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# A GENERALIZATION OF THE LIONS-TEMAM COMPACT IMBEDDING THEOREM 

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#### Abstract

Summary. The well-known theorem by J. L. Lions and R. Temam concerning the compact imbedding of the space $\left\{v \in L^{p}\left(0, T ; B_{0}\right) ; \mathrm{d} v / \mathrm{d} t \in L^{q}\left(0, T ; B_{1}\right)\right\}$ into $L^{p}(0, T ; B)$ is generalized to the case when $B_{0}$ is a reflexive Banach space imbedded compactly into a normed linear space $B$ that is continuously imbedded into a Hausdorff locally convex space $B_{1}$, and $1<p<+{ }_{\infty}$, $1 \leqq q \leqq+\infty$. Applications of such generalization to numerical analysis are outlined.


Keywords: compact imbedding, evolution equations, locally convex spaces.
AMS Subject Classification: Primary 46A50, Secondary 35K65, 65Mxx.
In [1; Chap. 1, Thm. 5.1] and [2; Chap. III, Thm. 2.1] J. L. Lions and R. Temam posed the broadly applicable theorem concerning the compact imbedding of the space

$$
\begin{equation*}
W^{p, q}\left(0, T ; B_{0}, B_{1}\right)=\left\{v \in L^{p}\left(0, T ; B_{0}\right) ; \quad \frac{\mathrm{d} v}{\mathrm{~d} t} \in L^{q}\left(0, T ; B_{1}\right)\right\} \tag{1}
\end{equation*}
$$

into the space $L^{p}(0, T ; B)$, where $B_{0} \subset B \subset B_{1}$ are three Banach spaces, $B_{0}, B_{1}$ are reflexive, the imbedding $B_{0} \subset B$ is compact and $B \subset B_{1}$ is continuous, $1<p<+\infty$, $1<q<+\infty$, and $T>0$. This theorem is very powerful since $B_{1}$ can be chosen arbitrarily large. The aim of this short note is to show that, in fact, it is sufficient to take for $B_{1}$ even an arbitrary locally convex space with the only condition that its topology is a Hausdorff one. Besides, $q$ may be equal to 1 or $+\infty$ and $B$ need not be complete. At the end of this note some applications of such generalization will be briefly outlined.

Let $B_{1}$ be a locally convex pace, $\left\{|\cdot|_{l}\right\}_{\ell \in I}$ being a collection of seminorms generating its topology ( $I$ is an index set). Let the seminorm $|\cdot|_{q \iota}$ be defined by

$$
|v|_{q \iota}= \begin{cases}\left(\int_{0}^{T}|v(t)|_{\iota}^{q} \mathrm{~d} t\right)^{1 / q} & \text { if } \quad 1 \leqq q<+\infty \quad \text { and } \\ \underset{\left.\substack{\text { ess sup } \\ 0 \leqq t \leqq T} v(t)\right|_{\iota}}{ } & \text { if } \quad q=+\infty\end{cases}
$$

Put $L^{q}\left(0, T ; B_{1}\right)=\left\{v:[0, T] \rightarrow B_{1} ; v\right.$ is Bochner integrable, $\left.|v|_{q \iota}<+\infty \forall \iota \in I\right\}$. By endowing $L^{q}\left(0, T ; B_{1}\right)$ with a collection of the seminorms $\left\{|\cdot|_{q \iota}\right\}_{\iota \in I}$, we obviously get a locally convex space. As usual, we will understand a linear operator to be compact if it maps bounded subsets into precompact ones.

Theorem. Let $B_{0}$ be a normed linear space imbedded compactly into another normed linear space $B$ which is continuously imbedded into a Hausdorff locally convex space $B_{1}$, and $1 \leqq p<+\infty$. If $v, v_{i} \in L^{p}\left(0, T ; B_{0}\right)$, $i \in N$, the sequence $\left\{v_{i}\right\}_{i \in N}$ converges weakly to $v$ in $L^{p}\left(0, T ; B_{0}\right)$, and $\left\{\mathrm{d} v_{i} / \mathrm{d} t\right\}_{i \in N}$ is bounded in $L^{1}(0, T$; $\left.B_{1}\right)$, then $\left\{v_{i_{i}}{ }_{i \in N}\right.$ converges to $v$ strongly in $L^{p}(0, T ; B)$.

