## Archivum Mathematicum

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Archivum Mathematicum, Vol. 30 (1994), No. 3, 215--225

Persistent URL: http://dml.cz/dmlcz/107508

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# NATURAL LIFTINGS OF (0,2)-TENSOR FIELDS TO THE TANGENT BUNDLE 

Miroslav Doupovec*


#### Abstract

We determine all first order natural operators transforming (0,2)tensor fields on a manifold $M$ into ( 0,2 )-tensor fields on $T M$.


## 1. Introduction

There are classical constructions of tensor fields on the tangent bundle $T M$ from a tensor field on the base manifold $M$, namely the vertical and the complete lifts, cf. [9] and [12]. Moreover, if $M$ is endowed with a linear connection, then one can also define the horizontal lift of a tensor field to $T M$. From a general point of view, geometrical constructions are natural differential operators. Then the full list of such operators gives the complete list of all possible geometric constructions.

The aim of this paper is to determine all first order natural operators $T^{*} \otimes T^{*} \rightsquigarrow$ ( $\left.T^{*} \otimes T^{*}\right) T$ transforming $(0,2)$-tensor fields on $M$ into $(0,2)$-tensor fields on $T M$. For comparison's sake, we point out that Kowalski and Sekizawa [7] determined all natural operators transforming Riemannian metrics on $M$ into metrics on $T M$. Recently Janyška [3] has classified all first order natural operators from Riemannian metrics into 2 -forms on the tangent bundle. In both of these examples the regularity of the original $(0,2)$-tensor field on the base manifold $M$ is essential, while we shall consider arbitrary ( 0,2 )-tensor fields without any additional requirement. In what follows we shall use the concept of a natural operator from [6].

We remark that liftings of tensor fields to the tangent bundle play an important role in the analytical mechanics, see e.g. [2]. All manifolds and maps are assumed to be infinitely differentiable.

[^0]
## 2. The canonical Liftings

Let $M$ be a manifold of dimension $m$. We denote by $p_{M}: T M \rightarrow M$ the tangent bundle and by $q_{M}: T^{*} M \rightarrow M$ the cotangent bundle of $M$. The canonical coordinates ( $x^{i}$ ) on $M$ induce the additional coordinates $y^{i}=d x^{i}$ on $T M$ and $p_{i}$ on $T^{*} M$. The coordinates on TTM will be denoted by ( $x^{i}, y^{i}, X^{i}=d x^{i}, Y^{i}=d y^{i}$ ), on $T T^{*} M$ by $\left(x^{i}, p_{i}, \xi^{i}=d x^{i}, P_{i}=d p_{i}\right)$ and on $T^{*} T M$ by ( $\left.x^{i}, w^{i}=d x^{i}, r_{i} d x^{i}+s_{i} d w^{i}\right)$.

If $f: M \rightarrow \mathbb{R}$ is a function, then the vertical lift of $f$ to $T M$ is a function $f^{V}: T M \rightarrow \mathbb{R}$ defined by $f^{V}=f \circ p_{M}$. The complete lift $f^{C}$ of $f$ is defined by $f^{C}(y)=d f(x)(y), x=p_{M}(y)$.

Let $X=\xi^{i}(x) \frac{\partial}{\partial x^{2}}$ be a vector field on $M$. The vertical lift of $X$ to $T M$ is a vertical vector field $X^{V}$ on $T M$ determined by the translations in the individual fibres of $T M$. The complete lift of $X$ to $T M$ is the flow prolongation $X^{C}$ of $X, X^{C}=\left.\frac{\partial}{\partial t}\right|_{0} T(\exp t X)$, where $\exp t X$ means the flow of $X$. In coordinates, $X^{V}=\xi^{i}(x) \frac{\partial}{\partial y^{2}}, X^{C}=\xi^{i}(x) \frac{\partial}{\partial x^{i}}+\frac{\partial \xi^{2}(x)}{\partial x^{i}} y^{j} \frac{\partial}{\partial y^{2}}$. Let us remark that $X^{V}$ and $X^{C}$ can also be defined by means of their actions on functions: $X^{V}\left(f^{C}\right)=(X f)^{V}$, $X^{C}\left(f^{C}\right)=(X f)^{C}$ for every function $f: M \rightarrow \mathbb{R}$.

To define the vertical and the complete lift of a tensor field we shall use the following assertion (see e.g. [2] and [9]).
Lemma 1. If $G$ and $G^{\prime}$ are $(0, r)$-tensor fields on $T M$ such that for all vector fields $X_{1}, \ldots, X_{r}$ on $M$ we have

$$
G\left(X_{1}^{C}, \ldots, X_{r}^{C}\right)=G^{\prime}\left(X_{1}^{C}, \ldots, X_{r}^{C}\right)
$$

then $G=G^{\prime}$.
Definition 1. Let $G$ be a tensor field of type $(0,2)$ on $M$. The vertical lift of $G$ to $T M$ is a tensor field $G^{V}$ of type $(0,2)$ on $T M$ defined by $G^{V}\left(X_{1}^{C}, X_{2}^{C}\right)=$ $\left(G\left(X_{1}, X_{2}\right)\right)^{V}$ for all vector fields $X_{1}, X_{2}$ on $M$. The complete lift of $G$ to $T M$ is a tensor field $G^{C}$ of type $(0,2)$ on $T M$ given by $G^{C}\left(X_{1}^{C}, X_{2}^{C}\right)=\left(G\left(X_{1}, X_{2}\right)\right)^{C}$ for all vector fields $X_{1}, X_{2}$ on $M$.

