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# MINIMUM VARIANCE QUADRATIC UNBIASED ESTIMATION OF VARIANCE COMPONENTS 

ŠTEFAN VARGA

## Introduction

Let us consider the linear model

$$
\begin{equation*}
\mathbf{Y}=\mathbf{X} \boldsymbol{\beta}+\mathbf{e}, \tag{1}
\end{equation*}
$$

where $X$ is a given $n \times p$-matrix, $\beta$ an unknown $p$-vector of parameters and $\mathbf{e}$ a random $n$-vector with expectation zero and covariance matrix

$$
\begin{equation*}
D(\mathbf{e})=D(\mathbf{Y})=\theta_{1} \mathbf{V}_{1}+\ldots+\theta_{m} \mathbf{V}_{m}=\mathbf{V}_{\theta} . \tag{2}
\end{equation*}
$$

The matrices $\mathbf{V}_{i}(i=1,2, \ldots, m)$ are known symmetric $n \times n$-matrices. We are interested in the estimation of the unknown parameter vector $\theta=\left(\theta_{1}, \ldots, \theta_{m}\right)$ belonging to the set $\mathcal{O}$ of all $\theta \in \mathscr{R}^{m}$ such that $\mathbf{V}_{\theta}$ becomes positive definite (p.d.).

Assume that the matrix $S$ containing prior values of elements of the covariance matrix $\mathbf{V}_{\boldsymbol{\theta}}$ is known (the $(i, j)$-th element of the matrix $\mathbf{S}$ is a prior value of the ( $i, j$ )-th element of the matrix $\mathbf{V}_{\theta}$ for $i, j=1,2, \ldots, n$ ).

A quadratic estimation of the linear function

$$
\begin{equation*}
q=\sum_{i=1}^{m} f_{i} \theta_{i}=\mathbf{f}^{\prime} \theta \tag{3}
\end{equation*}
$$

of $\theta$ will be considered in the form

$$
\begin{equation*}
\hat{q}(\mathbf{Y}, \mathbf{V}, \mathbf{S})=\mathbf{Y}^{\prime} \mathbf{A}(\mathbf{V}, \mathbf{S}) \mathbf{Y} \tag{4}
\end{equation*}
$$

where the matrix $\mathbf{V}$ is defined by

$$
\mathbf{V}=\left\langle\begin{array}{c}
\mathbf{V}_{1}+\ldots+\mathbf{V}_{m}  \tag{5}\\
\alpha_{1} \mathbf{V}_{1}+\ldots+\alpha_{m} \mathbf{V}_{m}
\end{array}\right.
$$

in dependence on whether a prior value $\alpha=\left(\alpha_{1}, \ldots, \alpha_{m}\right)^{\prime}$ of $\theta=(\theta, \ldots, \theta)^{\prime}$ is unknown (first row) or known (second row).

A natural question is how the knowledge of the matrix $\mathbf{S}$ contributes to estimating the variance components $\theta_{1}, \ldots, \theta_{m}$ and the function (3).

## 1. Symbols and auxiliary statements

Let $(\ell,\langle.,\rangle$.$) be a Hilbert space of symetric n \times n$ matrices, $\langle.,$.$\rangle denotes the$ inner product given by $\langle\mathbf{A}, \mathbf{B}\rangle=\operatorname{tr} \mathbf{A B}, \mathbf{A}, \mathbf{B} \in \mathscr{I}$; here $\operatorname{tr} \mathbf{C}$ denotes the trace of the matrix $C$. The matrix $A$ in (4) is from $\boldsymbol{\ell}$.

The natural estimator of the function (3) in the linear model (1) is defined by the formula

$$
\begin{equation*}
\mathbf{e}_{*}^{\prime} \sum_{i=1}^{m} \lambda_{i} \mathbf{V}^{-1 / 2} \mathbf{V}_{i} \mathbf{V}^{-1 / 2} \mathbf{e}_{*} \tag{6}
\end{equation*}
$$

(see (5.4.3) in [4]), where $\mathbf{e}_{*}=\mathbf{V}^{-1 / 2} \mathbf{e}$ and the vector $\lambda=\left(\lambda_{1}, \ldots, \lambda_{m}\right)^{\prime}$ is any solution of the linear system

$$
\begin{equation*}
\mathbf{M} \lambda=\mathbf{f} . \tag{7}
\end{equation*}
$$

The $(i, j)$-th element of the matrix $\mathbf{M}$ is $\{\mathbf{M}\}_{i, j}=\operatorname{tr} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{V}_{j}$ and $\mathbf{f}=\left(f_{1}, \ldots, f_{m}\right)^{\prime}$.
Definition 1.1. ([2]) A minimum norm invariant unbiased quadratic estimator (MINQUE(U, I)) of the function $\boldsymbol{f}^{\prime} \boldsymbol{\theta}$ is a statistic $\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}$, where the matrix $\mathbf{A}$ minimizes the expression $\operatorname{tr}$ AVAV in the class $A_{1}$.

