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## ON QUASIPARABOLICAL DIFFERENTIAL EQUATIONS OF HIGHER ORDER

IGOR BOCK

We shall be dealing with the initial value problem

$$
\begin{gather*}
A_{0} \frac{\mathrm{~d}^{m} u}{\mathrm{~d} t^{m}}+\ldots+A_{m-1} \frac{\mathrm{~d} u}{\mathrm{~d} t}+A_{m} u=f^{*}(t)  \tag{0.1}\\
\left.\frac{\mathrm{d}^{r} u}{\mathrm{~d} t^{r}}\right|_{t=0}=u_{r}, r=0,1, \ldots, m-1 \tag{0.2}
\end{gather*}
$$

with the functions $u:([0, \infty) \rightarrow H), f^{*}:\left([0, \infty) \rightarrow H^{*}\right)$, the operators $A_{r}:(H \rightarrow$ $H^{*}$ ) and the elements $u_{r} \in H$, where $H$ is a real Hilbert space and $H^{*}$ is a dual space to $H$.

The existence and the uniqueness of a solution of $(0.1)$, ( 0.2 ) will be verified in the first part. We shall analyze the behaviour of the solution for $t \rightarrow \infty$ in the second part. We restrict ourselves only to the problems of the first and second order. The application on the equation of bending of viscoelastic plate is shown in the third part.

## 1. Existence and Uniqueness of a Solution

Let $H$ be the real Hilbert space with a scalar product (.,.) and a norm $\|\|,. H^{*}$ be the dual space to $H$ i.e. the space of all linear and bounded functionals over $H$ with a norm $\|$. $\|_{*}$. If $f^{*} \in H, h \in H$, then we denote $\left\langle f^{*}, h\right\rangle=f^{*}(h)$. The Riesz operator $R \in L\left(H^{*}, H\right)$ is defined by

$$
\begin{equation*}
\left(R f^{*}, h\right)=\left\langle f^{*}, h\right\rangle, f^{*} \in H^{*}, h \in H \tag{1.1}
\end{equation*}
$$

We denote by $C^{(m)}([0, \infty), H)$ the space of all $m$-times continuously differentiable functions with the domain $[0, \infty)$ and with the values in $H$ and by $C\left([0, \infty), H^{*}\right)$ the space of all continuous functions with the domain $[0, \infty)$ and the values in $H^{*}$.

We assume that $A_{0}, \ldots, A_{m}$ are linear and bounded operators with the domain $H$ and the values in $H$ i.e.

$$
\begin{equation*}
A_{r} \in L\left(H, H^{*}\right), r=0,1, \ldots, m \tag{1.2}
\end{equation*}
$$

The operator $A_{0}$ is assumed to be coercive i.e.

$$
\begin{equation*}
\left\langle A_{0} x, x\right\rangle \geqslant \alpha_{0}\|x\|^{2}, x \in H, \alpha_{0}>0 \tag{1.3}
\end{equation*}
$$

Definition 1.1. Let $f^{*} \in C\left([0, \infty), H^{*}\right), \quad A_{k} \in L\left(H, H^{*}\right), \quad k=0,1, \ldots, m$, $u_{r} \in H, r=0,1, \ldots, m-1$. The function $u:([0, \infty) \rightarrow H)$ is a solution of the initial value problem (0.1), (0.2) iff
i) $u \in C^{(m)}([0, \infty), H)$
ii) $u$ satisfies (0.1), (0.2).

Theorem 1.1. Let $\quad f^{*} \in C\left([0, \infty), H^{*}\right), \quad u_{r} \in H, \quad r=0,1, \ldots, m-1$, $A_{k} \in L\left(H, H^{*}\right), k=0,1, \ldots, m, A_{0}$ satisfies (1.3). Then there exists a unique solution of the problem (0.1), (0.2).

Proof. Using the Riesz operator $R$ we convert the problem (0.1), (0.2) into the initial value problem for the differential equation in the space $H$ in the same way as in the paper [4]:

$$
\begin{gather*}
B_{0} \frac{\mathrm{~d}^{m} u}{\mathrm{~d} t^{m}}+\ldots+B_{m-1} \frac{\mathrm{~d} u}{\mathrm{~d} t}+B_{m} u=f(t)  \tag{1.4}\\
\left.\frac{\mathrm{d}^{r} u}{\mathrm{~d} t^{r}}\right|_{t=0}=u_{r}, r=0,1, \ldots, m-1 \tag{1.5}
\end{gather*}
$$

where

$$
\begin{gather*}
B_{r}=R A_{r} \in L(H, H), r=0,1, \ldots, m  \tag{1.6}\\
\left(B_{0} x, x\right) \geqslant \alpha_{0}\|x\|^{2}, x \in H, \alpha_{0}>0  \tag{1.7}\\
f=R f^{*} \in C([0, \infty), H) \tag{1.8}
\end{gather*}
$$

