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## Libor Čermák <br> A note on a discrete form of Friedrichs' inequality

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# A NOTE ON A DISCRETE FORM OF FRIEDRICHS' INEQUALITY 

Libor Čermák

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Discrete forms of Friedrichs' inequality in two-dimensional Euclidean space were introduced and analysed by Ženíšek [5], [6]. These inequalities enable us to extend the theory of curved finite elements introduced in [1] to the case of boundary value problems with various stable and unstable boundary conditions. The aim of this paper is to extend one of Ženíšek's results, namely to prove the discrete form of the "classical" Friedrichs' inequality in the $n$-dimensional Euclidean space for arbitrary $n \geqq 2$. The finite element space on which the discrete form of Friedrichs' inequality is proved originates from the 1 -regular triangulation of simplicial isoparametric elements.

Following Ciarlet and Raviart, see e.g. [1], we introduce the 1-regular family $\{K\}_{h}$ of simplicial isoparametric finite elements $K$. We are given
(a) A set $\hat{\Sigma}_{K}=\bigcup_{i=1}^{\hat{N}_{K}}\left\{\hat{a}_{i, K}\right\}$ of $\hat{N}_{K}$ distinct points of $R^{n}$ such that its closed convex hull $\widehat{K}$ is the unit $n$-simplex.
(b) A finite dimensional space $\hat{P}_{K}$ of functions defined on $\hat{K}$ with $\operatorname{dim} \hat{P}_{K}=\hat{N}_{K}$ such that $\widehat{\Sigma}_{K}$ is $\widehat{P}_{K}$-unisolvent, i.e. the Lagrange interpolation problem: "Find $\hat{p}_{K} \in \hat{P}_{K}$ such that $\hat{p}_{K}\left(a_{i, K}\right)=\alpha_{i}, 1 \leqq i \leqq \hat{N}_{K}$ " has one and only one solution for any real numbers $\alpha_{i}$.
(c) A set $\Sigma_{K}=\bigcup_{i=1}^{\hat{N}_{K}}\left\{a_{i, K}\right\}$ of $\hat{N}_{K}$ distinct points of $R^{n}$.

Then the finite element $K$ is the image of the set $\widehat{K}$ through the unique mapping $F_{K}: \hat{K} \rightarrow R^{n}$ which satisfies

$$
F_{K} \in \hat{P}_{K}^{n} \quad \text { and } \quad F_{K}\left(\hat{a}_{i, K}\right)=a_{i, K}, \quad 1 \leqq i \leqq \hat{N}_{K},
$$

where the notation $F_{K} \in \hat{P}_{K}^{n}$ means that

$$
F_{K}: \hat{x} \in \hat{K} \rightarrow F_{K}(\hat{x})=\left(F_{K 1}(\hat{x}), \ldots, F_{K n}(\hat{x})\right) \in R^{n}
$$

with

$$
F_{K i} \in \hat{P}_{K}, \quad 1 \leqq i \leqq n
$$

We suppose
(d) For all $h$ the mapping $F_{K}$ is a $C^{2}$-diffeomorphism and there exist constants $c_{0}, c_{1}, c_{2}$, independent of $h$, such that

$$
\begin{gather*}
\sup _{\hat{x} \in \mathbb{K}|\alpha|=i} \max _{\mid=i}\left|D^{\alpha} F_{K}(\hat{x})\right| \leqq c_{i} h^{i}, \quad i=1,2,  \tag{1}\\
0<c_{0} h^{n} \leqq\left|J_{K}(\hat{x})\right| \tag{2}
\end{gather*}
$$

where $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right),|\alpha|=\alpha_{1}+\ldots+\alpha_{n}$ and $J_{K}(\hat{x})$ is the Jacobian of the mapping $F_{K}$ at the point $\hat{x} \in \hat{K}$.
Every element $K$ is associated with the finite dimensional space $P_{K}$ (with $\operatorname{dim} P_{K}=$ $=\hat{N}_{K}$ ) of functions

$$
P_{K}=\left\{p_{K} \mid K \rightarrow R, p_{K}=\hat{p}_{K}\left(F_{K}^{-1}\right), \forall \hat{p}_{K} \in \hat{P}_{K}\right\} .
$$

Let us denote by $\hat{S}$ one of the $n+1$ surface $(n-1)$-simplexes of the unit simplex $\hat{K}$ and by $\hat{H}$ one of the $n$ surface $(n-2)$-simplexes of the simplex $\hat{S}$. We denote by $\hat{\Sigma}_{S}$ and $\hat{P}_{S}$ the restrictions to $\hat{S}$ of $\widehat{\Sigma}_{K}$ and $\hat{P}_{K}$, respectively, and similarly by $\hat{\Sigma}_{H}$ and $\hat{P}_{H}$ the restrictions to $\hat{H}$ of $\hat{\Sigma}_{S}$ and $\hat{P}_{S}$, respectively. Let $S=F_{K}(\hat{S}), H=F_{K}(\hat{H})$ and let $\Sigma_{S}$ denote the restriction of $\Sigma_{K}$ to $S$.