If $G=g_{i j} d x^{i} \otimes d x^{j}$ is the coordinate expression of $G$, then

$$
\begin{gathered}
G^{V}=g_{i j} d x^{i} \otimes d x^{j} \\
G^{C}=\left(\frac{\partial g_{i j}}{\partial x^{k}} y^{k}\right) d x^{i} \otimes d x^{j}+g_{i j} d x^{i} \otimes d y^{j}+g_{i j} d y^{i} \otimes d x^{j}
\end{gathered}
$$

Remark 1. Our concept of a complete lift to the tangent bundle coincides with the definition due to Yano and Ishihara [12] and Morimoto [9]. Morimoto even introduced liftings of tensor fields of type ( $p, q$ ) to the bundle $T_{1}^{r} M$ of 1-dimensional velocities. Moreover, liftings of tensor fields to the bundle $T_{k}^{r} M=J_{0}^{r}\left(\mathbb{R}^{k}, M\right)$ are studied in [10].

If $G=a_{i j} d x^{i} \wedge d x^{j}$ is a 2 -form on $M$, then $G^{V}=p_{M}^{*} G$, i.e. the vertical lift is exactly the pull-back of $G$ to $T M$. Further, the vertical lift of a Riemannian metric is a degenerated metric of rank $m$ on $T M$. One can easily prove

Lemma 2. Let $G$ be a ( 0,2 )-tensor field on $M$. We have
(1) If $G$ has rank $r$, then $G^{C}$ has rank $2 r$.
(2) If $G$ is symmetric (or skew-symmetric), then $G^{C}$ is symmetric (or skewsymmetric) as well.
(3) If $G$ is a Riemannian metric on $M$, then $G^{C}$ is a pseudoriemannian metric on $T M$ of signature $(m, m)$.
(4) If $G$ is a 2 -form on $M$, then $G^{C}$ is a 2 -form on $T M$ and we have $d G^{C}=$ $(d G)^{C}$.
(5) $G^{C}\left(X^{V}, Y^{C}\right)=G^{C}\left(X^{C}, Y^{V}\right)=G(X, Y)^{V}, G^{C}\left(X^{V}, Y^{V}\right)=0$ for all vector fields $X, Y$ on $M$.
(6) If $G$ is a symplectic form on $M$, then $G^{C}$ is a symplectic form on $T M$.
(7) $G^{V}\left(X^{V}, Y^{V}\right)=0$ for all vector fields $X, Y$ on $M$.

Denote by $\kappa_{M}: T T M \rightarrow T T M$ the canonical involution and by $s_{M}: T T^{*} M \rightarrow$ $T^{*} T M$ the canonical isomorphism [8], [11]. The coordinate expression of $s_{M}$ is $w^{i}=\xi^{i}, r_{i}=P_{i}, s_{i}=p_{i}$. It is well-known that the complete lift $X^{C}$ of a vector field $X$ can be described by $X^{C}=\kappa_{M} \circ T X$. We show that a similar characterization holds also for the complete lift of $(0,2)$-tensor fields to $T M$. There is a canonical isomorphism $\psi: A^{*} \otimes B^{*} \rightarrow \operatorname{Lin}\left(A, B^{*}\right), \psi\left(a^{*} \otimes b^{*}\right)(c)=\left\langle b^{*}, c\right\rangle a^{*}$. Hence we can identify every $(0,2)$-tensor field $G$ on $M$ with a linear map $G_{L}: T M \rightarrow T^{*} M$ over the identity of $M$, which is defined by $\left\langle G_{L}(y), z\right\rangle_{x}=G_{x}(z, y), y, z \in T_{x} M$. The coordinate expression of $G_{L}$ is

$$
p_{i}=g_{i j} y^{j} .
$$

Analogously, denote by $\bar{G}_{L}: T T M \rightarrow T^{*} T M$ the linear map over $\mathrm{id}_{T M}$ corresponding to a ( 0,2 )-tensor field $\bar{G}$ on $T M$.
Proposition 1. Let $G$ be an arbitrary $(0,2)$-tensor field on $M$. Then the complete lift $G^{C}$ is the only tensor field $\bar{G}$ on $T M$ satisfying

$$
\begin{equation*}
\bar{G}_{L}=s_{M} \circ T G_{L} \circ \kappa_{M} . \tag{1}
\end{equation*}
$$

Proof. The natural equivalence $s$ can be distinguished among all natural transformations $T T^{*} \rightarrow T^{*} T$ by the following geometric construction, [5]. If $X$ is a vector field and $\omega: M \rightarrow T^{*} M$ is a 1-form on $M$, then $\langle\omega, X\rangle: M \rightarrow \mathbb{R}$. By [5], $s$ is the only natural transformation $T T^{*} \rightarrow T^{*} T$ over the identity of $T$ satisfying $\left\langle s T \omega, X^{C}\right\rangle=\langle\omega, X\rangle^{C}$. Then the assertion follows from the definitions of $G_{L}$ and $G_{L}^{C}$ and from Lemma 1.

Let $\alpha=p_{i} d x^{i}$ be the Liouville 1 -form on $T^{*} M$. Then the pull-back $\beta:=\left(G_{L}\right)^{*} \alpha$ is a 1 -form on $T M, \beta=g_{i j} y^{j} d x^{i}$. (We can also define $\beta$ by $\beta(y)=(G(-, y))^{V}$.)
Definition 2. Let $G$ be a ( 0,2 )-tensor field on $M$. The antisymmetric lift of $G$ to $T M$ is a 2 -form $G^{A}$ on $T M$ defined by $G^{A}=d \beta$.

Obviously, $G^{A}$ is the pull-back $G_{L}^{*} \Omega$ of the canonical symplectic form $\Omega=d \alpha$ on $T^{*} M$. In coordinates,

$$
G^{A}=\left(\frac{\partial g_{j m}}{\partial x^{i}} y^{m}\right) d x^{i} \wedge d x^{j}-g_{i j} d x^{i} \wedge d y^{j}
$$

The corresponding matrix expression of $G^{A}$ is

$$
\left(\begin{array}{cc}
\left(\frac{\partial g_{j m}}{\partial x^{2}}-\frac{\partial g_{i m}}{\partial x^{j}}\right) y^{m} & -g_{i j} \\
g_{j i} & 0
\end{array}\right)
$$

If $G$ is a Riemannian metric on $M$, then the antisymmetric lift $G^{A}$ is exactly the canonical symplectic 2 -form on $T M$ defined by Janyška in [3]. In general, we have

Proposition 2. Let $G$ be a regular (0,2)-tensor field on $M$. Then $T M, T_{1}^{r} T M$, $T T_{1}^{r} M$ are symplectic manifolds.

