## Czechoslovak Mathematical Journal

## C. S. Lin

Asymptotic behavior of solutions of a $2 n^{t h}$ order nonlinear differential equation

Czechoslovak Mathematical Journal, Vol. 52 (2002), No. 3, 665-672
Persistent URL: http://dml.cz/dmlcz/127752

## Terms of use:

© Institute of Mathematics AS CR, 2002

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.


This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project DML-CZ: The Czech Digital Mathematics Library http://dml.cz

# ASYMPTOTIC BEHAVIOR OF SOLUTIONS OF A $2 n^{\text {th }}$ ORDER NONLINEAR DIFFERENTIAL EQUATION 

C. S. Lin, Taipei

(Received October 25, 1999)

Abstract. In this paper we prove two results. The first is an extension of the result of G. D. Jones [4]:
(A) Every nontrivial solution for

$$
\left\{\begin{array}{l}
(-1)^{n} u^{(2 n)}+f(t, u)=0, \text { in }(\alpha, \infty), \\
u^{(i)}(\xi)=0, \quad i=0,1, \ldots, n-1, \quad \text { and } \quad \xi \in(\alpha, \infty),
\end{array}\right.
$$

must be unbounded, provided $f(t, z) z \geqslant 0$, in $E \times \mathbb{R}$ and for every bounded subset $I$, $f(t, z)$ is bounded in $E \times I$.
(B) Every bounded solution for $(-1)^{n} u^{(2 n)}+f(t, u)=0$, in $\mathbb{R}$, must be constant, provided $f(t, z) z \geqslant 0$ in $\mathbb{R} \times \mathbb{R}$ and for every bounded subset $I, f(t, z)$ is bounded in $\mathbb{R} \times I$.

Keywords: asymptotic behavior, higher order differential equation
MSC 2000: 34D05

## 1. Introduction

Asymptotic behavior of solution to differential equations has been widely studied. For example Hastings and Lazer [2] proved that assuming

$$
\begin{equation*}
p(t) \in C^{1}[\alpha, \infty), \quad p^{\prime}(t) \geqslant 0 \text { and } \lim _{t \rightarrow \infty} p(t)=\infty \tag{1.1}
\end{equation*}
$$

all oscillatory solutions of

$$
\begin{equation*}
y^{(4)}-p(t) y=0 \tag{1.2}
\end{equation*}
$$

tend to zero. G. D. Jones [3] showed that, assuming

$$
\begin{equation*}
p(t) \in C^{1}[\alpha, \infty), \quad p^{\prime}(t) \leqslant 0 \text { and } \lim _{t \rightarrow \infty} p(t)=0 \tag{1.3}
\end{equation*}
$$

all oscillatory solutions of (1.2) are unbounded. Biernacki [1] proved that, assuming (1.1),

$$
\begin{equation*}
y^{(4)}+p(t) y=0 \tag{1.4}
\end{equation*}
$$

has at least one oscillatory solution tending to zero. This result was generalized by Švec [6]. Švec proved that (1.4) has two linearly independent oscillatory solutions that tend to zero assuming only $0<m \leqslant p(t)$. Sivec [6] also proved that if $0<m \leqslant$ $p(t) \leqslant M$ and (1.4) is oscillatory, then (1.4) has a pair of unbounded solutions.

Recently G. D. Jones [4] extended this result to the following: if $0 \leqslant p(t) \leqslant M$ and (1.4) is oscillatory, then it has a pair of solutions such that every linear combination of them is unbounded. In this paper we extend the result of G. D. Jones [4] and show that Liouville's theorem holds for (1.5.2). We now list our conclusions:
(A) Every nontrivial solution of (1.5.1) with assumptions (1.6.1) and (1.7) is unbounded, which is stated in Theorem 3.1.

