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## NUMERICAL ASPECTS OF COMPUTATION OF PERIODIC AND QUASIPERIODIC SOLUTIONS IN SYSTEMS OF PARTIAL DIFFERENTIAL EQUATIONS

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## 1. Introduction

In this paper we shall deal with some numerical aspects of computation of periodic and quasiperiodic solutions of the following system of two parabolic equations

$$
\begin{align*}
& \frac{\partial x}{\partial t}=\frac{D_{x}}{L^{2}} \frac{\partial^{2} x}{\partial z^{2}}+x^{2} y-(B+1) x+A \\
& \frac{\partial y}{\partial t}=\frac{D_{y}}{L^{2}} \frac{\partial^{2} y}{\partial z^{2}}+B x-x^{2} y . \tag{1}
\end{align*}
$$

These equations describe behaviour of a reaction - diffusion system (in spatially one-dimensional medium) with Brusselator reaction scheme [9.g.1]. Here $L$ is a characteristic dimension of the system, $z \in[0,1]$ is dimensionless spatial coordinate, $x, y$ concentrations and $t$ is time. For simplicity chocse boundary conditions of the Dirichlet type

$$
\begin{equation*}
x(t, 0)=x(t, 1)=\bar{x} \quad y(t, 0)=y(t, 1)=\bar{y}, \tag{2}
\end{equation*}
$$

where $\bar{x}$ and $\bar{y}$ satisfy $\bar{x}^{2} \bar{y}-(B+1) \bar{x}+A=0$ and $B \bar{x}-\bar{x}^{2} \bar{y}=0$, cf. Eq. (1). We consider $L$ as a bifurcation parameter, the values of remaining parameters are chosen: $D_{x}=0.008, D_{y}=0.004, A=2, B=5.45$. In our case are thus $\bar{x}=A=2$ and $\bar{y}=B / A=2.725$.

In the preceding paper [2] we presented the method of continuation of periodic solutions of Eq. (1), i.e. the way how to construct so called solution diagram of periodic solutions. The point of formation of a quasiperiodic solution was determined on the basis of an analysis of periodic solutions in dependence on $L$. The development of this quasiperiodic solution and its desintegration into a chaotic attractor via a cascade of the torus doubling was presented in the paper [3].

## 2. Computation of periodic solutions

The computation of periodic solutions for the system (1) is based on the transformation of the system of PDE's into a large set of ODE's by means of the method of lines (semidiscretization). We shall consider two discretizations of spatial derivatives here. Let us denote the approximations ( $z_{1}=i h, h=1 / N$ )

$$
\begin{equation*}
x_{i}(t) \sim x\left(t, z_{i}\right), y_{i}(t) \sim y\left(t, z_{i}\right), i=0,1, \ldots N . \tag{3}
\end{equation*}
$$

From the boundary conditions (2) it follows

$$
\begin{equation*}
x_{0}(t)=\bar{x}, x_{N}(t)=\bar{x}, y_{0}(t)=\bar{y}, y_{N}(t)=\bar{y} . \tag{4}
\end{equation*}
$$

The most simple discretization consists in a replacement of spatial derivatives by the folloving three-point finite difference formula ( $u$ is $x$ or $y$ ):

$$
\begin{equation*}
\left.\frac{\partial^{2} u}{\partial z^{2}}\right|_{\left(t, z_{i}\right)} \frac{u_{i-1}-2 u_{i}+u_{i+1}}{h^{2}}, \quad i=1,2 \ldots, N-1 \tag{5}
\end{equation*}
$$

After inserting (5) into Eqs. (1) we obtain a system of ODE's ( $i=1,2, \ldots, N-1$ ):

$$
\begin{align*}
& \frac{d x_{1}}{d t}=\frac{D_{x}}{L^{2} h^{2}}\left(x_{i-1}-2 x_{i}+x_{i+1}\right)+x_{i}^{2} y_{i}-(B+1) x_{i}+A \\
& \frac{d y_{i}}{d t}=\frac{D_{y}}{L^{2} h^{2}}\left(y_{i-1}-2 y_{i}+y_{i+1}\right)+B x_{i}-x_{i}^{2} y_{i} \tag{6}
\end{align*}
$$

