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MINIMUM VARIANCE QUADRATIC UNBIASED ESTIMATION OF VARIANCE COMPONENTS

ŠTEFAN VARGA

Introduction

Let us consider the linear model

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{e} \,, \tag{1}$$

where **X** is a given $n \times p$ -matrix, β an unknown p-vector of parameters and **e** a random n-vector with expectation zero and covariance matrix

$$D(\mathbf{e}) = D(\mathbf{Y}) = \theta_1 \mathbf{V}_1 + \dots + \theta_m \mathbf{V}_m = \mathbf{V}_{\theta}. \tag{2}$$

The matrices V_i (i = 1, 2, ..., m) are known symmetric $n \times n$ -matrices. We are interested in the estimation of the unknown parameter vector $\theta = (\theta_1, ..., \theta_m)$ belonging to the set \mathcal{O} of all $\theta \in \mathcal{R}^m$ such that V_{θ} becomes positive definite (p, d_n) .

Assume that the matrix **S** containing prior values of elements of the covariance matrix \mathbf{V}_{θ} is known (the (i, j)-th element of the matrix **S** is a prior value of the (i, j)-th element of the matrix \mathbf{V}_{θ} for i, j = 1, 2, ..., n).

A quadratic estimation of the linear function

$$q = \sum_{i=1}^{m} f_i \theta_i = \mathbf{f}' \theta \tag{3}$$

of θ will be considered in the form

$$\hat{q}(\mathbf{Y}, \mathbf{V}, \mathbf{S}) = \mathbf{Y}' \mathbf{A}(\mathbf{V}, \mathbf{S}) \mathbf{Y}, \tag{4}$$

where the matrix V is defined by

$$\mathbf{V} = \left\langle \begin{array}{cc} \mathbf{V}_1 + \dots + \mathbf{V}_m \\ \alpha_1 \mathbf{V}_1 + \dots + \alpha_m \mathbf{V}_m \end{array} \right. \tag{5}$$

in dependence on whether a prior value $\alpha = (\alpha_1, ..., \alpha_m)'$ of $\theta = (\theta, ..., \theta)'$ is unknown (first row) or known (second row).

A natural question is how the knowledge of the matrix **S** contributes to estimating the variance components $\theta_1, ..., \theta_m$ and the function (3).

1. Symbols and auxiliary statements

Let $(4, \langle .,. \rangle)$ be a Hilbert space of symetric $n \times n$ matrices, $\langle .,. \rangle$ denotes the inner product given by $\langle \mathbf{A}, \mathbf{B} \rangle = tr \ \mathbf{AB}, \mathbf{A}, \mathbf{B} \in \mathcal{A}$; here $tr \ \mathbf{C}$ denotes the trace of the matrix \mathbf{C} . The matrix \mathbf{A} in (4) is from \mathcal{A} .

The natural estimator of the function (3) in the linear model (1) is defined by the formula

$$\mathbf{e}_{*}' \sum_{i=1}^{m} \lambda_{i} \, \mathbf{V}^{-1/2} \, \mathbf{V}_{i} \, \mathbf{V}^{-1/2} \, \mathbf{e}_{*} \tag{6}$$

(see (5.4.3) in [4]), where $\mathbf{e} *= \mathbf{V}^{-1/2} \mathbf{e}$ and the vector $\lambda = (\lambda_1, ..., \lambda_m)'$ is any solution of the linear system

$$\mathbf{M}\lambda = \mathbf{f}.\tag{7}$$

The (i, j)-th element of the matrix \mathbf{M} is $\{\mathbf{M}\}_{i,j} = tr \ \mathbf{V}^{-1} \mathbf{V}_i \ \mathbf{V}^{-1} \mathbf{V}_j$ and $\mathbf{f} = (f_1, ..., f_m)'$. **Definition 1.1.** ([2]) A minimum norm invariant unbiased quadratic estimator (MINQUE(U, I)) of the function $\mathbf{f}'\theta$ is a statistic $\mathbf{Y}'\mathbf{A}\mathbf{Y}$, where the matrix \mathbf{A} minimizes the expression $tr \ \mathbf{A}\mathbf{V}\mathbf{A}\mathbf{V}$ in the class \mathcal{A}_1 .

