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# THE TANGENT BUNDLE OF $p^{r}$-VELOCITIES OVER A HOMOGENEOUS SPACE <br> Jacek Gancarzewicz, Krakow and Modesto Salgado, Santiago 

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## INTRODUCTION

Let $M$ be a differentiable manifold and $T^{p, r} M=J_{0}^{r}\left(R^{p}, M\right)$ be the bundle of $r$-jets at 0 of mappings $\boldsymbol{R}^{p} \rightarrow M$. This bundle $T^{p \cdot r} M \rightarrow M$ is called the tangent bundle of $p^{r}$-velocities of $M$. In this paper, we shall study the geometry of $T^{p \cdot r} M$ where $M$ is a homogeneous space.

The paper is structured into five sections.
In Section 1 we introduce general notations and prove some technical lemmas concerning the lifts of functions and vector fields from $M$ to $T^{p, r} M$ for later use.

Section 2 is devoted to the study of the group $T^{p, r} G$ when $G$ is a Lie group. In particular, we prove that the $\alpha$-lift $X^{\langle\alpha\rangle},|\alpha| \leqq r$, of a left invariant vector field $X$ on $G$ is left invariant on $T^{p, r} G$. Also we show that if $M$ is a $G$-space then $T^{p, r} M$ is a $T^{p, r} G$-space and that, for every element $X$ of the Lie algebra $\mathscr{L}(G)$ of $G$ and every $\alpha$ such that $|\alpha| \leqq r, X^{*\langle\alpha\rangle}=X^{\langle\alpha\rangle *}$, where $X^{*}$ and $X^{\langle\alpha\rangle *}$ are the fundamental vector fields defined on $M$ and $T^{p, r} M$ respectively. Section 2 is ended by proving that $\alpha$-lifts of $G$-invariant tensor fields and $G$-invariant connections from a $G$-space $M$ to $T^{p \cdot r} M$ are $T^{p, r} G$-invariant.

In Section 3 a natural Lie algebra isomorphism $\Omega_{G}: T^{p, r}(\mathscr{L}(G)) \rightarrow \mathscr{L}\left(T^{p, r} G\right)$ is constructed, where $\mathscr{L}(G)$ and $\mathscr{L}\left(T^{p, r} G\right)$ denote the Lie algebra of $G$ and $T^{p, r} G$ respectively. This isomorphism has a fundamental role in the next sections.

In Section 4 we consider the particular case of $M$ being a homogeneous space $M=G / H$. At first, it is shown that $T^{p, r} M$ is also a homogeneous space and, in fact, $T^{p, r} M=T^{p . r} G / T^{p . r} H$. In particular, if $p=r=1$, then $T M=T G / T H$, that is, the tangent bundle of a homogeneous space is also a homoegenous space; it is worth to remark that we show this without the assumption of $M=G / H$ be reductive (compare with Proposition 3.1 in [11]). Next we show that if $M=G / H$ is a reductive homogeneous space with respect to a decomposition $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$, then the homogeneous space $T^{p, r} M=T^{p, r} G / T^{p, r} H$ is reductive with respect to the decomposition $\mathscr{L}\left(T^{p . r} G\right)=\mathscr{L}\left(T^{p . r} H\right) \oplus \Omega_{G}\left(T^{p, r} W\right)$, and moreover, the fundamental affine connection of $T^{p, r} M$ is the complete lift of the canonical connection of $M$. Also it is
shown that if $(M, \nabla)$ is an affine reductive space, then $\left(T^{p, r} M, \nabla^{c}\right)$ is an affine reductive space too, where $\nabla^{c}$ is the complete lift of $\nabla$, and for the groups of transvections the following equality holds: $\operatorname{Tr}\left(T^{p, r} M, \nabla^{c}\right)=T^{p, r}(\operatorname{Tr}(M, \nabla))$. Finally, in this section, it is shown that if a homogeneous space $M=G / H$ is naturally reductive with respect to a $H$-invariant pseudometric $g$, then $T^{r} M=T^{r} G / T^{r} H$ is naturally reductive with respect to $g^{(r)}$. (Here $T^{r} M=T^{1, r} M$ is the tangent bundle of order $r$ and $g^{(r)}$ is the complete lift of $G$ to $T^{r} M$; we do not consider this situation for $p>1$ because A. Morimoto's liftings produce a pseudometric on $T^{p . r} M$ only if $p=1$ ).

In Section 5 we define prolongations of regular $s$-structures from $M$ to $T^{p, r} M$. We prove that if $\left(M,\left\{s_{x}\right\}\right)$ is a $s$-manifold then, there exists a $s$-structure $\left.\left\{s_{x}^{\prime}\right\}\right\}$ on $T^{p, r} M$ such that for every point $x$ of $M$ we have $s_{\bar{x}}^{\prime}=T^{p, r_{x}}$, where $\bar{x}$ is the $r$-jet at 0 of the constant mapping $R^{p} \in u \rightarrow x \in M$. We also prove that the canonical connection of $\left(T^{p . r} M,\left\{s_{x^{\prime}}^{\prime}\right\}\right)$ is the complete lift of the canonical connection of $\left(M,\left\{s_{x}\right\}\right)$ and for the group of the transvections we have $\operatorname{Tr}\left(T^{p, r} M,\left\{s_{x_{x}^{\prime}}^{\prime}\right\}\right)=T^{p, r}(\operatorname{Tr}(M,\{H s\}))$. Finally, we show that if $\left\{s_{x}\right\}$ is a Riemann $s$-structure on $(M, g)$, where $g$ is a pseudometric on $M$, then $\left\{s_{x^{\prime}}^{\prime}\right\}$ is a Riemann $s$-structure on $\left(T^{r} M, g^{(r)}\right)$.

All the results in this paper coincide with Sekizawa's results [11] when $p=r=1$, that is, for the tangent bundle. Nevertheless, the methods that we have used in Section 2 are completely different from those of Sekizawa because he has considered $T G$ as semidirect product of $G$ and $\mathscr{L}(G)$. Also the natural isomorphism $\Omega_{G}$ : $T^{p . r}(\mathscr{L}(G)) \rightarrow \mathscr{L}\left(T^{p, r} G\right)$ constructed in Section 3 is not used in [11] because with the identification of $T G \equiv G \times \mathscr{L}(G)$ is not needed. All the results in Section 4, except Theorems 4.9 and 4.10 , are obtained by using only the results of this section and the natural isomorphism $\Omega_{G}$. To prove Theorems 4.9 and 4.10 and the results in Section 5 we use the same arguments as M. Sekizawa in [11].

Through the paper we always suppose that all manifolds are differentiable manifolds of class $C^{\infty}$ and all functions, vector fields, tensor fields and so on are of class $C^{\infty}$.

We would like to express our sincere gratitude to Professor Luis A. Cordero from the University of Santiago de Compostela for suggesting us to study this problem. We would like to thank also to the Department of Geometry and Topology (University of Santiago de Compostela) for the convenience and the pleasant atmosphere for our research.

## 1. NOTATIONS AND TECHNICAL LEMMAS

Let $M$ be a manifold. We denote by

$$
T^{p \cdot r} M=J_{0}^{r}\left(\boldsymbol{R}^{p}, M\right)=\left\{j_{0}^{r} \gamma / \gamma: \boldsymbol{R}^{p} \rightarrow M \text { is of class } C^{\infty}\right\}
$$

the bundle of $p^{r}$-velocities and by $\pi: T^{p . r} M \rightarrow M, \pi\left(j_{0}^{r} \gamma\right)=\gamma(0)$ the bundle projection.

If $x$ is a point of $M$, we shall always denote by

$$
\begin{equation*}
\bar{x}=j_{0}^{r} x \tag{1.1}
\end{equation*}
$$

the $r$-jet at 0 of the constant mapping $\boldsymbol{R} \in u \rightarrow x \in M$. Now the mapping $M \ni x \rightarrow$ $\rightarrow \bar{x} \in T^{p, r} M$ is an imbedding.

If $\varphi: M \rightarrow N$ is a mapping of class $C^{\infty}$, then the induced mapping $T^{p, r} \varphi: T^{p, r} M \rightarrow$ $\rightarrow T^{p, r} N$ is given by

$$
\begin{equation*}
T^{p, r} \varphi\left(j_{0}^{r} \gamma\right)=j_{0}^{r}(\varphi \gamma) . \tag{1.2}
\end{equation*}
$$

Of course, for two mappings $\varphi: M \rightarrow N$ and $\psi: N \rightarrow K$ we have

$$
\begin{equation*}
T^{p, r} \psi \circ T^{p, r} \varphi=T^{p, r}(\psi \circ \varphi) . \tag{1.3}
\end{equation*}
$$

If $f$ is a function on $M$ and $\alpha=\left(\alpha_{1}, \ldots, \alpha_{p}\right)$ is a sequence of nonnegative integers such that $|\alpha|=\alpha_{1}+\ldots+\alpha_{p} \leqq r$, then the $\alpha$-lift $f^{(\alpha)}$ of $f$ from $M$ to $T^{p, r} M$ is defined by the formula

$$
\begin{equation*}
f^{(\alpha)}\left(j_{0}^{r} \gamma\right)=\frac{1}{\alpha!} D_{\alpha}(f \circ \gamma)(0) \tag{1.4}
\end{equation*}
$$

where $j_{0}^{r} \gamma \in T^{p, r} M . f^{(\alpha)}$ is a function of class $C^{\infty}$ on $T^{p, r} M$. If either $|\alpha|>r$ or there is at least one negative integer among $\alpha_{1}, \ldots, \alpha_{p}$ we set $f^{(\alpha)} \equiv 0$.

If $X$ is a vector field on $M$, then there is one and only one vector field $X^{\langle\alpha\rangle}$ on $T^{p, r} M$ (called the $\alpha$-lift of $X$ from $M$ to $T^{p, r} M$ ) such that

$$
\begin{equation*}
X^{\langle\alpha\rangle}\left(f^{(\beta)}\right)=(X f)^{(\beta-\alpha)} \tag{1.5}
\end{equation*}
$$

for all functions $f$ on $M$ and all $\beta=\left(\beta_{1}, \ldots, \beta_{n}\right)$ such that $|\beta| \leqq r$. The definitions of the $\alpha$-lifts are due to A. Morimoto ([8], [9]).

The following properties of $\alpha$-lifts of functions and vector fields are well known (see A. Morimoto [8], [9]):

$$
\left\{\begin{array}{l}
(f+g)^{(\alpha)}=f^{(\alpha)}+g^{(\alpha)}, \quad(f g)^{(\alpha)}=\sum_{\beta} f^{(\beta)} g^{(\alpha-\beta)},  \tag{1.6}\\
(X+Y)^{\langle\alpha\rangle}=X^{\langle\alpha\rangle}+Y^{\langle\alpha\rangle}, \quad(f X)^{\langle\alpha\rangle}=\sum_{\beta} f^{(\beta)} X^{\langle\alpha+\beta\rangle}, \\
{\left[X^{\langle\alpha\rangle}, Y^{\langle\beta\rangle}\right]=[X, Y]^{\langle\alpha+\beta\rangle}}
\end{array}\right.
$$

for all functions $f, g$ and all vector fields $X, Y$ on $M$.
If $\left(U, x^{i}\right)$ is a chart on $M$, then the induced chart $\left(\pi^{-1}(U), x^{i, x}\right)$ on $T^{p, r} M$ is given by

$$
x^{i, \alpha}=\left(x^{i}\right)^{(\alpha)}
$$

where $|x| \leqq r$. For the canonical frames we have (see A. Morimoto [8], [10])

$$
\begin{equation*}
\vartheta / \vartheta x^{i, \alpha}=\left(\vartheta / \vartheta x^{i}\right)^{\langle\alpha\rangle} . \tag{1.7}
\end{equation*}
$$

