## Czechoslovak Mathematical Journal

## Hafida Laasri; Omar El-Mennaoui

Stability for non-autonomous linear evolution equations with $L^{p}$-maximal regularity

Czechoslovak Mathematical Journal, Vol. 63 (2013), No. 4, 887-908

Persistent URL: http://dml.cz/dmlcz/143605

## Terms of use:

© Institute of Mathematics AS CR, 2013

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.


This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project DML-CZ: The Czech Digital Mathematics Library http://dml.cz

# STABILITY FOR NON-AUTONOMOUS LINEAR EVOLUTION EQUATIONS WITH $L^{p}$-MAXIMAL REGULARITY 

Hafida LaAsri, Ulm, Omar El-Mennaoui, Agadir

(Received May 31, 2012)

Abstract. We study stability and integrability of linear non-autonomous evolutionary Cauchy-problem

$$
(\mathrm{P})\left\{\begin{array}{l}
\dot{u}(t)+A(t) u(t)=f(t) \quad t \text {-a.e. on }[0, \tau] \\
u(0)=0
\end{array}\right.
$$

where $A:[0, \tau] \rightarrow \mathscr{L}(X, D)$ is a bounded and strongly measurable function and $X, D$ are Banach spaces such that $D \underset{d}{\hookrightarrow} X$. Our main concern is to characterize $L^{p}$-maximal regularity and to give an explicit approximation of the problem (P).

Keywords: maximal regularity; on-autonomous evolution equation; stability for linear evolution equation; integrability for linear evolution equation

MSC 2010: 35K90, 47D06

## 1. Introduction

We study $L^{p}$-maximal regularity for non-autonomous evolutionary linear Cauchyproblems.

Let $(X,\|\cdot\|)$ and $\left(D,\|\cdot\|_{D}\right)$ be two Banach spaces such that $D$ is continuously and densely embedded in $X$. Let $A:[0, \tau] \rightarrow \mathscr{L}(X, D)$ be a bounded and strongly measurable function. Let $p \in(1, \infty)$. We say that $A$ has $L^{p}$-maximal regularity on the bounded real interval $[0, \tau]$ (and we write $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ ) if for all subintervals $[a, b]$ of $[0, \tau]$ and for every $f \in L^{p}(a, b ; X)$ there exists a unique $u \in M R_{p}(a, b):=$

[^0] (DAAD).
$L^{p}(a, b ; D) \cap W^{1, p}(a, b ; X)$ such that
\[

\mathrm{CP}(a, b)\left\{$$
\begin{array}{l}
\dot{u}(t)+A(t) u(t)=f(t) \quad t \text {-a.e. on }[a, b], \\
u(a)=0 .
\end{array}
$$\right.
\]

In particular $\dot{u}$ and $A u$ have the same regularity as the inhomogeneity $f$. This property is the reason for the name maximal regularity. Recall that $W^{1, p}(a, b ; X) \subset$ $C([a, b] ; X)$, so the condition $u(a)=0$ above makes sense.

For the autonomous case, that is if $A(\cdot)=A$ is independent of $t \in[0, \tau]$, $L^{p}$-maximal regularity is independent of the bounded interval $[a, b]$ and if $A \in$ $\mathscr{M} \mathscr{R}_{p}(0, \tau)$ for some $p \in(1, \infty)$ then $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ for all $p \in(1, \infty)$ [22], [8]. Thus we denote by $\mathscr{M} \mathscr{R}$ the set of all operators $A \in \mathscr{L}(D, X)$ having $L^{p}$-maximal regularity. It is also well known that if $A$ has $L^{p}$-maximal regularity then $A$ is closed as unbounded operator on $X[6]$ and $-A$ generates a holomorphic $C_{0}$-semigroup on $X$ [12] and [17]. De Simon [10] showed that the converse is true if $X$ is a Hilbert space. However, the restriction to Hilbert spaces is essential by a result of Kalton and Lancien [16].

Maximal regularity has been studied by many authors in recent years. The reader may consults [1], [2], [4], [5], [6], [11], [14], [15], [19], [20] and the references therein for different sufficient conditions for $L^{p}$-maximal regularity in the non-autonomous case and for applications.

It is known [7, Lemma 1.2] that if $A \in \mathscr{M} \mathscr{R}$ then there exists a constant $M(A)>0$ such that

$$
\begin{align*}
& \left\|(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X), M R_{p}(a, b)\right)} \leqslant M(A) \text { and }  \tag{1.1}\\
& \left\|(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \leqslant \frac{M(A)}{1+\varrho}
\end{align*}
$$

for all intervals $[a, b] \subset[0, \tau]$ and all $\varrho \geqslant 0$, where $\mathscr{B}$ is the distributional derivative with domain $D(\mathscr{B})=\left\{u \in W^{1, p}(a, b ; X), u(a)=0\right\}$ and $\mathscr{A}$ the multiplication operator with domain $L^{p}(a, b ; D)$ defined by $(\mathscr{A} f)(s)=A f(s)$ a.e.

In the case where $A$ is not constant, we obtain a comparable result. Indeed, if $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$, then we show in Proposition 2.2 below that $\varrho+A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ for all $\varrho \in \mathbb{C}$ and there exists $M(A)>0$ such that

$$
\begin{aligned}
& \varrho^{1 / p}\left\|(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \leqslant M(A) \quad \text { and } \\
& \quad\left\|(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X), L^{p}(a, b ; D)\right)} \leqslant M(A)
\end{aligned}
$$

for all intervals $[a, b] \subset[0, \tau]$ and all $\varrho \geqslant 0$.

In Lemma 4.1 we will see that the constant $M(A(t))$ in (1.1) corresponding to each $A(t) \in \mathscr{M} \mathscr{R}$ does not depend on $t$ provided that $A$ is relatively continuous.

The notion of relative continuity was introduced recently in [7] by Arendt, Chill, Fornaro and Poupaud, who proved in [7, Theorem 2.7] $L^{p}$-maximal regularity assuming only that $A$ is bounded, strongly measurable and relatively continuous, and that $A(t) \in \mathscr{M} \mathscr{R}$ for every $t \in[0, \tau]$.

Theorem 2.7 in [7] establishes existence and uniqueness of a solution of the problem $\mathrm{CP}(0, \tau)$. But at least from a theoretical point of view, it is very important to exhibit an explicit approximation of this solution. Our goal is to characterize $L^{p}$-maximal regularity of $\mathrm{CP}(0, \tau)$. In particular, our approach gives an explicit approximation of the problem $\mathrm{CP}(0, \tau)$, which may have some interest.

Let $\Lambda=\lambda_{0}<\lambda_{1}, \ldots,<\lambda_{n+1}=\tau$ be a subdivision of $[0, \tau]$ and $A_{\Lambda}:[0, \tau] \rightarrow$ $\mathscr{L}(D, X)$ be given by

$$
t \mapsto A_{\Lambda}(t):= \begin{cases}A_{k} & \text { for } \lambda_{k} \leqslant t<\lambda_{k+1} \\ A_{n} & \text { for } t=\tau\end{cases}
$$

where

$$
A_{k} x:=\frac{1}{\lambda_{k+1}-\lambda_{k}} \int_{\lambda_{k}}^{\lambda_{k+1}} A(r) x \mathrm{~d} r \quad(x \in D, k=0,1, \ldots, n) .
$$

The function $A$ is said to be relatively $p$-approximable if for all $\varepsilon>0$ there exist $\delta>0, \eta \geqslant 0$ such that for all $f \in L^{p}(0, \tau ; D)$ and all subdivisions $\Lambda$ of $[0, \tau]$ of modulus $|\Lambda|:=\max _{j=0,1, \ldots, n}\left(\lambda_{j+1}-\lambda_{j}\right) \leqslant \delta$ we have

$$
\left\|\mathscr{A}_{\Lambda} f-\mathscr{A} f\right\|_{L^{p}(0, \tau ; D)} \leqslant \varepsilon\|f\|_{L^{p}(0, \tau ; D)}+\eta\|f\|_{L^{p}(0, \tau ; X)}
$$

Assume that $A$ is relatively $p$-approximable. We show (see Proposition 3.4) that if $A \in \mathscr{M}_{\mathscr{R}}(0, \tau)$ then there exists $\delta_{0}>0$ such that $A_{\Lambda} \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ for all subdivisions $\Lambda$ of $[0, \tau]$ such that $|\Lambda| \leqslant \delta_{0}$. This implies in particular that the means $A_{k}$ are in $\mathscr{M} \mathscr{R}, k=0,1, \ldots, n$. Moreover, if for each $[a, b] \subset[0, \tau]$ the unique solution $u_{\Lambda} \in M R_{p}(a, b)$ (see Section 3) of

$$
P_{\Lambda}(a, b)\left\{\begin{array}{l}
\dot{u}_{\Lambda}(t)+A_{\Lambda}(t) u_{\Lambda}(t)=f(t) \quad t \text {-a.e. on }[a, b] \\
u_{\Lambda}(0)=0
\end{array}\right.
$$

converges in $M R_{p}(a, b)$ as $|\Lambda| \rightarrow 0$ then $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$. In this case $u:=\lim _{|\Lambda| \rightarrow 0} u_{\Lambda}$ is the unique solution of $\operatorname{CP}(a, b)$ belonging to $M R_{p}(a, b)$ (see Theorem 3.5). Our main result shows that this convergence holds if $A$ is relatively continuous. This gives an alternative proof of Theorem 2.7 in [7]. We prove this result in Theorem 4.5
by a more general approach based on the stability of the problem $\mathrm{CP}(0, \tau)$. An application to a non-autonomous diffusion equation is given in Section 5.

## 2. Preliminaries

Throughout this paper $\left(D,\|\cdot\|_{D}\right)$ and $(X,\|\cdot\|)$ are two Banach spaces such that $D$ is continuously and densely embedded into $X$. We write $D \underset{d}{\hookrightarrow} X$. Let $A:[0, \tau] \rightarrow$ $\mathscr{L}(D, X)$ be a bounded, strongly Bochner measurable function. Let $p \in(1, \infty)$ be fixed throughout this section.

