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# SOME NEW CONVERGENCE RESULTS IN FINITE ELEMENT THEORIES FOR ELLIPTIC PROBLEMS 

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THE LINEAR PROBLEM

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    We consider the following variational problem: Find u E W such
that
\[
\begin{equation*}
a(u, v)=L(v) \equiv L^{\delta l}(v)+L^{\Gamma}(v) \quad \forall v \in V \tag{1}
\end{equation*}
\]
```

where

$$
\begin{aligned}
& a(v, w)=\iint_{\Omega} k_{i j} v r_{i} w,{ }_{j} d x, \\
& L^{\Omega}(v)=\iint_{\Omega} v f d x, \quad L^{\Gamma}(v)=\iint_{2} v q d s
\end{aligned}
$$

$$
\begin{equation*}
\mathrm{V}=\left\{\mathrm{v} \in \mathrm{H}^{1}(\Omega): \mathrm{v}=0 \text { on } \Gamma_{1} ; \text { mes }_{1} \Gamma_{1}>0\right\}, \mathrm{W}=\mathrm{z}+\mathrm{V} \tag{4}
\end{equation*}
$$

$\Omega$ is a bounded domain in $E_{2}$ with a boundary $\Gamma=\Gamma_{1} \cup \Gamma_{2}\left(\Gamma_{1} \cap \Gamma_{2}=\right.$ $=\phi) ; \mathrm{z} \in \mathrm{H}^{1}(\Omega), \mathrm{z}=\overline{\mathrm{u}}$ on $\Gamma_{1}, \overline{\mathrm{u}} \in \mathrm{L}_{2}\left(\Gamma_{1}\right)$ is a given function. In (2) and in what follows the summation convention over repeated subscripts is adopted and $v r_{i \sim}=\partial v / \partial x_{i}$. The functions $k_{i j}=k_{i j}(x)$ are bounded and measurable in $\Omega \supset \bar{\Omega}$ and satisfy

$$
\begin{equation*}
k_{i j}(x) \xi_{i} \xi_{j} \geq C \xi_{i} \xi_{i} \quad \forall x \in \widetilde{\Omega} \supset_{r} \bar{\Omega} \quad \forall \xi_{i}, \xi_{j} \in E_{1}, \tag{5}
\end{equation*}
$$

where $\mathrm{C}>0$, and $\mathrm{f} \in \mathrm{L}_{2}(\Omega)$, $q \in \mathrm{~L}_{2}\left(\Gamma_{2}\right)$. Assumption (5) and Friedrichs' inequality imply that the form $a(v, w)$ is $V$-elliptic. Thus, according to the Lax-Milaram lemma, problem (1) has just one solution.

Problem (1) is approximated by the problem: Find $u_{h} \in W_{h}$ such
that

$$
\begin{equation*}
a_{h}\left(u_{h}, v\right)=L_{h}(v) \equiv L_{h}^{\Omega}(v)+L_{h}^{\Gamma}(v) \quad \forall v \in v_{h} \tag{6}
\end{equation*}
$$

where $V_{h}$ is a finite element approximation of $V$ and $W_{h}=z_{h}+V_{h}, z_{h}$ being a finite element approximation of $z$. The forms $a_{h}(v, w), L_{h}(v)$ approximate the forms $\mathrm{a}(\mathrm{v}, \mathrm{w}), \mathrm{L}(\mathrm{v})$ in the following way: The sets $\Omega$ and $\Gamma_{2}$ appearing in (2), (3) are substituted by $\Omega_{h}$ and $\Gamma_{h 2}$ and the
obtained forms $\tilde{a_{h}}(v, w), \tilde{L}_{h}(v)$ are then computed numerically.
In the Ciarlet's and Raviart's theory and its modifications (see [1],[2],[6]) the solution $u$ of (1) is assumed to be sufficiently smooth, $u \in H^{n+1}(s i)(n \geq 1)$, and the maximum rate of convergence is proved:

$$
\begin{equation*}
\left\|\tilde{u}-u_{h}\right\|_{1, \Omega_{h}} \leq \mathrm{Ch}^{n} \tag{7}
\end{equation*}
$$

where $\tilde{u}$ is the Calderon's extension of $u$ into $H^{n+1}\left(E_{2}\right)$.