In case $p=1$, the $\alpha$-lift $X^{(\alpha)}$ of a vector field $X$ from $M$ to $T^{r} M=T^{1, r} M$ is defined by

$$
\begin{equation*}
X^{(\alpha)}=X^{\langle r-\alpha\rangle} \tag{1.8}
\end{equation*}
$$

where $\alpha=0, \ldots, r$. In this case, formulas (1.5), (1.6), (1.7) and (1.8) imply (see
A. Morimoto [8], [9], [10])

$$
\left\{\begin{array}{l}
X^{(\alpha)}\left(f^{(\beta)}\right)=(X f)^{(\alpha+\beta-r)}  \tag{1.9}\\
(f X)^{(\alpha)}=\sum_{\beta} f^{(\beta)} X^{(\alpha-\beta)} \\
{\left[X^{(\alpha)}, Y^{(\beta)}\right]^{=}=[X, Y]^{(\alpha+\beta-r)}} \\
\vartheta / \forall x^{i, \alpha}=\left(\vartheta / \vartheta x^{i}\right)^{(r-\alpha)}
\end{array}\right.
$$

Let $M$ and $M^{\prime}$ be differentiable manifolds. We shall always identity $T^{p, r}\left(M \times M^{\prime}\right)$ with $T^{p, r} M \times T^{p, r} M^{\prime}$ using the natural diffeomorphism

$$
T^{p, r}\left(M \times M^{\prime}\right) \ni j_{0}^{r}\left(\gamma, \gamma^{\prime}\right) \rightarrow\left(j_{0}^{r} \gamma, j_{0}^{r} \gamma^{\prime}\right) \in T^{p, r} M \times T^{p, r} M^{\prime} .
$$

If $f$ and $f^{\prime}$ are functions on $M$ and $M^{\prime}$, respectively, then we define the function $f \otimes f^{\prime}$ on $M \times M^{\prime}$ by

$$
\begin{equation*}
\left(f \otimes f^{\prime}\right)\left(x, x^{\prime}\right)=f(x) f\left(x^{\prime}\right) \tag{1.10}
\end{equation*}
$$

Using the standard verification, from (1.3) and (1.10) it follows

$$
\begin{equation*}
\left(f \otimes f^{\prime}\right)^{(x)}=\sum_{\beta} f^{(\beta)} \otimes\left(f^{\prime}\right)^{(\alpha-\beta)} \tag{1.11}
\end{equation*}
$$

If $X$ and $X^{\prime}$ are vector fields on $M$ and $M^{\prime}$ respectively, then we define the vector field $X \times X^{\prime}$ on $M \times M$ by the formula

$$
\begin{equation*}
\left(X \times X^{\prime}\right)\left(x, x^{\prime}\right)=\left(X(x), X^{\prime}\left(x^{\prime}\right)\right) \in T_{x} M \times T_{x}, \quad M^{\prime}=T_{\left(x, x^{\prime}\right)}\left(M \times M^{\prime}\right) . \tag{1.2}
\end{equation*}
$$

From the Leibniz's formula, for any function $h$ on $M \times M^{\prime}$

$$
\begin{equation*}
\left(\left(X \times X^{\prime}\right)(h)\right)\left(x, x^{\prime}\right)=X_{x}\left(\left.h\right|_{x^{\prime}} ^{2}\right)+X_{x}^{\prime}\left(\left.h\right|_{x} ^{1}\right) \tag{1.13}
\end{equation*}
$$

where $\left.h\right|_{x} ^{2}$, and $\left.h\right|_{x} ^{1}$ are the functions on $M$ and $M^{\prime}$ respectively, given by

$$
\left.h\right|_{x^{\prime}} ^{2}(x)=\left.h\right|_{x} ^{1}\left(x^{\prime}\right)=h\left(x, x^{\prime}\right) .
$$

In particular, if $h=f \otimes f^{\prime}$, then

$$
\begin{equation*}
\left(X \times X^{\prime}\right)\left(f \otimes f^{\prime}\right)=(X f) \otimes f^{\prime}+f \otimes\left(X^{\prime} f^{\prime}\right) \tag{1.14}
\end{equation*}
$$

Now, we can prove
Proposition 1.1. If $X$ and $X^{\prime}$ are vector fields on $M$ and $M^{\prime}$, respectively, then for every $\alpha$

$$
\left(X \times X^{\prime}\right)^{\langle\alpha\rangle}=X^{\langle\alpha\rangle} \times X^{\prime\langle\alpha\rangle} .
$$

Proof. First, if $f$ and $f^{\prime}$ are functions on $M$ and $M^{\prime}$ respectively, then from (1.5), (1.11) and (1.14) by straight-forward computations we obtain

$$
\begin{equation*}
\left(X \times X^{\prime}\right)^{\langle\alpha\rangle}\left(f \otimes f^{\prime}\right)^{(\beta)}=\left(X^{\langle\alpha\rangle} X^{\prime\langle\alpha\rangle}\right)\left(f \otimes f^{\prime}\right)^{(\beta)} \tag{1.15}
\end{equation*}
$$

for all $\beta$. Now, if $h$ is any function on $M \times M^{\prime}$ and $y_{0}$ is a point of $T^{p, r}\left(M \times M^{r}\right)$, then there exist functions $f_{1}, \ldots, f_{N}$ and $f_{1}^{\prime}, \ldots, f_{N}^{\prime}$ defined on $M$ and $M^{\prime}$, respectively, such that

$$
j_{z_{0}}^{r+1} h=j_{z_{0}}^{r+1}\left(\sum_{i} f_{i} \otimes f_{i}^{\prime}\right)
$$

where $z_{0}=\pi\left(y_{0}\right)$. Therefore, we have

$$
j_{y_{0}}^{1} h^{(\beta)}=j_{y_{0}}^{1}\left(\sum_{i} f_{i} \otimes f_{i}^{\prime}\right)^{(\beta)}
$$

and hence, from (1.14) we obtain

$$
\left(X \times X^{\prime}\right)^{\langle\alpha\rangle}\left(h^{(\beta)}\right)=\left(X^{\langle\alpha\rangle} \times X^{\prime\langle\alpha\rangle}\right)\left(h^{(\beta)}\right)
$$

at $y_{0}$.

## 2. PROLONGATIONS OF LIE GROUPS

Let $G$ be Lie group and let $\varphi: G \times G \rightarrow G$ be the product mapping given by

$$
\begin{equation*}
\varphi(\xi, \eta)=\xi \eta . \tag{2.1}
\end{equation*}
$$

The induced mapping $T^{p, r} \varphi: T^{p, r} G \times T^{p, r} G \rightarrow T^{p, r} G$ defines a Lie group structure on $T^{p, r} G$. In fact, for any $j_{0}^{r} \xi$ and $j_{0}^{r} \eta$ of $T^{p, r} G$ we have

$$
\begin{equation*}
j_{0}^{r} \xi \cdot j_{0}^{r} \eta=\left(T^{p, r} \varphi\right)\left(j_{0}^{r} \xi, j_{0}^{r} \eta\right)=j_{0}^{r}(\varphi \circ(\xi, \eta))=j_{0}^{r}(\xi \eta) \tag{2.2}
\end{equation*}
$$

where $\xi \eta: \boldsymbol{R}^{p} \rightarrow G$ is given by $(\xi \eta)(u)=\xi(u) \eta(u)$. The group $T^{p, r} G$ is called the Lie group of $p^{r}$-velocities of $G$. If $G \rightarrow G^{\prime}$ is a Lie group homomorphism, then the induced mapping $T^{p, r} f: T^{p, r} G \rightarrow T^{p, r} G^{\prime}$ is also a Lie group homomorphism.

Now, we prove the following proposition concerning left invariant vector fields on $G$ and $T^{p, r} G$.

Proposition 2.1. If $A$ is a left invariant vector field on $G$, then for every a such that $|\alpha| \leqq r, A^{\langle\alpha\rangle}$ is a left invariant vector field on $T^{p, r} G$. Equivalently, if $A \in \mathscr{L}(G)$. then $A^{\langle\alpha\rangle} \in \mathscr{L}\left(T^{p . r} G\right)$, where $\mathscr{L}(G)$ denotes the Lie algebra of the given Lie group,

Proof. Let $j_{0}^{r} \xi \in T^{p, r} G$. In order to prove that $\left(L_{j 0^{r} \xi}\right)_{*} A^{\langle\alpha\rangle}=A^{\langle\alpha\rangle}$ we only need to verify

$$
\begin{equation*}
A_{j_{0}{ }^{\prime} \eta}^{\langle x\rangle}\left(f^{(\beta)} \circ L_{j_{0}{ }^{r} \xi}\right)=A_{j_{0^{r}}(\xi \eta)}^{\langle\alpha\rangle}\left(f^{(\beta)}\right) \tag{2.3}
\end{equation*}
$$

for every function $f$ on $G$, every $\beta$ such that $|\beta| \leqq r$ and every point $j_{0}^{r} \eta \in T^{p, r} G$, where $L_{j 0^{r} \xi}$ is the left translation on $T^{p, r} G$.

Firstly, let us observe that

$$
\begin{aligned}
& \left(f^{(\beta)} \circ L_{j_{0}{ }^{r} \xi}\right)\left(j_{0}^{r} \eta\right)=f^{(\beta)}\left(j_{0}^{r}(\xi \eta)\right)= \\
& =\frac{1}{\beta!} D_{\beta}(f \circ \varphi(\xi, \eta))(0)=(f \circ \varphi)^{(\beta)}\left(j_{0}^{r} \xi, j_{0}^{\lambda} \eta\right),
\end{aligned}
$$

where $\varphi$ is given by (2.1). According to (1.13), (2.1) and Proposition 1.1, we obtain

$$
\begin{aligned}
& A_{j_{0} r}^{\langle\alpha\rangle}\left(f^{(\beta)} \circ L_{j_{j}{ }^{\circ} \xi}\right)=A_{j_{0} r}^{\langle\alpha\rangle}\left(\left.(f \circ \varphi)^{(\beta)}\right|_{j_{0} \xi \xi} ^{1}\right)= \\
& =\left((0 \times A)^{\langle\alpha\rangle}(f \circ \varphi)\left(j_{0}^{r} \xi, j_{0}^{r} \eta\right)=\right. \\
& =\left((0 \times A)(f \circ \varphi)^{(\beta-\alpha)}\right)\left(j_{0}^{r} \xi, j_{0}^{r} \eta\right) .
\end{aligned}
$$

Since $A$ is a left invariant vector field on $G$, then (1.13) implies

$$
\begin{aligned}
& ((0 \times A)(f \circ \varphi))\left(x, x^{\prime}\right)=A_{x^{\prime}}\left(\left.(f \circ \varphi)\right|_{x} ^{1}\right)=A_{x^{\prime}}\left(f \circ L_{x}\right)= \\
& =A_{x x^{\prime}} f=((A f) \circ \varphi)\left(x, x^{\prime}\right)
\end{aligned}
$$

and according to (1.4), we obtain

$$
\begin{aligned}
& A_{j_{0} r^{\prime} \eta}^{\langle\alpha\rangle}\left(f^{(\beta)} \circ L_{j_{0}{ }^{r} \xi}\right)=(A f \circ \varphi)^{(\beta-x)}\left(j_{0}^{r} \xi, j_{0}^{r} \eta\right)= \\
& =\frac{1}{(\beta-\alpha)!} D_{\beta-x}(A f \circ \varphi \circ(\xi, \eta))(0)= \\
& =\frac{}{(\beta-\alpha)!} D_{\beta-x}(A f \circ \xi \eta)(0)=(A f)^{(\beta-x)}\left(j_{0}^{r}(\xi \eta)\right)=A_{j 0^{\prime}(\xi \eta)}^{\langle\alpha\rangle}\left(f^{(\beta)}\right)
\end{aligned}
$$

and the proof is done.
Let $M$ be a $G$-space and let $\lambda: G \times M \rightarrow M$ be the action of $G$ on $M$. The induced mapping $T^{p . r} \lambda: T^{p, r} G \times T^{p, r} M \rightarrow T^{p, r} M$ defines an action of $T^{p, r} G$ on $T^{p, r} M$ because if $j_{0}^{r} \xi \in T^{p, r} G$ and $j_{0}^{r} \gamma \in T^{p, r} M$, then

$$
j_{0}^{r} \xi \cdot j_{0}^{r} \gamma=\left(T^{p . r} \lambda\right)\left(j_{0}^{r} \xi, j_{0}^{r} \gamma\right)=j_{0}^{r}(\xi \gamma)
$$

where $\xi^{\xi} \gamma: \boldsymbol{R}^{p} \rightarrow M$ is given by

$$
\begin{equation*}
(\xi \gamma)(u)=\xi(u) \gamma(u) . \tag{2.4}
\end{equation*}
$$

Proposition 2.2. Let $M$ be a $G$-space. For any $A \in \mathscr{L}(G)$ and any a such that $|\alpha| \leqq r$,

$$
A^{*\langle x\rangle}=A^{\langle x\rangle *},
$$

where $A^{*}$ and $A^{\langle x\rangle *}$ are the fundamental vector fields defined by $A$ and $A^{\langle x\rangle}$ on $M$ and $T^{p, r} M$ respectively.

