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# TOPOLOGICAL METHODS OF INVESTIGATION OF OPERATOR EQUATIONS 

 AND NONLINEAR BOUNDARY VALUE PROBLEMSI. V. Skrypnik<br>Doneck, USSR

Introduction

One of the fundamental methods of qualitative study of nonlinear elliptic and parabolic boundary value problems, which facilitates the study of solvability, branching, bifurcation of solutions, problems of eigenfunctions, is the topological method, based on the theory of degree of nonlinear mappings in Banach spaces. The origin of this method goes back to the remarkable paper by Leray-Schauder [1], where the authors, using Brouwer's theory of degree of finite-dimensional mappings, introduced the degree of a map $I-F: X \rightarrow X$, where $I$ is the identity, $F$ a totally continuous mapping of a Banach space $X$ (or its part) into itself. In the same paper the authors gave a method of reducing the quasilinear Dirichlet problem to the operator equation $u-\mathrm{Fu}=0$ with a totally continuous operator $\mathbf{F}$. Applying the theory of degree of a map the authors found that in order to prove an existence theorem it is sufficient to establish an apriori estimate of solutions of a certain parametric family of boundary value problems.

On the other hand, the limited possibilities of application of the Leray-Schauder degree to more general boundary value problems were soon recognized. The application of these methods to the Dirichlet problem for the general nonlinear equation is cumbersome and requires additional restrictions [2]. When studying the second fundamental problem for quasilinear elliptic equations - the Neumann problem - it was found [3] that by applying the Leray-Schauder scheme the differential problem reduces to the equation $u-\Phi u=0$ with a continuous but not compact operator $\Phi$. Consequently, applying the topological methods in this case we have either to change the way in which we reduce the problem, or to reduce the problem to other classes of operators.

In this way there appeared a demand for topological methods of investigation of more general classes of operator equations in Banach spaces, namely, of such classes to which it is possible to reduce differential boundary value problems for general nonlinear differential elliptic and parabolic equations with general nonlinear boundary value conditions.

The necessity of developing a theory of degree of more extensive classes of mappings also arose from the problem of existence of generalized solutions of boundary value problems for divergent equations. An essential feature of the study of generalized solvability is the sufficiency of considerably weaker apriori estimates of solutions estimates involving the energy norm. At the beginning of the sixties, Browder, Minty and others (see survey papers [4] - [7]) discovered new classes of operators - the monotone operators - whose essential property is that they preserve the weak convergence under Galerkin's approximations. Problems of finding generalized solutions for divergent elliptic and parabolic equations naturally lead to equations with similar operators. The application of the methods of monotone operators led to a considerable progress in the theory of nonlinear boundary value problems.

The results of various authors concerning solvability of equations with monotone operators (in the coercive case) (see [4] - [7]) were entailed by the establishment of the theory of degree of various classes of monotone operators and their generalizations, given simultaneously and independently by the author [8] and Browder, Petryshyn [9]. A survey of these and other related results is found in [10]. Browder and Petryshyn introduced a multivalued degree of $A$ - proper mappings. The non-uniqueness of the degree (the degree of a mapping is a subset of the set $Z \cup\{-\infty\} \cup\{+\infty\}$ ) as well as the fact that this degree fails to possess all the properties of the degree of fi-nite-dimensional mappings, make its application to differential problems difficult.

The author introduced a single-valued degree of mappings satisfying a certain condition ( $\alpha_{0}$ ). The degree introduced exhibits all the properties of the degree of finite-dimensional mappings. Even the analogue of Hopf's theorem asserting that the degree is the unique homotopic invariant of the class of mappings considered, is valid.

The above mentioned degree of a mapping satisfying the condition $\left(\alpha_{0}\right)$ was in the beginning employed in the study of boundary value problems for divergent quasilinear equations [11]. Further, the author demonstrated $[10,12,13]$ that this degree can serve as the basis for developing topological methods of investigation of boundary value problems for general essentially nonlinear elliptic and parabolic equations with general nonlinear boundary value conditions. Explicit constructive methods of reducing boundary value problems to the corresponding classes of operator equations in Sobolev spaces were given.

When verifying the condition ( $\alpha_{0}$ ) for the resulting operators, apriori $L_{p}$-estimates of elliptic and parabolic linear problems are essentially involved.

In the case of the general nonlinear Dirichlet problem it is possible to give simpler methods of reducing the original problems to operator equations with operators satisfying the condition ( $\alpha_{0}$ ). These simplifications are based on coercive estimates for pairs of linear elliptic operators, established in $[14,15]$ under weak assumptions.

The present text of the lectures is mainly based on the author's works. In Chap. 1 we give the definition of the degree of a mapping satisfying the condition ( $\alpha_{0}$ ) or one of its analogues, and we establish various properties of the degree. In Chap. 2 we show the methods of reducing the general nonlinear elliptic boundary value problems to the operator equations discussed in Chap. 1. Coercive estimates for pairs of linear differential operators are given in Chap. 3, together with a simpler method of reducing the general nonlinear Dirichlet problem to an operator equation. In Chap. 4 a number of examples of application of the topological methods developed above are given: the Dirichlet problem for the Monge-Ampere equation and a model nonlinear Neumann problem are discussed and an existence theorem for the general Dirichlet problem in a thin layer is established. The ways how to introduce topological characteristics for general nonlinear parabolic equations are shown in Chap. 5.

Let us point out that the methods developed enable us to investigate the behaviour of solutions of families of problems, in particular, branching, bifurcation, eigenvalue problems (see [10], [11]). However, these problems are not dealt with in the present paper.

## 1. The degree of generalized monotone mappings

1. Throughout this section $X$ is a real separable reflexive Banach space, $x^{*}$ its adjoint. We denote the strong and the weak convergence by $\rightarrow$ and $\rightarrow$, respectively; it will be clear from the context in which space the convergence is considered. Given elements $u \in X$ and $h \in X^{*}$ we denote by $\langle h, u>$ the value of the functional $h$ at the element $u$.

We will consider operators $A$, defined on a set $D_{A} \subset X$, with values in $X^{*}$. An operator $A$ will be called demicontinuous if it maps strongly convergent sequences into weakly convergent ones.

DEFINITION 1. We shall say that an operator $A$ satisfies the condition $\left(\alpha_{0}\right)$ if for any sequence $u_{n} \in D_{A}$, the relations $u_{n} \rightharpoonup u_{0}$, $A u_{n} \longrightarrow 0$ and

$$
\begin{equation*}
\lim _{n \rightarrow \infty}<A u_{n}, u_{n}-u_{0}>\leqq 0 \tag{1}
\end{equation*}
$$

imply the strong convergence of $u_{n}$ to $u_{0}$.
The set of operators satisfying the condition $\left(\alpha_{0}\right)$ is a certain extension of the set of operators satisfying the condition (S) + [16]. We say that an operator A satisfies the condition (S) ${ }_{+}$if for every sequence $u_{n} \in D_{A}$ that satisfies (1), the weak convergence $u_{n} \rightharpoonup u_{0}$ implies $u_{n} \rightarrow u_{0}$.

In this chapter we shall define the degree of a mapping $A$ satisfying the condition ( $\alpha_{0}$ ).
2. Operators satisfying the condition ( $S)_{+}$, and hence also ( $\alpha_{0}$ ), appear in problems of finding generalized solutions of divergent elliptic equations, under some rather weak assumptions (see [10]). We restrict ourselves to a single simple example of the Neumann problem for the quasilinear elliptic second order equation. This case illustrates in this section the general operator scheme. It is interesting that the application of the Leray-Schauder degree theory meets with considerable difficulties in this case [3].

Let $\Omega$ be a bounded domain in an n-dimensional Euclidean space $\mathrm{R}^{\mathrm{n}}$, with a boundary $\partial \Omega$ of a class $\mathrm{C}^{2, \lambda}, 0<\lambda<1$. Consider the boundary value problem

$$
\begin{equation*}
L(u)=\sum_{i=1}^{n} \frac{d}{d x_{i}} a_{i}\left(x, u, \frac{\partial u}{\partial x}\right)-a_{0}\left(x, u, \frac{\partial u}{\partial x}\right)=0, \quad x \in \Omega, \tag{2}
\end{equation*}
$$

$$
\begin{equation*}
B(u)=\sum_{i=1}^{n} a_{i}\left(x, u, \frac{\partial u}{\partial x}\right) \cos \left(v, x_{i}\right)+b(x, u)=0, \quad x \in \partial \Omega, \tag{3}
\end{equation*}
$$

where $v$ is the vector of the outer normal to $\partial \Omega$ at the point $\mathbf{x}$.
We assume that the following conditions are fulfilled with some positive constants $C_{1}, C_{2}$ and $p>1$ :
(i) the functions $a_{i}(x, u, \xi), a_{0}(x, u, \xi), b(y, u)$ are defined, continuous for $x \in \bar{\Omega}, y \in \partial \Omega, u \in R^{1}, \xi=\left(\xi_{1}, \ldots, \xi_{n}\right) \in R^{n}$ and satisfy the inequalities

$$
\begin{equation*}
\left|a_{i}(x, u, \xi)\right| \leqq c_{1}(1+|u|+|\xi|)^{p-1}, \quad i=0,1, \ldots, n, \tag{4}
\end{equation*}
$$

$$
\begin{equation*}
|b(x, u)| \leq c_{1}(1+|u|)^{p-1} \tag{5}
\end{equation*}
$$

(ii) for arbitrary $x \in \bar{\Omega}, u \in R^{1}, \xi, \eta \in \mathbb{R}^{n}$ the following inequalities hold:

$$
\begin{aligned}
& \sum_{i=1}^{n} a_{i}(x, u, \xi) \xi_{i} \geq c_{2}|\xi|^{p}-c_{1}|u|^{p}-c_{1}, \\
& \sum_{i=1}^{n}\left[a_{i}(x, u, \xi)-a_{i}(x, u, n)\right]\left(\xi_{i}-n_{i}\right)>0 \text { for } \xi \neq n .
\end{aligned}
$$

REMARK. The conditions (4), (5) can be further weakened (see [10]).
If the conditions (i), (ii) are fulfilled, it is possible to introduce the generalized solution of the problem (2), (3) belonging to $W_{p}^{1}(\Omega)$, which will be simply called a solution. A function $u \in W_{p}^{1}(\Omega)$ is called a solution of the problem (2), (3), if an arbitrary function $\phi \in W_{p}^{1}(\Omega)$ satisfies the integral identity

$$
\begin{equation*}
\int_{\Omega}\left[\sum_{i=1}^{n} a_{i}\left(x, u, \frac{\partial u}{\partial x}\right) \frac{\partial \phi}{\partial x}+a_{0}\left(x, u, \frac{\partial u}{\partial x}\right) \phi\right] d x+\int_{\partial \Omega} b(x, u) \phi d S=0 \tag{6}
\end{equation*}
$$

We associate the problem (2), (3) with an operator $A: W_{p}^{1}(\Omega) \rightarrow$ $\rightarrow\left(W_{p}^{1}(\Omega)\right)^{*}$, which is defined by the identity

$$
\begin{equation*}
\langle A u, \phi\rangle=\int_{\Omega}\left[\sum_{i=1}^{n} a_{i}\left(x, u, \frac{\partial u}{\partial x}\right) \frac{\partial \phi}{\partial x_{i}}+a_{0}\left(x, u, \frac{\partial u}{\partial x}\right) \phi\right] d x+\int_{\partial \Omega} b(x, u) \phi d s . \tag{7}
\end{equation*}
$$

It immediately follows from the given definitions that the solutions of the problem (2), (3) coincide with those of the operator equation $A u=0$.

LEMMA 1. The operator A : $W_{p}^{1}(\Omega) \rightarrow\left(W_{p}^{1}(\Omega)\right)^{*}$ defined by (7) satisfies the condition (S) provided (i), (ii) are fulfilled.

Proof. Let a sequence $u_{n} \in W_{p}^{1}(\Omega)$ satisfy $u_{n} \rightarrow u_{0}$,
$\lim _{n \rightarrow \infty}\left\langle A u_{n}, u_{n}-u_{0}\right\rangle \leq 0$. By virtue of compactness of the imbedding of $W_{p}^{1}(\Omega)$ in $L_{p}(\Omega)$ and $L_{p}(\partial \Omega)$ we obtain

$$
\begin{aligned}
& \lim _{n \rightarrow \infty}\left[\int_{\Omega} a_{0}\left(x, u_{n}, \frac{\partial u_{n}}{\partial x}\right)\left(u_{n}-u_{0}\right) d x+\int_{\partial \Omega} b\left(x, u_{n}\right)\left(u_{n}-u_{0}\right) d s\right]=0, \\
& \lim _{n \rightarrow \infty} \int_{\Omega} \sum_{i=1}^{n} a_{i}\left(x, u_{n}, \frac{\partial u_{0}}{\partial x}\right) \frac{\partial\left(u_{n}-u_{0}\right)}{\partial x_{i}} d x=0 .
\end{aligned}
$$

Consequently, the sequence $u_{n}$ satisfies the inequality

$$
\lim _{n \rightarrow \infty} \int_{\Omega} \sum_{i=1}^{n}\left[a_{i}\left(x, u_{n}, \frac{\partial u_{n}}{\partial x}\right)-a_{i}\left(x, u_{n}, \frac{\partial u_{0}}{\partial x}\right)\right] \frac{\partial}{\partial x_{i}}\left(u_{n}-u_{0}\right) d x \leqq 0
$$

The condition (ii) implies that $\frac{\partial u_{n}}{\partial x_{i}}$ converges to $\frac{\partial u_{0}}{\partial x_{i}}$ in measure, and yields the estimate

$$
\int_{E}\left|\frac{\partial u_{n}}{\partial x}\right|^{p} d x \leqq \alpha_{n}+c_{0} \int_{E}\left(\left|\frac{\partial u_{0}}{\partial x}\right|^{p}+\left|u_{n}\right|^{p}+1\right) d x
$$

with a constant $C_{0}$ independent of $n$ and with $\alpha_{n} \rightarrow 0$, which is valid for any measurable set $E \subset \Omega$. This yields the strong convergence of $u_{n}$ to $u_{0}$ in $W_{p}^{1}(\Omega)$.
3. Let us go back to the case of a general abstract operator $A: D_{A} \rightarrow x^{*}$, which was introduced in Sec. 1 .

Let $\left\{v_{i}\right\}, i=1,2, \ldots$ be an arbitrary complete system of the space $x$ and assume that the elements $v_{1}, \ldots, v_{N}$ are linearly independent for every $N$. Denote by $F_{n}$ the linear hull of the elements $v_{1}, \ldots, v_{n}$.

Let us assume that the interior of the set $D_{A}$ is nonempty and let $D$ be an arbitrary bounded open subset of the space $X$, such that $\bar{D} \subset D_{A}$. We will define the degree $\operatorname{Deg}(A, D, 0)$ of the mapping $A$ of the set $\bar{D}$ with respect to the point 0 of the space $x^{*}$.

Let us notice that in the author's papers $[10,11]$ the term of degree of a mapping is replaced by the term "rotation of a vector field on the boundary of a set". These two notions are equivalent.

For every $n=1,2, \ldots$ we shall introduce finite-dimensional approximations $A_{n}$ of the map $A, A_{n}: D_{n}=\bar{D} \cap F_{n} \rightarrow F_{n}$, by

$$
\begin{equation*}
A_{n}(u)=\sum_{i=1}^{n}\left\langle A u, v_{i}\right\rangle v_{i} . \tag{8}
\end{equation*}
$$

LEMMA 2. Let $\mathrm{A}: \mathrm{D}_{\mathrm{A}} \rightarrow \mathrm{x}^{*}$ be a demicontinuous bounded operator satisfying the condition $\left(\alpha_{0}\right), \bar{D} \subset D_{A}$ and $A u \neq 0$ for $u \in \partial \Omega$. Then there is a number $N_{1}$ such that Brouwer's degree $\operatorname{deg}\left(A_{n}, D_{n}, 0\right)$ is defined provided $\mathrm{n} \geqq \mathrm{N}_{1}$.