$$
\begin{equation*}
\ell_{1}=\left\{\mathbf{A} \in \mathscr{A}: \mathbf{A X}=\mathbf{0} ; \operatorname{tr} \mathbf{A} \mathbf{V}_{i}=\mathbf{f}_{i}, \quad i=1,2, \ldots, m\right\} \tag{8}
\end{equation*}
$$

Lemma 1.2. The $\operatorname{MINQUE}(U, I)$ of the function $f^{\prime} \theta$ is the statistic $\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}$, where $\mathbf{A}=\sum_{i=1}^{m} \delta_{i} \mathbf{Q}_{\mathbf{V}}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{V}$, the expression $\mathbf{Q}_{V}=\mathbf{I}-\mathbf{X}\left(\mathbf{X}^{\prime} \mathbf{V}^{-1} \mathbf{X}\right)^{-} \mathbf{X}^{\prime} \mathbf{V}^{-1}$ and the vector $\delta=\left(\delta_{1}, \ldots, \delta_{m}\right)^{\prime}$ is any solution of the linear system $\mathbf{B} \delta=\mathbf{f}$. The $(i, j)$-th element of the matrix $\mathbf{B}$ is $\operatorname{tr} \mathbf{V}_{j} \mathbf{Q}_{V} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{\mathbf{V}}$. I is a unite matrix.

Proof. See [4], Theorem 5.1.1 and Note 2.
Lemma 1.3. If $\mathbf{Y} \sim N_{n}\left(\mathbf{X} \beta, \sum_{i=1}^{m} \theta_{1} \mathbf{V}_{1}\right)$ and $\mathbf{A} \in \mathcal{l}_{1}$, then for the variance of the random variable $\mathbf{Y}^{\prime} \mathbf{A Y}$ the following holds

$$
\begin{equation*}
D_{\theta}\left(\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}\right)=2 \operatorname{tr} \mathbf{A} \mathbf{V}_{\hat{\theta}} \mathbf{A} \mathbf{V}_{\theta} . \tag{9}
\end{equation*}
$$

Proof. See [1], Theorem 1.

## 2. Natural estimation and S-estimation

Using the transformation $\mathbf{e}=\mathbf{S}^{1 / 2} \varepsilon\left(\varepsilon=\mathbf{S}^{-1 / 2} \mathbf{e}\right)$ in the linear model (1), the natural estimator (6) of $f^{\prime} \theta$ is

$$
\begin{equation*}
\varepsilon^{\prime} \mathbf{N} \varepsilon=\varepsilon^{\prime} \sum_{i=1}^{m} \chi_{i} \mathbf{S}^{1 / 2} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S}^{1 / 2} \varepsilon \tag{10}
\end{equation*}
$$

where the vector $\chi=\left(\chi_{1}, \ldots, \chi_{m}\right)^{\prime}$ is any solution of the linear system

$$
\begin{equation*}
\mathbf{M X}=\mathbf{f} . \tag{11}
\end{equation*}
$$

The matrix $\mathbf{M}$ is defined in (7).
The considered quadratic estimator (4) with respect to the transformation $\mathbf{e}=\mathbf{S}^{1 / 2} \varepsilon$ is

$$
\begin{gather*}
\hat{q}(\mathbf{Y}, \mathbf{V}, \mathbf{S})=\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}=\left(\mathbf{X} \beta+\mathbf{S}^{1 / 2} \varepsilon\right)^{\prime} \mathbf{A}\left(\mathbf{X} \beta+\mathbf{S}^{1 / 2} \varepsilon\right)= \\
=\left(\varepsilon^{\prime}, \boldsymbol{\beta}^{\prime}\right)\left(\begin{array}{ll}
\mathbf{S}^{1 / 2} \mathbf{A} \mathbf{S}^{1 / 2} & \mathbf{S}^{1 / 2} \mathbf{A X} \\
\mathbf{X}^{\prime} \mathbf{A} \mathbf{S}^{1 / 2} & \mathbf{X}^{\prime} \mathbf{A} \mathbf{X}
\end{array}\right)\binom{\varepsilon}{\beta} . \tag{12}
\end{gather*}
$$