Proof. Let $f$ be a function on $G$ and let $j_{0}^{r} \gamma$ be a point of $T^{p, r} M$. We only need to verify

$$
\begin{equation*}
A_{j_{0} r_{\gamma} \gamma}^{\langle\alpha\rangle}\left(f^{(\beta)}\right)=A_{j_{0}{ }^{r} \gamma}^{*\langle\alpha\rangle}\left(f^{(\beta)}\right)=\left(A^{*} f\right)^{(\beta-x)}\left(j_{0}^{r} \ddot{\gamma}\right) . \tag{2.5}
\end{equation*}
$$

If $\varrho_{j_{0^{r}},}: T^{p, r} G \rightarrow T^{p, r} M$ denotes the mapping given by

$$
\begin{equation*}
\varrho_{j_{0}{ }^{r} \gamma}\left(j_{0}^{r} \xi\right)=j_{0}^{r} \xi j_{0}^{r} \gamma=j_{0}^{r}(\xi \gamma)=j_{0}^{r}(\lambda 。(\xi, \gamma)), \tag{2.6}
\end{equation*}
$$

then

$$
A_{j_{0} r_{\gamma} \gamma}^{\langle\alpha \bar{x} *}=\left(d_{\bar{e}} p_{j_{o^{\prime}} \bar{\gamma}}\right)\left(A_{\bar{e}}^{\langle\alpha\rangle}\right)
$$

where $\bar{e}$ is the identity element of $T^{p, r} G$. This implies

$$
A_{j_{0} r_{j}^{\prime}}^{\langle\alpha\rangle *}\left(f^{(\beta)}\right)=A_{\bar{e}}^{\langle\alpha\rangle}\left(f^{(\beta)} \circ \varrho_{j_{0}{ }^{\circ} \xi}\right) .
$$

Since

$$
\begin{aligned}
& \left(f^{(\beta)} \circ p_{j_{0} r_{\gamma}}\right)\left(j_{0}^{r} \xi\right)=f^{(\beta)}\left(j_{0}^{r}(\lambda \circ(\xi, \gamma))=\right. \\
& =\frac{1}{\beta!} D_{\beta}\left(f \circ \lambda_{\circ}(\xi, \gamma)\right)=(f \circ \lambda)^{(\beta)}\left(j_{0}^{r} \xi, j_{0}^{r} \gamma\right),
\end{aligned}
$$

then using (1.13), (1.5) and Proposition 1.1 we have

$$
\begin{align*}
& A_{j_{0^{\prime}} r_{j}^{\prime},}^{\langle\alpha\rangle}\left(f^{(\beta)}\right)=A_{\bar{e}}^{\langle\alpha\rangle}\left(\left.f \circ \lambda\right|_{j_{0} 0_{\xi}^{r}} ^{2}\right)=  \tag{2.7}\\
& =(A \times 0)_{\left(\bar{e}, j_{0} \sigma^{r} \gamma\right)}^{\langle\alpha\rangle}(f \circ \lambda)^{(\beta)}=((A \times 0)(f \circ \lambda))^{(\beta-\alpha)}\left(\bar{e}, j_{0}^{r} \gamma\right)
\end{align*}
$$

If $\varrho_{x}: G \rightarrow M$ denotes the mapping given by

$$
\begin{equation*}
\varrho_{x}(\xi)=\xi x=\lambda(\xi, x) \tag{2.8}
\end{equation*}
$$

then using (1.13) and bearing in mind that $A$ is left invariant we obtain

$$
\begin{aligned}
& ((A \times 0)(f \circ \lambda))(\xi, x)=A_{\xi}\left(\left.(f \circ \lambda)\right|_{x} ^{2}=\left(\mathrm{d} L_{\xi}\right)\left(A_{e}\right)\left(f \circ \varrho_{x}\right)=\right. \\
& =A_{e}\left(f \circ \varrho_{x} L_{\xi}\right)=A_{e}\left(f \circ \varrho_{\xi_{x}}\right)=A_{\xi x}^{*}(f)=\left(\left(A^{*} f\right) \circ \lambda\right)(\xi, x) .
\end{aligned}
$$

Applying this formula to (2.7) and using (1.4) we get

$$
\begin{aligned}
& A_{j_{0} r_{\gamma},}^{\langle\alpha} f^{(\beta)}=\left(\left(A^{*} f\right) \circ \lambda\right)^{(\beta-x)}\left(\bar{e}, j_{0}^{r} \gamma\right)= \\
& =\frac{1}{(\beta-\alpha)!} D_{\beta-x}\left(\left(A^{*} f\right) \circ \gamma\right)(0)=\left(A^{*} f\right)^{(\beta-\alpha)}\left(j_{0}^{r} \gamma\right),
\end{aligned}
$$

and the proof of $(2.5)$ is complete.
If $M$ is a $G$-space and $x$ is a point of $M$, then

$$
\mathcal{O}_{x}=\{\xi x: \xi \in G\}
$$

will denote the orbit of $G$ through $x$ and

$$
\mathscr{S}_{x}=\{\xi \in G: \xi x=x\}
$$

the isotropy group of $G$ at $x$.
Proposition 2.3. If $x$ is a point of $M$, then $\mathcal{O}_{\bar{x}}=T^{p, r} \mathcal{O}_{x}$, where $\bar{x}$ is the point of $T^{p \cdot r} M$ given by (1.1).

Proof. Let $j_{0}^{r} \gamma \in T^{p, r} \mathcal{O}_{x}$, then $\gamma: \boldsymbol{R}^{p} \rightarrow \mathcal{O}_{x}$. Thus, there exists $\xi(u) \in G$ such that $\gamma(u)=\xi(u) x$. Using the standard methods we can choose $\xi(u)$ in such a way that the mapping $R^{p} \ni u \rightarrow \xi(u) \in G$ is of class $C^{\infty}$. Now $j_{0}^{r} \gamma=\left(j_{0}^{r} \xi\right) \bar{x}$ belongs to $\mathscr{O}_{\bar{x}}$.

Conversely, if $j_{0}^{r} \gamma \in \mathcal{O}_{\bar{x}}$, then there exists $j_{0}^{r} \xi \in T^{p, r} G$ such that $j_{0}^{r} \gamma=j_{0}^{r} \xi \bar{x}=j_{0}^{r}(\xi x)$. Since for every $u \in R^{p},(\xi x)(u)=\xi(u) x$ belongs to $\mathcal{O}_{x}$, then $j_{0}^{r} \gamma \in T^{p \cdot r} \mathcal{O}_{x}$.

This proposition implies immediately:
Corollary 2.4 (A. Morimoto [8], [9]). If $M$ is a $G$-space, then $T^{p, r} M$ is a $T^{p, r} G$ space.

Proposition 2.5. For every point $x$ of $M, T^{p, r} \mathscr{S}_{x}$ is an open subgroup of $\mathscr{S}_{\bar{x}}$, where $\bar{x}$ is the point of $T^{p . r} M$ given by (1.1).

Proof. Let $j_{0}^{r} \xi \in T^{p, r} \mathscr{S}_{x}$. Since for every $u \in R^{p}, \xi(u)$ belongs to $S_{x}$, then $j_{0}^{r} \xi \bar{x}=$ $=j_{0}^{r}(\xi x)=\bar{x}$, that is, $T^{p, r} \mathscr{S}_{x}$ is a subgroup of $\mathscr{S}_{\bar{x}}$.

The orbits $\mathcal{O}_{x}$ and $\mathcal{O}_{\bar{x}}$ are diffeomorphic to $G / \mathscr{S}_{x}$ and $T^{p, r} G / \mathscr{S}_{\bar{x}}$ respectively. Using

Proposition 2.3 we obtain

$$
\begin{aligned}
& \operatorname{dim} T^{p, r} \mathscr{S}_{x}=\binom{p+r}{r} \operatorname{dim} \mathscr{S}_{x}=\binom{p+r}{r}\left(\operatorname{dim} G-\operatorname{dim} \mathcal{O}_{x}\right), \\
& \operatorname{dim} \mathscr{S}_{\bar{x}}=\operatorname{dim} T^{p, r} G-\operatorname{dim} \mathscr{O}_{\bar{x}}=\operatorname{dim} T^{p, r} G-\operatorname{dim} T^{p, r} \mathcal{O}_{x}= \\
& =\binom{p+r}{r}\left(\operatorname{dim} G-\operatorname{dim} \mathcal{O}_{x}\right) .
\end{aligned}
$$

Thus the inclusion $T^{p . r} \mathscr{S}_{x} \subset \mathscr{S}_{\bar{x}}$ and the equality $\operatorname{dim} T^{p . r} \mathscr{S}_{x}=\operatorname{dim} \mathscr{S}_{\bar{x}}$ imply that $T^{p . r} \mathscr{S}_{x}$ is open in $\mathscr{S}_{\hat{x}}$.

Next we shall study the liftings of invariant tensor fields and invariant connections. We start with the following observation:

Proposition 2.6. The Lie algebra $\mathscr{L}\left(T^{p, r} G\right)$ of $T^{p, r} G$ is generated by $\left\{X^{\langle\alpha\rangle}\right.$ : $X \in \mathscr{L}(G),|\alpha| \leqq r\}$.

Proof. Let $X_{1}, \ldots, X_{k}$ be a basis of $\mathscr{L}(G)$. Then, from Proposition $2.1, B=$ $=\left\{X_{i}^{\langle\alpha\rangle}: i=1, \ldots, k,|\alpha| \leqq r\right\}$ is a set of linear independent elements of $\mathscr{L}\left(T^{p, r} G\right)$ (see also [3], [4]). The cardinal of $B$ is

$$
\# B=\binom{p+r}{r} k=\binom{p+r}{r} \operatorname{dim} G=\operatorname{dim} T^{p, r} G=\operatorname{dim} \mathscr{L}\left(T^{p, r} G\right)
$$

and this means that $B$ is a basis of $\mathscr{L}\left(T^{p, r} G\right)$.
Proposition 2.7. Let $G$ be a connected Lie group and let $M$ be a $G$-space. If $t$ is a $G$-invariant tensor field of type $(\varepsilon, q)$ on $M$, where $\varepsilon=0,1$, then the $\alpha$-lift $t^{(x)}$ of $t$ from $M$ to $T^{p . r} M$ is $T^{p, r} G$-invariant. If $\nabla$ is a $G$-invariant linear connection on $M$, then the complete lift $\nabla^{C}$ of $\nabla$ to $T^{p \cdot r} M$ is also $T^{p . r} G$-invariant.

