Bohdan Zelinka Equivalences between isomorphism classes on infinite graphs

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# EQUIVALENCES BETWEEN ISOMORPHISM CLASSES ON INFINITE GRAPHS

#### BOHDAN ZELINKA, Liberec

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Summary. The paper studies some equivalence relations between isomorphism classes of countable graphs which correspond in a certain sense to various distances between isomorphism classes of finite graphs.

*Keywords*: distance between graphs, isomorphism class graphs, tree, edge rotation, equivalence relation

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Various distances between isomorphism classes of graphs were defined. An isomorphism class of graphs is the class of all graphs which are isomorphic to a given graph. For the sake of brevity we may speak about distances between graphs instead of distances between isomorphism classes of graphs; in this case we must have in mind that two graphs whose distance is zero need not be identical, but they are isomorphic.

Let  $G_1$ ,  $G_2$  be two finite graphs with the same number *n* of vertices. The distance  $\delta(G_1, G_2)$  is equal to *n* minus the maximum number of vertices of a graph which is isomorphic simultaneously to an induced subgraph of  $G_1$  and to an induced subgraph of  $G_2$  [4].

Now let  $G_1$ ,  $G_2$  be arbitrary two finite graphs. The edge distance  $\delta_B(G_1, G_2)$ , introduced by V. Baláž, J. Koča, M. Kvasnička and M. Sekanina [1], is defined so that

 $\delta_E(G_1, G_2) = |E_1| + |E_2| - |E_{12}| + ||v_1| - |v_2||,$ 

where  $V_1$ ,  $V_2$  are the vertex sets of  $G_1$ ,  $G_2$  and  $E_1$ ,  $E_2$  are their edge sets, the symbol  $E_{12}$  denotes the edge set of a graph which is isomorphic simultaneously to a subgraph

of  $G_1$  and to a subgraph of  $G_2$  and has the maximum number of edges among all graphs with this property.

Let  $T_1, T_2$  be two finite trees with the same number *n* of vertices. The tree distance  $\delta_T(T_1, T_2)$  is equal to *n* minus the maximum number of vertices of a tree which is isomorphic simultaneously to a subtree of  $T_1$  and to a subtree of  $T_2$  [5].

Now we shall define the edge rotation and the edge shift. Let x, y, z be three vertices of an undirected graph G such that x is adjacent to y and not to z. To perform an edge rotation of the edge xy to the position xz means to delete the edge xy from G and to add the edge xz to it. If, moreover, y and z are adjacent in G, such an edge rotation is called an edge shift of the edge xy to the position xz along the edge yz.

Let  $G_1$ ,  $G_2$  be two finite graphs with the same number of vertices and the same number of edges. The edge-rotation distance  $\delta_R(G_1, G_2)$  is the minimum number of edge rotations which are necessary for transforming the graph  $G_1$  and  $G_2$  into a graph isomorphic to  $G_2$ . If, moreover, both  $G_1$  are connected, then the edge-shift distance  $\delta_S(G_1, G_2)$  is the minimum number of edge shifts which are necessary for transforming the graph  $G_1$  into a graph isomorphic to  $G_2$ . The edge-rotation distance was introduced by G. Chartrand, F. Saba and H.-B. Zou in [2], the edge-shift distance by M. Johnson in [3].

All these distances were defined and studied for finite graphs. Here we will introduce some equivalence relations between isomorphism classes of infinite graphs which correspond in a certain sense to the above mentioned distances. We will limit our considerations to countable graphs, i. e. graphs in which the cardinality of the vertex set is  $\aleph_0$ . For the sake of simplicity again we will speak about equivalences between graphs instead of equivalences between isomorphism classes of graphs. Obviously, if two graphs belong to the same isomorphism class, then they are equivalent in each of the described equivalence relations.

Thus we consider countable undirected graphs without loops and multiple edges. If G is a graph, then V(G) denotes its vertex set and E(G) its edge set.

First we shall define the relation  $\varepsilon$ . For two countable graphs  $G_1$ ,  $G_2$  we have  $(G_1, G_2) \in \varepsilon$  if and only if there exists an induced subgraph  $G'_1$  of  $G_1$  and an induced subgraph  $G'_2$  of  $G_2$  such that  $G'_1 \cong G'_2$  and the sets  $V(G_1) - V(G'_1)$ ,  $V(G_2) - V(G'_2)$  are finite.

Now let us define the relation  $\varepsilon_E$ . For two countable graphs  $G_1$ ,  $G_2$  we have  $(G_1, G_2) \in \varepsilon_E$  if and only if there exists a subgraph  $G'_1$  of  $G_1$  and a subgraph  $G'_2$  of  $G_2$  such that  $G'_1 \cong G'_2$  and the set  $E(G_1) - E(G'_1)$ ,  $E(G_2) - E(G'_2)$  are finite.

