## Acta Universitatis Carolinae. Mathematica et Physica

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Acta Universitatis Carolinae. Mathematica et Physica, Vol. 24 (1983), No. 1, 3--12
Persistent URL: http://dml.cz/dmlcz/142500

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# Dependent Random Variables with a Given Marginal Distribution 

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Received 22 December 1982

Some models for generating dependent random variables with a given covariance function and with a given marginal distribution are presented in the paper. The classical autoregressive process of the first order and general autoregressive processes with random coefficients are used for this purpose.

V práci jsou uvedeny modely, pomocí nichž lze generovat závislé náhodné veličiny s danou kovarianční funkcí a s daným marginálním rozdělením. Užívá se k tomu klasického autoregresního procesu prvního řádu a obecných autoregresních procesů s náhodnými koeficienty.

В статье рассматриваются модели для конструкции зависимых случайных величин с заданной ковариационной функцией и с заданным частным распределением. Используются классический процесс авторегрессии первого порядка и общие процессы авторегрессии со случайными параметрами.

## 1. Introduction

Pseudorandom variables with a given distribution are used in Monte Carlo methods. One of the important features of such variables is their statistical independence. However, for modelling real situations dependent pseudorandom variables with a given covariance function would be often more desirable. For example, the lengths of time intervals between the arrivals of customers can be exponentially distributed, but dependent. In a few last years the methods for simulating dependent random variables with the given distribution have been developed. Usually, the paper by Bernier [3] is quoted as one of the first works where the problem of non-normal dependent variables was considered.

One of the simplest models for creating dependent variables is the autoregressive model of the first order $-\operatorname{AR}(1)$. We shall assume that $\left\{Y_{s}\right\}$ are independent identically distributed (i.i.d.) random variables such that $E Y_{s}^{2}<\infty$ and $\operatorname{Var} Y_{s}=\sigma^{2}>0$. Let $\varrho \in(-1,1)$ be a given number. Then the process $\left\{X_{s}\right\}$ satisfying the relation

$$
\begin{equation*}
X_{s}=\varrho X_{s-1}+Y_{s} \tag{1.1}
\end{equation*}
$$

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having the form

$$
\begin{equation*}
X_{s}=\sum_{k=0}^{\infty} c_{k} Y_{s-k}, \quad \sum_{k=0}^{\infty} c_{k}^{2}<\infty, \tag{1.2}
\end{equation*}
$$

is called an $\operatorname{AR}(1)$ process. From (1.1) and (1.2) we have

$$
X_{s}=\sum_{k=0}^{\infty} \varrho^{k} Y_{s-k} .
$$

It is well known that the process $\left\{X_{s}\right\}$ has the variance $\operatorname{Var} X_{s}=\sigma^{2} /\left(1-\varrho^{2}\right)$ and the correlation function $\varrho_{s}=\varrho^{|s|}$. The problem can be then formulated as follows. Let a distribution of the variables $X_{s}$ in (1.1) be given. It is necessary to find the corresponding distribution of $Y_{s}$. Generally, it can happen, that the formulated problem has no solution.

Especially, exponential and gamma distributions of $X_{s}$ are very important in point processes, particularly in queuing theory. Some papers were devoted to this problem - see Gaver and Lewis [5] and references given there.

Denote

$$
\psi(t)=E \mathrm{e}^{\mathrm{i} t Y_{s}} \quad \text { and } \quad \omega(t)=E \mathrm{e}^{\mathrm{i} t X_{s}}
$$

the characteristic functions of $Y_{s}$ and $X_{s}$, respectively. From (1.1) we have the fundamental relation

$$
\begin{equation*}
\omega(t)=\omega(\varrho t) \psi(t) \tag{1.3}
\end{equation*}
$$

If $X$ is a random variable with characteristic function $\omega(t)$ such that for every $\varrho \in(0,1)$ there exists a characteristic function $\psi(t)$ satisfying (1.3), we say that $X$ belongs to the class $L$, or that $X$ is a self-decomposable random variable - see Feller [4], p. 588. Some results concerning the self-decomposable random variables are given in Shanbhag, Pestana and Sreehari [10], Shanbhag and Sreehari [11], Thorin [12] and Thorin [13].

