## Czechoslovak Mathematical Journal

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Czechoslovak Mathematical Journal, Vol. 24 (1974), No. 1, 97-106

Persistent URL: http://dml.cz/dmlcz/101220

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# ON A GROUP OF HOLOMORPHIC TRANSFORMATIONS IN $\mathscr{C}^{2}$ 

Alois Švec, Praha

(Received January 23, 1973)
0. Consider the space $\mathscr{C}^{2}$ with the complex coordinates $(x, y)$ and let $V$ be the layer of real hypersurfaces given by

$$
\begin{equation*}
i(y-\bar{y})+(x-\bar{x})^{2}=r, \quad r \in \mathscr{R} . \tag{0.1}
\end{equation*}
$$

Each hypersurface of $V$ has a non-degenerate Levi form at each its point. The Lie group

$$
\begin{gather*}
X=\alpha x+\beta, \quad Y=2 i \alpha(\beta-\bar{\beta}) x+i \alpha(\alpha-\bar{\alpha}) x^{2}+\alpha \bar{\alpha} y+\gamma ;  \tag{0.2}\\
\alpha, \beta, \gamma \in \mathscr{C} ;
\end{gather*}
$$

of the biholomorphic mappings of $\mathscr{C}^{2}$ preserves $V$, the hypersurface $(0.1)$ with the parameter $r$ being transformed into the hypersurface ( 0.1 ) with the parameter

$$
\begin{equation*}
r^{\prime}=\frac{1}{\alpha \bar{\alpha}}\left\{r+i(\bar{\gamma}-\gamma)-(\beta-\bar{\beta})^{2}\right\} . \tag{0.3}
\end{equation*}
$$

Obviously, $\operatorname{dim}_{\mathscr{R}} G=6$. We are going to prove the following
Theorem. Let V be a layer of real hypersurfaces in $\mathscr{C}^{2}$ such that each hypersurface of $V$ has a non-degenerate Levi form. Let $G$ be a Lie group of biholomorphic transformations of $\mathscr{C}^{2}$ which is transitive on $\mathscr{C}^{2}$ and preserves the layer $V$. Then $4 \leqq$ $\leqq \operatorname{dim} G \leqq 6$. In the case $\operatorname{dim} G=6$ there are, in $\mathscr{C}^{2}$, holomorphic coordinates $(x, y)$ such that $G$ is given by (0.2) and $V$ by (0.1).

1. Be given a differentiable manifold $M^{2 n}$ and an almost complex structure $J$ over it; all manifolds and maps are supposed to be of class $C^{\infty}$. The torsion of $J$ is defined as the vector 2 -form [ $J, J$ ] given by

$$
\begin{equation*}
\frac{1}{2}[J, J](u, v)=[J u, J v]-J[J u, v]-J[u, J v]-[u, v] . \tag{1.1}
\end{equation*}
$$

On $M^{2 n}$, let us choose vector fields $v_{\alpha}, v_{n+\alpha} ; \alpha=1, \ldots, n$; such that

$$
\begin{equation*}
J v_{\alpha}=v_{n+\alpha}, \quad J v_{n+\alpha}=-v_{\alpha} ; \quad \alpha=1, \ldots, n ; \tag{1.2}
\end{equation*}
$$

and write

$$
\begin{align*}
& {\left[v_{\alpha}, v_{\beta}\right]=a_{\alpha \beta}^{\gamma} v_{\gamma}+a_{\alpha \beta}^{n+\gamma} v_{n+\gamma},}  \tag{1.3}\\
& {\left[v_{\alpha}, v_{n+\beta}\right]=a_{\alpha, n+\beta}^{\gamma} v_{\gamma}+a_{\alpha, n+\beta}^{n+\gamma} v_{n+\gamma},} \\
& {\left[v_{n+\alpha}, v_{n+\beta}\right]=a_{n+\alpha, n+\beta}^{\gamma} v_{\gamma}+a_{n+\alpha, n+\beta}^{n+\gamma} v_{n+\gamma} .}
\end{align*}
$$

For

$$
\begin{equation*}
u=x^{\alpha} v_{\alpha}-x^{n+\alpha} v_{n+\alpha}, \quad v=y^{\alpha} v_{\alpha}-y^{n+\alpha} v_{n+\alpha} \tag{1.4}
\end{equation*}
$$

we obtain

$$
\begin{gather*}
\frac{1}{2}[J, J](u, v)=  \tag{1.5}\\
=\left(a_{n+\alpha, n+\beta}^{\gamma}-a_{\alpha \beta}^{\gamma}+a_{\alpha, n+\beta}^{n+\gamma}-a_{\beta, n+\alpha}^{n+\gamma}\right) . \\
\cdot\left\{\left(x^{\alpha} y^{\beta}-x^{n+\alpha} y^{n+\beta}\right) v_{\gamma}+\left(x^{\alpha} y^{n+\beta}+x^{n+\alpha} y^{\beta}\right) v_{n+\gamma}\right\}+ \\
+\left(a_{\alpha \beta}^{n+\gamma}-a_{n+\alpha, n+\beta}^{n+\gamma}+a_{\alpha, n+\beta}^{\gamma}-a_{\beta, n+\alpha}^{\gamma}\right) . \\
\cdot\left\{\left(x^{\alpha} y^{n+\beta}+x^{n+\alpha} y^{\beta}\right) v_{\gamma}-\left(x^{\alpha} y^{\beta}-x^{n+\alpha} y^{n+\beta}\right) v_{n+\gamma}\right\} .
\end{gather*}
$$