$$
\begin{gather*}
L u=(-1)^{n} u^{(2 n)}+f(t, u)=0 \text { in } E=(\alpha, \infty) .  \tag{1.5.1}\\
\quad(-1)^{n} u^{(2 n)}+f(t, u)=0 \text { in } \mathbb{R} .  \tag{1.5.2}\\
f(t, z) z \geqslant 0 \text { in } E \times \mathbb{R} \text { and } f(t, z) \text { is bounded in } E \times I  \tag{1.6.1}\\
\text { for every bounded subset } I \text { of } \mathbb{R} . \\
f(t, z) z \geqslant 0 \text { in } \mathbb{R} \times \mathbb{R} \text { and } f(t, z) \text { is bounded in } \mathbb{R} \times I  \tag{1.6.2}\\
\text { for every bounded subset } I \text { of } \mathbb{R} . \\
\text { There exists a } \xi \text { in the domain of } u \text { that } u^{(i)}(\xi)=0  \tag{1.7}\\
\text { for } i=0,1, \ldots, n-1 .
\end{gather*}
$$

In particular, let $f(t, u)=p(t) u$. Then we have the following generalization of the result of G. D. Jones [4]: Assume $p(t)$ is nonnegative and bounded in $E$. Then there are $n$ linearly independent solutions of (1.8) such that every linear combination of them is unbounded, except the trivial solution, which is stated in Theorem 3.2,

$$
\begin{equation*}
(-1)^{n} u^{(2 n)}+p(t) u=0 \text { in } E=(\alpha, \infty) \tag{1.8}
\end{equation*}
$$

(B) Every bounded solution $u$ of (1.5.2) with assumption (1.6.2) is constant.

## 2. Preliminary

We begin by defining some functionals and showing their relations.

Definition 2.1. Let $u \in C^{2 m}(\Omega), \Omega=[\beta, \gamma]$. We define

$$
\begin{gathered}
P_{2 m}(u, \Omega)=\int_{\beta}^{\gamma}(-1)^{m} u u^{(2 m)} \mathrm{d} t \quad \text { for } m=0,1, \ldots, \\
G_{2 m}(u)= \begin{cases}0, & \text { if } m=0 \\
\frac{\mathrm{~d}}{\mathrm{~d} t}\left(\frac{u^{2}}{2}\right), & \text { if } m=1, \\
(-1)^{m-1} \frac{\mathrm{~d}}{\mathrm{~d} t}\left(u u^{(2 m-2)}\right)+2 G_{2 m-2}\left(u^{\prime}\right)-G_{2 m-4}\left(u^{\prime \prime}\right), & \text { if } m \geqslant 2,\end{cases}
\end{gathered}
$$

and

$$
H_{2 m}(u)= \begin{cases}0, & \text { if } m=0 \\ \frac{u^{2}}{2}, & \text { if } m=1 \\ (-1)^{m-1}\left(u u^{(2 m-2)}\right)+2 H_{2 m-2}\left(u^{\prime}\right)-H_{2 m-4}\left(u^{\prime \prime}\right), & \text { if } m \geqslant 2\end{cases}
$$

In the following lemmas we now show their relations and properties.

Lemma 2.2. If $u \in C^{2 m}(\Omega)$ and $\Omega=[\beta, \gamma]$, then

$$
P_{2 m}(u, \Omega)=-\left.G_{2 m}(u)\right|_{\beta} ^{\gamma}+\int_{\beta}^{\gamma}\left(u^{(m)}\right)^{2} \mathrm{~d} t, \text { where } m=0,1, \ldots
$$

Proof. The proof is done by induction on $m$. For $m=0$ it is evident. For $m=1$, by integration by parts, we have

$$
\begin{aligned}
P_{2}(u, \Omega) & =\int_{\beta}^{\gamma}-u u^{\prime \prime} \mathrm{d} t \\
& =-\left.u u^{\prime}\right|_{\beta} ^{\gamma}+\int_{\beta}^{\gamma}\left(u^{\prime}\right)^{2} \mathrm{~d} t \\
& =-\left.G_{2}(u)\right|_{\beta} ^{\gamma}+\int_{\beta}^{\gamma}\left(u^{\prime}\right)^{2} \mathrm{~d} t .
\end{aligned}
$$