Proof. It is sufficient to verify that for large $n$,
$A_{n} u \neq 0$ for $u \in \partial D_{n}$. This will be proved by contradiction. Let there exist a sequence $u_{k} \in \partial D_{n_{k}}$ such that $n_{k} \rightarrow \infty, A_{n_{k}} u_{k}=0$. Evidently $u_{k} \in \partial D$. We may assume $u_{k} \rightarrow u_{0}$ and show that then $u_{k} \rightarrow u_{0}$. It is easily seen that $A u_{k} \rightarrow 0$. We choose a sequence $W_{k} \in F_{n_{k}}$ such that $W_{k} \rightarrow u_{0}$. Then

$$
\left\langle A u_{k}, u_{k}-u_{0}\right\rangle=\left\langle A u_{k}, W_{k}-u_{0}\right\rangle
$$

and the right hand side converges to zero with $k \rightarrow \infty$. In virtue of the condition $\left(\alpha_{0}\right)$ this implies the strong convergence of $u_{k}$ to $u_{0}$ and we obtain $A u_{0}=0, u_{0} \in \partial D$, which contradicts the assumptions of the lemma.

Further, we shall establish the stabilization of Brouwer's degree of the mappings $A_{n}$.

LEMMA 3. The limit $\lim _{\mathrm{n} \rightarrow \infty} \operatorname{deg}\left(\mathrm{A}_{\mathrm{n}}, \mathrm{D}_{\mathrm{n}}, 0\right)$ exists.
proof. We have to prove the existence of such a number $N_{2}$ that

$$
\begin{equation*}
\operatorname{deg}\left(A_{n}, D_{n}, 0\right)=\operatorname{deg}\left(A_{m}, D_{m}, 0\right) \text { for } n, m \geq N_{2} \tag{9}
\end{equation*}
$$

Let us consider an auxiliary mapping

$$
\tilde{A}_{n}(u)=\sum_{i=1}^{n-1}<A u, v_{i}>v_{i}+<n_{n}, u>v_{n}
$$

where $h_{n}$ is an arbitrary fixed element of $X^{*}$ which satisfies

$$
<h_{n}, v_{i}>=\delta_{i n}, \quad i \leqq n
$$

Here $\delta_{\text {in }}$ are the Kronecker symbols. According to the Leray-Schauder Lemma [1] we obtain

$$
\begin{equation*}
\operatorname{deg}\left(A_{n-1}, D_{n-1}, 0\right)=\operatorname{deg}\left(\tilde{A}_{n}, D_{n}, 0\right) \tag{10}
\end{equation*}
$$

for $n \geq N_{1}+1$. To prove (9) we only have to verify that for large $n$, the mappings $A_{n}$ and $A_{n}$ are homotopic on $D_{n}$. Let us consider a family of mappings $A_{n}^{(t)}: D_{n} \rightarrow F_{n}$, $t \in[0,1]^{n}$ depending on $t:$

$$
A_{n}^{(t)}(u)=\sum_{i=1}^{n-1}<A u, v_{i}>v_{i}+\left\{t<h_{n}, u>+(1-t)<A u, v_{n}>\right\} v_{n}
$$

Evidently $A_{n}^{(0)}=A_{n}, A_{n}^{(1)}=\tilde{A}_{n}$ and in virtue of the properties of Brouwer's degree, in order to establish the identity

$$
\begin{equation*}
\operatorname{deg}\left(A_{n}, D_{n}, 0\right)=\operatorname{deg}\left(\tilde{A}_{n}, D_{n}, 0\right) \tag{11}
\end{equation*}
$$

for large $n$ it suffices to verify that $A_{n}^{(t)}(u) \neq 0$ for $t \in[0,1]$, $u \in \partial D_{n}$ and $n$ sufficiently large.

On the contrary, let us assume that there are sequences $u_{k}, t_{k}$ such that

$$
\begin{equation*}
A_{n_{k}}^{\left(t_{k}\right)}\left(u_{k}\right)=0, \quad u_{k} \in \partial D_{n_{k}}, \quad t_{k} \in[0,1], n_{k} \rightarrow \infty \tag{12}
\end{equation*}
$$

We may assume $u_{k} \rightarrow u_{0}, t_{k} \rightarrow t_{0}$. Then (12) yields

$$
\begin{align*}
& \left\langle A u_{k}, v_{i}>=0,1 \leq i \leq n_{k}-1\right.  \tag{13}\\
& t_{k}<h_{n_{k}}, u_{k}>+\left(1-t_{k}\right)<A u_{k}, v_{n_{k}}>=0
\end{align*}
$$

Hence $A u_{k} \rightarrow 0$. According to Lemma $2, t_{k} \neq 0,1$ for $n_{k} \geq N_{1}+1$. We choose a sequence $W_{k} \in F_{n_{k}-1}$ so that $W_{k} \rightarrow u_{0}$. Then

$$
\begin{aligned}
\left\langle A u_{k}, u_{k}-u_{0}\right\rangle & =\left\langle A u_{k}, W_{k}-u_{0}\right\rangle+\left\langle h_{n_{k}}, u_{k}\right\rangle\left\langle A u_{k}, u_{k}\right\rangle= \\
& =\left\langle A u_{k}, W_{k}-u_{0}\right\rangle-\frac{t_{k}}{1-t_{k}}\left\langle h_{n_{k}}, u_{k}\right\rangle^{2},
\end{aligned}
$$

which in virtue of the condition ( $\alpha_{0}$ ) implies the strong convergence of the sequence $u_{k}$ to $u_{0}$. Hence $A u_{0}=0, u_{0} \in \partial D$, which contradicts the assumptions. The identities (10), (11) imply the assertion of the lemma.

Denote

$$
\begin{equation*}
D\left\{v_{i}\right\}=\lim _{n \rightarrow \infty} \operatorname{deg}\left(A_{n}, D_{n}, 0\right) \tag{14}
\end{equation*}
$$

We shall further prove that the limit $D\left\{v_{i}\right\}$ is independent of the choice of the system of elements $\left\{v_{i}\right\}$. Let $\left\{w_{i}\right\}$ be another system possessing the same properties as the system of elements $\left\{\mathrm{v}_{\mathrm{i}}\right\}$. Denote by $E_{n}$ the linear hull of the elements $w_{1}, \ldots, w_{n}$ and define the mapping

$$
A_{n}^{\prime}: D_{n}^{\prime}=\bar{D} \cap E_{n} \rightarrow E_{n}, \quad A_{n}^{\prime}(u)=\sum_{i=1}^{n}\left\langle A u, w_{i}\right\rangle w_{i} .
$$

LEMMA 4. Let the assumptions of Lemma 2 be fulfilled. Then $D\left\{v_{1}\right\}=$ $=D\left\{W_{i}\right\}=D$, where $D\left\{\mathrm{v}_{\mathrm{i}}\right\}$ is defined by (14) and $\mathrm{D}\left\{\mathrm{w}_{\mathrm{i}}\right\}$ is defined analogously.

Proof. It suffices to prove that there is $N_{3}$ such that (15)

$$
\operatorname{deg}\left(A_{n}, D_{n}, 0\right)=\operatorname{deg}\left(A_{n}^{\prime}, D_{n}^{\prime}, 0\right)
$$

provided $n \geq N_{3}$.
Moreover, we may assume that for any $n$ the systems $v_{1}, \ldots, v_{n}$, $w_{1}, \ldots, w_{n}$ are linearly independent. If this is not the case, we in addition construct intermediate system $\left\{g_{i}\right\}, i=1,2, \ldots$. Denote by $L_{2 n}$ the linear space spanned by the elements $v_{1}, \ldots, v_{n}, w_{1}, \ldots$ $\ldots, w_{n}$. Let $D_{2 n}^{\prime \prime}=D \cap L_{2 n}$ and

$$
A_{2 n}^{\prime \prime}(u)=\sum_{i=1}^{n}\left\{\left\langleA u, v_{i}>v_{i}+\left\langle A u, w_{i}>w_{i}\right\}, u \in D_{2 n}^{\prime \prime} .\right.\right.
$$

In order to prove (15) we only have verify that

$$
\begin{equation*}
\operatorname{deg}\left(A_{n}, D_{n}, 0\right)=\operatorname{deg}\left(A_{2 n}^{\prime}, D_{2 n}^{\prime}, 0\right) \tag{16}
\end{equation*}
$$

for large $n$, in virtue of the full symmetry of the left- and right--hand sides of (15). For every $n$ define elements $f_{i}^{(n)}, i=1, \ldots$ $\ldots, n$, belonging to $x^{*}$ and such that

$$
\begin{equation*}
\left\langle f_{i}^{(n)}, v_{j}\right\rangle=0,\left\langle f_{i}^{(n)}, w_{j}\right\rangle=\delta_{i j} \tag{17}
\end{equation*}
$$

holds for $i, j=1, \ldots, n$.
For $t \in[0,1]$ we define a parametric family of mappings $A_{2 n, t}: D_{2 n}^{\prime \prime} \rightarrow L_{2 n}$ by

$$
\left.\left.A_{2 n, t}(u)=\sum_{i=1}^{n}\left\langle A u, v_{i}\right\rangle v_{i}+\sum_{i=1}^{n}\left\{t<A u, w_{i}\right\rangle+(1-t)<f_{i}^{(n)}, u\right\rangle\right\} w_{i} .
$$

Evidently $A_{2 n, 1}=A_{2 n}^{\prime \prime}$ and for $n \geq N_{1}$,

$$
\begin{equation*}
\operatorname{deg}\left(A_{2 n, 0}, D_{2 n}^{\prime \prime}, 0\right)=\operatorname{deg}\left(A_{n}, D_{n}, 0\right) \tag{18}
\end{equation*}
$$

holds in virtue of the Leray-Schauder Lemma. To establish (16) it surfices to verify that for large $n, A_{2 n, t}(u) \neq 0$ for $t \in[0,1]$, $u \in \partial D_{2 n}^{\prime \prime}$. On the contrary, assume that there are sequences $u_{k} \in$ $\in \partial D_{2}^{\prime} \tilde{n}_{k}^{\prime}, t_{k} \in[0,1]$, such that $A_{2 n_{k}, t_{k}}\left(u_{k}\right)=0, n_{k} \rightarrow \infty$. Then

$$
\begin{align*}
& <A u_{k}, v_{i}>=0, i=1, \ldots, n_{k}, \\
& t_{k}<A u_{k}, w_{i}>+\left(1-t_{k}\right)<f_{i}^{\left(n_{k}\right)}, u_{k}>=0, i=1, \ldots, n_{k} . \tag{19}
\end{align*}
$$

We may assume that $u_{k} \rightarrow u_{0}, t_{k} \rightarrow t_{0}$. It follows from (19) that $A u_{k} \rightharpoonup 0$. Choose a sequence $\tilde{w}_{k} \in F_{n_{k}}$ such that $\tilde{w}_{k} \rightarrow u_{0}$.

Then

$$
\begin{aligned}
\left\langle A u_{k}, u_{k}-u_{0}\right\rangle & =\left\langle A u_{k}, \tilde{w}_{k}-u_{0}\right\rangle+\sum_{i=1}^{n_{k}}\left\langle f_{i}\left(n_{k}\right), u_{k}\right\rangle\left\langle A u_{k}, w_{i}\right\rangle= \\
& =\left\langle A u_{k}, \tilde{w}_{k}-u_{0}\right\rangle-\sum_{i=1}^{n_{k}}\left\langle f_{i}\left(n_{k}\right), u_{k}\right\rangle^{2} \frac{1-t_{k}}{t_{k}},
\end{aligned}
$$

for $n_{k} \geq N_{1}$. This together with the condition ( $\alpha_{0}$ ) yields the strong convergence of the sequence $u_{k}$ to $u_{0}, A u_{0}=0, u_{0} \in \partial D$, a contradiction.

Lemmas 2-4 enable us to introduce the following definition.

DEFINITION 2. The number $D$ from Lemma 4 is called the degree of the mapping $A$ of the set $\bar{D}$ with respect to the point $O \in x^{*}$ and is denoted by $\operatorname{Deg}(A, \bar{D}, 0)$.

Hence we have by definition

$$
\operatorname{Deg}(A, \bar{D}, 0)=D=D\left\{v_{i}\right\}=\lim _{n \rightarrow \infty} \operatorname{deg}\left(A_{n}, D_{n}, 0\right)
$$

4. The degree $\operatorname{Deg}(A, \bar{D}, 0)$ of a mapping introduced in Sec. 3 possesses all the properties of the degree of finite-dimensional mappings (see $[10,11]$ ). We mention only the most important of them, omitting the proofs.

DEFINITION 3. Let $D_{0}$ be an arbitrary set in the space $X$ and $A_{t}: D_{0} \rightarrow X, \quad t \in[0,1]$, a parametric family of mappings. The family $A_{t}$ is said to satisfy the condition $\left(\alpha_{0}^{(t)}\right.$ ), if for any sequences $u_{n} \in D_{0}, t_{n} \in[0,1]$, the relations $u_{n} \rightarrow u_{0}, t_{n} \rightarrow t_{0}$, $A_{t_{n}}\left(u_{n}\right) \rightharpoonup 0$ and

$$
\lim _{n \rightarrow \infty}\left\langle A_{t_{n}}\left(u_{n}\right), u_{n}-u_{0}\right\rangle \leqq 0
$$

imply the strong convergence of $u_{n}$ to $u_{0}$.
DEFINITION 4. Let $A^{\prime} A^{\prime \prime}: D_{0} \rightarrow X$ be bounded demicontinuous operators satisfying the condition $\left(\alpha_{0}\right)$, $D$ a bounded open set such that $\bar{D} \subset D_{0}$, and let $A^{\prime} u \neq 0, A^{\prime \prime} u \neq 0$ for $u \in \partial D$. The mappings $A^{\prime}$, $A^{\prime \prime}$ are called homotopic on $\bar{D}$, if there is a parametric family of mappings $A_{t}: \bar{D} \rightarrow X^{*}$ satisfying the condition $\left(\alpha_{0}^{(t)}\right.$ ) and the following conditions:
(a) $A_{t}(u) \neq 0$ for $u \in \partial D, t \in[0,1] ; \quad A_{0}=A^{\prime}, \quad A_{1}=A^{\prime \prime}$;
(b) for each $t \in[0,1]$, the operator $A_{t}$ is continuous;
(c) there is a function $\omega:[0,1] \rightarrow R^{1}, \omega(\rho) \rightarrow 0$ with $\rho \rightarrow 0$, such that $\sup _{u \in D}| | A_{t} u-A_{s} u| | \leqq \omega(|t-s|)$.

The following theorems provide a classification of mappings that satisfy the condition $\left(\alpha_{0}\right)$, in terms of the degree of a mapping. THEOREM 1. Let $\mathrm{A}^{\prime}: \overline{\mathrm{D}} \rightarrow \mathrm{X}^{*}, \mathrm{~A}^{\prime \prime}: \overline{\mathrm{D}} \rightarrow \mathrm{X}^{*}$ be two mappings that are homotopic to each other in the sense of Definition 4. Then $\operatorname{Deg}\left(A^{\prime}, \bar{D}, 0\right)=\operatorname{Deg}\left(A^{\prime \prime}, \bar{D}, 0\right)$.

THEOREM 2. Let D be a convex bounded open set in the space X and $\mathrm{A}^{\prime}: \overline{\mathrm{D}} \rightarrow \mathrm{X}^{*}$, $\mathrm{A}^{\prime \prime}: \overline{\mathrm{D}} \rightarrow \mathrm{X}^{*}$ bounded demicontinuous mappings satisfying the condition $\left(\alpha_{0}\right)$, such that $A^{\prime} u \neq 0$, $A^{\prime \prime} \dot{\prime} \neq 0$ for $u \in \partial D$ and $\operatorname{Deg}\left(\mathrm{A}^{\prime}, \overline{\mathrm{D}}, 0\right)=\operatorname{Deg}\left(\mathrm{A}^{\prime \prime}, \overline{\mathrm{D}}, 0\right)$. Then the mappings $\mathrm{A}^{\prime}, \mathrm{A}^{\prime \prime}$ are homotopic on $\overline{\mathrm{D}}$.

The application of the theory of degree of a mapping to the solvability of the operator equation

$$
\begin{equation*}
A u=0 \tag{20}
\end{equation*}
$$

is based on the following principle.

## Principle of Nonzero Rotation.

Let $A: \bar{D} \rightarrow X^{*}$ be a bounded demicontinuous operator satisfying the condition ( $\alpha_{0}$ ). A sufficient condition for the equation (20) to be solvable in $D$ is that $\operatorname{Deg}(A, \bar{D}, 0) \neq 0$.