Definition 2.1. We say that $A$ has $L^{p}$-maximal regularity on the bounded interval $[0, \tau]$, and we write $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$, if for all intervals $[a, b] \subset[0, \tau]$ and every $f \in L^{p}(a, b ; X)$ there exists a unique function $u$ belonging to the maximal regularity space $M R_{p}(a, b):=L^{p}(a, b ; D) \cap W^{1, p}(a, b ; X)$ such that

$$
\mathrm{CP}(a, b)\left\{\begin{array}{l}
\dot{u}(t)+A(t) u(t)=f(t) \quad t \text {-a.e. on }[a, b] \\
u(a)=0
\end{array}\right.
$$

The space $M R_{p}(a, b)$ is a Banach space for the norm

$$
\|u\|_{M R}:=\|u\|_{L^{p}(a, b ; D)}+\|u\|_{W^{1, p}(a, b ; X)}
$$

Let $M R_{0}(a, b)$ be the closed subspace of $M R_{p}(a, b)$ consisting of all $u$ satisfying $u(a)=0$.

It is useful to reformulate the property of $L^{p}$-maximal regularity in terms of sum methods, as initiated by Da Prato and Grisvard [9]. For this, consider for each interval $[a, b] \subset[0, \tau]$ the unbounded linear operators $\mathscr{A}=\mathscr{A}_{a, b}$ and $\mathscr{B}=\mathscr{B}_{a, b}$ with domains $D(\mathscr{A})=L^{p}(a, b ; D)$ and $D(\mathscr{B})=\left\{u \in W^{1, p}(a, b ; X), u(a)=0\right\}$ defined by

$$
(\mathscr{A} f)(t)=A(t) f(t) \quad \text { and } \quad(\mathscr{B} u)(t)=\dot{u}(t) \quad \text { for almost every } t \in[a, b] .
$$

In fact, if $C:=\sup _{t \in[0, \tau]}\|A(t)\|_{\mathscr{L}(D, X)}$, it is easy to see that $\mathscr{A} f$ is Bochner measurable and

$$
\|(\mathscr{A} f)(t)\| \leqslant C\|f(t)\|_{D} \quad t \text {-a.e. on }[a, b]
$$

for all $f \in L^{p}(a, b ; D)$. It follows that $\|\mathscr{A}\|_{\mathscr{L}\left(L^{p}(a, b ; D), L^{p}(a, b ; X)\right)} \leqslant C$.
Thus $A$ has the property of $L^{p}$-maximal regularity if and only if for all $[a, b] \subset[0, \tau]$ the unbounded operator $\mathscr{A}+\mathscr{B}$ with domain $D(\mathscr{A}+\mathscr{B})=M R_{0}(a, b)$ is invertible. It follows that if $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ then for each subinterval $[a, b]$ of $[0, \tau]$ and $f \in$ $L^{p}(a, b ; X)$ the problem $\mathrm{CP}(a, b)$ has a unique solution $u \in M R_{p}(a, b)$ and

$$
\begin{equation*}
\|u\|_{M R} \leqslant c\|f\|_{L^{p}(a, b ; X)} \tag{2.1}
\end{equation*}
$$

for some constant $c>0$ which is independent of $f$ and of the interval $[a, b]$. We do not need to assume here that the operators $A(t)$ are closed. Observe that $D$ is a Banach space and $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ is bounded and strongly measurable. By unique solvability of the problem $\operatorname{CP}(a, b)$, for every interval $[a, b] \subset[0, \tau]$ and every $f \in L^{p}(a, b ; X)$, the operator $\left(A_{a, b}+B_{a, b}\right)^{-1}$ can be seen as the restriction of the operator $\left(A_{0, \tau}+B_{0, \tau}\right)^{-1}$ to the space of functions in $L^{p}(0, \tau ; X)$ which vanish on $[0, a]$. This shows, in particular, that the constant $c$ in (2.1) does not depend on the interval $[a, b] \subset[0, \tau]$.

The following proposition is used in the next sections.
Proposition 2.2. Assume that $A \in \mathscr{M}_{\mathscr{R}_{p}}(0, \tau)$. Then the following holds.
(i) $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ if and only if $\varrho+A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ for some (or all) $\varrho \in \mathbb{C}$.
(ii) There exists $M(A)>0$ such that

$$
\begin{aligned}
& \varrho^{1 / p}\left\|(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \leqslant M(A) \quad \text { and } \\
& \quad\left\|(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X), L^{p}(a, b ; D)\right)} \leqslant M(A)
\end{aligned}
$$

for all intervals $[a, b] \subset[0, \tau]$ and all $\varrho \geqslant 0$.
Proof. (i) Let $f \in L^{p}(0, \tau ; X), \varrho \in \mathbb{C}$ and $g(t):=\mathrm{e}^{\varrho t} f(t)$. Let $p^{*}>1$ be such that $1 / p+1 / p^{*}=1$. Then $u$ satisfies

$$
\begin{equation*}
\dot{u}+A(t) u+\varrho u=f, \quad \text { a.e. on }[0, \tau], u(0)=0 \tag{2.2}
\end{equation*}
$$

if and only if $v(t):=\mathrm{e}^{\varrho t} u(t)$ satisfies

$$
\begin{equation*}
\dot{v}+A(t) v=g, \quad \text { a.e. on }[0, \tau], v(0)=0 \tag{2.3}
\end{equation*}
$$

which is assumed to have a unique solution in $M R_{p}(0, \tau)$. Thus (i) holds.
(ii) It suffices to prove the estimates in (ii) for $[a, b]=[0, \tau]$. From the proof of (i) we have that $u(t)=\mathrm{e}^{-\varrho t} v(t)=\mathrm{e}^{-\varrho t} \int_{0}^{t} \dot{v}(r) \mathrm{d} r$, where $u$ and $v$ are the solution of (2.2) and (2.3), respectively. Thus, for all $\varrho>0$

$$
\|u(t)\| \leqslant \mathrm{e}^{-\varrho t} \tau^{1 / p^{*}}\|\dot{v}\|_{L^{p}(0, t, X)} \leqslant \mathrm{e}^{-\varrho t} \tau^{1 / p^{*}}\|v\|_{M R(0, t)} \leqslant c \tau^{1 / p^{*}} \mathrm{e}^{-\varrho t}\|g\|_{L^{p}(0, t, X)}
$$

Then

$$
\begin{aligned}
\|u\|_{L^{p}(0, \tau ; X)}^{p} & \leqslant c^{p} \tau^{p / p^{*}} \int_{0}^{\tau} \int_{0}^{t} \mathrm{e}^{-p \varrho(t-r)}\|f(r)\|^{p} \mathrm{~d} r \mathrm{~d} t=c^{p} \tau^{p / p^{*}}\left\|\mathrm{e}^{-p \varrho}\right\|_{1}\|f\|_{L^{p}(0, \tau ; X)}^{p} \\
& \leqslant c^{p} \frac{\tau^{p / p^{*}}}{p \varrho}\|f\|_{L^{p}(0, \tau ; X)}^{p} .
\end{aligned}
$$

The first inequality follows. To prove the second inequality we integrate by parts. Since $\|u(t)\|_{D}=\mathrm{e}^{-\varrho t}\|v(t)\|_{D}$, then

$$
\begin{aligned}
\|u\|_{L^{p}(0, \tau ; D)}^{p} & =\int_{0}^{\tau} \mathrm{e}^{-\varrho p t}\|v(t)\|_{D}^{p} \mathrm{~d} t \\
& =\mathrm{e}^{-\varrho p \tau} \int_{0}^{\tau}\|v(t)\|_{D}^{p} \mathrm{~d} t+\varrho p \int_{0}^{\tau} \mathrm{e}^{-\varrho p t} \int_{0}^{t}\|v(r)\|_{D}^{p} \mathrm{~d} r \mathrm{~d} t
\end{aligned}
$$

It follows that

$$
\begin{aligned}
\|u\|_{L^{p}(0, \tau ; D)}^{p} & \leqslant c^{p}\left(\mathrm{e}^{-\varrho p \tau}\|g\|_{L^{p}(0, \tau, X)}^{p}+\varrho p \int_{0}^{\tau} \int_{0}^{t} \mathrm{e}^{-\varrho p(t-r)}\|f(r)\|^{p} \mathrm{~d} r \mathrm{~d} t\right) \\
& \leqslant c^{p}(1+\varrho p / \varrho p)\|f\|_{L^{p}(0, \tau ; X)}^{p}=2 c^{p}\|f\|_{L^{p}(0, \tau ; X)}^{p} .
\end{aligned}
$$

Setting $M(A):=2^{1 / p} c\left(1+\tau^{1 / p^{*}} / p\right)$, the proof is complete.
We may also consider the initial value problems

$$
\mathrm{CP}(a, b, x)\left\{\begin{array}{l}
\dot{u}(t)+A(t) u(t)=f(t) \quad t \text {-a.e. on }[a, b] \\
u(a)=x \in X
\end{array}\right.
$$

Assume that $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$. Then for all $0 \leqslant a \leqslant b \leqslant \tau$ the problem $\operatorname{CP}(a, b, x)$ has a unique solution in $M R_{p}(a, b)$ for all $f \in L^{p}(a, b ; X)$ and for all $x$ in the trace space

$$
\operatorname{Tr}=\left\{u(a), u \in M R_{p}(a, b)\right\} .
$$

The trace space $\operatorname{Tr}$ is a Banach space with the norm $\|x\|_{T r}:=\inf \left\{\|u\|_{M R}\right.$ : $u(a)=x\}$. Note that the trace space does not depend on the interval $[a, b]$ and does not depend on the choice of the point where the functions $u \in M R_{p}(a, b)$ are evaluated. This means that for every $\tau^{\prime}>0$ and $t \in\left[0, \tau^{\prime}\right]$

$$
\operatorname{Tr}=\left\{u(t): u \in M R\left(0, \tau^{\prime}\right)\right\} .
$$

Note that $\operatorname{Tr}$ is isomorphic to the real interpolation space $(X, D)_{1 / p *, p}$, where $1 / p *+$ $1 / p=1$ (see [18], Chapter 1 for more details). Moreover,

$$
M R_{p}(0, \tau) \underset{d}{\hookrightarrow} C([0, \tau] ; T r)
$$

The two following lemmas will be used in the sequel.

Lemma 2.3. Let $A_{n}:[0, \tau] \rightarrow \mathscr{L}(D, X)$ be a sequence of strongly measurable and bounded functions such that $\left\|A_{n}(t) x\right\| \leqslant c\|x\|_{D}$ for all $n \in \mathbb{N}, x \in D$ and $t$-a.e. for some constant $c>0$. Assume that for all $x \in D$ we have $A_{n}(t) x \rightarrow A(t) x$ $t$-a.e. on $[0, \tau]$ as $n \rightarrow \infty$. Then $A_{n}(\cdot) w_{n}(\cdot) \rightarrow A(\cdot) w(\cdot)$ in $L^{p}(0, \tau ; X)$ as $n \rightarrow \infty$ if $w_{n} \in L^{p}(0, \tau ; D)$ are such that $w_{n} \rightarrow w$ in $L^{p}(0, \tau ; D)$.

