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NONLINEAR OPERATOR EQUATIONS AND BOUNDARY-VALUE PROBLEMS

Walter PETRY, Düsseldorf

Abstract: Let W and V be real Banach spaces with duals W^* and V^* , respectively. Suppose that $W \subset V$ and let I_1 be the injection mapping of W into V. Let T be a mapping from $D_T \subset V$ into W^* and $f \in V^*$. Under suitable conditions on T the existence of at least one solution $u_c \in D_T$ of $Tu = I_1^* f$ is proved using regularization methods, where I_1^* is the dual mapping of I_1 . An application to nonlinear elliptic boundary-value problems is given.

Key words and phrases: Nonlinear elliptic boundary-value problem, regularization method, real Banach space.

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... Let W and V be two real Banach spaces with duals W* and V*, respectively, and let W c V. Recently, the author [6] has studied mappings T with domain of definition D_T in V and range in V*. Under suitable conditions on T there exists at least one solution $m_o \epsilon$ ϵ D_T to Tm = f with $f \in V^*$. The proof is based on regularization methods. This general existence theorem was applied to nonlinear elliptic boundary-value problems of

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 $c \rightarrow 2$. See also Hess [4], where a related theorem is given using other regularization methods. It is an open question, whether the general existence theorem in [6] can also be applied to differential equations of order greater than 2.

In this paper, we will suppose that T is a mapping with domain of definition \mathbb{D}_{T} in V and range in W^* and we will prove the existence of a solution $u_0 \in \mathbb{D}_{T}$ to $\mathbb{T}u = \mathbb{I}_{1}^{*} \mathbb{f}$, where \mathbb{I}_{1}^{*} is the dual mapping of the injection mapping \mathbb{I}_{1} of W into V (Theorem 1). This theorem is applied to a class of nonlinear elliptic boundary value problems of order 2m (Theorem 2). Bui An Ton [3] also studied operator equations of the form $\mathbb{T}u = \mathbb{I}_{1}^{*} \mathbb{f}$, but he assumes that T is a mapping of $\mathbb{D}_{T} = V$ into W^{*} . It should be remarked, that the result of [6] is valid - in the case of equations of order 2 - also for more general classes of differential equations, but for the class of differential equations studied in this paper, our present result is (for m = 4) less restrictive than the result of [6].

2. Let V and W be two real reflexive separable Banach spaces with $W \subset V$, where the natural injection mapping I_{1} of W into V shall be continuous.

Let \mathcal{V}^* and \mathcal{W}^* be the duals of V and \mathcal{W} , respectively. The pairing between V and \mathcal{V}^* shall be denoted by $((\cdot, \cdot))$ and that of \mathcal{W} and \mathcal{W}^* by (\cdot, \cdot) .

By \longrightarrow and \longrightarrow we will denote the strong and weak

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convergence, respectively.

By a theorem of Browder-Bui An Ton [2], there exists a separable Hilbert space H (the inner product shall be denoted by $\langle \cdot, \cdot \rangle$) and a compact linear mapping I_2 of H into W such that $I_2(H)$ is dense in W (see also [6]). The dual mappings of I_2 and I_4 shall be denoted by

 I_{2}^{*} and I_{4}^{*} , respectively.

To prove an existence theorem for operator equations with mappings from $D \subset V$ into W^* we will use regularization methods. Therefore we introduce

<u>Assumption 1</u>: (a) For each $\varepsilon \in [0, 4]$, let $A(\varepsilon, \cdot)$: : $\Upsilon \longrightarrow \Upsilon^*$ be bounded (i.e. maps bounded sets into bounded sets) and demi-continuous (i.e. continuous from the strong to the weak topology).

(b) Let there exist a mapping $A: V \longrightarrow W^*$ such that any sequences $\{w_m\} \subset W$ and $\{\varepsilon_m\} \subset J0, 1]$ satisfying $\varepsilon_n \longrightarrow 0$ and $I_1 w_m \longrightarrow u_0$ in V imply

 $I_1^* A(\varepsilon_m, I_1 w_m) \longrightarrow A(u_0) \text{ in } \mathbb{W}^* .$

(c) Suppose that for all $\varepsilon \in [0, 1]$ and all $w \in W$

$$((A(\varepsilon, I_1 w), I_1 w)) \ge \mathcal{G}(\|I_1 w\|_{V}) \cdot \|I_1 w\|_{V}$$

where $g: \mathbb{R}^1_+ \longrightarrow \mathbb{R}^1$ with (i) $g(\pi)$ continuous; (ii) $g(\pi) \longrightarrow \infty$ as $\pi \longrightarrow \infty$.