$$\mathcal{I}_1 = \{ \mathbf{A} \in \mathcal{A} : \mathbf{AX} = \mathbf{0} ; tr \ \mathbf{AV}_i = \mathbf{f}_i, \ i = 1, 2, ..., m \}$$
 (8)

Lemma 1.2. The MINQUE(U, I) of the function $\mathbf{f}'\theta$ is the statistic $\mathbf{Y}'\mathbf{A}\mathbf{Y}$, where $\mathbf{A} = \sum_{i=1}^{m} \delta_i \ \mathbf{Q}_V' \ \mathbf{V}^{-1}\mathbf{V}_i \ \mathbf{V}^{-1}\mathbf{Q}_V$, the expression $\mathbf{Q}_V = \mathbf{I} - \mathbf{X}(\mathbf{X}'\mathbf{V}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{V}^{-1}$ and the vector $\mathbf{\delta} = (\delta_1, ..., \delta_m)'$ is any solution of the linear system $\mathbf{B}\mathbf{\delta} = \mathbf{f}$. The (i, j)-th element of the matrix \mathbf{B} is $tr \ \mathbf{V}_j \mathbf{Q}_V \mathbf{V}^{-1} \mathbf{V}_i \mathbf{V}^{-1} \mathbf{Q}_V$. I is a unite matrix.

Proof. See [4], Theorem 5.1.1 and Note 2.

Lemma 1.3. If $\mathbf{Y} \sim N_n(\mathbf{X}\boldsymbol{\beta}, \sum_{i=1}^m \theta_i \mathbf{V}_i)$ and $\mathbf{A} \in \mathcal{A}_1$, then for the variance of the random variable $\mathbf{Y}'\mathbf{A}\mathbf{Y}$ the following holds

$$D_{\theta}(\mathbf{Y}'\mathbf{A}\mathbf{Y}) = 2 tr \mathbf{A}\mathbf{V}_{\theta}\mathbf{A}\mathbf{V}_{\theta}. \tag{9}$$

Proof. See [1], Theorem 1.

2. Natural estimation and S-estimation

Using the transformation $\mathbf{e} = \mathbf{S}^{1/2} \mathbf{\epsilon}$ ($\mathbf{\epsilon} = \mathbf{S}^{-1/2} \mathbf{e}$) in the linear model (1), the natural estimator (6) of $\mathbf{f}'\theta$ is

$$\varepsilon' \mathbf{N} \varepsilon = \varepsilon' \sum_{i=1}^{m} \chi_i \mathbf{S}^{1/2} \mathbf{V}^{-1} \mathbf{V}_i \mathbf{V}^{-1} \mathbf{S}^{1/2} \varepsilon, \qquad (10)$$

where the vector $\chi = (\chi_1, ..., \chi_m)'$ is any solution of the linear system

$$\mathbf{M}\mathbf{X} = \mathbf{f}.\tag{11}$$

The matrix \mathbf{M} is defined in (7).

The considered quadratic estimator (4) with respect to the transformation $\mathbf{e} = \mathbf{S}^{1/2} \mathbf{\epsilon}$ is

$$\hat{q}(\mathbf{Y}, \mathbf{V}, \mathbf{S}) = \mathbf{Y}' \mathbf{A} \mathbf{Y} = (\mathbf{X} \boldsymbol{\beta} + \mathbf{S}^{1/2} \boldsymbol{\epsilon})' \mathbf{A} (\mathbf{X} \boldsymbol{\beta} + \mathbf{S}^{1/2} \boldsymbol{\epsilon}) =$$

$$= (\boldsymbol{\epsilon}', \boldsymbol{\beta}') \begin{pmatrix} \mathbf{S}^{1/2} \mathbf{A} \mathbf{S}^{1/2} & \mathbf{S}^{1/2} \mathbf{A} \mathbf{X} \\ \mathbf{X}' \mathbf{A} \mathbf{S}^{1/2} & \mathbf{X}' \mathbf{A} \mathbf{X} \end{pmatrix} \begin{pmatrix} \boldsymbol{\epsilon} \\ \boldsymbol{\beta} \end{pmatrix}. \tag{12}$$