Proof. Clearly, if $G$ is regular, then $G_{L}: T M \rightarrow T^{*} M$ is an isomorphism and $G^{A}$ is a symplectic form on $T M$. By [1], $T_{1}^{r} T^{*} M$ is a symplectic manifold. If $\omega$ is the corresponding symplectic form on $T_{1}^{r} T^{*} M$, then the pull-back ( $T_{1}^{r} G_{L}$ )* $\omega$ is a symplectic form on $T_{1}^{r} T M$. Finally, the well-known identification $T_{1}^{r} T M \approx$ $T T_{1}^{r} M$ determined by the exchange homomorphism of Weil algebras, [6], defines a symplectic structure on $T T_{1}^{r} M$.

Let $\Gamma$ be a linear connection on $M$ with the local Christoffel symbols $\Gamma_{j k}^{i}$. Then the tangent space of $T M$ at any point $y \in T M$ splits into the horizontal and vertical subspace with respect to $\Gamma, T_{y} T M=H_{y} \oplus V_{y}$, and we have a linear isomorphism $T_{x} M \rightarrow H_{y}, x=p_{M}(y)$. This isomorphism defines the horizontal lift of a vector field $X$ on $M$ into a vector field $X^{H}$ on $T M$.

Definition 3. Let $G$ be a $(0,2)$-tensor field on $M$. The horizontal lift of $G$ to $T M$ is a tensor field $G^{H}$ of the same type on $T M$ given by $G^{H}\left(X^{V}, Y^{V}\right)=$ $G^{H}\left(X^{H}, Y^{H}\right)=0, G^{H}\left(X^{H}, Y^{V}\right)=G^{H}\left(X^{V}, Y^{H}\right)=(G(X, Y))^{V}$ for all vector fields $X, Y$ on $M$.

We have

$$
G^{H}=\left(g_{i s} \Gamma_{k j}^{s} y^{k}+g_{s j} \Gamma_{k i}^{s} y^{k}\right) d x^{i} \otimes d x^{j}+g_{i j} d x^{i} \otimes d y^{j}+g_{i j} d y^{i} \otimes d x^{j}
$$

Proposition 3. Let $G$ be a (0,2)-tensor field on $M$. Then $G^{H}=G^{C}$ if and only if $\nabla G=0$.
Proof. A direct calculation gives $\nabla G=0$ iff $\frac{\partial g_{i j}}{\partial x^{k}}=g_{i s} \Gamma_{k j}^{s}+g_{s j} \Gamma_{k i}^{s}$.
It is interesting to point out that the same assertion holds also for the horizontal and complete lift of $(0,1)$-tensor fields (i.e. 1 - forms) provided we define the horizontal lift by $\alpha^{H}\left(X^{H}\right)=0, \alpha^{H}\left(X^{V}\right)=(\alpha(X))^{V}$ for every vector field $X$ on $M$.

## 3. Invariant functions on $J^{1}\left(T^{*} \otimes T^{*}\right) \oplus T T$

The aim of this section is to determine all first order natural operators transforming ( 0,2 )-tensor fields on $M$ into functions on TTM. Such functions will
then play the role of coefficients of natural transformations $T T M \rightarrow T^{*} T M$ (see Proposition 6 in the next section).

Denote by $Q=\otimes^{2} \mathbb{R}^{m *} \times \otimes^{3} \mathbb{R}^{m *} \times \times^{3} \mathbb{R}^{m}$ the standard fibre of the bundle functor $J^{1}\left(T^{*} \otimes T^{*}\right) \oplus T T$ and by $G_{m}^{r}$ the group of all invertible $r$-jets of $\mathbb{R}^{m}$ into $\mathbb{R}^{m}$ with source and target zero. We shall denote by ( $a_{j}^{i}, a_{j k}^{i}$ ) the canonical coordinates in $G_{m}^{2}$ and by tilde the coordinates of the inverse element. If $\left(g_{i j}, g_{i j, k}:=\frac{\partial g_{i j}(x)}{\partial x^{k}}, y^{i}, X^{i}, Y^{i}\right)$ are the canonical coordinates on $Q$, then the action of $G_{m}^{2}$ on $Q$ is given by

$$
\begin{align*}
\bar{g}_{i j} & =\tilde{a}_{i}^{k} \tilde{a}_{j}^{\ell} g_{k \ell}, \quad \bar{g}_{i j, k}=\tilde{a}_{i}^{m} \tilde{a}_{j}^{n} \tilde{a}_{k}^{p} g_{m n, p}+\left(\tilde{a}_{i k}^{m} \tilde{a}_{j}^{n}+\tilde{a}_{i}^{m} \tilde{a}_{j k}^{n}\right) g_{m n}, \\
\bar{y}^{i} & =a_{j}^{i} y^{j}, \quad \bar{X}^{i}=a_{j}^{i} X^{j}, \quad \bar{Y}^{i}=a_{j}^{i} Y^{j}-a_{\ell}^{i} \tilde{a}_{m n}^{\ell} a_{j}^{m} a_{k}^{n} y^{j} X^{k} . \tag{2}
\end{align*}
$$

Denote further

$$
\begin{align*}
& I_{1}=g_{i j} y^{i} y^{j}, \quad I_{2}=g_{i j} X^{i} X^{j}, \quad I_{3}=g_{i j} X^{i} y^{j}, \quad I_{4}=g_{i j} y^{i} X^{j}, \\
& I_{5}=g_{i j, k} y^{i} y^{j} X^{k}+g_{i j} y^{i} Y^{j}+g_{i j} Y^{i} y^{j},  \tag{3}\\
& I_{6}=g_{i j, k} X^{i} X^{j} y^{k}+g_{i j} X^{i} Y^{j}+g_{i j} Y^{i} X^{j} .
\end{align*}
$$