Assumption 2: (a) For each $\varepsilon \in]0, 1]$ let $B(\varepsilon, \cdot)$: : $V \longrightarrow V^*$ be bounded and demicontinuous. Furthermore

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suppose that for all $\varepsilon \in [0, 1]$ and all $w \in W$

 $((\mathbb{B}(\varepsilon, I_1 w), I_1 w)) \ge 0$.

(b) Let there exist a mapping $B: D(B) \subset V \longrightarrow W^*$, i.e. $D(B) = \{u \in V : B(u) \in W^* \}$, such that any sequences $\{\varepsilon_m \} \subset]0, 4]$ and $\{w_m \} \subset W$ satisfying $\varepsilon_m \longrightarrow 0$, $I_1 w_m \longrightarrow w_0$ in V and $0 \leq ((B(\varepsilon_m, I_4 w_m), I_4 w_m)) \leq \mathcal{C}$ with some $\mathcal{C} > 0$ imply $w_0 \in D(B)$, i.e. $B(w_0) \in W^*$, and

 $I_{q}^{*}B(\varepsilon_{n}, I_{q}w_{n}) \longrightarrow B(w_{o})$ in W^{*} .

In this section we will consider the existence of a solution $\mu_n \in \mathbb{D}(\mathbb{B})$ to

(2.1)
$$A(u) + B(u) = I_{a}^{*}f$$

with $f \in V^*$.

We formulate our main theorem:

<u>Theorem 1</u>: Suppose that Assumption 1,2 holds. Let $f \in V^*$. Then there exists at least one solution $u_o \in D(B)$ satisfying (2.1).

Proof: The proof follows by several steps.

(a) For $\varepsilon \in [0, 4]$ and $x \in H$ we set

 $T(\varepsilon, x) := \frac{1}{\varepsilon} (I_{2}^{*}, I_{1}^{*} f - I_{2}^{*} I_{1}^{*} A(\varepsilon, I_{1} I_{2} x) - I_{2}^{*} I_{1}^{*} B(\varepsilon, I_{1} I_{2} x)).$

By Assumption 1 (a), 2 (a) and the above remarks, it follows that for each $\varepsilon \in]0, 4]$, the mapping $T(\varepsilon, \cdot)$ is compact and continuous from H to H. Furthermore it follows by Assumptions 1 (c), 2 (a)

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$$\langle x - T(\varepsilon, x), x \rangle = \|x\|_{H}^{2} - \frac{1}{\varepsilon} \langle I_{2}^{*} I_{1}^{*} f, x \rangle + \\ + \frac{1}{\varepsilon} \{ \langle I_{2}^{*} I_{1}^{*} A(\varepsilon, I_{1} I_{2} x), x \rangle + \langle I_{2}^{*} I_{1}^{*} B(\varepsilon, I_{1} I_{2} x), x \rangle \} \\ = \|x\|_{H}^{2} - \frac{1}{\varepsilon} ((f, I_{1} I_{2} x)) + \frac{1}{\varepsilon} \{ ((A(\varepsilon, I_{1} I_{2} x)), I_{1} I_{2} x)) + \\ + ((B(\varepsilon, I_{1} I_{2} x), I_{1} I_{2} x)) \geq \|x\|_{H}^{2} - \frac{1}{\varepsilon} \|f\|_{V^{*}} \|I_{1} I_{2} x\|_{V} + \\ + \frac{1}{\varepsilon} \frac{\varphi(\|I_{1} I_{2} x\|_{V}) \|I_{1} I_{2} x\|_{V} \geq \|x\|_{H}^{2} - \|f\|_{V^{*}}) \geq 0 \\ \text{for all} \quad \forall \varepsilon \in \{1, 1, 1, 2\} \leq \xi \in \{1, 2, 3\}, 1 \in \mathbb{R} \}$$

for all $x \in S_R : \{x \in H : \|x\|_H = R_E\}$, where R_E is a suitable positive constant. Indeed, this follows by the assumption on φ and the inequality $\|I_1 I_2 x\|_V \leq \gamma \|x\|_H$ with some constant $\gamma > 0$. Hence by a theorem of Krasnoselskii there exists for each $\varepsilon \in]0, 1]$ a fixed point $x_E \in H$ of $T(\varepsilon, \cdot)$, i.e.