The problem of convergence of $u_{h}$ to $\tilde{u}$ (when $u \in H^{l}(\Omega)$ only) was solved recently in [8]. In this section we present outlines of considerations of [8].

Theorem 1. Let the boundary $\Gamma$ of the domain $\Omega$ be piecewise of class $\overline{C^{n+1}}$. Let $\Gamma_{h}$ approximate $r$ piecewise by arcs of degree $n$. Let $k_{i j}, f \in W_{\infty}^{(n)}(\tilde{\Omega})$ and let the quadrature formula used on the standard triangle $T_{0}$ for calculation of $a_{h}(v, w)$ and $L_{h}^{\Omega}(v)$ be of degree of precision $2 n-2$. Let $q \in C^{n}(\bar{U})$, where $U$ is a domain containing $\Gamma_{2}$, and let the quadrature formula used on $[0,1]$ for calculation of $L_{h}^{\Gamma}(v)$ be of degree of precision $2 \mathrm{n}-1$. Let $\overline{\mathrm{u}}$ be so smooth that there exists a function $z \in H^{2}(\Omega)$ such that $z=\bar{u}$ on $\Gamma_{1}$. Then

$$
\begin{equation*}
\left\|\tilde{u}-u_{h}\right\|_{1, \Omega_{h}} \rightarrow 0 \text { if } h \rightarrow 0 . \tag{8}
\end{equation*}
$$

Proof. The assumptions concerning $\Gamma$ and $a_{h}(v, w)$ imply, according to [2] and [7], that the forms $a_{h}(v, w)$ are uniformly $V_{h}$-elliptic. Thus we have similarly as in [1], [2]:

$$
\begin{align*}
& \left\|\tilde{u}-u_{h}\right\|_{1, \Omega_{h}} \leq c\left\{\sup _{w \in V_{h}} \frac{\left|L_{h}(w)-\tilde{a}_{h}(\tilde{u}, w)\right|}{\mathbb{T}_{w} \|_{1, \Omega_{h}}}+\right. \\
& \left.\quad+\inf _{v \in W_{h}}\left[\|\tilde{u}-v\|_{1, \Omega_{h}}+\sup _{w \in V_{h}} \frac{\left|\tilde{a}_{h}(v, w)-a_{h}(v, w)\right|}{\|w\|_{1, \Omega_{h}}}\right]\right\} . \tag{9}
\end{align*}
$$

For simplicity we prove Theorem $l$ only in the case $\Gamma_{1}=\Gamma$, $\bar{u}=0$ and $n=1$, i.e. $\Omega_{h}$ has a polygonal boundary and we use linear triangular finite elements. As $\Gamma$ is piecewise of class $C^{2}$ each boundary triangle satisfies (for sufficiently small h) one of the following possibilities:

$$
\begin{equation*}
\text { a) } T \subseteq T_{i d}, \quad \text { b) } \quad T_{i d} \subset T \text {, } \tag{10}
\end{equation*}
$$

where $T_{i d}$ is the ideal boundary triangle (see [9]) whose approximation is $T$.