The difference between the considered estimator (12) and the natural estimator (10) of the function $\mathbf{f}'\theta$ is

$$\mathbf{Y}'\mathbf{A}\mathbf{Y} - \varepsilon'\mathbf{N}\varepsilon = (\varepsilon', \beta') \begin{pmatrix} \mathbf{S}^{1/2}\mathbf{A}\mathbf{S}^{1/2} - \mathbf{N} & \mathbf{S}^{1/2}\mathbf{A}\mathbf{X} \\ \mathbf{X}'\mathbf{A}\mathbf{S}^{1/2} & \mathbf{X}'\mathbf{A}\mathbf{X} \end{pmatrix} \begin{pmatrix} \varepsilon \\ \beta \end{pmatrix}$$
(13)

The minimum norm quadratic estimation which is a function of the matrix **S** (MINQE (**S**)) is obtained by minimizing the Euclidean norm of the matrix **H** of the quadratic form (13) defined as follows

$$\mathbf{H} = \begin{pmatrix} \mathbf{S}^{1/2} \mathbf{A} \mathbf{S}^{1/2} - \mathbf{N} & \mathbf{S}^{1/2} \mathbf{A} \mathbf{X} \\ \mathbf{X}' \mathbf{A} \mathbf{S}^{1/2} & \mathbf{X}' \mathbf{A} \mathbf{X} \end{pmatrix}$$
(14)

The square of the Euclidean norm of **H** is

$$\|\mathbf{H}\|^2 = tr (\mathbf{S}^{1/2}\mathbf{A}\mathbf{S}^{1/2} - \mathbf{N})^2 + 2tr \mathbf{X}'\mathbf{A}\mathbf{S}\mathbf{A}\mathbf{X} + tr (\mathbf{X}'\mathbf{A}\mathbf{X})^2.$$
 (15)

We consider the class of invariant unbiased quadratic estimators of the function $\mathbf{f}'\theta$ in the linear model (1), i.e. the class of the statistics $\mathbf{Y}'\mathbf{A}\mathbf{Y}$, where the matrix \mathbf{A} belongs to the class \mathcal{A}_1 defined in (8).

Definition 2.1. A minimum norm unbiased invariant quadratic estimator (MIN-QE(U, I, S)) of the function $\mathbf{f}'\theta$ is a statistic $\hat{q}(\mathbf{Y}, \mathbf{V}, \mathbf{S}) = \mathbf{Y}'\mathbf{A}\mathbf{Y}$, where the matrix \mathbf{A} minimizes the expression (15) in the class \mathcal{A}_1 .

Lemma 2.2. A quadratic estimator Y'AY of the function $f'\theta$ is the MIN-QE(U, I, S) if the matrix A minimizes the expression

$$tr \mathbf{ASAS} - 2\sum_{i=1}^{m} \chi_i tr \mathbf{SV}^{-1} \mathbf{V}_i \mathbf{V}^{-1} \mathbf{SA}$$
 (16)

in the class \mathcal{A}_1 .

Proof. As the matrix **A** satisfies the condition AX = 0 the expression (15) is of the following form

$$\|\mathbf{H}\|^{2} = tr (\mathbf{S}^{1/2}\mathbf{A}\mathbf{S}^{1/2} - \mathbf{N})^{2} = tr \mathbf{S}^{1/2}\mathbf{A}\mathbf{S}\mathbf{A}\mathbf{S}^{1/2} - 2tr \mathbf{S}^{1/2}\mathbf{A}\mathbf{S}^{1/2}\mathbf{N} + tr \mathbf{N}^{2} = tr \mathbf{A}\mathbf{S}\mathbf{A}\mathbf{S} - 2\sum_{i=1}^{m} \chi_{i}tr \mathbf{S}\mathbf{V}^{-1}\mathbf{V}_{i}\mathbf{V}^{-1}\mathbf{S}\mathbf{A} + tr \mathbf{N}^{2}.$$

The expression $tr \ N^2$ is independent of the matrix **A** and hence we have the MINQE(U, I, S) of $f' \theta$ in the form Y'AY, where the matrix **A** minimizes the expression (16) in the class \mathcal{A}_1 .