$$(2\cdot 2) \varepsilon \cdot \times_{\varepsilon} = \varepsilon \cdot T(\varepsilon, \times_{\varepsilon}) = I_{2}^{*} I_{1}^{*} f - I_{2}^{*} I_{1}^{*} A(\varepsilon, I_{1} I_{2} \times_{\varepsilon}) - I_{2}^{*} I_{1}^{*} B(\varepsilon, I_{1} I_{2} \times_{\varepsilon}).$$

Therefore by Assumption 1 (c), 2 (b)

$$(2.3) \begin{cases} 0 = \langle \varepsilon \times_{\varepsilon} + I_{2}^{*} I_{1}^{*} A(\varepsilon, I_{1} I_{2} \times_{\varepsilon}) + I_{2}^{*} I_{1}^{*} B(\varepsilon, I_{1} I_{2} \times_{\varepsilon}) - \\ - I_{2}^{*} I_{1}^{*} f_{1} \times_{\varepsilon} \rangle = \varepsilon \| \times_{\varepsilon} \|_{H}^{2} + ((A(\varepsilon, I_{1} I_{2} \times_{\varepsilon}), I_{1} I_{2} \times_{\varepsilon})) + \\ + ((B(\varepsilon, I_{1} I_{2} \times_{\varepsilon}), I_{1} I_{2} \times_{\varepsilon})) - ((f, I_{1} I_{2} \times_{\varepsilon})) \ge \varepsilon \| \times_{\varepsilon} \|_{H}^{2} + \\ + (\varphi (\| I_{1} I_{2} \times_{\varepsilon} \|_{V}) - \| f \|_{V^{*}}) \cdot \| I_{1} I_{2} \times_{\varepsilon} \|_{V} \end{cases}$$

Hence there exist positive constants ℓ_1 , ℓ_2 such that

(2.4)
$$\sqrt{\varepsilon} \|_{X_{\varepsilon}} \|_{H} \leq \ell_{1}, \| \|_{1} \|_{2} |_{\varepsilon} \|_{V} \leq \ell_{2}$$

for all $\varepsilon \in [0, 1]$.

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(b) By virtue of (2.4) there exists a sequence $\{\varepsilon_m\} \subset]0,1]$ such that $\varepsilon_m \to 0, \varepsilon_m \cdot \times_{\varepsilon_m} \to 0$ in H and $I_1 I_2 \times_{\varepsilon_m} \to u_0$ in V. From (2.3) we obtain by Assumption 1 (c), 2 (a)

$$0 \leq \left(\left(\mathbb{B}(\varepsilon_{m}; \mathbb{I}_{1} | \mathbb{I}_{2} \times \varepsilon_{m}\right), \mathbb{I}_{1} | \mathbb{I}_{2} \times \varepsilon_{m}\right) = -\varepsilon_{m} \| \times_{m} \|_{H}^{2}$$
$$= \left(\left(\mathbb{A}(\varepsilon_{m}, \mathbb{I}_{1} | \mathbb{I}_{2} \times \varepsilon_{m}\right), \mathbb{I}_{1} | \mathbb{I}_{2} \times \varepsilon_{m}\right) + \left(\left(\mathbb{f}, \mathbb{I}_{1} | \mathbb{I}_{2} \times \varepsilon_{m}\right)\right)$$
$$\leq -\varphi(\|\mathbb{I}_{1} | \mathbb{I}_{2} \times \varepsilon_{m} \|_{V}) \|\mathbb{I}_{1} | \mathbb{I}_{2} \times \varepsilon_{m} \|_{V} + \|\mathbb{f}\|_{V^{*}} \| \mathbb{I}_{1} | \mathbb{I}_{2} \times \varepsilon_{m} \|_{V} \leq \mathcal{C}$$