## 2. Classical AR(1) model

The basic tool for investigating $\operatorname{AR}(1)$ models is the relation (1.3), which immediately gives

$$
\begin{equation*}
\psi(t)=\omega(t) / \omega(\varrho t) . \tag{2.1}
\end{equation*}
$$

This allows to calculate the characteristic function $\psi(t)$ in cases when the solution exists. However, the ratio $\omega(t) / \omega(\varrho t)$ may not be a characteristic funtion. Now, we shall briefly apply (2.1) to some frequently occurring distributions.
a. Normal distribution

If $X_{s} \sim N\left(0, v^{2}\right), \quad$ then $\omega(t)=\exp \left\{-v^{2} t^{2} / 2\right\} \quad$ and $\quad(2.1)$ gives $\psi(t)=$
$\exp \cdot\left\{-v^{2} t^{2} / 2\right\} / \exp \left\{-v^{2} \varrho^{2} t^{2} / 2\right\}=\exp \left\{-v^{2}\left(1-\varrho^{2}\right) t^{2} / 2\right\}$. Thus we have the known result $Y_{s} \sim N\left[0,\left(1-\varrho^{2}\right) v^{2}\right]$.
b. Exponential distribution (Gaver and Lewis [5])

Let $X_{s}$ have an exponential distribution with parameter $a$, i.e. the density

$$
f(x)=a^{-1} \exp \{-x / a\} \text { for } x>0
$$

and $f(x)=0$ for $x \leqq 0$. This distribution will be denoted $E x(a)$. Then $\omega(t)=$ $=(1-i a t)^{-1}$ and from (2.1)

$$
\psi(t)=\varrho+(1-\varrho)(1-\mathrm{i} a t)^{-1}
$$

For $0 \leqq \varrho<1$ the function $\psi(t)$ corresponds to a random variable which is zero with probability (w.p.) $\varrho$ and equals to a random variable having $\operatorname{Ex}(a)$ with probability $1-\varrho$. If $E_{s}$ is a sequence of i.i.d. variables with $E x(a)$, then the model (1.1) takes on the form

$$
X_{s}= \begin{cases}\varrho X_{s-1} & \text { w.p. } \varrho,  \tag{2.2}\\ \varrho X_{s-1}+E_{s} & \text { w.p. } \\ 1-\varrho\end{cases}
$$

c. Gamma distribution (Gaver and Lewis [5])

Let $X_{s}$ have $\Gamma(a, p)$ distribution with the density

$$
f(x)=\frac{1}{a^{p} \Gamma(p)} \mathrm{e}^{-x / a} x^{p-1} \text { for } x>0
$$

and $f(x)=0$ for $x \leqq 0$, where $a>0$ and $p>0$ are given parameters. The characteristic function of $\Gamma(a, p)$ is $\omega(t)=(1-\mathrm{i} a t)^{-p}$. Then

$$
\psi(t)=\left[\varrho+(1-\varrho)(1-\mathrm{i} a t)^{-1}\right]^{p}
$$

Consider the case $0 \leqq \varrho<1$. The result for $p=1$ is given above in (2.2), since $\Gamma(a, 1)=E x(a)$. If $p$ is an integer, then we can obtain explicit results. For $p=2$ we get

$$
\psi(t)=\varrho^{2}+2 \varrho(1-\varrho)(1-\mathrm{i} a t)^{-1}+(1-\varrho)^{2}(1-\mathrm{i} a t)^{-2}
$$

in the case $p=3$ we have

$$
\begin{gathered}
\psi(t)=\varrho^{3}+3 \varrho^{2}(1-\varrho)(1-\mathrm{i} a t)^{-1}+3 \varrho(1-\varrho)^{2}(1-\mathrm{i} a t)^{-2}+ \\
+(1-\varrho)^{3}(1-\mathrm{i} a t)^{-3}
\end{gathered}
$$

For $p=2$, the distribution corresponding to $\psi(t)$ is a mixture of zero, $\Gamma(a, 1)$ and $\Gamma(a, 2)$ with weights $\varrho^{2}, 2 \varrho(1-\varrho)$ and $(1-\varrho)^{2}$, respectively. Similar result follows for $p=3$ etc.
d. Laplace (double exponential) distribution (Anděl [2])