Theorem 2.3. a) The MINQE(U, I, S) of the function $f'\theta$ is the statistic $Y'A_1Y$, where

$$\mathbf{A}_{1} = \sum_{i=1}^{m} \chi_{i} \mathbf{Q}_{S}^{\prime} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{S} - \sum_{i=1}^{m} \gamma_{i} \mathbf{Q}_{S}^{\prime} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{Q}_{S}$$
(17)

and $\mathbf{Q}_s = \mathbf{I} - \mathbf{X}(\mathbf{X}'\mathbf{S}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{S}^{-1}$, the vector $\mathbf{\chi} = (\chi_1, ..., \chi_m)'$ is any solution of the linear system (11) and the vector $\mathbf{\gamma} = (\gamma_1, ..., \gamma_m)'$ is any solution of the linear system

$$\sum_{i=1}^{m} \gamma_i \operatorname{tr} \mathbf{V}_j \mathbf{Q}_S' \mathbf{S}^{-1} \mathbf{V}_i \mathbf{S}^{-1} \mathbf{Q}_S = \sum_{i=1}^{m} \chi_i \operatorname{tr} \mathbf{V}_j \mathbf{Q}_S' \mathbf{V}^{-1} \mathbf{V}_i \mathbf{V}^{-1} \mathbf{Q}_S - f_j$$
 (18)

for j = 1, 2, ..., m.

b) The MINQE(U, I, S) of the function $f'\theta$ exists if and only if the systems (11) and (18) are consistent.

Proof. It is evident that the matrix \mathbf{A}_1 is symmetric. The equation $\mathbf{A}_1\mathbf{X} = \mathbf{0}$ is satisfied because of $\mathbf{Q}_S\mathbf{X} = \mathbf{0}$. The equations $tr \ \mathbf{A}_1\mathbf{V}_j = \mathbf{f}_j$ for j = 1, 2, ..., m are satisfied because the equation (18) holds. It suffices to prove that the matrix \mathbf{A}_1 minimizes the expression (16) in the class \mathcal{A}_1 .

Let **D** be a matrix for which

$$D' = D; DX = 0; tr DV_i = 0, i = 1, 2, ..., m$$
 (19)

holds. The matrix \mathbf{A}_1 minimizes the expression (16) in the class l_1 if for each matrix \mathbf{D} which satisfies the conditions (19) $tr(\mathbf{A}_1 + \mathbf{D})\mathbf{S}(\mathbf{A}_1 + \mathbf{D})\mathbf{S} - 2\sum_{i=1}^{m} \chi_i tr \mathbf{S}\mathbf{V}^{-1}\mathbf{V}_i\mathbf{V}^{-1}\mathbf{S}(\mathbf{A}_1 + \mathbf{D}) \ge tr \mathbf{A}_1\mathbf{S}\mathbf{A}_1\mathbf{S} - 2\sum_{i=1}^{m} \chi_i tr \mathbf{S}\mathbf{V}^{-1}\mathbf{V}_i\mathbf{V}^{-1}\mathbf{S}\mathbf{A}_1$ holds.

$$tr (\mathbf{A}_1 + \mathbf{D})\mathbf{S}(\mathbf{A}_1 + \mathbf{D})\mathbf{S} - 2\sum_{i=1}^{m} \chi_i tr \mathbf{S}\mathbf{V}^{-1}\mathbf{V}_i\mathbf{V}^{-1}\mathbf{S}(\mathbf{A}_1 + \mathbf{D}) =$$

$$= tr \mathbf{A}_1\mathbf{S}\mathbf{A}_1\mathbf{S} - 2\sum_{i=1}^{m} \chi_i tr \mathbf{S}\mathbf{V}^{-1}\mathbf{V}_i\mathbf{V}^{-1}\mathbf{S}\mathbf{A}_1 + tr \mathbf{D}\mathbf{S}\mathbf{D}\mathbf{S} +$$

$$+ 2 tr \mathbf{A}_1\mathbf{S}\mathbf{D}\mathbf{S} - 2\sum_{i=1}^{m} \chi_i tr \mathbf{S}\mathbf{V}^{-1}\mathbf{V}_i\mathbf{V}^{-1}\mathbf{S}\mathbf{D}.$$