Proof. Let $A_{n}:[0, \tau] \rightarrow \mathscr{L}(D, X)(n=0,1,2, \ldots)$ be strongly measurable and bounded with $\left\|A_{n}(t) x\right\| \leqslant c\|x\|_{D}(x \in D, n \in \mathbb{N})$. Let $x \in D$ and let $\Omega$ be a measurable subset of $[0, \tau]$. We set $w=x \otimes 1_{\Omega}$. Then $\left\|\mathscr{A}_{n} w-\mathscr{A} w\right\|_{p}^{p}=$ $\int_{\Omega}\left\|A_{n}(t) x-A(t) x\right\|^{p} \mathrm{~d} t \rightarrow 0$ as $n \rightarrow \infty$ by Lebesgue's Theorem. It follows that $\left\|\mathscr{A}_{n} w-\mathscr{A} w\right\|_{p}$ as $n \rightarrow \infty$ for all $\omega \in L^{p}(0, \tau ; D)$. Let now $\left(\omega_{n}\right)_{n \in \mathbb{N}} \subset L^{p}(0, \tau ; D)$ be such that $w_{n} \rightarrow w$ in $L^{p}(0, \tau ; D)$. Then

$$
\left\|\mathscr{A}_{n} \omega_{n}-\mathscr{A} \omega\right\|_{p} \leqslant c\left\|\omega_{n}-\omega\right\|_{p}+\left\|\mathscr{A}_{n} \omega-\mathscr{A} \omega\right\|_{p}
$$

and the statement follows.

Lemma 2.4. Let $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ be a bounded and strongly Bochner measurable function. Assume that there exists a sequence $A_{n}:[0, \tau] \rightarrow \mathscr{L}(D, X)$, $n \in \mathbb{N}$, of strongly measurable functions such that
(i) $A_{n} \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ for all $n \in \mathbb{N}$,
(ii) for each $x \in D$ one has $\left\|A_{n}(t) x-A(t) x\right\| \rightarrow 0$ as $n \rightarrow \infty$ a.e.,
(iii) $\sup _{n}\left\|A_{n}(t) x\right\| \leqslant c\|x\|_{D}$ a.e. on $[0, \tau]$ for some constant $c>0$ and all $x \in D$.

Assume that for each $[a, b] \subset[0, \tau]$ and for each $f \in L^{p}(a, b ; X)$ the unique solution $u_{n}$ in $M R_{p}(a, b)$ of

$$
\dot{u}_{n}(t)+A_{n}(t) u_{n}(t)=f(t) \quad t \text {-a.e. on }[a, b], \quad u_{n}(a)=0
$$

converges in $M R_{p}(a, b)$ as $n \rightarrow \infty$. Then $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$. Moreover, for each $[a, b] \subset[0, \tau]$ the limit $u:=\lim _{n \rightarrow \infty} u_{n}$ is the unique solution of the problem $\operatorname{CP}(a, b)$.

Proof. Let $[a, b] \subset[0, \tau]$ and $f \in L^{p}(a, b ; X)$.
Existence: Let $u_{n}$ be the unique solution in $M R_{p}(a, b)$ of

$$
\dot{u}_{n}(t)+A_{n}(t) u_{n}(t)=f(t) \quad t \text {-a.e. on }[a, b], u_{n}(a)=0 .
$$

Let $u \in M R_{p}(a, b)$ such that $u_{n} \rightarrow u$ in $M R_{p}(a, b)$ as $n \rightarrow \infty$. Hence $\dot{u}_{n} \rightarrow \dot{u}$ and by Lemma 2.3, $A_{n} u_{n} \rightarrow A u$ in $L^{p}(a, b ; X)$ as $n \rightarrow \infty$. It follows that

$$
\begin{equation*}
\dot{u}(t)+A(t) u(t)=f(t) \quad t \text {-a.e. on }[a, b], u(a)=0 \text {. } \tag{2.4}
\end{equation*}
$$

Uniqueness: Since $\left(\mathscr{A}_{n}+\mathscr{B}\right)^{-1} f=u_{n}$ converges in $M R_{p}(a, b)$ as $n \rightarrow \infty$ to some solution $u$ of (2.4), it follows from the principle of uniform boundedness that

$$
M:=\sup _{n \geqslant 0}\left\|\left(\mathscr{A}_{n}+\mathscr{B}\right)^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X), M R_{p}(a, b)\right)}<\infty .
$$

Let $v \in M R_{p}(a, b)$ be such that

$$
\dot{v}(t)+A(t) v(t)=0 \quad t \text {-a.e. on }[a, b], v(a)=0 .
$$

Since $v=\left(\mathscr{A}_{n}+\mathscr{B}\right)^{-1}\left(\mathscr{A}_{n}+\mathscr{B}\right) v$, then $\|v\|_{M R} \leqslant M\left\|\left(\mathscr{A}_{n}+\mathscr{B}\right) v\right\|_{L^{p}(a, b ; X)}$. Letting $n \rightarrow \infty$ and using Lemma 2.3 we obtain $v=0$.

## 3. Integrability

Let $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ be strongly Bochner measurable. We want to characterize $L^{p}$-maximal regularity under some additional regularity assumptions on $A$.

If $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ is independent of $t$, the problem $\mathrm{CP}(a, b)$ being an autonomous Cauchy problem, then $-A$ seen as an unbounded operator on $X$ with domain $D$ generates an analytic $C_{0}$-semigroup $(T(s))_{s \geqslant 0}$ on $X$ [6]. Hence $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ if and only if for every $f \in L^{p}(0, \tau ; X)$ the function

$$
u(t):=\int_{0}^{t} T(t-r) f(r) \mathrm{d} r, \quad 0 \leqslant t \leqslant \tau
$$

belongs to $M R_{p}(0, \tau)$ and is the unique solution of the problem $\mathrm{CP}(0, \tau)$.
The case when $A$ is a step function is also easy to understand. Let $\Lambda=\lambda_{0}<\lambda_{1}<$ $\ldots<\lambda_{n+1}$ be a subdivision of $[0, \tau]$. Consider $A_{k} \in \mathscr{L}(D, X)$ for $k=0,1, \ldots, n$ and let $A$ be given by $A(t)=A_{\Lambda}(t):=A_{k}$ for $\lambda_{k} \leqslant t<\lambda_{k+1}$ and $A(\tau)=A_{\Lambda}(\tau):=A_{n}$. Choosing $f$ with support in $\left[\lambda_{k}, \lambda_{k+1}\right.$ ), we obtain that $L^{p}$-maximal regularity of each $A_{k}$ is a necessary condition on $A$ to have $L^{p}$-maximal regularity. This condition is also sufficient. In fact, assume that each $A_{k} \in \mathscr{M} \mathscr{R}$ and let $\left(T_{k}(s)\right)_{s \geqslant 0}$ denote the $C_{0}$-semigroup on $X$ generated by $-A_{k}$ (with domain $D$ ) for $k=0,1, \ldots, n$. For each interval $[a, b] \subset[0, \tau]$ such that $\lambda_{m-1} \leqslant a<\lambda_{m}<\ldots<\lambda_{l-1} \leqslant b<\lambda_{l}$ we define the operators $P_{\Lambda}(a, b) \in \mathscr{L}(X)$ by

$$
\begin{equation*}
P_{\Lambda}(a, b)=T_{l}\left(b-\lambda_{l-1}\right) T_{l-1}\left(\lambda_{l-1}-\lambda_{l-2}\right) \ldots T_{m+1}\left(\lambda_{m+1}-\lambda_{m}\right) T_{m}\left(\lambda_{m}-a\right), \tag{3.1}
\end{equation*}
$$

and for $\lambda_{l-1} \leqslant a \leqslant b<\lambda_{l}$ by

$$
\begin{equation*}
P_{\Lambda}(a, b)=T_{l}(b-a) . \tag{3.2}
\end{equation*}
$$

It is easy to see that $(a, b) \mapsto P_{\Lambda}(a, b)$ is strongly continuous on $X$ for $0 \leqslant a \leqslant b \leqslant \tau$. Moreover, for every $f \in L^{p}(a, b ; X)$ the function

$$
\begin{equation*}
u_{\Lambda}(t):=\int_{a}^{t} P_{\Lambda}(r, t) f(r) \mathrm{d} r \tag{3.3}
\end{equation*}
$$

belongs to $M R_{p}(a, b)$ and is the unique solution of problem

$$
\mathrm{CP}_{\Lambda}(a, b) \begin{cases}\dot{v}(t)+A_{\Lambda}(t) v(t)=f(t) \quad t \text {-a.e. on }[a, b] \\ v(a)=0\end{cases}
$$

Note also that, for all $x \in \operatorname{Tr}$ and $f \in L^{p}(a, b, X)$ the function $v_{\Lambda}(t)=P_{\Lambda}(a, t) x+$ $\int_{a}^{t} P_{\Lambda}(r, t) f(r) \mathrm{d} r$ belongs to $M R_{p}(a, b)$ and is the unique solution of the initial value problem

$$
\mathrm{CP}_{\Lambda}(a, b, x)\left\{\begin{array}{l}
\dot{v}(t)+A_{\Lambda}(t) v(t)=f(t) \quad t \text {-a.e. on }[a, b], \\
v(a)=x
\end{array}\right.
$$

The product given by (3.1)-(3.2), and also the existence of a limit of this product as $|\Lambda|$ converges to 0 uniformly on $[a, b] \subset[0, T]$, was studied in our work [13]. This leads to a theory of integral product, comparable to that of the classical Riemann integral. The notion of product integral has been introduced by Vito Volterra at the end of the 19th century. We refer to Antonín Slavík [21] and the reference therein for a discussion of the work of V. Volterra and for more details on product integration theory.

Consider now the general case where $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ is bounded and strongly measurable. We want to approximate $A$ by step functions as follows:

Let $\Lambda:=\lambda_{0}<\lambda_{1}<\ldots<\lambda_{n+1}$ be a subdivision of $[0, \tau]$ and $A_{\Lambda}:[0, \tau] \rightarrow$ $\mathscr{L}(D, X)$ be defined by $A_{\Lambda}(t):=A_{k}$ for $\lambda_{k} \leqslant t<\lambda_{k+1}$ and $A_{\Lambda}(\tau):=A_{n}$, where $A_{k}$ is given by

$$
\begin{equation*}
A_{k} x:=\frac{1}{\lambda_{k+1}-\lambda_{k}} \int_{\lambda_{k}}^{\lambda_{k+1}} A(r) x \mathrm{~d} r \quad(x \in D, k=0,1, \ldots, n) . \tag{3.4}
\end{equation*}
$$

The following lemma says that $A_{\Lambda}$ converges strongly and almost everywhere to $A$ as $|\Lambda| \rightarrow 0$.