The condition $[J, J]=0$ is thus equivalent to

$$
\begin{gather*}
a_{n+\alpha, n+\beta}^{\gamma}-a_{\alpha \beta}^{\gamma}+a_{\alpha, n+\beta}^{n+\gamma}-a_{\beta, n+\alpha}^{n+\gamma}=0,  \tag{1.6}\\
a_{\alpha \beta}^{n+\gamma}-a_{n+\alpha, n+\beta}^{n+\gamma}+a_{\alpha, n+\beta}^{\gamma}-a_{\beta, n+\alpha}^{\gamma}=0 ; \quad \alpha, \beta, \gamma=1, \ldots, n .
\end{gather*}
$$

The following result is classic: Be given a manifold $M^{2 n}$, the almost complex structure $J$ over $M^{2 n}$ be given by means of the vector fields $v_{\alpha}, v_{n+\alpha}$ and (1.2); the structure $J$ is complex if and only if (1.6).
2. Consider a manifold $M^{4}$, a complex structure $J$ over $M^{4}$, and let $V$ be a layer of hypersurfaces in $M^{4}$. At each point $m \in M^{4}$, let us choose vectors $v_{1}, \ldots, v_{4} \in T_{m}\left(M^{4}\right)$ such that: (i) $v_{1}, v_{2}, v_{3}$ are tangent to the hypersurface of $V$ going through $m$, (ii) $J v_{1}=$ $=v_{3}, J v_{2}=v_{4}$. (iii) the vector fields $v_{1}, \ldots, v_{4}$ are of class $C^{\infty}$. The vector fields $w_{1}, \ldots, w_{4}$ satisfying (i)-(iii) as well, there are real-valued functions $\alpha, \beta, \gamma, \varphi, \delta$ on $M^{4}$ such that

$$
\begin{array}{ll}
v_{1}=\alpha w_{1}-\beta w_{3}, & v_{2}=\gamma w_{1}+\varphi w_{2}-\delta w_{3}  \tag{2.1}\\
v_{3}=\beta w_{1}+\alpha w_{3}, & v_{4}=\delta w_{1}+\gamma w_{3}+\varphi w_{4} ; \quad\left(\alpha^{2}+\beta^{2}\right) \varphi \neq 0
\end{array}
$$

The complex structure $J$ together with the layer $V$ induce a $G$-structure $B_{G}$ on $M^{4}$, the group $G$ being the set of non-singular matrices of the type

$$
\left(\begin{array}{rrrr}
\alpha & 0 & -\beta & 0  \tag{2.2}\\
\gamma & \varphi & -\delta & 0 \\
\beta & 0 & \alpha & 0 \\
\delta & 0 & \gamma & \varphi
\end{array}\right)
$$

Let us write

$$
\begin{align*}
& {\left[v_{1}, v_{2}\right]=a_{1} v_{1}+a_{2} v_{2}+a_{3} v_{3},}  \tag{2.3}\\
& {\left[v_{1}, v_{3}\right]=b_{1} v_{1}+b_{2} v_{2}+b_{3} v_{3},} \\
& {\left[v_{1}, v_{4}\right]=c_{1} v_{1}+c_{2} v_{2}+c_{3} v_{3}+c_{4} v_{4},} \\
& {\left[v_{2}, v_{3}\right]=d_{1} v_{1}+d_{2} v_{2}+d_{3} v_{3},} \\
& {\left[v_{2}, v_{4}\right]=e_{1} v_{1}+e_{2} v_{2}+e_{3} v_{3}+e_{4} v_{4},} \\
& {\left[v_{3}, v_{4}\right]=f_{1} v_{1}+f_{2} v_{2}+f_{3} v_{3}+f_{4} v_{4} ;}
\end{align*}
$$

the conditions (1.6) reduce to

$$
\begin{align*}
f_{1}-a_{1}+c_{3}-d_{3}= & 0, \quad f_{2}-a_{2}+c_{4}=0, \quad a_{3}-f_{3}+c_{1}-d_{1}=0,  \tag{2.4}\\
& f_{4}-c_{2}+d_{2}=0
\end{align*}
$$

Analoguously, let us write

$$
\begin{gather*}
{\left[w_{1}, w_{2}\right]=A_{1} w_{1}+A_{2} w_{2}+A_{3} w_{3}}  \tag{2.5}\\
\quad \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \\
{\left[w_{3}, w_{4}\right]=F_{1} w_{1}+F_{2} w_{2}+F_{3} w_{3}+F_{4} w_{4}}  \tag{2.6}\\
F_{1}-A_{1}+C_{3}-D_{3}=0, \quad F_{2}-A_{2}+C_{4}=0, \\
A_{3}-F_{3}+C_{1}-D_{1}=0, \quad F_{4}-C_{2}+D_{2}=0
\end{gather*}
$$