Suppose that the assertion holds for $m=0,1, \ldots, k$. We shall show that it is true for $m=k+1$. By repeating integration by parts we obtain

$$
\begin{aligned}
P_{2 k+2}(u, \Omega)= & \left.\int_{\beta}^{\gamma}(-1)^{k+1} u u^{(2 k+2}\right) \mathrm{d} t \\
= & \left.(-1)^{k+1} u u^{(2 k+1)}\right|_{\beta} ^{\gamma}-\int_{\beta}^{\gamma}(-1)^{k+1} u^{\prime} u^{(2 k+1)} \mathrm{d} t \\
= & \left.(-1)^{k+1} u u^{(2 k+1)}\right|_{\beta} ^{\gamma}-\left.(-1)^{k+1} u^{\prime} u^{(2 k)}\right|_{\beta} ^{\gamma}+\int_{\beta}^{\gamma}(-1)^{k+1} u^{\prime \prime} u^{(2 k)} \mathrm{d} t \\
= & P_{2 k-2}\left(u^{\prime \prime}, \Omega\right)+\left.(-1)^{k+1} \frac{\mathrm{~d}}{\mathrm{~d} t}\left(u u^{(2 k)}\right)\right|_{\beta} ^{\gamma}-\left.2(-1)^{k+1} u^{\prime} u^{(2 k)}\right|_{\beta} ^{\gamma} \\
= & P_{2 k-2}\left(u^{\prime \prime}, \Omega\right)+\left.(-1)^{k+1} \frac{\mathrm{~d}}{\mathrm{~d} t}\left(u u^{(2 k)}\right)\right|_{\beta} ^{\gamma} \\
& -2\left[\int_{\beta}^{\gamma}(-1)^{k+1} u^{\prime \prime} u^{(2 k)} \mathrm{d} t+\int_{\beta}^{\gamma}(-1)^{k+1} u^{\prime} u^{(2 k+1)} \mathrm{d} t\right] \\
= & P_{2 k-2}\left(u^{\prime \prime}, \Omega\right)+\left.(-1)^{k+1} \frac{\mathrm{~d}}{\mathrm{~d} t}\left(u u^{(2 k)}\right)\right|_{\beta} ^{\gamma}-2\left[P_{2 k-2}\left(u^{\prime \prime}, \Omega\right)-P_{2 k}\left(u^{\prime}, \Omega\right)\right] \\
= & \left.(-1)^{k+1} \frac{\mathrm{~d}}{\mathrm{~d} t}\left(u u^{(2 k)}\right)\right|_{\beta} ^{\gamma}-P_{2 k-2}\left(u^{\prime \prime}, \Omega\right)+2 P_{2 k}\left(u^{\prime}, \Omega\right) \\
= & \left.(-1)^{k+1} \frac{\mathrm{~d}}{\mathrm{~d} t}\left(u u^{(2 k)}\right)\right|_{\beta} ^{\gamma}-\left.2 G_{2 k}\left(u^{\prime}\right)\right|_{\beta} ^{\gamma}+\left.G_{2 k-2}\left(u^{\prime \prime}\right)\right|_{\beta} ^{\gamma}+\int_{\beta}^{\gamma}\left(u^{(k+1)}\right)^{2} \mathrm{~d} t \\
= & -\left.G_{2 k+2}(u)\right|_{\beta} ^{\gamma}+\int_{\beta}^{\gamma}\left(u^{(k+1)}\right)^{2} \mathrm{~d} t,
\end{aligned}
$$

where the last identity holds by virtue of the definition of $G_{2 n}(u)$. Hence the proof of the lemma is complete.

The following lemma is often used in the proofs of the main theorems.

