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CERTAIN RELATION BETWEEN VECTOR FIELDS AND DISTRIBUTIONS ON A DIFFERENTIABLE MANIFOLD

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Let M be a differentiable manifold. Let X be a vector field on M and let Δ be a distribution of h-dimensional tangent subspaces on M.

In this paper we shall study some relations between the fields X and distribution Δ . In the following computations we use the calculus of jets, see [2].

1. Let $T_h^1(M)$ be the vector space of all h^1 -velocities on the manifold M, i.e. the space of all 1-jets of local mappings from R^h into M with the source $0 \in R^h$. Let X be a vector field on M and ${}^t \Phi$ its 1-parametric local group. Let us remind that the vector field X can be naturally prolonged to $T_h^1(M)$ according to the rule

$${}^{1}X(u) = j_0^1[j_0^1({}^{t}\Phi \cdot \varphi)], \text{ for } u \in T_h^1(M), \text{ where } u = j_0^1\varphi$$

Let (x^i) , i = 1, 2, ..., n, be local coordinates on M, dim M = n; let (x^i, y^i_j) , j = 1, 2, ..., h, $h \leq n$, be corresponding local coordinates on $T_h^1(M)$ and let

(1)
$${}^{1}X \equiv a^{i}(x) \partial/\partial x_{i} + b^{i}_{j} \partial/\partial y^{j}_{i}$$

be the prolongation of the vector field X to the manifold $T_h^1(M)$. To determine the components b_I^i let us remind that

$$T_h^1(M) \equiv (x^i, y^i_j) \equiv j_0^1 \varphi$$
, where $\varphi : R^h \to M$, i.e. $\varphi : x^i = \varphi^i(u^j)$.

The vector field X determines a local 1-parametric group ${}^{t}\Phi$ of transformations on M

$${}^{t}\Phi:\bar{x}^{k}=f^{k}(x^{i},t) \text{ for } k=1,2,...,n$$

Then

$${}^{t}\Phi \cdot \varphi : \bar{x}^{k} = f^{k}(\varphi^{i}(u^{j}), t) \text{ and } j^{1}_{0}({}^{t}\Phi \cdot \varphi) \equiv \frac{\partial f^{k}}{\partial x^{i}} \cdot \frac{\partial x^{i}}{\partial u^{j}}$$

Hence

$$j_{0t}^{1}[j_{0x}^{1}({}^{t}\Phi \cdot \varphi)] \equiv \frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial f^{k}}{\partial x^{i}} \cdot \frac{\partial x^{i}}{\partial u^{j}} \right) = \frac{\partial}{\partial x^{i}} \left(\frac{\mathrm{d}f^{k}}{\mathrm{d}t} \right) y_{j}^{i} = \frac{\partial a^{k}}{\partial x^{i}} y_{j}^{i} \equiv b_{j}^{k} \cdot b_{j}^{k}$$

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Consequently the vector field ${}^{1}X$ from (1) can be expressed in the form

(1')
$${}^{1}X \equiv a^{i}(x) \partial/\partial x_{i} + \frac{\partial a^{i}}{\partial x^{k}} y^{k}_{j} \partial/\partial y^{j}_{i}.$$

2. Let us consider a global cross-section

(2)
$$\overline{\Gamma}: M \to T^1_h(M)$$
.

In local coordinates

$$\bar{\Gamma}: x^i = x^i, \quad y^i_j = f^i_j(x^k).$$

The restriction of the prolonged vector field ${}^{1}X$ to the submanifold $\overline{\Gamma}(M) \subset T_{h}^{1}(M)$ is given by

(3)
$${}^{1}X/\overline{\Gamma}(M) \equiv a^{i}(x) \partial/\partial x_{i} + \frac{\partial a^{i}}{\partial x^{\lambda}} f^{\lambda}_{j}(x^{k}) \partial/\partial y^{j}_{i}$$

for $\lambda = 1, 2, ..., n$.