With regard to the fact that the expression tr **DSDS** is nonnegative it suffices to prove that $\sum_{i=1}^{m} \chi_i tr \mathbf{SV}^{-1} \mathbf{V}_i \mathbf{V}^{-1} \mathbf{SD} = tr \mathbf{A}_1 \mathbf{SDS}$.

$$tr \ \mathbf{A}_{1} \mathbf{SDS} = tr \left(\sum_{i=1}^{m} \chi_{i} \mathbf{Q}_{S}^{i} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{S} - \sum_{i=1}^{m} \gamma_{i} \mathbf{Q}_{S}^{i} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{Q}_{S} \right) \mathbf{SDS} =$$

$$= \sum_{i=1}^{m} \chi_{i} \ tr \ \mathbf{SQ}_{S}^{i} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{Q}_{S} \mathbf{SD} - \sum_{i=1}^{m} \gamma_{i} \ tr \ \mathbf{SQ}_{S}^{i} \mathbf{S}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{Q}_{S} \mathbf{SD} =$$

$$= \sum_{i=1}^{m} \chi_{i} \ tr \ (\mathbf{SV}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{SD} - \mathbf{X} (\mathbf{X}^{i} \mathbf{S}^{-1} \mathbf{X})^{-} \mathbf{X}^{i} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{SD}) -$$

$$- \sum_{i=1}^{m} \gamma_{i} \ tr \ (\mathbf{SS}^{-1} \mathbf{V}_{i} \mathbf{S}^{-1} \mathbf{SD} - \mathbf{X} (\mathbf{X}^{i} \mathbf{S}^{-1} \mathbf{X})^{-} \mathbf{X}^{i} \mathbf{Y}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{SD}) =$$

$$= \sum_{i=1}^{m} \chi_{i} \ tr \ (\mathbf{SV}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{SD} - \mathbf{DX} (\mathbf{X}^{i} \mathbf{S}^{-1} \mathbf{X})^{-} \mathbf{X}^{i} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{S}) -$$

$$- \sum_{i=1}^{m} \gamma_{i} \ tr \ (\mathbf{V}_{i} \mathbf{D} - \mathbf{DX} (\mathbf{X}^{i} \mathbf{S}^{-1} \mathbf{X})^{-} \mathbf{X}^{i} \mathbf{S}^{-1} \mathbf{V}_{i}) = \sum_{i=1}^{m} \chi_{i} \ tr \ \mathbf{SV}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{SD}.$$

The proof of statement b) is clear.

In the next three corollaries we shall be using the notation: $(tr \, \mathbf{V}_i \mathbf{A} \mathbf{V}_i \mathbf{B})$ is a matrix of the type $m \times m$, whose (j, i)-th element is $tr \, \mathbf{V}_i \mathbf{A} \mathbf{V}_i \mathbf{B}$.

Corollary 2.4. One choice of the MINQE(U, I, S) of the function $f'\theta$ is

$$f'(\mathbf{M}^{-}\mathbf{u} - \mathbf{M}^{-}\mathbf{L}\mathbf{K}^{-}\mathbf{v} + \mathbf{K}^{-}\mathbf{v}), \tag{20}$$