Second discretization uses five-point finite-difference formulas ( $u$ is $x$ or $y$ ):

$$
\left.\frac{\partial^{2} u}{\partial z^{2}}\right|_{\left(t, z_{i}\right)} \frac{-2 u_{i-2}+32 u_{i-1}-60 u_{i}+32 u_{i+1}-2 u_{i+2}}{24 h^{2}}, \quad i=2,3, \ldots, N-2
$$

$$
\begin{align*}
& \left.\frac{\partial^{2} u}{\partial z^{2}}\right|_{\left(t, z_{1}\right)} \sim \frac{22 u_{0}-40 u_{1}+12 u_{2}+8 u_{3}-2 u_{4}}{24 h^{2}}  \tag{7}\\
& \left.\frac{\partial^{2} u}{\partial z^{2}}\right|_{\left(t, z_{N-1}\right)} \underset{\sim}{ } \frac{-2 u_{N-4}+8 u_{N-3}+12 u_{N-2}-40 u_{N-1}+22 u_{N}}{24 h^{2}}
\end{align*}
$$

After inserting (7) into Eqs (1) we obtain again a system of 2(N-1) ODE's analogously as in the preceding case, cf. Eq.(6).

Comparison of accuracy of resulting periodic solutions obtained for different $N$ indicates Table 1. There the values of the period $T$ and absolute values of two leading characteristic multipliers $\lambda_{2}$ and $\lambda_{3}$ (eigenvalues of the monodromy matrix, $\lambda_{1}=1$ always for an autonomous system) are presented. Let us note that the periodic solution has in the chosen semidiscretization alltogether 2(N-1) characteristic multipliers. We can conclude from the Table that the results for (6) and $N=40$ are comparable with results for (7) and $N=20$ and that the approximation (6) gives also for $N=20$ satisfactory results.

Table 1: Period $T$ and $\left|\lambda_{2,3}\right|$ in dependence on $N$, $L=1.338533$ (cf. the branch with tori bifurcation point $T_{1}$ in [3]). Periodic solution 1 s stable, $\lambda_{2}$ and $\lambda_{3}$ are mutually complex conjugate.

|  |  | approximation (6) |  | approximation (7) |  |
| ---: | :--- | :--- | :--- | :--- | :---: |
| N | T | $\left\|\lambda_{2,3}\right\|$ | T | $\left\|\lambda_{2,3}\right\|$ |  |
| 5 | divergence |  | divergence |  |  |
| 10 | 3.412599 | 0.931 | 3.417790 | 0.849 |  |
| 20 | 3.412613 | 0.901 | 3.412665 | 0.890 |  |
| 40 | 3.412666 | 0.892 |  |  |  |

3. Computation of quasiperiodic solutions

The point of invariant torus bifurcation (denoted as $\mathrm{T}_{1}$ in [3]) has been detected on the branch considered for $L \doteq 1.37$. At this point a branch of stable quasiperiodic solutions bifurcates. We studied behaviour of trajectories in the neighbourhood of the invariant torus by using dynamic simulation of the system (6) for $N=20$. The visualization of the trajectory will be made by using a trajectory of

the Poincare map, i.e. in our case the map from a hyperplane $x_{6}=2$ into the same hyperplane. A projection of this trajectory into the plane $x_{10}-y_{10}(i . e . x(t, 0.5)-y(t, 0.5))$ is depicted in Figs 1,2 and 3. In all three cases the same initial condition was chosen as the corresponding periodic solution perturbed on third decimal place. The points of the trajectory of Poincarè map No. 500-1500, 1500-2500 and 3000-4000 are depicted in Fig. 1,2 and 3, respectively. It can be concluded from the figures that the attractivity of the invariant torus is low. Fig. 3 presents already the "intersection" of the torus with the hyperplane $x_{6}=2$. The low attractivity of the torus is probably caused by a weakly repelling periodic solution in the neighbourhood. This periodic solution has only two multipliers outside the unit circle and in absolute value near to unity, cf. Table 2.

Table 2: Leading 14 multipliers for unstable periodic solution for $\mathrm{L}=1.405, \mathrm{~T}=3.405269$. Approximation (6), $N=20$. Remaining multipliers $\lambda_{15}, \ldots, \lambda_{38}$ are close to zero, $\lambda_{1}=1$.

| $\left\|\lambda_{2,3}\right\|$ | 1.1017 | $\left\|\lambda_{8,9}\right\|$ | 0.1361 |
| :--- | :--- | :--- | :--- |
| $\left\|\lambda_{4}\right\|$ | 0.7797 | $\left\|\lambda_{10}\right\|$ | 0.0569 |
| $\left\|\lambda_{5,6}\right\|$ | 0.3919 | $\left\|\lambda_{11}, 12\right\|$ | 0.0401 |
| $\left\|\lambda_{7}\right\|$ | 0.1869 | $\left\|\lambda_{13,14}\right\|$ | 0.0127 |

## Literature

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