with some constant \mathscr{C} by (2.4) and the assumption on φ . Hence by Assumption 1 (b), 2 (b) and $w_{m} = I_2 \times_{\varepsilon_m} \in W$, we obtain $u_{\varphi} \in D(\mathbb{B})$ and

$$I_{1}^{*}A(\varepsilon_{m}, I_{1}I_{2}\times_{\varepsilon_{m}}) \longrightarrow A(u_{0}), I_{1}^{*}B(\varepsilon_{m}, I_{1}I_{2}\times_{\varepsilon_{m}}) \longrightarrow B(u_{0})$$

in W* as $m \to \infty$. From (2.2) it follows for each $\times \in \mathbb{H}$ $\langle \varepsilon_m \times_{\varepsilon_m}, \times \rangle + (I_1^* \mathbb{A}(\varepsilon_m, I_1 I_2 \times_{\varepsilon_m}), I_2 \times) + (I_1^* \mathbb{B}(\varepsilon_m, I_1 I_2 \times_{\varepsilon_m}), I_2 \times) = (I_1^* \mathbb{f}, I_2 \times).$

Therefore as $m \rightarrow \infty$

$$(A(u_0), I_2 \times) + (B(u_0), I_2 \times) = (I_1^* f, I_2 \times)$$

from which we get

$$A(u_{0}) + B(u_{0}) = I_{1}^{*}f$$
,

since I, (H) is dense in W, proving Theorem 1.

<u>Remark</u>: Theorem 1 in this section is related to meorem 1 in [6] but none of them implies the other (see the following application).

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3. In this section we will apply Theorem 1 to nonlinear elliptic differential equations. We use the notations of Browder in [1]. Suppose that $\Omega \subset \mathbb{R}^{n}$ is a bounded open domain with sufficiently smooth boundary $\partial \Omega$ such that the Imbedding Theorems of Sobolev are applicable (see e.g. [1]).

It is our purpose to study differential equations of the form

$$\sum_{\substack{|\alpha|=m}}^{\infty} (-1)^{|\alpha|} \mathbb{D}^{\alpha} (A_{\alpha}(x, \xi_{m-1}(u)(x))) \mathbb{D}^{\alpha} u(x))$$

$$+ \sum_{\substack{|\alpha|=m-4}}^{\infty} (-1)^{|\alpha|} \mathbb{D}^{\alpha} \mathbb{B}_{\alpha}(x, \xi_{m-1}(u)(x)) = f(x)$$

for $x \in \Omega$ with Dirichlet boundary conditions. Precisely, we set $[f,g] := \int_{\Omega} f(x) g(x) dx$, $V := \tilde{W}_{m,2}(\Omega)$ and $W := W_{m^*,2}(\Omega) \cap V$ with $m^* > m + m/2$, where we introduce in W the norm of $W_{m^*,2}(\Omega)$. In addition, we set

$$(3.1) \mathbb{D}(\mathbb{B}) := \{ \mathcal{U} \in \mathcal{V} : | \Sigma = [\mathbb{B}_{\alpha}(\cdot, \xi_{m-1}(\mathcal{U})), \mathbb{D}^{\alpha} w] \} \leq |\alpha| \leq m-1 \leq \mathcal{L}_{\mathcal{U}} \| w \|_{W}$$

for all $w \in W$ with some constant \mathcal{C}_{u} 3. Furthermore let f be an element of V^* . Then we ask for an element $u_o \in D(B)$ satisfying

$$(3.2) \begin{cases} \sum \left[A_{\alpha}(\cdot, \widehat{s}_{m-1}(u_0)) D^{\alpha}u_0, D^{\alpha}w\right] \\ |\alpha| = m \end{cases} + \sum \left[B_{\alpha}(\cdot, \widehat{s}_{m-1}(u_0)), D^{\alpha}w\right] = [f, w] \end{cases}$$

for all we W .