In the sequel, by $\Omega$ we mean a bounded domain in $R^{n}(n \geqq 2)$ with $\Omega \in \mathscr{C}^{1,1}$ (for the definition of such domains see e.g. Nečas [3], p. 55). Then we can suppose that there exist $R$ coordinate systems $\left\{x^{r}\right\}=\left\{\left(x_{1}^{r}, \ldots, x_{n}^{r}\right)\right\}, r=1, \ldots, R$, such that every point of the boundary $\Gamma$ of the domain $\Omega$ can be described in one of such coordinate systems by an equation

$$
x_{n}^{r}=\varphi^{r}\left(x^{\prime r}\right), \quad x^{\prime r} \in \Delta^{r},
$$

see Fig. 1; here $x^{\prime r}=\left(x_{1}^{r}, \ldots, x_{n-1}^{r}\right), \Delta^{r}$ is an $(n-1)$-dimensional closed cube and $\varphi^{r}$ is a function with Lipschitz continuous first derivatives on $\Delta^{r}$, i.e. $\varphi^{r} \in C^{1,1}\left(\Delta^{r}\right)$.

Following Ciarlet and Raviart [1] we define the 1-regular triangulation of the domain $\Omega$. Let $\Omega_{h}$ be the union of a finite number of simplicial elements $K$. The boundary of $\Omega_{h}$ is denoted by $\Gamma_{h}$. Every element $K=F_{K}(\hat{K})$ is determined by $\hat{N}_{K}$ points $a_{i, K}$. We suppose that all points $a_{i, K}$ belong to $\bar{\Omega}$. The family of elements constructed in this way is called a triangulation of $\Omega$ and denoted by $\tau_{h}$. We say that a triangulation $\tau_{h}$ of $\Omega$ is 1 -regular if:
(a) The family of all elements by which the triangulation is formed is 1-regular.
(b) The geometric shape of any "face" $S$ of a given element $K \in \Omega_{h}$ must be completely determined by those points $a_{i, K}$ which belong to $S$, i.e. the set $\widehat{\Sigma}_{S}$ contains a $\hat{P}_{S^{-}}$ unisolvent subset.
(c) The geometric shape of any "edge" $H$ of a given element $S \in \Gamma_{h}$ must be completely determined by those points $a_{i, K}$ which belong to $H$, i.e. the set $\hat{\Sigma}_{H}$ contains a $\widehat{P}_{H^{-}}$-unisolvent subset.
(d) There exist Lipschitz continuous functions $\psi^{r}$ defined on $\Delta^{r}, r=1, \ldots, R$, such
that every point of the boundary $\Gamma_{h}$ may be described at least by one of the equations

$$
x_{n}^{r}=\psi^{r}\left(x^{\prime r}\right), \quad x^{\prime r} \in \Delta^{r},
$$

see Fig. 1. Moreover, we suppose
(3)

$$
\max _{x^{\prime} r \in \Delta \Delta^{r}}\left|\varphi^{r}\left(x^{\prime r}\right)-\psi^{r}\left(x^{\prime r}\right)\right| \leqq c h^{2},
$$

where $c$ is a constant independent of $h$.


Fig. 1.
It can be proved that the assumption (d) in the above definition follows from the assumption
(d') All points $a_{i, K}$ lying on $\Gamma_{h}$ belong to $\Gamma$.
In the sequel we will suppose that for a 1-regular triangulation the assumption ( $\mathrm{d}^{\prime}$ ) is fulfilled.

The parametr $h$ has the usual geometrical meaning, i.e. $h$ is the maximum of diameters of finite elements $\{K\}_{h}$. It is understood that $h$ approaches zero in the limit.

A given 1-regular triangulation is associated with the finite dimensional space $V_{h}$ of Lipschitz continuous test functions $v$ defined by

$$
V_{h}=\left\{v \mid v \in C^{0,1}\left(\bar{\Omega}_{h}\right), v_{K} \in P_{K}, \forall K \in \Omega_{h}\right\},
$$

where $v_{K}$ is the restriction of the function $v$ to the set $K$.