Proof. First we will prove that $\forall \eta>0 \exists J_{\eta} \in \mathscr{F}(I) \exists c_{\eta} \in \boldsymbol{R} \forall u \in B_{0}$ :

$$
\begin{equation*}
\|u\|_{B}^{p} \leqq \eta\|u\|_{B_{0}}^{p}+c_{\eta} \sum_{\iota \in J_{\eta}}|u|_{\iota}^{p}, \tag{2}
\end{equation*}
$$

where $\mathscr{F}(I)$ is the set of all finite subsets of $I$. Supposing the contrary, we get $\eta>0$ such that $\forall J \in \mathscr{F}(I) \forall c \in R \quad \exists u_{J_{c}} \in B_{0}:\left\|u_{J c}\right\|_{B}^{p} \geqq \eta\left\|u_{J_{c}}\right\|_{B_{0}}^{p}+c \sum_{(\epsilon J}\left|u_{J c}\right|_{i}^{p}$. Putting $w_{J_{c}}=u_{J c}\| \| u_{J c} \|_{B_{0}}$, we get:

$$
\begin{equation*}
\left\|w_{J c}\right\|_{B}^{p} \geqq \eta+c \sum_{l \in J}\left|w_{J c}\right|_{l}^{p}, \tag{3}
\end{equation*}
$$

and also $\left\|w_{J C}\right\|_{B} \leqq C$, where $C=\sup _{u \neq 0}\|u\|_{B}\| \| u \|_{B_{0}}$ represents the norm of the imbedding operator $B_{0} \rightarrow B$. Hence $\sum_{\lfloor\in J}\left|w_{J c}\right|_{i}^{p} \leqq C^{p} / c$, and thus also $\left|w_{J_{c}}\right|_{\iota} \leqq$ $\leqq C c^{-1 / p}$ whenever $\iota \in J$. Thus $\lim _{c \rightarrow+\infty, J \in \mathscr{F}(I)}\left|w_{J c}\right|_{\iota}=0$ for every $\iota \in I$. Note that $\mathscr{F}(I)$ and $\boldsymbol{R}$ are directed by the relations $\subset$ and $\leqq$, respectively, and thus we can speak actually about the net $\left.\left\{w_{J c}\right\}\right\}_{\boldsymbol{J} \in \mathscr{F}(I), c \in \boldsymbol{R}}$ and about its possible limit.

This net forms a precompact subset of $B$ because it is bounded in $B_{0}$ which is compactly imbedded into $B$. Hence there is its subnet (denote it by same indices, for simplicity) such that $w_{J_{c}} \rightarrow w$ strongly in $\bar{B}$, where $\bar{B}$ denotes the completion of $B$ (î̂ $B$ is a Banach space, then, of ccurse, $\bar{B}=B$ ). As the imbedding $B \subset B_{1}$ is continuous, each of the seminorms $|\cdot|_{\text {t }}$ is uniformly continuous on $B$, and we may extend it continuously on $\bar{B}$, denoting the extension again by $|\cdot|_{\iota}$, for simplicity. Therefore we have $\left|w_{J c}-w\right|_{\imath} \rightarrow 0$ for every $\iota \in I$. Clearly, we can write $|w|_{\iota} \leqq$ $\leqq\left|w_{J c}\right|_{\imath}+\left|w_{J c}-w\right|_{\imath}$. Passing to the limit, we get $|w|_{\imath}=0$ for every $\imath \in I$. Thus $w=0$ because the topology of $B_{1}$ has been supposed to be Hausdorff. In other words, $w_{J r} \rightarrow 0$ strongly in $B$, which contradicts (3), thus proving (2).

Without lcss of generality we may take $v=0$. Let $\varepsilon>0$. As the sequence $\left\{v_{i j}\right\}_{i \in N}$ is bounded in $L^{p}\left(0, T ; B_{0}\right)$, we can take $\eta=\varepsilon /\left(2 \cdot \sup _{i \in N}\left\|v_{i}\right\|_{L^{p}\left(0 . T ; B_{0}\right)}^{p}\right)$. Integrating (2) over $[0, T]$ we get

$$
\left\|v_{i}\right\|_{L^{p}(0, T ; B)}^{p} \leqq \frac{\varepsilon}{2}+c \sum_{\ell \in J}\left|v_{i}\right|_{p \iota}^{p}
$$

with some $c \in \boldsymbol{R}$ and $J \in \mathscr{F}(I)$ dependirg on $\varepsilon$. The proof will be completed if we show that

$$
\begin{equation*}
\lim _{i \rightarrow \infty}\left|v_{i}\right|_{p \iota}^{p}=0 \text { for all } \quad \iota \in I . \tag{4}
\end{equation*}
$$