Proof. Let $t$ be a tensor field of type $(1, q)$ on $M$. Let us recall that $t^{(x)}$ is a tensor field of type $(1, q)$ on $T^{p, r} M$ such that

$$
\begin{equation*}
t^{(x)}\left(Y_{1}^{\left\langle\beta_{1}\right\rangle}, \ldots, Y_{q}^{\left\langle\beta_{q}\right\rangle}\right)=\left(t\left(Y_{1}, \ldots, Y_{q}\right)\right)^{\left\langle x+\beta_{1}+\ldots+\beta_{q}\right\rangle} \tag{2.9}
\end{equation*}
$$

for all vector fields $Y_{1}, \ldots, Y_{q}$ on $M$ and all $\beta_{1}, \ldots, \beta_{q}$ such that $\left|\beta_{1}\right| \leqq r, \ldots,\left|\beta_{q}\right| \leqq r$ (see A. Morimoto [8], [9]). Also the following formula holds:

$$
\begin{equation*}
\left(L_{Y<v\rangle} t^{(x\rangle}\right)\left(Y_{1}^{\left\langle\beta_{1}\right\rangle}, \ldots, Y_{q}^{\left\langle\beta_{q}\right\rangle}\right)=\left(\left(L_{\gamma} t\right)\left(Y_{1}, \ldots, Y_{q}\right)\right)^{\left\langle\alpha+\beta_{1}+\ldots+\beta_{q}+v\right\rangle} \tag{2.10}
\end{equation*}
$$

where $L$ denotes the Lie derivation.
Since $t$ is $G$-invariant, $L_{X^{*}} t=0$ for every $X \in \mathscr{L}(G)$. Now, according to Proposition 2.2, formula (2.10) implies that $L_{X^{<\infty>}} t^{(x)}=0$ for all $v$. Thus, using Proposition 2.6 we obtain $L_{X} t^{(\alpha)}=0$ for every $\widetilde{X} \in \mathscr{L}\left(T^{p, r} G\right)$. This means that $t^{(\alpha)}$ is $\widetilde{G}$-invariant, where $\widetilde{G}$ is the subgroup of $T^{p, r} G$ generated by $\exp \left(\mathscr{L}\left(T^{p, r} G\right)\right)$. But $G$ is connected, so $\widetilde{G}=T^{p, r} G$.

Analogously, the proposition can be proved for a tensor field $g$ of type $(0, q)$
on $M$. In fact, it suffices to substitute formulas (1.9) and (2.10) by

$$
\begin{aligned}
& g^{(\alpha)}\left(Y_{1}^{\left\langle\beta_{1}\right\rangle}, \ldots, Y_{k}^{\left\langle\beta_{k}\right\rangle}\right)=\left(g\left(Y_{1}, \ldots, Y_{k}\right)\right)^{\left(\alpha-\beta_{1}-\ldots-\beta_{k}\right)} \\
& \left(L_{Y}\left\langle\nu t^{(\alpha)}\right)\left(Y_{1}^{\left\langle\beta_{1}\right\rangle}, \ldots, Y_{k}^{\left\langle\beta_{k}\right\rangle}\right)=\left(\left(L_{y} g\right)\left(Y_{1}, \ldots, Y_{q}\right)\right)^{\left(\alpha-v-\beta_{1}-\ldots-\beta_{q}\right)},\right.
\end{aligned}
$$

respectively.
If $\nabla$ is a linear connection on $M$, then the complete lift $\nabla^{c}$ of $\nabla$ is a linear connection on $T^{p . r} M$ such that

$$
\begin{equation*}
\nabla_{X}^{C}{ }^{\langle\alpha\rangle} Y^{\langle\beta\rangle}=\left(\nabla_{*} Y\right)^{\langle\alpha+\beta\rangle} \tag{2.11}
\end{equation*}
$$

for all vector fields $X$ and $Y$ on $M$ (see A. Morimoto [6], [8]).
If $\nabla$ is $G$-invariant, then for every $X \in \mathscr{L}(G)$ the fundamental vector field $X^{*}$ induced on $M$ is an infinitesimal affine transformation of $\nabla$. From Lemma 6.6 in [8] and Proposition 2.2, $X^{\langle\nu\rangle}$ is an infinitesimal affine transformation of $\nabla^{\boldsymbol{c}}$ for every $v$. According to Proposition 2.6 this means that $\nabla$ is $T^{p, r} G$-invariant (because $G$ is connected).
3. THE LIE ALGEBRA OF $T^{p, r} G$

Let $A$ be a Lie algebra. Then $T^{p . r} A$ is also a Lie algebra and for $j_{0}^{r} k, j_{0}^{r} k^{\prime} \in T^{p, r} A$ we have

$$
a j_{0}^{r} k+a^{\prime} j_{0}^{r} k^{\prime}=j_{0}^{r}\left(a k+a^{\prime} k^{\prime}\right), \quad\left[j_{0}^{r} k, j_{0}^{r} k^{\prime}\right]=j_{0}^{r}\left[k, k^{\prime}\right]
$$

where for mappings $k, k^{\prime}: \boldsymbol{R}^{p} \rightarrow A$ we define

$$
\left(a k+a^{\prime} k^{\prime}\right)(u)=a k(u)+a^{\prime} k^{\prime}(u), \quad\left[k, k^{\prime}\right](u)=\left[k(u), k^{\prime}(u)\right] .
$$

If $f: A \rightarrow A^{\prime}$ is a Lie algebra homomorphism, then the induced mapping $T^{p, r} f$ : $T^{p, r} A \rightarrow T^{p, r} A^{\prime}$ is also a Lie algebra homomorphism.

Let $G$ be a Lie group. We shall construct a natural Lie algebra isomorphism between the Lie algebras $T^{p, r}(\mathscr{L}(G))$ and $\mathscr{L}\left(T^{p, r} G\right)$.

Let $X=j_{0}^{r} k$ be an element of $T^{p, r}(\mathscr{L}(G))$, where $k: \boldsymbol{R}^{p} \rightarrow \mathscr{L}(G)$. This means that for each $u \in \boldsymbol{R}^{\boldsymbol{p}} k(u)$ is a left invariant vector field on $G$. We consider the mapping

$$
\begin{equation*}
\bar{k}: \boldsymbol{R}^{p} \times \boldsymbol{R} \ni(u, t) \rightarrow \exp _{G} t k(u) \in G \tag{3.1}
\end{equation*}
$$

and we define $\bar{k}^{u}: \boldsymbol{R} \rightarrow G$ and $\bar{k}_{t}: \boldsymbol{R}^{\boldsymbol{p}} \rightarrow G$ by

$$
\begin{equation*}
\bar{k}^{u}(t)=\bar{k}_{t}(u)=\bar{k}(u, t)=\exp _{G} t k(u) . \tag{3.2}
\end{equation*}
$$

From (3.1) and (3.2) we have

$$
\begin{equation*}
\left(\frac{\mathrm{d}}{\mathrm{~d} t} \bar{k}^{u}\right)(0)=k(u)_{e}, \tag{3.3}
\end{equation*}
$$

where $e$ is the identity element of $G$. Since for each fixed $u, \bar{k}_{T}(u)$ is an 1-parameter subgroup of $k(u)$, then $j_{0}^{r} \bar{k}_{t}$ is a 1 -parameter subgroup of $T^{p, r} G$. Let $\Omega_{G}(X)$ be the
left invariant vector field on $T^{p . r} G$ defined by this 1-parameter subgroup $j_{0}^{r} \bar{k}_{t}$. Then

$$
\begin{equation*}
\left(\Omega_{G}(X)\right)_{\bar{e}}=\left.\frac{\mathrm{d}}{\mathrm{~d} t}\left(j_{0}^{r} \bar{k}_{t}\right)\right|_{0} \tag{3.4}
\end{equation*}
$$

where $\bar{e}$ is the identity element of $T^{p, r} G$.
Theorem 3.2. The mapping $\Omega_{G}: T^{p, r}(\mathscr{L}(G)) \rightarrow \mathscr{L}\left(T^{p, r} G\right)$ defined by (3.4) is a natural Lie algebra isomorphism.

The proof will be given in a few steps.
Proposition 3.2. $\Omega_{G}$ is linear.
Proof. $\Omega_{G}$ is a mapping of class $C^{\infty}$ between finite dimensional vector spaces. If $X=j_{0}^{r} k \in T^{p, r}(\mathscr{L}(G))$ and $a \in \boldsymbol{R}$, then we shall denote by $\bar{k}$ and $\bar{k}$ the mappings defined by (3.1) for $X=j_{0}^{r} k$ and $a X=j_{0}^{r}(a k)$ respectively. Thus we have

$$
\ddot{k}(u, t)=\exp _{G}(\operatorname{tak}(u))=\bar{k}(t a, u) .
$$

This implies that $\overline{\bar{k}}_{t}=\bar{k}_{a t}$ and hence

$$
\left(\Omega_{G}(a X)\right)_{\bar{e}}=\left.\frac{\mathrm{d}}{\mathrm{~d} t}\left(j_{0}^{r} \bar{k}_{t}\right)\right|_{0}=\left.a \frac{\mathrm{~d}}{\mathrm{~d} t}\left(j_{0}^{r} \bar{k}_{t}\right)\right|_{0}=a\left(\Omega_{G}(X)\right)_{\bar{e}},
$$

that is, $\Omega_{G}(a X)=a \Omega_{G}(X)$ because $\Omega_{G}(a X)$ and $a \Omega_{G}(X)$ are left invariant. Since $\Omega_{G}$ is of class $C^{\infty}$, it follows that $\Omega_{G}$ is linear.

Proposition 3.3. The following diagram is

commutative.
Proof. Let $X=j_{0}^{r} k \in T^{p, r}(\mathscr{L}(G))$ and let $\bar{k}, \bar{k}_{t}$ be the mappings defined by (3.1) and (3.2). Since $j_{0}^{r} \bar{k}_{t}$ is the 1-parameter subgroup of $\Omega_{G}(X) \in \mathscr{L}\left(T^{p, r} G\right)$, thus

$$
\left(\exp _{T^{p, r G}} \circ \Omega_{G}\right)(X)=j_{0}^{r} \bar{k}_{1}=j_{0}^{r}\left(\exp _{G} k\right)=\left(T^{p, r} \exp _{G}\right)(X) .
$$

Proposition 3.4. $\Omega_{G}$ is bijective.
Proof. Let $X=j_{0}^{r} k \in T^{p, r}(\mathscr{L}(G))$ such that $\Omega_{G}(X)=0$. Let $k$ and $k_{t}$ be the mappings defined by (3.1) and (3.2). $\Omega_{G}(X)$ is a left invariant vector field on $T^{p, r} G$, and $j_{0}^{r} \bar{k}_{t}$ is the 1-parameter subgroup of $\Omega_{G}(X)$. This implies that $j_{0}^{r} \bar{k}_{t}=\bar{e}$ for each $t$. Since the diagram in Proposition 3.3 is commutative, it follows

$$
\begin{equation*}
T^{p, r}\left(\exp _{G}\right)(t X)=j_{0}^{r} \bar{k}_{t}=\bar{e} . \tag{3.5}
\end{equation*}
$$

The mapping $\exp _{G}$ is a diffeomorphism of a neighborhood $V$ of 0 in $\mathscr{L}(G)$ onto a neighborhood of $e$. Therefore $T^{p, r} \exp _{G}$ is a diffeomorphism of $\pi^{-1}(V)$, neighborhood of $0 \in T^{p, r}(\mathscr{L}(G))$, onto a neighborhood of $\bar{e}$, where $\pi$ : $T^{p, r}(\mathscr{L}(G)) \rightarrow \mathscr{L}(G)$
is the canonical projection. Then there exists $t \neq 0$ such that $t X \in \pi^{-1}(V)$. Now (3.5) implies that $t X=0$, and hence, $X=0$. Since $\Omega_{G}$ is linear, $\Omega_{G}: T^{p . r}(\mathscr{L}(G)) \rightarrow$ $\rightarrow \mathscr{L}\left(T^{p, r} G\right)$ is injective. On the other hand,

$$
\operatorname{dim} T^{p, r}(\mathscr{L}(G))=\binom{p+r}{r} \operatorname{dim} G=\operatorname{dim} \mathscr{L}\left(T^{p, r} G\right)
$$

which implies that $\Omega_{G}$ is a linear isomorphism.
Proposition 3.5. Let $\operatorname{Ad}_{j_{0} r_{\xi}}: \mathscr{L}\left(T^{p, r} G\right) \rightarrow \mathscr{L}\left(T^{p, r} G\right)$ be the adjoint automorphism. Then the mapping

$$
\overline{\mathrm{Ad}}_{j_{0^{r} \xi}}=\Omega_{G}^{-1} \circ \operatorname{Ad}_{j_{0} r \xi} \circ \Omega_{G}: T^{p, r}(\mathscr{L}(G)) \rightarrow T^{p, r}(\mathscr{L}(G))
$$

is given by

$$
\begin{equation*}
\overline{\mathrm{Ad}}_{j_{0} 0_{\xi}}(X)=X^{\prime} \tag{3.6}
\end{equation*}
$$

where $X=j_{0}^{r} k, X^{\prime}=j_{0}^{r} k^{\prime}$ and $k^{\prime}(u)=\operatorname{Ad}_{\xi(u)}(k(u))$.
Proof. Let $\bar{k}$ and $\bar{k}_{t}$ be the mappings defined by (3.1) and (3.2) for $X=j_{0}^{r} k$. Define

$$
\bar{k}^{\prime}: R^{p} \times R \ni(u, t) \rightarrow \xi(u) k(u, t) \xi^{-1}(u) \in G
$$

and $\bar{k}_{t}^{\prime}(u)=\bar{k}^{\prime}(u, t)=\xi(u) \bar{k}_{t}(u) \xi^{-1}(u)$. For a fixed $u \in \boldsymbol{R}^{p}, \bar{k}_{t}^{\prime}(u)$ is a 1-parameter subgroup of $G$ which defines the left invariant vector field $k^{\prime}(u)=\operatorname{Ad}_{\xi(u)}(k(u))$. So, bearing in mind the definition of $\Omega_{G}$ we obtain (3.6).