Let us present two criteria of non-vanishing of the degree of a mapping.

THEOREM 3. Let $\mathrm{B}(0, \mathrm{r})=\{\mathrm{u} \in \mathrm{X}:\|\mathrm{u}\| \leq \mathrm{r}\}$, Let $\mathrm{A}: \mathrm{B}(0, \mathrm{r}) \rightarrow \mathrm{X}^{*}$ be a bounded demicontinuous operator satisfying the condition ( $\alpha_{0}$ ). Assume that for every $u \in \partial B(0, r)$ the inequalities

$$
\begin{equation*}
A u \neq 0, \frac{A u}{\|A u\|_{*}} \neq \frac{A(-u)}{\|A(-u)\|_{*}} \tag{21}
\end{equation*}
$$

hold. Then $\operatorname{Deg}(A, B(0, r), 0)$ is an odd number.

THEOREM 4. Let D be an arbitrary bounded domain in the space X $0 \notin \partial \mathrm{D}$ and $\mathrm{A}: \overline{\mathrm{D}} \rightarrow \mathrm{X}^{*}$ a bounded demicontinuous operator satisfying the condition $\left(\alpha_{0}\right)$. Assume that for $u \in \partial D$ the inequalities

$$
A u \neq 0, \quad\langle A u, u\rangle \geq 0
$$

hold. Then $\operatorname{Deg}(A, \bar{D}, 0)=1$ for $0 \in D, \operatorname{Deg}(A, \bar{D}, 0)=0$ for $0 \notin \bar{D}$.
Let us formulate an easy consequence of Theorem 1 and the principle of nonzero rotation.

THEOREM 5. Let D be a bounded domain in X and $\mathrm{A}_{\mathrm{t}}: \overline{\mathrm{D}} \rightarrow \mathrm{X}^{*}$ a family of operators that realize the homotopy between. $\mathrm{A}_{0}$ and $\mathrm{A}_{1}$ in the sense of Definition 4. Assume that $\operatorname{Deg}\left(A_{0}, \bar{D}, 0\right) \neq 0$. Then the equation $A_{1} u=0$ has in $D$ at least one solution.
5. In this section we present the application of the results of the previous section to the proof of solvability of the problem (2), (3).

First of all, it is easy to formulate conditions on the functions $a_{i}(x, u, \xi), a_{0}(x, u, \xi), \phi(x, u)$ guaranteeing that the operator A defined by the identity (7) satisfies the condition (22), provided that for $D$ we choose a ball $B(0, R)$ of a sufficiently large radius $R$. In that case the existence theorem immediately follows.

Here we give a less evident result on solvability of the problem (2), (3), proving existence of a classical solution belonging to $C^{2, \delta}(\bar{\Omega})$ with some $\delta>0$. Naturally, this requires stronger smoothness assumptions to be imposed on the functions $a_{i}(x, u, \xi)$, $a_{0}(x, u, \xi)$ than those from Sec. 2.

Let $p>1$ and for $(x, u, \xi) \in \bar{\Omega} \times R^{1} \times R^{n}$ let the following conditions be fulfilled:
(i) $a_{i}(x, u, \xi), b(x, u)$ are three times, and $a_{0}(x, u, \xi)$ twice differentiable functions of their arguments;
(ii) for $\eta \in R^{n}$ there are positive constants $C_{1}, C_{2}$ such that

$$
\begin{aligned}
& \sum_{i, j=1}^{n} \frac{\partial a_{i}(x, u, \xi)}{\partial \xi_{j}} n_{i} n_{j} \geq c_{1}(1+|\xi|)^{p-2}|n|^{2}, \\
& \left\{\sum_{i, j=1}^{n}\left|\frac{\partial a_{i}}{\partial \xi_{j}}\right|+\sum_{i=1}^{n}\left|\frac{\partial a_{i}}{\partial u}\right|\right\}(1+|u|+|\xi|)+\left|a_{0}(x, u, \xi)\right| \leq \\
& \leq c_{2}(1+|u|+|\xi|)^{p-1}, \\
& \sum_{i, j=1}^{n}\left|\frac{\partial a_{i}}{\partial x_{j}}\right|+\sum_{i=1}^{n}\left|\frac{\partial a_{0}}{\partial \xi_{i}}\right|+\left|\frac{\partial a_{0}}{\partial u}\right|+\sum_{i=1}^{n}\left|\frac{\partial a_{0}}{\partial x_{i}}\right| \leq c_{2}(1+|u|+|\xi|)^{p-1},
\end{aligned}
$$

$$
|b(x, u)| \leq c_{2}(1+|u|)^{p-1}
$$

(iii) there is $R>0$ such that for $|u|>R$,

$$
\sum_{i=1}^{n} \frac{\partial^{2} a_{i}(x, u, 0)}{\partial x_{i} \partial u}-\frac{\partial a_{0}(x, u, 0)}{\partial u} \leq c<0, x \in \bar{\Omega}
$$

$$
u\left[\sum_{i=1}^{n} a_{i}(x, u, 0) \cos \left(v, x_{i}\right)+b(x, u)\right]>0, \quad x \in \partial \Omega
$$

THEOREM 6. Let (i) - (iii) be fulfilled and let $\partial \Omega$ be a surface of class $c^{2, \lambda}, \lambda>0$. Then there is $\delta>0$ such that the problem (2), (3) has a solution belonging to $\mathrm{c}^{2, \delta}(\Omega)$.

Proof. We include the problem (2), (3) into a parametric family

$$
\begin{equation*}
t L(u)+(1-t)\left\{\sum_{i=1}^{n} \frac{d}{d x_{i}}\left[\left(1+\left|\frac{\partial u}{\partial x}\right|\right)^{p-2}\right] \frac{\partial u}{\partial x_{i}}-u\right\}=0, \quad x \in \Omega, \tag{23}
\end{equation*}
$$

(24) $\quad t B u+(1-t)\left(1+\left|\frac{\partial u}{\partial x}\right|\right)^{p-2} \frac{\partial u}{\partial v}=0, \quad x \in \partial \Omega$.

Analogously to [3] we can show that the generalized solution of the problem (23), (24), which belongs to $W_{p}^{1}(\Omega)$, belongs to $c^{2, \delta}(\Omega)$ as well. Then, applying the maximum principle, we easily obtain the estimate

$$
\begin{equation*}
\max _{\Omega}|\mathrm{u}(\mathrm{x})| \leq \mathrm{M}_{0} \tag{25}
\end{equation*}
$$

for an arbitrary solution of the problem (23), (24), with a constant $M_{0}$ independent of $t$. Then the integral identity yields the estimate

$$
\begin{equation*}
\|u\|_{w_{p}}(\Omega) \leq M_{1} \tag{26}
\end{equation*}
$$

for an arbitrary solution $u(x)$ of the problem (23), (24), $M_{1}$ being a positive number.

Now let us consider the parametric family of mappings

$$
\begin{aligned}
& A_{t}: B\left(0, M_{1}+1\right) \rightarrow\left[w_{p}^{1}(\Omega)\right]^{*}, \\
& A_{t}=t A+(1-t) A_{0}
\end{aligned}
$$

with the operator $A$ defined by the identity (7) and the operator $A_{0}$ by the identity

$$
\left\langle A_{0} u, \phi\right\rangle=\int_{\Omega}\left\{\left(1+\left|\frac{\partial u}{\partial x}\right|\right)^{p-2} \sum_{i=1}^{n} \frac{\partial u}{\partial x_{i}} \frac{\partial \phi}{\partial x_{i}}+u_{\phi}\right\} d x .
$$

Theorem 4 applied to the operator $A_{0}$ implies that $\operatorname{Deg}\left(A_{0}, B\left(0, M_{1}+1\right), 0\right)=1$. From Theorem 2 and the estimate (26) we easily obtain that $\operatorname{Deg}\left(A, B\left(0, M_{1}+1\right), 0\right)=1$. The assertion of Theorem 6 now follows by virtue of the nonzero rotation principle.

## 2. Topological characteristics of general nonlinear elliptic problems

1. In this chapter it is shown how general elliptic problems can be reduced to operator equations of the form (20) with the operator $A$ satisfying the condition ( $\alpha_{0}$ ).

In what follows, $\Omega$ is a bounded domain in $R^{n}$ with an infinitely differentiable boundary $\partial \Omega, n_{0}=\left[\frac{n}{2}\right]+1, m, m_{1}, \ldots, m_{m}$ are nonnegative integers, $m \geqq 1$. We denote by $M(q)$ the number of mutually distinct multiindices $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right)$ with nonnegative integer coordinates $\alpha_{i}$ and the length $|\alpha|=\alpha_{1}+\ldots+\alpha_{n}$ not greater than $q$.

Let $\ell_{0}=\max \left(2 m, m_{1}+\frac{1}{2}, \ldots, m_{m}+\frac{1}{2}\right)$ and assume that functions

$$
\begin{aligned}
& F: \bar{\Omega} \times R^{M(2 m)} \rightarrow R^{1}, \\
& G_{j}: \bar{\Omega} \times R^{M\left(m_{j}\right)} \rightarrow R^{1}, j=1, \ldots, m,
\end{aligned}
$$

are given, possessing continuous derivatives with respect to all their arguments up to the orders $\ell-2 \mathrm{~m}+1, \ell-2 \mathrm{~m}_{\mathrm{j}}+1$, respectively, where the number $\ell$ satisfies the condition $\ell \geqq \ell_{0}+n_{0}$.

The functions $F(x, \xi), G_{j}(x, \eta), \quad \xi=\left(\xi_{\alpha}:|\alpha| \leq 2 m\right), \quad \eta=$ $=\left(\eta_{\beta}:|\beta| \leqq m_{j}\right)$ will be also written in the form

$$
\begin{aligned}
& F(x, \xi)=F\left(x, \xi_{0}, \xi_{1}, \ldots, \xi_{2 m}\right), \\
& G_{j}(x, \eta)=G_{j}\left(x, n_{0}, \eta_{1}, \ldots, n_{m_{j}}\right),
\end{aligned}
$$

with $\xi_{k}=\left(\xi_{\alpha}:|\alpha|=k\right), \quad n_{k}=\left(n_{\alpha}:|\alpha|=k\right)$.
We shall also use the notation $D^{\alpha}(u)=\left(\frac{\partial}{\partial x_{1}}\right)^{\alpha_{1}} \ldots\left(\frac{\partial}{\partial x_{n}}\right)^{\alpha_{n}} u$ for any multiindex $\alpha, D^{k} u=\left\{D^{\alpha} u:|\alpha|=k\right\}$.

Finally, let

$$
\begin{equation*}
F_{\alpha}(x, \xi)=\frac{\partial F(x, \xi)}{\partial \xi_{\alpha}}, \quad G_{j, \beta}(x, n)=\frac{\partial G_{j}(x, n)}{\partial \eta_{\beta}} . \tag{27}
\end{equation*}
$$

In the present chapter we shall consider the boundary value problem

$$
\begin{align*}
& F\left(x, u, \ldots, D^{2 m_{u}}\right)=f(x), \quad x \in \Omega,  \tag{28}\\
& G_{j}\left(x, u, \ldots, D^{m_{j}} u\right)=g_{j}(x), j=1, \ldots, m, \quad x \in \partial \Omega \tag{29}
\end{align*}
$$

under the following conditions:
(i) for an arbitrary function $v(x) \in c^{\ell_{0}, \delta}(\bar{\Omega}), 0<\delta<1$, the operator

$$
\begin{aligned}
\ell(v) & : H^{\varepsilon_{0}}(\Omega) \rightarrow H^{\ell_{0}}(\Omega, \partial \Omega)= \\
& =H^{\ell_{0}-2 m}(\Omega) \times H^{\ell_{0}-m_{1}-\frac{1}{2}}(\partial \Omega) \times \ldots \times H^{\ell_{0}-m_{m}-\frac{1}{2}}(\partial \Omega)
\end{aligned}
$$

defined by the identities
(30)

$$
\begin{aligned}
& \theta(v) u=\left(L(v) u, B_{1}(v) u, \ldots, B_{m}(v) u\right), \\
& L(v) u=\sum_{|\alpha| \leq 2 m} F_{\alpha}\left(x, v, \ldots, D^{2 m} v\right) D^{\alpha} u, \\
& B_{j}(v) u=\sum_{|\beta| \leq m_{j}} G_{j, \beta}\left(x, v, \ldots,\left.D^{m} j_{v) D^{\beta} u}\right|_{\partial \Omega}\right.
\end{aligned}
$$

is elliptic and Fredholm; here $H^{\ell}(\Omega)=W_{2}^{\ell}(\Omega)$;
(ii) there is a function $H: \bar{\Omega} \times R^{M(2 m-1)} \rightarrow R^{1}$ of the class $C^{\ell-2 m}$, such that the problem

$$
\begin{aligned}
& L(v) u+M(v) u=0, \quad x \in \Omega, \\
& B_{j}(v) u=0, j=1, \ldots, m, \quad x \in \partial \Omega,
\end{aligned}
$$

has in $c^{\ell_{0}, \delta}(\bar{\Omega})$ only the zero solution for an arbitrary function $v \in C^{\ell_{0}, \delta}(\Omega)$. Here

$$
M(v) u=\sum_{|\gamma| \leqq 2 m-1} H_{\gamma}\left(x, v, \ldots, D^{2 m-1} v\right) D^{\gamma} u, \quad H_{\gamma}(x, \xi)=\frac{\partial H(x, \xi)}{\partial \xi} .
$$

The condition (i) expresses the ellipticity of the operator $L(v)$ and the fact that $L(v)$ and $B_{j}(v)$ at each point $x \in \partial \Omega$ satisfy the condition of Ya. B. LopatinskiY, while the fact that er is a Fredholm operator indicates that its index vanishes.

REMARK 1. Introducing simple modifications, we could replace the operator $M(v)$ from the condition (ii) by a totally continuous ope-
rator $\Gamma(v): H^{\ell_{0}}(\Omega) \rightarrow H^{\ell_{0}}(\Omega, \partial \Omega)$, such that for every $v \in C^{\ell_{0}, \delta}(\bar{\Omega})$ the operator $\varepsilon(v)+\Gamma(v)$ would represent an isomorphism of the corresponding spaces. Since the existence of such an operator $\Gamma(v)$ is obvious, the condition (ii) does not restrict the class of problems for which we below introduce the topological characteristic.

REMARK 2. The results of the present chapter are easily obtained provided the index of the operator $\varepsilon \|(v)$ is negative. If the index of the operator is positive then no one-to-one correspondence between the solution of the problem (28), (29) and those of the operator equation of the form (20) is established. In this case it is possible to define a finite number of nonlinear functionals $\ell_{i}(u)$ (their number being equal to the index) in such a way that the solutions of the operator equation $A u=0$ subjected to the condition $\ell_{i}(u)=0$ (orthogonality type conditions) are solutions of the problem (28), (29) as well.

Let $D$ be an arbitrary bounded domain in the space $H^{\ell}(\Omega)$ with a boundary $\partial \Omega$, let $f(x), g_{j}(x)$ be fixed elements of the spaces $H^{\ell-2 m}(\Omega), H^{\ell-m_{j}-\frac{1}{2}}(\partial \Omega)$, respectively.

We define a nonlinear operator $A_{1}: H^{\ell}(\Omega) \rightarrow\left[H^{\ell}(\Omega)\right]^{*}$ by

$$
\begin{align*}
\left\langle A_{1} u, \phi\right\rangle= & \left(F\left(x, u, \ldots, D^{2 m_{u}}\right)-f(x), L(u)_{\phi}+M(u)_{\phi}\right)_{\ell-2 m, \Omega}+ \\
& +\sum_{j=1}^{m}\left(G_{j}\left(x, u, \ldots, D^{m_{j}} u\right)-g_{j}(x), B_{j}(u)_{\phi}\right)_{\ell-m_{j}-\frac{1}{2}, \partial \Omega}, \tag{32}
\end{align*}
$$

where $(., \cdot)_{\ell, \Omega}$ and $(., .)_{\ell, \partial \Omega}$ are the inner products in the spaces $\mathrm{H}^{\ell}(\Omega), \mathrm{H}^{\ell}(\partial \Omega)$, respectively.