The operator $R$ is linear bounded and invertible and hence the problems (0.1), ( 0.2 ) and (1.4), (1.5) are equivalent. It is sufficient to show that there exists a solution $u \in C^{(m)}([0, \infty), H)$ of the problem (1.4), (1.5). That solution will be the solution of $(0.1),(0.2)$ too. The initial value problem (1.4), (1.5) is equivalent with the problem

$$
\begin{align*}
& \frac{\mathrm{d}^{m} u}{\mathrm{~d} t^{m}}+\sum_{r=1}^{m} B_{0}^{-1} B_{r} \frac{\mathrm{~d}^{m-r} u}{\mathrm{~d} t^{m-r}}=B_{0}^{-1} f(t)  \tag{1.9}\\
& \left.\frac{\mathrm{d}^{r} u}{\mathrm{~d} t^{r}}\right|_{t=0}=u_{r}, r=0,1, \ldots, m-1 \tag{1.10}
\end{align*}
$$

where the inverse operator $B_{0}^{\mathbf{t}^{1}} \in L(H, H)$ exists due to (1.7). The existence and the uniqueness of a solution of (1.9), (1.10) is proved in [9] under more general assumptions. It is sufficient to conşider the problem (1.9), (1.10) as the initial value problem of the first order in the space $\mathscr{H}=H^{m}$. A solution $u \in C([0, \infty), H)$ of (1.9), (1.10) is then a unique solution of the problem (1.4), (1.5) and (0.1), (0.2).

Remark. We can consider in (0.1) under suitable assumptions also the families of nonlinear operators $\boldsymbol{A}_{r}(t)$. The assumptions must be similar as in [4] for the problem of the first order.

## 2. Behaviour of a Solution for $t \rightarrow \infty$

We restrict our consideration only to the equations of the first and second order.
The initial value problem ( 0.1 ), ( 0.2 ) for $m=1$ has the form

$$
\begin{gather*}
A_{0} \frac{\mathrm{~d} u}{\mathrm{~d} t}+A_{1} u=f^{*}(t)  \tag{2.1}\\
u(0)=u_{0} \tag{2.2}
\end{gather*}
$$

We assume that $A_{0}, A_{1}$ satisfy the assumptions (1.2), (1.3) and moreover $A_{0}$ is symmetric and $A_{1}$ is coercive i.e.

$$
\begin{gather*}
\left\langle A_{0} x, y\right\rangle=\left\langle A_{0} y, x\right\rangle, x, y \in H  \tag{2.3}\\
\left\langle A_{1} x, x\right\rangle \geqslant \alpha_{1}\|x\|^{2}, x \in H, \alpha_{1}>0 \tag{2.4}
\end{gather*}
$$

The following theorem expresses the asymptotic behaviour of the solution of the problem (2.1), (2.2).

Theorem 2.1. Assume that the function $f^{*}$, the element $u_{0}$ the operators $A_{0}, A_{1}$ satisfy the assumptions of Theorem 1.1 and $A_{0}, A_{1}$ satisfy (2.3), (2.4). Then the next estimate for a solution $u \in C^{(1)}([0, \infty), H)$ of (2.1), (2.2) holds with the constants $M, v>0$ depending only on $A_{0}, A_{1}$

$$
\begin{equation*}
\|u(t)\| \leqslant M . \mathrm{e}^{-v t}\left(\left\|u_{0}\right\|+\int_{0}^{1} \mathrm{e}^{v \tau}\left\|f^{*}(\tau)\right\|_{*} \mathrm{~d} \tau\right), t \geqslant 0 \tag{2.5}
\end{equation*}
$$

If there exists such an element $f_{\infty}^{*} \in H^{*}$ that

$$
\begin{equation*}
\lim _{t \rightarrow \infty}\left\|f^{*}(t)-f_{\infty}^{*}\right\|_{*}=0 \tag{2.6}
\end{equation*}
$$

then

$$
\begin{equation*}
\lim _{t \rightarrow \infty}\left\|u(t)-u_{\infty}\right\|=0 \tag{2.7}
\end{equation*}
$$

where $u_{\infty}$ is a solution of the equation

$$
\begin{equation*}
A_{1} u_{\infty}=f_{\infty}^{*} \tag{2.8}
\end{equation*}
$$

Proof. The initial value problem (2.1), (2.2) is equivalent with the initial value problem

$$
\begin{gather*}
\frac{\mathrm{d} u}{\mathrm{~d} t}+B_{0}^{-1} B_{1} u=B_{0}^{-1} f(t)  \tag{2.9}\\
u(0)=u_{0} \tag{2.10}
\end{gather*}
$$

with the operators $B_{0}, B_{1}$ and the function $f$ defined in (1.6) and (1.8). The operators $B_{r}$ are coercive i.e.

$$
\begin{equation*}
(B r x, x) \geqslant \alpha_{r}\|x\|^{2}, x \in H, \alpha_{r}>0, r=0,1 \tag{2.11}
\end{equation*}
$$

and $B_{0}$ is symmetric i.e.