Let $X_{s}$ have Laplace distribution $L(b)$ with the density

$$
f(x)=(2 b)^{-1} \exp \{-|x| / b\}, \quad-\infty<x<\infty,
$$

where $b>0$ is a parameter. This distribution has the characteristic function

$$
\omega(t)=\left(1+b^{2} t^{2}\right)^{-1}
$$

Therefore, (2.1) gives

$$
\psi(t)=\varrho^{2}+\left(1-\varrho^{2}\right)\left(1+b^{2} t^{2}\right)^{-1} .
$$

This corresponds to a mixture of zero and $L(b)$ with the weights $\varrho^{2}$ and $1-\varrho^{2}$, respectively. Thus

$$
X_{s}= \begin{cases}\varrho X_{s-1} & \text { w.p. } \varrho^{2},  \tag{2.3}\\ \varrho X_{s-1}+L_{s} & \text { w.p. } 1-\varrho^{2},\end{cases}
$$

where $\left\{L_{s}\right\}$ are i.i.d. random variables with $L(b)$.
e. Continuous rectangular distribution (Anděl [2])

Let $X_{s}$ have a continuous rectangular distribution on $[-a, a]$, where $a>0$. The corresponding characteristic function is

$$
\omega(t)=(a t)^{-1} \sin a t .
$$

We shall consider only the non-trivial case $\varrho \neq 0$. From (2.1)

$$
\begin{equation*}
\psi(t)=\varrho \frac{\sin a t}{\sin \varrho a t} . \tag{2.4}
\end{equation*}
$$

The function $\psi(t)$ does not depend on the sign of $\varrho$ and thus we shall investigate only $\varrho>0$. There are three possible situations.
(i) Let $\varrho=1 /(2 n), n=1,2, \ldots$

Then

$$
\psi(t)=\frac{1}{2 n} \frac{\sin a t}{\sin (a t / 2 n)}=\frac{1}{2 n} \sum_{k=1}^{n}\left[\exp \left\{\frac{\mathrm{i}(2 k-1) a t}{2 n}\right\}+\exp \left\{-\frac{\mathrm{i}(2 k-1) a t}{2 n}\right\}\right]
$$

is the characteristic function of the discrete rectangular distribution concentrated at the points

$$
\begin{gathered}
-\frac{2 n-1}{2 n} a,-\frac{2 n-3}{2 n} a, \ldots,-\frac{3}{2 n} a,-\frac{1}{2 n} a, \frac{1}{2 n} a, \frac{3}{2 n} a, \ldots, \\
\ldots \frac{2 n-3}{2 n} a, \frac{2 n-1}{2 n} a .
\end{gathered}
$$

Each point has probability $1 /(2 n)$.
(ii) Let $\varrho=1 /(2 n+1), n=1,2, \ldots$

In this case

$$
\psi(t)=\frac{1}{2 n+1} \sum_{k=-n}^{n} \exp \left\{i \frac{2 k a t}{2 n+1}\right\}
$$

which is the characteristic function of the discrete rectangular distribution concentrated at the points

$$
\begin{gathered}
-\frac{2 n}{2 n+1} a,-\frac{2 n-2}{2 n+1} a, \ldots,-\frac{2}{2 n+1} a, 0, \frac{2}{2 n+1} a, \ldots, \frac{2 n-2}{2 n+1} a \\
\frac{2 n+1}{2 n} a
\end{gathered}
$$

The probability of each point is $1 /(2 n+1)$.
(iii) Let $\varrho \neq 1 / n, n=1,2, \ldots$

If $t \rightarrow \pi / \varrho a$, then $\sin \varrho a t \rightarrow 0$ and $\sin a t \rightarrow \sin \pi / \varrho \neq 0$. From (2.4) we can see that $|\psi(t)| \rightarrow \infty$. Obviousiy, $\psi(t)$ cannot be a characteristic function (the absolute value of any characteristic function cannot exceed 1 ). Therefore, for $\varrho \neq 1 / n$ there exists no distribution of $Y_{s}$ which would lead to continuous rectangular distribution of $X_{s}$ in model (1.1).
f. Mixed exponential distribution