Proposition 3.6. $\Omega_{G}$ is a Lie algebra isomorphism.
Proof. According to Proposition 3.2 and 3.4 we only need to verify that for any $X=j_{0}^{r} k$ and $Y=j_{0}^{r} l$ in $T^{p, r}(\mathscr{L}(G))$

$$
\begin{equation*}
\Omega_{G}[X, Y]=\left[\Omega_{G}(X), \Omega_{G}(Y)\right] \tag{3.7}
\end{equation*}
$$

Let $\bar{k}$ and $\bar{k}_{t}$ be the mappings defined by (3.1) and (3.2) for $X=j_{0}^{r} k$. The definition of $\Omega_{G}$ implies that $a_{t}=j_{0}^{r} \overline{\bar{k}}_{t}$ is the 1-parameter subgroup of $\Omega_{G}(X)$. Then we have

$$
\left[\Omega_{G}(X), \Omega_{G}(Y)\right]=\frac{\mathrm{d}}{\mathrm{~d} t}\left(\left.\operatorname{Ad}_{a_{t}}\left(\Omega_{G}(Y)\right)\right|_{t=0}=\Omega_{G}\left(\left.\frac{\mathrm{~d}}{\mathrm{~d} t}\left(\Omega_{G}^{-1} \circ \operatorname{Ad}_{a_{\mathrm{t}}} \circ \Omega_{G}\right)(Y)\right|_{t=0}\right)\right.
$$

where in the last equality we use the linearity of $\Omega_{G}^{-1}$. Now from Proposition 3.5 we get

$$
\left[\Omega_{G}(X), \Omega_{G}(Y)\right]=\Omega_{G}\left(\left.\frac{\mathrm{~d}}{\mathrm{~d} t}\left(j_{0}^{r} l_{t}^{\prime}\right)\right|_{t=0}\right)
$$

where $l_{t}^{\prime}(u)=\operatorname{Ad}_{\bar{k}_{t}(u)}(l(u))$. Since $\bar{k}_{t}(u)$ is the 1-parameter subgroup of $k(u)$ and

$$
\left.\frac{\mathrm{d}}{\mathrm{~d} t}\left(j_{0}^{r} l_{t}^{\prime}\right)\right|_{t=0}=[k(u), l(u)]=[k, l](u)
$$

we obtain that (3.7) holds.

Proposition 3.7. If $f: G \rightarrow G^{\prime}$ is a Lie group homomorphism, then the diagram

commutes.
Proof. Let $X=j_{0}^{r} k \in T^{p, r}(\mathscr{L}(G))$ and let $k$ and $k_{t}$ be the mappings defined by (3.1) and (3.2). Define

$$
\bar{k}^{\prime}(u, t)=f(\bar{k}(u, t)), \quad \bar{k}_{t}(u)=\bar{k}^{\prime}(u, t)=\left(f \circ \bar{k}_{t}\right)(u),
$$

$\bar{k}_{t}^{\prime}(u)$ is the 1-parameter subgroup of $\mathscr{L}(f) k(u)$. On the other hand $j_{0}^{r} k_{t}^{\prime}=\left(T^{p, r}\right)\left(j_{0}^{r} k_{t}\right)$ is the 1-parameter subgroup of $\mathscr{L}\left(T^{p, r} f\right)\left(\Omega_{G}(X)\right)$. Then

$$
\begin{aligned}
& \left(\Omega_{G^{\prime}} \circ T^{p, r}(\mathscr{L} f)\right)(X)=\Omega_{G^{\prime}}\left(j_{0}^{r}((\mathscr{L} f) \circ k)\right)=\left.\frac{\mathrm{d}}{\mathrm{~d} t}\left(j_{0}^{r} \bar{k}_{t}^{\prime}\right)\right|_{t=0}= \\
& =\mathscr{L}\left(T^{p \cdot r} f\right)\left(\Omega_{G}(X)\right)
\end{aligned}
$$

and the proof of the Proposition 3.7 is complete.
Proof of Theorem 3.1. It follows directly as an immediate consequence of Propositions 3.6 and 3.7.

Proposition 3.8. If $H$ is a Lie subgroup of a Lie group G, then $T^{p, r}(\mathscr{L}(H))$ and $\mathscr{L}\left(T^{p, r} H\right)$ are Lie subalgebras of $T^{p, r}(\mathscr{L}(G))$ and $\mathscr{L}\left(T^{p, r} G\right)$ respectively and $\Omega_{H}=\left.\Omega_{G}\right|_{T^{p, r(\mathscr{Y}(H))}}$.

Proof. The inclusion $i_{H}: H \rightarrow G$ induces the inclusions $T^{p, r}\left(\mathscr{L} i_{H}\right): T^{p, r}(\mathscr{L}(H)) \rightarrow$ $\rightarrow T^{p, r}(\mathscr{L}(G))$ and $\mathscr{L}\left(T^{p, r} i_{H}\right): \mathscr{L}\left(T^{p, r} H\right) \rightarrow \mathscr{L}\left(T^{p, r} G\right)$. Now the result follows from Proposition 3.7.

## 4. PROLONGATIONS OF HOMOGENEOUS SPACES

First we prove the following proposition.
Proposition 4.1. If $M=G / H$ is a homogeneous space, then $T^{p, r} M$ is also a homogeneous space and $T^{p, r} M=T^{p, r} G / T^{p, r} H$.

Proof. Let us consider the point $o=e H$ of $M$ and let $H$ be the isotropy group of $G$ at $o$. The action of $T^{p, r} G$ on $T^{p, r} M$ is transitive according to Corollary 2.4. Let $\bar{\sigma}$ be the point of $T^{p, r} M$ defined by (1.1) and $\bar{H}$ the isotropy subgroup of $T^{p, r} G$ at $\bar{o}$, then $T^{p, r} M=T^{p, r} G / \bar{H}$. To prove the proposition we only need to show

$$
\begin{equation*}
\bar{H}=T^{p, r} H \tag{4.1}
\end{equation*}
$$

The inclusion $T^{p, r} H \subset \bar{H}$ is an immedaite consequence of Proposition 2.5. To verify the second inclusion we define the mappings

$$
\begin{array}{ll}
\varrho_{0}: G \rightarrow M, & \varrho_{0}(\xi)=\xi_{0} \\
\varrho_{o}: T^{p, r} G \rightarrow T^{p, r} M, & \varrho_{0}\left(j_{0}^{r} \xi\right)=j_{0}^{r} \xi \bar{o} .
\end{array}
$$

Then $\left(T^{p . r} \varrho_{0}\right)\left(j_{0}^{r} \xi\right)=j_{0}^{r}\left(\varrho_{0} \xi\right)=j_{0}^{r}(\xi o)=j_{0}^{r} \xi \bar{o}=\varrho_{0}\left(j_{0}^{r} \xi\right)$, that is

$$
\begin{equation*}
T^{p, r} \varrho_{o}=\bar{\varrho}_{o} . \tag{4.2}
\end{equation*}
$$

We fix a vector subspace $W$ of $\mathscr{L}(G)$ such that $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$ (we do not suppose that $W$ is $\mathscr{L}(H)$-invariant). Now the mapping $\psi: \mathscr{L}(G) \rightarrow G, \psi(v)=$ $=\exp _{G}\left(v_{1}\right) \exp _{G}\left(v_{2}\right)$, where $v=v_{1}+v_{2}$ and $v_{1} \in \mathscr{L}(H), v_{2} \in W$, is a diffeomorphism of some neighborhood $U_{0}$ of zero in $\mathscr{L}(G)$ onto a neighborhood $V_{e}$ of $e$ in $G$ (see [1], [2]). We can suppose that $U_{0}=U_{10} \times U_{20}$, where $U_{10}$ and $U_{20}$ are neighborhoods of zero in $\mathscr{L}(H)$ and $W$ respectively. We consider a element $j_{0}^{r} \xi$ of $\bar{H}$, that is, $j_{0}^{r} \xi \bar{o}=\bar{o}$. This implies that $\xi(0)$ belongs to $H$. There exists a positive number $\varepsilon>0$ such that $(\xi(o))^{-1} \xi(u)$ belongs to $V_{e}$ for $|u| \times \varepsilon$. For every $u$ such that $|u|<\varepsilon$ there exists one and only one couple $(h(u), w(u))$ such that

$$
\begin{align*}
& (h(u), w(u)) \in U_{10} \times U_{20} \subset \mathscr{L}(H) \times W  \tag{4.3}\\
& \xi^{-1}(0) \xi(u)=\exp _{G}(h(u)) \exp _{G}(w(u)) . \tag{4.3}
\end{align*}
$$

Since $\xi(o)$ belongs to $H$, then $\xi(0)=j_{0}^{r}(\xi(0))$ given by (1.1) belongs to $T^{p, r} H \subset \bar{H}$. For every $u$ such that $|u|<\varepsilon$ we have $\exp _{G}(h(u)) \in H$ and from this $j_{0}^{r}\left(\exp _{G} h\right) \in$ $\in T^{p \cdot r} H \subset \bar{H}$. Now (4.3) implies

$$
\begin{equation*}
\overline{\xi(0)}{ }^{-1} j_{0}^{r} \xi=j_{0}^{r}\left(\exp _{G} h\right) j_{0}^{r}\left(\exp _{G} w\right) . \tag{4.4}
\end{equation*}
$$

From this we obtain

$$
\begin{equation*}
j_{0}^{r}\left(\exp _{G} w\right) \in \bar{H} . \tag{4.5}
\end{equation*}
$$

From Lemma 4.1 in [2] there is a neighborhood of zero in $W$ such that $\varrho_{0}$ 。 - $\exp _{G i W}: W \rightarrow M$ is a diffeomorphism of this neighborhood onto some open neighborhood of $o$ in $M$. We can suppose that $U_{20}$ is a such neighborhood in $W$. This implies that

$$
T^{p, r}\left(\varrho_{0} \circ \exp _{G \mid W}\right): T^{p, r} W \rightarrow T^{p, r} M
$$

is a diffeomorphism of $\left.T^{p, r} W\right|_{U_{20}}$ onto some neighborhood of $\bar{o}$ in $T^{p, r} M$. From (4.3) we have $w(0)=0$. It follows that $\left.j_{0}^{r} w \in T^{p, r} W\right|_{U_{20}}$. Now, from (4.2) and (4.5) we obtain

$$
T^{p, r}\left(\varrho_{o} \circ \exp _{G \mid U}\right)\left(j_{0}^{r} w\right)=\left(T^{p, r} \varrho_{o}\right)\left(j_{0}^{r}\left(\exp _{G} w\right)\right)=\bar{\varrho}_{o}\left(j_{0}^{r}\left(\exp _{G} w\right)\right)=\bar{o} .
$$

On the other hand, we also have $T^{p, r}\left(\varrho_{0} \circ \exp _{G \mid W}\right)(0)=\bar{o}$, which implies that $j_{0}^{r} w=$ $=0$, and from Propositions 3.2 and 3.2 we obtain

$$
j_{0}^{r}\left(\exp _{G} w\right)=\left(T^{p, r} \exp _{G}\right)(0)=\left(\exp _{T^{p}, r_{G}} \circ \Omega_{G}\right)(0)=\bar{e}
$$

where $\bar{e}$ is the identity element of $T^{p, r} G$.
Now from (4.4) $\overline{\xi(0)}{ }^{-1} j_{0}^{r} \xi=j_{0}^{r}\left(\exp _{G} \circ h\right)$ belongs to $T^{p, r} H$, which implies that $j_{0}^{r} \xi$ belongs to $T^{p, r} H$ because $\overline{\xi(0)} \in T^{p, r} H$. The proof of (4.1) is done.