Let us denote

$$
\Gamma^{r}=\left\{\left(x^{\prime r}, \varphi^{r}\left(x^{\prime r}\right)\right) \mid x^{\prime r} \in \Delta^{r}\right\}, \quad \Gamma_{h}^{r}=\left\{\left(x^{\prime r}, \psi^{r}\left(x^{\prime r}\right)\right) \mid x^{\prime r} \in \Delta^{r}\right\} .
$$

For a function $v$ defined on $\Gamma^{r}$ we denote

$$
\varphi_{\varphi} v\left(x^{\prime r}\right)=v\left(x^{\prime \boldsymbol{r}}, \varphi^{r}\left(x^{\prime r}\right)\right), \quad x^{\prime \boldsymbol{r}} \in \Delta^{r}
$$

and similarly for a function $w$ defined on $\Gamma_{h}^{r}$ we denote

$$
\psi^{r} w\left(x^{\prime r}\right)=w\left(x^{\prime r}, \psi^{r}\left(x^{\prime r}\right)\right), \quad x^{\prime r} \in \Delta^{r} .
$$

In the sequel the constants independent of $h$ are denoted by $c$. The notation is generic, i.e. $c$ does not necessarily mean the same constant at any two places.

The norm in the Lebesgue space $L_{2}(A)$ is denoted by $\|\cdot\|_{0, A}$, the norm in the Sobolev space $H^{m}(A)$ by $\|v\|_{m, A}=\left(\sum_{i=0}^{m}|v|_{i, A}^{2}\right)^{1 / 2}$, where $|v|_{i, A}=\left(\sum_{|\alpha|=i}\left\|D^{\alpha} v\right\|_{0, A}^{2}\right)^{1 / 2}$, and the norm in the Sobolev space $W^{m, \infty}(A)$ by $\|v\|_{m, \infty, A}=\max _{0 \leqq i \leqq m}|v|_{i, \infty, A}$, where $|v|_{i, \infty, A}=\max _{|\alpha|=i} \operatorname{ess}_{x \in A} \sup _{x \in A}\left|D^{\alpha} v\right|$.
The norms in the Lebesgue spaces $L_{2}(\Gamma)$ and $L_{2}\left(\Gamma_{h}\right)$ are denoted by $\|v\|_{0, \Gamma}=$ $=\left(\int_{\Gamma} v^{2} \mathrm{~d} \Gamma\right)^{1 / 2}$ and $\|v\|_{0, \Gamma_{h}}=\left(\int_{\Gamma_{h}} v^{2} \mathrm{~d} \Gamma_{h}\right)^{1 / 2}$, respectively.
Let $\Phi(x)$ be a function defined on the element $K$. Then the function $\Phi\left(F_{K}(\hat{x})\right)$ is defined on $\widehat{K}$ and we will denote it by $\hat{\Phi}(\hat{x})$.

Now we are able to formulate and to prove the discrete form of Friedrichs' inequality. The following theorem extends Ženísek's results [6] to 3 and more dimensions.

Theorem. Let $\tau_{h}$ be a 1 -regular triangulation of the domain $\Omega \in \mathscr{C}^{1,1}$. Let $\Gamma^{*}$ be part of the boundary $\Gamma$ with meas $\Gamma^{*}>0$. Then for any function $v \in V_{h}$ there exists a constant $c$ independent of $h$ and $v$ such that the inequality

$$
\begin{equation*}
\|v\|_{1, \Omega_{h}} \leqq c\left(\|v\|_{0, \Gamma_{h}}+|v|_{1, \Omega_{h}}\right) \tag{4}
\end{equation*}
$$

holds true for all $h$ sufficiently small. Here $\Gamma_{h}^{*}$ denotes the set

$$
\Gamma_{h}^{*}=\left\{x \mid x \in S, S \in \Gamma_{h} \text { is such that } \Sigma_{S} \in \Gamma^{*}\right\} .
$$

The proof of the theorem will be accomplished in five steps.

1. Given a function $v \in V_{h}$ we construct the extension $\tilde{v} \in H^{1}\left(\Omega_{h} \cup \Omega\right)$ such that

$$
\begin{equation*}
\|\tilde{v}\|_{1, \Omega-\Omega_{h}} \leqq c h^{1 / 2}\|v\|_{1, \Omega_{h}} . \tag{5}
\end{equation*}
$$

2. We prove the inequality

$$
\begin{equation*}
\|v\|_{1, \Omega_{h}} \leqq c\|\tilde{v}\|_{1, \Omega} \tag{6}
\end{equation*}
$$