The difference between the considered estimator (12) and the natural estimator (10) of the function $f^{\prime} \theta$ is

$$
\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}-\varepsilon^{\prime} \mathbf{N} \varepsilon=\left(\varepsilon^{\prime}, \boldsymbol{\beta}^{\prime}\right)\left(\begin{array}{cc}
\mathbf{S}^{1 / 2} \mathbf{A} \mathbf{S}^{1 / 2}-\mathbf{N} & \mathbf{S}^{1 / 2} \mathbf{A X}  \tag{13}\\
\mathbf{X}^{\prime} \mathbf{A} S^{1 / 2} & \mathbf{X}^{\prime} \mathbf{A X}
\end{array}\right)\binom{\varepsilon}{\beta}
$$

The minimum norm quadratic estimation which is a function of the matrix $\mathbf{S}$ (MINQE (S)) is obtained by minimizing the Euclidean norm of the matrix $\mathbf{H}$ of the quadratic form (13) defined as follows

$$
H=\left(\begin{array}{cc}
S^{1 / 2} A S^{1 / 2}-N & S^{1 / 2} \mathbf{A X}  \tag{14}\\
\mathbf{X}^{\prime} A S^{1 / 2} & X^{\prime} \mathbf{A X}
\end{array}\right)
$$

The square of the Euclidean norm of $\mathbf{H}$ is

$$
\begin{equation*}
\|\mathbf{H}\|^{2}=\operatorname{tr}\left(\mathbf{S}^{1 / 2} \mathbf{A} \mathbf{S}^{1 / 2}-\mathbf{N}\right)^{2}+2 \operatorname{tr} \mathbf{X}^{\prime} \mathbf{A S A X}+\operatorname{tr}\left(\mathbf{X}^{\prime} \mathbf{A X}\right)^{2} . \tag{15}
\end{equation*}
$$

We consider the class of invariant unbiased quadratic estimators of the function $\mathbf{f}^{\prime} \boldsymbol{\theta}$ in the linear model (1), i.e. the class of the statistics $\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}$, where the matrix $\mathbf{A}$ belongs to the class $\mathscr{A}_{1}$ defined in (8).

Definition 2.1. A minimum norm unbiased invariant quadratic estimator (MIN$\mathbf{Q E}(\mathrm{U}, \mathrm{I}, \mathbf{S})$ ) of the function $\mathbf{f}^{\prime} \boldsymbol{\theta}$ is a statistic $\hat{q}(\mathbf{Y}, \mathbf{V}, \mathbf{S})=\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}$, where the matrix $\mathbf{A}$ minimizes the expression (15) in the class $l_{1}$.

Lemma 2.2. A quadratic estimator $\mathbf{Y}^{\prime} \mathbf{A Y}$ of the function $f^{\prime} \boldsymbol{\theta}$ is the MIN$\mathrm{QE}(\mathrm{U}, \mathrm{I}, \mathbf{S})$ if the matrix $\mathbf{A}$ minimizes the expression

$$
\begin{equation*}
\operatorname{tr} \mathbf{A S A S}-2 \sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{S V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S A} \tag{16}
\end{equation*}
$$

in the class $\ell_{1}$.
Proof. As the matrix $\mathbf{A}$ satisfies the condition $\mathbf{A X}=\mathbf{0}$ the expression (15) is of the following form

$$
\begin{aligned}
&\|\mathbf{H}\|^{2}=\operatorname{tr}\left(\mathbf{S}^{1 / 2} \mathbf{A} \mathbf{S}^{1 / 2}-\mathbf{N}\right)^{2}=\operatorname{tr} \mathbf{S}^{1 / 2} \mathbf{A S A S} \\
&=\operatorname{tr} \mathbf{A S A S}-2 \sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{S} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S} \mathbf{A} \mathbf{S}^{1 / 2} \mathbf{N}+\operatorname{tr} \mathbf{N}^{2}
\end{aligned}
$$

The expression $\operatorname{tr} \mathbf{N}^{2}$ is indenpendent of the matrix $\mathbf{A}$ and hence we have the $\operatorname{MINQE}(\mathbf{U}, \mathbf{I}, \mathbf{S})$ of $\mathbf{f}^{\prime} \boldsymbol{\theta}$ in the form $\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}$, where the matrix $\mathbf{A}$ minimizes the expression (16) in the class $\ell_{1}$.