Lemma 3.1. Let $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ be bounded and strongly measurable. Then for all $x \in D$ we have $A_{\Lambda}(t) x \rightarrow A(t) x$ in $X$ as $|\Lambda| \rightarrow 0 t$-a.e.

Proof. Let $C \geqslant 0$ be such that $\|A(t) x\|_{X} \leqslant C\|x\|_{D}$ for all $x \in D$ and for almost every $t \in[0, \tau]$. Let $\Lambda$ be any subdivision of $[0, \tau]$ and $A_{k}$ be given by (3.4)
for $k=0,1, \ldots n$. We have $\left\|A_{k} x\right\|_{X} \leqslant C\|x\|_{D}$ for all $x \in D$. Let $t$ be any Lebesgue point of $A(\cdot) x$. Let $k \in\{0,1, \ldots, n\}$ be such that $t \in\left[\lambda_{k}, \lambda_{k+1}\right)$. Then

$$
\begin{aligned}
A_{\Lambda}(t) x & -A(t) x=\frac{1}{\lambda_{k+1}-\lambda_{k}} \int_{\lambda_{k}}^{\lambda_{k+1}}(A(r) x-A(t) x) \mathrm{d} r \\
= & \frac{1}{\lambda_{k+1}-\lambda_{k}} \int_{\lambda_{k}}^{t}(A(r) x-A(t) x) \mathrm{d} r+\frac{1}{\lambda_{k+1}-\lambda_{k}} \int_{t}^{\lambda_{k+1}}(A(r) x-A(t) x) \mathrm{d} r \\
= & \frac{t-\lambda_{k}}{\lambda_{k+1}-\lambda_{k}} \frac{1}{t-\lambda_{k}} \int_{\lambda_{k}}^{t}(A(r) x-A(t) x) \mathrm{d} r \\
\quad & +\frac{\lambda_{k+1}-t}{\lambda_{k+1}-\lambda_{k}} \frac{1}{\lambda_{k+1}-t} \int_{t}^{\lambda_{k+1}}(A(r) x-A(t) x) \mathrm{d} r
\end{aligned}
$$

Using [3, Proposition 1.2.2, page 16] we obtain that $A_{\Lambda}(t) x-A(t) x \rightarrow 0$ as $|\Lambda| \rightarrow 0$. The result follows since almost all points of $[0, \tau]$ are Lebesgue points of $A(\cdot) x$.

In order to prove results on the convergence of the solutions $u_{\Lambda}$ of $\mathrm{CP}_{\Lambda}(0, \tau)$ we need more regularity on $A$.

Recall that the function $A$ is relatively continuous (in the sense of [7, Definition 2.5]) if for each $t \in[0, T]$ and all $\varepsilon>0$ there exist $\delta>0, \eta \geqslant 0$ such that for all $s \in[0, T],|t-s| \leqslant \delta$ implies that

$$
\|A(t) x-A(s) x\| \leqslant \varepsilon\|x\|_{D}+\eta\|x\| \quad \text { for } x \in D
$$

The relative continuity on the compact interval $[0, \tau]$ is equivalent to uniform relative continuity, that is, for every $\varepsilon>0$ there exist $\delta>0$ and $\eta \geqslant 0$ such that for all $x \in D$ and for all $t, s \in[0, T]$ one has

$$
\|A(t) x-A(s) x\| \leqslant \varepsilon\|x\|_{D}+\eta\|x\|
$$

whenever $|t-s| \leqslant \delta$. If $A$ is relatively continuous then $A$ is bounded (see [7, Remark 2.6]).

Next we give some sufficient and necessary conditions for $L^{p}$-maximal regularity. This is based on the following definition.

Definition 3.2. A function $A:[0, \tau] \mapsto \mathscr{L}(D, X)$ is called relatively p-approximable if for all $\varepsilon>0$ there exist $\delta>0, \eta \geqslant 0$ such that for all $f \in L^{p}(0, \tau ; D)$ and for all subdivisions $\Lambda$ of $[0, \tau],|\Lambda| \leqslant \delta$ implies that

$$
\begin{equation*}
\left\|\mathscr{A}_{\Lambda} f-\mathscr{A} f\right\|_{L^{p}(0, \tau ; D)} \leqslant \varepsilon\|f\|_{L^{p}(0, \tau ; D)}+\eta\|f\|_{L^{p}(0, \tau ; X)} . \tag{3.5}
\end{equation*}
$$

The relative $p$-approximability is weaker than relative continuity. Indeed each relatively continuous function $A$ is relatively $p$-approximable. The converse is not true, a counterexample is given by step functions.

Proposition 3.3. Assume that $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ is relatively continuous. Then $A$ is relatively $p$-approximable.

Proof. Let $\varepsilon>0$. By the relative continuity there exist $\delta \geqslant 0$ and $\eta \geqslant 0$ such that $\left|t-t^{\prime}\right| \leqslant \delta$ implies $\left\|A(t) x-A\left(t^{\prime}\right) x\right\| \leqslant \varepsilon\|x\|_{D}+\eta\|x\|_{X}(x \in D)$. Let $\Lambda$ be a subdivision of $[0, \tau]$ with $|\Lambda|<\delta$ and let $t \in\left[\lambda_{k}, \lambda_{k+1}\right)$. Since

$$
\begin{aligned}
\left\|A_{\Lambda}(t) f(t)-A(t) f(t)\right\|_{X} & =\int_{\lambda_{k}}^{\lambda_{k+1}}\|A(r) f(t)-A(t) f(t)\|_{X} \frac{\mathrm{~d} r}{\lambda_{k+1}-\lambda_{k}} \\
& \leqslant \varepsilon\|f(t)\|_{D}+\eta\|f(t)\|_{X}
\end{aligned}
$$

it follows that $\left\|\mathscr{A}_{\Lambda} f-\mathscr{A} f\right\|_{L^{p}(0, \tau ; D)} \leqslant \varepsilon\|f\|_{L^{p}(0, \tau ; D)}+\eta\|f\|_{L^{p}(0, \tau ; X)}$.

Proposition 3.4. Let $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ be strongly measurable and relatively $p$-approximable. Assume that $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$. Then there exists $\delta_{0}>0$ such that for each subdivision $\Lambda$ of $[0, \tau]$ with $|\Lambda| \leqslant \delta_{0}$ we have $A_{\Lambda} \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$.

Proof. According to point (1) of Proposition 2.2, it suffices to prove the proposition for $\varrho+A_{\Lambda}$ for some $\varrho \geqslant 0$. Let $M(A)$ be the constant from Proposition 2.2. For $\varepsilon_{0}=1 /[2 M(A)]$, since $A(\cdot)$ is relatively $p$-approximable, there exist $\delta_{0}>0$ and $\eta_{0} \geqslant 0$ such that $|\Lambda| \leqslant \delta_{0}$ implies that

$$
\left\|\mathscr{A}_{\Lambda} f-\mathscr{A} f\right\|_{L^{p}(0, \tau ; D)} \leqslant \varepsilon_{0}\|f\|_{L^{p}(0, \tau ; D)}+\eta_{0}\|f\|_{L^{p}(0, \tau ; X)}
$$

for all $f \in L^{p}(0, \tau ; D)$. Let $\Lambda$ be a subdivision of $[0, \tau]$ such that $|\Lambda| \leqslant \delta_{0}$ and let $f \in L^{p}(0, \tau ; X)$. Then

$$
\begin{aligned}
\|\left(\mathscr{A}_{\Lambda}-\mathscr{A}\right) & (\varrho+\mathscr{A}+\mathscr{B})^{-1} f \|_{L^{p}(0, \tau ; X)} \\
& \leqslant \frac{1}{2 M(A)}\left\|(\varrho+\mathscr{A}+\mathscr{B})^{-1} f\right\|_{L^{p}(0, \tau ; D)}+\eta_{0}\left\|(\varrho+\mathscr{A}+\mathscr{B})^{-1} f\right\|_{L^{p}(0, \tau ; X)} \\
& \leqslant \frac{1}{2}\|f\|_{L^{p}(0, \tau ; X)}+\frac{\eta_{0} M(A)}{\varrho^{1 / p}}\|f\|_{L^{p}(0, \tau ; X)} .
\end{aligned}
$$

Thus, for $\varrho \geqslant \varrho_{0}:=\left(4 M(A) \eta_{0}\right)^{p}$ we have $\left\|\left(\mathscr{A}_{\Lambda}-\mathscr{A}\right)(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(0, \tau ; X)\right)} \leqslant$ $3 / 4$. Therefore, $\left(\varrho+\mathscr{A}_{\Lambda}+\mathscr{B}\right)$ is invertible whenever $|\Lambda| \leqslant \delta_{0}$ and $\varrho \geqslant \varrho_{0}$.

The main result of this section is the following.

Theorem 3.5. Let $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ be strongly measurable and relatively $p$-approximable. Then the following assertions are equivalent.
(i) $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$.
(ii) There exists $\delta_{0}>0$ such that $A_{\Lambda} \in \mathscr{M}_{\mathscr{R}_{p}}(0, \tau)$ for all subdivisions $\Lambda$ of $[0, \tau]$ such that $|\Lambda| \leqslant \delta_{0}$ and for each $[a, b] \subset[0, \tau]$ the solution $u_{\Lambda}$ of $\mathrm{CP}_{\Lambda}(a, b)$, given by (3.3), converges in $M R_{p}(a, b)$ as $|\Lambda| \rightarrow 0$.