The geometrical construction of $I_{1}, \ldots, I_{6}$ is straightforward. Denote by $G(u, v)$ the full contraction of $G$ with $u, v \in T M$. On the iterated tangent bundle we have two canonical projections $p_{T M}, T p_{M}: T T M \rightarrow T M$. Then $I_{1}=G\left(p_{T M}(A)\right.$, $\left.p_{T M}(A)\right), I_{2}=G\left(T p_{M}(A), T p_{M}(A)\right), I_{3}=G\left(T p_{M}(A), p_{T M}(A)\right), I_{4}=G\left(p_{T M}(A)\right.$, $\left.T p_{M}(A)\right), A \in T T M$. Further, differentiating $I_{1}$ we get $I_{5}$, and $I_{6}=I_{5} \circ \kappa_{M}$, where $\kappa_{M}: T T M \rightarrow T T M$ is the canonical involution. Obviously, $I_{1}, \ldots, I_{6}$ are invariants of $G_{m}^{2}$. Now we prove that $I_{1}, \ldots, I_{6}$ generate all $G_{m}^{2}$-invariants defined on $Q$.

Proposition 4. For $m=\operatorname{dim} M \geqq 3$, all first order natural operators transforming (0,2)-tensor fields on $M$ into functions on TTM are of the form

$$
\varphi\left(I_{1}, \ldots, I_{6}\right)
$$

where $\varphi$ is an arbitrary smooth function of six variables.

Proof. According to the general theory of natural operators, [6], we have to determine all $G_{m}^{2}$-invariant maps $f: Q \rightarrow \mathbb{R}, f=f\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}\right)$. Using the tensor evaluation theorem from [6] we get $f=\varphi\left(P_{1}, \ldots, P_{36}\right)$, where $\varphi$ is an
arbitrary smooth function of 36 variables

$$
\begin{aligned}
P_{1} & =g_{i j} y^{i} y^{j}, P_{2}=g_{i j} X^{i} X^{j}, P_{3}=g_{i j} Y^{i} Y^{j}, P_{4}=g_{i j} y^{i} X^{j}, P_{5}=g_{i j} X^{i} y^{j}, \\
P_{6} & =g_{i j} y^{i} Y^{j}, P_{7}=g_{i j} Y^{i} y^{j}, P_{8}=g_{i j} X^{i} Y^{j}, P_{9}=g_{i j} Y^{i} X^{j}, P_{10}=g_{i j, k} y^{i} y^{j} y^{k}, \\
P_{11} & =g_{i j, k} X^{i} X^{j} X^{k}, P_{12}=g_{i j, k} Y^{i} Y^{j} Y^{k}, P_{13}=g_{i j, k} y^{i} X^{j} X^{k}, P_{14}=g_{i j, k} y^{i} Y^{j} Y^{k}, \\
P_{15} & =g_{i j, k} y^{i} y^{j} X^{k}, P_{16}=g_{i j, k} y^{i} X^{j} y^{k}, P_{17}=g_{i j, k} y^{i} y^{j} Y^{k}, P_{18}=g_{i j, k} y^{i} Y^{j} y^{k}, \\
P_{19} & =g_{i j, k} y^{i} X^{j} Y^{k}, P_{20}=g_{i j, k} y^{i} Y^{j} X^{k}, P_{21}=g_{i j, k} X^{i} y^{j} y^{k}, P_{22}=g_{i j, k} X^{i} Y^{j} Y^{k}, \\
P_{23} & =g_{i j, k} X^{i} y^{j} X^{k}, P_{24}=g_{i j, k} X^{i} X^{j} y^{k}, P_{25}=g_{i j, k} X^{i} y^{j} Y^{k}, P_{26}=g_{i j, k} X^{i} Y^{j} y^{k}, \\
P_{27} & =g_{i j, k} X^{i} X^{j} Y^{k}, P_{28}=g_{i j, k} X^{i} Y^{j} X^{k}, P_{29}=g_{i j, k} Y^{i} y^{j} y^{k}, P_{30}=g_{i j, k} Y^{i} X^{j} X^{k}, \\
P_{31} & =g_{i j, k} Y^{i} y^{j} X^{k}, P_{32}=g_{i j, k} Y^{i} X^{j} y^{k}, P_{33}=g_{i j, k} Y^{i} y^{j} Y^{k}, P_{34}=g_{i j, k} Y^{i} Y^{j} y^{k}, \\
P_{35} & =g_{i j, k} Y^{i} X^{j} Y^{k}, P_{36}=g_{i j, k} Y^{i} Y^{j} X^{k} .
\end{aligned}
$$

Replace ( $P_{15}, P_{6}, P_{7}$ ) by a new triple of independent variables $P_{15}^{\prime}:=P_{15}-P_{6}-P_{7}$, $I_{5}=P_{15}+P_{6}+P_{7}, P_{7}^{\prime}:=P_{6}-P_{7}$. Analogously, we replace $\left(P_{24}, P_{8}, P_{9}\right)$ by $P_{24}^{\prime}:=P_{24}-P_{8}-P_{9}, I_{6}=P_{24}+P_{8}+P_{9}, P_{9}^{\prime}:=P_{8}-P_{9}$. Then $\varphi$ is of the form

$$
\begin{equation*}
\varphi\left(I_{1}, \ldots, I_{6}, P_{3}, P_{7}^{\prime}, P_{9}^{\prime}, P_{10}, \ldots, P_{14}, P_{15}^{\prime}, P_{16}, \ldots, P_{23}, P_{24}^{\prime}, P_{25}, \ldots, P_{36}\right) \tag{4}
\end{equation*}
$$