where the vectors $\mathbf{u} = (\mathbf{Y}'\mathbf{Q}_S'\mathbf{V}^{-1}\mathbf{V}_1\mathbf{V}^{-1}\mathbf{Q}_S\mathbf{Y}, ..., \mathbf{Y}'\mathbf{Q}_S'\mathbf{V}^{-1}\mathbf{V}_m\mathbf{V}^{-1}\mathbf{Q}_S\mathbf{Y})'$ $\mathbf{v} = (\mathbf{Y}'\mathbf{Q}_S'\mathbf{S}^{-1}\mathbf{V}_1\mathbf{S}^{-1}\mathbf{Q}_S\mathbf{Y}, ..., \mathbf{Y}'\mathbf{Q}_S'\mathbf{S}^{-1}\mathbf{V}_m\mathbf{S}^{-1}\mathbf{Q}_S\mathbf{Y})'$ and the matrices $\mathbf{M} = (tr\ \mathbf{V}_i\mathbf{V}^{-1}\mathbf{V}_i\mathbf{V}^{-1}),$ $\mathbf{L} = (tr\ \mathbf{V}_i\mathbf{Q}_S'\mathbf{V}^{-1}\mathbf{V}_i\mathbf{V}^{-1}\mathbf{Q}_S)$ and $\mathbf{K} = (tr\ \mathbf{V}_i\mathbf{Q}_S'\mathbf{S}^{-1}\mathbf{V}_i\mathbf{S}^{-1}\mathbf{Q}_S).$

Proof. The MINQE(U, I, S) of the function $f'\theta$ is, according to (17),

$$\mathbf{Y}'\mathbf{A}_1\mathbf{Y} = \sum_{i=1}^m \chi_i \mathbf{Y}'\mathbf{Q}_S'\mathbf{V}^{-1}\mathbf{V}_i\mathbf{V}^{-1}\mathbf{Q}_S\mathbf{Y} - \sum_{i=1}^m \gamma_i \mathbf{Y}'\mathbf{Q}_S'\mathbf{S}^{-1}\mathbf{V}_i\mathbf{S}^{-1}\mathbf{Q}_S\mathbf{Y} = \chi'\mathbf{u} - \gamma'\mathbf{v}.$$

For the vectors χ and γ of (11) and (18) we have $\chi' = \mathbf{f}'\mathbf{M}^-$ and $\gamma' = \mathbf{f}'(\mathbf{M}^-\mathbf{L} - \mathbf{I})\mathbf{K}^-$.

$$Y'A_1Y = \chi'u - \gamma'v = f'M^-u - f'(M^-L - I)K^-v =$$

= $f'(M^-u - M^-LK^-v + K^-v)$.

Corollary 2.5. One choice of the MINQE(U, I, S) of the vector of unknown variance components $\theta = (\theta_1, ..., \theta_m)'$ is

$$\hat{\boldsymbol{\theta}} = \mathbf{M}^{-}\mathbf{u} - \mathbf{M}^{-}\mathbf{L}\mathbf{K}^{-}\mathbf{v} + \mathbf{K}^{-}\mathbf{v}. \tag{21}$$

Corollary 2.6. The MINQE(U, I, S) of the function $\mathbf{f}'\theta$ exists if and only if $\mathbf{f} \in \mathcal{R}(\mathbf{M})$ and $(\mathbf{L}\mathbf{M}^- - \mathbf{I})\mathbf{f} \in \mathcal{R}(\mathbf{K}')$, where $\mathcal{R}(\mathbf{N})$ denotes the range of the matrix N.

The estimations MINQE(U, I, S) obtained in this paper ((17)) and MINQE(U, I) obtained by Rao, discused in Lemma 1.2, are unbiased invariant quadratic estimations of the function $\mathbf{f}'\theta$. We shall compare both these results from the standpoint of their variance. Here, the following two possibilities are interesting. The first, $\mathbf{S} = \mathbf{V}$, it means that the matrix S does not contribute to an estimated situation by a new information; then the MINQE(U, I, S) and the MINQE(U, I) are the same (Theorem 2.7). The second, $\mathbf{S} = \mathbf{V}_{\theta}$, the information obtained from the matrix S is precise; then $D_{\theta}(\text{MINQE}(U, I, \mathbf{S})) \leq D_{\theta}(\text{MINQE}(U, I))$ (Theorem 2.8).

Theorem 2.7. If S = V, then the MINQE(U, I, S) of the function $f'\theta$ is equal to the MINQE(U, I).