$$
\begin{equation*}
\left(B_{0} x, y\right)=\left(x, B_{0} y\right), x, y \in H \tag{2.12}
\end{equation*}
$$

The solution $u(t)$ of (2.9), (2.10) can be expressed (see [1]) in the form

$$
\begin{equation*}
u(t)=\mathrm{e}^{-B_{0}^{-B_{1}}} u_{0}+\int_{0}^{t} \mathrm{e}^{-B_{0}^{-1} B_{1}(t-\tau)} B_{0}^{-1} f(\tau) \mathrm{d} \tau \tag{2.13}
\end{equation*}
$$

where $\mathrm{e}^{-B_{0} \boldsymbol{\sigma}^{1} B_{1} t}$ is the abstract exponential-operator function with values in the Banach space $L(H, H)$ of all linear and bounded operators in $H$. The Bochner integral in $H$ ([10]) is considered in (2.13). In order to estimate (2.13) we shall use the spectral theory. For this purpose we extend the space $H$ to the complex Hilbert space which we denote again $H$. We extend the operators $B_{r}$ over the complex space too. It can be verified easily that $B_{0}=B_{0}^{*}$ and $B_{1}$ satisfy the inequalities

$$
\begin{gather*}
\left(B_{0} x, x\right) \geqslant \alpha_{0}\|x\|^{2}, \alpha_{0}>0  \tag{2.14}\\
\operatorname{Re}\left(B_{1} x, x\right) \geqslant \alpha_{i}\|x\|^{2}, \alpha_{1}>0, x \in H . \tag{2.15}
\end{gather*}
$$

Let $\sigma\left(-B_{0}^{-1} B_{1}\right)$ be the spectrum of $-B_{0}^{-1} B_{1}$. If there exists such a constant $v>0$, that

$$
\begin{equation*}
\operatorname{Re} \lambda<v, \lambda \in \sigma\left(-B_{0}^{-1} B_{1}\right) \tag{2.16}
\end{equation*}
$$

then there exists such a constant $N$ depending only on $B_{0}, B_{1}$ that

$$
\begin{equation*}
\left\|\mathrm{e}^{-B_{0} B_{1} B_{1} t}\right\| \leqslant N \mathrm{e}^{-v t}, t \in[0, \infty) \tag{2.17}
\end{equation*}
$$

This assertion is proved in ([6], Th. 1.2). If (2.17) holds with $v>0$ then the conclusions of the theorem follow easily from (2.13). We show at first that $\operatorname{Re} \lambda<0$ for all $\lambda \in \sigma\left(-B_{0}^{-1} B_{1}\right)$. It is sufficient to show that the relation $0 \in \sigma\left(\lambda B_{0}+B_{1}\right)$ implies $\operatorname{Re} \lambda<0$.

Let $\operatorname{Re} \lambda \geqslant 0$. We denote by.

$$
\begin{equation*}
T(\lambda)^{*}=\bar{\lambda} B_{0}+B_{1}^{*} \tag{2.18}
\end{equation*}
$$

the operator adjoint to $T(\lambda)=\lambda B_{0}+B_{1}$. The operators $T(\lambda)$ and $T(\lambda)$ * satisfy the relations

$$
\begin{equation*}
\operatorname{Re}(T(\lambda) x, x)=\operatorname{Re}\left(T(\lambda)^{*} x, x\right) \geqslant \alpha_{1}\|x\|^{2}, \alpha_{1}>0, x \in H \tag{2.19}
\end{equation*}
$$

Using the Schwarz inequality and the corollary from ([10], VII) we obtain

$$
\begin{equation*}
R(T(\lambda))=H, N(T(\lambda))=\{\overline{0}\}, \tag{2.20}
\end{equation*}
$$

where $R(T(\lambda))$ is the range of the operator $T(\lambda)$ and $N(T(\lambda))=$ $\{x \in H, T(\lambda) x=\overline{0}\}$. Hence $\lambda \notin \sigma\left(-B_{0}^{-1} B_{1}\right) \quad$ and $\quad$ so $\operatorname{Re} \lambda<0 \quad$ for all $\lambda \in \sigma\left(-B_{0}^{-1} B_{1}\right)$.

It remains to show the existence of a number $v>0$ such that $\operatorname{Re} \lambda<-v$ for all $\lambda \in \sigma\left(-B_{0}^{-1} B_{1}\right)$. Assume that there does not exist such a number. Then there exists a sequence $\lambda_{n} \in \sigma\left(-B_{0}^{-1} B_{1}\right)$ such that $\lim _{n \rightarrow \infty} \operatorname{Re} \lambda_{n}=0$. All points of $\sigma\left(-B_{0}{ }^{1} B_{1}\right)$ lie in the circle $|\lambda| \leqslant\left\|-B_{0}^{-1} B_{1}\right\|$ We can choose such a subsequence $\lambda_{n_{k}}$, that $\lim _{k \rightarrow \infty} \lambda_{n_{k}}=\lambda_{0}$ and $\operatorname{Re} \lambda_{0}=0$. The spectrum $\sigma\left(-B_{0}{ }^{1} B_{1}\right)$ is closed in the complex plane ( $[7]$ ) and thereby $\lambda_{0} \in \sigma\left(-B_{0}^{-1} B_{1}\right)$, $\operatorname{Re} \lambda_{0}=0$ that is a contradiction which completes the proof of (2.16). As we remarked above (2.16) implies (2.17) Then due to (1.8), (2.13), (2.14) the estimate (2.5) holds with the constant $M=N \max \left(1, \alpha^{\prime}\right)$.

