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## A REMARK TO THE PAPER "ON CONDENSING DISCRETE DYNAMICAL SYSTEMS"

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Abstract. In the paper a new proof of Lemma 11 in the above-mentioned paper is given. Its original proof was based on Theorem 3 which has been shown to be incorrect.

*Keywords*: condensing discrete dynamical system, singular interval, stability, orderpreserving mapping

MSC 2000: 37B99, 47H07, 47H10, 37C99

## INTRODUCTION

Theorem 3 in [4, p. 292] is not correct as the following example of a non locally connected continuum in  $\mathbb{R}^2$  shows. This example was suggested by N. Dancer in [1]. (For similar results, see [3, p. 162], [2, Example 5.1].)

$$X = \{(0, y) \colon 0 \le y \le 2\} \cup \{(x, y) \colon y = 1 + \sin\frac{1}{x}, \ 0 < x \le \frac{2}{\pi}\} \cup \{(x, 2) \colon \frac{2}{\pi} < x \le 2\}.$$

In view of this, Theorem 4, Remark 4, Lemma 9 and Theorem 5, Lemma 11 in [4] are true in a weaker formulation. They only guarantee the existence of a continuum of sub- and superequilibria and a continuum of equilibria, respectively. They will be rewritten here. Also a new proof of Lemma 11 from the above-mentioned paper will be given. This will guarantee that, with these changes, all results of [4] remain valid.

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**Theorem 4.** Let assumption (H3) be fulfilled, let  $[z_1, z_2] \subset [a, b]$  be a positively invariant interval for the operator T and let  $z_1, z_2 \in C_2$ . Then the set F of all subequilibria and all superequilibria lying in  $C_2$  forms a continuous branch connecting the points  $z_1, z_2$  and contains a continuum possessing  $z_1, z_2$ .

Remark 4. By Theorem 2, each equilibrium belongs to  $C_2$ . Further, if z is a subequilibrium (superequilibrium) and there is a sequence  $z_k \to z$  such that  $z_k$  are superequilibria (subequilibria), then z is an equilibrium. We also have that the set of all equilibria lying in a continuum C is closed, and thus the set of all sub- and superequilibria in C is open (with respect to that continuum).

**Theorem 5.** If assumption (H3) is satisfied and  $[z_1, z_2] \subset [a, b]$  is a singular interval for the mapping T, then the set  $F_p$  of all equilibria lying in  $[z_1, z_2]$  forms a continuous branch connecting the points  $z_1$ ,  $z_2$  and contains a continuum possessing  $z_1$ ,  $z_2$ .

**Lemma 9.** Let assumption (H3) be fulfilled, let  $[z_1, z_2] \subset [a, b]$  be a positively invariant interval for T and let  $z_1, z_2$  be two equilibria. Then the following alternative holds: Either

- (a) there exists a further equilibrium in  $[z_1, z_2]$ , or
- (b) there exists a continuum C in [z<sub>1</sub>, z<sub>2</sub>] containing z<sub>1</sub>, z<sub>2</sub> such that all points of C except z<sub>1</sub>, z<sub>2</sub> are strict subequilibria, or
- (c) there exists a continuum C in  $[z_1, z_2]$  containing  $z_1, z_2$  such that all points of C except  $z_1, z_2$  are strict superequilibria.

**Lemma 11.** Let assumption (H3) be satisfied, let  $z_1$ ,  $z_2$  be two equilibria such that  $a \leq z_1 < z_2 \leq b$  and let T be order-preserving in  $[z_1, z_2]$ . Further, let all equilibria in  $[z_1, z_2]$  be stable. Then there is a continuum of equilibria in  $[z_1, z_2]$  containing  $z_1$ ,  $z_2$ .

The proof of this lemma will be based on Theorem 4 and on the following

**Lemma.** Let assumption (H3) be fulfilled, let  $a \leq z_1 < z_2 \leq b$  be two points such that  $z_1$  ( $z_2$ ) is a subequilibrium (superequilibrium) and T is order-preserving in [ $z_1, z_2$ ]. Further, let all equilibria in [ $z_1, z_2$ ] be stable. Denote F ( $F_p$ ) the set of all sub- and superequilibria (the set of all equilibria) lying in [ $z_1, z_2$ ]. Then:

- (a) For each  $x \in F$  there exists  $\lim_{k \to \infty} T^k(x) \in [z_1, z_2]$ .
- (b) The mapping  $U: F \to F_p$  defined by

(1) 
$$U(x) = \lim_{k \to \infty} T^k(x), \quad x \in F,$$

is continuous.

Proof. The statement (a) follows from Lemma 10 and hence the mapping U defined by (1) is well-defined. Let  $x \in F$  be an arbitrary point and  $\varepsilon > 0$  an arbitrary number. Then by the stability of y = U(x) there exists a  $\delta > 0$  such that

(2) 
$$||y - T^k(u)|| < \varepsilon$$
 for each  $u \in [z_1, z_2], ||u - y|| < \delta$  and each natural k.

Since  $\lim_{k \to \infty} T^k(x) = y$ , there exists a natural  $k_0$  with the property

(3) 
$$||T^{k_0}(x) - y|| < \frac{\delta}{2}.$$

As  $T^{k_0}$  is continuous at x, there exists a  $\delta_1 > 0$  such that  $z \in F$ ,  $||x - z|| < \delta_1$  implies

(4) 
$$||T^{k_0}(x) - T^{k_0}(z)|| < \frac{\delta}{2}$$

Then for each  $z \in F$ ,  $||x - z|| < \delta_1$ , (4) and (3) give that

(5) 
$$||T^{k_0}(z) - y|| \leq ||T^{k_0}(z) - T^{k_0}(x)|| + ||T^{k_0}(x) - y|| < \delta.$$

Put  $u = T^{k_0}(z)$  in (2). In view of (5), (2) implies that

(6) 
$$||y - T^{k_0+k}(z)|| < \varepsilon$$
 for each natural k.

Thus we get that  $||x - z|| < \delta_1$ ,  $z \in F$ , implies the inequality  $||U(x) - U(z)|| \leq \varepsilon$ which means the continuity of U at x.

Proof of Lemma 11. By Theorem 4 above, there is a continuum C containing  $z_1, z_2$  in the set F of all subequilibria and all superequilibria lying in  $C_2$ . Lemma assures the existence of a continuous map U which maps C onto a continuum of equilibria in  $[z_1, z_2]$  containing  $z_1, z_2$ .

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