Theorem 2.3. a) The $\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathbf{S})$ of the function $\mathbf{f}^{\prime} \theta$ is the statistic $\mathbf{Y}^{\prime} \mathbf{A}_{1} \mathbf{Y}$. where

$$
\begin{equation*}
\mathbf{A}_{1}=\sum_{i=1}^{m} \chi_{i} \mathbf{Q}_{s}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{S}-\sum_{i=1}^{m} \gamma_{i} \mathbf{Q}_{s}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{1} \mathbf{Q}_{s} \tag{17}
\end{equation*}
$$

and $\mathbf{Q}_{s}=\mathbf{I}-\mathbf{X}\left(\mathbf{X}^{\prime} \mathbf{S}^{-1} \mathbf{X}\right)^{-} \mathbf{X}^{\prime} \mathbf{S}^{-1}$, the vector $\chi=\left(\chi_{1}, \ldots, \chi_{m}\right)^{\prime}$ is any solution of the linear system (11) and the vector $\gamma=\left(\gamma_{1}, \ldots, \gamma_{m}\right)^{\prime}$ is any solution of the linear system

$$
\begin{equation*}
\sum_{i=1}^{m} \gamma_{i} \operatorname{tr} \mathbf{V}_{i} \mathbf{Q}_{s}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{Q}_{S}=\sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{V}, \mathbf{Q}_{s}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{S}-f_{j} \tag{18}
\end{equation*}
$$

for $j=1,2, \ldots, m$.
b) The $\operatorname{MINQE}(\mathbf{U}, \mathrm{I}, \mathbf{S})$ of the function $\mathbf{f}^{\prime} \boldsymbol{\theta}$ exists if and only if the systems (11) and (18) are consistent.

Proof. It is evident that the matrix $\mathbf{A}_{1}$ is symmetric. The equation $\mathbf{A}_{1} \mathbf{X}=\mathbf{0}$ is satisfied because of $\mathbf{Q}_{\mathbf{S}} \mathbf{X}=\mathbf{0}$. The equations $\operatorname{tr} \mathbf{A}_{1} \mathbf{V}_{i}=\mathbf{f}_{j}$ for $j=1,2, \ldots, m$ are satisfied because the equation (18) holds. It suffices to prove that the matrix $\mathbf{A}_{1}$ minimizes the expression (16) in the class $l_{1}$.

Let $D$ be a matrix for which

$$
\begin{equation*}
\mathbf{D}^{\prime}=\mathbf{D} ; \mathbf{D X}=\mathbf{0} ; \operatorname{tr} \mathbf{D} \mathbf{V}_{i}=\mathbf{0}, \quad i=1,2, \ldots, m \tag{19}
\end{equation*}
$$

holds. The matrix $A_{1}$ minimizes the expression (16) in the class $l_{1}$ if for each matrix $\mathbf{D}$ which satisfies the conditions (19) $\operatorname{tr}\left(\mathbf{A}_{1}+\mathbf{D}\right) \mathbf{S}\left(\mathbf{A}_{1}+\mathbf{D}\right) \mathbf{S}$ $2 \sum_{i=1}^{m} \chi_{1} \operatorname{tr} \mathbf{S} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S}\left(\mathbf{A}_{1}+\mathbf{D}\right) \geqq \operatorname{tr} \mathbf{A}_{1} \mathbf{S} \mathbf{A}_{1} \mathbf{S}-2 \sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{S V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S} \mathbf{A}_{1}$ holds.

$$
\begin{aligned}
& \operatorname{tr}\left(\mathbf{A}_{1}+\mathbf{D}\right) \mathbf{S}\left(\mathbf{A}_{1}+\mathbf{D}\right) \mathbf{S}-2 \sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{S} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S}\left(\mathbf{A}_{1}+\mathbf{D}\right)= \\
& =\operatorname{tr} \mathbf{A}_{1} \mathbf{S} \mathbf{A}_{1} \mathbf{S}-2 \sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{S V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S} \mathbf{A}_{1}+\operatorname{tr} \mathbf{D S D S}+ \\
& \quad+2 \operatorname{tr} \mathbf{A}_{1} \mathbf{S D S}-2 \sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{S} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S D}
\end{aligned}
$$

With regard to the fact that the expression $t r$ DSDS is nonnegative it suffices to prove that $\sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{S V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S D}=\operatorname{tr} \mathbf{A}_{1} \mathbf{S D S}$.