We verify now the second part of the theorem. Assume that (2.6) holds. The existence of $u_{\infty}$ in (2.8) is secured because $A_{1} \in L\left(H, H^{*}\right)$ and (2.4) holds. Let us denote

$$
\begin{align*}
v(t) & =u(t)-u_{\infty}  \tag{2.21}\\
v_{0} & =u_{0}-u_{\infty} \tag{2.22}
\end{align*}
$$

$$
\begin{equation*}
g^{*}(t)=f^{*}(t)-f_{\infty}^{*} \tag{2.23}
\end{equation*}
$$

The function $v$ is a solution of the initial value problem

$$
\begin{gather*}
A_{0} \frac{\mathrm{~d} v}{\mathrm{~d} t}+A_{1} v=g^{*}(t)  \tag{2.24}\\
v(0)=v_{0}
\end{gather*}
$$

Using (2.5) we obtain

$$
\begin{equation*}
\|v(t)\| \leqslant M \mathrm{e}^{-v t}\left(\left\|v_{o}\right\|+\int_{0}^{t} \mathrm{e}^{v \tau}\left\|g^{*}(\tau)\right\| * \mathrm{~d} \tau\right) \tag{2.26}
\end{equation*}
$$

If $\lim _{\tau \rightarrow \infty} \int_{0}^{t} \mathrm{e}^{\nu \tau}\left\|g^{*}(\tau)\right\|_{* \mathrm{~d}} \tau<\infty$ then

$$
\begin{equation*}
\lim _{t \rightarrow \infty}\|v(t)\|=0 \tag{2.27}
\end{equation*}
$$

otherwise we use L'Hospitale rule and we obtain (2.27) from (2.6) too. Comparing (2.21) and (2.27) we arrive at (2.7) which completes the proof.

Let us consider now the initial value problem of the second order

$$
\begin{equation*}
A_{0} \frac{\mathrm{~d}^{2} u}{\mathrm{~d} t^{2}}+A_{1} \frac{\mathrm{~d} u}{\mathrm{~d} t}+A_{2} u=f^{*}(t) \tag{2.28}
\end{equation*}
$$

$$
\begin{gather*}
u(0)=u_{0}  \tag{2.29}\\
\left.\frac{\mathrm{~d} u}{\mathrm{~d} t}\right|_{t=0}=u_{1}
\end{gather*}
$$

We assume that $A_{0}, A_{1}, A_{2}$ satisfy the assumptions of Theorem 1.1, $A_{0}, A_{1}$ satisfy (2.3), (2.4) and $A_{2}$ is symmetric and coercive i.e.

$$
\begin{gather*}
\left\langle A_{2} x, y\right\rangle=\left\langle A_{2} y, x\right\rangle ., x, y \in H  \tag{2.31}\\
\left\langle A_{2} x, x\right\rangle \geqslant \alpha_{2} \cdot\|x\|^{2}, \quad \alpha_{2}>0, x \in H \tag{2.32}
\end{gather*}
$$

The following theoren expresses the asymptotic behaviour of a solution of the problem (2.28), (2.29), (2.30).

Theorem 2.2. Assume that the funnction $f^{*}$, the elements $u_{0}$, $u_{1}$, the operators $A_{0}, A_{1}, A_{2}$ satisfy the assumptions of Theorem 1.1 and $A_{0}, A_{1}, A_{2}$ satisfy (2.3), (2.4), (2.31), (2.32). Then a solution $u \in C^{(2)}([0, \infty), H)$ of (2.28), (2.29), (2.30) satisfies the estimate

$$
\begin{equation*}
\left(\|u(t)\|^{2}+\left\|u^{\prime}(t)\right\|^{2}\right)^{1 / 2} \tag{2.33}
\end{equation*}
$$

$$
M \mathrm{e}^{-v . t}\left[\left(\left\|u_{0}\right\|^{2}+\left\|u_{1}\right\|^{2}\right)^{1 / 2}+\int_{0}^{t} \mathrm{e}^{\nu \tau}\left\|f^{*}(\tau)\right\|_{*} \mathrm{~d} \tau\right]
$$

with the constants $M, v>0$ depending only on $A_{0}, A_{1}, A_{2}$.
If there exists such a functional $f^{*} \in H$ that

$$
\begin{equation*}
\lim _{t \rightarrow \infty}\left\|f^{*}(t)-f_{*}^{*}\right\|_{*}=0 \tag{2.34}
\end{equation*}
$$

then

$$
\begin{equation*}
\lim _{t \rightarrow \infty}\left(\left\|u(t)-u_{\infty}\right\|+\left\|u^{\prime}(t)\right\|\right)=0 \tag{2.35}
\end{equation*}
$$

where $u_{x} \in H$ is a solution of the equation

$$
\begin{equation*}
A_{2} u_{\infty}=f_{\infty}^{*} . \tag{2.36}
\end{equation*}
$$