It suffices to deduce that $\varphi$ is independent of all $P^{\prime} s$. Consider the equivariance of (4) on the kernel of the jet projection $G_{m}^{2} \rightarrow G_{m}^{1}$, which is characterized by $a_{j}^{i}=\delta_{j}^{i}$, and put $y=(1,0, \ldots, 0), X=(0,1,0, \ldots, 0), Y=(0,0,1,0, \ldots, 0)$. We obtain

$$
\begin{aligned}
& \varphi\left(I_{1}, \ldots, I_{6}, P_{3}, P_{7}^{\prime}, P_{9}^{\prime}, P_{10}, \ldots, P_{14}, P_{15}^{\prime}, P_{16}, \ldots, P_{23}, P_{24}^{\prime}, P_{25}, \ldots, P_{36}\right) \\
& \quad=\varphi\left(I_{1}, \ldots, I_{6}, \bar{P}_{3}, \bar{P}_{7}^{\prime}, \bar{P}_{9}^{\prime}, \bar{P}_{10}, \ldots, \bar{P}_{14}, \bar{P}_{15}^{\prime}, \bar{P}_{16}, \ldots, \bar{P}_{23}, \bar{P}_{24}^{\prime}, \bar{P}_{25}, \ldots, \bar{P}_{36}\right)
\end{aligned}
$$

where $P_{3}=g_{33}, \bar{P}_{3}=g_{33}\left(1+a_{12}^{3}\right)\left(1+a_{12}^{3}\right), \ldots, P_{36}=g_{33,2}, \bar{P}_{36}=\left(g_{33,2}+\tilde{a}_{32}^{m} g_{m 3}+\right.$ $\left.\tilde{a}_{32}^{n} g_{3 n}\right)\left(1+a_{12}^{3}\right)\left(1+a_{12}^{3}\right)$. Setting $a_{12}^{3}=-1$ we get that $\varphi$ does not depend on all $P^{\prime} s$ except $P_{10}, P_{11}, P_{13}, P_{15}^{\prime}, P_{16}, P_{21}, P_{23}, P_{24}^{\prime}$. By the choice of $\tilde{a}_{11}^{m}$ we prove that $\varphi$ is independent of $P_{10}, P_{16}, P_{21}$. Analogously, by means of $\tilde{a}_{22}^{m}$ we get that $\varphi$ does not depend on $P_{11}, P_{13}, P_{23}$ and the choice of $\tilde{\boldsymbol{a}}_{12}^{m}$ yields the independence of $\varphi$ on $P_{15}^{\prime}$ and $P_{24}^{\prime}$.

In the case $m=2$, the same result holds if we restrict ourselves to tensor fields which are either symmetric or antisymmetric.

Proposition 5. For $m=2$, all first order natural operators transforming symmetric or antisymmetric ( 0,2 )-tensor fields on $M$ into functions on TTM are of the form

$$
\begin{equation*}
\varphi\left(I_{1}, \ldots, I_{6}\right) \tag{5}
\end{equation*}
$$

where $\varphi$ is an arbitrary smooth function of six variables.
Proof. Consider the function $f\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}\right)$ from the proof of Proposition 4 and define $\varphi$ by the formula $\varphi\left(z_{1}, \ldots, z_{6}\right)=f\left(1,0 ; 0,1 ; 0,0 ; g_{11}=z_{1}, g_{22}=\right.$
$\left.z_{2}, g_{12}=z_{3}, g_{21}=z_{4} ; g_{11,2}=z_{5}, g_{22,1}=z_{6}, 0,0,0,0,0,0\right)$. There is a linear transformation transforming independent vectors $y$ and $X$ into (1,0) and (0,1). Next, (2) with $a_{j}^{i}=\delta_{j}^{i}$ yields $\bar{Y}^{i}=Y^{i}-\tilde{a}_{12}^{i}, \bar{g}_{i j, k}=g_{i j, k}+\tilde{a}_{i k}^{m} g_{m j}+\tilde{a}_{j k}^{n} g_{i n}$. By the choice of $\tilde{a}_{12}^{1}$ and $\tilde{\boldsymbol{a}}_{12}^{2}$ we obtain $\bar{Y}^{i}=0$. Further, for $g_{i j} \neq 0$ the choice of $\tilde{\boldsymbol{a}}_{11}^{1}$ and $\tilde{\boldsymbol{a}}_{11}^{2}$ gives $\bar{g}_{11,1}=0, \bar{g}_{12,1}=0$. Analogously, using $\tilde{a}_{22}^{1}$ and $\tilde{a}_{22}^{2}$ we get $\bar{g}_{22,2}=0, \bar{g}_{12,2}=0$. By symmetry or antisymmetry we have $\bar{g}_{21,1}=\bar{g}_{12,1}=0, \bar{g}_{21,2}=\bar{g}_{12,2}=0$. Then $I_{1}=g_{11}, I_{2}=g_{22}, I_{3}=g_{12}, I_{4}=g_{21}, I_{5}=g_{11,2}, I_{6}=g_{22,1}$. Thus $\varphi$ is of the form (5) on an open dense subset.

## 4. The classification theorem

We first prove the following auxiliary assertion, which has also a number of interesting features in its own right (see Remark 2).
Proposition 6. For $m \geqq 3$, all first order natural operators $T^{*} \otimes T^{*} \rightsquigarrow\left(T T, T^{*} T\right)$ transforming $(0,2)$-tensor fields on $M$ into morphisms $T T M \rightarrow T^{*} T M$ are of the form