Definition 1. A vector field X on M is said to be conjugate to the map $\overline{\Gamma}$ if

(4)
$$\bar{\Gamma}_*(X) \equiv {}^1X/\bar{\Gamma}(M) \, .$$

 $\overline{\Gamma}_*(X)$ is a vector field on $\overline{\Gamma}(M)$. Therefore, according to (2) and (3), its local expression is given by

(5)
$$\bar{\Gamma}_{*}(X) \equiv a^{i}(x) \partial/\partial x_{i} + a^{k} \frac{\partial f_{j}^{i}}{\partial x^{k}} \partial/\partial y_{j}^{j}.$$

Substituing from (3) and (5) into (4) we obtain

(6)
$$\frac{\partial a^i}{\partial x^{\lambda}} f^{\lambda}(x) = a^k \frac{\partial f^i(x)}{\partial x^k}.$$

The map (2) determines h vector fields X_r on M with the local expressions

(7)
$$X_r = f_r^i(x) \partial/\partial x_i \text{ for } r = 1, 2, ..., h$$

When X is an arbitrary vector field conjugate to the map $\overline{\Gamma}$, we get

(8)
$$[X, X_r] = \left\{ \frac{\partial f_r^k(x)}{\partial x^i} \cdot a^i(x) - \frac{\partial a^k(x)}{\partial x^i} f_r^i(x) \right\} \partial / \partial x_k ,$$

where $[X, X_r]$ are Lie brackets.

By comparison of (6) and (8) we obtain

Lemma 1. A necessary and sufficient condition for a vector field X to be conjugate to the map $\overline{\Gamma}$ is that

$$[X, X_r] = 0$$
 for each $r = 1, 2, ..., h$.

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3. Let $R T_h^1(M)$ denote the set of all regular h^1 -velocities on M. Obviously, $RT_h^1(M)$ is an open submanifold of the manifold $T_h^1(M)$. If X is a vector field on M then ${}^1X/R T_h^1(M)$ is a vector field on $R T_h^1(M)$. Let $K_h^1(M)$ denote the factor space of $RT_h^1(M)$ consisting of all classes of the form $Y \cdot L_h^1$, where Y is a regular h^1 -velocity on M and L_h^1 is the full linear transformation group of R^h . Let Δ be the distribution of *h*-dimensional tangent subspaces determined by a map $\Gamma : M \to K_h^1(M)$. We have the canonical projection $\varrho : R T_h^1(M) \to K_h^1(M)$. If ${}^t\Phi$ is the 1-parametric local group on $R T_h^1(M)$ generated by the vector field X and if ${}^t\Phi_h^1$ is the 1-parametric local group on $R T_h^1(M)$ generated by the vector field $X T_h^1(M)$ then

(9)
$${}^{t}\Phi_{h}^{1}(u) = {}^{t}\Phi \cdot u , \quad u \in RT_{h}^{1}(M)$$

Here the dot denotes the composition of jets. It follows from (9) that the map ${}^{t}\Phi_{h}^{1}$ preserves the classes Y. L_{h}^{1} . Thus we can define a 1-parametric local group on $K_{h}^{1}(M)$ by the formula

(10)
$${}^{t}\overline{\Phi}_{h}^{1}:[v]\mapsto [{}^{t}\Phi\cdot v]$$

where $[v] \in K_h^1(M)$ denotes the class of $v \in R$ $T_h^1(M)$. The vector field ${}^1\overline{X}$ on $K_h^1(M)$ induced by ${}^t\overline{\Phi}_h^1$ will be called the h^1 -tangent prolongation of the vector field X. Obviously we have

(11)
$$\varrho_*({}^1X) = {}^1\overline{X}.$$

The map $\Gamma: M \to \Gamma(M)$ is a diffeomorfism and $\Gamma_*(X)$ is a vector field on $\Gamma(M) \subset \subset K^1_h(M)$.

Definition 2. A vector field on M is said to be conjugate to the distribution Δ if $\Gamma_*(X) = {}^1\overline{X}/\Gamma(M)$.

Let us remark that A. DEKRÉT in [1] investigates the conjugacy of special vector fields and special distributions on the manifold T(M).

Definition 3. A vector field on M is called a subfield of the distribution Δ if $X(m) \in \Gamma_m$ for all $m \in M$.

Lemma 2. Suppose that, for each subfield Y of Δ , the Lie bracket [X, Y] is also a subfield of Δ . Then for each point $u \in M$ there is a neighbourhood $U \subset M$ and vector fields $X \equiv X_1, X_2, ..., X_{h+1}$ on U such that Δ is generated by $X_2, ..., X_{h+1}$ and $[X, X_s] = 0$ holds for s = 2, 3, ..., h + 1.