Proof. If S = V, then MINQE(U, I, S) of the function $f'\theta$ (17) is

$$\hat{q} = \sum_{i=1}^{m} (\chi_i - \gamma_i) \mathbf{Y}' \mathbf{Q}_V' \mathbf{V}^{-1} \mathbf{V}_i \mathbf{V}^{-1} \mathbf{Q}_V \mathbf{Y},$$
(22)

where $\mathbf{Q}_V = \mathbf{I} - \mathbf{X}(\mathbf{X}'\mathbf{V}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{V}^{-1}$ and the vector $(\chi_1 - \gamma_1, ..., \chi_m - \gamma_m)'$ is any solution of the linear system

$$\sum_{i=1}^{m} (\chi_i - \gamma_i) \operatorname{tr} \mathbf{V}_j \mathbf{Q}_V' \mathbf{V}^{-1} \mathbf{V}_i \mathbf{V}^{-1} \mathbf{Q}_V = f_j.$$
 (23)

Denoting $(\chi_i - \gamma_i) = \delta_i$ in (22), (23) we obtain the MINQE(U, I) defined in Lemma 1.2.

Theorem 2.8. Let the realization vector \mathbf{Y} have a normal distribution $N_n(\mathbf{X}\boldsymbol{\beta}, \mathbf{V}_{\theta})$, let $\mathbf{S} = \mathbf{V}_{\theta}$ and let the expressions $tr \ \mathbf{V}_{\theta} \mathbf{V}^{-1} \mathbf{V}_{i} \mathbf{V}^{-1} \mathbf{V}_{\theta} \mathbf{A}$ be independent of the matrix \mathbf{A} (i=1, ..., m). Then the MINQE(U, I, S) of the function $\mathbf{f}'\mathbf{\theta}$ has a minimum variance in the class \mathcal{A}_1 for such $\mathbf{\theta} \in \mathbb{O}$ that $\mathbf{V}_{\theta} = \mathbf{S}$ is valid.

Proof. If $\mathbf{S} = \mathbf{V}_{\theta}$, then according to Lemma 2.2 we have that the MIN-QE(U, I, S) is a statistic $\mathbf{Y}'\mathbf{A}_{1}\mathbf{Y}$, where \mathbf{A}_{1} minimizes the expression $tr\ \mathbf{A}\mathbf{V}_{\theta}\mathbf{A}\mathbf{V}_{\theta} - 2\sum_{i=1}^{m}\chi_{i}\ tr\ \mathbf{V}_{\theta}\mathbf{V}^{-1}\mathbf{V}_{i}\mathbf{V}^{-1}\mathbf{V}_{\theta}\mathbf{A}$. With respect to the assumptions $tr\ \mathbf{V}_{\theta}\mathbf{V}^{-1}\mathbf{V}_{i}\mathbf{V}^{-1}\mathbf{V}_{\theta}\mathbf{A}$ are independent of the matrix \mathbf{A} , the matrix \mathbf{A}_{1} in the estimator $\mathbf{Y}'\mathbf{A}_{1}\mathbf{Y}$ minimizes the expression $tr\ \mathbf{A}\mathbf{V}_{\theta}\mathbf{A}\mathbf{V}_{\theta}$ in the class \mathcal{A}_{1} . Since $D_{\theta}(\mathbf{Y}'\mathbf{A}\mathbf{Y}) = 2\ tr\ \mathbf{A}\mathbf{V}_{\theta}\mathbf{A}\mathbf{V}_{\theta}$ (Lemma 1.3), the theorem is proved.

Corollary 2.9. If the assumptions of the theorem 2.8 are satisfied, then

$$D_{\theta}(\text{MINQE}(U, I, \mathbf{S})) \le D_{\theta}(\text{MINQE}(U, I)).$$
 (24)

Proof is obvious.

Example.

Let $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{e}$, where $\mathbf{X} = (1, 1, 1)'$ and

$$D(\mathbf{Y}) = D(\mathbf{e}) = \begin{pmatrix} \theta_1 & \theta_2 - \theta_1 & 0 \\ \theta_2 - \theta_1 & \theta_1 & 0 \\ 0 & 0 & \theta_2 \end{pmatrix} =$$

$$= \theta_1 \begin{pmatrix} 1 - 1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \theta_2 \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \theta_1 \mathbf{V}_1 + \theta_2 \mathbf{V}_2 = \mathbf{V}_{\theta}.$$

Let $\alpha_1 = \alpha_2 = 1$, i.e. $\mathbf{V} = \mathbf{V}_1 + \mathbf{V}_2 = \mathbf{I}$ and let the matrix **S** contains prior values of elements of the matrix \mathbf{V}_{θ} .