Lemma 2.3. Let $i=1,2$. If $u$ is a solution of (1.5.i) satisfying assumption (1.6.i), then
(1) $\mathrm{d} / \mathrm{dt} H_{2 n}(u)=G_{2 n}(u)$.
(2) $G_{2 n}(u)$ is increasing.
(3) $H_{2 n}(u)(\xi)=0$ and $G_{2 n}(u)(\xi)=0$ provided $u$ satisfies condition (1.7).
(4) There exists $c \in[\xi, \infty)$ such that $G_{2 n}(u)(t)>0$ if $t>c$ provided $u$ satisfies condition (1.7) and does not vanish in $[\xi, \infty)$.

Proof. (1) By the definitions of $H_{2 n}(u)$ and $G_{2 n}(u)$, and using the induction on $n$, it is easy to check that part (1) is true.
(2) Multiplying both sides of $L u=0$ by $u$, integrating the resulting expression over any closed subset $\Omega=[\beta, \gamma]$ of the domain of $u$ and using Lemma 2.2, we have

$$
\begin{align*}
0 & =\int_{\beta}^{\gamma} u L u \mathrm{~d} t=\int_{\beta}^{\gamma}(-1)^{n} u u^{(2 n)} \mathrm{d} t+\int_{\beta}^{\gamma} f(t, u) u \mathrm{~d} t  \tag{2.1}\\
& =P_{2 n}(u, \Omega)+\int_{\beta}^{\gamma} f(t, u) u \mathrm{~d} t \\
& =-\left.G_{2 n}(u)\right|_{\beta} ^{\gamma}+\int_{\beta}^{\gamma}\left(u^{(n)}\right)^{2} \mathrm{~d} t+\int_{\beta}^{\gamma} f(t, u) u \mathrm{~d} t
\end{align*}
$$

and this implies that $\left.G_{2 n}(u)\right|_{\beta} ^{\gamma} \geqslant 0$ for every $\gamma>\beta$.
Hence $G_{2 n}(u)$ is increasing and we have completed the proof of part (2).
(3) We assume that the identities hold for $n=0,1, \ldots, k-1$. We shall show that $G_{2 k}(u)(\xi)=0$ provided $u^{(i)}(\xi)=0, i=0,1, \ldots, k-1$. By Definition 2.1, it is easy to verify that

$$
G_{2 k}(u)(\xi)=\left[(-1)^{(k-1)} \frac{\mathrm{d}}{\mathrm{~d} t}\left(u u^{(2 k-2)}\right)+2 G_{2 k-2}\left(u^{\prime}\right)-G_{2 k-4}\left(u^{\prime \prime}\right)\right](\xi)=0
$$

since $G_{2 k-2}\left(u^{\prime}\right)(\xi)=0$ and $G_{2 k-4}\left(u^{\prime \prime}\right)(\xi)=0 \operatorname{provided} u^{(j)}(\xi)=0, j=1,2, \ldots, k-1$. Similarly we have $H_{2 n}(u)(\xi)=0$. Hence the proof of part (3) is complete.
(4) We denote the domain of $u$ by $D$. By parts (2) and (3) we have

$$
\begin{equation*}
G_{2 n}(u)(t) \geqslant 0 \text { in }[\xi, \infty) . \tag{2.2}
\end{equation*}
$$

Suppose the result is not true. Then we have $G_{2 n}(u)(t)=0$ in $[\xi, \infty)$ by virtue of (2.2) and Lemma 2.3, part (2). Multiplying both sides of $L u=0$ by $u$ and integrating over any subset $[\beta, \gamma)$ of $D$, we get

$$
\begin{aligned}
0=\int_{\beta}^{\gamma} u L u \mathrm{~d} t & =\int_{\beta}^{\gamma}(-1)^{n} u u^{(2 n)} \mathrm{d} t+\int_{\beta}^{\gamma} f(t, u) u \mathrm{~d} t \\
& =P_{2 n}(u, \Omega)+\int_{\beta}^{\gamma} f(t, u) u \mathrm{~d} t \\
& =-\left.G_{2 n}(u)\right|_{\beta} ^{\gamma}+\int_{\beta}^{\gamma}\left[\left(u^{(n)}\right)^{2}+f(t, u) u\right] \mathrm{d} t \\
& =\int_{\beta}^{\gamma}\left[\left(u^{(n)}\right)^{2}+f(t, u) u\right] \mathrm{d} t .
\end{aligned}
$$