3. We can suppose that $\Gamma^{*}$ may be completely described in one coordinate system $\left\{x^{s}\right\}$ for some $s \in\{1, \ldots, R\}$ (otherwise we take $\Gamma^{*} \cap \Gamma^{s}$ for a suitable $s$ instead of $\Gamma^{*}$ ). Moreover, we can suppose that for all $h$ sufficiently small the inclusion

$$
\begin{equation*}
\omega_{s}=\left\{x^{\prime s} \mid x^{\prime s} \in \Delta^{s},\left(x^{\prime s}, \varphi^{s}\left(x^{\prime s}\right)\right) \in \Gamma^{*}\right\} \subset\left\{x^{\prime s} \mid x^{\prime s} \in \Delta^{s},\left(x^{\prime s}, \psi^{s}\left(x^{\prime s}\right)\right) \in \Gamma_{h}^{*}\right\} \tag{7}
\end{equation*}
$$

holds (otherwise we take a suitable subset of $\Gamma^{*}$ with nonzero measure instead of $\Gamma^{*}$ ). From Friedrichs' inequality we deduce

$$
\begin{equation*}
\|\tilde{v}\|_{1, \Omega} \leqq c\left(\|\tilde{v}\|_{0, \Gamma^{*}}+|\tilde{v}|_{1, \Omega}\right) . \tag{8}
\end{equation*}
$$

4. We prove the inequality

$$
\begin{equation*}
\|\tilde{v}\|_{0, \Gamma^{*}} \leqq c\left(\|v\|_{0, \Gamma_{h}}+|v|_{1, \Omega_{h}}+|\tilde{v}|_{1, \Omega-\Omega_{h}}\right) . \tag{9}
\end{equation*}
$$

5. Combining (6), (8) and (9) we obtain

$$
\|v\|_{1, \Omega_{h}} \leqq c\left(\|v\|_{0, \Gamma_{h}{ }^{*}}+|v|_{1, \Omega_{h}}+|\tilde{v}|_{1, \Omega-\Omega_{h}}\right) .
$$

Hence and from (5) we get the assertion of the theorem.
Proof of Step 1. We define the sets

$$
A_{\varepsilon}^{r}=\left\{x\left|x=\left(x^{\prime r}, x_{n}^{r}\right), x^{\prime r} \in \Delta^{r}, \operatorname{dist}\left(x^{\prime r}, \partial \Delta^{r}\right)>0,\left|x_{n}^{r}-\varphi^{r}\left(x^{\prime r}\right)\right|<\varepsilon\right\},\right.
$$

where $\varepsilon$ is a sufficiently small positive number, see Fig. 1. Then for $h$ sufficiently small we have

$$
A_{\varepsilon} \equiv \bigcup_{r=1}^{R} A_{\varepsilon}^{r} \supset \Omega-\Omega_{h} .
$$

The theorem on the partition of unity, see e.g. Yosida [4], p. 61, asserts that there exist functions $a^{r} \in C^{\infty}\left(R^{n}\right)$ such that $\operatorname{supp}\left(a^{r}\right) \subset A_{\varepsilon}^{r}$ and that $\sum_{r=1}^{R} a^{r}(x)=1$ for any $x \in A_{\varepsilon}$.

For a function $v \in V_{h}$ we define functions

$$
\tilde{v}^{r}(x)= \begin{cases}v(x), & x \in A_{\varepsilon}^{r} \cap \Omega_{h}, \\ v\left(x^{\prime r}, \psi^{r}\left(x^{\prime r}\right)\right), & x \in A_{\varepsilon}^{r}-\Omega_{h}, \quad r=1, \ldots, R . \\ 0, & x \in A_{\varepsilon}-A_{\varepsilon}^{r},\end{cases}
$$

Further, we define the function

$$
\tilde{v}(x)=\sum_{r=1}^{R} a^{r}(x) \tilde{v}^{r}(x), \quad x \in A_{\varepsilon} .
$$

Evidently $\tilde{v}(x)=v(x)$ for $x \in A_{\varepsilon} \cap \Omega_{h}$. If we set

$$
\tilde{v}(x)=v(x) \text { for } x \in \Omega_{h}-A_{\varepsilon},
$$

then $\tilde{v}$ is the extension of the function $v$ from $\Omega_{h}$ to $\Omega_{h} \cup A_{\varepsilon}$. Moreover, from the smoothness of the functions $\psi^{r}$ we deduce that $\tilde{v} \in H^{1}\left(\Omega_{h} \cup A_{\varepsilon}\right)$ and hence also $\tilde{v} \in H^{1}\left(\Omega_{h} \cup \Omega\right)$.