From (2.3 $),\left(2.5_{2}\right)$ and (2.1), we get

$$
\begin{gathered}
{\left[v_{1}, v_{3}\right]=\left[\alpha w_{1}-\beta w_{3}, \beta w_{1}+\alpha w_{3}\right]=(\cdot) w_{1}+(\cdot) w_{3}+\left(\alpha^{2}+\beta^{2}\right) B_{2} w_{2}=} \\
=(\cdot) w_{1}+(\cdot) w_{3}+b_{2} \varphi w_{2}
\end{gathered}
$$

i.e.,

$$
\begin{equation*}
\left(\alpha^{2}+\beta^{2}\right) B_{2}=\varphi b_{2} . \tag{2.7}
\end{equation*}
$$

It is easy to see that $b_{2} \neq 0$ because of the non-degeneracy of the Levi forms of the hypersurfaces of $V$. Thus we are in the position to choose the frames $\left(v_{1}, \ldots, v_{4}\right)$ of the $G$-structure $B_{G}$ in such a way that

$$
\begin{equation*}
b_{2}=1 ; \tag{2.8}
\end{equation*}
$$

from $B_{2}=b_{2}=1$, we get

$$
\begin{equation*}
\varphi=\alpha^{2}+\beta^{2} . \tag{2.9}
\end{equation*}
$$

Further,

$$
\begin{gathered}
{\left[v_{1}, v_{4}\right]=\left[\alpha w_{1}-\beta w_{3}, \delta w_{1}+\gamma w_{3}+\varphi w_{4}\right]=} \\
=(\cdot) w_{1}+(\cdot) w_{3}+(\cdot) w_{4}+\left(\alpha \gamma+\beta \delta+\alpha \varphi C_{2}-\beta \varphi F_{2}\right) w_{2}= \\
=(\cdot) w_{1}+(\cdot) w_{3}+(\cdot) w_{4}+c_{2} \varphi w_{2} \\
{\left[v_{3}, v_{4}\right]=\left[\beta w_{1}+\alpha w_{3}, \delta w_{1}+\gamma w_{3}+\varphi w_{4}\right]=} \\
=(\cdot) w_{1}+(\cdot) w_{3}+(\cdot) w_{4}+\left(\beta \gamma-\alpha \delta+\beta \varphi C_{2}+\alpha \varphi F_{2}\right) w_{2}= \\
=(\cdot) w_{1}+(\cdot) w_{3}+(\cdot) w_{4}+f_{2} \varphi w_{2},
\end{gathered}
$$

i.e.,

$$
\begin{align*}
& \alpha \gamma+\beta \delta+\alpha \varphi C_{2}-\beta \varphi F_{2}=\varphi c_{2},  \tag{2.10}\\
& \beta \gamma-\alpha \delta+\beta \varphi C_{2}+\alpha \varphi F_{2}=\varphi f_{2} .
\end{align*}
$$

The frames of $B_{G}$ may be chosen in such a way that (2.8) and

$$
\begin{equation*}
c_{2}=f_{2}=0 \tag{2.11}
\end{equation*}
$$

and we get

$$
\begin{equation*}
\gamma=\delta=0 \tag{2.12}
\end{equation*}
$$

Further,

$$
\begin{gathered}
{\left[v_{2}, v_{4}\right]=\left[\varphi w_{2}, \varphi w_{4}\right]=} \\
=\varphi w_{2} \varphi \cdot w_{4}-\varphi w_{4} \varphi \cdot w_{2}+\varphi^{2}\left(E_{1} w_{1}+E_{2} w_{2}+E_{3} w_{3}+E_{4} w_{4}\right)= \\
=e_{1}\left(\alpha w_{1}-\beta w_{3}\right)+e_{2} \varphi w_{2}+e_{3}\left(\beta w_{1}+\alpha w_{3}\right)+e_{4} \varphi w_{4},
\end{gathered}
$$

i.e.,

$$
\begin{equation*}
\varphi^{2} E_{1}=\alpha e_{1}+\beta e_{3}, \varphi^{2} E_{3}=-\beta e_{1}+\alpha e_{3} \tag{2.13}
\end{equation*}
$$

and

$$
\begin{equation*}
\varphi^{2}\left(E_{1} w_{1}+E_{3} w_{3}\right)=e_{1} v_{1}+e_{3} v_{3} . \tag{2.14}
\end{equation*}
$$

The direction of the vector $e_{1} v_{1}+e_{3} v_{3}$ is thus invariant. Suppose that $e_{1} v_{1}+$ $+e_{3} v_{3} \neq 0$. The frames $\left(v_{1}, \ldots, v_{4}\right) \in B_{G}$ may be chosen in such a way that

$$
\begin{equation*}
e_{1}=1, \quad e_{3}=0 \tag{2.15}
\end{equation*}
$$

This means

$$
\begin{equation*}
\alpha=1, \quad \beta=0, \quad \varphi=1 \tag{2.16}
\end{equation*}
$$

and the induced structure $B_{G}$ is reduced to the $\{e\}$-structure $B_{\{e\}}$. Denote by $G(V)$ the group of biholomorphic transformations of $\mathscr{C}^{2}$ preserving $V$. Obviously, $G(V)$ preserves the induced $G$-structure $B_{G}$ and the reduced structure $B_{\{e\}}$. In our case $\operatorname{dim} G(V) \leqq 4$.