Let $X_{s}$ have the density

$$
f(x)=p_{1} a_{1}^{-1} \mathrm{e}^{-x / a_{1}}+p_{2} a_{2}^{-1} \mathrm{e}^{-x / a_{2}} \text { for } x>0
$$

and $f(x)=0$ for $x \leqq 0$, where $p_{1}=1-p_{2}$ and $a_{1}>a_{2}>0$ are some parameters. The results are derived in Gaver and Lewis [5] and in Lawrance [6].
g. Cauchy distribution

Let $X_{s}$ have a Cauchy distribution $C(a, b)$ with the density

$$
f(x)=\frac{1}{\pi} \frac{b}{b^{2}+(x-a)^{2}}, \quad-\infty<x<\infty
$$

where $a$ is a real and $b$ a positive number. Since

$$
\omega(t)=\exp \{\mathrm{i} a t|b-b| t \mid\}
$$

we obtain

$$
\psi(t)=\exp \{\operatorname{iat}(1-\varrho) / b-b(1-|\varrho|)|t|\}
$$

Thus $Y_{s}$ has

$$
C[a(1-\varrho)(1-|\varrho|), b(1-|\varrho|)]
$$

It is a little surprising that the results of the type (2.2) and (2.3) are not satisfactory. We shall consider (2.2) in detail. First of all, it is easy to see that

$$
E\left(X_{s+1} \mid X_{s}=x\right)=\varrho x+(1-\varrho) a
$$

If $x>a$, then $\varrho x+(1-\varrho) a<x$ and similarly for $x<a$. Generally, a typical realization of (2.2) consists of decreasing variables with the coefficient $\varrho$ and only from time to time a shock $E_{s}$ causes a jump to higher values. If we denote by $R$ the number of runs down of the type $X_{s-1}=\varrho X_{s}$, then

$$
E R=\varrho /(1-\varrho), \quad \operatorname{Var} R=\varrho /(1-\varrho)^{2}
$$

A key to understanding the bad behaviour of the model is given in the following two assertions.

Lemma 2.1. Let $X$ and $Y$ be independent $E x(a)$ variables. If $c>0$, then $P(X<c Y)=c /(1+c)$.

Proof is obvious.
Theorem 2.2. Let $X_{s}$ be defined by (2.2). Then

$$
P\left(X_{s}<X_{s-1}\right)=1 /(2-\varrho)>0.5 .
$$

Proof. Using Lemma 2.1 we get

$$
\begin{aligned}
& \quad P\left(X_{s}<X_{s-1}\right)=\varrho+(1-\varrho) P\left(\varrho X_{s-1}+E_{s}<X_{s-1}\right)= \\
& =\varrho+(1-\varrho) P\left[E_{s}<(1-\varrho) X_{s-1}\right]=\varrho+(1-\varrho) \frac{1-\varrho}{2-\varrho}=\frac{1}{2-\varrho} .
\end{aligned}
$$

The problem is to construct such models in which $P\left(X_{s}<X_{s-1}\right)=0.5$. New models were proposed by Lawrance and Lewis [8].

## 3. Modified AR(1) models

Consider the following three models, where $E_{s}$ are independent $E x(a)$ variables.
Model I: $\quad X_{s}=\varrho X_{s-1}+\left\{\begin{array}{lll}0 & \text { w.p. } & \varrho, \\ E_{s} & \text { w.p. } & 1-\varrho, \quad 0 \leqq \varrho<1 .\end{array}\right.$
Model II: $\quad X_{s}=(1-\alpha) E_{s}+\left\{\begin{array}{lll}X_{s-1} & \text { w.p. } \alpha, \\ 0 & \text { w.p. } 1-\alpha,\end{array} \quad 0<\alpha<1\right.$.
Model III: $\quad X_{s}=\varepsilon_{s}+\left\{\begin{array}{lll}\beta X_{s-1} & \text { w.p. } & \alpha, \\ 0 & \text { w.p. } & 1-\alpha,\end{array} \quad 0 \leqq \alpha \leqq 1\right.$,
where $0 \leqq \beta \leqq 1, \alpha \beta \neq 1$ and $\varepsilon_{s}$ are i.i.d. random variables with a distribution which will be derived later.

Model I is known from Section 2. It was derived that $X_{s}$ has $E x(a)$ distribution. Since model I is the classical $\operatorname{AR}(1)$, its correlation function is $\varrho_{s}=\varrho^{|s|}$.