Proof. We can consider instead of (2.28) the equation

$$
\begin{equation*}
\frac{\mathrm{d}^{2} u}{\mathrm{~d} t^{2}}+B_{0}^{-1} B_{1} \frac{\mathrm{~d} u}{\mathrm{~d} t}+B_{0}^{1} B_{2}=B_{0}^{-1} f(t) \tag{2.37}
\end{equation*}
$$

with the operators $B_{r}=R A_{r}, r=0,1,2$ and the function $f=R f^{*}$. The initial value problem (2.28), (2.29), (2.30) is equivalent with the problem (2.37), (2.29), (2.30). The operators $B_{r}$ are coercive

$$
\begin{equation*}
\left(B_{r} x, x\right) \geqslant \alpha_{r}\|x\|^{2}, \alpha_{r}>0, r=0,1,2, x \in H \tag{2.38}
\end{equation*}
$$

The operators $B_{0}, B_{2}$ are symmetric

$$
\begin{equation*}
\left(B_{r} x, y\right)=\left(x, B_{r} y\right), r=0,2 ; x, y \in H \tag{2.39}
\end{equation*}
$$

The problem (2.37), (2.29), (2.30) can be formulated as the initial value problem. of the first order in the space $\mathscr{H}=H \otimes H$

$$
\begin{gather*}
\frac{\mathrm{d} U}{\mathrm{~d} t}+\mathscr{B} U=F(t)  \tag{2.40}\\
U(0)=U_{0} \tag{2.41}
\end{gather*}
$$

with

$$
\begin{gather*}
F(t)=\left(\overline{0}, B_{0}^{-1} f(t)\right)^{T}  \tag{2.42}\\
U_{0}=\left(u_{0}, u_{1}\right)^{T}  \tag{2.43}\\
\mathscr{B}=\left(\begin{array}{cc}
0 & -I \\
B_{0}^{-1} B_{1} & B_{0}^{-1} B_{2}
\end{array}\right) \tag{2.44}
\end{gather*}
$$

A solution $U \in C^{(1)}([0, \infty), \mathscr{H})$ of (2.40), (2.41) has the form

$$
\begin{equation*}
U(t)=\mathrm{e}^{-\Im t} U_{0}+\int_{0}^{t} \mathrm{e}^{-\circledast(\mathrm{t}-\tau)} \mathrm{F}(\tau) \mathrm{d} \tau . \tag{2.45}
\end{equation*}
$$

We shall use the spectral theory in the same way as in the proof of Theorem 2.1. We extend the space $H$ to the complex Hilbert space. The extended operators $B_{0}, B_{1}, B_{2}$ remain coercive and $B_{0}, B_{2}$ remain symmetric. Our aim is to verify the existence of a constant $v>0$ such that

$$
\begin{equation*}
\operatorname{Re} \lambda<-v, \lambda \in \sigma(-\mathscr{B}) \tag{2.46}
\end{equation*}
$$

If (2.46) holds, then there exists a constant $N$ depending only on $\mathscr{B}$ such that

$$
\begin{equation*}
\left\|\mathrm{e}^{-\infty t}\right\|_{\mathscr{X}} \leqslant N \mathrm{e}^{-v} t, t \in[0, \infty) \tag{2.47}
\end{equation*}
$$

Comparing with the proof of Theorem 2.1 we can see, that it is sufficient to verify
that $\operatorname{Re} \lambda<0$ for all $\lambda \in \sigma(-\mathscr{B})$. It can be verified easily that $\lambda \in \sigma(-\mathscr{B})$ iff $0 \in \sigma(D(\lambda))$, where

$$
\begin{equation*}
D(\lambda)=\lambda^{2} B_{1}+\lambda B_{1}+B_{2} . \tag{2.48}
\end{equation*}
$$

If $\lambda=0$, then $D(\lambda)=B_{2}$. The operator $B_{2}$ is coercive and hence $0 \in \sigma(D(\lambda))$. Let $\operatorname{Re} \lambda \geqslant 0, \lambda \neq 0$. We consider, instead od $D(\lambda)$, the operator ([5])

$$
\begin{equation*}
T(\lambda)=\lambda{ }^{1} D(\lambda)=\lambda B_{0}+B_{1}+\lambda^{-1} B_{2} . \tag{2.49}
\end{equation*}
$$

The adjoint operator $T(\lambda)^{*}$ has the form

$$
\begin{equation*}
T(\lambda)^{*}=\bar{\lambda} B_{0}+B_{1}^{*}+\bar{\lambda}^{-1} B_{2} \tag{250}
\end{equation*}
$$