If $\operatorname{dim} G(V)>4$, we should have

$$
\begin{equation*}
e_{1}=e_{3}=0 \tag{2.17}
\end{equation*}
$$

i.e.,

$$
\begin{align*}
& {\left[v_{1}, v_{2}\right] }=a_{1} v_{1}+a_{2} v_{2}+a_{3} v_{3}  \tag{2.18}\\
& {\left[v_{1}, v_{3}\right] }=b_{1} v_{1}+v_{2}+b_{3} v_{3} \\
& {\left[v_{1}, v_{4}\right] }=c_{1} v_{1}+c_{3} v_{3}+a_{2} v_{4} \\
& {\left[v_{2}, v_{3}\right] }=d_{1} v_{1}+d_{2} v_{2}+d_{3} v_{3}, \\
& {\left[v_{2}, v_{4}\right] }=e_{2} v_{2}+e_{4} v_{4} \\
& {\left[v_{3}, v_{4}\right] }=f_{1} v_{1} \\
& f_{1}-a_{1}+c_{3}-d_{3} v_{3}-d_{2} v_{4}  \tag{2.19}\\
& 0, a_{3}-f_{3}+c_{1}-d_{1}=0
\end{align*}
$$

the admissible transformations of the frames are given by

$$
\begin{array}{ll}
v_{1}=\alpha w_{1}-\beta w_{3}, & v_{2}=\varphi w_{2},  \tag{2.20}\\
v_{3}=\beta w_{1}+\alpha w_{3}, & v_{4}=\varphi w_{4} ; \quad \varphi=\alpha^{2}+\beta^{2}
\end{array}
$$

From the Jacobi identities
(2.21) $\left[v_{i},\left[v_{j}, v_{k}\right]\right]+\left[v_{j},\left[v_{k}, v_{i}\right]\right]+\left[v_{k},\left[v_{i}, v_{j}\right]\right]=0 ; i, j, k=1,2,3,4 ;$
it follows

$$
\begin{align*}
& v_{1} d_{1}-v_{2} b_{1}+v_{3} a_{1}+\left(d_{2}+b_{1}\right) a_{1}+\left(d_{3}-a_{1}\right) b_{1}-\left(b_{3}+a_{2}\right) d_{1}=0,  \tag{2.22}\\
& v_{1} d_{2}+v_{3} a_{2}+\left(d_{2}+b_{1}\right) a_{2}+d_{3}-a_{1}-\left(b_{3}+a_{2}\right) d_{2}=0, \\
& v_{1} d_{3}-v_{2} b_{3}+v_{3} a_{3}+\left(d_{2}+b_{1}\right) a_{3}+\left(d_{3}-a_{1}\right) b_{3}-\left(b_{3}+a_{2}\right) d_{3}=0, \\
&-v_{2} c_{1}+v_{4} a_{1}+\left(e_{2}+c_{1}\right) a_{1}+\left(e_{4}-a_{1}\right) c_{1}-c_{3} d_{1}-a_{3} f_{1}=0, \\
& v_{1} e_{2}+v_{4} a_{2}+\left(e_{2}+c_{1}\right) a_{2}-c_{3} d_{2}-2 a_{2} e_{2}=0, \\
&-v_{2} c_{3}+v_{4} a_{3}+\left(e_{2}+c_{1}\right) a_{3}+\left(e_{4}-a_{1}\right) c_{3}-c_{3} d_{3}-a_{3} f_{3}=0, \\
& v_{1} e_{4}-v_{4} a_{2}+\left(e_{4}-a_{1}\right) a_{2}-2 a_{2} e_{4}+a_{3} d_{2}=0, \\
& v_{1} f_{1}-v_{3} c_{1}+v_{4} a_{1}+\left(f_{3}+c_{1}\right) b_{1}-\left(d_{2}+a_{1}\right) c_{1}-\left(a_{2}+a_{3}\right) f_{1}=0, \\
& v_{4} a_{2}+f_{3}+c_{1}-a_{2} e_{2}=0, \\
& v_{1} f_{3}-v_{3} c_{3}+v_{4} a_{3}+\left(f_{3}+c_{1}\right) b_{3}-\left(d_{2}+a_{1}\right) c_{3}-\left(a_{2}+a_{3}\right) f_{3}=0, \\
&-v_{1} d_{2}-v_{3} a_{2}-\left(d_{2}+a_{1}\right) a_{2}+\left(a_{2}+a_{3}\right) d_{2}-a_{2} e_{4}=0, \\
& v_{2} f_{1}+v_{4} d_{1}-f_{1} a_{1}+\left(f_{3}+e_{2}\right) d_{1}-\left(e_{4}+d_{3}\right) f_{1}-d_{1} c_{1}=0, \\
&-v_{3} e_{2}+v_{4} d_{2}-f_{1} a_{2}+\left(f_{3}+e_{2}\right) d_{2}-2 d_{2} e_{2}=0, \\
& v_{2} f_{3}+v_{4} d_{3}-f_{1} a_{3}+\left(f_{3}+e_{2}\right) d_{3}-\left(e_{4}+d_{3}\right) f_{3}-d_{1} c_{3}=0, \\
&-v_{2} d_{2}-v_{3} e_{4}-2 d_{2} e_{4}+\left(e_{4}+d_{3}\right) d_{2}-d_{1} a_{2}=0 .
\end{align*}
$$