Let us denote $B^{r}=A_{\varepsilon}^{r} \cap\left(\Omega-\Omega_{h}\right), B^{\prime r}=\left\{x^{\prime r} \mid x^{\prime r} \in \Delta^{r},\left(x^{\prime r}, x_{n}^{r}\right) \in B^{r}\right\}$. As $\Omega-$ $-\Omega_{h} \subset \bigcup_{r=1}^{R} B^{r}$ we have

$$
\begin{gather*}
\|\tilde{v}\|_{1, \Omega-\Omega_{h}}^{2} \leqq \sum_{r=1}^{R}\|\tilde{v}\|_{1, B^{r}}^{2}=\sum_{r=1}^{R}\left\|\sum_{j=1}^{R} a^{j} \tilde{v}^{j}\right\|_{1, B^{r}}^{2} \leqq  \tag{10}\\
\leqq(2 n+1) R \max _{j=1, \ldots, R}\left\|a^{j}\right\|_{1, \infty, A_{k}}^{2} \sum_{r=1}^{R} \sum_{j=1}^{R}\left\|\tilde{v}^{j}\right\|_{1, B^{r} \cap A_{k} j}^{2} \leqq c \sum_{r=1}^{R}\left\|\tilde{v}^{r}\right\|_{1, B^{r}}^{2} .
\end{gather*}
$$

For $x^{r} \in B^{r}$ we have $\tilde{v}^{r}\left(x^{\prime r}, x_{n}^{r}\right)=v\left(x^{\prime r}, \psi^{r}\left(x^{\prime r}\right)\right)$; then

$$
\frac{\partial \tilde{v}^{r}}{\partial x_{i}^{r}}\left(x^{\prime r}, x_{n}^{r}\right)=\frac{\partial v\left(x^{\prime r}, \psi^{r}\left(x^{\prime r}\right)\right)}{\partial x_{i}^{r}}, \quad i=1, \ldots, n-1 \quad \text { and } \quad \frac{\partial \tilde{v}^{r}\left(x^{\prime r}, \psi^{r}\left(x^{\prime \prime}\right)\right)}{\partial x_{n}^{r}}=0 .
$$

Hence

$$
\begin{align*}
& \left\|\tilde{v}^{r}\right\|_{1, B^{r}}^{2}=\int_{B^{\prime r}}\left|\int_{\varphi^{r}\left(x^{\prime \prime}\right)}\left\{\sum_{i=1}^{\psi^{r}\left(x^{\prime r}\right)}\left[\frac{\partial \tilde{v}^{r}\left(x^{\prime r}, x_{n}^{r}\right)}{\partial x_{i}^{r}}\right]^{2}+\left[\tilde{v}^{r}\left(x^{\prime \prime}, x_{n}^{r}\right)\right]^{2}\right\} \mathrm{d} x_{n}^{r}\right| \mathrm{d} x^{\prime r}=  \tag{11}\\
& =\int_{B^{\prime r}}\left|\int_{\varphi^{r}\left(x^{\prime r}\right)}^{\psi^{r}\left(x^{\prime \prime r}\right)}\left\{\sum_{i=1}^{n-1}\left[\frac{\partial v\left(x^{\prime r}, \psi^{r}\left(x^{\prime r}\right)\right)}{\partial x_{i}^{r}}\right]^{2}+\left[v\left(x^{\prime \prime}, \psi^{r}\left(x^{\prime r}\right)\right)\right]^{2}\right\} \mathrm{d} x_{n}^{r}\right| \mathrm{d} x^{\prime r} \leqq \\
& \leqq\left\|\varphi^{r}-\psi^{r}\right\|_{0, \infty, B^{\prime r}}\left\|_{\psi^{r} v}\right\|_{1, B^{\prime r}}^{2} \leqq\left\|\varphi^{r}-\psi^{r}\right\|_{0, \infty, 4^{r}}\left\|_{\psi^{r} v}\right\|_{1, A^{r}}^{2!}
\end{align*}
$$

Let a "face" $S$ have a non-empty intersection $S_{*}^{r}$ with the set $\Gamma_{h}^{r}$. If we denote by $S_{*}^{\prime r}$ the projection of $S_{*}^{r}$ into the hyperplane $x_{n}^{r}=0$, then $\Delta^{r}=\bigcup S_{*}^{\prime r}$. We can and will suppose that the image $\hat{S}_{*}=F_{K}^{-1}\left(S_{*}^{r}\right)$ of the set $S_{*}^{r}$ lies in the hyperplane $\hat{x}_{n}=0$. Then

$$
\left|\psi_{r} v\right|_{0, \Sigma_{*}{ }^{\prime \prime}}^{2}=\int_{S_{*^{\prime}} r} \psi_{r} v^{2} \mathrm{~d} x^{\prime r}=\int_{\hat{S}_{*}} \hat{v}^{2} J_{K}^{(n, n)} \mathrm{d} \hat{x}^{\prime},
$$

where $J_{K}^{(n, n)}$ denotes the cofactor of the Jacobian $J_{K}$. Hence and from (1) we have

$$
\left|\left.\right|_{\psi r} v\right|_{0, S_{*^{\prime}} r}^{2} \leqq c h^{n-1}|\hat{v}|_{0, \hat{s}_{*}}^{2} .
$$