The operators $T(\lambda), T(\lambda)^{*}$ satisfy the relations

$$
\begin{gather*}
\operatorname{Re}(T(\lambda) x, x)=\operatorname{Re}\left(T(\lambda)^{*} x, x\right)= \\
=\operatorname{Re} \lambda\left(B_{0} x, x\right)+\operatorname{Re}\left(B_{1} x, x\right)+\operatorname{Re} \lambda|\lambda|^{-2}\left(B_{2} x, x\right) \geqslant  \tag{2.51}\\
\geqslant \operatorname{Re}\left(B_{1} x, x\right) \geqslant \alpha_{1}\|x\|^{2}, \alpha_{1}>0, x \in H
\end{gather*}
$$

(2.51) implies, in the same way as (219) in the proof of Theorem 2.1, that ${ }^{0} \sigma(T(\lambda))$ i. e. $\lambda \notin \sigma(-\mathscr{B})$. Hence $\operatorname{Re} \lambda<0$ for all $\lambda \in \sigma(-\mathscr{B})$ and as we remarked there exists $v>0$ such that (2.46) holds. (2.46) implies (2.47). Combining (2.45) and (2.47) we obtain

$$
\begin{equation*}
\|U(t)\|_{\ngtr} \leqslant N \mathrm{e}^{-v t}\left(\left\|U_{0}\right\|_{\ngtr}+\int_{0}^{t} \mathrm{e}^{v \tau}\|F(\tau)\|_{\ngtr} \mathrm{d} \tau\right) \tag{2.52}
\end{equation*}
$$

Using (2.40), (2.42), (2.43), (2.52) we obtain the inequality (2.33) with the constant $M=N \max \left(1, \alpha_{0}{ }^{1}\right)$.

The second assertion of the theorem can be verified in the same way as (2.7) in Theorem 2.1. It is sufficient to use (2.33).

## 3. Bending of Viscoelastic Plates

The previous theory can be applied to the mixed problems which. express bending of viscoelastic plates ([2], [3]).

$$
\begin{gather*}
\sum_{r}^{m} K_{i, k l}^{(r)} \frac{\mathrm{d}^{m r}}{\mathrm{~d} t^{m-r}} u,_{, i k l}=f^{*}\left(x_{1}, x_{2}, t\right)  \tag{3.1}\\
\left.\frac{\mathrm{d}^{r} u}{\mathrm{~d} t^{r}}\right|_{t-0}=u_{r}, r=0,1, \ldots, m-1  \tag{3.2}\\
u=\frac{\partial u}{\partial n}=0 \quad \text { on } \quad \partial \Omega \tag{3.3}
\end{gather*}
$$

or

$$
u=0 \quad \text { on }
$$

$$
\begin{equation*}
N u=\sum_{r=0}^{m} K_{i, k l}^{(r)} \frac{\mathrm{d}^{m-r}}{\mathrm{~d} t^{m-r}} u,_{i j} \cos \left(n, x_{k}\right) \cos \left(n, x_{e}\right)=0 \quad \text { on } \quad \partial \Omega \tag{3.4}
\end{equation*}
$$

We use the notation $u,_{i j k l}=\frac{\partial^{4} u}{\partial x_{i} \partial x_{j} \partial x_{k} \partial x_{l}}, i, j, k, l \in\{1,2\}$. Summation over repeated subscripts $i . j . k . l$ is implied. The plate has the form of a bounded domain $\Omega \subset E_{2}$ with Lipschitzian boundary $\partial \Omega$ (def. [8]). The coefficients $K_{i, k l}^{(r)}$ are symmetric i. e.

$$
\begin{equation*}
K_{i j k l}^{(r)}=K_{i j k l}^{(r)}=K_{i j l k}^{(r)}=K_{k l i j}^{(r)} \tag{3.5}
\end{equation*}
$$

and positive definite i.e.

$$
\begin{gather*}
K_{i j k l}^{(r)} \varepsilon_{i j} \varepsilon_{k l} \geqslant c_{r}\left(\varepsilon_{1_{1}}^{2}+\varepsilon_{1_{2}}^{2}+\varepsilon_{2_{2}}^{2}\right),  \tag{3.6}\\
c_{r}>0, r=0,1, \ldots, m,\left(\varepsilon_{11}, \varepsilon_{12}, \varepsilon_{22}\right) \in E_{3} .
\end{gather*}
$$

The classical solutions of the problems (3.1), (3.2), (3.3) or (3.4) can be established only for sufficiently smooth boundary $\partial \Omega$ ([2]). We introduce therefore a weak solutions of the problems.