Proof. (i) $\Longrightarrow$ (ii) Let $\delta_{0}>0$ and $\varrho=\varrho_{0}$ be as in the proof of Proposition 3.4. Let $\Lambda$ and $\Gamma$ be two subdivisions of $[0, \tau]$ such that $|\Lambda|,|\Gamma| \leqslant \delta_{0}$. Let $[a, b] \subset[0, \tau]$. We have $\left\|\left(\mathscr{A}_{\Lambda}-\mathscr{A}\right)(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \leqslant 3 / 4$. Hence

$$
\left(\varrho+\mathscr{A}_{\Lambda}+\mathscr{B}\right)^{-1}=(\varrho+\mathscr{A}+\mathscr{B})^{-1} \sum_{k=0}^{\infty}\left(\left(\mathscr{A}_{\Lambda}-\mathscr{A}\right)(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right)^{k} .
$$

The same is also true if we replace $\Lambda$ by $\Gamma$. Let now $\varepsilon>0$ and $f \in L^{p}(a, b ; X)$. Let $n_{0} \in \mathbb{N}$ be such that

$$
\begin{aligned}
&\left\|\sum_{k=n_{0}+1}^{\infty}\left(\left(\mathscr{A}_{\Lambda}-\mathscr{A}\right)(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right)^{k}-\sum_{k=n_{0}+1}^{\infty}\left(\left(\mathscr{A}_{\Gamma}-\mathscr{A}\right)(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right)^{k}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \\
& \leqslant \frac{\varepsilon}{2 M(A)} .
\end{aligned}
$$

We set $I_{k, \Lambda}:=\left(\left(\mathscr{A}_{\Lambda}-\mathscr{A}\right)(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right)^{k}$ and $I_{k, \Gamma}:=\left(\left(\mathscr{A}_{\Gamma}-\mathscr{A}\right)(\varrho+\mathscr{A}+\mathscr{B})^{-1}\right)^{k}$ for $k=0,1, \ldots, n_{0}$.

By Lemma 3.1 we conclude that $I_{1, \Lambda} f-I_{1, \Gamma} f=\left(\mathscr{A}_{\Lambda}-\mathscr{A}_{\Gamma}\right)(\varrho+\mathscr{A}+\mathscr{B})^{-1} f$ converges to 0 on $L^{p}(a, b ; X)$ as $|\Lambda|,|\Gamma| \rightarrow 0$. It is not difficult to deduce that also all $I_{k, \Lambda} f-I_{k, \Gamma} f$ converge to 0 as $|\Lambda|,|\Gamma| \rightarrow 0$.

Then let $\delta^{\prime}>0$ be such that

$$
\begin{aligned}
&|\Lambda|,|\Gamma| \leqslant \delta^{\prime} \Longrightarrow\left\|I_{k, \Lambda} f-I_{k, \Gamma} f\right\|_{L^{p}(a, b ; X)} \leqslant \varepsilon\left(\left(n_{0}+1\right) M(A)\right)^{-1} \\
& \text { for every } 0 \leqslant k \leqslant n_{0} .
\end{aligned}
$$

We deduce that $\left\|u_{\Lambda}-u_{\Gamma}\right\|_{M R} \leqslant \varepsilon / 2\|f\|+\varepsilon / 2$ whenever $|\Lambda|,|\Gamma| \leqslant \min \left\{\delta_{0}, \delta^{\prime}\right\}$.
The implication $(\mathrm{ii}) \Longrightarrow(\mathrm{i})$ is given by Lemma 2.4.

## 4. Stability and maximal Regularity

In this section we give a stability result for the $L_{p}$-maximal regularity.
Throughout this section we assume that $A:[0, \tau] \mapsto \mathscr{L}(D, X)$ is strongly measurable and relatively continuous and $A(t) \in \mathscr{M} \mathscr{R}$ for all $t \in[0, \tau]$. We assume also that there exists an approximation $A_{n}:[0, \tau] \mapsto \mathscr{L}(D, X)$ (strongly measurable) of $A$ with the following properties.
$\left(\mathrm{H}_{1}\right)$ There exists $C>0$ such that $\left\|A_{n}(t)\right\|_{\mathscr{L}(D, X)} \leqslant C$ for all $t \in[0, \tau]$ and $n \in \mathbb{N}$.
$\left(\mathrm{H}_{2}\right)$ For each $x \in D$ one has $A_{n}(t) x \rightarrow A(t) x$ as $n \rightarrow \infty$ in $X t$-a.e. on $[0, \tau]$.
$\left(\mathrm{H}_{3}\right)$ For every $\varepsilon>0$ there exist $\eta \geqslant 0, n_{0} \in \mathbb{N}$ such that for all $x \in D, n \geqslant n_{0}, t \in$ $[0, \tau]$ one has

$$
\left\|A_{n}(t) x-A(t) x\right\| \leqslant \varepsilon\|x\|_{D}+\eta\|x\| .
$$

$\left(\mathrm{H}_{4}\right) A_{n} \in \mathscr{M} \mathscr{R}(0, \tau)$ for all $n \in \mathbb{N}$.
We have seen in Lemma 2.4 that if there exists a sequence $A_{n}$ satisfying the assumptions $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$ then $A \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$ provided that for each $[a, b] \subset[0, \tau]$ and for every $f \in L^{p}(a, b ; X)$ the unique solution $u_{n}$ in $M R_{p}(a, b)$ of

$$
\dot{u}_{n}(t)+A_{n}(t) u_{n}(t)=f(t) \quad t \text {-a.e. on }[a, b], u_{n}(a)=0
$$

converges in $M R_{p}(a, b)$ as $n \rightarrow \infty$. The main result is Theorem 4.5 which says, in particular, that this convergence holds if $A$ is relatively continuous. We also show that $A_{\Lambda}:[0, \tau] \mapsto \mathscr{L}(D, X)$ defined in the previous section satisfies $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$ as $|\Lambda| \rightarrow 0$ provided that $A$ is relatively continuous. This gives an alternative proof of Theorem 2.7 in [7].

We begin with the following useful auxiliary result. For each $t_{0} \in[a, b] \subset[0, \tau]$ we denote by $\mathscr{A}\left(t_{0}\right)=\mathscr{A}\left(t_{0}\right)_{a, b}$ the unbounded operator on $L^{p}(a, b ; X)$ with domain $L^{p}(a, b ; D)$ defined by $\left(\mathscr{A}\left(t_{0}\right) f\right)(s)=A\left(t_{0}\right) f(s) s$-a.e.

Lemma 4.1. Let $A:[0, \tau] \mapsto \mathscr{L}(D, X)$ be strongly measurable and relatively continuous. Assume that $A(t) \in \mathscr{M} \mathscr{R}$ for all $t \in[0, \tau]$. Then there exist $M \geqslant 0$, $\varrho_{0} \geqslant 0$ independent of $t \in[0, \tau]$ such that

$$
\begin{aligned}
&\left\|(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X), M R_{p}(a, b)\right)} \leqslant M \\
& \text { and } \quad\left\|(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \leqslant \frac{M}{1+\varrho},
\end{aligned}
$$

for all intervals $[a, b] \subset[0, \tau]$ and all $\varrho \geqslant \varrho_{0}$.

Proof. a) Let $[a, b] \subset[0, \tau]$. For each $t \in[a, b]$ there exist $\eta_{t} \geqslant 0, \delta_{t}>0$ such that for all $s \in\left[t-\delta_{t}, t+\delta_{t}\right]$ we have

$$
\|A(t) x-A(s) x\| \leqslant \frac{1}{2 M(A(t))}\|x\|_{D}+\delta_{t}\|x\| \quad(x \in D)
$$

where $M(A(t))$ is the constant in (1.1) (see Section 1). By compactness we find $t_{i} \in[a, b]$ such that $[a, b] \subset \bigcup_{i=0}^{n}\left[t_{i}-\delta_{t_{i}}, t_{i}+\delta_{t_{i}}\right]$. We may assume that this covering is minimal. Thus $t_{i} \neq t_{j}$ for $i \neq j$. We arrange then $t_{i}$ in such way that $a \leqslant t_{0}<t_{1}<$ $t_{2}<\ldots<t_{n} \leqslant b$. Thus

$$
t_{i}-\delta_{t_{i}} \leqslant t_{i+1}-\delta_{t_{i+1}} \leqslant t_{i}+\delta_{t_{i}} \leqslant t_{i+1}+\delta_{t_{i+1}}
$$

Setting $\tau_{0}=a, \tau_{i}=\max \left\{t_{i-1}, t_{i}-\delta_{i}\right\}, i=1, \ldots, n-1$ and $\tau_{n}=b$ we obtain that $\tau_{0}<\tau_{1}<\ldots<\tau_{n}$ form a subdivision of $[0, \tau]$ with $t_{i} \in\left[\tau_{i}, \tau_{i+1}\right] \subset\left[t_{i}-\delta_{t_{i}}, t_{i}+\delta_{t_{i}}\right]$ and for all $t \in\left[\tau_{i}, \tau_{i+1}\right]$.

$$
\left\|A(t) x-A\left(t_{i}\right) x\right\| \leqslant \frac{1}{2 M\left(A\left(t_{i}\right)\right)}\|x\|_{D}+\delta_{t_{i}}\|x\| \quad(x \in D, i=0,1, \ldots, n)
$$

b) Let $[a, b] \in[0, \tau]$ and let $f \in L^{p}(a, b ; X)$. Let $t \in[a, b]$ and let $i$ be such that $t \in\left[\tau_{i}, \tau_{i+1}\right]$. It follows from step a) that

$$
\begin{aligned}
&\left\|\left(\mathscr{A}(t)-\mathscr{A}\left(t_{i}\right)\right)\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1} f\right\|_{L^{p}(a, b ; X)} \\
& \leqslant \frac{1}{2 M\left(A\left(t_{i}\right)\right)}\left\|\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1} f\right\|_{L^{p}(a, b ; D)}+\eta_{t_{i}}\left\|\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1} f\right\|_{L^{p}(a, b ; X)} \\
& \leqslant \frac{1}{2 M\left(A\left(t_{i}\right)\right)}\left\|\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1} f\right\|_{M R_{p}(a, b)}+\eta_{t_{i}}\left\|\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1} f\right\|_{L^{p}(a, b ; X)} \\
& \leqslant \frac{1}{2}\|f\|_{L^{p}(a, b ; X)}+\frac{\eta_{t_{i}} M\left(A\left(t_{i}\right)\right)}{1+\varrho}\|f\|_{L^{p}(a, b ; X)}
\end{aligned}
$$

for all $\varrho \geqslant 0$. Hence we find $\varrho_{0} \geqslant 0$ such that for all $\varrho \geqslant \varrho_{0}$ we have $\|(\mathscr{A}(t)-$ $\left.\mathscr{A}\left(t_{i}\right)\right)\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1} \|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \leqslant 3 / 4$. Thus,

$$
\begin{aligned}
(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1} & =\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}+\mathscr{A}(t)-\mathscr{A}\left(t_{i}\right)\right)^{-1} \\
& =\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1}\left(I+\left(\mathscr{A}(t)-\mathscr{A}\left(t_{i}\right)\right)\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1}\right)^{-1} .
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
\|(\varrho+\mathscr{A}( & t) \\
\leqslant & \mathscr{B})^{-1} \|_{\mathscr{L}\left(L^{p}(a, b ; X), M R_{p}(a, b)\right)} \\
\leqslant & \left\|(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X), M R_{p}(a, b)\right)} \\
& \times\left\|\left(I+\left(\mathscr{A}(t)-\mathscr{A}\left(t_{i}\right)\right)\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1}\right)^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \\
\leqslant & \left.\sup _{j=1, \ldots, n} M\left(A\left(t_{j}\right)\right) \sum_{k=0}^{\infty}\left\|\left(\mathscr{A}(t)-\mathscr{A}\left(t_{i}\right)\right)\left(\varrho+\mathscr{A}\left(t_{i}\right)+\mathscr{B}\right)^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)}^{k}\right) \\
\leqslant & M:=4 \sup _{j=1, \ldots, n} M\left(A\left(t_{j}\right)\right) .
\end{aligned}
$$

This completes the proof.
We now show that the problems $\mathrm{CP}(a, b)$ are well posed in $L^{p}(a, b ; X)$ for all subintervals $[a, b]$ which are small enough, provided $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$ hold and $A$ is relatively continuous. For the proof we need the following Lemma.