Clearly, $\left|v_{i}\right|_{p t}^{p}=\int_{0}^{T / 2}\left|v_{i}(t)\right|_{i}^{p} \mathrm{~d} t+\int_{T / 2}^{T}\left|v_{i}(t)\right|_{i}^{p} \mathrm{~d} t$ and we may investigate only the first term, whilc the second can be treated analogously. For every $s>0$ such that $s \leqq T / 2$ and every $t \in[0, T / 2]$ we may write $v_{i}(t)=a_{i}(t)+b_{i}(t)$, where

$$
a_{i}(t)=\frac{1}{s} \int_{0}^{s} v_{i}\left(t+\tau_{j} \mathrm{~d} \tau \quad \text { and } \quad b_{i}(t)=\int_{0}^{s}\left(\frac{\tau}{s}-1\right) \frac{\mathrm{d}}{\mathrm{~d} t} v_{i}(t+\tau) \mathrm{d} \tau .\right.
$$

Hence

$$
\int_{0}^{T / 2}\left|v_{1}(t)\right|_{l}^{p} \mathrm{~d} t=2^{p-1} \int_{0}^{T / 2}\left|a_{i}(t)\right|_{l}^{p} \mathrm{~d} t+2^{p-1} \int_{0}^{T / 2}\left|b_{i}(t)\right|_{l}^{p} \mathrm{~d} t=I_{1}+I_{2}
$$

We can estimate

$$
\begin{aligned}
& I_{2} \leqq 2^{p-1} \int_{0}^{T / 2}\left(\int_{0}^{s}\left(1-\frac{\tau}{s}\right)\left|\frac{\mathrm{d}}{\mathrm{~d} t} v_{i}(t+\tau)\right|_{t} \mathrm{~d} \tau\right)^{p} \mathrm{~d} t= \\
& =2^{p-1}\left\|\left|\frac{\mathrm{~d}}{\mathrm{~d} t} v_{i}\right|_{\tau} * \psi_{s}\right\|_{L^{p}(0, T / 2)}^{p},
\end{aligned}
$$

where ,,*" denotes the convolution, i.e. $[f * g](t)=\int f(\tau) g(t-\tau) \mathrm{d} \tau$, and $\psi_{s}: \boldsymbol{R} \rightarrow$ $\rightarrow \boldsymbol{R}$ is defined by

$$
\left.\psi_{s_{.}}^{( } t\right)= \begin{cases}t / s+1 & \text { for }-s \leqq t \leqq 0 \\ 0 & \text { clsewhere }\end{cases}
$$

The collowing estimates are wall known: $\|f * g\|_{\left.L^{1} ; \boldsymbol{R}\right)} \leqq\|f\|_{\boldsymbol{L}^{1}(\boldsymbol{R})}\|g\|_{\boldsymbol{L}^{1}(\boldsymbol{R})}$ and $\|f * g\|_{L^{\infty}(\boldsymbol{R})} \leqq\|f\|_{L^{1}(\boldsymbol{R})}\|g\|_{L^{\infty}(\boldsymbol{R})}$. As $g \mapsto f * g$ is a lirec:r operator on $L^{1}(R)$, we can obtain by interpolation (using the classical Riesz-Thorin convexity theorem) the estimate

$$
\|f * g\|_{L^{p}(\boldsymbol{R})} \leqq\|f\|_{L^{1}(\boldsymbol{R})}\|g\|_{L^{p}(\boldsymbol{R})} .
$$

It yields the estimate

$$
\left\|\left|\frac{\mathrm{d}}{\mathrm{~d} t} v_{i}\right|_{t} * \psi_{s}\right\|_{L^{p}(0, T / 2)} \leqq\left\|\left|\frac{\mathrm{d}}{\mathrm{~d} t} v_{i}\right|\right\|_{i}\left\|_{L^{1}(0, T / 2+s)}\right\| \psi_{s} \|_{L^{p}(\boldsymbol{R})} .
$$

As $\left\|\psi_{s}\right\|_{L^{p}(\boldsymbol{R})} \leqq s^{1 / p}$, we get $I_{2} \leqq 2^{p-1} s\left|\mathrm{~d} v_{i} / \mathrm{d} t\right|_{1 \iota}^{p}$, and we see that $I_{2}=\mathcal{O}(s)$ for $s \rightarrow 0$ because, by the assumptions, $\left\{\mathrm{d} v_{i} / \mathrm{d} t\right\}_{i \in N}$ is bounded in $L^{1}\left(0, T ; B_{1}\right)$, hence particularly in the seminorm $|\cdot|_{1 \text { c }}$. Thus the term $I_{2}$ can be made arbitrarily small when taking $s$ small enough.