We denote by $H^{2}(\Omega)$ the Sobolev space of all functions from $L_{2}(\Omega)$, whose generalized derivatives up to the 2 -nd order are in $L_{2}(\Omega)$. The scalar product in $H^{2}(\Omega)$ is defined by

$$
\begin{align*}
& (u, v)_{2}=\sum_{|i| \leqslant 2} \int_{\Omega} D^{i} u D^{i} v \mathrm{~d} \Omega  \tag{3.7}\\
& \left(D^{i} u=\frac{\partial^{|c|} u}{\partial x_{1}^{i_{1}} \partial x_{2}^{i_{2}}}, \quad i=i_{1}+i_{2}\right)
\end{align*}
$$

Let $\mathscr{D}(\Omega)$ be the set of all arbitrarily differentiable functions with a compact support in $\Omega$ and $H_{0}^{2}(\Omega)$ be the closure of $\mathscr{D}(\Omega)$ in the space $H^{2}(\Omega)$. It is well known ([8]) that $H_{o}^{2}(\Omega)$ is a Hilbert space with a scalar product

$$
\begin{equation*}
(u, v)_{0}=\sum_{\mid, 1 \leqslant 2} \int_{\Omega} D^{i} u D^{i} v \mathrm{~d} \Omega \tag{3.8}
\end{equation*}
$$

and a norm

$$
\begin{equation*}
\|u\|_{0}=\left(\sum_{\mid i=2} \int_{\Omega}\left(D^{i} u\right)^{2} \mathrm{~d} \Omega\right)^{1 / 2} \tag{3.9}
\end{equation*}
$$

which is equivalent with the original norm in $H^{2}(\Omega)$. We denote further by $H^{-2}(\Omega)$
the space of all linear functionals over $H_{0}^{2}(\Omega)$. It can be verified with the help of Fridrichs inequality $([8])$, that $L_{2}(\Omega) \subset H^{-2}(\Omega)$ and if $f^{*} \in L_{2}(\Omega), h \in H_{0}^{2}(\Omega)$, then $\left\langle f^{*}, h\right\rangle=f^{*}(h)=\int_{\Omega} f^{*} h \mathrm{~d} \Omega$.

Definition 3.1. Let $f^{*} \in C\left([0, \infty), H^{-2}(\Omega)\right), u_{r} \in H_{0}^{2}(\Omega), r=0,1, \ldots, m-1$. The function $u \in C^{(m)}\left([0, \infty), H_{0}^{2}(\Omega)\right)$ which is for each $h \in H_{0}^{2}(\Omega)$ a solution of the initial value problem

$$
\left.\begin{gather*}
\sum_{r=0}^{m} \frac{\mathrm{~d}^{m-r}}{\mathrm{~d} t^{m-r}} \int_{\Omega} K_{i j k l}^{(r)} u, i j(t) h, k l  \tag{3.10}\\
\frac{\mathrm{~d}}{}\left(\mathrm{~d} u=\left\langle f^{*}(t), h\right\rangle\right.  \tag{3.11}\\
\mathrm{d} t^{r}
\end{gather*}\right|_{t=0}=u_{r}, \quad r=0,1, \ldots, m-1,
$$

is a weak solution of the problem (3.1), (3.2), (3.3).
Theorem 3.1. There exists a unique weak solution of the problem (3.1), (3.2), (3.3).

Proof. It is sufficient to use Theorem 1.1. In this case the operators $A_{r}:\left(H_{0}^{2}(\Omega) \rightarrow H^{-2}(\Omega)\right)$ are defined with the help of the duality

$$
\begin{align*}
& \left\langle A_{r} u, h\right\rangle=\int_{\Omega} K_{i j k l}^{(r)} u_{, i j} h,_{, k l} \mathrm{~d} \Omega  \tag{3.12}\\
& u, h \in H_{0}^{2}(\Omega), r=0,1, \ldots, m
\end{align*}
$$

The operators $A_{r}$ are linear and bounded i. e. $A_{r} \in L\left(H_{0}^{2}(\Omega), H^{-2}(\Omega)\right)$. Using (3.5), (3.6), (3.9) we obtain that $A_{r}$ are symmetric and coercive and hence all assumptions of Theorem 1.1 are fulfilled. The initial value problem (0.1), (0.2) is in this case equivalent with the problem (3.10), (3.11) and the proof is complete.

In the case of the problem (3.1), (3.2), (3.4) we define a weak solution which satisfies only the essential boundary condition $u=0$ on $\partial \Omega$. We denote by $\dot{H}^{2}(\Omega)$ the subspace of $H^{2}(\Omega)$ which consists of all functions vanishing on $\partial \Omega$ :

$$
\begin{equation*}
\dot{H}^{2}(\Omega)=\left\{u \in H^{2}(\Omega), u=0 \text { on } \partial \Omega\right\} \tag{3.13}
\end{equation*}
$$

Due to the theorem on traces ([8]) $\dot{H}^{2}(\Omega)$ is the closed subspace of $H^{2}(\Omega)$ and hence $\dot{H}^{2}(\Omega)$ is the Hilbert space with the scalar product (3.7). It can be verified with the help of Friedrichs and Poincaré inequalities ([8]) that (.,. $)_{0}$ defined in (3.8) is the scalar product on $\dot{H}^{2}(\Omega)$ and the norm $\|\cdot\|_{0}$ in (3.9) is equivalent with the original norm $\|\cdot\|_{2}=(., .)^{1 / 2}$. Let us denote by $\dot{H}^{-2}(\Omega)$ the dual space of $\dot{H}^{2}(\Omega)$.