From the trace theorem and from the equivalence of norms on the finite dimensional space $\widehat{P}_{K}$ we immediately obtain
and consequently

$$
|\hat{v}|_{0, \hat{S}_{*}}^{2} \leqq c\|\hat{v}\|_{1, \hat{K}}^{2} \leqq c|\hat{v}|_{0, \hat{K}}^{2}
$$

Using (2) we have

$$
\left|{ }_{\psi} r v\right|_{0, S *^{\prime} r}^{2} \leqq c h^{n-1}|\hat{v}|_{0, K}^{2} .
$$

$$
\begin{equation*}
\left.\left.\right|_{\psi^{\prime} \cdot} \cdot\right|_{0, S_{*^{\prime}} r} ^{2} \leqq c h^{-1}|v|_{0, K}^{2} \tag{12}
\end{equation*}
$$

where $K$ is an element such that $S_{*}^{r} \subset \partial K$. From the chain rule (on the differentiating of the composite function) we obtain

$$
\begin{equation*}
\frac{\partial F_{K i}^{-1}}{\partial x_{j}}=\frac{J_{K}^{(j, i)}}{J_{K}} \tag{13}
\end{equation*}
$$

and consequently

$$
\begin{gathered}
\left|\psi_{\psi r} v\right|_{1, S_{*}, r}^{2}=\int_{S_{*^{\prime}}} \sum_{j=1}^{n-1}\left[\frac{\partial_{\psi^{\prime}} v}{\partial x_{j}}\right]^{2} \mathrm{~d} x^{\prime r}= \\
=\int_{\hat{S}_{*}} \sum_{j=1}^{n-1}\left[\sum_{i=1}^{n-1} \frac{\partial \hat{v}}{\partial \hat{x}_{i}} \frac{\partial F_{K i}^{-1}}{\partial x_{j}}\right]^{2} J_{K}^{(n, n)} \mathrm{d} \hat{x}^{\prime}=\sum_{j=1}^{n-1} \int_{S_{*}}\left[\sum_{i=1}^{n-1} \frac{\partial \hat{v}}{\partial \hat{x}_{i}} \frac{J_{K}^{(j, i)}}{J_{K}}\right]^{2} J_{K}^{(n, n)} \mathrm{d} \hat{x}^{\prime} .
\end{gathered}
$$

Here again $J_{K}^{(j, i)}$ is the cofactor of the Jacobian $J_{K}$. The last equality and (1), (2) yield

$$
\begin{equation*}
\left.\left.\right|_{\psi r r}\right|_{1, S_{*}^{\prime} r} ^{2} \leqq c h^{n-3} \sum_{i=1}^{n-1}\left|\frac{\partial \hat{v}}{\partial \hat{x}_{i}}\right|_{0, \hat{S}_{*}}^{2} . \tag{14}
\end{equation*}
$$

Using the trace theorem and the equivalence of norms on a finite dimensional space we see that

$$
\left|\frac{\partial \hat{v}}{\partial \hat{x}_{i}}\right|_{0, \hat{S}_{*}} \leqq c\left\|\frac{\partial \hat{v}}{\partial \hat{x}_{i}}\right\|_{1, K} \leqq c\left\|\frac{\partial \hat{v}}{\partial \hat{x}_{i}}\right\|_{0, K} .
$$

Since

$$
\frac{\partial \hat{v}}{\partial \hat{x}_{i}}=\sum_{j=1}^{n} \frac{\partial v}{\partial x_{j}} \frac{\partial F_{K j}}{\partial \hat{x}_{i}}
$$

we obtain from the last two inequalities and from (1), (2) and (14)

$$
\begin{equation*}
\left|\psi_{\psi r} v\right|_{1, S x^{\prime \prime}}^{2} \leqq c h^{-1}|v|_{1, K}^{2} . \tag{15}
\end{equation*}
$$