<u>Assumption 3</u>: (a) Each $A_{\infty}(x, \xi_{m-1})$ (with $|\alpha| = m$) is measurable in x for fixed ξ_{m-1} in $\mathbb{R}^{h_{m-1}}$ and continuous in ξ_{m-1} on $\mathbb{R}^{h_{m-1}}$ for almost all x in Ω . Let & be the greatest integer less than m - m/2and let ξ_{k} denote the vector $\xi_{k} := \{\xi_{\alpha} : |\alpha| \le k\}$ from the vector space $\mathbb{R}^{h_{k}}$. There exist continuous functions c_{α} and c_{γ} from $\mathbb{R}^{h_{k}}$ to $L^{2}(\Omega)$ and \mathbb{R}^{1} , respectively, and a constant $c_{\alpha} > 0$, such that the following inequalities hold:

$$\begin{split} \mathbf{c}_{o} &\leq \mathbf{A}_{\sigma}(\mathbf{x}, \mathbf{\hat{\xi}_{m-1}}) \leq \mathbf{c}_{\sigma}(\mathbf{\hat{\xi}_{k}})(\mathbf{x}) + \mathbf{c}_{1}(\mathbf{\hat{\xi}_{kr}}) \underset{\mathcal{X} < |\mathbf{\hat{\beta}}| \leq m-1}{\overset{1}{2}} |\mathbf{\hat{\xi}_{\beta}}|^{\frac{t_{\beta}}{2}} \\ \text{for all } \mathbf{x} \in \boldsymbol{\Omega} \quad \text{and} \quad \mathbf{\hat{\xi}_{m-1}} \in \mathbb{R}^{\overset{\mathbf{\hat{\beta}}_{m-1}}{\overset{\mathbf{m}}{1}} \quad \text{with} \\ & \frac{1}{t_{\sigma}} > \frac{1}{2} - \frac{1}{m} (m - |\mathbf{\hat{\beta}}|) \; . \end{split}$$

(b) Each $\mathbb{B}_{\infty}(x, \mathfrak{f}_{m-1})$ (with $|\infty| \leq m-1$) is a continuous function from $\Omega \times \mathbb{R}^{5m-1}$ to \mathbb{R}^1 such that for all $\mathfrak{E} \in [0, 1]$, all \mathfrak{f}_{m-1} in \mathbb{R}^{5m-1} and almost all \times in Ω

$$\sum_{\substack{|\alpha| \leq m-1}} \frac{B_{\alpha}(x, \xi_{m-1})\xi_{\alpha}}{1 + \varepsilon |B_{\alpha}(x, \xi_{m-1})|} \geq 0$$

Suppose that there exists a constant $c_2 \ge 0$ and a function $F: \Omega \times \mathbb{R}^{m-1} \times \mathbb{R}^{m-1} \longrightarrow \mathbb{R}^1$ such that for all $\varepsilon \in [0,1]$, all ξ_{m-1}, ξ'_{m-1} in \mathbb{R}^{m-1} and almost all x in Ω .

$$\begin{split} \left| \sum_{\substack{|\alpha| \le m-1}} \frac{B_{\alpha}(x, \xi_{m-1}) \xi_{\alpha}}{1 + \varepsilon | B_{\alpha}(x, \xi_{m-1})|} \right| &= F(x, \xi_{m-1}, \xi_{m-1}) \\ &+ c_2 \sum_{\substack{|\alpha| \le m-1}} \frac{B_{\alpha}(x, \xi_{m-1}) \xi_{\alpha}}{1 + \varepsilon | B_{\alpha}(x, \xi_{m-1})|} \end{split}$$

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In addition, suppose that for all $w \in W$, the mapping $F(\xi_{m-1}(\cdot), \xi_{m-1}(w))$, defined by $F(\xi_{m-1}(\omega), \xi_{m-1}(w))(x) := F(x, \xi_{m-1}(\omega)(x), \xi_{m-1}(w)(x))$, is bounded and continuous from $W_{m-1,2}$ to L^1 .

<u>Theorem 2</u>: Let Assumption 3 be satisfied. Then there exists at least one solution $\mu_o \in \mathcal{D}(B)$ of (3.2).