From Proposition 4.1 we obtain immediately (the case $p=r=1$ ).
Corollary 4.2. If $M=G / H$ is a homogeneous space, then the tangent bundle $T M$ is a homogeneous space and $T M=T G / T H$.

The above corollary generalizes the Proposition 3.1 of M. Sekizawa (see [11]).
Proposition 4.3. If $M=G / H$ is a reductive homogeneous space with respect to a $\mathscr{L}(H)$-invariant decomposition $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$, then $T^{p, r} M=T^{p, r} G / T^{p, r} H$ is a reductive homogeneous space with respect to a decomposition $\mathscr{L}\left(T^{p, r} H\right) \oplus$ $\oplus \Omega_{G}\left(T^{p, r} W\right)$, where $\Omega_{G}$ is the natural isomorphism constructed in Section 3.

Proof. The equality $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$ imply $T^{p . r}(\mathscr{L}(G))=T^{p . r}(\mathscr{L}(H)) \oplus$ $\oplus T^{p, r} W$. Since $\Omega_{G}$ is a Lie algebra isomorphism and $\Omega_{G}\left(T^{p, r}(\mathscr{L}(H))=\mathscr{L}\left(T^{p, r} H\right)\right.$ (this is a consequence of Proposition 3.8), then $\mathscr{L}\left(T^{p, r} G\right)=\mathscr{L}\left(T^{p, r} H\right) \oplus \Omega_{G}\left(T^{p, r} W\right)$. Now, we only need to show that $\operatorname{Ad}\left(T^{p, r} H\right)\left(\Omega_{G}\left(T^{p, r} W\right)\right) \subset \Omega_{G}\left(T^{p, r} W\right)$. If $j_{0}^{r} k \in T^{p, r} W$ and $j_{0}^{r} \xi \in T^{p . r} H$, then, taking into account Proposition 3.5 we have

$$
\operatorname{Ad}\left(j_{0}^{r} \xi\right)\left(\Omega_{G}\left(j_{0}^{r} k\right)\right)=\Omega_{G}\left(\overline{\operatorname{Ad}}\left(j_{0}^{r} \xi\right)\left(j_{0}^{r} k\right)\right)=\Omega_{G}\left(j_{0}^{r}\left(\operatorname{Ad}_{\xi} k\right)\right) \in \Omega_{G}\left(T^{p, r} W\right)
$$

because $\operatorname{Ad}(H)(W) \subset W$.
Therefore, according to Proposition 4.1, $T^{p, r} M$ is a reductive homogeneous space with respect to the $\mathscr{L}\left(T^{p, r} H\right)$-invariant decomposition $\mathscr{L}\left(T^{p, r} G\right)=\mathscr{L}\left(T^{p, r} H\right) \oplus$ $\left.\left.\oplus \Omega_{G}\right) T^{p, r} W\right)$.

As an immediate consequence of Proposition 4.3 we have
Proposition 4.4. (M. Sekizawa [11]). If $M=G / H$ is a reductive homogeneous space with respect to a decomposition $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$, then $T M=T G / T H$ is a reductive homogeneous space with respect to a decomposition $\mathscr{L}(T G)=$ $=\mathscr{L}(T H) \oplus \Omega_{G}(T W)$. We can identify $\Omega_{G}(T W)$ with $T W$.

Next, we shall study canonical connections on reductive homogeneous spaces. Firstly, we prove the following lemma:

Lemma 4.5. If $X$ is an element of $\mathscr{L}(G)$ and $\Omega_{G}$ is the natural isomorphism constructed in Section 3, then for every $\alpha$ such that $|\alpha| \leqq r$ we have

$$
\Omega_{G}\left(j_{0}^{r} k_{X}^{\alpha}\right)=X^{\langle\alpha\rangle}
$$

where $k_{X}^{\alpha}: R^{p} \rightarrow \mathscr{L}(G)$ is given by $k_{X}^{\alpha}(u)=u^{\alpha} X$.
Proof. It suffices to show

$$
\begin{equation*}
\left(\Omega_{G}\left(j_{0}^{r} k_{X}^{\alpha}\right)_{\bar{e}}=X_{\bar{e}}^{\langle\alpha\rangle},\right. \tag{4.6}
\end{equation*}
$$

where $\bar{e}$ is the identity element of $T^{p, r} G$.
Let us consider the mapping

$$
\begin{equation*}
\bar{k}: R^{p} \times R \ni(u, t) \rightarrow \exp _{G}\left(t k_{X}^{\alpha}(u)\right) \in G \tag{4.7}
\end{equation*}
$$

and $\bar{k}_{t}(u)=\bar{k}(u, t)$. From the definition of $\Omega_{G}$ we have

$$
\left(\Omega_{G}\left(j_{0}^{r} k_{X}^{\alpha}\right)\right)_{\bar{e}}=\left.\frac{\mathrm{d}}{\mathrm{~d} t}\left(j_{0}^{r} \bar{k}_{t}\right)\right|_{t=0} .
$$

Now we choose a chart in a neighborhood of the identity element $e$. The induced
chart on $T^{p, r} G$ is defined in some neighborhood of $\bar{e}$. From (4.7) we deduce that the coordinates $\tilde{X}^{i}$ of $\left(\Omega_{G}\left(j_{0}^{r} k_{X}^{\alpha}\right)\right)_{\bar{e}}$ are given by

$$
\begin{aligned}
& \tilde{X}_{\beta}^{i}=\left.\frac{\mathrm{d}}{\mathrm{~d} t}\left(\frac{1}{\beta!}\left(D_{\beta} \bar{k}_{t}^{i}\right)(0)\right)\right|_{t=0}=\left.\frac{1}{\beta!} D_{\beta}\left(\left.\left(\frac{\mathrm{d}}{\mathrm{~d} t} \bar{k}_{t}^{i}\right)(u)\right|_{t=0}\right)\right|_{u=0}= \\
& =\left.\frac{1}{\beta!} D_{\beta}\left(u^{\alpha} X^{i}\right)\right|_{u=0}=\delta_{\beta}^{\alpha} X^{i} .
\end{aligned}
$$

On the other hand, the coordinates $\bar{X}_{\beta}^{i}$ of $X^{\langle\alpha\rangle}$ are (see A. Morimoto [8], [9])

$$
\bar{X}_{\beta}^{i}=\left(X^{i}\right)^{(\beta-\alpha)}(\bar{e})=\frac{1}{(\beta-\alpha)!} D_{\beta-x}\left(X^{i}(e)\right)=\delta_{\alpha}^{\beta} X^{i} .
$$

Thus, identity (4.6) holds.
Let us recall that the canonical connection on a reductive homogeneous space is characterized by the following theorem (Theorem I. 10 O. Kowalski [7]).

Theorem 4.6. Let $M=G / H$ be a reductive homogeneous space with respect to a decomposition $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$, where $G$ is a connected Lie group. The canonical connection on $M$ is the unique G-invariant affine connection such that

$$
\begin{equation*}
\left(\nabla_{U^{*}} Y\right)_{0}=\left[U^{*}, Y\right]_{0} \tag{4.8}
\end{equation*}
$$

for any element $U \in W$ and every vector field $Y$ on $M$, where $o=e H$, and $U^{*}$ denotes the fundamental vector field on $M$ defined by $U$.

Using this theorem we can state:
Proposition 4.7. Let $M=G / H$ be a reductive homogeneous space with respect to a decomposition $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$, where $G$ is a connected Lie group. If $\nabla$ is the canonical connection on $M$, then the complete lift $\nabla^{c}$ of $\nabla$ from $M$ to $T^{p, r} M$ is the canonical connection on $T^{p, r} M=T^{p, r} G / T^{p, r} H$.

Proof. According to Proposition 4.3, $T^{p, r} M$ is a reductive homogeneous space with respect to a decomposition $\mathscr{L}\left(T^{p, r} G\right)=\mathscr{L}\left(T^{p, r} H\right) \oplus \Omega_{G}\left(T^{p, r} W\right)$.

By Proposition 2.7 the connection $\nabla^{c}$ is $T^{p, r} G$-invariant affine connection on $T^{p, r} M$. To prove the proposition we are reduced to show

$$
\begin{equation*}
\left(\nabla_{\tilde{\sigma}^{*}}^{C}, \tilde{Y}\right)_{\bar{o}}=\left[\tilde{U}^{*}, \tilde{Y}\right]_{\bar{o}} \tag{4.9}
\end{equation*}
$$

where $\tilde{U}$ is an element of $\mathscr{L}_{G}\left(T^{p, r} W\right)$ and $\tilde{Y}$ is a vector field on $T^{p, r} M$.
Let $U$ be an element of $W$ and $Y$ be a vector field on $M$. By Lemma 4.5, for every $\alpha$ such that $|\alpha| \leqq r$, we have $U^{\langle\alpha\rangle}=\Omega_{G}\left(j_{0}^{r} k_{U}^{\alpha}\right)$, where $k_{U}^{\alpha}(u)=u^{\alpha} U \in W$, and so $U^{\langle\alpha\rangle}$ belongs to $\Omega_{G}\left(T^{p, r} W\right)$.

Now for every $\alpha, \beta$ such that $|\alpha| \leqq r,|\beta| \leqq r$, using Proposition 2.2 and formulas (2.11) and (4.8) we obtain

$$
\begin{equation*}
\nabla_{U^{\langle\alpha\rangle} *}^{C} Y^{\langle\alpha\rangle}=\left[U^{\langle\alpha\rangle *}, Y^{\langle\beta\rangle}\right] . \tag{4.10}
\end{equation*}
$$

Thus, (4.9) holds in the case $\tilde{U}=U^{\langle\alpha\rangle}$ and $\tilde{Y}=Y^{\langle\beta\rangle}$.