Combining (12) and (15) and summing over all elements $S_{*}^{\prime r}$ we obtain

$$
\left\|\psi_{\psi^{r} v}\right\|_{1, a^{r}}^{2} \leqq c h^{-1}\|v\|_{1, \Omega_{h}}^{2} .
$$

Together with (11) and (3) this yields

$$
\left\|\tilde{v}^{r}\right\|_{1, B^{r}}^{2} \leqq c h\|v\|_{1, \Omega_{h}}^{2} .
$$

This together with (10) proves (5).
Proof of Step 2. For an element $K$ having a non-empty intersection with the set $\Omega_{h}-\Omega$ we denote $K_{*}=K \cap\left(\Omega-\Omega_{h}\right)$ and $\hat{K}_{*}=F_{K}^{-1}\left(K_{*}\right)$. Using (1), (13) and (2) we have

$$
\begin{align*}
& \|v\|_{1, K_{*}}^{2}=|v|_{0, K_{*}}^{2}+|v|_{1, K_{*}}^{2}=\int_{R_{*}} \hat{v}^{2} J_{K} \mathrm{~d} \hat{x}+\int_{K_{*}} \sum_{j=1}^{n}\left[\sum_{i=1}^{n} \frac{\partial \hat{v}}{\partial \hat{x}_{i}} \frac{\partial F_{K i}^{-1}}{\partial x_{j}}\right]^{2} J_{K} \mathrm{~d} \hat{x} \leqq  \tag{16}\\
& \leqq c h^{n}\left(|\hat{v}|_{0, R_{*}}^{2}+h^{-2}|\hat{v}|_{1, R_{*}}^{2}\right) \leqq c h^{n} \text { meas } \hat{K}_{*}\left(|\hat{v}|_{0, \infty, R}^{2}+h^{-2}|\hat{v}|_{1, \infty, \hat{R}}^{2}\right) .
\end{align*}
$$

From the equivalence of norms on finite dimensional spaces we deduce

$$
|\hat{v}|_{i, \infty, R} \leqq c|\hat{v}|_{i, R}, \quad i=0,1 .
$$

Hence, from (16), (1) and (2) we get

$$
\begin{equation*}
\|v\|_{1, K_{*}}^{2} \leqq c h^{n} \text { meas } \hat{K}_{*}\left(|\hat{v}|_{0, K}^{2}+h^{-2}|\hat{v}|_{1, k}^{2}\right) \leqq c \text { meas } \hat{K}_{*}\|v\|_{1, K}^{2} . \tag{17}
\end{equation*}
$$

Let us suppose that

$$
\begin{equation*}
\text { meas } \hat{K}_{*} \leqq c h . \tag{18}
\end{equation*}
$$

Then summing over all elements $K_{*}$ we obtain

$$
\begin{equation*}
\|v\|_{1, \Omega_{h}-\Omega}^{2} \leqq c h\|v\|_{1, \Omega_{h}}^{2} . \tag{19}
\end{equation*}
$$

Since $\|v\|_{1, \Omega_{h}}^{2} \leqq\|\tilde{v}\|_{1, \Omega}^{2}+\|v\|_{1, \Omega_{h}-\Omega}^{2}$, (6) follows for all $h$ sufficiently small from the last two inequalities.
To prove (18) it suffices to prove that for any point $\hat{x} \in \hat{K}_{*}$ the inequality

$$
\begin{equation*}
\operatorname{dist}(\hat{x}, \partial \hat{K}) \leqq c h \tag{20}
\end{equation*}
$$

holds, see Fig. 2. Let $\hat{x} \in \hat{K}_{*}$ and let $x=\left(x^{\prime r}, x_{n}^{r}\right)=F_{K}(\hat{x}), z=\left(x^{\prime r}, \psi^{r}\left(x^{\prime r}\right)\right)$ and $\hat{z}=F_{K}^{-1}(z)$. Then

$$
\begin{aligned}
& \operatorname{dist}(\hat{x}, \partial \hat{K})=\left|\hat{x}-\hat{x}_{P}\right| \leqq|\hat{x}-\hat{z}|=\left|F_{K}^{-1}(x)-F_{K}^{-1}(z)\right| \leqq \\
& \leqq \max _{|\alpha|=1} \sup _{y \in K}\left|D^{\alpha} F_{K}^{-1}(y)\right| \max _{y^{\prime}{ }^{\prime} \in \Delta^{r}}\left|\varphi^{r}\left(y^{\prime r}\right)-\psi^{r}\left(y^{\prime r}\right)\right|
\end{aligned}
$$

and (20) follows from (13), (1), (2) and (3).



Fig. 2.