From (2.18), the analoguous equations for $\left[w_{i}, w_{j}\right]$ and from (2.20), we get

$$
\begin{align*}
&-\varphi w_{2} \alpha+\alpha \varphi A_{1}+\beta \varphi D_{1}=\alpha a_{1}+\beta a_{3},  \tag{2.23}\\
& \varphi w_{2} \alpha-\beta \varphi A_{3}+\alpha \varphi D_{3}=-\beta d_{1}+\alpha d_{3}, \\
& \varphi w_{2} \beta+\alpha \varphi A_{3}+\beta \varphi D_{3}=-\beta a_{1}+\alpha a_{3}, \\
& \varphi w_{2} \beta-\beta \varphi A_{1}+\alpha \varphi D_{1}=\alpha d_{1}+\beta d_{3}, \\
&-\varphi w_{4} \alpha+\alpha \varphi C_{1}-\beta \varphi F_{1}=\alpha c_{1}+\beta c_{3}, \\
&-\varphi w_{4} \alpha+\beta \varphi C_{3}+\alpha \varphi F_{3}=-\beta f_{1}+\alpha f_{3}, \\
& \varphi w_{4} \beta+\alpha \varphi C_{3}-\beta \varphi F_{3}=-\beta c_{1}+\alpha c_{3}, \\
&-\varphi w_{4} \beta+\beta \varphi C_{1}+\alpha \varphi F_{1}=\alpha f_{1}+\beta f_{3}, \\
& \alpha w_{1} \varphi-\beta w_{3} \varphi+\alpha \varphi A_{2}+\beta \varphi D_{2}=\varphi a_{2},  \tag{2.24}\\
&-\beta w_{1} \varphi-\alpha w_{3} \varphi-\beta \varphi A_{2}+\alpha \varphi D_{2}=\varphi d_{2}, \\
& w_{2} \varphi+\varphi E_{4}=e_{4}, \quad-w_{4} \varphi+\varphi E_{2}=e_{2},  \tag{2.25}\\
& \alpha w_{1} \beta-\beta w_{3} \beta-\beta w_{1} \alpha-\alpha w_{3} \alpha+\varphi B_{1}=\alpha b_{1}+\beta b_{3},  \tag{2.26}\\
& \alpha w_{1} \alpha-\beta w_{3} \alpha+\beta w_{1} \beta+\alpha w_{3} \beta+\varphi B_{3}=-\beta b_{1}+\alpha b_{3} .
\end{align*}
$$

From $\left(2.23_{1,2}\right)+\left(2.23_{3,4}\right)$ and $\left(2.23_{5,6}\right)+\left(2.23_{7,8}\right)$, we get

$$
\begin{align*}
& \alpha \varphi\left(A_{1}+D_{3}\right)+\beta \varphi\left(D_{1}-A_{3}\right)=\alpha\left(a_{1}+d_{3}\right)-\beta\left(d_{1}-a_{3}\right),  \tag{2.27}\\
& \alpha \varphi\left(D_{1}-A_{3}\right)-\beta \varphi\left(A_{1}+D_{3}\right)=\alpha\left(d_{1}-a_{3}\right)+\beta\left(a_{1}+d_{3}\right), \\
& \alpha \varphi\left(C_{1}-F_{3}\right)-\beta \varphi\left(F_{1}+C_{3}\right)=\alpha\left(c_{1}-f_{3}\right)+\beta\left(f_{1}+c_{3}\right),  \tag{2.28}\\
& \alpha \varphi\left(F_{1}+C_{3}\right)+\beta \varphi\left(C_{1}-F_{3}\right)=\alpha\left(f_{1}+c_{3}\right)-\beta\left(c_{1}-f_{3}\right) .
\end{align*}
$$

The equations (2.28) are the consequence of (2.27) because of (2.19). From (2.27),

$$
\begin{equation*}
\varphi\left\{\left(A_{1}+D_{3}\right)^{2}+\left(D_{1}-A_{3}\right)^{2}\right\}=\left(a_{1}+d_{3}\right)^{2}+\left(d_{1}-a_{3}\right)^{2} \tag{2.29}
\end{equation*}
$$