Let $\tilde{U}$ be an element of $\Omega_{G}\left(T^{p . r} W\right)$ and $\tilde{Y}$ be a vector field on $T^{p, r} M$. If $U_{1}, \ldots, U_{k}$ is a basis of $W$, then (see the proof of Proposition 2.6)

$$
\left\{U_{i}^{\langle\alpha\rangle}: i=1, \ldots, k ;|\alpha| \leqq r\right\}
$$

is a basis of $\Omega_{G}\left(T^{p \cdot r} W\right)$. Therefore there exist real numbers $a_{\alpha}^{i}, i=1, \ldots, k,|\alpha| \leqq r$ such that

$$
\begin{equation*}
\tilde{U}=\sum_{i} \sum_{\alpha} a_{\alpha}^{i} U_{i}^{\langle\alpha\rangle} . \tag{4.11}
\end{equation*}
$$

For a vector field $\tilde{Y}$ on $T^{p . r} M$ there exist vector fields $Y_{1}, \ldots, Y_{s}$ on $M$, functions $\tilde{h}_{1}, \ldots, \tilde{h}_{s}$ on $T^{p . r} M$ and $\alpha_{1}, \ldots, x_{s}$ such that $\left|\alpha_{j}\right| \leqq r, j=1, \ldots, s$, and

$$
\begin{equation*}
\tilde{Y}=\sum_{i} \tilde{h}_{i} Y_{i}^{\left\langle\alpha_{i}\right\rangle} . \tag{4.12}
\end{equation*}
$$

Then from (4.10), (4.11) and (4.12) we obtain (4.9) in the general case.
We also prove another result for later use:
Proposition 4.8. If $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$ is a $\mathscr{L}(H)$-invariant decomposition of a Lie algebra $\mathscr{L}(G)$ of a Lie group $G$, where $H$ is a closed subgroup of $G$, and

$$
\begin{equation*}
\mathscr{L}(G)=W \oplus[W, W] \tag{4.13}
\end{equation*}
$$

then for the Lie algebra $\mathscr{L}\left(T^{p, r} G\right)=\mathscr{L}\left(T^{p, r} H\right) \oplus \Omega_{G}\left(T^{p, r} W\right)$ we have

$$
\begin{equation*}
\mathscr{L}\left(T^{p, r} G\right)=\bar{W} \oplus[\bar{W}, \bar{W}], \tag{4.14}
\end{equation*}
$$

where $\bar{W}=\Omega_{G}\left(T^{p \cdot r} W\right)$.
Proof. Since $M=G / H$ is a reductive homogeneous space with respect to a decomposition $\mathscr{L}(G)=\mathscr{L}(G) \oplus W$, by Proposition 4.3 we have

$$
\mathscr{L}\left(T^{p, r} G\right)=\mathscr{L}\left(T^{p, r} H\right) \oplus \bar{W}, \quad\left[\mathscr{L}\left(T^{p, r} H\right), \bar{W}\right] \subset \bar{W}
$$

where $\bar{W}=\Omega_{G}\left(T^{p, r} W\right)$. If $X_{1}, \ldots, X_{k}$ is a basis of $W$, then (4.13) implies that the set

$$
\left\{X_{1}, \ldots, X_{k}\right\} \cup\left\{\left[X_{i}, X_{j}\right]: i, j=1, \ldots, k\right\}
$$

generates $\mathscr{L}(G)$. Hence, there exist $i_{1}, \ldots, i_{q}, j_{1}, \ldots, j_{q}$ such that $\left\{X_{1}, \ldots, X_{k}\right.$, $\left.\left[X_{i_{1}}, X_{j_{1}}\right], \ldots,\left[X_{i_{2}}, X_{j_{2}}\right]\right\}$ is a basis of $\mathscr{L}(G)$.

Let $\tilde{X}$ be an element of $\mathscr{L}\left(T^{p, r} G\right)$. Since $\Omega_{G}$ is an isomorphism, there exists $j_{0}^{r} k \in$ $\in T^{p, r}(\mathscr{L}(G))$ such that $\tilde{X}=\Omega_{G}\left(j_{0}^{r} k\right)$.

For every $u \in R^{p}, k(u)$ is an element of $\mathscr{L}(G)$. This implies that there are real numbers $a_{1}(u), \ldots, a_{k}(u)$ and $b_{1}(u), \ldots, b_{s}(u)$ such that

$$
k(u)=\sum_{i=1}^{k} a_{i}(u) X_{i}+\sum_{q=1}^{s} b_{q}(u)\left[X_{i_{q}}, X_{j_{q}}\right] .
$$

The unicity of the $a_{i}(u)$ and $b_{q}(u)$ implies that $a_{i}$ and $b_{q}$ are functions of class $C^{\infty}$ on $R^{p}$. Now

$$
j_{0}^{r} k=\sum_{i=1}^{k} j_{0}^{r}\left(a_{i} X_{i}\right)+\sum_{q=1}^{s} j_{0}^{r}\left(b_{q}\left[X_{i_{q}}, X_{j_{q}}\right]\right)
$$

belongs to $T^{p, r} W+\left[T^{p, r} W, T^{p, r} W\right]$. Since $\Omega_{G}$ is a Lie algebra homomorphism, $\tilde{X}=\Omega_{G}\left(j_{0}^{r} k\right)$ belongs to $\bar{W} \oplus[\bar{W}, \bar{W}]$, where $\bar{W}=\Omega_{G}\left(T^{p, r} W\right)$. The proof of (4.14) is done.

Let $\nabla$ be an affine connection on a connected manifold $M$. The group of all transformations of $M$ preserving each holonomy subbundle of the principal fibre bundle $L M$ of linear frames is called the group of transvections of $(M, \nabla)$. This group will be denoted by $\operatorname{Tr}(M, \nabla) .(M, \nabla)$ is called an affine reductive space if the group $\operatorname{Tr}(M, \nabla)$ acts transitively on each holonomy subbundle of $L M$ (this definition is due to O. Kowalski [7]). Now we prove:

Theorem 4.9. If $(M, \nabla)$ is an affine reductive space, then $\left(T^{p, r} M, \nabla^{c}\right)$ is an affine reductive space, where $\nabla^{c}$ is the complete lift of $\nabla$ to $T^{p . r} M$. Furthermore

$$
\operatorname{Tr}\left(T^{p, r} M, \nabla^{C}\right)=T^{p, r}(\operatorname{Tr}(M, \nabla))
$$

Proof. According to Theorem 1.25 in [7], $M$ can be expressed as $M=G / H$, where $G=\operatorname{Tr}(M, \nabla)$ and $H$ is the isotropy subgroup of $G$ at a point $o$ of $M$. Moreover, $M=G / H$ is a reductive homogeneous space with respect to a decomposition $\mathscr{L}(G)=$ $=\mathscr{L}(H) \oplus W, \nabla$ is the canonical connection of $M$ and we have $\mathscr{L}(G)=W \oplus$ $\oplus[W, W]$. Now from Proposition 4.3, $T^{p, r} M=T^{p, r} G / T^{p, r} H$ is a reductive homogeneous space with respect to the decomposition $\mathscr{L}\left(T^{p, r} G\right)=\mathscr{L}\left(T^{p, r} H\right) \oplus \bar{W}$, where $\bar{W}=\Omega_{G}\left(T^{p, r} W\right)$. From Proposition 4.7, the complete lift $\nabla^{C}$ of $\nabla$ is the canonical connection on $T^{p, r} M$ and from Proposition 4.8 we also have $\mathscr{L}\left(T^{p, r} G\right)=$ $=\bar{W} \oplus[\bar{W}, \bar{W}]$. Using Theorem I. 25 in [7] we obtain that $\left(T^{p, r} M, \nabla^{C}\right)$ is an affine reductive space and

$$
\operatorname{Tr}\left(T^{p, r} M, \nabla^{c}\right)=T^{p, r} G=T^{p, r}(\operatorname{Tr}(M, \nabla)) .
$$

The proof is now complete.
To prove the above theorem we have used the same arguments that M. Sekizawa in [11] who proved this theorem in case $p=r=1$.

Let $M=G / H$ be a homogeneous space and $g$ be a $G$-invariant pseudometric tensor on $M .(M, g)$ is called naturally reductive if there exists an $\mathscr{L}(H)$-invariant decomposition $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$ such that

$$
\begin{equation*}
\left\langle[U, V]_{W}, Z\right\rangle=\left\langle U,[V, Z]_{W}\right\rangle \tag{4.15}
\end{equation*}
$$

for all elements $U, V, Z$ of $W$, where $\langle$,$\rangle denotes the inner product on W$ induced by $g$ via the isomorphism $\left.d_{e} \pi\right|_{W}: W \rightarrow T_{0} M$, where $\pi: G \ni \xi \rightarrow \xi o \in M$ is the projection and $[U, V]_{W}$ is the $W$-component of $[U, V]$ with respect to the decomposition $\mathscr{L}(G)=\mathscr{L}(H) \oplus W$. It is easy observe that the condition (4.15) is equivalent to the following one:

$$
\begin{equation*}
g\left(\left([U, V]_{W}\right)^{*}, Z^{*}\right)=g\left(U^{*},\left([V, Z]_{W}\right)^{*}\right), \tag{4.16}
\end{equation*}
$$

where $U^{*}$ is the fundamental vector field defined by $U$.

In the case of the tangent bundle $T^{r} M=T^{1, r} M$ of order $r$ we can state the following theorem:

Theorem 4.10. If a homogeneous space $M=G \mid H$, where $G$ is a connected Lie group, is naturally reductive with respect to a $G$-invariant pseudometric $g$, then the homogeneous space $T^{p, r} M=T^{p, r} G / T^{p, r}$ is naturally reductive with respect to the complete lift $g^{(r)}$ of $g$ to $T^{p, r} M$.

Proof. We recall that the complete lift $g^{(r)}$ of $g$ to the bundle $T^{r} M$, which is a pseudometric tensor on $T^{r} M$, is given by (see A. Morimoto [8], [10])

$$
\begin{equation*}
g^{(r)}\left(X^{(\alpha)}, Y^{(\beta)}\right)=(g(x, y))^{(\alpha+\beta-r)} \tag{4.17}
\end{equation*}
$$

where $X^{(\alpha)}$ is the $\alpha$-lift of a vector field $X$ from $M$ to $T^{p, r} M$. From Proposition $2.7 g^{(r)}$ is $T^{r} G$-invariant.

If $U$ is an element of $W$, then for every $\alpha, U^{(x)}$ belongs to $\Omega_{G}\left(T^{r} W\right)$ because Lemma 4.5 and formula (1.8) imply $U^{(\alpha)}=U^{\langle r-\alpha\rangle}=\Omega_{G}\left(j_{0}^{r} k_{U}^{r-\alpha}\right)$ and $k_{U}^{r-\alpha}(u)=u^{r-\alpha}$. Now according to (1.9) for every $\alpha, \beta=0, \ldots, r$ and $U, V \in W$ we have

$$
\begin{equation*}
\left[U^{(x)}, V^{(\beta)}\right]_{W}=\left([U, V]_{W}\right)^{(x+\beta-r)} . \tag{4.18}
\end{equation*}
$$

From (4.16), (4.17), (4.18) and Proposition 2.2 we obtain

$$
g^{(r)}\left(\left(\left[U^{(x)}, V^{(\beta)}\right]_{W}\right)^{*}, \quad Z^{(\gamma) *}\right)=g^{(r)}\left(U^{(x) *},\left(\left[V^{(\beta)}, Z^{(\gamma)}\right]_{W}\right)^{*}\right)
$$

which means that $T^{r} M$ is naturally reductive with respect to $g^{(r)}$, because the set $\left\{U^{(\alpha)}: U \in W, \alpha=0, \ldots, r\right\}$ generates $\bar{W}$.

In case $r=1$, the above theorem was obtained by M. Sekizawa [11]. In Theorem 4.10 we consider only the bundle $T^{r} M=T^{1, r} M$ instead of $T^{p, r} M$, because A. Morimoto's construction gives a pseudometric on $T^{p, r} M$ as a lift of a pseudometric from $M$ uniquelly in case $p=1$ (see [8], [9], [10]).

## 5. PROLONGATIONS OF $s$-STRUCTURES

A regular $s$-structure on a manifold $M$ is a mapping

$$
M \times M \ni(x, y) \rightarrow s_{x}(y) \in M
$$

of class $C^{\infty}$ such that for all points $x$ and $y$ we have

$$
\begin{align*}
& s_{x}(x)=x  \tag{5.1}\\
& s_{x}: M \rightarrow M \text { is a diffeomorphism }  \tag{5.2}\\
& s_{x} \circ s_{y}=s_{z} \circ s_{x}, \text { where } z=s_{x}(y)  \tag{5.3}\\
& d_{x} s_{x}: T_{x} M \rightarrow T_{x} M \text { has not fixed vectors except the null vector. } \tag{5.4}
\end{align*}
$$

A couple $\left(M,\left\{s_{x}\right\}\right)$ is called a s-manifold if $M$ is a manifold and $\left\{s_{x}\right\}$ is a regular $s$-structure on $M$. For each $x, s_{x}$ is called a symmetry. A diffeomorphism $\varphi: M \rightarrow M$ is called an automorphism of $\left(M,\left\{s_{x}\right\}\right)$ if for every point $x$ of $M$ we have

$$
\begin{equation*}
\varphi \circ s_{x}=s_{\varphi(x)} \circ \varphi . \tag{5.5}
\end{equation*}
$$

The condition (5.3) implies that each symmetry $s_{x}$ is an automorphism of $\left(M,\left\{s_{x}\right\}\right)$. The definition of $s$-structures was introduced by O. Kowalski [7].