This show that $u^{(n)}$ vanishes in $[\xi, \infty)$. So $u$ must be a polynomial function of degree less than $n$ with $n$ roots at $\xi$, since $u^{(i)}(\xi)=0, i=0,1, \ldots, n-1$, and this impies that $u$ vanishes in $[\xi, \infty)$, which contradicts our hypothesis. Hence part (4) is done.

In order to show that $H_{2 n}(u)$ and $G_{2 n}(u)$, which are used in the main theorems, are both bounded provided $u$ is bounded, we quote the result of [5].

Lemma 2.4 ([5]). Let $1 \leqslant k \leqslant \infty$, let $i, j$ be integers with $1 \leqslant j \leqslant i$, and let $J$ be any interval of the real line bounded or unbounded. Given any $\varepsilon>0$ there exists a positive $k(\varepsilon)$ such that if $y \in L^{k}(J), y^{(i-1)}$ is locally absolutely continuous and $y^{(i)} \in L^{k}(J)$, then $y^{(j)} \in L^{k}(J)$ and

$$
\left\|y^{(j)}\right\|_{k} \leqslant \varepsilon\left\|y^{(i)}\right\|_{k}+k(\varepsilon)\|y\|_{k},
$$

where $k(\varepsilon)$ depends only on $\varepsilon$ and the length of $J$ and $\|y\|_{k}$ denotes the $L^{k}$ norm of $y$.

Remark 2.5. If $u$ is a bounded solution of (1.5.i) satisfying the assumption (1.6. i), then $u^{(2 n)}$ is bounded. According to Lemma 2.4, we have that $u^{(i)}$ is bounded, $i=0,1, \ldots, 2 n$. Hence $H_{2 n}(u)$ and $G_{2 n}(u)$ also are bounded by virtue of the definitions of $H_{2 n}(u)$ and $G_{2 n}(u)$.

## 3. Main result

We are now ready to show our main theorems.
Theorem 3.1. Every nontrivial solution of (1.5.1) satisfying assumptions (1.6.1) and (1.7) is unbounded.

Proof. Suppose that a solution $u$ is bounded in $E$. Then we have

$$
\begin{equation*}
H_{2 n}(u) \text { is bounded in } E \text {, } \tag{3.1}
\end{equation*}
$$

according to Remark 2.5. By Lemma 2.3, parts (2) and (4), there exists a number $c$ in $E$ such that

$$
\begin{equation*}
G_{2 n}(u)(t) \geqslant G_{2 n}(u)(c)>0 \quad \text { for } \quad t>c, \tag{3.2}
\end{equation*}
$$

and using (3.1), Lemma 2.3. part (1) and the mean value theorem, we have

$$
\left|H_{2 n}(u)(t)-H_{2 n}(u)(c)\right|=\left|G_{2 n}(u)(d)(t-c)\right| \geqslant G_{2 n}(c)(t-c),
$$

where $d \in(c, t)$, since the last inequality follows by (3.2). So $H_{2 n}(u)(t) \rightarrow \infty$ as $t \rightarrow \infty$. Thus $H_{2 n}(u)(t)$ is unbounded, which contradicts (3.1).

Hence we have completed the proof of the theorem.

The following result which is an extension of the result of G. D. Jones [4], is a special case of Theorem 3.1.

Theorem 3.2. Suppose $p(t)$ is nonnegative and bounded in $E$. There are $n$ linearly independent solutions of (1.8) such that every linear combination of them is unbounded, except the trivial solution.