Now, let us take $s>0$ fixed and investigate the term $I_{1}$. Since $v_{i} \rightarrow 0$ weakly in $L^{p}\left(0, T, B_{0}\right)$, we can see that $a_{i}(t) \rightarrow 0$ weakly in $B_{0}$ for every $t$, hence also strongly in $B$ because the imbedding $B_{0} \subset B$ is compact. Thercfore also $\left|a_{i}(t)\right|_{i}^{p} \rightarrow 0$ because of the continuity of the imbedding $B \subset B_{1}$. Obviously, the sequence $\left\{v_{i}\right\}_{i \in N}$ is bounded in $L^{P^{\prime}} 0, T ; B_{0}$ ), hence also in $L^{1}(0, T ; B)$, and we can estimate:

$$
\left\|a_{i}(t)\right\|_{B} \leqq \frac{1}{s} \int_{0}^{s}\left\|v_{i}^{\prime}(t+\tau)\right\|_{B} \mathrm{~d} \tau \leqq \frac{1}{s}\left\|v_{i}\right\|_{L^{1}(0, T ; B)}
$$

Using again the continuity of the imbedding $B \subset B_{1}$, we see that also $\left|a_{i}(t)\right|_{i}^{p}$ is bounded (independently of $t$ and $i$ ), and we can employ the Lebesgue theorem to show the convergence of $I_{1}=2^{p-1} \int_{0}^{T / 2}\left|a_{i}(t)\right|_{i}^{p} \mathrm{~d} t$ to 0 for $i \rightarrow \infty$. Altc gether we have proved (4).

Let us consider the set $W^{p, q}\left(0, T ; B_{0}, B_{1}\right)$ from (1) endoved with the collection of the (semi)norms $v \mapsto\|v\|_{L^{p}\left(0, T ; B_{0}\right)}$ and $v \mapsto|\mathrm{~d} v / \mathrm{d} t|_{q \iota}, \iota \in I$. It clearly makes $W^{p, q}(0, T$; $B_{0}, B_{1}$ ) a locally convex space. Then the above theorem immediately offers a generalization of the Lions-Temam theorem.

Corollary. Let the assumptions of Theorem above be fulfilled and, in addition, let $B_{0}$ be reflexive, $1<p<+\infty$, and $1 \leqq q \leqq+\infty$. Then the imbedding $W^{p . q}\left(0, T ; B_{0}, B_{1}\right) \subset L^{p}(0, T ; B)$ is compact.

Proof. As $L^{p}(0, T ; B)$ is a metric space with the completion $L^{p}(0, T ; \bar{B})$ (recall that $\bar{B}$ denotes the Banach space corresponding to $B$ ), we are only to show that every sequence $\left\{v_{i}\right\}_{i \in N}$, bounded in $W^{p, q}\left(0, T ; B_{0}, B_{1}\right)$, contains a subsequence converging (strongly) in $L^{p}(0, T ; \bar{B})$. Since $B_{0}$ is reflexive and $1<p<+\infty, L^{p}\left(0, T ; B_{0}\right)$ is reflexive as well, and thus there is a subsequence $\left\{v_{i_{k}, k \in N}{ }^{\prime}\right.$ converging weakly to some $v \in L^{p}\left(0, T ; B_{0}\right)$. As the sequence $\left\{\mathrm{d} v_{i_{k}} / \mathrm{d} t\right\}_{k \in N}$ is bounded in $L^{q}\left(0, T ; B_{1}\right)$, it is bounded in $L^{1}\left(0, T ; B_{1}\right)$ as well. Thus we can use our theorem, which gives the strong convergence of $\left\{v_{i_{k}}\right\}_{k \in N}$ even in $L^{p}(0, T ; B)$, hence in $L^{p}(0, T ; \bar{B})$, too.