In order to estimate the first term on the right-hand side of (9) let us define a function $\widehat{w} \in V$ associated with $w \in V_{h}$ in the following
way: $\hat{w}\left(P_{i}\right)=w\left(P_{i}\right)$ at the vertices $P_{i}$ of the triangles of the triangulation $T_{h}$ of the domain $\Omega_{h}$; the function $\hat{w}$ is continuous on $\bar{\Omega}$, linear on each interior triangle of $T_{h}$, equal to zero on $\mathrm{T}_{\mathrm{id}}-\mathrm{T}$ and linear on $T$ in the case (10) and, finallv, equal to zlámal's ideal "linear" interpolate of $w$ on $T_{i d}$ in the case (: b) (see | 9|). Thus we can write, accordina to (1):

$$
\begin{equation*}
L_{h}(w)-\tilde{a}_{h}(\tilde{u}, w)=L_{h}(w)-L(\hat{w})+a(u, \hat{w})-\bar{a}_{h}\left(\tilde{u}_{w} w\right) . \tag{11}
\end{equation*}
$$

We have

$$
L(\hat{w})=\iint_{\Omega} f \hat{w} d x=\iint_{\Omega_{h}} f w d x+\int_{b}\left\{\int_{i d}(\hat{w}-w) f d x-\int_{T-T_{i d}} w f d x\right\}
$$

where the sum is taken over all boundary triangles (1,b). Expressing similarly $a(u, \hat{w})-\tilde{a}_{h}(\tilde{u}, w)$ we obtain from (11):

$$
\begin{align*}
& \left|L_{h}(w)-\tilde{a}_{h}(\tilde{u}, w)\right| \leq\left|\tilde{L}_{h}^{\Omega /}(w)-L_{h}^{\Omega /}(w)\right|+ \\
& +\sum_{b}\left|\int_{T_{i d}}\left\{(w-\hat{w}) f+k_{i j} u,_{i}(\hat{w}-w),{ }_{j}\right\} d x\right|+ \\
& +\left.\sum_{b}\right|_{T-T} \iint_{i d}\left(w f-k_{i j} \tilde{u}^{\prime}{ }_{i}{ }^{w,}{ }_{j}\right) d x \mid . \tag{1;}
\end{align*}
$$

According to [2, Theorem 4.1.5],

$$
\begin{equation*}
\left\|\tilde{L}_{h}^{\Omega}(w)-L_{h}^{\Omega}(w) \mid \leq C h\right\| w \|_{1, \Omega_{h}} \tag{13}
\end{equation*}
$$

Denoting the first sum in (12) briefly by $S_{1}$ we have, according to the Cauchy inequality and the boundedness of $k_{i j}$ :

$$
\left|S_{l}\right| \leq\left(\|f\|_{0, \Omega}+C\|u\|_{1, \Omega}\right)\left\{\sum_{b}\|\hat{w}-w\|_{1, T_{i d}}^{2}\right\}^{1 / 2}
$$

The definition of $\widehat{w}$ and the proof of $[9$, Theorem 2] imply

$$
\left\|_{\mathrm{w}}-\hat{\mathrm{w}}\right\|_{1, \mathrm{~T}_{\mathrm{id}}} \leq C h\left\|_{\mathrm{w}}\right\|_{2, \mathrm{~T}_{i d}} \leq C h\left\|_{\mathrm{w}}\right\|_{1, \mathrm{~T}}
$$

because $w$ is linear on $T$ and (10b) holds. Thus

$$
\begin{aligned}
& \left|S_{l}\right| \leq C h\left\|_{\mathrm{w}}\right\|_{I, \Omega_{h}} \\
& \text { As mes }\left(T-T_{i d}\right)=0\left(h^{3}\right) \text { we have } \\
& \sum_{\mathrm{b}}\left\|_{\mathrm{w}}\right\|_{0, T-T_{i d}}^{2} \leq \mathrm{Ch}^{3} \sum_{\mathrm{b}} \max \mathrm{w}^{2} .
\end{aligned}
$$

Further, similarly as $[7,(39)]$ we can prove

$$
\left\|_{w}\right\|_{0, \Omega_{h}}^{2} \geq \mathrm{Ch}^{2} \sum_{\mathrm{T} \in T_{h}} \sum_{i=1}^{3}\left[w\left(\mathrm{P}_{\mathrm{T}}^{\mathrm{i}}\right)\right]^{2}
$$

where $P_{T}^{i}(i=1,2,3)$ are the vertices of $T$. Using these results and the fact that $w_{i}$ are constants on each $T \in T_{h}$ we can easily find for the second sum $S_{2}$ on the right-hand side of (12):

$$
\begin{align*}
& \left|S_{2}\right| .\|w\|_{i, \Omega_{h}}^{-1} \leq C\left\{\sum_{b}\|w\|_{0, T-T}^{2}\left\|_{w}\right\|_{0, \Omega_{h}}^{-2}+\right. \tag{15}
\end{align*}
$$

According to (12) - (15), the first term on the right-hand side of (a) is $O\left(h^{l / 2}\right)$.