THEOREM 7. If the conditions (i), (ii) are fulfilled and $\ell \geq \ell_{0}+n_{0}$, then the operator $A_{1}$ defined by (32) is continuous, bounded and satisfies the condition (S).. If the problem (28), (29) has no solutions belonging to $\partial \mathrm{D}$, then the degree $\operatorname{Deg}\left(\mathrm{A}_{1}, \overline{\mathrm{D}}, 0\right)$ of the mapping $A_{1}$ of the domain $\bar{D}$ with respect to zero of the space $\left[H^{\ell}(\Omega)\right]^{*}$ is defined.

Proof. The continuity and boundedness of the operator $A_{1}$ are easily verified. Let us prove the validity of the condition ( S$)_{+} \cdot$

Let $u_{n}$ be an arbitrary sequence weakly converging to $u_{0}$, let
$u_{n} \in D$ and
(33)

$$
\lim _{n \rightarrow \infty}\left\langle A_{1} u_{n}, u_{n}-u_{0}\right\rangle \leq 0
$$

The weak convergence of $u_{n}$ in $H^{l}(\Omega)$ implies the strong convergence of $u_{n}$ to $u_{0}$ in $c^{\ell_{0}}(\Omega)$, since $\ell-\ell_{0} \frac{\geq}{\ell_{0}} n_{0}=\left[\frac{n}{2}\right]+1$ and the corresponding imbedding operator $\mathrm{H}^{\ell}(\Omega) \rightarrow \mathrm{C}^{\ell}(\bar{\Omega})$ is compact. For $\ell_{0}<$ $<j<\ell$ the Nirenberg-Gagliardo inequality yields

$$
\begin{align*}
& \sum_{|\alpha|=j}\left\|D^{\alpha}\left(u_{n}-u_{0}\right)\right\| I_{2\left(\ell-\ell_{0}\right) /\left(j-\ell_{0}\right)} \leq \\
& \leq c \sum_{|\alpha|=\ell}\| \|^{\alpha}\left(u_{n}-u_{0}\right)| |_{2}^{\frac{j-\ell_{0}}{\ell-\ell}}| | u_{n}-u_{0} \|_{c}^{1-\frac{j-\ell_{0}}{\ell-\ell}} \ell_{(\Omega)}+  \tag{34}\\
& +c| | u_{n}-u_{0} \|_{c^{\ell_{0}}(\bar{\Omega})}
\end{align*}
$$

and this implies that $u_{n} \rightarrow u_{0}$ in $w_{2\left(\ell-\ell_{0}\right) /\left(j-\ell_{0}\right)}^{j}(\Omega)$.
Consider $D^{\alpha} F\left(x, u, \ldots, D^{2 m} u\right)$ with $|\alpha| \leqq \ell-2 m$. An easy computation yields

$$
D^{\alpha} F\left(x, u, \ldots, D^{2 m} u\right)=\sum_{|\beta| \leqq 2 m} F_{\beta}\left(x, u, \ldots, D^{2 m} u\right) D^{\alpha+\beta} u+R_{\alpha} u,
$$

where $R_{\alpha}(u)$ satisfies the estimate

$$
\begin{equation*}
\left|R_{\alpha}(u)\right| \leq c_{0}(M)\left\{\sum_{j=\ell_{0}+1}^{\ell-1}\left|D^{j} u\right|^{\frac{\ell-\ell_{0}}{j-\ell_{0}}}+1\right\} \tag{35}
\end{equation*}
$$

provided the function $u(x)$ satisfies the inequality

$$
\begin{equation*}
\|\left. u\right|_{C} ^{\ell_{0}(\Omega)} \leq M \tag{36}
\end{equation*}
$$

with a constant M.
Analogously we verify that $D^{\alpha}(M(u) v)=R_{1, \alpha}(u, v)$,

$$
\begin{equation*}
D^{\alpha}(L(u) v)=L(u) D^{\alpha} v+R_{2, \alpha}(u, v) \tag{37}
\end{equation*}
$$

where $R_{i, \alpha}(u, v)$ satisfies the estimate

$$
\begin{equation*}
\left|R_{i, \alpha}(u, v)\right| \leq\left. c_{0}(M)| | v\right|_{c} ^{\ell_{0}}{ }_{(\Omega)}\left\{\sum_{j=\ell_{0}+1}^{\ell-1}\left|D^{j} u\right|^{\frac{\ell-\ell_{0}}{j-\ell_{0}}}+1\right\}+ \tag{38}
\end{equation*}
$$

$$
+C_{0}(M) \sum_{i=\ell_{0}+1}^{\ell-1}\left|D^{i} v\right|\left\{\sum_{j=\ell}^{\ell+2 m-i}\left|D^{j} u\right|^{\frac{\ell-i}{j-\ell}}+1\right\}, \quad i=1,2,
$$

provided the function $u(x)$ satisfies the condition (36).
Using the above identities we can write

$$
\begin{align*}
& \left(F \left(x, u_{n}, \ldots, D^{\left.\left.2 m_{u_{n}}\right)-f(x), L\left(u_{n}\right)\left(u_{n}-u_{0}\right)+M\left(u_{n}\right)\left(u_{n}-u_{0}\right)\right)_{\ell-2 m, \Omega}=}\right.\right.  \tag{39}\\
& =\sum_{|\alpha| \leq \ell-2 m} \int_{\Omega} D^{\alpha}\left[F \left(x, u_{n}, \ldots, D^{\left.\left.2 m_{u_{n}}\right)-f(x)\right]\left\{D^{\alpha} L\left(u_{n}\right)\left(u_{n}-u_{0}\right)+\right.}\right.\right. \\
& \left.+D^{\alpha} M\left(u_{n}\right)\left(u_{n}-u_{0}\right)\right\} d x= \\
& =\sum_{|\alpha| \leqq \ell-2 m} \int_{\Omega}\left[L\left(u_{n}\right) D^{\alpha} u_{n}+R_{\alpha}\left(u_{n}\right)-D^{\alpha} f\right]\left[L\left(u_{n}\right) D^{\alpha}\left(u_{n}-u_{0}\right)+\right. \\
& \left.+\sum_{j=1}^{2} R_{j, \alpha}\left(u_{n}, u_{n}-u_{0}\right)\right] d x=\left(L\left(u_{0}\right) u_{n}, L\left(u_{0}\right)\left(u_{n}-u_{0}\right)\right)_{\ell-2 m, \Omega}+ \\
& +R_{1}^{(n)} \text {, }
\end{align*}
$$

where

$$
\begin{aligned}
& R_{1}^{(n)}=\sum_{|\alpha| \leq \ell-2 m} \int_{\Omega}\left\{\left[L\left(u_{n}\right) D^{\alpha} u_{n}-L\left(u_{0}\right) D^{\alpha} u_{n}-R_{2, \alpha}\left(u_{0}, u_{n}\right)+R_{\alpha}\left(u_{n}\right)-D^{\alpha} f\right] \cdot\right. \\
& \cdot\left[L\left(u_{n}\right) D^{\alpha}\left(u_{n}-u_{0}\right)+\sum_{j=1}^{2} R_{j, \alpha}\left(u_{n}, u_{n}-u_{0}\right)\right]+D^{\alpha}\left(L\left(u_{0}\right) u_{n}\right) \cdot \\
& \cdot\left[L\left(u_{n}\right) D^{\alpha}\left(u_{n}-u_{0}\right)-L\left(u_{0}\right) D^{\alpha}\left(u_{n}-u_{0}\right)+\sum_{j=1}^{2} R_{j, \alpha}\left(u_{n}, u_{n}-u_{0}\right)-\right. \\
& \left.\left.-R_{2, \alpha}\left(u_{0}, u_{n}-u_{0}\right)\right]\right\} d x .
\end{aligned}
$$

In virtue of the inequalities (35), (38) and the above mentioned strong convergence of $u_{n}$ to $u_{0}$ in $c^{\ell_{0}(\Omega)}$ and $w_{2\left(\ell-\ell_{0}\right) /\left(j-\ell_{0}\right)}{ }^{j}(\Omega)$ we easily obtain

$$
\begin{equation*}
\lim _{n \rightarrow \infty} R_{1}^{(n)}=0 \tag{40}
\end{equation*}
$$

Now we pass to integrals over $\partial \Omega$ in (32), denoting
(41)

$$
\begin{aligned}
& G_{j}\left(x, u_{n}, \ldots, D^{m} j_{u_{n}}\right)=G_{j}\left(x, u_{0}, \ldots, D^{m} j_{u_{0}}\right)+ \\
& +\int_{0}^{1} B_{j}\left(u_{0}+t\left(u_{n}-u_{0}\right)\right)\left(u_{n}-u_{0}\right) d t .
\end{aligned}
$$

Then

$$
\begin{align*}
& \left(G_{j}\left(x, u_{n}, \ldots, D^{m} j_{u_{n}}\right)-g_{j}(x), B_{j}\left(u_{n}\right)\left(u_{n}-u_{0}\right)\right)_{\ell-m_{j}-\frac{1}{2}, \partial \Omega}=  \tag{42}\\
& =\left(B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right), B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right)\right)_{\ell-m_{j}-\frac{1}{2}, \partial \Omega}+R_{2, j}^{(n)},
\end{align*}
$$

where

$$
\begin{aligned}
& R_{2, j}^{(n)}=\left(B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right), B_{j}\left(u_{n}\right)\left(u_{n}-u_{0}\right)-B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right)\right) \\
& \ell-m_{j}-\frac{1}{2}, \partial \Omega
\end{aligned}+\quad \begin{aligned}
& m_{j} \\
&+\left(G_{j}\left(x, u_{0}, \ldots, D^{u_{0}}\right)-g_{j}(x)+\int_{0}^{1} B_{j}\left(u_{0}+t\left(u_{n}-u_{0}\right)\right)\left(u_{n}-u_{0}\right) d t-\right. \\
&\left.-B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right), B_{j}\left(u_{n}\right)\left(u_{n}-u_{0}\right)\right)_{\ell-m_{j}-\frac{1}{2}, \partial \Omega} .
\end{aligned}
$$

We shall prove that

$$
\begin{equation*}
\lim _{n \rightarrow \infty} R_{2, j}^{(n)}=0 \tag{43}
\end{equation*}
$$

Taking into account the boundedness of the imbedding operator $\mathrm{W}_{2}^{\ell-m_{j}}(\Omega) \rightarrow W_{2}^{\ell-m_{j}-\frac{1}{2}}(\partial \Omega)$, we conclude, for example for the first sum-
mand:

$$
\begin{align*}
& \left|\left(B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right) \cdot, B_{j}\left(u_{n}\right)\left(u_{n}-u_{0}\right)-B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right)\right)_{\ell-m_{j}-\frac{1}{2}, \partial \Omega}\right| \leq  \tag{44}\\
& \leq C| | B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right)| |_{\ell-m_{j}, \Omega} . \\
& \cdot \| B_{j}\left(u_{n}\right)\left(u_{n}-u_{0}\right)-B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right)| |_{\ell-m_{j}, \Omega} .
\end{align*}
$$

Further, writing the operator $B_{j}$ in the form of (37), we find that the first summand on the right hand side of (44) is uniformly bounded while the second tends to zero. Analogously we show that the limit of the second summand for $R_{2, j}^{(n)}$ vanishes, which completes the proof of (43).

The above considerations imply
(45)

$$
\begin{aligned}
&<A_{1}\left(u_{n}\right), u_{n}-u_{0}>=\left\|L\left(u_{0}\right)\left(u_{n}-u_{0}\right)\right\|_{\ell-2 m, \Omega}^{2}+ \\
&+\sum_{j=1}^{m}\left\|B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right)\right\|_{\ell-m_{j}-\frac{1}{2}, \partial \Omega}^{2}+R^{(n)}
\end{aligned}
$$

where

$$
R^{(n)}=\left(L\left(u_{0}\right) u_{0}, L\left(u_{0}\right)\left(u_{n}-u_{0}\right)\right)_{\ell-2 m, \Omega}+R_{1}^{(n)}+\sum_{j=1}^{m} R_{2, j}^{(n)} \text { and }
$$

$$
R^{(n)} \rightarrow 0 \text { for } n \rightarrow \infty
$$

Making use of the apriori estimates for linear elliptic operators [17], we obtain

$$
\begin{align*}
& \left|\left|u_{n}-u_{0}\right|\right|_{\ell, \Omega}^{2} \leq C\left\{| | L\left(u_{0}\right)\left(u_{n}-u_{0}\right)| |_{\ell-2 m, \Omega}^{2}+\right.  \tag{46}\\
& \left.\quad+\sum_{j=1}^{m}| | B_{j}\left(u_{0}\right)\left(u_{n}-u_{0}\right)| |_{\ell-m_{j}-\frac{1}{2}, \partial \Omega}^{2}+\left|\left|u_{n}-u_{0}\right|\right|_{0, \Omega}^{2}\right\}
\end{align*}
$$

Now (33), (45) and (46) imply the strong convergence of $u_{n}$ to $u_{0}$ in $H^{\ell}(\Omega)$, which completes the proof of the theorem.

REMARK 3. The coefficients of the operators $L\left(u_{0}\right), B_{j}\left(u_{0}\right)$ are not sufficiently smooth to allow for immediate application of the results of $[17]$ when establishing the inequality (46). In this case it is necessary to obtain more precise estimates, based on the form of the operators $L\left(u_{0}\right), B_{j}\left(u_{0}\right)$, on the inclusion of $u_{0}$ in the space $H^{\ell}(\Omega)$ and on the Nirenberg-Gagliardo inequality. We are not going into details since the procedure is straightforward.
2. The degree of a mapping $A_{1}$ introduced in Theorem 7 enables us to apply topological methods when studying the problem (28), (29). In particular, these methods are based on the investigation of a family of parametric problems and, in presence of apriori estimates, on the possibility of a homotopy between the problem (28), (29) and another simpler and more special problem of the same type.

We restrict ourselves to the formulation of a single one of the possible consequences.
$\frac{\text { THEOREM 8. }}{M\left(m_{j}\right)}$ Let $\hat{F}:[0,1] \times \bar{\Omega} \times R^{M(2 m)} \rightarrow R^{1}, \mathcal{G}_{j}:[0,1] \times \bar{\Omega} \times$ $\times R^{M\left(m_{j}\right)} \rightarrow R^{1}, j=1, \ldots, m$ be continuous mappings. Assume that for each $t \in[0,1]$, the functions $F_{t}(x, \xi)=\hat{F}(t, x, \xi), G_{j, t}(x, \eta)=$ $=\vec{G}_{j}(t, x, n)$ satisfy the conditions (i), (ii) of Sec. 1 and, moreover,
(a) there exists a positive function $K: R_{+}^{1} \rightarrow R^{1}$ such that for $t \in[0,1], u \in H^{\ell}(\Omega)$, the relations

$$
\begin{align*}
F_{t}\left(x, u, \ldots, D^{2 m} u\right) & =t f(x), \quad x \in \Omega,  \tag{47}\\
G_{j, t}\left(x, u, \ldots, D^{m_{u}}\right. & =t g_{j}(x), j=1, \ldots, m, \quad x \in \partial \Omega,
\end{align*}
$$

imply the estimate

$$
\left||u|_{\ell, \Omega} \leq K\left(\left.| | f\right|_{\ell-2 m, \Omega}+\sum_{j=1}^{m}| | g_{j}| |_{\ell-m_{j}-\frac{1}{2}, \partial \Omega}\right) ;\right.
$$

(b) $\quad F_{0}(x,-\xi)=-F_{0}(x, \xi), \quad G_{j}(x,-\eta)=-\bar{G}_{j}(x, \eta)$.

Then the problem (47) has at least one solution in $H^{\ell}(\Omega)$ for arbitrary $f \in H^{\ell-2 m}(\Omega), g_{j} \in H^{\ell-m_{j}-\frac{1}{2}}(\partial \Omega)$.

The proof of the theorem follows from Theorems 5 and 3, provided that for fixed $f, g_{j}$, we replace $D$ by the ball $B(0, R)$ in $H^{\ell}(\Omega)$ of the radius

$$
R=k\left(\|f\|_{\ell-2 m, \Omega}+\sum_{j=1}^{m}\left\|g_{j}\right\|_{\ell-m_{j}-\frac{1}{2}, \partial \Omega}\right)+1 .
$$

The operators $A_{t}$ corresponding to the problem (47) are introduced according to the identity (32).