We wish to find the MINQE(U, I) and the MINQE(U, I, S) of the function $\mathbf{f}'\theta = f_1\theta_1 + f_2\theta_2$.

The matrix **A** of the estimator **Y'AY** is an element of the class \mathcal{A}_1 and therefore

$$\mathbf{A} = \frac{1}{6} \begin{pmatrix} f_1 - f_2 - 6a & -f_1 + f_2 & 6a \\ -f_1 + f_2 & 3f_1 + 3f_2 + 6a & -2f_1 - 4f_2 - 6a \\ 6a & -2f_1 - 4f_2 - 6a & 2f_1 + 4f_2 \end{pmatrix}$$

where $a \in (-\infty, \infty)$.

If we estimate $\theta_1 + \theta_2$ $(f_1 = f_2 = 1)$, then

$$\mathbf{A} = \begin{pmatrix} -a & 0 & a \\ 0 & 1+a & -1-a \\ a & -1-a & 1 \end{pmatrix},$$

where $a \in (-\infty, \infty)$.

The MINQE(U, I) of the function $\theta_1 + \theta_2$ is the estimator Y'AY, where we assing the parameter a of the matrix A additionally in such a way that

$$tr \, AVAV = 6a^2 + 6a + 4 = min$$

The expressions $tr \ \mathbf{V}_{\theta} \mathbf{V}^{-1} \mathbf{V}_{\theta} \mathbf{A}$ (i = 1, 2) are independent of the matrix \mathbf{A} (They are independent of the parameter a) because $tr \ \mathbf{V}_{\theta} \mathbf{V}^{-1} \mathbf{V}_{1} \mathbf{V}^{-1} \mathbf{V}_{\theta} \mathbf{A} = 2(\theta_{1} - \theta_{2})^{2} f_{1}$ and $tr \ \mathbf{V}_{\theta} \mathbf{V}^{-1} \mathbf{V}_{2} \mathbf{V}^{-1} \mathbf{V}_{\theta} \mathbf{A} = 2(\theta_{1} \theta_{2} - \theta_{1}^{2}) f_{1} + \theta_{2}^{2} f_{2}$. If $\mathbf{S} = \mathbf{V}_{\theta}$ holds too, then the MINQE(U, I, S) of the function $\theta_{1} + \theta_{2}$ is the estimator $\mathbf{Y}' \mathbf{A} \mathbf{Y}$, where we assign the parameter a of the matrix \mathbf{A} additionally in such a way that

$$tr \ \mathbf{AV}_{\theta} \mathbf{AV}_{\theta} = (\theta_1 + \theta_2)^2 - 6(\theta_2^2 - 2\theta_1\theta_2)a - 6(\theta_2^2 - 2\theta_1\theta_2)a^2 = min.$$

Since $D_{\theta}(Y'AY) = 2 \text{ tr } AV_{\theta}AV_{\theta}$, it is obvious that the MINQE(U, I, S) of the function $\theta_1 + \theta_2$ is an estimator with minimal variance in the class \mathcal{A}_1 .

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НЕСМЕЩЕННАЯ КВАДРАТИЧЕСКАЯ ОЦЕНКА ВАРИАЦИОННЫХ КОМПОНЕНТОВ С МИНИМАЛЬНОЙ ДИСПЕРСИЕЙ

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Резюме

На основе реализации матрицы S, которая является оценкои ковариационной матрицы $V_\Theta = \Theta_1 V_1 + \ldots + \Theta_m V_m$ случайного вектора Y, получается оценка MINQE(U, I, S) линейной функции $f_1\Theta_1 + \ldots + f_m\Theta_m$ в форме YA(S) Y. Показана сигуация, когда MINQE(U, I, S) имеет минимальную дисперсию.