Proof. Let $u \in M$. Let $(U, x^1, x^2, ..., x^n)$ is a chart on M such that $X \equiv \partial/\partial x_1$ in the neighbourhood U of u. On U there are vector fields $X \equiv \partial/\partial x_1 \equiv Y_1, Y_2, ...$..., Y_{h+1} , where $Y_2, ..., Y_{h+1}$ generate the distribution Δ on U. Because [X, Y]is a subfield of Δ for each subfield Y of Δ we can see that $[Y_1, Y_\alpha]$ are subfields of Δ on U for $\alpha = 2, ..., h + 1$. Let

$$Y_1 \equiv X \equiv \partial/\partial x_1, \quad Y_a = a_a^i \partial/\partial x_i,$$

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where a_{α}^{i} are real functions on U. The matrix $||a_{\alpha}^{i}||$ has rank h for each point $x \in U$. Suppose e.g. that det. $||a_{\alpha}^{s}|| \neq 0$. Let $||b_{\alpha}^{s}||$ denote the inverse if $||a_{\alpha}^{s}||$. Put

$$X_s = b_s^{\alpha} Y_{\alpha} = b_s^{\alpha} a_{\alpha}^i \partial |\partial x_i|.$$

Then

$$X_s = \partial/\partial x_s + b_s^{\alpha} a_{\alpha}^{\beta} \partial/\partial x_{\beta}$$
, where $\beta = 1, h + 2, ..., n$

i.e.

(12)
$$X_s = \partial/\partial x_s + c_s^\beta \partial/\partial x_\beta.$$

Because [X, Y] is a subfield of Δ and the vector fields X_s generate the distribution Δ on U, we get

(13)
$$[X_1, X_{\alpha}] = \lambda_{\alpha}^s X_s = \lambda_{\alpha}^s \partial/\partial x_s + \lambda_{\alpha}^s c_s^{\beta} \partial/\partial x_{\beta}$$

From (12) and (13) we derive

(14)
$$[X_1, X_s] = \frac{\partial c_s^{\beta}}{\partial x_1} \partial \partial x_{\beta} .$$

By comparing (13) and (14) we obtain

(15)
$$\lambda_{\alpha}^{s} = 0.$$

Finally, substituting (15) into (13) we get $[X, X_s] = 0$, q.e.d.

Definition 4. The map $\overline{\Gamma}: M \to RT_h^1(M)$ is called related to the distribution Δ given by the map $\Gamma: M \to K_h^1(M)$ if $\Gamma = \varrho \cdot \overline{\Gamma}$.

Lemma 3. Let the map $\overline{\Gamma}$ be related to the distribution Δ , let a vector field X be conjugate to the map Γ . Then X is conjugate to the distribution Δ .

The proof follows from (11).

Lemma 4. If the distribution Δ is conjugate to the field X then there is locally a map $\overline{\Gamma}$ from M into $RT_h^1(M)$ which is releated to the distribution Δ and conjugate to the field X.

The proof follows from the definition of $K_h^1(M)$.

Theorem. Let Δ be a distribution on a manifold M given by a map $\Gamma : M \to K^1_h(M)$. Let X be a vector field on M and Y a vector subfield of Δ . Then a necessary and sufficient condition for X to be conjugate with Δ is that [X, Y] is a subfield of Δ for each subfield Y.

Proof. Let X satisfy the condition that [X, Y] is a subfield of Δ for each subfield Y. According to Lemma 2 there are vector fields X_s such that $[X, X_s] = 0$. The vector fields X_2, \ldots, X_{h+1} determine uniquely the map $\overline{\Gamma} : M \to RT_h^1(M)$. From Lemma 1 it follows that $\overline{\Gamma}$ is conjugate with X. Lemma 3 implies that Δ is conjugate with X, too. Conversely: Let Δ be conjugate with X. According to Lemma 4 there is a map $\overline{\Gamma}$ which is conjugate with X. The map $\overline{\Gamma}$ determines vector fields X_2, \ldots, X_{h+1} such that $[X, X_{\alpha}] = 0$, on account of Lemma 1. Let $Y = \mu^{\alpha} X_{\alpha}$, the [X, Y] is of the form $\nu^{\alpha} X_{\alpha}$, as well, and hence [X, Y] is a subfield of Δ , q.e.d.

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