$$
\begin{aligned}
& \operatorname{tr} \mathbf{A}_{1} \mathbf{S D S}=\operatorname{tr}\left(\sum_{i=1}^{m} \chi_{i} \mathbf{Q}_{S}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{S}-\sum_{i=1}^{m} \gamma_{i} \mathbf{Q}_{s}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{Q}_{S}\right) \mathbf{S D S}= \\
& =\sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{S} \mathbf{Q}_{S}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{S} \mathbf{S D}-\sum_{i=1}^{m} \gamma_{i} \operatorname{tr} \mathbf{S} \mathbf{Q}_{S}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{Q}_{S} \mathbf{S D}= \\
& =\sum_{i=1}^{m} \chi_{i} \operatorname{tr}\left(\mathbf{S} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S D}-\mathbf{X}\left(\mathbf{X}^{\prime} \mathbf{S}^{-1} \mathbf{X}\right)^{-} \mathbf{X}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S D}\right)- \\
& -\sum_{i=1}^{m} \gamma_{i} \operatorname{tr}\left(\mathbf{S} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{S D}-\mathbf{X}\left(\mathbf{X}^{\prime} \mathbf{S}^{-1} \mathbf{X}\right)^{-} \mathbf{X}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{S D}\right)= \\
& =\sum_{i=1}^{m} \chi_{i} \operatorname{tr}\left(\mathbf{S} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S D}-\mathbf{D X}\left(\mathbf{X}^{\prime} \mathbf{S}^{-1} \mathbf{X}\right)^{-} \mathbf{X}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S}\right)- \\
& -\sum_{i=1}^{m} \gamma_{i} \operatorname{tr}\left(\mathbf{V}_{i} \mathbf{D}-\mathbf{D X}\left(\mathbf{X}^{\prime} \mathbf{S}^{-1} \mathbf{X}\right)^{-} \mathbf{X}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{i}\right)=\sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{S} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S D} .
\end{aligned}
$$

The proof of statement $b$ ) is clear.
In the next three corollaries we shall be using the notation: $\left(\operatorname{tr} \mathbf{V}_{i} \mathbf{A V} \mathbf{V} \mathbf{B}\right)$ is a matrix of the type $m \times m$, whose ( $j, i$ )-th element is $\operatorname{tr} \mathbf{V}_{i} \mathbf{A} \mathbf{V}_{i} \mathbf{B}$.

Corollary 2.4. One choice of the $\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathbf{S})$ of the function $\mathbf{f}^{\prime} \boldsymbol{\theta}$ is

$$
\begin{equation*}
\mathbf{f}^{\prime}\left(\mathbf{M}^{-} \mathbf{u}-\mathbf{M}^{-} \mathbf{L K} \mathbf{K}^{-} \mathbf{v}+\mathbf{K}^{-} \mathbf{v}\right) \tag{20}
\end{equation*}
$$

where the vectors $\mathbf{u}=\left(\mathbf{Y}^{\prime} \mathbf{Q}_{s}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{\mathbf{1}} \mathbf{V}^{-1} \mathbf{Q}_{\mathbf{S}} \mathbf{Y}, \ldots, \quad \mathbf{Y}^{\prime} \mathbf{Q}_{s}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{m} \mathbf{V}^{-1} \mathbf{Q}_{s} \mathbf{Y}\right)^{\prime} \quad \mathbf{v}=$ $\left(\mathbf{Y}^{\prime} \mathbf{Q}_{s}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{\mathbf{I}} \mathbf{S}^{-1} \mathbf{Q}_{\mathbf{S}} \mathbf{Y}, \ldots, \mathbf{Y}^{\prime} \mathbf{Q}_{s}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{m} \mathbf{S}^{-1} \mathbf{Q}_{S} \mathbf{Y}\right)^{\prime}$ ind the matrices $\mathbf{M}=\left(\operatorname{tr} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1}\right)$, $\mathbf{L}=\left(\operatorname{tr} \mathbf{V}_{i} \mathbf{Q}_{s}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{s}\right)$ ind $\mathbf{K}=\left(\operatorname{tr} \mathbf{V}_{i} \mathbf{Q}_{s}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{Q}_{S}\right)$.

Proof. The $\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathbf{S})$ of the function $\mathbf{f}^{\prime} \theta$ is, according to (17),

$$
\mathbf{Y}^{\prime} \mathbf{A}_{1} \mathbf{Y}=\sum_{i=1}^{m} \chi_{i} \mathbf{Y}^{\prime} \mathbf{Q}_{S}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{S} \mathbf{Y}-\sum_{i=1}^{m} \gamma_{i} \mathbf{Y}^{\prime} \mathbf{Q}_{S}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{Q}_{S} \mathbf{Y}=\chi^{\prime} \mathbf{u}-\gamma^{\prime} \mathbf{v}
$$

For the vectors $\chi$ and $\gamma$ of (11) and (18) we have $\chi^{\prime}=\mathbf{f}^{\prime} \mathbf{M}^{-}$and $\gamma^{\prime}=$ $\mathbf{f}^{\prime}\left(\mathbf{M}^{-} \mathbf{L}-\mathbf{I}\right) \mathbf{K}^{-}$.