The next relation is  $\varepsilon_R$ . If  $G_1$ ,  $G_2$  are countable graphs, then  $(G_1, G_2) \in \varepsilon_R$  if and only if  $G_1$  can be transformed by a finite number of edge rotations into a graph isomorphic to  $G_2$ . Finally, let  $T_1, T_2$  be two countable trees. We have  $(T_1, T_2) \in \varepsilon_T$  if and only if there exists a subtree  $T'_1$  of  $T_1$  and a subtree  $T'_2$  of  $T_2$  such that  $T'_1 \cong T'_2$  and the sets  $V(T_1) - V(T'_1), V(T_2) - V(t'_2)$  are finite.

Evidently, the following assertion holds.

**Theorem 1.** The relation  $\varepsilon$ ,  $\varepsilon_E$ ,  $\varepsilon_R$  are equivalences on the set of all isomorphism classes of countable graphs, the relation  $\varepsilon_T$  is an equivalence on the set of all isomorphism classes of countable trees.

We can call  $\varepsilon$  the subgraph equivalence,  $\varepsilon_E$  the edge equivalence,  $\varepsilon_R$  the edgerotation equivalence,  $\varepsilon_T$  the tree equivalence.

**Theorem 2.** Let  $G_1, G_2$  be two countable graphs without infinite sets of isolated vertices, and let  $(G_1, G_2) \in \varepsilon_E$ . Then  $(G_1, G_2) \in \varepsilon$ .

Proof. Let  $G'_1$ ,  $G'_2$  be the graphs described in the definition of  $\varepsilon_E$ . Let  $V_1$  be the set of all end vertices of edges from the set  $E(G_1) - E(G'_1)$  which belong to  $V(G'_1)$ . Similarly, let  $V_2$  be the set of all end vertices of edges from  $E(G_2) - E(G'_2)$  which belong to  $V(G'_2)$ . The sets  $V_1$ ,  $V_2$  are evidently finite. Let  $\varphi$  be an isomorphic mapping of  $G'_1$  onto  $G'_2$ . Let  $G''_1$  be the subgraph of  $G'_1$  induced by the set  $V(G'_1) - (V_1 \cup \varphi^{-1}(V_2))$ , let  $G''_2$  be the subgraph of  $G'_2$  induced by the set  $V(G'_2) - (V_2 \cup \varphi(V_1))$ . Evidently, the restriction of  $\varphi$  onto  $V(G''_1)$  maps  $G''_1$  isomorphically onto  $G''_2$  and therefore  $G''_1 \cong G''_2$ . The subgraph of  $G_1$  induced by the set  $V(G_1) - V(G'_1)$  has a finite edge set (a subset of  $E(G_1) - E(G'_1)$ ), and therefore a finite number of non-isolated vertices. As we have assumed that  $G_1$  does not contain an infinite set of isolated vertices, the set  $V(G_1) - V(G'_1)$  is finite. The set  $V(G_1) - V(G''_1)$  is the union of three finite sets  $V(G_1) - V(G'_1)$ ,  $V_1$ ,  $\varphi^{-1}(V_2)$  and thus it is finite. Analogously,  $V(G_2) - V(G''_2)$  is finite. Hence  $(G_1, G_2) \in \varepsilon$ .

R e m a r k 1. There exist countable graphs  $G_1, G_2$  without infinite sets of isolated vertices such that  $(G_1, G_2) \in \varepsilon$  and  $(G_1, G_2) \notin \varepsilon_E$ .

For  $G_2$  we may take an arbitrary locally finite countable graph without an infinite set of isolated vertices; the graph obtained from  $G_2$  by adding a new vertex v and joining it by edges with all vertices of  $G_2$  will be  $G_1$ . Evidently  $(G_1, G_2) \in \varepsilon$ . Now let  $G'_1$  be a subgraph of  $G_1$  such that  $E(G_1) - E(G'_1)$  is finite. The vertex v is incident in  $G_1$  with infinitely many edges; as only a finite number of them is in  $E(G_1) - E(G'_1)$ , the vertex v has the infinite degree also in  $G'_1$ . The graph  $G'_1$  is not locally finite and cannot be isomorphic to any subgraph of the locally finite graph  $G_2$ . This implies  $(G_1, G_2) \notin \varepsilon_E$ .

The following assertion is evident.

**Theorem 3.** Let  $G_1$ ,  $G_2$  be two locally finite countable graphs such that  $(G_1, G_2) \in \varepsilon$ . Then  $(G_1, G_2) \in \varepsilon_E$ .

Now we turn to trees.

**Theorem 4.** Let  $T_1, T_2$  be two countable trees such that  $(T_1, T_2) \in \varepsilon_T$ . Then  $(T_1, T_2) \in \varepsilon_E$ .