Definition 3.2. Let $f^{*} \in C\left([0, \infty), \dot{H}^{-2}(\Omega)\right), u_{r} \in \dot{H}^{2}(\Omega), r=0,1, \ldots, m-1$. The function $u \in C^{(m)}\left([0, \infty), \dot{H}^{2}(\Omega)\right)$ which is for each $h \in \dot{H}^{2}(\Omega)$ a solution of the initial value problem

$$
\begin{gather*}
\sum_{r=0}^{m} \frac{\mathrm{~d}^{r}}{\mathrm{~d} t^{r}} \int_{\Omega} K_{i j k l}^{(r)} u,_{, j}(t) h_{, k l} \mathrm{~d} \Omega=\left\langle f^{*}(t), h\right\rangle  \tag{3.14}\\
\left.\quad \frac{\mathrm{d}^{r} u}{\mathrm{~d} t^{r}}\right|_{t=0}=u_{r}, \quad r=0,1, \ldots, m-1
\end{gather*}
$$

is a weak solution of the problem (3.1), (3.2), (3.4).
Theorem 3.2. There exists a unique weak solution of the problem (3.1), 3.2), (3.4).

Proof. It is sufficient to use Theorem 1.1 in the same way as in the proof of Theorem 3.1. The operators $A_{r}:\left(\dot{H}^{2}(\Omega) \rightarrow \dot{H}^{-2}(\Omega)\right)$ are of the form (3.12) for $u, h \in \dot{H}^{2}(\Omega)$. They are symmetric due to (3.5) and coercive due to (3.6) and (3.9).

Theorem 3.3. Assume that $m=1$, or $m=2$. Let $f^{*} \in C\left([0, \infty), H^{2}(\Omega)\right)$, $\left.f_{\infty}^{*} \in H^{-2}(\Omega)\left(f^{*} \in C\left([0, \infty), \dot{H}^{-2}(\Omega)\right), f_{\infty}^{*} \in \dot{H}^{-2}(\Omega)\right)\right), \lim _{\rightarrow \infty}\left\|f^{*}(t)-f_{\infty}^{*}\right\|_{*}-0$. If $u \in C^{(m)}\left([0, \infty), H_{o}^{2}(\Omega)\right)\left(u \in C^{(m)}\left([0, \infty), \dot{H}^{2}(\Omega)\right)\right.$ is a weak solution of the problem (3.1), (3.2), (3.3), ((3.4)) then

$$
\begin{equation*}
\lim _{t \rightarrow \infty}\left\|u(t)-u_{\infty}\right\|=0 \tag{3.16}
\end{equation*}
$$

where $u_{\infty} \in H_{0}^{2}(\Omega)\left(u_{\infty} \in \dot{H}^{2}(\Omega)\right)$ is for each $h \in H_{0}^{2}(\Omega)\left(h \in \dot{H}^{2}(\Omega)\right)$ a solution of the problem

$$
\begin{equation*}
\int_{\Omega} K_{i j k l}^{(m)} u,_{, i j} h_{, k l} \mathrm{~d} \Omega=\left\langle f_{\infty}^{*}, h\right\rangle \tag{3.17}
\end{equation*}
$$

Proof. Due to the symmetry and the coerciveness of the operators $A_{r}$ in (3.12) Theorems 2.1 and 2.2 can be applied. The result follows directly.

Remark. Theorem 3.3 expresses the fact that a solution of viscoelastic problems (3.1), (3.2), (3.3), or (3.4) behaves for great time values as a solution of ela tic problem (3.17).

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## ПСЕУДОПАРАВОЛИЧЕСКИЕ ДИФФЕРЕНЦИАЛЬНЫЕ УРАВНЕНИЯ БЫСШЕГО ПОРЯДКА

Иıор Бок

## Резюме

В этой работе изучается начальная задача (0.1), (0.2) в пространстве Гильберта $H$ с операторами $A_{r} \in L\left(H, H^{*}\right)$. Если оператор $\boldsymbol{A}_{\circ}$ коэрцивный, потом для любой непрерывнои функции и любых элементов $u_{r} \in H$ существует единственное решение начальной задачи ( 0.1 ), (0.2). Если эта начальная задача первого или второго порядка, операторы $A, A_{1}, A_{2}$ коэрцивные, операторы $A_{0}, A_{2}$ симетрические и $\lim _{t \rightarrow \infty} \| f^{*}(t)-\left.f_{\infty}^{*}\right|_{*}=0, f_{\infty}^{*} \in H^{*}$, то $\lim _{t \rightarrow \infty} \| u(t)-u_{\infty} \mid-$ 0 , где $u_{\infty} \in H$ решение уравнения $A_{m} v=f_{\infty}^{*}$. Полученные результаты используются для решениа смешанных проблем, которые определяют изгибы вязкоупругих пластин