REMARK 4. The condition (a) of Theorem 8 may be weakened by requiring an apriori estimate of the problem (47) in $\mathrm{C}^{\ell \gamma^{+\alpha}}(\Omega)$.
3. The definition of the operator $A_{1}$ introduced in Sec. 1 requires sufficient smoothness of the functions $F(x, \xi), G_{j}(x, n)$. It is possible to weaken the conditions concerning smoothness of these functions by considering the corresponding operators in the space $W_{p}^{\ell_{0}+1}(\Omega)$ for $p>n$.

Let the functions $F: \bar{\Omega} \times R^{M(2 m)} \rightarrow R^{1}, G_{j}: \bar{\Omega} \times R^{M\left(m_{j}\right)} \rightarrow R^{1}$, $j=1, \ldots, m$, belong to the spaces $C^{\ell_{0}+2-2 m}, C^{\ell_{0}+2-m} j$, respectively, and let the conditions (i), (ii) from Sec. 1 be satisfied for them with some $\delta, 0<\delta<1-\frac{n}{\mathrm{p}}$.

Let $D$ be an arbitrary bounded domain in the space $W_{p}^{\ell_{0}+1}(\Omega)$ with a boundary $\partial \Omega$, let $f(x), g_{j}(x)$ be functions from the spaces $\mathrm{w}_{\mathrm{p}}^{\ell_{0}-2 m+1}(\Omega), \mathrm{B}_{\mathrm{p}}^{\ell_{0}-m_{j}-\frac{1}{p}+1}(\partial \Omega)$, where $\mathrm{B}_{\mathrm{p}}^{\mathrm{s}}(\partial \Omega)$ denotes a Besov space. Under these conditions the operator of defined above can be considered as an operator from $W_{p}^{\ell_{0}+1}(\Omega)$ into ${\underset{W}{p}}_{\ell_{0}+1}^{(\Omega, \partial \Omega)}$ :

$$
W_{p}^{\ell_{0}+1}(\Omega, \partial \Omega)=W_{p}^{\ell_{0}-2 m+1}(\Omega) \times \prod_{j=1}^{m} B_{p}^{\ell_{0}+1-m_{j}-\frac{1}{p}}(\partial \Omega)
$$

Introduce a nonlinear operator $A_{2}: W_{p}^{\ell_{0}+1}(\Omega) \rightarrow\left[W_{p}^{\ell_{0}+1}(\Omega)\right]^{*}$ by the identity

$$
\begin{align*}
& \left\langle A_{2} u, \phi\right\rangle=\sum_{|\alpha| \leq \ell_{0}+1-2 m} \int_{\Omega} \psi_{p}\left\{D^{\alpha}\left[F\left(x, u, \ldots, D^{2 m} u\right)-f\right]\right\} D^{\alpha}[\mathrm{L}(u) \phi+  \tag{48}\\
& +M(u) \phi] d x+ \\
& +\sum_{j=1}^{m} \sum_{|\beta|=\ell_{0}-m_{j}} \int_{\partial \Omega} \int_{\partial \Omega} \psi_{p}\left\{D_{x}^{\beta}\left[G_{j}\left(x, \ldots, D_{x}^{m_{j}} u(x)\right)-g_{j}(x)\right]-\right. \\
& \left.-D_{y}^{\beta}\left[G_{j}\left(y, \ldots, D_{y}^{m}{ }_{u}(y)\right)-g_{j}(y)\right]\right\}\left[D_{x}^{\beta} B_{j}(u) \phi(x)-D_{y}^{\beta} B_{j}(u) \phi(y)\right] \text {. } \\
& \text { - } \frac{1}{|x-y|^{n+p-2}} d_{x} s d_{y} s+ \\
& +\sum_{j=1}^{m} \int_{\partial \Omega} \psi_{p}\left\{G_{j}\left(x, \ldots, D^{m}{ }_{j}(x)\right)-g_{j}(x)\right\} B_{j}(u) \phi d S \text {, }
\end{align*}
$$

where

$$
\psi_{p}(t)=t+|t|^{p-2} t
$$

THEOREM 9. The operator $\mathrm{A}_{2}: \mathrm{W}_{\mathrm{p}}^{\ell_{0}+1}(\Omega) \rightarrow\left[\mathrm{W}_{\mathrm{p}}^{\ell_{0}+1}(\Omega)\right]^{*}$ defined by (48) is continuous, bounded and satisfies the condition ( S$)_{+}$for $\mathrm{p}>$ $>\mathrm{n}$. If the problem (28), (29) has no solutions belonging to $\partial \mathrm{D}$, then the degree $\operatorname{Deg}\left(\mathrm{A}_{2}, \overline{\mathrm{D}}, 0\right)$ of the mapping $\mathrm{A}_{2}$ of the set $\overline{\mathrm{D}}$ with respect to zero of the space $\left[\mathrm{W}_{\mathrm{p}}^{\ell_{0}+1}(\Omega)\right]^{*}$ is defined.

Proof proceeds analogously to that of Theorem 7.
Notice that, if the condition (ii) is satisfied, the solutions of the problem (28), (29) coincide with those of the operator equation $A_{2} u=0$ in the same way as was the case in Sec. 1.

REMARK 5. We can assume that the operator $\&$ (v) is elliptic not for all smooth functions $v$ but only for those which are solutions of the problem (28), (29). Then a construction analogous to that given above yields operators $A_{1}, A_{2}$ corresponding to the differential problem (28), (29). These operators satisfy the condition ( $\alpha_{0}$ ) and consequently, we can in this case define the degree of the mapping.

## 3. Nonlinear Dirichlet problem and coercive estimates for pairs of linear elliptic operators

1. In Chap. 2 we introduced the degree of a mapping, correspon-
ding to general nonlinear elliptic boundary value problems, by constructing the mappings $A_{1}, A_{2}$. When applying the theory of degree to individual problems it is desirable to have, as far as possible, a simpler representation of the mappings in question. A simpler construction of the mappings $A$ can be obtained in the case of nonlinear Dirichlet problem; it is based on important coercive estimates for pairs of linear operators.

We shall be interested in inequalities of the type

$$
\begin{equation*}
(L u, M u)_{\ell} \geq c_{1}| | u| |_{2 m+\ell}^{2}-c_{2}| | u| |_{0}^{2} \tag{49}
\end{equation*}
$$

for functions $u(x) \in W_{2}^{2 m+\ell}(\Omega) \cap \stackrel{W}{W}_{2}^{m}(\Omega)$, that is, satisfying the boundary value conditions

$$
\begin{equation*}
D^{\alpha} u(x)=0, \quad|\alpha| \leqq m-1, \quad x \in \partial \Omega \tag{50}
\end{equation*}
$$

The symbols $(., \cdot)_{\ell}, \quad| | \cdot \|_{\ell}$ in (49) stand for the inner product and the norm in $W_{2}^{\ell}(\Omega)$, respectively, while $L, M$ are linear differential operators of the order 2 m with sufficiently smooth coefficients. It is easy to see that a necessary condition for the inequality (49) to be valid with positive constants $C_{1}, C_{2}$ independent of $u$ is that the operators $L$, $M$ be elliptic. This follows from the fact that the ellipticity of the operator $L$ is necessary for the validity of the inequality (49) in the case $L=M$ (see [17]).

In [17], the estimate (49) is proved provided $L=M$. For $\ell=0$ the inequality (49) was proved in the papers by P. E. Sobolevskii and O. A. Ladyženskaya for arbitrary elliptic operators $L, M$ of the second order $(m=1)$.

For $\ell>0$ or $m>1$ the inequality (49) need not hold. Examples of linear elliptic operators $L, M$ of the fourth order ( $m=2$ ), such that the inequality (49) fails to hold for $\ell=0$, are given in [14]. In the same paper the reader will find examples of second order operators, for which (49) is not valid for $\ell=1$, as well as an example óf operators $L, M$ with complex-valued coefficients, for which the analogue of the inequality (49) does not hold in the complex case.

The above consideration shows that to make the validity of the estimate (49) possible it is necessary to have a certain relation between the operators $L$, $M$. Among the most general and important possible approaches let us point out the following one: for a given family of operators $L$, prove the existence and present a construction
of an operator $M$ such that the estimate (49) holds for the operator $M$ and for any operator $L$ from the given family. It turned out that this formulation of the problem admits its solution, which was presented in [14].

Let $\Omega$ be a bounded domain in $R^{n}$ with a boundary $\partial \Omega$ of the class $C^{\infty}$. A positive number $A$ is called a constant of ellipticity of a linear operator

$$
L(x, D)=\sum_{|\alpha| \leq 2 m} a_{\alpha}(x) D^{\alpha}, \quad x \in \bar{\Omega} \subset R^{n}
$$

if for $x \in \bar{\Omega}, \quad \xi=\left(\xi_{1}, \ldots, \xi_{n}\right) \in \mathbb{R}^{n}$ the inequality

$$
\operatorname{Re} \sum_{|\alpha,|=2 m} a_{\alpha}(x) \xi^{\alpha} \geq A|\xi|^{2 m}
$$

holds. The coefficients $a_{\alpha}(x)$ of the operator $L(x, D)$ are considered to be complex-valued.

For a nonnegative integer $\ell$ and $0<\lambda<1$ let us denote by $Z_{2 m}^{\ell, \lambda}(A, B, \Omega)$ the family of linear regularly elliptic operators $L(x, D)$ of the 2 m -th order with a single constant of ellipticity $A$ and with coefficients $a_{\alpha}(x)$ of the class $C^{\ell, \lambda}(\bar{\Omega})$, which satisfy the conditions

$$
\left|\left|a_{\alpha}(x)\right|_{C}^{\ell, \lambda}(\bar{\Omega}) \leq B, \quad\right| \alpha \mid \leq 2 m .
$$

THEOREM 10. For arbitrary positive numbers $\mathrm{A}, \mathrm{B}, \lambda$ there are positive constants $C_{1}, C_{2}$, depending only on $A, B, \lambda, m, \Omega$, and a linear operator $M(x, D)=\sum_{|\alpha| \leq 2 m} b_{\alpha}(x) D^{\alpha}$ with infinitely differentiable real coefficients $b_{\alpha}(x)$, such that $M(x, D) \in Z_{2 m}^{0, \lambda}\left(1, C_{2}, \Omega\right)$ and for $L(x, D) \in Z_{2 m}^{0, \lambda}(A, B, \Omega)$ the inequality

$$
\begin{equation*}
\operatorname{Re} \int_{\Omega} L(x, D) u \cdot \overline{M(x, D) u} d x \geqq\left. C_{1}| | u\right|_{2 m} ^{2}-\left.C_{2}| | u\right|_{0} ^{2} \tag{51}
\end{equation*}
$$

holds for any $\mathrm{u}(\mathrm{x}) \in \mathrm{W}_{2}^{2 \mathrm{~m}}(\Omega) \cap \mathrm{W}_{2}^{\mathrm{m}}(\Omega)$.

Proof of the apriori estimate (51) and the construction of the operator $M(x, D)$ proceeds by means of the corresponding local considerations and their putting together by means of the partition of unity. Since the concluding phase of the proof is more standard and is given in [14], we restrict ourselves to establishing the apriori estimate in the model case.

First, let us consider functions of one variable $x$, which are defined on the half-axis $R_{+}^{1}=\left\{x \in R^{1}: x \geqq 0\right\}$. By $P_{2 m}\left(A, B, R_{+}^{1}\right)$ we denote the family of ordinary differential operators $P(D)=$ $=\sum_{j=0}^{2 m} p_{j} D^{j}, D=\frac{1}{i} \frac{d}{d x}$, with constant complex coefficients $p_{j}$ and satisfying for $\xi \in R^{1}$ the conditions

$$
\operatorname{Re} P(\xi) \geqq A\left(1+|\xi|^{2}\right)^{m}, \quad\left|p_{j}\right| \leqq B, \quad j=0, \ldots, 2 m
$$

LEMMA 5. There are positive numbers $q, k, q \geq 1, k \leqq A$ depending only on $A, B, m$ and such that for $P(D) \in P_{2 m}\left(A, B, R_{+}^{1}\right), Q(D)=$ $=q^{2 m}+D^{2 m}$ and for any function $u(x) \in W_{2}^{2 m}\left(R_{+}^{1}\right) \cap \stackrel{o}{m}_{2}^{m}\left(R_{+}^{1}\right)$ the inequality
holds.

$$
\begin{equation*}
\operatorname{Re} \int_{R_{+}^{1}} P u \overline{Q u} d x \geq k \int_{R_{+}^{1}} \sum_{j=0}^{2 m}\left|D^{j} u\right|^{2} d x \tag{52}
\end{equation*}
$$

Proof. In order to verify the estimate (52) we only have to notice that

$$
\begin{align*}
& \operatorname{Re} \int_{R_{+}^{1}} P u \cdot \overline{D^{2 m} u} d x \geq k_{1} \int_{R_{+}^{1}}\left|D^{2 m} u\right|^{2} d x-k_{2} \int_{R_{+}^{1}}^{2 m-1} \sum_{j=0}\left|D^{j} u\right|^{2} d x  \tag{53}\\
& \operatorname{Re} \int_{R_{+}^{1}} P u \bar{u} d x \geq k_{3} \int_{R_{+}^{1}} \sum_{j=0}^{m}\left|D^{j} u\right|^{2} d x
\end{align*}
$$

holds with some constants $\mathrm{k}_{1}, \mathrm{k}_{2}, \mathrm{k}_{3}$ depending only on $\mathrm{A}, \mathrm{B}$. The first inequality in (53) follows from the Cauchy inequality. In order to obtain the second inequality we set

$$
\int_{R_{+}^{1}} P u \bar{u} d x=\sum_{j=0}^{m} p_{j} \int_{R^{1}} D^{j} \tilde{u} \overline{\tilde{u}} d x+\sum_{j=m+1}^{2 m} p_{j} \int_{R^{1}} D^{m} \tilde{u} \overline{D^{j-m} \tilde{u}} d x
$$

where $\tilde{u}(x)$ is the extension of $u(x)$ to $R^{1}$ by zero outside $R_{+}^{1}$. Then the second inequality in (53) is a consequence of the Parseval identity and of the condition imposed on $\operatorname{Re} P(\xi)$.

Now the inequality (52) follows from (53) by the interpolation inequality and by a proper choice of $q$.

Lemma 5 enables us to prove in a simple way the corresponding
assertion for the homogeneous elliptic operator with constant coefficients and functions defined in $R_{+}^{n}=\left\{x=\left(x_{1}, \ldots, x_{n}\right) \in R^{n}: x_{n} \geq 0\right\}$. For $n \geq 2$ we denote by $P_{2 m}\left(A, B, R_{+}^{m}\right)$ the family of differential operators $P(D)=\sum_{|\alpha|=2 m} p_{\alpha} D^{\alpha}$ with constant complex coefficients $p_{\alpha}$ satisfying the conditions

$$
\operatorname{Re} P(\xi) \geq A|\xi|^{2 m}, \quad\left|p_{\alpha}\right| \leqq B, \quad|\alpha|=2 m \quad \text { for } \xi \in R^{n} .
$$

LEMMA 6. For any function $\mathrm{u}(\mathrm{x}) \in \mathrm{w}_{2}^{2 \mathrm{~m}}\left(\mathrm{R}_{+}^{\mathrm{n}}\right) \cap \stackrel{\circ}{\mathrm{w}}_{2}^{\mathrm{m}}\left(\mathrm{R}_{+}^{\mathrm{n}}\right)$ and $\mathrm{P}(\mathrm{D}) \in$ $\in P_{2 m}\left(A, B, R_{+}^{n}\right), Q(D)=q^{2 m}\left[\sum_{j=1}^{n-1} D_{j}^{2}\right]^{m}+D_{n}^{2 m}$, the inequality

$$
\begin{equation*}
\operatorname{Re} \int_{R_{+}^{n}} P(D) u \overline{Q(D) u} d x \geq k \int_{R_{+}^{n}} \sum_{|\alpha|=2 m}\left|D^{\alpha} u\right|^{2} d x \tag{54}
\end{equation*}
$$

holds with the constants $\mathrm{k}, \mathrm{q}$ defined in Lemma 5.
Lemma 6 is a consequence of Lemma 5 and the Parseval identity.
The rest of the proof of Theorem 10 proceeds on the basis of the model inequality (54) by means of the partition of unity.