Theorem 3.1. Consider Model II. Then $X_{s}$ has $\operatorname{Ex}(a)$ distribution and $\left\{X_{s}\right\}$ is a stationary process with the correlation function $\varrho_{s}=\alpha^{|s|}$.

Proof. In the first part it is sufficient to show that if $X_{s-1} \sim E x(a)$, then $X_{s} \sim$ $\sim E x(a)$. Introduce a random variable $\xi$ by

$$
\xi= \begin{cases}X_{s-1} & \text { w.p. } \\ 0 & \text { w.p. } \quad 1-\alpha .\end{cases}
$$

Then $\xi$ has the characteristic function

$$
1-\alpha+\frac{\alpha}{1-\mathrm{i} a t}
$$

whereas $(1-\alpha) E_{s}$ has the characteristic function $[1-\mathrm{i} a(1-\alpha) t]^{-1}$. Then $(1-\alpha) E_{s}+\xi$ has the characteristic function

$$
[1-\mathrm{i} a(1-\alpha) t]^{-1}\left[1-\alpha+\frac{\alpha}{1-\mathrm{i} a t}\right]=(1-\mathrm{i} a t)^{-1}
$$

which corresponds to $E x(a)$.
It is important to notice that model II is the special case of an autoregressive model with random parameters (ARRP). The assertion about the correlation function follows from general theory of ARRP - see Anděl [1] and Nicholls and Quinn [9].

Theorem 3.2. Consider model III. Then $X_{s} \sim E x(a)$ if and only if

$$
\varepsilon_{s}=\left\{\begin{array}{llr}
E_{s} & \text { w.p. } & (1-\beta)[1-(1-\alpha) \beta]^{-1},  \tag{3.1}\\
(1-\alpha) \beta E_{s} & \text { w.p. } & \alpha \beta[1-(1-\alpha) \beta]^{-1} .
\end{array}\right.
$$

Proof. Denote $\psi(t)$ the characteristic function of $\varepsilon_{s}$. Then $X_{s-1}$ and $X_{s}$ are $\operatorname{Ex}(a)$ variables if and only if the relation

$$
(1-\mathrm{i} a t)^{-1}=\psi(t)\left[1-\alpha+\frac{\alpha}{1-\mathrm{i} a \beta t}\right]
$$

holds. From here we obtain

$$
\begin{gathered}
\psi(t)=\frac{1-\mathrm{i} a \beta t}{(1-\mathrm{i} a t)} \frac{1}{[1-\mathrm{i} a(1-\alpha) \beta t]}= \\
=\frac{1-\beta}{1-(1-\alpha) \beta} \frac{1}{1-\mathrm{i} a t}+\frac{\alpha \beta}{1-(1-\alpha) \beta} \frac{1}{1-\mathrm{i} a(1-\alpha) \beta t},
\end{gathered}
$$

which is the characteristic function corresponding to (3.1).
Let us remark that model I is the special case of model III when $\alpha=1$. Then we have $\varrho=\beta$. Also model II is the special case of model III, when $\beta=1$. Model III also belongs to ARRP and the correlation function of $\left\{X_{s}\right\}$ is $\varrho_{s}=(\alpha \beta)^{|s|}$.

Theorem 3.3. Consider model III. Let $\alpha \neq 1, \beta \neq 1$. Then

$$
P\left(X_{s}<X_{s-1}\right)=\frac{(1-\alpha)(1+\beta)}{2[1+(1-\alpha) \beta]}+\frac{\alpha(1-\beta)}{(2-\beta)(1-\alpha \beta)} .
$$

Proof. We have

$$
P\left(X_{s}<X_{s-1}\right)=(1-\alpha) P\left(X_{s-1}>\varepsilon_{s}\right)+\alpha P\left(X_{s-1}>\varepsilon_{s}+\beta X_{s-1}\right) .
$$

It can be calculated that

$$
\begin{gathered}
P\left(X_{s-1}>\varepsilon_{s}\right)=\frac{1}{1-(1-\alpha) \beta}\left[\frac{1-\beta}{2}+\frac{\alpha \beta}{1+(1-\alpha) \beta}\right] \\
P\left[X_{s-1}>(1-\beta)^{-1} \varepsilon_{s}\right]=\frac{1}{1-(1-\alpha) \beta}\left[\frac{1}{1+\frac{1}{1-\beta}}+\frac{\alpha \beta}{1+\frac{(1-\alpha) \beta}{1-\beta}}\right] .
\end{gathered}
$$