$$
\begin{aligned}
\mathbf{Y}^{\prime} \mathbf{A}_{1} \mathbf{Y}= & \chi^{\prime} \mathbf{u}-\gamma^{\prime} \mathbf{v}=\mathbf{f}^{\prime} \mathbf{M}^{-} \mathbf{u}-\mathbf{f}^{\prime}\left(\mathbf{M}^{-} \mathbf{L}-\mathbf{I}\right) \mathbf{K}^{-} \mathbf{v}= \\
& =\mathbf{f}^{\prime}\left(\mathbf{M}^{-} \mathbf{u}-\mathbf{M}^{-} \mathbf{L} \mathbf{K}^{-} \mathbf{v}+\mathbf{K}^{-} \mathbf{v}\right) .
\end{aligned}
$$

Corollary 2.5. One choice of the $\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathbf{S})$ of the vector of unknown variance components $\theta=\left(\theta_{1}, \ldots, \theta_{m}\right)^{\prime}$ is

$$
\begin{equation*}
\hat{\theta}=\mathbf{M}^{-} \mathbf{u}-\mathbf{M}^{-} \mathbf{L} \mathbf{K}^{-} \mathbf{v}+\mathbf{K}^{-} \mathbf{v} . \tag{21}
\end{equation*}
$$

Corollary 2.6. The $\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathbf{S})$ of the function $\mathbf{f}^{\prime} \theta$ exists if and only if $\mathbf{f} \in \mathscr{R}(\mathbf{M})$ and $\left(\mathbf{L M}^{-}-\mathbf{I}\right) \mathbf{f} \in \mathscr{R}\left(\mathbf{K}^{\prime}\right)$, where $\mathscr{R}(\mathbf{N})$ denotes the range of the matrix $\mathbf{N}$.

The estimations MINQE(U, I, S) obtained in this paper ((17)) and MINQE(U, I) obtained by Rao, discused in Lemma 1.2, are unbiased invariant quadratic estimations of the function $f^{\prime} \theta$. We shall compare both these results from the standpoint of their variance. Here, the following two possibilities are interesting. The first, $\mathbf{S}=\mathbf{V}$, it means that the matrix $\mathbf{S}$ does not contribute to an estimated situation by a new information; then the $\operatorname{MINQE}(\mathbf{U}, \mathrm{I}, \mathbf{S})$ and the $\operatorname{MINQE}(\mathrm{U}, \mathrm{I})$ are the same (Theorem 2.7). The second, $\mathbf{S}=\mathbf{V}_{\boldsymbol{A}}$, the information obtained from the matrix $\mathbf{S}$ is precise; then $D_{\theta}(\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathbf{S})) \leqq D_{\theta}(\operatorname{MINQE}(\mathrm{U}, \mathrm{I}))$ (Theorem 2.8).

Theorem 2.7. If $\mathbf{S}=\mathbf{V}$, then the $\operatorname{MINQE}(\mathbf{U}, \mathbf{I}, \mathbf{S})$ of the function $\mathbf{f}^{\prime} \theta$ is equal to the $\operatorname{MINQE}(\mathrm{U}, \mathrm{I})$.

Proof. If $\mathbf{S}=\mathbf{V}$, then $\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathbf{S})$ of the function $\mathbf{f}^{\prime} \theta(17)$ is

$$
\begin{equation*}
\hat{q}=\sum_{i=1}^{m}\left(\chi_{i}-\gamma_{t}\right) \mathbf{Y}^{\prime} \mathbf{Q}_{V}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{V} \mathbf{Y} \tag{22}
\end{equation*}
$$

where $\mathbf{Q}_{V}=\mathbf{I}-\mathbf{X}\left(\mathbf{X}^{\prime} \mathbf{V}^{-1} \mathbf{X}\right)^{-} \mathbf{X}^{\prime} \mathbf{V}^{-1}$ ind the vector $\left(\chi_{1}-\gamma_{1}, \ldots, \chi_{m}-\gamma_{m}\right)^{\prime}$ is any solution of the linear system

$$
\begin{equation*}
\sum_{i=1}^{m}\left(\chi_{i}-\gamma_{i}\right) \operatorname{tr} \mathbf{V}_{i} \mathbf{Q}_{v}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{v}=f_{j} \tag{23}
\end{equation*}
$$

Denoting $\left(\chi_{i}-\gamma_{i}\right)=\delta_{t}$ in (22), (23) we obtain the $\operatorname{MINQE}(\mathrm{U}, \mathrm{I})$ defined in Lemma 1.2.