As to the second term on the right-hand side of (9) we can find a set $\left\{\mathrm{v}_{\mathrm{h}}\right\}$, where $\mathrm{v}_{\mathrm{h}} \in \mathrm{W}_{\mathrm{h}}$, such that

$$
\begin{equation*}
\left\|\tilde{u}-v_{h}\right\|_{1, \Omega_{h}} \rightarrow 0 \text { if } h \rightarrow 0 \tag{16}
\end{equation*}
$$

The following proof of (16) holds also in the case mes ${ }_{1} \Gamma_{1}<\operatorname{mes}_{1} \Gamma$ : The set $G=C^{\infty}(\bar{\Omega}) \cap \mathrm{V}$ is dense in $V$ (see [3]). Thus for every $\varepsilon>0$ we can find $v_{\varepsilon} \in G$ such that $\left\|_{u}-v_{\varepsilon}\right\|_{1, \Omega}<\varepsilon$. Let $\tilde{v}_{\varepsilon}$ and $\tilde{v}_{\varepsilon}^{*}$ be the Calderon's extensions of $v_{\varepsilon}$ into $H^{\ell}\left(E_{2}^{\varepsilon}\right)$ and $H^{2}\left(E_{2}\right),{ }^{\varepsilon}$ respectively. We have

$$
\begin{align*}
\| \tilde{u} & -I_{h} v_{\varepsilon}\left\|_{1, \Omega_{h}} \leq\right\| \tilde{u}-\tilde{v}_{\varepsilon} \|_{1, \Omega_{h}}+ \\
& +\left\|\tilde{v}_{\varepsilon}-\tilde{v}_{\varepsilon}^{*}\right\|_{1, \Omega_{h}}-\Omega_{2}+\left\|\tilde{v}_{\varepsilon}^{*}-I_{h} v_{\varepsilon}\right\|_{1, \Omega_{h}} \tag{17}
\end{align*}
$$

where $I_{h} v_{\varepsilon}$ is the interpolate of $v_{\varepsilon}$ in $W_{h}$, i.e. the piecewise linear function which has the same function values at the vertices of $T \in T_{h}$ as the function $v_{\varepsilon}$. The properties of the Calderon's extensions, the absolute continuity of the Lebesque integral and the finite element interpolation theorem imply that for all $h \leq h_{0}(\varepsilon)$ the right-hand side of (17) is bounded by $K \varepsilon$, where $K$ does not depend on $\varepsilon$. As $I_{h} V_{\varepsilon} \in V_{h}=W_{h}$ relation (17) implies (16).

The set $\left\{\mathrm{v}_{\mathrm{h}}\right\}$ appearing in (16) is bounded. Thus, according to [2, Theorem 4.l.4], the third term on the right-hand side of (9) is $0(h)$. This finishes the proof in our simple case. The general case $\Gamma_{1} \subset \Gamma$, $\mathrm{n} \geq 1$ is considered in [8].

## SOME NONLINEAR PROBLEMS

Let the form $a(u, v)$ appearing in (1) be now nonlinear in $u$, linear in $v$, strongly monotone and Lipschitz continuous and let $a(0, v)=0$ for all $v \in H^{l}(\Omega)$. In addition, let the forms $a_{h}(v, w)$ be uniformly strongly monotone and uniformly Lipschitz continuous in $X_{h}$ (the finite element approximations of $H^{1}(\Omega)$ ), i.e. let

$$
a_{h}(v, v-w)-a_{h}(w, v-w) \geq c|v-w|_{l, \Omega_{h}}^{2},
$$

$$
\begin{aligned}
\left|a_{h}(v, z)-a_{h}(w, z)\right| \leq & k\|v-w\| 1,\left\|_{h} l,\right\|_{h} \\
& r v, w, z \in X_{h} \overbrace{i}^{1})
\end{aligned}
$$

where the positive constants $C, K$ do not depend on $v, w, z$ and h. Finally, let the forms $\bar{a}_{h}(v, w)$ be uniformly Linschitz continuous. Under these assumptions the abstract error estimate has again the form (9) (see [5]).

