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# THE GENERALIZED HOLDITCH THEOREM FOR THE HOMOTHETIC MOTIONS ON THE PLANAR KINEMATICS 

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Abstract. W. Blaschke and H. R. Müller [4, p. 142] have given the following theorem as a generalization of the classic Holditch Theorem: Let $E / E^{\prime}$ be a 1-parameter closed planar Euclidean motion with the rotation number $\nu$ and the period $T$. Under the motion $E / E^{\prime}$, let two points $A=(0,0), B=(a+b, 0) \in E$ trace the curves $k_{A}, k_{B} \subset E^{\prime}$ and let $F_{A}, F_{B}$ be their orbit areas, respectively. If $F_{X}$ is the orbit area of the orbit curve $k$ of the point $X=(a, 0)$ which is collinear with points $A$ and $B$ then

$$
F_{X}=\frac{\left[a F_{B}+b F_{A}\right]}{a+b}-\pi \nu a b .
$$

In this paper, under the 1-parameter closed planar homothetic motion with the homothetic scale $h=h(t)$, the generalization given above by W. Blaschke and H. R. Müller is expressed and

$$
F_{X}=\frac{\left[a F_{B}+b F_{A}\right]}{a+b}-h^{2}\left(t_{0}\right) \pi \nu a b,
$$

is obtained, where $\exists t_{0} \in[0, T]$.
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MSC 2000: 53A17

## 1. Introduction

Let $E$ and $E^{\prime}$ be moving and fixed Euclidean planes and $\left\{O ; \mathbf{e}_{\mathbf{1}}, \mathbf{e}_{\mathbf{2}}\right\}$ and $\left\{O^{\prime} ; \mathbf{e}_{\mathbf{1}}^{\prime}, \mathbf{e}_{\mathbf{2}}^{\prime}\right\}$ be their coordinate systems, respectively. By taking $\mathbf{O O}^{\prime}=\mathbf{u}=$ $u_{1} \mathbf{e}_{\mathbf{1}}+u_{2} \mathbf{e}_{2}$ for $u_{1}, u_{2} \in \mathbb{R}$, the motion defined by the transformation

$$
\begin{equation*}
\mathbf{x}^{\prime}=h \mathbf{x}-\mathbf{u} \tag{1.1}
\end{equation*}
$$

is called 1-parameter planar homothetic motion and denoted by $E / E^{\prime}$, where $h$ is a homothetic scale of the motion $E / E^{\prime}$ and $\mathbf{x}$ and $\mathbf{x}^{\prime}$ are the position vectors with
respect to the moving and fixed rectangular coordinate systems of a point $X \in E$, respectively. The homothetic scale $h$ and the vectors $\mathbf{x}, \mathbf{x}^{\prime}$ and $\mathbf{u}$ are continuously differentiable functions of a real parameter $t$. Furthermore, at the initial time $t=0$ the coordinate systems $\left\{O ; \mathbf{e}_{\mathbf{1}}, \mathbf{e}_{\mathbf{2}}\right\}$ and $\left\{O^{\prime} ; \mathbf{e}_{\mathbf{1}}^{\prime}, \mathbf{e}_{\mathbf{2}}^{\prime}\right\}$ are coincident. Taking $\varphi=\varphi(t)$ as the rotation angle between $\mathbf{e}_{\mathbf{1}}$ and $\mathbf{e}_{\mathbf{1}}^{\prime}$, the equation

$$
\begin{align*}
& \mathbf{e}_{\mathbf{1}}=\cos \varphi \mathbf{e}_{\mathbf{1}}^{\prime}+\sin \varphi \mathbf{e}_{\mathbf{2}}^{\prime}  \tag{1.2}\\
& \mathbf{e}_{\mathbf{2}}=-\sin \varphi \mathbf{e}_{\mathbf{1}}^{\prime}+\cos \varphi \mathbf{e}_{\mathbf{2}}^{\prime}
\end{align*}
$$