$$
\begin{align*}
w^{i} & =A_{1} y^{i}+A_{2} X^{i}, \\
s_{i} & =A_{3} g_{j i} y^{j}+\bar{A}_{3} g_{i j} y^{j}+A_{4} g_{j i} X^{j}+\bar{A}_{4} g_{i j} X^{j} \\
r_{i} & =\left(A_{1} A_{4}+A_{2} A_{3}\right) g_{j i} Y^{j}+\left(A_{1} \bar{A}_{4}+A_{2} \bar{A}_{3}\right) g_{i j} Y^{j}+A_{2} A_{3} g_{j i, k} y^{j} X^{k} \\
& +A_{2} \bar{A}_{3} g_{i j, k} y^{j} X^{k}+A_{1} A_{4} g_{j i, k} X^{j} y^{k}+A_{1} \bar{A}_{4} g_{i j, k} X^{j} y^{k} \\
& +A_{5} g_{j i} y^{j}+\bar{A}_{5} g_{i j} y^{j}+A_{6} g_{j i} X^{j}+\bar{A}_{6} g_{i j} X^{j}  \tag{6}\\
& -B_{1} g_{j i} Y^{j}-B_{2} g_{j i} Y^{j}-B_{1} g_{i j} Y^{j}-B_{2} g_{i j} Y^{j} \\
& -B_{1} g_{j i, k} y^{j} X^{k}-B_{2} g_{i j, k} y^{j} X^{k}-B_{2} g_{j i, k} X^{j} y^{k} \\
& -B_{1} g_{i j, k} X^{j} y^{k}+B_{1} g_{j k, i} y^{j} X^{k}+B_{2} g_{j k, i} X^{j} y^{k} \\
& +C_{1} g_{j k, i} y^{j} y^{k}+C_{2} g_{j k, i} X^{j} X^{k}
\end{align*}
$$

where $A_{i}, \bar{A}_{i}$ and $B_{i}$ are arbitrary smooth functions of the invariants $I_{1}, \ldots, I_{6}$ and

$$
C_{1}=A_{1} A_{3}=A_{1} \bar{A}_{3}, \quad C_{2}=A_{2} A_{4}=A_{2} \bar{A}_{4}
$$

Proof. Let $S=\mathbb{R}^{m} \times \mathbb{R}^{m *} \times \mathbb{R}^{m *}$ be the standard fibre of $T^{*} T$ with the canonical coordinates $\left(w^{i}, s_{i}, r_{i}\right)$. Then we have to determine all $G_{m}^{2}$-equivariant maps $Q \rightarrow$ $S$,

$$
\begin{aligned}
w^{i} & =w^{i}\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}\right) \\
s_{i} & =s_{i}\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}\right) \\
r_{i} & =r_{i}\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}\right)
\end{aligned}
$$

Using standard evaluations we find that the action of $G_{m}^{2}$ on $S$ is

$$
\bar{w}^{i}=a_{j}^{i} w^{j}, \quad \bar{s}_{i}=\tilde{a}_{i}^{j} s_{j}, \quad \bar{r}_{i}=\tilde{a}_{i}^{j} r_{j}-\tilde{a}_{i}^{j} a_{j k}^{\ell} \tilde{a}_{\ell}^{m} s_{m} w^{k}
$$

while the action of $G_{m}^{2}$ on $Q$ is given by (2). First we discuss $w^{i}\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}\right)$. Let us introduce new variables $u_{i} \in \mathbb{R}^{m *}, \bar{u}_{i}=\tilde{a}_{i}^{j} u_{j}$. Then $\varphi:=w^{i} u_{i}$ is a $G_{m}^{2}-$ invariant function, $\varphi=\varphi\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}, u_{i}\right)$ and $I_{7}=y^{i} u_{i}, I_{8}=X^{i} u_{i}$ are further $G_{m}^{2}$-invariants. In the same way as in the proof of Proposition 4 we deduce $\varphi=\varphi\left(I_{1}, \ldots, I_{8}\right)$, so that $w^{i} u_{i}=\varphi\left(I_{1}, \ldots, I_{6}, y^{i} u_{i}, X^{i} u_{i}\right)$. Differentiating with respect to $u_{i}$ and then setting $u_{i}=0$ we obtain $w^{i}=A_{1}\left(I_{1}, \ldots, I_{6}\right) y^{i}+$ $A_{2}\left(I_{1}, \ldots, I_{6}\right) X^{i}$. This corresponds to the first equation of (6). Using a similar procedure for $s_{i}\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}\right)$ we deduce the second equation of (6).

Finally, assume $r_{i}\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}\right)$ in the form

$$
\begin{aligned}
r_{i} & =\alpha_{1} g_{j i} Y^{j}+\bar{\alpha}_{1} g_{i j} Y^{j}+\alpha_{2} g_{j i, k} y^{j} X^{k}+\bar{\alpha}_{2} g_{i j, k} y^{j} X^{k}+\alpha_{3} g_{j i, k} X^{j} y^{k} \\
& +\bar{\alpha}_{3} g_{i j, k} X^{j} y^{k}+\beta_{1} g_{j k, i} y^{j} X^{k}+\beta_{2} g_{j k, i} X^{j} y^{k}+\gamma_{1} g_{i j, k} y^{j} y^{k}+\gamma_{2} g_{i j, k} X^{j} X^{k} \\
& +\gamma_{3} g_{j i, k} y^{j} y^{k}+\gamma_{4} g_{j i, k} X^{j} X^{k}+\gamma_{5} g_{j k, i} y^{j} y^{k}+\gamma_{6} g_{j k, i} X^{j} X^{k} \\
& +\tilde{r}_{i}\left(y^{i}, X^{i}, Y^{i}, g_{i j}, g_{i j, k}\right) .
\end{aligned}
$$

Applying equivariance on the kernel of the jet projection $G_{m}^{2} \rightarrow G_{m}^{1}$ we get the following relations: $A_{2} A_{3}=\alpha_{2}+\beta_{1}, A_{2} \bar{A}_{3}=\bar{\alpha}_{2}+\beta_{2}, A_{1} A_{4}=\alpha_{3}+\beta_{2}, A_{1} \overline{\bar{A}}_{4}=$ $\bar{\alpha}_{3}+\beta_{1}, \alpha_{1}=\alpha_{2}+\alpha_{3}, \bar{\alpha}_{1}=\bar{\alpha}_{2}+\bar{\alpha}_{3}, \gamma_{1}=\gamma_{2}=\gamma_{3}=\gamma_{4}=0, A_{1} A_{3}=A_{1} \bar{A}_{3}=$ $\gamma_{5}, A_{2} A_{4}=A_{2} \bar{A}_{4}=\gamma_{6}$. Then the full equivariance reads $\tilde{a}_{i}^{j} \tilde{r}_{j}\left(y^{i}, \ldots, g_{i j, k}\right)=$ $\tilde{r}_{i}\left(\bar{y}_{i}, \ldots, \bar{g}_{i j, k}\right)$ so that $\tilde{r}_{i}$ has the same transformation law as $s_{i}$. Thus $\tilde{r}_{i}=$ $A_{5} g_{j i} y^{j}+\bar{A}_{5} g_{i j} y^{j}+A_{6} g_{j i} X^{j}+\bar{A}_{6} g_{i j} X^{j}$.