Theorem 2.8. Let the realization vector $\mathbf{Y}$ have a normal distribution $N_{n}\left(\mathbf{X} \beta, \mathbf{V}_{\boldsymbol{\theta}}\right)$, let $\mathbf{S}=\mathbf{V}_{\boldsymbol{\theta}}$ and let the expressions $\operatorname{tr} \mathbf{V}_{\mathrm{A}} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{V}_{\theta} \mathbf{A}$ be indenpendent of the matrix $\mathbf{A}(i=1, \ldots, m)$. Then the $\operatorname{MINQE}(\mathbf{U}, \mathbf{I}, \mathbf{S})$ of the function $f^{\prime} \theta$ has a minimum variance in the class $a_{1}$ for such $\theta \in \mathcal{O}$ that $\mathbf{V}_{\boldsymbol{\theta}}=\mathbf{S}$ is valid.

Proof. If $\mathbf{S}=\mathbf{V}_{\boldsymbol{A}}$, then according to Lemma 2.2 we have that the MIN$\mathrm{QE}(\mathrm{U}, \mathbf{I}, \mathbf{S})$ is a statistic $\mathbf{Y}^{\prime} \mathbf{A}_{1} \mathbf{Y}$, where $\mathbf{A}_{1}$ minimizes the expression $\operatorname{tr} \mathbf{A} \mathbf{V}_{\mathbf{A}} \mathbf{A} \mathbf{V}_{\boldsymbol{\theta}}$ $2 \sum_{i=1}^{m} \chi_{i} \operatorname{tr} \mathbf{V}_{\mathbf{A}} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{V}_{\mathrm{A}} \mathbf{A}$. With respect to the assumptions $\operatorname{tr} \mathbf{V}_{\mathbf{A}} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{V}_{\mathrm{A}} \mathbf{A}$ ire indenpendent of the matrix $\mathbf{A}$, the matrix $\mathbf{A}_{1}$ in the estimator $\mathbf{Y}^{\prime} \mathbf{A}_{1} \mathbf{Y}$ minimizes the expression $\operatorname{tr} \mathbf{A} \mathbf{V}_{\theta} \mathbf{A} \mathbf{V}_{\theta}$ in the class $\mathscr{A}_{1}$. Since $D_{\theta}\left(\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}\right)=2 \operatorname{tr} \mathbf{A V}_{\theta} \mathbf{A} \mathbf{V}_{\theta}$ (Lemma 1.3), the theorem is proved.

Corollary 2.9. If the assumptions of the theorem 2.8 are satisfied, then

$$
\begin{equation*}
D_{\theta}(\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathbf{S})) \leqq D_{\ominus}(\operatorname{MINQE}(\mathrm{U}, \mathrm{I})) \tag{24}
\end{equation*}
$$

Proof is obvious.

Example.
Let $\mathbf{Y}=\mathbf{X} \beta+\mathbf{e}$, where $\mathbf{X}=(1,1,1)^{\prime}$ and

$$
\begin{gathered}
D(\mathbf{Y})=D(\mathrm{e})=\left(\begin{array}{ccc}
\theta_{1} & \theta_{2}-\theta_{1} & 0 \\
\theta_{2}-\theta_{1} & \theta_{1} & 0 \\
0 & 0 & \theta_{2}
\end{array}\right)= \\
=\theta_{1}\left(\begin{array}{rrr}
1-1 & 0 \\
-1 & 1 & 0 \\
0 & 0 & 0
\end{array}\right)+\theta_{2}\left(\begin{array}{lll}
0 & 1 & 0 \\
1 & 0 & 0 \\
0 & 0 & 1
\end{array}\right)=\theta_{1} \mathbf{V}_{1}+\theta_{2} \mathbf{V}_{2}=\mathbf{V}_{\theta} .
\end{gathered}
$$

Let $\alpha_{1}=\alpha_{2}=1$, i.e. $\mathbf{V}=\mathbf{V}_{1}+\mathbf{V}_{2}=\mathbf{I}$ and let the matrix $\mathbf{S}$ contains prior values of elements of the matrix $\mathbf{V}_{\mathbf{g}}$.
We wish to find the $\operatorname{MINQE}(\mathrm{U}, \mathrm{I})$ and the $\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathrm{S})$ of the function $\mathbf{f}^{\prime} \theta=f_{1} \theta_{1}+f_{2} \theta_{2}$.
The matrix $\mathbf{A}$ of the the estimator $\mathbf{Y}^{\prime} \mathbf{A} \mathbf{Y}$ is an element of the class $x_{1}$ and therefore

$$
\mathbf{A}=\frac{1}{6}\left(\begin{array}{ccc}
f_{1}-f_{2}-6 a & -f_{1}+f_{2} & 6 a \\
-f_{1}+f_{2} & 3 f_{1}+3 f_{2}+6 a & -2 f_{1}-4 f_{2}-6 a \\
6 a & -2 f_{1}-4 f_{2}-6 a & 2 f_{1}+4 f_{2}
\end{array}\right)
$$