Suppose

$$
\begin{equation*}
\left(a_{1}+d_{3}\right)^{2}+\left(d_{1}-a_{3}\right)^{2} \neq 0 . \tag{2.30}
\end{equation*}
$$

Thus we may choose the frames of $B_{G}$ in such a way that

$$
\begin{equation*}
\left(a_{1}+d_{3}\right)^{2}+\left(d_{1}-a_{3}\right)^{2}=1 \tag{2.31}
\end{equation*}
$$

i.e.,

$$
\begin{equation*}
\varphi=\alpha^{2}+\beta^{2}=1 \tag{2.32}
\end{equation*}
$$

We have $\operatorname{dim} G(V) \leqq 5$ because the system (2.23)-(2.26) is, in the best case, completely integrable.

## Suppose

$$
\begin{equation*}
d_{3}=-a_{1}, \quad d_{1}=a_{3} ; \tag{2.33}
\end{equation*}
$$

from (2.19), we obtain

$$
\begin{equation*}
f_{1}=-c_{3}, \quad f_{3}=c_{1} . \tag{2.34}
\end{equation*}
$$

From $\left(2.23_{1,3}\right)+\left(2.25_{1}\right)$ and $\left(2.23_{5,7}\right)+\left(2.25_{2}\right)$,

$$
\begin{equation*}
\varphi\left(2 A_{1}+E_{4}\right)=2 a_{1}+e_{4}, \quad \varphi\left(E_{2}-2 C_{1}\right)=e_{2}-2 c_{1} . \tag{2.35}
\end{equation*}
$$

Again, $2 a_{1}+e_{4} \neq 0$ or $e_{2}-2 c_{1} \neq 0$ implies $\operatorname{dim} G(V) \leqq 5$.
3. Finally, suppose (2.18) with

$$
\begin{equation*}
d_{3}=-a_{1}, \quad d_{1}=a_{3}, \quad f_{1}=-c_{3}, \quad f_{3}=c_{1}, \quad e_{4}=-2 a_{1}, \quad e_{2}=2 c_{1} . \tag{3.1}
\end{equation*}
$$

The equations (2.25) reduce to

$$
\begin{equation*}
w_{2} \varphi=2 \varphi A_{1}-2 a_{1}, \quad w_{4} \varphi=2 \varphi C_{1}-2 c_{1} . \tag{3.2}
\end{equation*}
$$

Consider the system

$$
\begin{equation*}
w_{2} \varphi=-2 a_{1}, \quad w_{4} \varphi=-2 c_{1} . \tag{3.3}
\end{equation*}
$$

Then $w_{4} w_{2} \varphi=-2 w_{4} a_{1}, w_{2} w_{4} \varphi=-2 w_{2} c_{1}$, and we get

$$
\left[w_{2}, w_{4}\right] \varphi=-2 w_{2} c_{1}+2 w_{4} a_{1}=2 c_{1} w_{2} \varphi-2 a_{1} w_{4} \varphi=-4 c_{1} a_{1}+4 a_{1} c_{1}=0
$$

by means of $\left(2.18_{5}\right)$. The integrability condition of the system (3.3) is $w_{2} c_{1}-w_{4} a_{1}=$ $=0$, i.e., $v_{2} c_{1}-v_{4} a_{1}=0$. This equation being satisfied because of $\left(2.22_{14}\right)$, the system (3.3) is completely integrable. It follows the possibility to choose the frames of $B_{G}$ such that $A_{1}=C_{1}=0$. Let us suppose

$$
\begin{equation*}
a_{1}=c_{1}=0 \tag{3.4}
\end{equation*}
$$

and

$$
\begin{equation*}
w_{2} \varphi=w_{4} \varphi=0 . \tag{3.5}
\end{equation*}
$$

From (2.23 $3_{3,7}$ ),

$$
\begin{equation*}
\varphi w_{2} \beta+\alpha \varphi A_{3}=\alpha a_{3}, \quad \varphi w_{4} \beta+\alpha \varphi C_{3}=\alpha c_{3} . \tag{3.6}
\end{equation*}
$$

Consider the system

$$
\begin{equation*}
v_{2} \beta=\alpha a_{3}, \quad v_{4} \beta=\alpha c_{3} . \tag{3.7}
\end{equation*}
$$