can be written. If

$$
\begin{align*}
u_{j}(t+T) & =u_{j}(t), \quad j=1,2  \tag{1.3}\\
\varphi(t+T) & =\varphi(t)+2 \pi \nu, \quad \forall t \in[0, T]
\end{align*}
$$

then the motion $E / E^{\prime}$ is called 1-parameter closed planar homothetic motion with the period $T>0$ and the rotation number $\nu \in Z$. To avoid the cases of the pure translation and the pure rotation we assume that

$$
\dot{\varphi}(t)=\frac{\mathrm{d} \varphi}{\mathrm{~d} t} \neq 0
$$

Under the 1-parameter closed planar homothetic motions, if $P=\left(p_{1}, p_{2}\right)$ is the pole point of the motion at the time $t$ then the sliding velocity of a fixed point $X=\left(x_{1}, x_{2}\right) \in E$ with respect to $E^{\prime}$ is

$$
\begin{equation*}
\mathrm{d} \mathbf{x}^{\prime}=\left\{\left(x_{1}-p_{1}\right) \mathrm{d} h-\left(x_{2}-p_{2}\right) h \mathrm{~d} \varphi\right\} \mathbf{e}_{\mathbf{1}}+\left\{\left(x_{1}-p_{1}\right) h \mathrm{~d} \varphi+\left(x_{2}-p_{2}\right) \mathrm{d} h\right\} \mathbf{e}_{\mathbf{2}} . \tag{1.4}
\end{equation*}
$$

Furthermore, the orbit area $F_{X}$ of the point $X$, given by Gauss area formula [3], is

$$
\begin{equation*}
F_{X}=\frac{1}{2} \oint\left(x_{1}^{\prime} \mathrm{d} x_{2}^{\prime}-x_{2}^{\prime} \mathrm{d} x_{1}^{\prime}\right) \tag{1.5}
\end{equation*}
$$

where the integration is taken along the closed orbit curve of $X$. Then, we obtain

$$
\begin{align*}
2 F_{X}= & \left(x_{1}^{2}+x_{2}^{2}\right) \int_{0}^{T} h^{2}(t) \mathrm{d} \varphi(t)-2 x_{1} \int_{0}^{T} p_{1}(t) h^{2}(t) \mathrm{d} \varphi(t)  \tag{1.6}\\
& -2 x_{2} \int_{0}^{T} p_{2}(t) h^{2}(t) \mathrm{d} \varphi(t)+\int_{0}^{T}\left\{u_{1}(t) p_{1}(t) h(t) \mathrm{d} \varphi(t)\right. \\
& \left.+u_{2}(t) p_{2}(t) h(t) \mathrm{d} \varphi(t)+u_{1}(t) p_{2}(t) \mathrm{d} h(t)-u_{2}(t) p_{1}(t) \mathrm{d} h(t)\right\} \\
& +x_{1} \int_{0}^{T}\left\{u_{2}(t) \mathrm{d} h(t)-2 p_{2}(t) h(t) \mathrm{d} h(t)+h(t) \mathrm{d} u_{2}(t)\right\} \\
& +x_{2} \int_{0}^{T}\left\{-u_{1}(t) \mathrm{d} h(t)+2 p_{1}(t) h(t) \mathrm{d} h(t)-h(t) \mathrm{d} u_{1}(t)\right\},
\end{align*}
$$

Moreover, using the mean value theorem of integral-calculus for the closed interval $0 \leqslant t \leqslant T$, there exists at least a point $t_{0} \in[0, T]$ such that

$$
\begin{equation*}
\int_{0}^{T} h^{2}(t) \mathrm{d} \varphi(t)=\int_{0}^{T} h^{2}(t) \dot{\varphi}(t) \mathrm{d} t=2 h^{2}\left(t_{0}\right) \pi \nu \tag{1.7}
\end{equation*}
$$