Let $G=g_{i j} d x^{i} \otimes d x^{j}$ be a ( 0,2 )-tensor field on $M$. Then $G$ induces a symmetric tensor field $S=S_{i j} d x^{i} \otimes d x^{j}$ and an antisymmetric tensor field $R=R_{i j} d x^{i} \otimes d x^{j}$ by $S_{i j}=\frac{1}{2}\left(g_{i j}+g_{j i}\right), R_{i j}=\frac{1}{2}\left(g_{i j}-g_{j i}\right)$. Denote further

$$
G^{\prime}=g_{j i} d x^{i} \otimes d x^{j}
$$

Clearly, $G=S+R, G^{\prime}=S-R$. Now we prove the main result of this paper.
Theorem. For $m \geqq 3$, all first order natural operators $T^{*} \otimes T^{*} \rightsquigarrow\left(T^{*} \otimes T^{*}\right) T$ transforming ( 0,2 )-tensor fields on $M$ into ( 0,2 )-tensor fields on $T M$ are of the form

$$
\begin{equation*}
G \mapsto K_{1}\left(G^{\prime}\right)^{C}+K_{2} G^{C}+K_{3}\left(G^{\prime}\right)^{V}+K_{4} G^{V}+K_{5}\left(G^{\prime}\right)^{A}+K_{6} G^{A} \tag{7}
\end{equation*}
$$

where $K_{i}=K_{i}\left(g_{i j} y^{i} y^{j}\right)$ are arbitrary smooth functions of the invariant $I_{1}$ and $G^{C}, G^{V}$ and $G^{A}$ denote the canonical liftings.

Proof. Taking into account an identification of every (0,2)-tensor field $\bar{G}$ on $T M$ with a linear map $\bar{G}_{L}: T T M \rightarrow T^{*} T M$ over the identity of $T M$, it suffices to choose suitable morphisms (6) from Proposition (6). Clearly, all such linear maps
are of the form

$$
\begin{align*}
w^{i} & =y^{i}, \\
s_{i} & =A_{4} g_{j i} X^{j}+\bar{A}_{4} g_{i j} X^{j}, \\
r_{i} & =A_{4}\left(g_{j i} Y^{j}+g_{j i, k} X^{j} y^{k}\right)+\bar{A}_{4}\left(g_{i j} Y^{j}+g_{i j, k} X^{j} y^{k}\right) \\
& +B_{1}\left(g_{j k, i}-g_{j i, k}\right) y^{j} X^{k}+B_{2}\left(g_{k j, i}-g_{i j, k}\right) y^{j} X^{k}  \tag{8}\\
& -B_{1} g_{i j, k} X^{j} y^{k}-B_{2} g_{j i, k} X^{j} y^{k} \\
& -B_{1} g_{j i} Y^{j}-B_{2} g_{j i} Y^{j}-B_{1} g_{i j} Y^{j}-B_{2} g_{i j} Y^{j}+A_{6} g_{j i} X^{j}+\bar{A}_{6} g_{i j} X^{j} .
\end{align*}
$$

This can be rewritten as

$$
\begin{aligned}
w^{i} & =y^{i} \\
s_{i} & =\left(A_{4}-B_{2}\right) g_{j i} X^{j}+\left(\bar{A}_{4}-B_{1}\right) g_{i j} X^{j}+B_{2} g_{j i} X^{j}+B_{1} g_{i j} X^{j} \\
r_{i} & =\left(A_{4}-B_{2}\right)\left(g_{j i} Y^{j}+g_{j i, k} X^{j} y^{k}\right)+\left(\bar{A}_{4}-B_{1}\right)\left(g_{i j} Y^{j}+g_{i j, k} X^{j} y^{k}\right) \\
& +B_{1}\left(g_{j k, i}-g_{j i, k}\right) y^{j} X^{k}+B_{2}\left(g_{k j, i}-g_{i j, k}\right) y^{j} X^{k} \\
& -B_{1} g_{j i} Y^{j}-B_{2} g_{i j} Y^{j}+A_{6} g_{j i} X^{j}+\bar{A}_{6} g_{i j} X^{j}
\end{aligned}
$$

which is nothing but the coordinate form of (7), where $K_{1}=A_{4}-B_{2}, K_{2}=$ $\bar{A}_{4}-B_{1}, K_{3}=A_{6}, K_{4}=\bar{A}_{6}, K_{5}=B_{1}, K_{6}=B_{2}$. Finally, on the standard fibre $V=\otimes^{2} \mathbb{R}^{m *} \times \otimes^{3} \mathbb{R}^{m *} \times \mathbb{R}^{m}$ of $J^{1}\left(T^{*} \otimes T^{*}\right) \oplus T$ we have only one invariant $I_{1}=g_{i j} y^{i} y^{j}$, so that the coefficients $K_{i}$ are smooth functions of $I_{1}$ only (this also follows from the linearity of $\bar{G}_{L}$ ).