To outline some applications in numerical analysis we consider, as a simple model example, the nonlinear parabolic equation describing e.g. a Stefan problem in the so-called enthalpy formulation (the nctation will be standard):

$$
\frac{\partial z}{\partial t}=\Delta \beta(z) \quad \text { on } \quad \Omega \times(0, T)
$$

with an initial condition $z(\cdot, 0)=z_{0}$ and the Dirichlet boundary condition $\beta(z(x, \cdot))=0$ for $x \in \partial \Omega$, where $\partial \Omega$ is the boundary of the Lipschitz domain $\Omega$ and $\beta: \boldsymbol{R} \rightarrow \boldsymbol{R}$ is a nondecreasing continuous function. An approximate solution $z_{h} \in L^{2}\left(0, T ; V_{h}\right)$ obtained after a spatial discretization of a finite-element type ( $h>0$ denotes a mesh parameter) fulfils the identity:

$$
\begin{equation*}
\left\langle\frac{\partial}{\partial t} z_{h}, v\right\rangle=\left\langle\nabla \beta\left(z_{h}\right), \nabla v\right\rangle \tag{5}
\end{equation*}
$$

for all $v \in V_{h}$ and a.a. $t \in[0, T]$, where $V_{h}$ is a finite-dimensional subspace of the Sobolev space $H_{0}^{1}(\Omega)$, and $\langle\cdot, \cdot\rangle$ is the standard scalar product in $L^{2}(\Omega)$. Typically, $V_{h_{1}} \subset V_{h_{2}}$ for $h_{1} \geqq h_{2}>0$ and $U_{h>0} V_{h}$ is dense in $H_{0}^{1}(\Omega)$. Sometimes, e.g. if $\beta^{-1}$ is not Lipschitz, we cannot estimate the time derivative of $\beta\left(z_{h}\right)$ and we are forced to estimate the time derivative of $z_{h}$. However, we cannot estimate it directly in the norm of $L^{2}\left(0, T ; H^{-1}(\Omega)\right)$ because we cannot test (5) by general functions $v \in H_{0}^{1}(\Omega)$. Nevertheless, putting $v=v(t) \in V_{h}$ with $\|v\|_{L^{2}\left(0, T ; H^{1}(\Omega)\right)} \leqq 1$ into (5) and integrating it over the time interval $[0, T]$, we can estimate (under some additional assumptions) $\left|\int_{0}^{T}\left\langle\partial z_{h} \mid \partial t, v\right\rangle \mathrm{d} t\right| \leqq C$ with $C$ independent of $h$. This yields the estimate of $\partial z_{h} / \partial t$ for every $h \leqq h_{0}$ in the seminorm $|\cdot|_{p \iota}$ with $p=2, \iota=h_{0}$, and $|u|_{h_{0}}=$
$=\sup \left\{\langle u, v\rangle ; v \in V_{h_{0}},\|v\|_{H_{0}(\Omega)} \leqq 1\right\}$. As $\bigcup_{h>0} V_{h}$ is dense in $H_{0}^{1}(\Omega)$, the collection of the seminorms $\left\{|\cdot|_{h}\right\}_{h>0}$ generates a Hausdorff topology on $B_{1}=H^{-1}(\Omega)$, hence our theorem can be readily employed with $B_{0}=L^{2}(\Omega), B=H^{-1}(\Omega)$, and $p=q=2$.

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## Souhrn

# ZOBECNĚNÍ LIONS-TEMAMOVY VĚTY O KOMPAKTNÍM VNOŘENÍ <br> Tomáš Roubičéek 

Známá věta J. L. Lionse a R. Temama o kompaktním vnoření prostoru $\left\{v \in L^{p}\left(0, T ; B_{0}\right)\right.$; $\left.\mathrm{d} v / \mathrm{d} t \in L^{q}\left(0, T ; B_{1}\right)\right\}$ do $L^{p}(0, T ; B)$ je zobecněna pro prípad, kdy $B_{0}$ je reflexivní Banachův prostor, vnořený kompaktně do normovaného lineárního prostoru $B$, jenž je spojitě vnořen do Hausdorffova lokálně konvexního prostoru $B_{1}$, a $1<p<+\infty, 1 \leqq q \leqq+\infty$. Je naznačeno užití takového zobecnění v numerické analýze.

## Резюме

ОБОБЩЕНИЕ ТЕОРЕМЫ ЛИОНСА-ТЕМАМА О КОМПАКТНОМ ВЛОЖЕНИИ

## TomÁš Roubíček

Известная теорема Ж. Л. Лионса и Р. Темана о компактном вложении пространства $\left\{\nu \in L^{p}\left(0, T ; B_{0}\right) ; \mathrm{d} v / \mathrm{d} t \in L^{q}\left(0, T ; B_{1}\right)\right\}$ в $L^{p}(0, T ; B)$ обобщается для случая, когда $B_{0}$ рефлексивное банахово пространство, вложеное компактно в нормированное линейное пространство $B$, котороз вложено непргрывно в одделимое локально выпуклое пространство $B_{1}$, и $1<p<$ $<+\infty, 1 \leqq q \leqq+\infty$. Указывается применение таково обобщения в вычислительном анализе.

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