From (3.5) and (3.7), $v_{2} \alpha=-\beta a_{3}, v_{4} \alpha=-\beta c_{3}$, from (3.7) and (2.185), $v_{2} v_{4} \beta=$ $=-\beta a_{3} c_{3}+\alpha v_{2} c_{3}, v_{4} v_{2} \beta=-\beta c_{3} a_{3}+\alpha v_{4} a_{3}$. The integrability condition of (3.7) $0=\left[v_{2}, v_{4}\right] \beta=\alpha\left(v_{2} c_{3}-v_{4} a_{3}\right)$ is now satisfied because of $\left(2.22_{6}\right)$. The system (3.7) being integrable, we are in the position to choose the frames in such a way that $A_{3}=$ $=C_{3}=0$. Suppose

$$
\begin{equation*}
a_{3}=c_{3}=0 \tag{3.8}
\end{equation*}
$$

and, consequently,

$$
\begin{equation*}
w_{2} \alpha=w_{2} \beta=w_{4} \alpha=w_{4} \beta=0 . \tag{3.9}
\end{equation*}
$$

The condition $\operatorname{dim} G(V)>5$ for a layer $V$ implies the existence of sections $\left(v_{1}, \ldots, v_{4}\right)$ of $B_{G}$ such that

$$
\begin{array}{ll}
{\left[v_{1}, v_{2}\right]=a_{2} v_{2},} & {\left[v_{2}, v_{3}\right]=d_{2} v_{2},}  \tag{3.10}\\
{\left[v_{1}, v_{3}\right]=b_{1} v_{1}+v_{2}+b_{3} v_{3},} & {\left[v_{2}, v_{4}\right]=0,} \\
{\left[v_{1}, v_{4}\right]=a_{2} v_{4} ;} & {\left[v_{3}, v_{4}\right]=d_{2} v_{4} .}
\end{array}
$$

The equations (2.22) reduce to

$$
\begin{array}{ll}
v_{2} b_{1}=v_{2} b_{3}=0, & v_{2} a_{2}=v_{4} a_{2}=0, \quad v_{2} d_{2}=v_{4} d_{2}=0,  \tag{3.11}\\
v_{1} d_{2}+v_{3} a_{2}=0, & a_{2} d_{2}+a_{2} b_{1}-b_{3} d_{2}=0
\end{array}
$$

The equations (2.24) may be written as

$$
\begin{equation*}
v_{1} \varphi+\alpha \varphi A_{2}+\beta \varphi D_{2}=\varphi a_{2}, \quad-v_{3} \varphi-\beta \varphi A_{2}+\alpha \varphi D_{2}=\varphi d_{2} \tag{3.12}
\end{equation*}
$$

the equation (2.26) as

$$
\begin{equation*}
v_{1} \beta-v_{3} \alpha+\varphi B_{1}=\alpha b_{1}+\beta b_{3}, \quad v_{1} \alpha+v_{3} \beta+\varphi B_{3}=-\beta b_{1}+\alpha b_{3} \tag{3.13}
\end{equation*}
$$

The integrability condition of (3.12) is

$$
\begin{equation*}
a_{2} d_{2}=\varphi A_{2} D_{2} . \tag{3.14}
\end{equation*}
$$

The condition $a_{2} d_{2} \neq 0$ implies $\operatorname{dim} G(V) \leqq 5$. Suppose

$$
\begin{equation*}
a_{2}=0 \tag{3.15}
\end{equation*}
$$

the case $d_{2}=0$ being symmetric. Because of (3.11), the system $v_{1} \varphi=0, v_{3} \varphi=-\varphi d_{2}$ is integrable, and we may choose the frames of $B_{G}$ in such a way that

$$
\begin{equation*}
a_{2}=d_{2}=0 \tag{3.16}
\end{equation*}
$$

which implies

$$
\begin{equation*}
v_{1} \varphi=v_{3} \varphi=0 \tag{3.17}
\end{equation*}
$$

Then $\alpha v_{1} \alpha+\beta v_{1} \beta=\alpha v_{3} \alpha+\beta v_{3} \beta=0$, and we get

$$
\begin{equation*}
v_{1} \alpha=\alpha \beta B_{1}-\beta^{2} B_{3}-\beta b_{1}, \quad v_{3} \alpha=\beta^{2} B_{1}+\alpha \beta B_{3}-\beta b_{3} \tag{3.18}
\end{equation*}
$$

from (3.13). The integrability condition of (3.18) is

$$
\begin{equation*}
v_{1} b_{3}-v_{3} b_{1}-b_{1}^{2}-b_{3}^{2}=\varphi\left(w_{1} B_{3}-w_{3} B_{1}-B_{1}^{2}-B_{3}^{2}\right) . \tag{3.19}
\end{equation*}
$$

The condition $v_{1} b_{3}-v_{3} b_{1}-b_{1}^{2}-b_{3}^{2} \neq 0$ implies $\operatorname{dim} G(V) \leqq 5$. Let us suppose

$$
\begin{equation*}
v_{1} b_{3}-v_{3} b_{1}-b_{1}^{2}-b_{3}^{2}=0 \tag{3.20}
\end{equation*}
$$

The system $v_{1} \alpha=-\beta b_{1}, v_{3} \alpha=-\beta b_{3}$ being integrable, there are sections $\left(v_{1}, \ldots, v_{4}\right)$ satisfying

$$
\begin{equation*}
b_{1}=b_{3}=0, \tag{3.21}
\end{equation*}
$$

and we have

$$
\begin{equation*}
v_{1} \alpha=v_{1} \beta=v_{3} \alpha=v_{3} \beta=0 . \tag{3.22}
\end{equation*}
$$