Proof of Step 4. For any point $x^{\prime s} \in \omega_{s}$, for the definition of $\omega_{s}$ see (7), we have

$$
\tilde{v}\left(x^{\prime s}, \varphi^{s}\left(x^{\prime s}\right)\right)=v\left(x^{\prime s}, \psi^{s}\left(x^{\prime s}\right)\right)+\int_{\psi^{s}\left(x^{\prime s}\right)}^{\varphi^{s}\left(x^{\prime s}\right)} \frac{\partial}{\partial x_{n}^{s}} \tilde{v}\left(x^{\prime s}, \tau\right) \mathrm{d} \tau .
$$

Squaring, using Cauchy's inequality, integrating over the set $\omega_{s}$ and using (7) we get

$$
\begin{gather*}
\int_{\omega_{s}} \tilde{v}^{2}\left(x^{\prime s}, \varphi^{s}\left(x^{\prime s}\right)\right) \mathrm{d} x^{\prime s} \leqq c\left[\int_{\omega_{s}} v^{2}\left(x^{\prime s}, \psi^{s}\left(x^{\prime s}\right)\right) \mathrm{d} x^{\prime s}+\right.  \tag{21}\\
\left.+\int_{\omega_{s}}\left|\int_{\psi^{s}\left(x^{\prime s}\right)}^{\varphi^{s}\left(x^{\prime s}\right)}\left[\frac{\partial}{\partial x_{n}^{s}} \tilde{v}\left(x^{\prime s}, \tau\right)\right]^{2} \mathrm{~d} \tau\right| \mathrm{d} x^{\prime s}\right] \leqq c\left(\|v\|_{0, I_{h}}^{2}+|\tilde{v}|_{1, \Omega-\Omega_{h} \cup \Omega_{h}-\Omega}^{2}\right) .
\end{gather*}
$$

Due to the smoothness of the boundary $\Gamma$ we have

$$
\|\tilde{v}\|_{0, r^{*}}^{2}=\int_{\omega_{s}} \tilde{v}^{2}\left(x^{\prime s}, \varphi^{s}\left(x^{\prime s}\right)\right) \sqrt{\left(1+\sum_{i=1}^{n-1}\left[\frac{\partial \varphi^{s}\left(x^{\prime s}\right)}{\partial x_{i}^{s}}\right]^{2}\right) \mathrm{d} x^{\prime s} \leqq c \int_{\omega_{s}} \tilde{v}^{2}\left(x^{\prime s}, \varphi^{s}\left(x^{\prime s}\right)\right) \mathrm{d} x^{\prime s} . . . ~ . ~}
$$

From the last two inequalities we obtain (9).
Using the same technique we can prove the discrete form of Friedrichs' inequality also for other isoparametric triangulations, e.g. for the triangulation based on using quadrilateral isoparametric finite elements.

The discrete form of Friedrichs' inequality is applied in the analysis of the finite element solution of elliptic partial differential equations of the second order with unstable boundary conditions, see [5], [6], [2]. To illustrate it let us consider the bilinear form

$$
b_{h}(v, w)=\int_{\Omega_{h}} \sum_{i, j=1}^{n} a_{i j}(x) \frac{\partial v}{\partial x_{i}} \frac{\partial w}{\partial x_{j}} \mathrm{~d} \Omega_{h}+\int_{\Gamma_{h}} a(x) v w \mathrm{~d} \Gamma_{h}^{*}
$$

such that

$$
\sum_{i, j=1}^{n} a_{i j}(x) \xi_{i} \xi_{j} \geqq c_{1} \sum_{i=1}^{n} \xi_{i}^{2} \quad \forall x \in \Omega_{h}, \quad\left(\xi_{1}, \ldots, \xi_{n}\right) \in R^{n}, \quad c_{1}>0
$$

and

$$
a(x) \geqq c_{2}>0 \quad \forall x \in \Gamma_{h}^{*} .
$$

Then the theorem on the discrete form of Friedrichs' inequality yields

$$
b_{h}(v, v) \geqq c\|v\|_{1, \Omega_{h}}^{2} \quad \forall v \in V_{h}, \quad c>0,
$$

i.e. the bilinear form $b_{h}(v, w)$ is uniformly (with respect to $h$ ) $V_{h}$-elliptic.

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## Souhrn

## POZNÁMKA O DISKRÉTNÍM TVARU FRIEDRICHSOVY NEROVNOSTI

 Libor ČermákPráce je věnována důkazu Friedrichsovy nerovnosti na třídě konečně dimensionálních prostorů používaných v metodě konečných prvkủ. Konkrétně jsou uvažovány aproximační prostory generované simpliciálními izoparametrickými elementy.

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