THEOREM 11. For arbitrary positive numbers A, B a nonnegative integer $\ell$ and $\lambda, 0<\lambda<1$, there are infinitely differentiable real-valued functions $C_{\alpha \beta}(x),|\alpha|,|\beta| \leqq \ell, C_{\alpha \beta}(x)=C_{\beta \alpha}(x)$, and positive constants $\mathrm{k}_{1}, \mathrm{k}_{2}$ depending only on $\mathrm{A}, \mathrm{B}, \mathrm{m}, \ell$, $\lambda, \Omega$, such that for $L(x, D) \in \mathrm{z}_{2 \mathrm{~m}}^{\ell, \lambda}(\mathrm{A}, \mathrm{B}, \Omega), \mathrm{u}(\mathrm{x}) \in \mathrm{W}_{2}^{2 \mathrm{~m}+\ell}(\Omega) \cap{ }_{\mathrm{W}}^{\mathrm{m}}(\Omega)$ the inequality

$$
\begin{equation*}
\operatorname{Re}[\mathrm{Lu}, \mathrm{Mu}]_{\ell} \geq \mathrm{k}_{1}| | u\left\|_{2 \mathrm{~m}+\ell}^{2}-\mathrm{k}_{2}\right\| \mathrm{u} \|_{0}^{2} \tag{55}
\end{equation*}
$$

holds, where the operator $M$ was introduced in Theorem 10, and

$$
\begin{gather*}
{\left[v_{1}, v_{2}\right]_{\ell}=\sum_{|\alpha|,|\beta| \leq \ell} \int_{\Omega} C_{\alpha \beta}(x) D^{\alpha} v_{1} \cdot \overline{D^{\beta} v_{2}} d x,}  \tag{56}\\
k_{1}| | v| |_{\ell}^{2} \leq[v, v]_{\ell} \leq k_{2}| | v| |_{\ell}^{2} \tag{57}
\end{gather*}
$$

hold for any $\mathrm{v}(\mathrm{x}), \mathrm{v}_{1}(\mathrm{x}), \mathrm{v}_{2}(\mathrm{x}) \in \mathrm{w}_{2}^{\ell}(\Omega)$.
In the beginning let us point out that in order to obtain the validity of the inequality of the form (49), it was of advantage to introduce a special scalar product $[., .]_{\ell}$ in the space $W_{2}^{\ell}(\Omega)$.

The counterexamples given in [14] demonstrate the importance of the special choice of the scalar product.

Theorem 11 will be first proved for the case of differential operators on the half-axis and then it will be established in the usual way, by employing the partition of unity, for the general case.

LEMMA ?. For arbitrary positive numbers $\mathrm{A}, \mathrm{B}$ and a nonnegative integer $\ell$ there are positive numbers $\rho, K, \rho>1$, depending only on $A, B, \ell, m$ and suoh that for $P(D) \in P_{2 m}\left(A, B, R_{+}^{1}\right), u(x) \in$


$$
\begin{equation*}
\operatorname{Re} \int_{R_{+}^{1}}\left\{D^{\ell} P u \cdot D^{\ell} Q u+\rho P u \cdot \overline{Q u}\right\} d x \geq K \int_{R_{+}^{1}}^{2 m+\ell} \sum_{j=0}^{2}\left|D^{j} u\right|^{2} d x \tag{58}
\end{equation*}
$$

holds with the operator $Q(D)$ introduced in Lemma 5.
In order to prove the inequality it suffices to notice that

$$
\operatorname{Re} \int_{R_{+}^{1}} D^{\ell} P u \cdot D^{\ell} Q u d x \geq K^{\prime} \int_{R_{+}^{1}}\left|D^{2 m+\ell} u\right|^{2} d x-K^{\prime \prime} \int_{R_{+}^{1}}^{2 m+\ell-1} \sum_{j=\ell}^{2}\left|D^{j} u\right|^{2} d x
$$

holds with constants $K^{\prime}$, $K^{\prime \prime}$ depending only on $A, B$, and then to use the estimate (52) and the interpolation inequality.

Applying the Parseval identity to Lemma 7, we obtain the estimate

$$
\operatorname{Re} \sum_{|\alpha|=\ell} \int_{R_{+}^{n}} C_{\alpha}(\rho) D^{\alpha} P(D) u \cdot D^{\alpha} Q(D) u d x \geq K \int_{R_{+}^{n}} \sum_{|\alpha|=2 m+\ell}\left|D^{\alpha} u\right|^{2} d x
$$

for any function $u(x) \in W_{2}^{2 m+\ell}\left(R_{+}^{n}\right) \cap{ }^{\circ} m\left(R_{+}^{n}\right)$ and an operator $P(D) \in$ $\in P_{2 m}\left(A, B, R_{+}^{n}\right)$, where $Q(D)$ is the operator introduced in Lemma 6 and $C_{\alpha}(\rho)$ is defined as follows:

$$
\begin{array}{ll}
C_{\alpha}(\rho)=\frac{l!}{\alpha_{1}!\cdots \alpha_{n-1}} & \text { for } \alpha_{n}=0, \\
C_{\alpha}(\rho)=0 & \text { for } 0<\alpha_{n}<l, \\
C_{\alpha}(\rho)=\rho & \text { for } \alpha_{n}=l .
\end{array}
$$

REMARK 6. Theorem 11 still holds if the family of operators
$z_{2 m}^{\ell, \lambda}(A, B, \Omega)$ is for $\ell>\frac{n}{2}$ replaced by the family $\tilde{z}_{2 m}^{\ell}(A, B, \Omega)$ that consists of linear regularly elliptic operators $L(x, D)$ of the $2 m$-th order with a single constant of ellipticity $A$ and with the coefficients $a_{\alpha}(x)$ of the class $W_{2}^{\ell}(\Omega)$, satisfying the conditions

$$
\left|\left|a_{\alpha}(x)\right|_{W_{2}^{\ell}(\Omega)} \leq \mathrm{B}, \quad\right| \alpha \mid \leq 2 \mathrm{~m}
$$

To verify the assertion of the remark it suffices to estimate the subordinate terms when applying the partition of unity, using the Hölder inequality and the imbedding theorem for the Sobolev spaces.
2. Now we shall show a simple way of reducing the Dirichlet problem to an operator equation with an operator satisfying the condition (S) ${ }_{+}$on the basis of Theorem 11. For the sake of simplicity we will consider the case of the homogeneous boundary value problem.

Let a function $F: \bar{\Omega} \times R^{M(2 \mathrm{ni})} \rightarrow \mathrm{R}^{1}$ have continuous derivatives up to an order $\ell+1, \ell \geqq\left[\frac{n}{2}\right]+1$, and let us assume that there is a nonnegative nonincreasing function $v: R_{+}^{1} \rightarrow R^{1}$ such that

$$
\sum_{|\alpha|=2 m} F_{\alpha}(x, \xi) \eta^{\alpha} \geq \nu(|\xi|) \cdot|\eta|^{2 m}
$$

holds provided $x \in \bar{\Omega}, \quad \xi \in R^{M(2 m)}, \eta \in R^{n}$. (We keep here the notation from Chap. 2, Sec. 1.)

We shall discuss the solvability in $x=w_{2}^{2 m+l}(\Omega) \cap \stackrel{\circ}{W_{2}^{m}}(\Omega)$ of the problem

$$
\begin{align*}
& F\left(x, u, \ldots, D^{2 m_{u}}\right)=f(x), \quad x \in \Omega  \tag{59}\\
& D^{\alpha} u=0, \quad|\alpha| \leqq m-1, \quad x \in \partial \Omega \tag{60}
\end{align*}
$$

Let $D$ be an arbitrary bounded domain in the space $X$ and assume that the problem (59), (60) has no solution belonging to $\partial D$.

Consider the family $Z=\{L(v): v \in \bar{D}\}$, the operator $L(v)$ being defined in Chap. 2, Sec. 1. In virtue of Theorem 11 and Remark 6 we can construct a linear uniformily elliptic operator $M(x, D)$ of the order 2 m , with infinitely differentiable in $\bar{\Omega}$ coefficients, and a scalar product $[., .]_{\ell}$ in the space $W_{2}^{\ell}(\Omega)$ so that there are constants $C_{1}, C_{2}$ such that

$$
\begin{align*}
& {[L(v) u, M u]_{\ell} \geq C_{1}| | u\left\|_{2 m+\ell}^{2}-C_{2}\right\| u \|_{0}^{2} \text { for } v \in \bar{D},}  \tag{61}\\
& (-1)^{m} \int_{\Omega} M u \cdot u d x \geq C_{1}| | u \|_{m}^{2} .
\end{align*}
$$

We define a nonlinear operator $A_{3}: \bar{D} \rightarrow x^{*}$ by

$$
\begin{equation*}
\left\langle A_{3} u, \phi\right\rangle=\left[F\left(x, u, \ldots, D^{2 m} u\right)-f(x), M \phi\right]_{\ell} \tag{62}
\end{equation*}
$$

THEOREM 12. The operator $\mathrm{A}_{3}: \overline{\mathrm{D}} \rightarrow \mathrm{X}^{*}$ defined by (62) is continuous, bounded and satisfies the condition (S) .' If the problem (59), (60) has no solution belonging to $\partial D$, then $\operatorname{Deg}\left(A_{3}, \bar{D}, 0\right)$ is defined.

Proof is analogous to that of Theorem 7. If $u_{n} \in \bar{D}$ and $u_{n}$ weakly converges to $u_{0}$ in $X$, then analogously to (45) we can obtain

$$
<A_{3} u_{n}, u_{n}-u_{0}>=\left[L\left(u_{0}\right)\left(u_{n}-u_{0}\right), M\left(u_{n}-u_{0}\right)\right]_{\ell^{+}} \tilde{R}^{(n)},
$$

where $\tilde{R}^{(n)} \rightarrow 0$ with $n \rightarrow \infty$. The strong convergence of $u_{n}$ to $u_{0}$ then follows from (61), provided $\lim _{n \rightarrow \infty}<A_{3} u_{n}, u_{n}-u_{0}>\leq 0$.

REMARK 7. If we study the problem (59), (60) that is elliptic only on the solutions, we have to take the family $\left\{L(v), v \in N_{D}\right\}$ for $Z$ when constructing the operator $M$. Here $N_{D}$ is the set of solutions of the problem (59), (60) which belong to $\bar{D}$.

## 4. Solvability of nonlinear boundary value problems

In the present chapter we apply the topological methods developed above to three distinct nonlinear boundary value problems: the Dirichlet problem for the Monge-Ampere equation and for the general nonlinear equation of the thin layer, and the Neumann problem for the quasilinear second order elliptic equation.

The common feature of all the problems considered is that they differ from the well-known classes of quasilinear divergent equations in the Sobolev spaces. Another common feature is the essential nonlinearity of the problems, as well as the fact that for all these problems it is possible to find apriori estimates and establish the existence theorem for the classical solution.

1. Let us study the problem of existence of a solution regular in a closed domain, of the Dirichlet problem

$$
\begin{equation*}
u_{x x} u_{y y}-u_{x y}^{2}=\phi\left(x, y, u, \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}\right), \quad(x, y) \in \Omega \tag{63}
\end{equation*}
$$

$$
\begin{equation*}
\left.u\right|_{\partial \Omega}=g(x, y) \tag{64}
\end{equation*}
$$

Here $\Omega$ is a circle of radius $R$ and centre at the origin of the coordinate system. We assume $g(x, y) \in c^{4, \lambda}(\partial \Omega), \phi(x, y, u, p, q)$ is a positive function of a class $C^{2, \lambda}(G), 0<\lambda<1$, where $G=$ $=\left\{(x, y, u, p, q):(x, y) \in \bar{\Omega},(u, p, q) \in R^{3}\right\}$, and $g, \phi$ satisfy the conditions
(i) $\phi(x, y, u, p, q)<\Phi\left(x^{2}+y^{2}\right) f\left(p^{2}+q^{2}\right)$
provided $u \leqq m=\max _{(x, y) \in \partial \Omega} g(x, y)$;
(ii) $\iint_{\Omega} \Phi\left(x^{2}+y^{2}\right) d x d y<\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \inf _{(\xi-p)^{2}+(\eta-q)^{2}<M_{k}} f^{-1}\left(\xi^{2}+\eta^{2}\right) d p d q$, $M_{k}$ being the lower winding of the curve ${ }^{*}$ ) determined by the condition (64).

The existence of a solution, regular in the closed domain $\bar{\Omega}$, of the problem (63), (64) is proved in [18] by the Newton-Kantorovic method under the conditions (i), (ii) and the additional assumption

$$
\begin{equation*}
\frac{\partial \phi(x, y, u, p, q)}{\partial u} \geq 0 . \tag{65}
\end{equation*}
$$

Making use of the apriori estimates of a solution of the problem (63), (64), given in [18], as well as of the topological method developed in [12], the author with A. E. Siškov proved in [19] the classical solvability of the problem (63), (64), assuming only (i), (ii) but without the assumption (65).

Let us denote by $H_{4}^{+}(\Omega)$ the family of functions belonging to $W_{2}^{4}(\Omega)$ and satisfying the conditions

$$
u_{x x} u_{y y}-u_{x y}^{2}>0, u_{x x}>0,(x, y) \in \bar{\Omega}
$$

THEOREM 13 [19]. Let $\mathrm{g}(\mathrm{x}, \mathrm{y}) \in \mathrm{c}^{4, \lambda}(\partial \Omega), \phi(\mathrm{x}, \mathrm{y}, \mathrm{u}, \mathrm{p}, \mathrm{q}) \in \mathrm{c}^{2, \lambda}(\mathrm{G})$ and let the conditions (i), (ii) be fulfilled. Then the problem (63), (64) has at least one solution in $\mathrm{H}_{4}^{+}(\Omega)$.
*) The lower winding of the curve $z=\phi(x, y),(x, y) \in \partial \Omega$ is the number
$\left(x_{0}, y_{0}\right) \in \partial \Omega$ [inf $\left\{p^{2}+q^{2} ;(p, q) \in R^{2}\right.$ such that the plane $z=$. $=p\left(x-x_{0}\right)+q\left(y-y_{0}\right)+\phi\left(x_{0}, y_{0}\right)$ touches the curve from below]].
(see [18], p. 110).

REMARK 8. It follows from the imbedding theorems in the Sobolev spaces and from [17] that the solution whose existence is asserted in Theorem 13, belongs to $c^{4, \lambda}(\bar{\Omega})$.

We will show how to reduce the problem (63), (64) to a nonlinear operator equation. It follows from [18] and [17] that under the assumptions of Theorem 13, solutions of the problem

$$
\begin{gather*}
u_{x x} u_{y y}-u_{x y}^{2}=  \tag{66}\\
\tau \phi\left(x, y, u, \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}\right)+(1-\tau) \Phi\left(x^{2}+y^{2}\right) f\left(|\nabla u|^{2}\right), \\
(x, y) \in \Omega,  \tag{67}\\
\\
\left.u\right|_{\partial \Omega}=\tau g(x, y),
\end{gather*}
$$

which belong to $H_{4}^{+}(\Omega)$, satisfy the apriori estimate $\|u\|_{4} \leq k$ with a certain positive constant $k$, provided $0 \leq \tau \leq 1$. Here and in what follows $\|\cdot\|_{\ell}$ stands for the norm in $W_{2}^{\bar{l}}(\Omega)$.

Let $h(x, y) \in W_{2}^{4}(\Omega)$ be a harmonic function in $\Omega$ satisfying the boundary value condition (64). In $x=W_{2}^{4}(\Omega) \cap \stackrel{\circ}{W}_{2}^{1}(\Omega)$ let us define a domain $D$ by

$$
D=\left\{v=u-\tau h: u \in H_{4}^{+}(\Omega),\|u \mid\|_{4}<k+1,0 \leqq \tau \leqq 1\right\}
$$

For $v \in D$ we consider the parametric family of differential equations

$$
\begin{align*}
& F_{\tau}\left(x, y, v, \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y}, \frac{\partial^{2} v}{\partial x^{2}}, \frac{\partial^{2} v}{\partial x \partial y}, \frac{\partial^{2} v}{\partial y^{2}}\right)=\left(v_{x x}+\tau h_{x x}\right)\left(v_{y y}+\tau h_{y y}\right)-  \tag{68}\\
& -\left(v_{x y}+\tau h_{x y}\right)^{2}-\tau \phi\left(x, y, v+\tau h, \frac{\partial v}{\partial x}+\tau \frac{\partial h}{\partial x}, \frac{\partial v}{\partial y}+\tau \frac{\partial h}{\partial y}\right)- \\
& -(1-\tau) \Phi\left(x^{2}+y^{2}\right) f\left(|\nabla(v+\tau h)|^{2}\right)=0 .
\end{align*}
$$

By $N_{\bar{D}}$ we denote the set of solutions of the equation (68) which belong to $\bar{D}$. Then $N_{\bar{D}} \cap \partial D=\varnothing$.