**Proof.** Let  $T'_1, T'_2$  be the trees used in the definition of  $\varepsilon_T$ . The set  $V(T_1) - V(T'_1)$  is finite. Consider the set  $E(T_1) - E(T'_1)$ . No edge of this set may join two vertices of  $T'_1$ ; otherwise there would be a circuit in  $T_1$  and  $T_1$  would not be a tree. For the same reason each vertex of  $V(T_1) - V(T'_1)$  may be adjacent at most to one vertex of  $T'_1$ . The set  $E(T_1) - E(T'_1)$  consists of the edge set of the subgraph of  $G_1$  induced by  $V(T_1) - V(T'_1)$  and of all edges joining a vertex of  $V(T_1) - V(T'_1)$  with a vertex of  $T'_1$ . The former set is the edge of a graph with a finite vertex set, therefore it is finite. The latter set has a cardinality not exceeding the cardinality of  $V(T_1) - V(T'_1)$ , therefore it is also finite. Hence  $E(T_1) - E(T'_1)$  is finite and  $(T_1, T_2) \in \varepsilon_E$ .

Remark 2. There exist countable trees  $T_1$ ,  $T_2$  such that  $(T_1, T_2) \in \varepsilon_E$  and  $(T_1, T_2) \notin \varepsilon_T$ .

Let  $C_1$ ,  $C_2$  be two vertex-disjoint two-way infinite paths. Choose a vertex  $u_1$  of  $C_1$  and a vertex  $u_2$  of  $C_2$ . Add a new vertex v and join it by edges with  $u_1$  and  $u_2$ ; the tree thus obtained will be denoted by  $T_1$ . If instead of v we take two new vertices  $w_1$ ,  $w_2$  and new edges  $u_1w_1$ ,  $w_1w_2$ ,  $u_2w_2$ , we obtain a tree  $T_2$ . Evidently  $(T_1, T_2) \in \varepsilon_E$ . Evidently, every proper subtree  $T'_1$  of  $T_1$  has the property that there exists a one-way infinite path in  $T_1$  which is disjoint with  $T'_1$ , and thus  $T_1$  is in the relation  $\varepsilon_T$  only with itself. The same holds for  $T_2$ . Hence  $(T_1, T_2) \notin \varepsilon_T$ .

Now we shall treat edge rotations. The following assertion is evident.

**Theorem 5.** Let  $G_1, G_2$  be two countable graphs, let  $(G_1, G_2) \in \varepsilon_R$ . Then  $(G_1, G_2) \in \varepsilon_E$ .

Note that at each edge rotation the number of vertices of odd (finite) degrees in the graph either increases by two, or decreases by two, or remains the same. The same holds also for the number of vertices of even degrees. This implies the following assertion.

**Theorem 6.** Let  $G_1$ ,  $G_2$  be two locally finite countable graphs such that  $(G_1, G_2) \in \varepsilon_R$ . Then the numbers of vertices of odd degrees in  $G_1$  and  $G_2$  are

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either both infinite, or both finite and congruent modulo 2, and the same assertion holds for the numbers of vertices of even degrees.

Remark 3. There exist countable graphs  $G_1, G_2$  such that  $(G_1, G_2) \in \epsilon_T$  and  $(G_1, G_2) \notin \epsilon_R$ .

The vertex set of the graph  $G_1$  consists of the vertices  $u_i$  for all non-negative integers *i* and of the vertices  $v_i$  for all positive integers *i*. The edges of  $G_1$  are  $u_iu_{i+1}$ for all non-negative integers *i* and  $u_iv_i$  for all positive integers *i*. The graph  $G_2$  is obtained from  $G_1$  by deleting the vertex  $v_1$  and the edge  $u_1v_1$ . Both  $G_1$ ,  $G_2$  are trees and evidently  $(G_1, G_2) \in \varepsilon_T$ . All vertices of  $G_1$  have odd degrees, while  $G_2$  has exactly one vertex, namely  $u_1$ , of an even degree. According to Theorem 6 we have  $(G_1, G_2) \notin \varepsilon_R$ .

At the end we state an evident assertion on edge shifts.

**Theorem 7.** Let  $G_1, G_2$  be two connected countable graphs and let  $(G_1, G_2) \in \varepsilon_R$ . Then  $G_1$  can be transformed into a graph isomorphic to  $G_2$  by a finite number of edge shifts.

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#### Souhrn

## EKVIVALENCE MEZI TŘÍDAMI ISOMORFISMŮ

### U NEKONEČNÝCH GRAFŮ

#### BOHDAN ZELINKA

Článek se zabývá třídami ekvivalence mezi třídami isomorfismu spočetných grafů, které v jistém smyslu odpovídají různým vzdálenostem mezi třídami isomorfismu konečných grafů.

Author's address: 461 17 Liberec 1, Sokolská 8 (katedra matematiky VŠST).