Proof: (a) We remark that by the Imbedding Theorems of Sobolev it follows

$$\mathbb{W}_{m^{*},2}(\Omega) \subset \mathbb{C}^{m}(\overline{\Omega}); \mathbb{W}_{m^{*},2}(\Omega) \subset \mathbb{W}_{m,2}(\Omega)$$

with continuous injection. Hence W and V are two real reflexive separable Banach spaces with $W \subset V$, where the injection mapping of W into V is continuous.

(b) We now define for $\varepsilon \in]0,1]$ and $\mu, \nu \in V$

$$a(\varepsilon, \mu, v) := \sum_{|\alpha|=m} \left[\frac{A_{\alpha}(\cdot, \xi_{m-1}(\mu))}{1 + \varepsilon A_{\alpha}(\cdot, \xi_{m-1}(\mu))} \mathbb{D}^{\alpha}_{\mu}, \mathbb{D}^{\alpha}_{\nu} \right] ,$$

$$\mathscr{E}(\varepsilon, u, w) := \sum_{|\alpha| \neq m-1} \left[\frac{B_{\alpha}(\cdot, \xi_{m-1}(u))}{1 + \varepsilon |B_{\alpha}(\cdot, \xi_{m-1}(u))|}, D^{\alpha} r \right].$$

For MEV and WEW let

$$\alpha(u, w) := \sum_{\substack{|\alpha|=m}} [A_{\alpha}(\cdot, \xi_{m-1}(u))]^{\alpha}u, D^{\alpha}v]$$

and for μ eD(B) and μ e W we set

$$\&r(u, w) := \sum_{|\alpha| \le m-1} [B_{\alpha}(\cdot, \xi_{m-1}(u)), D^{\alpha}w]$$

It follows by Assumption 3 and a well-known theorem (see e.g. [1]): For each $\epsilon \in]0,1]$ there exist bounded continuous

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mappings $A(\varepsilon, \cdot): Y \longrightarrow Y^*$ and $B(\varepsilon, \cdot): Y \longrightarrow Y^*$ such that for all $\omega, w \in Y$

$$((A(\varepsilon, u), v)) = a(\varepsilon, u, v), \quad ((B(\varepsilon, u), v)) =$$
$$= b(\varepsilon, u, v).$$

By (3.1) it follows the existence of a mapping $B: D(B) \longrightarrow W^*$ such that for all $u \in D(B)$ and $w \in W$ we have $(B(u), w) = \mathcal{B}(u_2, w)$.

By the Imbedding Theorem of Sobolev $W_{m,2}(\Omega) \subset W_{|\beta|,t_{\beta}}(\Omega)$ for $\mathscr{D} < |\beta| \le m - 4$ and $W_{m,2}(\Omega) \subset C^{|\beta|}(\overline{\Omega})$ for $|\beta| \le \mathscr{D}$ with continuous and compact injection mapping. Hence any weakly convergent sequence in $W_{m,2}(\Omega)$ is strongly convergent in $W_{|\beta|,t_{\alpha}}(\Omega)$ for $\mathscr{D} < |\beta| \le m - 4$ and in $C^{|\beta|}(\overline{\Omega})$ for $|\beta| \le \mathscr{D}$,

respectively. Since $W \subset C^{m}(\overline{\Omega})$, we obtain by Assumption 3(a)

for $u \in V$ and $w \in W$ using the inequality of Schwarz

$$\begin{split} &\sum_{\substack{|\alpha|=m}} \left[A_{\alpha}(\cdot, \xi_{m-1}(u)) D^{\alpha}u, D^{\alpha}u \right] \\ &\leq \sum_{\substack{|\alpha|=m}} \|D^{\alpha}w\|_{c^{0}} \|A_{\alpha}(\cdot, \xi_{m-1}(u)) D^{\alpha}u\|_{L^{1}} \\ &\leq \sum_{\substack{|\alpha|=m}} \|D^{\alpha}w\|_{c^{0}} \|A_{\alpha}(\cdot, \xi_{m-1}(u))\|_{L^{2}} \cdot \|D^{\alpha}u\|_{L^{2}} \\ &\leq \mathcal{C}_{1}(\|u\|_{V}) \sum_{\substack{|\alpha|=m}} \|D^{\alpha}w\|_{c^{0}} \leq \mathcal{C}_{2}(\|u\|_{V}) \|w\|_{W} \end{split}$$

i.e. there exists a mapping $A: V \longrightarrow W^*$ such that for all $u \in V$ and all $w \in W$

$$(Au, w) = a(u, w)$$
.