Theorem 5.1 (O. Kowalski [7]). Let $\left(M,\left\{s_{x}\right\}\right)$ be a connected s-manifold. We denote by $S$ the tensor field of type (1.1) on $M$ defined by $S_{x}=d_{x} s_{x}$ for $x \in M$. Then:
(a) There exists an unique connection $\nabla$ on $M$ (called the canonical connection) such that $\nabla$ is invariant under each symmetry $s_{x}$ and $\nabla S=0 . \nabla$ is complete and has parallel torsion and curvature.
(b) The group $\operatorname{Aut}\left(M,\left\{s_{x}\right\}\right)$ is a transitive Lie group of transformations of $M$, which is a closed subgroup of the group of affine transformations of $\nabla$.
(c) Let $G$ be the identity component of $\operatorname{Aut}\left(M,\left\{s_{x}\right\}\right)$, o a fixed point of $M$ and $H$ the isotropy subgroup of $G$ at 0 . Then $G / H$ is a reductive homogeneous space and, under the standard identification $G / H \ni x H \rightarrow x o \in M$, the connection $\nabla$ coincides with the canonical connection of $G / H$.

Let $\left(M,\left\{s_{x}\right\}\right)$ be a $s$-manifold. The group generated by all transformations of $M$ of type $s_{x}^{-1} \circ s_{y}$, where $x, y \in M$, is called the group of transvections of $\left(M,\left\{s_{x}\right\}\right)$ and denoted by $\operatorname{Tr}\left(M,\left\{s_{x}\right\}\right)$.

Theorem 5.2 (O. Kowalski). If $\left(M,\left\{s_{x}\right\}\right)$ is a s-manifold and $\nabla$ is the canonical connection on $M$, then $\operatorname{Tr}\left(M,\left\{s_{x}\right\}\right)=\operatorname{Tr}(M, \nabla)$.

It is easy to show the following proposition:
Proposition 5.3. Let $M$ be a connected manifold, $x_{0}$ a point of $M$ and $s_{0}: M \rightarrow M$ be a diffeomorphism such that $s_{0}\left(x_{0}\right)=x_{0}$, and suppose that $d_{x_{0}} s_{0}: T_{x_{0}} M \rightarrow T_{x_{0}} M$ has not fixed vectors except the null vector. If $G$ is a transitive Lie group of transformations of $M$ such that $s_{0}$ belongs to the center of the isotropy subgroup $H$ at $x_{0}$, then there exists an unique regular $s$-structure $\left\{s_{x}\right\}$ on $M$ such that $s_{x_{0}}=s_{0}$ and the transformations of $G$ are automorphisms of $\left(M,\left\{s_{x}\right\}\right)$.

Proof. If $x=\xi x_{0}$, then we define

$$
\begin{equation*}
s_{x}=\xi \circ s_{0} \circ \xi^{-1} \tag{5.6}
\end{equation*}
$$

Since every element of $H$ commutes with $s_{0}$, $\left\{s_{x}\right\}$ is a well-defined family of diffeomorphisms of $M$. The standard verification shows that $\left\{s_{x}\right\}$ is a regular $s$-structure on $M$ satisfying the statements of the proposition. We use precisely the same arguments as in the proof of Lemma 0.15 in [7].

Now we formulate the following theorem:
Theorem 5.4. If $\left(M,\left\{s_{x}\right\}\right)$ is a connected s-manifold, then there is a s-structure $\left\{s_{x}^{\prime}\right\}$ on $T^{p, r} M$ such that for every point $x$ of $M$

$$
s_{\bar{x}}^{\prime}=T^{p, r_{x}}
$$

where $\bar{x}$ is the $r$-jet at 0 of the constant mapping $R^{p} \ni u \rightarrow x \in M$.

If $\nabla$ is the canonical connection on $\left(M,\left\{s_{x}\right\}\right)$, then the complete lift $\nabla^{c}$ of $\nabla$ to $T^{p, r} M$ is the canonical connection on $\left(T^{p, r} M,\left\{s_{x^{\prime}}^{\prime}\right\}\right)$. Furthermore,

$$
\operatorname{Tr}\left(T^{p, r} M,\left\{s_{x}^{\prime}\right\}\right)=T^{p, r}\left(\operatorname{Tr}\left(M,\left\{s_{x}\right\}\right)\right) .
$$

To prove this theorem we need the lemma:
Lemma 5.5. Let $M$ be a manifold and $x_{0}$ a point of $M$. If $f: M \rightarrow M$ is a diffeomorphism such that $f\left(x_{0}\right)=x_{0}$ and $d_{x_{0}} f: T_{x_{0}} M \rightarrow T_{x_{0}} M$ has no fixed vectors except the null vector, then $T^{p, r} f\left(\bar{x}_{0}\right)=\bar{x}_{0}$ and $d_{\bar{x}_{0}}\left(T^{p, r} f\right): T_{\bar{x}_{0}} M \rightarrow T_{\bar{x}_{0}} M$ has no fixed vector except the null vector, where $\bar{x}_{0}$ is given by (1.1).

Proof. Let $\left(U, x^{i}\right)$ be a chart on $M$ such that $x^{i}\left(x_{0}\right)=0$. We denote by $\left(f^{1}, \ldots, f^{n}\right)$ the local expression of $f$ with respect to this chart. The hypothesis about $f$ imply

$$
\begin{align*}
& f^{i}(0)=0  \tag{5.7}\\
& \left(\vartheta f^{i} / \vartheta x^{j}\right)(0) v^{j}=0 \Rightarrow v^{i}=0, \quad i=1, \ldots, n . \tag{5.8}
\end{align*}
$$

On the other hand, the condition $\left(T^{p \cdot r} f\right)\left(\bar{x}_{0}\right)=\bar{x}_{0}$ is an immediate consequence of the equality $f\left(x_{0}\right)=x_{0}$. Let $V$ be a vector in $T_{\bar{x}_{0}}\left(T^{p, r} M\right)$ such that

$$
\begin{equation*}
d_{\bar{x}_{0}}\left(T^{p, r} f\right)(V)=V . \tag{5.9}
\end{equation*}
$$

If we denote by $V^{i}$ the coordinates of $V$ with respect to the induced chart, then from (5.9) and from the fact that the coordinates $x_{\alpha}^{i}$ of $\bar{x}_{0}$ are zero for all $i=1, \ldots, n$ and all $\alpha$ such that $|\alpha| \leqq r$, we obtain

$$
V_{x}^{i}=\left(\vartheta f^{i} / \vartheta x^{j}\right)(0) V_{x}^{j} .
$$

Now (5.8) implies that $V_{o}^{i}=0$ for all $i$ and $\alpha$. This means that $d_{\hat{x}_{0}}\left(T^{p, r} f\right)$ has no fixed vectors except the null vector.

Proof of Theorem 5.4. We fix a point $x_{0}$ of $M$. Let $G$ be the identity component of $\left(M,\left\{s_{x}\right\}\right)$ and $H$ be the isotropy subgroup of $G$ at $x_{0}$. Now $s_{0}=s_{x_{0}}$ belongs to the center of $H$. According to Lemma 5.5, $s_{0}^{\prime}=T^{p, r_{s}}$ is a diffeomorphism of $T^{p, r} M$ onto itself such that $s_{0}^{\prime}\left(\bar{x}_{0}\right)=\bar{x}_{0}$ and $d_{\bar{x}_{0}} s_{0}^{\prime}$ has no fixed vectors except the null vector. We also have

$$
\begin{equation*}
s_{0}^{\prime}=T^{p, r} s_{0} \in T^{p, r}(\text { center } H) \subset \operatorname{center}\left(T^{p, r} H\right) \tag{5.10}
\end{equation*}
$$

According to Proposition 5.1, $M$ is diffeomorphic to $G / H$. From Proposition 4.1, $T^{p, r} M$ is now diffeomorphic to $T^{p, r} G / T^{p, r} H$. From (5.10) and Proposition 5.3 there exists a regular $s$-structure $\left\{s_{x}^{\prime}\right\}$ on $T^{p, r} M$ such that

$$
\begin{equation*}
s_{\bar{x}_{0}}^{\prime}=s_{0}^{\prime}=T^{p, r_{x_{0}}} . \tag{5.11}
\end{equation*}
$$

From (5.6) and (5.11) for a point $x=\xi x_{0}$ of $M$ we have $\bar{x}=\bar{\xi} \bar{x}_{0}$ and

$$
s_{\bar{x}}^{\prime}=\bar{\xi} \circ s_{\bar{x}_{0}}^{\prime} \circ \bar{\xi}^{-1}=T^{p, r} \xi \circ T^{p, r} s_{x_{0}} \circ T^{p, r} \xi^{-1}=T^{p, r} s_{x} .
$$

Now, combining the results of Theorem 5.1, Theorem 5.2, Proposition 4.7 and Theorem 4.9 we obtain Proposition 5.4.

Let $(M, g)$ be a pseudometric space. A regular $s$-structure $\left\{s_{x}\right\}$ on $M$ is called a Riemann s-structure if each symmetry $s_{x}: M \rightarrow M$ is an isometry of $(M, g)$. In the case $p=1$, we can consider the complete lift $g^{(r)}$ of $g$ to $T^{r} M=T^{1, r} M . g^{(r)}$ given by the formula (4.7) is a pseudometric on $T^{r} M$.

We can state the following theorem.
Theorem 5.6. If $\left\{s_{x}\right\}$ is a Riemann s-structure on a connected pseudometric space $(M, g)$, then there exists a Riemann s-structure $\left\{s_{x_{x}^{\prime}}^{\prime}\right\}$ on $\left(T^{r} M, g^{(r)}\right)$ such that for every point $x$ of $M$

$$
\begin{equation*}
s_{\bar{x}}^{\prime}=T^{r} S_{x}, \tag{5.12}
\end{equation*}
$$

where $g^{(r)}$ is the complete lift of $g$ to $T^{r} M$ and $\bar{x}$ is the $r$-jet at 0 of the constant mapping $R \ni u \rightarrow x \in M$. The canonical connection on $T^{r} M$ is the complete lift of the canonical connection on $M$. Furthermore

$$
\begin{equation*}
T^{r}\left(\operatorname{Tr}\left(M, g,\left\{s_{x}\right\}\right)\right)=\operatorname{Tr}\left(T^{r} M, g^{(r)},\left\{s_{\bar{x}}^{\prime}\right\}\right) . \tag{5.13}
\end{equation*}
$$

Proof. We fix a point $x_{0}$ of $M$. Let $\operatorname{Aut}\left(M, g,\left\{s_{x}\right\}\right)$ denote the group of isometries $\varphi$ of $(M, g)$ such that (5.5) holds. Since $s_{x}$ belongs to $\operatorname{Aut}\left(M, g,\left\{s_{x}\right\}\right)$ for every $x \in M$, then from Lemma 0.3 in [7] $\operatorname{Aut}\left(M, g,\left\{s_{x}\right\}\right)$ is a transitive Lie group of transformations of $M$. If $G$ is the identity component of $\left(M, G,\left\{s_{x}\right\}\right)$ and $H$ the isotropy subgroup $\mathrm{pf} G$ at $x_{0}$, then using the same arguments as in the proof of Theorem 5.4, we show that (5.12) holds for each point $x$ of $M$. Since the pseudometric $g$ is $G$ invariant, Proposition 2.7 implies that $g^{(r)}$ is $T^{r} G$-invariant, which means that $s_{x}^{\prime}$, is an isometry of $\left(T^{r} M, g^{(r)}\right)$, and hence, $\left\{s_{x^{\prime}}^{\prime}\right\}$ is a Riemann $s$-structure on $T^{r} M$. Theorem 5.4 implies that the canonical connection of $\left(T^{r} M,\left\{s_{x}^{\prime}\right\}\right)$ is the complete lift of the canonical connection of $\left(M,\left\{s_{x}\right\}\right)$. From Theorems 4.9 and 5.2 we obtain (5.13). The proof is done.

Theorems 5.4 and 5.6 were proved by M. Sekizawa in the case $p=r=1$ (see [11]). In this general case we have used the same arguments as M. Sekizawa.

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