4. The condition $\operatorname{dim} G(V)>5$ implies $\operatorname{dim} G(V)=6$ and the existence of a section $\left(v_{1}, \ldots, v_{4}\right)$ of $B_{G}$ such that

$$
\begin{equation*}
\left[v_{1}, v_{3}\right]=v_{2}, \quad\left[v_{1}, v_{2}\right]=\left[v_{1}, v_{4}\right]=\left[v_{2}, v_{3}\right]=\left[v_{2}, v_{4}\right]=\left[v_{3}, v_{4}\right]=0 . \tag{4.1}
\end{equation*}
$$

Consider the layer $V(0.1)$. It is easy to check that the real vector fields

$$
\begin{array}{ll}
v_{1}=i \frac{\partial}{\partial x}+2(\bar{x}-x) \frac{\partial}{\partial y}-i \frac{\partial}{\partial \bar{x}}+2(x-\bar{x}) \frac{\partial}{\partial \bar{y}}, & v_{2}=4\left(\frac{\partial}{\partial y}+\frac{\partial}{\partial \bar{y}}\right)  \tag{4.2}\\
v_{3}=-\frac{\partial}{\partial x}+2 i(\bar{x}-x) \frac{\partial}{\partial y}-\frac{\partial}{\partial \bar{x}}-2 i(x-\bar{x}) \frac{\partial}{\partial \bar{y}}, & v_{4}=4 i\left(\frac{\partial}{\partial y}-\frac{\partial}{\partial \bar{y}}\right)
\end{array}
$$

over $\mathscr{C}^{2}$ satisfy the following conditions: (i) $v_{3}=J v_{1}, v_{4}=J v_{2}$, (ii) at each point $z \in \mathscr{C}^{2}, v_{1}, v_{2}, v_{3}$ are tangent to the hypersurface of $V$ going through $z$, (iii) $v_{1}, \ldots, v_{4}$ satisfy (4.1). The Lie group (0.2) preserving $V$, we have obtained an example of a layer satisfying the conditions of our Theorem. It remains to show that any two layers satisfying these conditions are biholomorphically equivalent. Consider the complex manifold $M^{4}$ and its layer $V$ such that in its corresponding structure $B_{G}$ there is a section ( $v_{1}, \ldots, v_{4}$ ) satisfying (4.1). Let $N^{4}$ be another complex manifold with a layer $W$ of hypersurfaces such that in the associated structure $B_{G}^{\prime}$ there is a section $\left(w_{1}, \ldots, w_{4}\right)$ such that

$$
\begin{gather*}
{\left[w_{1}, w_{3}\right]=w_{2},}  \tag{4.3}\\
{\left[w_{1}, w_{2}\right]=\left[w_{1}, w_{4}\right]=\left[w_{2}, w_{3}\right]=\left[w_{2}, w_{4}\right]=\left[w_{3}, w_{4}\right]=0 .}
\end{gather*}
$$

On $M^{4} \times N^{4}$, consider the vector fields $v_{i}^{*}, w_{i}^{*}$ defined by the relations $\mathrm{d} \pi_{1}\left(v_{i}^{*}\right)=v_{i}$, $\mathrm{d} \pi_{2}\left(v_{i}^{*}\right)=0, \mathrm{~d} \pi_{1}\left(w_{i}^{*}\right)=0, \mathrm{~d} \pi_{2}\left(w_{i}^{*}\right)=w_{i} ; \pi_{1}: M^{4} \times N^{4} \rightarrow M^{4}, \pi_{2}: M^{4} \times N^{4} \rightarrow N^{4}$ being the natural projections. Let $\alpha, \beta \in \mathscr{R}, \varphi=\alpha^{2}+\beta^{2} \neq 0$. On $M^{4} \times N^{4}$, consider the distribution $D$ such that its space $D_{(m, n)}^{4} \subset T_{(m, n)}\left(M^{4} \times N^{4}\right)$ is spanned by the vectors

$$
\begin{aligned}
& V_{1}=v_{1}^{*}+\alpha w_{1}^{*}-\beta w_{3}^{*}, \quad V_{2}=v_{2}^{*}+\varphi w_{2}^{*}, \quad V_{3}=v_{3}^{*}+\beta w_{1}^{*}+\alpha w_{3}^{*} \\
& V_{4}=v_{4}^{*}+\varphi w_{4}^{*} .
\end{aligned}
$$

Because of

$$
\left[V_{1}, V_{3}\right]=V_{2}, \quad\left[V_{1}, V_{2}\right]=\left[V_{1}, V_{4}\right]=\left[V_{2}, V_{3}\right]=\left[V_{2}, V_{4}\right]=\left[V_{3}, V_{4}\right]=0,
$$

the distribution $D$ is integrable and its integral manifold represents a (local) biholomorphic map $M^{4} \rightarrow N^{4}$ transforming $V$ into $W$.

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