(c) We now apply Theorem 1. We first prove Assumption 1 (b). Let $\{w_m\} \subset W$ and $\{\varepsilon_m\} \subset [0, 4]$ with $\varepsilon_m \rightarrow 0$ and $w_m := 1, w_m \longrightarrow w_o$ in V. Then by the remark under (b)

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 $\{ \mathbb{D}^{\beta} u_{m} \}$ converges strongly to $\mathbb{D}^{\beta} u_{o}$ in $\mathbb{L}^{\dagger \beta} (\Omega)$ for $\mathcal{W} = |\beta| \le m - 1$ and in $\mathbb{C}^{\circ} (\overline{\Omega})$ for $|\beta| \le \mathcal{W}$, respectively. Let $w \in W$ then we obtain by $\mathcal{W} \subset \mathbb{C}^{m} (\overline{\Omega})$ and Assumption 3

$$\begin{split} &|(\mathbf{I}_{1}^{*}\mathbf{A}(\mathbf{e}_{m},\boldsymbol{u}_{m}),\boldsymbol{w}) - (\mathbf{A}(\boldsymbol{u}_{0}),\boldsymbol{w})| = |(\mathbf{I}_{1}^{*}\mathbf{A}(\mathbf{e}_{m},\boldsymbol{u}_{m}) - \mathbf{A}(\boldsymbol{u}),\boldsymbol{w})| \\ &= \sum_{|\alpha|=m}^{1} \left| \left[\frac{A_{\alpha}(\cdot, \xi_{m-1}(\boldsymbol{u}_{m}))}{1 + \epsilon_{m}A_{\alpha}(\cdot, \xi_{m-1}(\boldsymbol{u}_{m}))} \, \mathbb{D}^{\alpha}_{\boldsymbol{u}_{m}} - A_{\alpha}(\cdot, \xi_{m-1}(\boldsymbol{u}_{0})) \, \mathbb{D}^{\alpha}_{\boldsymbol{u}_{0}}, \, \mathbb{D}^{\alpha}_{\boldsymbol{w}} \right] \right| \\ &\leq \mathcal{I}_{1m} + \mathcal{I}_{2m} \\ &\text{with} \end{split}$$

$$\begin{split} &\mathcal{I}_{1n} := \sum_{|\alpha|=m} \left[\left[A_{\alpha} \left(\cdot, \xi_{m-1} \left(u_{0} \right) \right) \mathcal{D}_{w}^{\alpha}, \mathcal{D}_{u_{m}}^{\alpha} - \mathcal{D}_{u_{0}}^{\alpha} \right] \right] \\ &\mathcal{I}_{2n} := \sum_{|\alpha|=m} \left[\left[\left(\frac{A_{\alpha} \left(\cdot, \xi_{m-1} \left(u_{m} \right) \right)}{1 + \epsilon_{n} A_{\alpha} \left(\cdot, \xi_{m-1} \left(u_{m} \right) \right)} - A_{\alpha} \left(\cdot, \xi_{m-1} \left(u_{0} \right) \right) \right] \mathcal{D}_{w}^{\alpha}, \mathcal{D}_{u_{m}}^{\alpha} \right] \right] . \\ &\text{It follows by virtue of } A_{\alpha} \left(\cdot, \xi_{m-1} \left(u_{0} \right) \right) \mathcal{D}_{w}^{\alpha} \in L^{2} \left(\Omega \right) \quad \text{and} \\ &\mathcal{D}^{\alpha} u_{m} \longrightarrow \mathcal{D}^{\alpha} u_{0} \quad \text{in } L^{2} \left(\Omega \right) \quad \text{for } |\alpha| = m \quad \text{that } \mathcal{I}_{1n} \longrightarrow \\ &\longrightarrow 0 \quad \text{as } m \longrightarrow \infty \quad . \end{split}$$