Lemma 4.2. Assume that the family $A_{n}, n \in \mathbb{N}$ satisfies the condition $\left(\mathrm{H}_{3}\right)$. Then there exist $\delta>0, \varrho_{1} \geqslant 0$ and $n_{0} \in \mathbb{N}$ such that for each $[a, b] \subset[0, \tau],|b-a| \leqslant \delta$ implies that

$$
\left\|\left(\mathscr{A}_{n}-\mathscr{A}(t)\right)(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \leqslant 3 / 4,
$$

for all $t \in[a, b], n \geqslant n_{0}$ and all $\varrho \geqslant \varrho_{1}$.
Proof. Let $\varepsilon:=1 /(4 M)$, where $M$ is the constant from Lemma 4.1. By the assumption on $A$, there exist $\delta>0$ and $\eta_{1} \geqslant 0$ such that for all $s_{1}, s_{2} \in[0, \tau]$, $\left|s_{2}-s_{1}\right| \leqslant \delta$ implies

$$
\left\|A\left(s_{1}\right) x-A\left(s_{2}\right) x\right\| \leqslant \frac{1}{4 M}\|x\|_{D}+\eta_{1}\|x\| \quad(x \in D) .
$$

By the assumption $\left(\mathrm{H}_{3}\right)$ there exist $\eta_{2} \geqslant 0$ and $n_{0} \in \mathbb{N}$ such that for all $x \in D$, $n \geqslant n_{0}$ and $t \in[0, \tau]$ one has

$$
\left\|A_{n}(t) x-A(t) x\right\| \leqslant \frac{1}{4 M}\|x\|_{D}+\eta_{2}\|x\| \quad(x \in D)
$$

Let now $[a, b]$ be a subinterval of $[0, \tau]$ such that $|b-a| \leqslant \delta$. Let $f \in L^{p}(a, b ; X)$ and $\varrho \geqslant \varrho_{0}$ (with $\varrho_{0}$ from Lemma 4.1). Using Lemma 4.1 we obtain that for each
$t \in[a, b]$ and $n \geqslant n_{0}$

$$
\begin{aligned}
\|\left(\mathscr{A}_{n}-\right. & \mathscr{A}(t))(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1} f \|_{L^{p}(a, b ; X)} \\
= & \left(\int_{a}^{b}\left\|\left(A_{n}(s)-A(t)\right)\left((\varrho+\mathscr{A}(t)+\mathscr{B})^{-1} f\right)(s)\right\|_{X}^{p} \mathrm{~d} s\right)^{1 / p} \\
\leqslant & \left(\int _ { a } ^ { b } \left[\frac{1}{2 M}\left\|\left((\varrho+\mathscr{A}(t)+\mathscr{B})^{-1} f\right)(s)\right\|_{D}\right.\right. \\
& \left.\left.+\left(\eta_{2}+\eta_{1}\right)\left\|\left((\varrho+\mathscr{A}(t)+\mathscr{B})^{-1} f\right)(s)\right\|_{X}\right]^{p} \mathrm{~d} s\right)^{1 / p} \\
\leqslant & \frac{1}{2 M}\left\|(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1} f\right\|_{L^{p}(a, b ; D)}+\left(\eta_{2}+\eta_{1}\right)\left\|(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1} f\right\|_{L^{p}(a, b ; X)} \\
\leqslant & \frac{1}{2}\|f\|_{L^{p}(a, b ; X)}+\frac{\left(\eta_{1}+\eta_{2}\right) M}{\varrho+1}\|f\|_{L^{p}(a, b ; X)} .
\end{aligned}
$$

Hence for all $\varrho \geqslant \varrho_{1}:=\max \left\{\varrho_{0}, 4\left(\eta_{2}+\eta_{1}\right) M\right\}$ we have $\|\left(\mathscr{A}_{n}(\cdot)-\mathscr{A}(t)\right)(\varrho+\mathscr{A}(t)+$ $\mathscr{B})^{-1} \|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)} \leqslant 3 / 4$.

Theorem 4.3. Assume that the family $A_{n}, n \in \mathbb{N}$ satisfies the conditions $\left(\mathrm{H}_{1}\right)-$ $\left(\mathrm{H}_{4}\right)$. Then there exists $\eta>0$ such that for all $[a, b] \subset[0, \tau]$ with $|b-a|<\eta$ and all $f \in L^{p}(a, b ; X)$ the unique solution $u_{n}$ in $M R_{p}(a, b)$ of

$$
\begin{equation*}
\dot{u}_{n}(t)+A_{n}(t) u_{n}(t)=f(t) \quad t \text {-a.e. on }[a, b], \quad u_{n}(a)=0 \tag{4.1}
\end{equation*}
$$

converges in $M R_{p}(a, b)$ as $n \rightarrow \infty$ and $u:=\lim _{n \rightarrow \infty} u_{n}$ is the unique solution of $\mathrm{CP}(a, b)$.

Proof. We use the same idea as in the proof of Theorem 3.5. Let $\delta, \varrho_{1}$ and $n_{0}$ be the constants given by Lemma 4.2. According to Proposition 2.2 we can assume that $\varrho_{1}=0$. Let $[a, b] \subset[0, \tau]$ be such that $|b-a| \leqslant \delta$. Let $t_{0} \in[a, b]$ and $f \in L^{p}(a, b ; X)$ be fixed. Let $\varepsilon>0$ and $k_{0} \in \mathbb{N}$ be such that

$$
\begin{equation*}
\left\|\sum_{k=k_{0}+1}^{\infty}\left(\mathscr{A}_{n}-\mathscr{A}\left(t_{0}\right)\right)\left(\mathscr{A}\left(t_{0}\right)+\mathscr{B}\right)^{-1}\right\|_{\mathscr{L}\left(L^{p}(a, b ; X)\right)}^{k} \leqslant \frac{\varepsilon}{2 M} \tag{4.2}
\end{equation*}
$$

where $M$ is the constant in Lemma 4.1. We have the following equality

$$
\begin{equation*}
u_{n}=\left(\mathscr{A}_{n}+\mathscr{B}\right)^{-1} f=\left(\mathscr{A}\left(t_{0}\right)+\mathscr{B}\right)^{-1}\left(I+\left(\mathscr{A}_{n}-\mathscr{A}\left(t_{0}\right)\right)\left(\mathscr{A}\left(t_{0}\right)+\mathscr{B}\right)^{-1}\right)^{-1} \tag{4.3}
\end{equation*}
$$

For each $k \in\left\{0,1, \ldots, k_{0}\right\}$ and $n \in \mathbb{N}$ we set

$$
I_{k, n}:=\left(\left(\mathscr{A}_{n}-\mathscr{A}\left(t_{0}\right)\right)\left(\mathscr{A}\left(t_{0}\right)+\mathscr{B}\right)^{-1}\right)^{k} .
$$

By the hypothesis $\left(\mathrm{H}_{2}\right)$ we have $I_{1, n} f-I_{1, m} f=\left(\mathscr{A}_{n}-\mathscr{A}_{m}\right)\left(\mathscr{A}\left(t_{0}\right)+\mathscr{B}\right)^{-1} f$, and thus all $I_{n, k} f-I_{m, k} f$ converge to 0 on $L^{p}(a, b ; X)$ as $n, m \rightarrow \infty$. Let $N>0$ be such that

$$
\begin{equation*}
n, m \geqslant N \Longrightarrow\left\|I_{n, k} f-I_{m, k} f\right\|_{L^{p}(a, b ; X)} \leqslant \frac{\varepsilon}{\left(k_{0}+1\right) M} \quad \text { for every } 0 \leqslant k \leqslant n_{0} \tag{4.4}
\end{equation*}
$$

From (4.2), (4.3) and (4.4) we deduce that $\left(u_{n}\right)_{n \in \mathbb{N}}$ is a Cauchy sequence on the Banach space $M R_{p}(a, b)$. The last claim follows from Lemma 2.4.

We are now ready for the proof of our main results. Let $\delta$ be the constant given by Lemma 4.2 and $[a, b]$ be a subinterval of $[0, \tau]$ such that $|a-b| \leqslant \delta$. Then we have the following stability result.