where $a \in(-\infty, \infty)$.
If we estimate $\theta_{1}+\theta_{2}\left(f_{1}=f_{2}=1\right)$, then

$$
\mathbf{A}=\left(\begin{array}{ccc}
-a & 0 & a \\
0 & 1+a & -1-a \\
a & -1-a & 1
\end{array}\right) .
$$

where $a \in(-\infty, \infty)$.
The $\operatorname{MINQE}(\mathrm{U}, \mathrm{I})$ of the function $\boldsymbol{\theta}_{1}+\boldsymbol{\theta}_{\mathbf{2}}$ is the estimator $\mathbf{Y}^{\prime} \mathbf{A Y}$. where we assing the parameter $a$ of the matrix $\mathbf{A}$ additionally in such a way that

$$
\operatorname{tr} \mathrm{AVAV}=6 a^{2}+6 a+4=\min .
$$

The expressions $\operatorname{tr}_{\mathbf{V}}^{\mathbf{A}} \mathbf{V}^{-1} \mathbf{V}_{\mathbf{i}} \mathbf{V}^{-1} \mathbf{V}_{\mathbf{A}} \mathbf{A}(i=1,2)$ are indenpendent of the matrix $\mathbf{A}$ (They are indenpendent of the parameter $a$ ) because $\operatorname{tr}_{\mathbf{V}} \mathbf{V}^{-1} \mathbf{V}_{1} \mathbf{V}^{-1} \mathbf{V}_{A} \mathbf{A}=$ $2\left(\theta_{1}-\theta_{2}\right)^{2} f_{1}$ and $\operatorname{tr} \mathbf{V}_{\mathbf{A}} \mathbf{V}^{-1} \mathbf{V}_{2} \mathbf{V}^{-1} \mathbf{V}_{A} \mathbf{A}=2\left(\theta_{1} \theta_{2}-\theta_{1}^{2}\right) f_{1}+\theta_{2}^{2} f_{2}$. If $\mathbf{S}=\mathbf{V}_{\boldsymbol{\theta}}$ holds too, then the $\operatorname{MINQE}(\mathbf{U}, \mathbf{I}, \mathbf{S})$ of the function $\theta_{1}+\theta_{2}$ is the estimator $\mathbf{Y}^{\prime} \mathbf{A Y}$. where we assign the parameter $a$ of the matrix $\mathbf{A}$ additionally in such a way that

$$
\operatorname{tr} \mathrm{AV}_{\mathrm{A}} \mathbf{A V _ { \theta } = ( \theta _ { 1 } + \theta _ { 2 } ) ^ { 2 } - 6 ( \theta _ { 2 } ^ { 2 } - 2 \theta _ { 1 } \theta _ { 2 } ) a - 6 ( \theta _ { 2 } ^ { 2 } - 2 \theta _ { 1 } \theta _ { 2 } ) a ^ { 2 } = \operatorname { m i n } . . . ~}
$$

Since $D_{\theta}\left(Y^{\prime} \mathbf{A Y}\right)=2 \operatorname{tr} \mathbf{A V} \mathbf{V}_{\mathrm{A}} \mathbf{A} \mathbf{V}_{\mathrm{A}}$. it is obvious that the $\operatorname{MINQE}(\mathbf{U}, \mathbf{I}, \mathbf{S})$ of the function $\theta_{1}+\theta_{2}$ is an estimator with minimal variance in the class $\%_{1}$.

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## НЕСМЕЩЕННАЯ КВАДРАТИЧЕСКАЯ ОЦЕНКА ВАРИАЦИОННЫХ КОМПОНЕНТОВ С МИНИМАЛЬНОЙ ДИСПЕРСИЕЙ

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Резюме

На основе реализации матрицы $\mathbf{S}$, которая является оценкои ковариационной матрицы $\mathbf{V}_{\boldsymbol{\Theta}}=\Theta_{1} \mathbf{V}_{1}+\ldots+\Theta_{m} \mathbf{V}_{m}$ случайного вектора $\mathbf{Y}$, получается оценка $\operatorname{MINQE}(\mathrm{U}, \mathrm{I}, \mathbf{S})$ линейной функции $f_{1}+\ldots+f_{m} \Theta_{m}$ в форме $\mathbf{Y}^{\prime} \mathbf{A ( S )} \mathbf{Y}^{\prime}$. Показанд сигуация, когда $\operatorname{MINOE}(\mathrm{U}, \mathrm{I}, \mathrm{S})$ имест минимальную дисперсию.

