\rangle,\left\langle a, q_{i}(y, v, b)\right\rangle\right\rangle \in \psi$
for $1 \leqslant i \leqslant m$. Applying the same substitutions in the identities (2) (i) we find that $\langle\langle x, y\rangle,\langle u, v\rangle\rangle \in \underset{1 \leqslant i \leqslant m}{V} \theta\left(\left\langle p_{i}(x, u, a), b\right\rangle,\left\langle a, q_{i}(y, v, b)\right\rangle\right) \subseteq \theta(\psi \cap \mathrm{A} \times\{b\} \times\{a\} \times \mathrm{B})$, which proves that $\psi$ is determined by pairs on the different axes $\mathbf{A} \times\{b\}$ and $\{a\} \times B$. The proof is complete.

Example 2. Let $V$ be a variety of Abelian groups. We propose the terms from Theorem 2(2) as follows:

$$
\begin{aligned}
& p_{1}(x, y, z)=x-y+z \\
& q_{1}(x, y, z)=y-x+z \\
& t_{1}\left(a, c_{1}, c_{2}\right)=a+c_{1}-c_{2} \\
& c_{1}(x, y, z)=y, \quad c_{2}(x, y, z)=z \\
& d_{1}(x, y, z)=x, \quad d_{2}(x, y, z)=z \\
& s_{1}^{1}\left(a, f_{1}, f_{2}\right)=a-f_{1}+f_{2}, \\
& f_{1}(x, y, z)=y, \quad f_{2}(x, y, z)=z \\
& g_{1}(x, y, z)=x, \quad g_{2}(x, y, z)=z
\end{aligned}
$$

Then

$$
\begin{aligned}
& t_{1}\left(p_{1}(x, y, z), c_{1}(x, y, z), c_{2}(x, y, z)\right)=(x-y+z)+y-z=x \\
& t_{1}\left(z, d_{1}(x, y, z), d_{2}(x, y, z)\right)=z+x-z=x \\
& t_{1}\left(z, c_{1}(x, y, z), c_{2}(x, y, z)\right)=z+y-z=y \\
& t_{1}\left(q_{1}(x, y, z), d_{1}(x, y, z), d_{2}(x, y, z)\right)=(y-x+z)+x-z=y
\end{aligned}
$$

and

$$
\begin{aligned}
& s_{1}^{1}\left(x, f_{1}(x, y, z), f_{2}(x, y, z)\right)=x-y+z=p_{1}(x, y, z) \\
& s_{1}^{1}\left(x, g_{1}(x, y, z), g_{2}(x, y, z)\right)=x-x+z=z \\
& s_{1}^{1}\left(y, f_{1}(x, y, z), f_{2}(x, y, z)\right)=y-y+z=z \\
& s_{1}^{1}\left(y, g_{1}(x, y, z), g_{2}(x, y, z)\right)=y-x+z=q_{1}(x, y, z)
\end{aligned}
$$

Corollary 2. Any variety whose congruences are determined by pairs on different axes is congruence regular and hence congruence modular and n-permutable for an integer $n>1$.

Proof. Congruence regularity was already verified in the proof of Theorem 2. The remaining conclusions are due to J. Hagemann [9].

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Souhrn

## STOPY KONGRUENCÍ NA OSÁCH

## Jaromir Duda

Jsou ukázány Mal'cevovské podmínky pro variety $V$ jejichż kongruence na součinu $A \times B$, $A, B \in V$, jsou určeny již stopami na osách v $\mathbf{A} \times B$.

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