Theorem 4.4. Assume that $A$ is relatively continuous and $A(t) \in \mathscr{M} \mathscr{R}$ for all $t \in[0, \tau]$. We also assume that the $A_{n}$ satisfy the hypothese $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$. Let $x_{n} \in \operatorname{Tr}$ and $f_{n} \in L^{p}(a, b ; X)$ be such that $x_{n} \rightarrow x$ in $\operatorname{Tr}$ and $f_{n} \rightarrow f$ in $L^{p}(a, b ; X)$. Then the solution $u_{n}$ of

$$
\begin{equation*}
\dot{u}_{n}(t)+A_{n}(t) u_{n}(t)=f_{n}(t) \quad \text { a.e. on }[a, b], \quad u_{n}(a)=x_{n} \tag{4.5}
\end{equation*}
$$

converges in $M R_{p}(a, b)$ and $u:=\lim _{n \rightarrow \infty} u_{n}$ is the unique solution of

$$
\begin{equation*}
\dot{u}(t)+A(t) u(t)=f(t) \quad \text { a.e. on }[a, b], \quad u(a)=x . \tag{4.6}
\end{equation*}
$$

Proof. (a) Let $f_{n} \in L^{p}(a, b ; X)$ be such that $f_{n} \rightarrow f$ in $L^{p}(a, b ; X)$. We have

$$
u_{n}=\left(\mathscr{A}_{n}+\mathscr{B}\right)^{-1} f_{n}=\left(\mathscr{A}_{n}+\mathscr{B}\right)^{-1}\left(f_{n}-f\right)+\left(\mathscr{A}_{n}+\mathscr{B}\right)^{-1} f
$$

Theorem 4.3 implies that the second term on the right-hand side of the above equality converges in $M R_{p}(a, b)$ to $(\mathscr{A}+\mathscr{B})^{-1} f$. Using the Banach-Steinhaus Theorem we obtain

$$
\lim _{n \rightarrow \infty}\left\|\left(\mathscr{A}_{n}+\mathscr{B}\right)^{-1} f_{n}-(\mathscr{A}+\mathscr{B})^{-1} f\right\|_{M R}=0
$$

(b) Now let $x_{n} \rightarrow x$ and $f_{n} \rightarrow f$, respectively, in $\operatorname{Tr}$ and in $L^{p}(a, b ; X)$. There exist $w_{n}, w \in M R_{p}(a, b)$ such that $w_{n}(a)=x_{n}, w(a)=x$ and $\lim _{n \rightarrow \infty}\left\|w_{n}-w\right\|_{M R}=0$. Let $u_{n} \in M R_{p}(a, b)$ be such that

$$
\dot{u}_{n}(t)+A_{n}(t) u_{n}(t)=f_{n}(t) \quad \text { a.e. on }[a, b], \quad u_{n}(a)=x_{n}
$$

There exists a unique $v_{n} \in M R_{p}(a, b)$ such that

$$
\dot{v}_{n}(t)+A_{n}(t) v_{n}(t)=-\dot{w}_{n}(t)-A_{n}(t) w_{n}(t)+f_{n}(t) \quad \text { a.e. on }[a, b], \quad v_{n}(a)=0
$$

By unique solvability we have $u_{n}=v_{n}+w_{n}$. The assumption $\left(\mathrm{H}_{2}\right)$ implies that $\dot{w}_{n}+A_{n} w_{n}+f_{n} \rightarrow \dot{w}+A w+f$ in $L^{p}(a, b ; X)$. Thus from (a) it follows that $v_{n} \rightarrow v$ in $M R_{p}(a, b)$ and $v$ is the unique solution in $M R_{p}(a, b)$ of

$$
\dot{v}(t)+A(t) v(t)=-\dot{w}(t)-A(t) w(t)+f(t) \quad \text { a.e. on }[a, b], \quad v(a)=0 .
$$

Thus $u_{n} \rightarrow u:=v+w$ in $M R_{p}(a, b)$ and

$$
\dot{u}(t)+A(t) u(t)=f(t) \quad \text { a.e. on }[a, b], \quad u(a)=x .
$$

The uniqueness follows from (a).
From Theorem 4.4 we deduce the following global stability result.

Theorem 4.5. Let $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ be strongly measurable and relatively continuous. Assume that $A(t) \in \mathscr{M} \mathscr{R}$ for all $t \in[0, \tau]$ and $A_{n}$ satisfy the hypothese $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$. Let $x_{n} \in \operatorname{Tr}$ and $f_{n} \in L^{p}(0, \tau ; X)$ be such that $x_{n} \rightarrow x$ in $\operatorname{Tr}$ and $f_{n} \rightarrow f$ in $L^{p}(0, \tau ; X)$. Then the unique solution $u_{n}$ of

$$
\begin{equation*}
\dot{u}_{n}(t)+A_{n}(t) u_{n}(t)=f_{n}(t) \quad \text { a.e. on }[0, \tau], \quad u_{n}(0)=x_{n} \tag{4.7}
\end{equation*}
$$

converges in $M R_{p}(0, \tau)$ and $u:=\lim _{n \rightarrow \infty} u_{n}$ is the unique solution of

$$
\begin{equation*}
\dot{u}(t)+A(t) u(t)=f(t) \quad \text { a.e. on }[0, \tau], \quad u(0)=x . \tag{4.8}
\end{equation*}
$$

Proof. Let $u_{n}$ be the solution of (4.7). From Theorem 4.4, $u_{n}$ converges in $M R_{p}(a, b)$ for all $[a, b] \subset[0, \tau]$ such that $|b-a| \leqslant \delta$. We put

$$
\tau_{1}:=\max \left\{0 \leqslant \tau^{\prime} \leqslant \tau, \text { such that } u_{n} \rightarrow u \text { in } M R\left(0, \tau^{\prime}\right)\right\} .
$$

Thus $\tau_{1} \geqslant \delta$. We show that $\tau_{1}=\tau$. Indeed, we assume by contradiction that $\tau_{1}<\tau$ and choose $\tau_{1}^{\prime}<\tau_{1}$ such that $\tau_{1}-\tau_{1}^{\prime} \leqslant \delta / 2$. Then $u_{n} \rightarrow u$ in $M R\left(0, \tau_{1}^{\prime}\right)$. On the other hand, $u_{n}$ coincides on the interval $\left[\tau_{1}^{\prime},\left(\tau_{1}^{\prime}+\delta\right) \wedge \tau\right]$ with the solution of

$$
\dot{u}(t)+A_{n}(t) u(t)=f_{n}(t) \quad \text { a.e. on }\left[\tau_{1}^{\prime},\left(\tau_{1}^{\prime}+\delta\right) \wedge \tau\right], \quad u\left(\tau_{1}^{\prime}\right)=u_{n}\left(\tau_{1}^{\prime}\right) \in \operatorname{Tr}
$$

which converges by Theorem 4.4 on $M R\left(\tau_{1}^{\prime},\left(\tau_{1}^{\prime}+\delta\right) \wedge \tau\right)$. Then $u_{n} \rightarrow u$ on $M R(0$, $\left.\left(\tau_{1}^{\prime}+\delta\right) \wedge \tau\right)$. Thus $\left(\tau_{1}^{\prime}+\delta\right) \wedge \tau \leqslant \tau_{1}$, which is a contradiction to the definition of $\tau_{1}$.

We now consider the approximation $A_{\Lambda}:[0, \tau] \mapsto \mathscr{L}(D, X)$ introduced in Section 2. We have proved in Lemma 3.1 and Proposition 3.3 that $A_{\Lambda}$ satisfies $\left(\mathrm{H}_{2}\right)$ and $\left(\mathrm{H}_{3}\right)$. Moreover, since $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ is relatively continuous, there exists $\delta>0$ such that the coefficients $A_{k}$ which are defined for all $k=0,1, \ldots, n$ by

$$
A_{k} x:=\frac{1}{\lambda_{k+1}-\lambda_{k}} \int_{\lambda_{k}}^{\lambda_{k+1}} A(r) x \mathrm{~d} r \quad(x \in D),
$$

belong to $\mathscr{M} \mathscr{R}$ provided $|\Lambda| \leqslant \delta$. Indeed, for $t \in\left[\lambda_{k}, \lambda_{k+1}\right]$

$$
\varrho+\mathscr{A}_{k}+\mathscr{B}=\left(I d+\left(\mathscr{A}_{k}-\mathscr{A}(t)\right)(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1}\right)(\varrho+\mathscr{A}(t)+\mathscr{B}) .
$$

By an analogous argument as in the proof of Lemma 4.2, we obtain that

$$
\left\|\left(\mathscr{A}_{k}-\mathscr{A}(t)\right)(\varrho+\mathscr{A}(t)+\mathscr{B})^{-1}\right\|_{\mathscr{L}\left(L^{p}(0, \tau ; X)\right)} \leqslant 3 / 4
$$

for all $\varrho \geqslant \varrho_{0}$ and $|\Lambda| \leqslant \delta$ for some $\varrho_{0} \geqslant 0$ and $\delta>0$. Thus $A_{k} \in \mathscr{M} \mathscr{R}, k=0,1, \ldots, n$. This is equivalent as proved in Section 3 to the fact that $A_{\Lambda} \in \mathscr{M} \mathscr{R}_{p}(0, \tau)$. Thus $A_{\Lambda}:[0, \tau] \mapsto \mathscr{L}(D, X)$ as defined above satisfies the hypothese $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$ for all subdivisions $\Lambda$ of $[0, \tau]$ such that $|\Lambda|<\delta$. We have thus proved the following.

Corollary 4.6. Assume that $A:[0, \tau] \rightarrow \mathscr{L}(D, X)$ is strongly measurable and relatively continuous and $A(t) \in \mathscr{M} \mathscr{R}$ for all $t \in[0, \tau]$. Then $A \in \mathscr{M} \mathscr{R}(0, \tau)$, and for each $[a, b] \subset[0, \tau]$ the unique solution $u$ in $\operatorname{MR}_{p}(a, b)$ of $\operatorname{CP}(a, b)$ satisfies

$$
\lim _{|\Lambda| \rightarrow 0}\left\|u-u_{\Lambda}\right\|_{M R}=0
$$

where $u_{\Lambda}$ is given by (3.3).

## 5. An example

Let $\Omega \subset \mathbb{R}^{n}$ be an open set such that $\partial \Omega$ is bounded and of class $C^{2}$. As example we consider the non-autonomous diffusion equation which is described in [7]

$$
\begin{cases}\partial_{t} u(t, x)-\mathscr{A}(t, x, D) u(t, x)=f(t, x) & \text { a.e. on }(0, \tau) \times \Omega,  \tag{5.1}\\ u(t)(x)=0 & \text { on }(0, \tau) \times \partial \Omega, \\ u(0, x)=u_{0}(x) & \text { a.e. on } \Omega,\end{cases}
$$

where $\mathscr{A}(t, x, D)$ is the partial differential operator defined by

$$
\begin{equation*}
\mathscr{A}(t, x, D) u(x):=\sum_{i, j=1}^{n} a_{i j}(t, x) \partial_{i} \partial_{j} u(x)+\sum_{i, j=1}^{n} b_{j}(t, x) \partial_{j} u(x)+b_{0}(t, x) u(x), \tag{5.2}
\end{equation*}
$$

such that $a_{i j} \in C([0, \tau] \times \bar{\Omega})$ for $i, j=1, \ldots, n$ is uniformly continuous, bounded and uniformly elliptic, i.e.

$$
\sum_{i, j=1}^{n} a_{i j}(t, x) \xi_{i} \xi_{j} \geqslant \beta|\xi|^{2}
$$

for some $\beta>0$ and all $\xi \in \mathbb{R}^{n}, x \in \bar{\Omega}, t \in[0, \tau]$, and $b_{j} \in L^{\infty}((0, \tau) \times \Omega)$ for $j=0,1, \ldots, n$.