Let $L_{\tau}(v)$ be a linear differential operator constructed for the function $F_{\tau}$ from (68) in an analogous way as the operator $L(v)$ was constructed for the function $F(x, \xi)$ in Chap. 2, Sec. 1. Consider the family of differential operators

$$
z=\left\{L_{\tau}(v): v \in N_{\bar{D}}, \tau \in[0,1]\right\}
$$

According to Theorem 11 we can construct a linear elliptic operator $M$ of the second order and an inner product $[$,$] in W_{2}^{2}(\Omega)$ so that

$$
\left[L_{\tau}(v) u, M u\right] \geqq C_{1}| | u\left|\left\|_{4}^{2}-c_{2}| | u\right\|_{0}^{2}\right.
$$

and

$$
-(M u, u) \geq c_{1}| | u \|_{1}^{2}
$$

Analogously to (62) we now define the family of nonlinear operators $A_{\tau}: \bar{D} \rightarrow X^{*}$

$$
\begin{equation*}
\left\langle A_{\tau} v, \phi\right\rangle=\left[F_{\tau}\left(x, y, v, \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y}, \frac{\partial^{2} v}{\partial x^{2}}, \frac{\partial^{2} v}{\partial x \partial y}, \frac{\partial^{2} v}{\partial y^{2}}\right), M \phi\right] . \tag{69}
\end{equation*}
$$

Analogously to Theorem 12 it is verified that $A_{\tau}$ are bounded demicontinuous operators and that the family of operators $A_{\tau}$ satisfies the condition $\left(\alpha_{0}^{(\tau)}\right)$. Since the equation $A_{\tau} u=0$ has no solution with $u \in \partial D$, we have $\operatorname{Deg}\left(A_{1}, \bar{D}, 0\right)=\operatorname{Deg}\left(A_{0}, \bar{D}, 0\right)$ by Theorem 1. For $\tau=0$ the equation (68) has a unique solution in $\bar{D}$. This solution represents a non-degenerate critical point of the field $A_{0}(v)$ (in the terminology of [8]). Hence $\operatorname{Deg}\left(A_{0}, \bar{D}, 0\right) \neq 0$ and the solvability of the problem (63), (64) is a consequence of Theorem 5.

REMARK 9. Using a topological method developed in [12], A. E. Siškov obtained apriori estimates and solvability for a more general boundary value problem, which results by adding a quasilinear second order elliptic operator to the left hand side of (63).
2. In this section we establish the existence of a classical solution of the Dirichlet problem for the general nonlinear elliptic equation in a narrow strip. By $\left\{\Omega_{h}, 0<h \leqq 1\right\}$ we denote the family of domains in $R^{n}$ with infinitely differentiable boundaries, such that
(a) $\Omega_{h_{1}} \subset \Omega_{h_{2}}$ for $h_{1}<h_{2}$;
(b) there are open coverings $\left\{U_{i}: i=1, \ldots, I\right\}$ of the set $\bar{\Omega}_{1}$ and diffeomorphisms $\phi_{i}: U_{i} \cap \bar{\Omega}_{1} \rightarrow R^{n}$ of the class $C^{\infty}$ satisfying $\phi_{i}\left(U_{i} \cap \bar{\Omega}_{h}\right)=S_{h}=\left\{x \in R^{n}:\left|x^{\prime}\right|<1,0 \leqq x_{n} \leqq h\right\}, \quad x=$ $=\left(x^{\prime}, x_{n}\right), x^{\prime}=\left(x_{1}, \ldots, x_{n-1}\right)$.

Let $\left\{\psi_{i}(x)\right\}, i=1, \ldots, I$ be a partition of unity subordinate to the covering.

For nonnegative integers $m, \ell, k$ and an arbitrary $p>1$ we denote by $W_{p}^{2 m, \ell, k}\left(\Omega_{h}\right)$ the closure of the set of functions infinitely differentiable in $\Omega_{h}$, with respect to the norm

$$
\|u\|_{w_{p}^{2 m, \ell, k}(\Omega)}^{p}=\left.\sum_{i=1}^{I}\left\|\psi_{i}\left(\phi_{i}^{-1}(y)\right) u\left(\phi_{i}^{-1}(y)\right)\right\|\right|_{W_{p}^{2 m}, \ell, k_{\left(S_{h}\right)}^{p}} ^{p}
$$

where

$$
\begin{aligned}
& \| v(y)| |_{w_{p}^{2 m}, \ell, k}^{p}\left(S_{h}\right) \\
& =\sum_{|\alpha| \leq 2 m} \int_{S_{h}}\left\{\sum_{j=0}^{k} \mid D_{n}^{\left.\left.j_{D} D^{\alpha} v(y)\right|^{p}+\sum_{|\beta| \leq \ell}^{\prime}\left|D^{\beta} D^{\alpha} v(y)\right|^{p}\right\} d y .}\right.
\end{aligned}
$$

Here we use the usual multiindex notation; $\Sigma^{\prime \prime}$ indicates the summation over all multiindices with the last coordinate zero.

The space $c^{s, r, \lambda}\left(\Omega_{h}\right)$ for nonnegative integers $s, r$ and $\lambda \in$ $\varepsilon[0,1]$ consists of functions defined in $\Omega_{h}$ which have the finite norm

$$
\|u(x)\|_{C} s, r, \lambda\left(\Omega_{h}\right)=\max _{i} \| \psi_{i}\left(\phi_{i}^{-1}(y)\right) u{\left(\phi_{i}^{-1}(y)\right) \|}_{\|_{C}, \dot{r}, \lambda}^{\left(s_{h}\right)}
$$

where

$$
\|v(y)\|_{C^{s, r, \lambda}\left(S_{h}\right)}=\sum_{|\beta| \leqq s} \sum_{|\alpha| \leq r}^{\prime}\left\|D^{\beta} D^{\alpha} v(y)\right\|_{C} 0, \lambda\left(S_{h}\right)
$$

and $\|\cdot\|_{C^{0}, \lambda}$ is the current norm in the space of functions satisfying the Holder condition with the exponent $\lambda$.

In order to obtain apriori estimates of solutions of both linear and nonlinear equations in the domains $\Omega_{h}$ we shall need some inequalities which are connected with the imbedding and interpolation of the corresponding Sobolev spaces. We shall give only two of such estimates, in which the letter $k$ denotes a constant depending only on $\mathrm{n}, \mathrm{m}, \mathrm{l}$ and of the constants characterizing the differential properties of the functions $\phi_{i}, \psi_{i}$, which are assumed to be fixed.
 $\ell \geq \mathrm{n}+1,0<\lambda<\frac{1}{2}$ satisfies the estimate
(70) $\quad\|u(x)\|_{C^{2 m-1,2, \lambda}\left(\Omega_{h}\right)} \leq k h^{\frac{1}{2}-\lambda} \cdot\|u(x)\|_{w_{2}^{2 m, \ell, 0}\left(\Omega_{h}\right)}$.

LEMMA 9. An arbitrary function $\mathrm{u}(\mathrm{x}) \in \mathrm{W}_{2}^{2 \mathrm{~m}, \ell, 0}\left(\Omega_{\mathrm{h}}\right) \cap \stackrel{\circ}{\mathrm{W}}_{2}^{\mathrm{m}}\left(\Omega_{\mathrm{h}}\right) \cap$ $\cap \mathrm{w}_{2 l}^{2 \mathrm{~m}, 1,0}\left(\Omega_{\mathrm{h}}\right)$ satisfies estimate

$$
\begin{aligned}
& \left\|\left.u(x)\right|_{w_{2 \ell / r}^{2 m, r}, 0} ^{\frac{2 \ell}{r}}{\left(\Omega_{h}\right)}^{x} \leq \varepsilon\right\| u(x) \|_{W_{2}^{2 m, \ell, 0}\left(\Omega_{h}\right)}^{2}+ \\
& +k \varepsilon^{-\frac{\ell(r-1)}{\ell-r}}\|u(x)\|_{w_{2 \ell}^{2 m, 1,0}\left(\Omega_{h}\right)}^{2 \ell}
\end{aligned}
$$

with an arbitrary positive $\varepsilon$ and $1<r \leq \ell-1$.
Further, we give a coercive estimate for pairs of linear elliptic operators in $S_{h}$. This estimate differs from those of Chap. 3 by its uniformity for $h \in(0,1]$ and, on the other hand, by a special choice of the function space whose elements are involved in the estimate.

The next lemma in which we keep the notation from Chap. 3 for $\mathrm{z}_{2 \mathrm{~m}}^{\ell, \lambda}(\mathrm{A}, \mathrm{B}, \Omega)$ is of crucial importance for the estimates of solutions of the nonlinear problem as well as for the proof of the existence theorem.

LEMMA 10. There are constants $\mathbf{C}_{1}, \mathrm{C}_{2}$ depending only on $\mathbf{A}, \mathrm{B}$, $\mathrm{m}, \mathrm{n}, \ell, \lambda$, such that for $\mathrm{q}>\mathrm{C}_{1}, \rho>\mathrm{qC}_{1}$, an arbitrary operator $\mathrm{L}(\mathrm{x}, \mathrm{D}) \in \mathrm{z}_{2 \mathrm{~m}}^{1, \lambda}\left(\mathrm{~A}, \mathrm{~B}, \mathrm{~S}_{\mathrm{h}}\right)$ and an arbitrary function $\mathrm{u}(\mathrm{x}) \in$ $\in W_{2}^{2 m, l, 1}\left(S_{h}\right) \cap \dot{W}_{2}^{m}\left(S_{h}\right)$ that vanishes for $\left|x^{\prime}\right|$ close to one, the estimate

$$
\begin{align*}
& \int_{S_{h}}\left\{L(x, D) D_{n}^{\prime} u \cdot M(D) D_{n}^{\prime} u+\rho \sum_{|\alpha| \leq \ell^{\prime}}^{\prime} L(x, D) D^{\alpha} u \cdot M(D) D^{\alpha} u\right\} d x \geq  \tag{71}\\
& \geq \frac{A}{2} \int_{S_{h}}\left|D_{n}^{2 m+1} u\right|^{2} d x+\frac{\rho A}{2} \int_{S_{h}} \sum_{|\alpha| \leq \ell}^{\prime}\left|D^{\alpha} D_{n}^{2 m} u\right|^{2} d x+ \\
& \quad+C_{2} \rho q \sum_{|\alpha| \leq \ell}^{\sum_{n}^{\prime} \quad \sum_{\beta \mid=m} \sum_{|\gamma|=m}^{\prime} \int_{S_{h}}\left|D^{\alpha+\beta+\gamma} u\right|^{2} d x-} \\
& \quad-C(\rho, q) \int_{S_{h}} \sum_{|\alpha| \leq 2 m}\left|D^{\alpha} u\right|^{2} d x,
\end{align*}
$$

holds, where $M(D)=D_{n}^{2 m}+q\left[D_{1}^{2}+\ldots+D_{n-1}^{2}\right]^{m}$ and $C(\rho, q)$ is a constant depending only on $\mathrm{A}, \mathrm{B}, \mathrm{m}, \mathrm{n}, \lambda, \mathrm{p}, \mathrm{q} \cdot$

In the case of a homogeneous operator $L(x, D)$ with constant coefficients, the proof of Lemma 10 is close to that of Lemma 7, only it is based on uniform (with respect to $h$ ) interpolation inequalities.

In what follows we fix the number $\ell, \ell \geq n+1$. We will consider the solvability in $W_{2}^{2 m, l, 1}\left(\Omega_{h}\right)$ of the nonlinear Dirichlet problem

$$
\begin{align*}
& F\left(x, u, \ldots, D^{2 m_{u}} u\right)=f(x), \quad x \in \Omega_{h},  \tag{72}\\
& D^{\alpha} u=0, \quad x \in \partial \Omega_{h}, \quad|\alpha| \leq m-1 \tag{73}
\end{align*}
$$

The function $F(x, \xi)$ is assumed to be defined on $\bar{\Omega}_{1} \times R^{M(2 m)}$, to have continuous derivatives up to the order $l$ and to satisfy the uniform ellipticity condition

$$
\begin{equation*}
\sum_{|\alpha|=2 m} F_{\alpha}(x, \xi) \eta^{\alpha} \geq v|\eta|^{2 m} \tag{74}
\end{equation*}
$$

for $n \in \mathbb{R}^{n}$ with a positive constant $v$.
We shall assume that $F(x, 0)=0$, the function $f(x)$ belongs to the space $W_{2}^{0, \ell, 1}\left(\Omega_{1}\right) \cap C^{1, \lambda}\left(\bar{\Omega}_{1}\right)$ and

$$
\left|\left|f\left\|_{W_{2}^{0}, \ell, 1_{\left(\Omega_{1}\right)}}+\right\|\right| f\right|_{C^{1}, \lambda\left(\bar{\Omega}_{1}\right)} \leq R,\left.\quad| | F(x, \xi)\right|_{C_{\left(\bar{\Omega}_{1} \times B_{t}\right)}} \leq g(t)
$$

where $B_{t}=\left\{\xi \in M^{M(2 m)}:|\xi| \leq t\right\}$ and $g(t)$ is a nondecreasing positive function.

We include the problem (72), (73) in the parametric family of problems of the same type

$$
\begin{align*}
& \operatorname{tF}\left(x, u, \ldots, D^{2 m_{u}} u\right)+(1-t) L_{0} u=t f(x), \quad x \in \Omega_{h},  \tag{75}\\
& D^{\alpha} u=0, \quad x \in \partial \Omega_{h}, \quad|\alpha| \leq m-1 \tag{76}
\end{align*}
$$

where $L_{0}(D)=\sum_{|\alpha|=2 m} a_{\alpha} D^{\alpha}$ is a fixed elliptic operator with a constant of ellipticity $v$.

THEOREM 14. Let $u(x)$ be an arbitrary solution of the problem (75), (76) satisfying

$$
\begin{equation*}
\left||u(x)|_{c}^{2 m-1,2, \lambda}<1\right. \tag{77}
\end{equation*}
$$

Then there is a constant $N$ depending on $m, N, \ell, \nu, R$, meas $\Omega_{1}$ and on the functions $g(t), \phi_{i}, \psi_{i}$, such that

$$
\begin{equation*}
\|u(x)\|_{w_{2}^{2 m}, \ell, 1\left(\Omega_{h}\right)} \leqq N \tag{78}
\end{equation*}
$$

Proof of the theorem proceeds first by establishing an
estimate $\|u(x)\|_{C^{2 m}\left(\Omega_{h}\right)} \leq C$ with a constant $C$ depending only on the known parameters, and then by proving the estimate (78) via Lemmas 8-10.

The proof of the existence theorem is based on the application of the methods from Chap. 1 , with the choice of $x=W_{2}^{2 m, l, 1}\left(\Omega_{h}\right) \cap$ $\cap \stackrel{\circ}{{\underset{W}{2}}_{2}^{m}}\left(\Omega_{h}\right), \quad D=\left\{u \in X:\|u\|_{W_{2}}^{\left.2 m, \ell, 1_{\left(\Omega_{h}\right)} \leq N+1\right\} \text {, where }}\right.$ the number $N$ is defined in Theorem 14. For $x \in \underset{i}{U} \cap \bar{\Omega}_{h}$ we pass from the variable $x$ to the new variable $y$ by the substitution $x=\phi_{i}^{-1}(y)$ and denote by $F_{i}, L_{i}$ the differential operators resulting from $F, L_{0}$ by the above change of variables. Consider the family of linear operators of the type

$$
L_{t}\left(y, D_{y}\right)=t \sum_{|\alpha| \leqq 2 m} F_{i, \alpha}\left(y, u_{i}, \ldots, D_{y}^{\left.2 m_{u_{i}}\right) D_{y}^{\alpha}+(1-t) L_{i}\left(y, D_{y}\right)}\right.
$$

for $u(x) \in D, u_{i}(y)=u\left(\phi_{i}^{-1}(y)\right)$.
It is easily verified that the set of such operators is contained in the family $\mathrm{z}_{2 \mathrm{~m}}^{1, \lambda}\left(\mathrm{~A}, \mathrm{~B}, \mathrm{~S}_{\mathrm{h}}\right)$ for certain values of $\mathrm{A}, \mathrm{B}$ and hence according to Lemma 10 the set considered can be associated with an operator $M(D)$ and constants $\rho, q$ such that (71) holds. In what follows, the numbers $\rho, q$ are assumed to be chosen in the just mentioned way.