Using the symmetric tensor field $S$ and antisymmetric tensor field $R$ one can also express (7) in the form

$$
G \mapsto K_{1} S^{C}+K_{2} R^{C}+K_{3} S^{V}+K_{4} R^{V}+K_{5} S^{A}+K_{6} R^{A}
$$

Corollary 1. For $m \geqq 3$, all first order natural operators transforming symmetric or antisymmetric $(0,2)$-tensor fields on $M$ into $(0,2)$-tensor fields on $T M$ are of the form

$$
G \mapsto K_{1} G^{C}+K_{2} G^{V}+K_{3} G^{A}
$$

where $K_{i}=K_{i}\left(I_{1}\right)$ are arbitrary smooth functions of the invariant $I_{1}$.
Corollary 2. For $m \geqq 3$, all first order natural $\mathbb{R}$-linear operators $T^{*} \otimes T^{*} \leadsto$ $\left(T^{*} \otimes T^{*}\right) T$ are of the form (7), where $K_{i}$ are arbitrary real numbers.
Remark 2. Janyška, [3], has described some natural transformations TTM $\rightarrow$ $T^{*} T M$ on a Riemannian manifold $M$. He has in fact constructed certain first order natural operators $\operatorname{Reg} S^{2} T^{*} \rightsquigarrow\left(T T, T^{*} T\right)$, where $\operatorname{Reg} S^{2} T^{*}$ denotes the bundle functor of Riemannian metrics. In Proposition 6 we have determined the analytical
form of all first order natural operators $T^{*} \otimes T^{*} \rightsquigarrow\left(T T, T^{*} T\right)$, provided $\operatorname{dim} M \geqq$ 3. Such operators were then essentially used in the proof of our classification theorem. By Kolář and Radziszewski [5] there is no natural equivalence $T T M \rightarrow$ $T^{*} T M$. This is due to the essentially different character of natural transformations $T T M \rightarrow T T M$ and $T^{*} T M \rightarrow T^{*} T M$. On the other hand, from (6) we can see that a ( 0,2 )-tensor field on $M$ induces a 'wide' class of natural transformations $T T M \rightarrow T^{*} T M$. Now we give the geometrical construction of some morphisms $T T M \rightarrow T^{*} T M$ from Proposition 6.

1. The choice $A_{1}=0, A_{2}=1, A_{3}=0, \bar{A}_{3}=0, C_{1}=0, C_{2}=0$ in (6) gives (8). Then $\bar{A}_{4}$ or $A_{4}$ correspond to the complete lift of $G=g_{i j} d x^{i} \otimes d x^{j}$ or $G^{\prime}=g_{j i} d x^{i} \otimes d x^{j}$, respectively. Analogously, $A_{6}$ and $\bar{A}_{6}$ correspond to the vertical lift and $B_{1}$ and $B_{2}$ correspond to the antisymmetric lift.
2. Each map $f: T M \rightarrow T^{*} M$ defines a function $\tilde{f}: T M \rightarrow \mathbb{R}$ given by $\tilde{f}(y)=$ $\langle f(y), y\rangle$, so that a $(0,2)$ - tensor field $G$ on $M$ determines a function $\widetilde{G}_{L}: T M \rightarrow \mathbb{R}$, $\widetilde{G}_{L}(y)=g_{i j} y^{i} y^{j}$. Its exterior differential $d \widetilde{G}_{L}$ is a 1 -form on $T M$, in coordinates $d \widetilde{G}_{L}=g_{j k, i} y^{j} y^{k} d x^{i}+\left(g_{i j} y^{j}+g_{j i} y^{j}\right) d y^{i}$. Then the morphisms $d \widetilde{G}_{L} \circ p_{T M}$ and $d \widetilde{G}_{L} \circ T p_{M}: T T M \rightarrow T^{*} T M$ correspond to the terms with $C_{1}$ and $C_{2}$ in (6).
3. All the morphisms $T T M \rightarrow T^{*} T M$ from (6) with $B_{1}=B_{2}=C_{1}=C_{2}=0$ can be constructed as follows. Denote by $t_{M}: T^{*} T M \rightarrow T^{*} T M$ any natural transformation over the identity of $T M$ determined by Kolář and Radziszewski in [5]. Further, let $h_{M}: T T M \rightarrow T T M$ be any natural transformation by Kolár̆ [4]. Moreover, we denote by $s_{M}: T T^{*} M \rightarrow T^{*} T M$ the canonical isomorphism [8], [11]. Take the $\operatorname{map} G_{L}: T M \rightarrow T^{*} M$ which canonically corresponds to a $(0,2)-$ tensor field $G$ on $M$ and evaluate the composition $t_{M} \circ s_{M} \circ T G_{L}: T T M \rightarrow T^{*} T M$. Quite similarly, the tensor field $G^{\prime}$ induces a map $t_{M} \circ s_{M} \circ T G_{L}^{\prime}: T T M \rightarrow T^{*} T M$. Next, for $Z \in T T M$ the sum of $\left(t_{M} \circ s_{M} \circ T G_{L}\right)(Z)$ and $\left(t_{M} \circ s_{M} \circ T G_{L}^{\prime}\right)(Z)$ with respect to the vector bundle structure $T^{*} T M \rightarrow T M$ determines a map $f: T T M \rightarrow T^{*} T M$. Then $f \circ h_{M}$ is exactly (6) with $B_{1}=B_{2}=C_{1}=C_{2}=0$. If $G$ is symmetric or antisymmetric, then the whole construction is much easier. In fact, in this case it suffices to evaluate $s_{M} \circ T G_{L} \circ h_{M}$ (compare with $s_{M} \circ T G_{L} \circ \kappa_{M}$ in (1)).
Remark 3. The proof of our classification theorem was based on the identification of $(0,2)$-tensor fields with linear maps $T M \rightarrow T^{*} M$. A similar procedure can be used for liftings of (1,1)-tensor fields to $T M$ which we identify with linear maps $T M \rightarrow T M$.

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[^0]:    1991 Mathematics Subject Classification: 53A55, 58A20.
    Key words and phrases: natural operator, tensor field, complete lift, vertical lift.
    Received June 14, 1993.
    *Research supported by GA CR, grant No. 201/93/2195.