From here we get the result.
A similar calculation or the limit procedure gives

$$
\begin{array}{ll}
P\left(X_{s}<X_{s-1}\right)=(2-\beta)^{-1}>0.5 & \text { for } \alpha=1 \\
P\left(X_{s}<X_{s-1}\right)=(1-\alpha) /(2-\alpha)<0.5 & \text { for } \quad \beta=1
\end{array}
$$

Therefore, $P\left(X_{s}<X_{s-1}\right)=0.5$ in the following cases:
(i) $\alpha=0$;
(ii) $\beta=0$;
(iii) $\beta=1 /(2-\alpha)$.

## 4. Models of higher order

The attempts to generalize model (1.1) to $\operatorname{AR}(n)$ with $n \geqq 2$ for obtaining dependent random variables were not succesful. Lawrance and Lewis [7] proposed the model

$$
X_{s}=\left\{\begin{array}{llll}
\alpha_{1} & X_{s-1} & \text { w.p. } & 1-\alpha_{2}  \tag{4.1}\\
\alpha_{2} & X_{s-2} & \text { w.p. } & \alpha_{2}
\end{array}\right\}+\varepsilon_{s} .
$$

For $\alpha_{2}=0$ we get a model of type (2.2). Let us look for such a distribution of $\varepsilon_{s}$ that $X_{s} \sim \operatorname{Ex}(a)$. If $\psi(t)$ is the characteristic function of $\varepsilon_{s}$, then (4.1) leads to the condition

$$
(1-\mathrm{i} a t)^{-1}=\left(\frac{1-\alpha_{2}}{1-\mathrm{i} a \alpha_{1} t}+\frac{\alpha_{2}}{1-\mathrm{i} a \alpha_{2} t}\right) \psi(t) .
$$

From here

$$
\psi(t)=A+B(1-\mathrm{i} a t)^{-1}+C\left[1-\mathrm{i} a \alpha_{2}\left(1+\alpha_{1}-\alpha_{2}\right) t\right]^{-1}
$$

where

$$
\begin{gathered}
A=\alpha_{1} /\left(1+\alpha_{1}-\alpha_{2}\right), \quad B=\left(1-\alpha_{1}\right)\left(1-\alpha_{2}\right) /\left[1-\alpha_{2}\left(1+\alpha_{1}-\alpha_{2}\right)\right] \\
C=\left(1-\alpha_{2}\right)\left(\alpha_{1}-\alpha_{2}\right)^{2} /\left\{\left(1+\alpha_{1}-\alpha_{2}\right)\left[1-\alpha_{2}\left(1-\alpha_{1}-\alpha_{2}\right)\right]\right\}
\end{gathered}
$$

Therefore, $X_{s}$ will have $E x(a)$ if and only if

$$
\varepsilon_{s}=\left\{\begin{array}{lll}
0 & \text { w.p. } & A, \\
E x(a) & \text { w.p. } & B, \\
\alpha_{2}\left(1+\alpha_{1}-\alpha_{2}\right) E x(a) & \text { w.p. } & C .
\end{array}\right.
$$

Again, (4.1) is ARRP model. Its correlation function is given by the relation

$$
\varrho_{r}=\alpha_{1}\left(1-\alpha_{2}\right) \varrho_{r-1}+\alpha_{2}^{2} \varrho_{r-2}, \quad r \geqq 2 .
$$

It is possible to generalize model (4.1) to a higher order.

## 5. Other models

Lawrance and Lewis [7] proposed also MA and ARMA models with random coefficients for calculating dependent random variables with $\operatorname{Ex}(a)$ distribution. The simplest model is

$$
X_{s}= \begin{cases}\beta E_{s} & \text { w.p. } \\ \beta E_{s}+E_{s-1} & \text { w.p. } \\ 1-\beta\end{cases}
$$

where $E_{s} \sim E x(a)$ are i.i.d. variables.
However, let us remark that is possible to use also classical MA models. For example, put

$$
X_{s}=Y_{s}+Y_{s-1}
$$

If $Y_{s}$ are i.i.d. variables, $Y_{s} \sim \Gamma(a, 0.5)$, then $X_{s} \sim E x(a)$.

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