A typical form $a(u, v)$ satisfying all assumptions presented in this section is given bv relation ( ${ }^{\prime}$ ) with

$$
\begin{equation*}
k_{i j}=b\left(x,(\nabla v)^{2}\right) s_{i j} \tag{18}
\end{equation*}
$$

where $\delta_{i j}$ is the Kronecker delta and where the function $b(x, y)$ has the following properties (see [4|):
a) The functions $b(x, \eta), \partial b(x, \eta) / \partial x_{i}, \partial b(x, n) /$ in are continuous in $\tilde{\Omega} \times[0, \infty)$, where $\tilde{\Omega} \supset \bar{\Omega}$.
b) There exist constants $c_{1}>0, c_{2}>0$ such that
$c_{1} \leq b \leq c_{2},\left|\partial b / \partial x_{i}\right| \leq c_{2}, \quad 0 \leq j b / \partial \eta \leq c_{2}$ in $\tilde{s} \times \quad[(1, \infty)$,
$|\xi|(\partial b / \partial \eta)\left(x, \xi^{2}\right), \quad \xi^{2}(\partial b / \partial \eta)\left(x, \xi^{2}\right) \leq c_{2} \quad \forall x \in \tilde{\gamma}, \quad \forall \varepsilon \in E_{1}$.
The functions (18) with properties a), b) appear in many physical and technical applications.

Now we generalize the result introduced in Theorem 1 :

Theorem 2. Let the form $a(u, v)$ appearing in (1) be defined by (2) and (18) and let the function $b(x, \eta)$ have properties $a)$, b). Let the assumptions of Theorem 1 be satisfied with $n=1$. Then the solutions $u$ and $u_{h}$ of problems (1) and (6) exist and are unique and relation (8) holds. In addition, if $u \in H^{2}(\Omega)$ then the rate of convergence is given by (7), where $n=1$.

Proof. As $n=1$ we consider only linear triangular elements. We again restrict ourselves to the case $\Gamma_{1}=\Gamma, \bar{u}=0$. The existence and uniqueness of $u$ and $u_{h}$ is proved in [4]. The first property $b$ ) allows us to repeat (11) - (15). Thus the first term on the right--hand side of (9) is $0\left(h^{1 / 2}\right.$ ). Also relation (16) remains unchanged, only the analysis of the third term on the right-hand side of (9) is different: As $\nabla v=$ const. on $T \in T_{h}$ for all $v \in V_{h}=W_{h}$ we can write

$$
\begin{aligned}
& \left|a_{h}\left(v_{h}, w\right)-\tilde{a}_{h}\left(v_{h}, w\right)\right| \leq \sum_{T \in T_{h}} \mid \operatorname{mes}(T) b\left(P_{T},\left.g_{h}\right|_{T}\right)- \\
& \quad-\iint_{T} b\left(x, g_{h}\right) d x|\cdot|\left(\left.\left.\nabla v_{h}\right|_{T} \cdot \nabla W\right|_{T}\right) \mid
\end{aligned}
$$

where $v_{h}$ are the functions from (16) and $g_{h}=\left(\nabla v_{h}\right)^{2}$. We used one--point integration formula with the centre of gravity $P_{T}$ of $T \in T_{h}$. Using the properties of the function $b(x, \eta)$ we see, according to [2, Theorem 4.1.51, that the absolute value of the difference on the right-hand side is bounded by Ch mes(T). Thus the right-hand side of the last inequality is bounded by $C h\|w\|\left\|_{1}\right\|_{h}$ and relation (8) is valid. The error estimate in the case $u \in H^{2}(\Omega)$ is derived in [5] where also more general forms $a(v, w)$ are considered.

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