Recall that if $X$ and $D$ are two Banach spaces and $Y$ an intermediate space such that $D \hookrightarrow Y \hookrightarrow X$ then we say that $Y$ is close to $X$ compared with $D$ if for each $\varepsilon>0$ there exists $\eta \geqslant 0$ such that $\|x\|_{Y} \leqslant \varepsilon\|x\|_{D}+\eta\|x\|_{X}, x \in D$ (see [7] for more details and several examples).

Let $p, q \in(1, \infty)$. Let $D:=W^{2, p}(\Omega) \cap W_{0}^{1, p}(\Omega)$. The space $W^{1, p}(\Omega)$ is close to $L^{p}(\Omega)$ compared with $W^{2, p}(\Omega)$. We deduce from [7, Theorem 2.10, Theorem 1.3] that $A:[0, \tau] \rightarrow\left(D, L^{p}(\Omega)\right)$ given by

$$
A(t) u:=-\sum_{i, j=1}^{n} a_{i, j}(t, x) \partial_{i} \partial_{j} u-\sum_{i, j=1}^{n} b_{j}(t, \cdot) \partial_{j} u-b_{0}(t, \cdot) u \quad(u \in D)
$$

is relatively continuous and $A(t) \in \mathscr{M} \mathscr{R}$ for all $t \in[0, \tau]$. Thus the problem (5.1) is stable in the sense of Theorem 4.5 for all initial data $u_{0} \in B_{p q}^{2 / q^{*}} \cap \check{B}_{p q}^{1 / q^{*}}(\Omega)$ (see [24] for the Besov spaces $B_{p q}^{2 / q^{*}}$ ). Moreover, the unique solution

$$
u \in C\left([0, \tau] ; B_{p q}^{2 / q^{*}} \cap B_{p q}^{1 / q^{*}}(\Omega)\right) \cap W^{1, q}\left(0, \tau ; L^{p}(\Omega)\right) \cap L^{q}\left(0, \tau ; W^{2, p} \cap W_{0}^{1, p}(\Omega)\right)
$$

of (5.1) can be explicitly approximated as follows:
Let $\Lambda:=\left(\lambda_{0}, \lambda_{1}, \ldots, \lambda_{m}\right)$ be a subdivision of $[0, \tau]$ and define

$$
\begin{aligned}
a_{i j}^{k}(\cdot) & :=\frac{1}{\lambda_{k+1}-\lambda_{k}} \int_{\lambda_{k}}^{\lambda_{k+1}} a_{i j}(r, \cdot) \mathrm{d} r \\
b_{j}^{k}(\cdot) & :=\frac{1}{\lambda_{k+1}-\lambda_{k}} \int_{\lambda_{k}}^{\lambda_{k+1}} b_{j}(r, \cdot) \mathrm{d} r, \quad \text { and } \\
b_{0}^{k}(\cdot) & :=\frac{1}{\lambda_{k+1}-\lambda_{k}} \int_{\lambda_{k}}^{\lambda_{k+1}} b_{0}(r, \cdot) \mathrm{d} r
\end{aligned}
$$

for $i, j=0,1, \ldots, n$ and $k=0,1, \ldots, m$. The coefficients $A_{k}$, introduced in Section 3, are then given in the situation of (5.2) as follows

$$
A_{k} u:=-\sum_{i, j=1}^{n} a_{i j}^{k}(\cdot) \partial_{i} \partial_{j} u \mathrm{~d} r-\sum_{j=1}^{n} b_{j}^{k}(\cdot) \partial_{j} u-b_{0}^{k}(\cdot) u \quad(u \in D) .
$$

Let $u_{\Lambda}$ be the unique solution in $W^{1, q}\left(0, \tau ; L^{p}(\Omega)\right) \cap L^{q}\left(0, \tau ; W^{2, p} \cap W_{0}^{1, p}(\Omega)\right)$ of the approximated problem

$$
\begin{cases}\partial_{t} u(t, x)-\mathscr{A}_{\Lambda}(t, x, D) u(t, x)=f(t, x) & \text { a.e. on }(0, \tau) \times \Omega \\ u(t)(x)=0 \text { on }(0, \tau) \times \partial \Omega, & \text { a.e. on } \Omega \\ u(0, x)=u_{0}(x) & \end{cases}
$$

Then $u_{\Lambda}$ is given explicitly by (3.3) where

$$
A_{\Lambda}(t):= \begin{cases}A_{k} & \text { for } \lambda_{k} \leqslant t<\lambda_{k+1}, k=0,1, \ldots, m \\ A_{m} & \text { for } t=\tau\end{cases}
$$

and by Corollary 4.6

$$
\lim _{|\Lambda| \rightarrow 0}\left\|u-u_{\Lambda}\right\|_{M R}=0
$$

## References

[1] H. Amann: Maximal regularity for nonautonomous evolution equations. Adv. Nonlinear Stud. 4 (2004), 417-430.
[2] W.Arendt: Semigroups and evolution equations: Functional calculus, regularity and kernel estimates. Handbook of Differential Equations: Evolutionary Equations vol. I (C. M. Dafermos et al., eds.). Elsevier/North-Holland, Amsterdam, 2004, pp. 1-85.
[3] W. Arendt, C. J. K. Batty, M. Hieber, F. Neubrander: Vector-Valued Laplace Transforms and Cauchy Problems. Monographs in Mathematics 96. Birkhäuser, Basel, 2001.
[4] W. Arendt, S. Bu: The operator-valued Marcinkiewicz multiplier theorem and maximal regularity. Math. Z. 240 (2002), 311-343.
[5] W. Arendt, S. Bu: Tools for maximal regularity. Math. Proc. Camb. Philos. Soc. 134 (2003), 317-336.
[6] W. Arendt, S. Bu: Fourier series in Banach spaces and maximal regularity. Vector Measures, Integration and Related Topics. Selected papers from the 3rd conference on vector measures and integration, Eichstätt, Germany, September 24-26, 2008. Operator Theory: Advances and Applications 201. Birkhäuser, Basel, 2010, pp. 21-39.
[7] W. Arendt, R. Chill, S. Fornaro, C. Poupaud: $L^{p}$-maximal regularity for nonautonomous evolution equations. J. Differ. Equations 237 (2007), 1-26.
[8] P. Cannarsa, V. Vespri: On maximal $L^{p}$ regularity for the abstract Cauchy problem. Boll. Unione Mat. Ital., VI. Ser., B 5 (1986), 165-175.
[9] G.DaPrato, P. Grisvard: Sommes d'opérateurs linéaires et équations différentielles opérationnelles. J. Math. Pur. Appl., IX. Sér. 54 (1975), 305-387. (In French.)
[10] L. De Simon: Un'applicazione della teoria degli integrali singolari allo studio delle equazioni differenziali lineari astratte del primo ordine. Rend. Sem. Mat. Univ. Padova 34 (1964), 205-223. (In Italian.)
[11] R. Denk, M. Hieber, J. Prüss: $\mathscr{R}$-boundedness, Fourier Multipliers and Problems of Elliptic and Parabolic Type. vol. 166, Mem. Am. Math. Soc., Providence RI, 2003.
[12] G. Dore: $L^{p}$-regularity for abstract differential equations. Functional Analysis and Related Topics, 1991. Proceedings of the international conference in memory of Professor

Kôsaku Yosida held at RIMS, Kyoto University, Japan, July 29-Aug. 2, 1991. Lect. Notes Math. 1540. Springer, Berlin, 1993, pp. 25-38.
[13] O. El-Mennaoui, V. Keyantuo, H. Laasri: Infinitesimal product of semigroups. Ulmer Seminare 16 (2011), 219-230.
[14] M. Hieber, S. Monniaux: Heat kernels and maximal $L_{p}-L_{q}$ estimates: The nonautonomous case. J. Fourier Anal. Appl. 6 (2000), 468-481.
[15] M. Hieber, S. Monniaux: Pseudo-differential operators and maximal regularity results for non-autonomous parabolic equations. Proc. Am. Math. Soc. 128 (2000), 1047-1053.
[16] N. J. Kalton, G. Lancien: A solution to the problem of $L^{p}$-maximal regularity. Math. Z. 235 (2000), 559-568.
[17] P. C. Kunstmann, L. Weis: Maximal $L^{p}$-regularity for parabolic equations, Fourier multiplier theorems and $H^{\infty}$-functional calculus. Functional Analytic Methods for Evolution Equations. Based on lectures given at the autumn school on evolution equations and semigroups, Levico Terme, Trento, Italy, October 28-November 2, 2001. Lecture Notes in Mathematics 1855 (M. Iannelli, et al., eds.). Springer, Berlin, 2004, pp. 65-311.
[18] A. Lunardi: Analytic Semigroups and Optimal Regularity in Parabolic Problems. Progress in Nonlinear Differential Equations and their Applications 16. Birkhäuser, Basel, 1995.
[19] P. Portal, Ž. Štrkalj: Pseudodifferential operators on Bochner spaces and an application. Math. Z. 253 (2006), 805-819.
[20] J. Prüss, R. Schnaubelt: Solvability and maximal regularity of parabolic evolution equations with coefficients continuous in time. J. Math. Anal. Appl. 256 (2001), 405-430.
[21] A. Slavik: Product Integration, Its History and Applications. History of Mathematics 29, Jindřich Nečas Center for Mathematical Modeling Lecture Notes 1. Matfyzpress, Praha, 2007.
[22] P. E. Sobolevskij: Coerciveness inequalities for abstract parabolic equations. Sov. Math., Dokl. 5 (1964), 894-897; Dokl. Akad. Nauk SSSR 157 (1964), 52-55. (In Russian.)
[23] H. Triebel: Theory of Function Spaces. Monographs in Mathematics 78. Birkhäuser, Basel, 1983.

Authors' addresses: H afida Laasri, Ulm University, Institute of Applied Analysis, 89069 Ulm, Germany, and Bergische Universität Wuppertal, FB-C Math, Gauss Strasse 20, 42097 Wuppertal, Germany, e-mail: laasrihafida@gmail.com; Omar El-Mennaoui, Department of Mathematics, University Ibn Zohr, Faculty of Sciences, Agadir, Morocco, e-mail: elmennaouiomar@yahoo.fr.


[^0]:    This work was financially supported by the Deutscher Akademischer Austauschdienst