Proof. Let $u_{i}, i=0,1, \ldots, 2 n-1$, be $2 n$ linearly independent solutions of (1.8) that satisfy $u_{i}^{(k)}(\xi)=\delta_{i k}, i, k=0,1, \ldots, 2 n-1$, where $\delta_{i k}$ is the Kronecker symbol. And let $u=\sum_{i=n}^{2 n-1} b_{i} u_{i}$, where $b_{i}, i=n, n+1, \ldots, 2 n-1$, be constants such that at least one $b_{i}$ is not zero. It is easy to verify that $u$ satisfies assumption (1.7) in Theorem 3.1 and by virtue of Theorem 3.1, $u$ is unbounded in $E$. Hence the theorem is proved.

Now we show the last theorem.
Theorem 3.3. Every bounded solution $u$ of (1.5.2) satisfying assumption (1.6.2) is a constant.

Proof. According to Remark 2.5, $H_{2 n}(u)$ is bounded. We claim that $G_{2 n}(u)(t)$ vanishes in $\mathbb{R}$.

Suppose there is a $c \in \mathbb{R}$ such that $G_{2 n}(u)(c)>0$. According to Lemma 2.3, parts (1), (2) and the fundamental theorem of calculus, we have

$$
\left|H_{2 n}(u)(t)-H_{2 n}(u)(c)\right|=\left|\int_{c}^{t} G_{2 n}(u)(s) \mathrm{d} s\right| \geqslant|t-c|\left|G_{2 n}(u)(c)\right|, \quad \text { for } \quad t \geqslant c
$$

and this implies that $\left|H_{2 n}(u)(t)\right| \rightarrow \infty$ as $t \rightarrow \infty$. This contradicts the fact that $H_{2 n}(u)$ is bounded. If there is a $c \in \mathbb{R}$ such that $G_{2 n}(u)(c)<0$, then by the same argument we have

$$
\left|H_{2 n}(u)(c)-H_{2 n}(u)(t)\right|=\left|\int_{t}^{c} G_{2 n}(u)(s) \mathrm{d} s\right| \geqslant|t-c|\left|G_{2 n}(u)(c)\right| \quad \text { for } \quad c \geqslant t
$$

and this implies that $\mid H_{2 n}(u)(t) \rightarrow \infty$ as $t \rightarrow \infty$. This is also a contradiction.
Hence $G_{2 n}(u)(t)$ vanishes in $\mathbb{R}$. According to (2.1), we conclude that $u^{(n)}=0$ in $\mathbb{R}$. This means $u$ is a polynomial function of degree less than $n$. It is well known that a bounded polynomial function must be constant. Hence we have completed the proof of the theorem.

Acknowledgement. I wish to thank the referee for his helpful suggestions that led to an improved presentation of my work.

## References

[1] M. Biernacki: Sur l'equation differentielle $y^{(4)}+A(x) y=0$. Ann. Univ. Mariae CurieSkłodowska 6 (1952), 65-78.
[2] S.P. Hastings and A. C. Lazer: On the asymptotic behavior of solutions of the differential equation $y^{(4)}=p(x) y$. Czechoslovak Math. J. 18(93) (1968), 224-229.
[3] G.D. Jones: Asymptotic behavior of solutions of a fourth order linear differential equation. Czechoslovak Math. J. 38(113) (1988), 578-584.
[4] G. D. Jones: Oscillatory solutions of a fourth order linear differential equation. Lecture notes in pure and apllied Math. Vol 127. 1991, pp. 261-266.
[5] M. K. Kwong and A. Zettl: Norm Inequalities for Derivatives and Differences. Lecture notes in Mathematics, 1536. Springer-Verlag, Berlin, 1992.
[6] M. Švec: Sur le comportement asymtotique des intégrales de l'équation differentielle $y^{(4)}+Q(x) y=0$. Czechoslovak Math. J. 8(83) (1958), 230-245.

Author's address: Department of Mathematics, Hsing Wu College No 11-2, Fen-liao Rd., Lin-kou, Taipei 224, Taiwan, R.O.C., e-mail t10035@mail.hwc.edu.tw.