By taking $\nu \neq 0$, the Steiner point $S=\left(s_{1}, s_{2}\right)$ for the closed planar homothetic motion can be written as

$$
\begin{equation*}
s_{j}=\frac{\int_{0}^{T} h^{2}(t) p_{j}(t) \mathrm{d} \varphi(t)}{\int_{0}^{T} h^{2}(t) \mathrm{d} \varphi(t)}, \quad j=1,2 . \tag{1.8}
\end{equation*}
$$

Thus, from Eqs. (1.6), (1.7) and (1.8) we get

$$
\begin{equation*}
F_{X}=F_{0}+h^{2}\left(t_{0}\right) \pi \nu\left(x_{1}^{2}+x_{2}^{2}-2 x_{1} s_{1}-2 x_{2} s_{2}\right)+\mu_{1} x_{1}+\mu_{2} x_{2}, \tag{1.9}
\end{equation*}
$$

where $F_{0}$ is the orbit area of the origin of the moving coordinate system and

$$
\begin{align*}
& \mu_{1}=\frac{1}{2} \int_{0}^{T}\left\{-2 h(t) p_{2}(t) \mathrm{d} h(t)+h(t) \mathrm{d} u_{2}(t)+u_{2}(t) \mathrm{d} h(t)\right\},  \tag{1.10}\\
& \mu_{2}=\frac{1}{2} \int_{0}^{T}\left\{2 h(t) p_{1}(t) \mathrm{d} h(t)-h(t) \mathrm{d} u_{1}(t)-u_{1}(t) \mathrm{d} h(t)\right\} .
\end{align*}
$$

Eq. (1.9) is called the Steiner area formula for the 1-parameter closed planar homothetic motion.

## 2. The generalized Holditch theorem for the closed planar HOMOTHETIC MOTIONS

Theorem 1. Let $E / E^{\prime}$ be 1-parameter planar homothetic motion with the rotation number $\nu$. Let $F_{A}, F_{B}$ denote the orbit areas of the orbit curves $k_{A}, k_{B} \subset E^{\prime}$ of the points $A=(0,0), B=(a+b, 0) \in E$, respectively. If $F_{X}$ is the orbit area of the orbit curve $k$ of the point $X=(a, 0)$, which is collinear with points $A$ and $B$, then

$$
\begin{equation*}
F_{X}=\frac{\left[a F_{B}+b F_{A}\right]}{a+b}-h^{2}\left(t_{0}\right) \pi \nu a b \tag{2.1}
\end{equation*}
$$

Proof. From Eq. (1.9), for the orbit areas $F_{A}, F_{B}$ and $F_{X}$, we obtain

$$
\begin{align*}
& F_{A}=F_{0}  \tag{2.2}\\
& F_{B}=F_{0}+h^{2}\left(t_{0}\right) \pi \nu\left[(a+b)^{2}-2 s_{1}(a+b)\right]+\mu_{1}(a+b) \tag{2.3}
\end{align*}
$$

and

$$
\begin{equation*}
F_{X}=F_{0}+h^{2}\left(t_{0}\right) \pi \nu\left(a^{2}-2 s_{1} a\right)+\mu_{1} a \tag{2.4}
\end{equation*}
$$

From Eqs. (2.2) and (2.3), we have

$$
\begin{equation*}
\frac{a F_{B}+b F_{A}}{a+b}-h^{2}\left(t_{0}\right) \pi \nu a b=F_{0}+h^{2}\left(t_{0}\right) \pi \nu\left(a^{2}-2 s_{1} a\right)+\mu_{1} a \tag{2.5}
\end{equation*}
$$

Then, from Eqs. (2.4) and (2.5), we get Eq. (2.1).

Special case 1. In the case of the homothetic scale $h \equiv 1$, we get

$$
\begin{equation*}
F_{X}=\frac{\left[a F_{B}+b F_{A}\right]}{a+b}-\pi \nu a b, \tag{2.6}
\end{equation*}
$$

which was given by [4].

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