By the inequality of Schwarz and $w \in C^{m}(\overline{\Omega})$ it follows

$$\begin{split} & \mathcal{J}_{2m} \in \sum_{|\alpha|=m} \|D^{\alpha} u_m\|_{L^2} \quad \left\| \left(\frac{A_{\alpha}(\cdot, \xi_{m-1}(u_m))}{1 + \varepsilon_m A_{\alpha}(\cdot, \xi_{m-1}(u_m))} - A_{\alpha}(\cdot, \xi_{m-1}(u_m)) \right) \right\|_{L^2} \\ & - A_{\alpha}(\cdot, \xi_{m-1}(u_0)) \right) D^{\alpha} w\|_{L^2} \\ & \leq \sum_{|\alpha|=m} \|D^{\alpha} u_m\|_{L^2} \|D^{\alpha} w\|_{C^0} \left\| \frac{A_{\alpha}(\cdot, \xi_{m-1}(u_m))}{1 + \varepsilon_m A_{\alpha}(\cdot, \xi_{m-1}(u_m))} - A_{\alpha}(\cdot, \xi_{m-1}(u_0)) \right\|_{L^2} \\ & \leq \mathcal{C} \|u_m\|_{V} \|w\|_{W} \sum_{|\alpha|=m} (\|A_{\alpha}(\cdot, \xi_{m-1}(u_m)) - A_{\alpha}(\cdot, \xi_{m-1}(u_0))\|_{L^2} \\ & + \varepsilon_{\infty} \sup_{|\alpha|=m} \left| 1 - \frac{1}{1 + \varepsilon_m A_{\alpha}(x, \xi_{m-1}(u_m)(x))} \right| \cdot \|A_{\alpha}(\cdot, \xi_{m-1}(u_m))\|_{L^2} \\ & \text{with some } \mathcal{C} > 0 \quad \text{By Assumption 3 (a) and the above remark} \\ & \text{the right hand side of the inequality converges to zero as} \\ & m \to \infty \quad \text{Hence it follows } I_1^* A(\varepsilon_m, u_m) \longrightarrow A(u_0) \quad \text{in } W^*, \\ & \text{proving Assumption 1 (b)}. \end{split}$$

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(d) Let $\varepsilon \in [0, 1]$ and $w \in W$, then we obtain by Assumption 3 (a) $((A(\varepsilon, I_{aw}), I_{aw})) = \sum \left[\frac{A_{\infty}(\cdot, \xi_{m-1}(w))}{A + \varepsilon + \varepsilon} \mathbb{D}_{w}^{\infty} \mathbb{D}_{w}^{\infty}\right]$

$$\geq \sum_{\substack{i \in l = m \\ i \in l = m}} \left[\frac{c_0}{1 + \varepsilon c_0} D^{\alpha}_{N_2} D^{\beta}_{N_2} \right] = \frac{c_0}{1 + \varepsilon c_0} \sum_{\substack{i \in l = m \\ i \in l = m}} \|D^{\alpha}_{N_2} u^{\mu}\|_{L^2}^2 \geq c_1 \|I_1 u^{\mu}\|_{V}^2$$

with some $c_1 > 0$, since for $u \in V$ the usual norm $\|u\|_{\gamma}$ of V and $(\sum_{|\alpha|=m} \|D^{\alpha}u\|_{L^2}^2)^{\frac{1}{2}}$ are equivalent norms (see [5]). Hence Assumption 1 (c) is satisfied.

(e) The second part of Assumption 2 (a) is a direct consequence of Assumption 3 (b), while Assumption 2 (b) is proved in [6] by using Assumption 3 (b). Hence Theorem 2 follows by Theorem 1.

<u>Remark</u>: (a) Conditions on $B_{\infty}(x, \xi_{m-1})$ which are more useful in applications and which imply Assumption 3 (b) are given in [6] Proposition 3 and Remark 3.

(b) The differential equations studied in this paper are of more special form than those studied in [6], but the order of the differential equation can be of order 2m with m integer, while in [6] the differential equation is of second order i.e. m = 1 and it is an open question whether the order 2m can also be studied. In addition, considering the special class of differential equations studied in this paper, the present Theorem 2 (for the case m = 1) is more general than the corresponding theorem in [6].

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