We define a family of nonlinear operators $A_{t}: D \rightarrow X^{*}$ by the identity

$$
\begin{align*}
& \left\langle A_{t} u, v\right\rangle=\sum_{i=1}^{I} \int_{S_{h}} \psi_{i}^{2}(y)\left\{D _ { n } ^ { 1 } \left[t F _ { i } \left(y, u_{i}, \ldots, D_{y}^{\left.\left.2 m u_{i}\right) L_{i} u_{i}-t f_{i}(y)\right] D_{n}^{\prime} M v_{i}+}\right.\right.\right.  \tag{79}\\
& \left.\quad+\rho \sum_{|\alpha| \leq \ell}^{\prime} D^{\alpha}\left[t F_{i}\left(y, u_{i}, \ldots, D_{y}^{2 m_{i}} u_{i}\right)+(1-t) L_{i} u_{i}-t f_{i}(y)\right] D^{\alpha} M v_{i}\right\} d y .
\end{align*}
$$

LEMMA 11. The family of operators $A_{t}$ defined by (79) satisfies the condition ( $\alpha_{0}^{(t)}$ ).

The assertion follows from Lemma 10 and is verified analogously as the corresponding assertions of Chap. 2.

We choose a number $h_{0}>0$ so that

$$
\begin{equation*}
\operatorname{kh}_{0}^{\frac{1}{2}-\lambda}(N+1) \leq 1 \tag{80}
\end{equation*}
$$

where the numbers $k$, $N$ are defined in accordance with the inequalities (70), (78).

THEOREM 15. Let $0<h \leq h_{0}$, where $h_{0}$ is defined by the inequality (80). Then the problem (72), (73) has at least one solution, which belongs to $\mathrm{W}_{2}^{2 \mathrm{~m}, \ell, 1}\left(\Omega_{\mathrm{h}}\right)$.

Proof. By virtue of Theorem 5, in order to prove Theorem 15 it suffices to verify that
(a) the equation $A_{t} u=0$ has no solution $u \in \partial D$;
(b) $\operatorname{Deg}\left(A_{0}, \bar{D}, 0\right) \neq 0$.

We shall verify (a) by contradiction. Let $u \in \partial D$ and $A_{t} u=0$. Then $u$ is a solution of the problem (75), (76). Since $\|u\|_{W_{2} 2 m, \ell, 1_{\left(\Omega_{h}\right)}}=N+1$, the function $u(x)$ in virtue of Lemma 8 and the inequality (80) satisfies the inequality (77) and consequently, by Theorem 14 , the inequality (78) as well. The last inequality contradicts the condition $u \in \partial D$.

The validity of (b) follows, for instance, from Theorem 3. Thus the assertions (a), (b) and hence Theorem 15 are proved.
3. In conclusion we will present one result concerning the solvability of the model nonlinear Neumann problem. The result was obtain by A. E. Šiškov [20]. Consider the problem

$$
\begin{align*}
& L u \equiv\left(1+\left|\frac{\partial u}{\partial x}\right|^{2}\right) \frac{\partial^{2} u}{\partial x^{2}}+2 \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} \frac{\partial^{2} u}{\partial x \partial y}+\left(1+\left(\frac{\partial u}{\partial y}\right)^{2}\right) \frac{\partial^{2} u}{\partial y^{2}}-  \tag{81}\\
&-a\left(u,\left(\frac{\partial u}{\partial x}\right)^{2}+\left(\frac{\partial u}{\partial y}\right)^{2}\right)-f(x, y)=0, \quad(x, y) \in \Omega \\
& B u \equiv \frac{\partial u}{\partial n} \exp \left[\frac{1}{2}\left(1+\left|\frac{\partial u}{\partial x}\right|^{2}+\left|\frac{\partial u}{\partial y}\right|^{2}\right)\right]-b(x, y, u)=0,  \tag{82}\\
&(x, y) \in \partial \Omega
\end{align*}
$$

Here $\Omega$ is a circle $x^{2}+y^{2} \leqq R^{2}, n$ the interior normal to $\partial \Omega$, $a(u, t), f(x, y), b(x, y, u)$ functions of the class $c^{1, \alpha}$ with respect to all their arguments.

The interest in problems of the type (81), (82) is caused by the fact that in the general case of non-divergent equations, for such problems no apriori estimates of solution are known, and hence no general theory has been developed for such problems. In particular, as concerns the very problem (81), (82), the condition of uniform ellipticity is not valid and, secondly, when attempting to reduce the problem to the divergent form, we obtain equations not covered by the theory developed in [3].

Let us include the problem (81), (82) in the parametric family of problems of the same type

$$
\begin{align*}
& t\left(\Delta u-C_{1} u\right)+(1-t) L u=0  \tag{83}\\
& t\left[\frac{\partial u}{\partial n}-c_{1} u\right]+\left.(1-t) B u\right|_{\partial \Omega}=0 \tag{84}
\end{align*}
$$

where $C_{1}$ is a positive constant, $\Delta$ the Laplace operator, $t \in$ $\in[0,1]$.

Apriori estimates for the problem (83), (84) are given in the following lemma.

LEMMA 12. Let there exist positive constants C and $\mathrm{R}, \mathrm{R}_{1}$ such that
(a) $[a(u, 0,0)+f(x, y)] u>0$ for $|u|>R$;
(b) $\frac{\partial b(x, y, u)}{\partial u} \geqq C$;
(c) $\frac{\partial a(u, t)}{\partial u} \geqq C$ for, $t>R_{1}$.

Then every solution $u(x, y)$ of the problem (83), (84) satisfies the estimate

$$
\left||u|_{C^{1}(\Omega)} \leqq M\right.
$$

with a constant $M$ depending only on the known parameters.
The estimate of $u(x, y)$ in $c^{1}$ enables us to obtain (by the methods from [3]) an apriori estimate of the solution in $C^{2, \alpha}(\Omega)$ and, applying the general scheme from Sec. 2 , we easily obtain the existence theorem.

THEOREM 16. For any $\mathrm{p}>\mathrm{n}$, the problem (81), (82) has at least one solution belonging to $W_{p}^{2}(\Omega)$, provided the assumptions of Lemma 12 are fulfilzed.

## 5. Topological characteristics of general nonlinear parabolic boundary value problems

We shall only sketch the method of reducing general nonlinear parabolic problems to operator equations satisfying the condition $\left(\alpha_{0}\right)$. We will consider only equations solved with respect to the time derivative, even if this is no essential restriction.

In what follows we shall deal with the problem

$$
\begin{align*}
& \frac{\partial u}{\partial t}-F\left(x, t, u, \ldots, D_{x}^{2 m_{u}} u\right)=f(x, t), \quad(x, t) \in Q=\Omega \times\left(0, T_{0}\right),  \tag{85}\\
& G_{j}\left(x, t, u, \ldots, D_{x}^{m} j_{u}\right)=g_{j}(x, t), \quad \begin{array}{l}
j=1, \ldots, m, \\
(x, t) \in S=\partial \Omega \times\left(0, T_{0}\right)
\end{array}
\end{align*}
$$

(87)

$$
\left.u\right|_{t=0}=0, \quad x \in \Omega,
$$

where $\Omega$ is a bounded domain in $\cdot \mathrm{R}^{\mathrm{n}}$ with an infinitely differentiable boundary $\partial \Omega$. Let $\ell_{0}=\max \left\{2 m, m_{1}, \ldots, m_{m}\right\}$. The methods developed above enable us to investigate the solvability of the problem (85) - (87) in the space $W_{p}^{2 m k, k}(Q)$ with $\left(2 m k-\ell_{0}\right) p>n+2 m$ (the definition of this space is given e.g. in [21]). We restrict our considerations in this chapter to the Hilbert case, that is, $p=2$, as being the simplest possible. Analogously to Chap. 2 we can introduce operators corresponding to the problem (85) - (87) with an arbitrary p , which in particular enables us to weaken the assumptions concerning the smoothness of the functions $F, G_{j}$ and the order of the compatibility.

We introduce the following assumptions:
(i) The functions $F(x, \xi), G_{j}(y, t, \eta), j=1, \ldots, m_{M}$, are defined for $(x, t) \in \bar{Q},(y, t) \in S, \xi \in \mathbb{R}^{M(2 m)}, \eta \in R^{M\left(m_{j}\right)}$ and belong to the classes $c^{\ell-2 m+1}, C^{\ell-m_{j}+1}$, respectively, with some $k$ and $2 m \ell>\ell_{0}+m+\frac{n}{2}$. The functions $f(x, t), g(y, t)$ belong respectively to

(ii) For any function $v \in W_{2}^{2 m \ell, \ell}(Q)$ the operator

$$
\begin{equation*}
\Lambda(v)=\frac{\partial}{\partial t}-\sum_{|\alpha| \leq 2 m} F_{\alpha}\left(x, t, v, \ldots, D_{x}^{2 m} v\right) D^{\alpha} \tag{88}
\end{equation*}
$$

is parabolic; $\Lambda(v)$ and the boundary value operators

$$
\begin{equation*}
r_{j}(v)=\sum_{|\beta| \leqq m_{j}} G_{j, \beta}\left(x, t, v, \ldots, D_{x}^{m_{j}}{ }_{v}\right) D^{\beta}, \quad j=1, \ldots, m \tag{89}
\end{equation*}
$$

satisfy the "complementarity condition" (see e.g. [21], §9, Chap. VII), which represents an analogue of the Ya. B. Lopatinskiy condition for the parabolic case.
(iii) For $x \in \bar{\Omega}, y \in \partial \Omega$ the conditions
(90)

$$
F(x, t, 0, \ldots, 0)=0, \quad G_{j}(y, t, 0, \ldots, 0)=0, \quad t \in[0, T],
$$

$$
\begin{equation*}
\left.\frac{\partial^{i}}{\partial t^{i}} f(x, t)\right|_{t=0}=0, \frac{\partial^{i}}{\partial t^{i}} g_{j}(y, t)=0, i \leq \ell-1 \tag{91}
\end{equation*}
$$

are satisfied.
The conditions (90), (91) guarantee the compatibility of the data of the problem (85) - (87). If (90), (91) are fulfilled, then the solvability of the problem (85) - (87) can be considered in the space

$$
W_{0}^{2 m \ell, \ell}(Q)=\left\{u \in W_{2}^{2 m \ell, \ell}(Q):\left.\frac{\partial^{i} u}{\partial t^{i}}\right|_{t=0}=0, i \leq \ell-1\right\}
$$

Let us introduce the operator $A: W_{0}^{2 m \ell, \ell}(Q) \rightarrow\left[W_{2}^{2 m \ell, \ell}(Q)\right]^{*}$ by the identity

$$
\begin{align*}
& \left\langle A u, \phi>=\left(\frac{\partial u}{\partial t}-F\left(x, t, u, \ldots, D_{x}^{2 m} u\right)-f(x, t), \Lambda(u) \phi\right)_{2 m(\ell-1), Q}+\right.  \tag{92}\\
& \quad+\sum_{j=1}^{m}\left(G_{j}\left(x, t, u, \ldots, D_{x}^{m_{j}}\right)-g_{j}(x, t), \Gamma_{j}(u) \phi\right)_{2 m \ell-m_{j}-\frac{3}{2}, s},
\end{align*}
$$

where the symbols $(., .)_{\ell, Q}$ and $(., .)_{\ell, s}$ denote the scalar products in the spaces $\mathrm{w}_{2}^{\ell, \frac{\ell}{2 m}}(Q), \mathrm{w}_{2}^{\ell, \frac{\ell}{2 m}}(\mathrm{~S})$, respectively, while the operators $\Lambda(u), r_{j}(u)$ are defined by the identities (88), (89).

Employing the apriori estimates of solutions of linear parabolic problems [21] we establish

THEOREM 17. Assume that the conditions (i) - (iii) are fulfilled and that the numbers $\frac{1}{2 m}\left(2 m \ell-m_{j}-\frac{1}{2}\right)-\frac{1}{2}$ are nonintegers. Then the operator A defined by (92) is continuous, bounded and satisfies the condition $(S)_{+} \cdot$

From the result of Chap. 1 and from Theorem 17 it follows that the degree $\operatorname{Deg}(A, \bar{D}, 0)$ is determined for an arbitrary bounded domain $D$ in $W_{0}^{2 m \ell, \ell(Q)}$ such that there are no solutions of the problem (85) - (87) on $\partial D$. By applying the theorems on solvability of operator equations given in Chap. 1 it is possible to obtain an analogous assertion for the problem (85) - (87). In particular, it is easy to formulate the existence theorem for the problem (85) - (87) provided a certain apriori estimate is available.

Let us mention only one of the results that holds, generally speaking, only in the parabolic case, and that follows from Theorem
I. 7 in [10] on the invariance of the domain for locally one-to-one mappings satisfying the condition ( $\alpha_{0}$ ).

THEOREM 18. The set of $\left(f, g_{1}, \ldots, g_{m}\right)$ for which the problem (85) (37) has a solution under the assumptions of Theorem 17, is open in

$$
{\underset{o}{W}}_{2 m(\ell-1), \ell-1}^{2}(Q) \times \prod_{j=1}^{m} W_{2}^{2 m \ell-m_{j}-\frac{1}{2}, \ell-\frac{1}{2 m}\left(m_{j}+\frac{1}{2}\right)}(S)
$$

For the Dirichlet boundary value problem the construction of the operator A can be simplified analogously to the elliptic case from Chap. 3. We restrict ourselves to the case of homogeneous boundary value problems

$$
\begin{equation*}
D_{x}^{\alpha} u(x, t)=0, \quad|\alpha| \leq m-1, \quad(x, t) \in S . \tag{93}
\end{equation*}
$$

We denote by $x$ the subspace of the space ${ }^{\circ} W_{2}^{2 m}, \ell(Q)$ formed by the functions satisfying the condition (93).

THEOREM 19. Assume that a function $F(x, t, \xi)$ satisfies the conditions that follow from (i) - (iii) for an integer $\ell$ such that $2 \mathrm{~m} \ell>\frac{\mathrm{n}}{2}+1$. Let $\mathrm{f}(\mathrm{x}, \mathrm{t})$ satisfy the conditions (91) and let $\frac{1}{2 m}\left(2 m \ell-m_{j}-\frac{1}{2}\right)-\frac{1}{2}$ be noninteger. Then for an arbitrary bounded domain D in X there exists a linear parabolic operator

$$
P=\frac{\partial}{\partial t}-\sum_{|\alpha| \leq 2 m} m_{\alpha}(x, t) D^{\alpha}, \quad(x, t) \in \bar{Q}
$$

with infinitely differentiable coefficients, such that the operator $\mathrm{A}: \mathrm{D} \rightarrow \mathrm{X}^{*}$ given by
$\langle A u, \phi\rangle=\left[\frac{\partial u}{\partial t}-F\left(x, t, u, \ldots, D_{x}^{2 m} u\right)-f(x, t), P \phi\right]_{2 m(\ell-1), Q}$
is continuous, bounded and satisfies the condition (S) ${ }_{+}$. Here $[., \cdot]_{2 \mathrm{~m}(1-\ell), \mathrm{Q}}$ is a certain inner product in $\mathrm{W}_{2}^{2 \mathrm{~m}(\ell-1), \ell-1}(\mathrm{Q})$.

The existence of the operator $P$ is guaranteed by the results of the author and A. E. Šiškov. An explicit formula can be given for the operator $P$ as well as for the inner product $[\cdot, \cdot]_{2 m(\ell-1), Q}$.
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