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NONISOLATED SINGULARITIES OF SOLUTIONS TO A QUASILINEAR ELLIPTIC SYSTEM

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Abstract: There is presented an example of a quasilinear elliptic system which has solutions with nonisolated discontinuities.

Key words: Elliptic systems of partial differential equations, weak solutions, regularity.

Classification: 35J60, 35D10

1. Introduction. Let $\Omega \subset {\rm R}^{\rm n}$ be an open set. We consider quasilinear elliptic systems

(1) $D_{A} \stackrel{A}{\overset{(i)}{i}} (u) D_{A} u^{j} = 0, i = 1, ..., m.$

(The summation convention concerning repeated indices is used throughout the paper; i,j=1,...,m, $\boldsymbol{\ll}, \boldsymbol{\beta}$ =1,...,n.) Referring to the system (1) we always assume the coefficients to be bounded uniformly continuous functions on R^m satisfying the ellipticity condition

(2) $A_{ij}^{\alpha\beta} \xi_{\alpha}^{i} \xi_{\beta}^{j} Z |\xi|^{2}$ for each $\xi \in \mathbb{R}^{mn}$.

By a (weak) solution of (1) we understand a (vector valued) function $u\in W^{1,2}_{loc}$ (Ω,R^m) such that

(3) D, b_i^{oc} = 0, i=1,...,m

holds in the sense of distributions for

(4) $b_i = A_{ij} (u) D_{\beta} u^j$.

The counterexample by E. Giusti and M. Miranda [3] shows that for $n \ge 3$ the discontinuous function

 $u:x \mapsto \frac{x}{|x|}$

solves a system of type (1). Thus one cannot expect full regularity results in this general setting. Typical results estimate the Hausdorff dimension of singularities. **Theorem 1.** (E. Giusti [2], see also [1].) Let u be a weak solution of (1). Then there is an open set $\Omega_0 \subset \Omega$ such that u is locally Hölder continuous on Ω_0 and the Hausdorff dimension of $\Omega \setminus \Omega_0$ is less than n-2.

An easy modification of the above mentioned counterexample shows that for every $n \ge 4$ there is a system of type (1) which has a solution discontinuous at every point of

 $x \in \mathbb{R}^{n}: x_{1} = x_{2} = x_{3} = 0$

Thus, it has been known for a long time that the singular set can be nonisolated if $n \leq 4$. We shall prove the following theorem concerning n=3.

Theorem 2. There are a weak solution $s:\mathbb{R}^3 \longrightarrow \mathbb{R}^6$ of a system of type (1) and a sequence $\{z_k\}$ of discontinuity points for s such that $z_k \neq 0$, $z_k \rightarrow 0$.

2. Reduction to two singularities. Let $z_0 \in \mathbb{R}^3$, $z_0 \neq 0$. Let u_0 be a bounded weak solution of (1). For each k=0,1,... denote

(B(z,r) denotes the open ball with center at z and radius r). By a simple homothety argument we see that u_k also solve (1) (the coefficients are fixed!). Now let us assume that

$$s_1 = \begin{cases} u_0 \text{ outside } B_1 \\ u_1 \text{ on } B_1. \end{cases}$$

Of course, $s_1 = u_1$ outside B_0 . As the concept of weak solution is local, we see that s_1 solves (1). We define recurrently (k=2,3,...)

$$s_{k} = \begin{cases} s_{k-1} & \text{outside } B_{k}, \\ u_{k} & \text{on } B_{k}. \end{cases}$$

We see by induction that s_k solve (1) and

$$\|\mathbf{s}_{k}-\mathbf{s}_{k-1}\|_{W^{1,2}(\Omega)}^{2} \leq \mathbb{C}(\Omega) 2^{-k}$$

for every bounded domain $\Omega \subset \mathbb{R}^3$. Hence the sequence $\{s_k\}$ has a limit s in the sense of (strong) $W_{loc}^{1,2}$ convergence. By routine arguments we see that s solves (1), too. If u_o is discontinuous at z_o, then s is discontinuous at

all points z_k (and at the origin).

Conclusion. Theorem 2 is proved if we construct a system (1) (i.e. coefficients $A_{j,1}^{\epsilon}$) and its bounded weak solution u such that

- (5) u is discontinuous at some point $z \in \mathbb{R}^3$, $z \neq 0$,
- (6) u(2x)=u(x) for all $x \notin B(z, |z|/4) \cup B(z/2, |z|/8)$.

3. Construction. Fix a decreasing function $\varphi \in C^2(10,11)$ with

 $\varphi'(1)=0, \varphi(0)=1, \varphi(1)=0$

and denote by ψ its inverse. Now, prolong the functions φ and ψ to $[0,\infty)$ putting

 $\varphi(r)=0, \ \Psi(t)=0 \text{ for } r, t \in (1, \infty).$

Fix a point $z \in \mathbb{R}^3$, |z|=4. Denote

v=x-z for every $x \in \mathbb{R}^3$.

Let c be a fixed constant,

(7)
$$c \ge 2 \sup (4+r) | \varphi'(r) | : r \in (0,1).$$

Put

(8)
$$u^{i}(x) = \begin{cases} c \frac{x_{i-3}}{|x|} \text{ if } i=4,5,6, \\ q(|y|) \frac{y_{i}}{|y|} \text{ if } i=1,2,3. \end{cases}$$

We have

(9)
$$\mathbb{D}_{\mathbf{x}} u^{i} = \begin{cases} \frac{c}{|x|} (\mathbf{x}_{i-3}^{\mathbf{x}} - \frac{x_{i-3}^{\mathbf{x}}}{|x|^{2}}) & \text{if } i=4,5,6, \\ \frac{\mathbf{y}(|y|)}{|y|} (\mathbf{x}_{i}^{\mathbf{x}} - \frac{y_{i}y_{\mathbf{x}}}{|y|^{2}}) + \mathbf{y}(|y|) \frac{y_{i}y_{\mathbf{x}}}{|y|^{2}} & \text{if } i=1,3,3. \end{cases}$$

Denote

(10)
$$b_{i}^{\mathbf{c}} = \begin{cases} \frac{c}{|x|} (\mathbf{s}_{i-3}^{\mathbf{c}} + \frac{x_{i-3}^{2}\mathbf{s}_{\mathbf{c}}}{|x|^{2}}) & \text{if } i=4,5,6, \\ \frac{\mathbf{g}(|y|)}{|y|} (\mathbf{s}_{i}^{\mathbf{c}} + \frac{y_{i}y_{\mathbf{c}}}{|y|^{2}}) + \mathbf{g}'(|y|) (\mathbf{s}_{i}^{\mathbf{c}} - \frac{y_{i}y_{\mathbf{c}}}{|y|^{2}}) & \text{if } i=1,2,3. \end{cases}$$

By a routine calculation we obtain the validity of (3). Obviously, the function u satisfies (5) and (6). It remains only to find coefficients $A_{ij}^{\epsilon,\beta}$ such that (4) holds.

- 423 -

4. Coefficients. In this section we construct coefficients $A_{ij}^{\epsilon\ell\beta}(v,w) (v,w \in \mathbb{R}^3)$ such that the functions u^i , $b_i^{\epsilon\ell}$ given by (8), (10) satisfy (11) $b^{\epsilon\ell} = A^{\epsilon\ell\beta}((u^1 u^2 u^3) (u^4 u^5 u^6)) D_{\epsilon\ell} u^j$

(11)
$$b_{i}^{\alpha} = A_{ij}^{\alpha}((u^{1}, u^{2}, u^{3}), (u^{4}, u^{5}, u^{6})) D_{\beta} u^{j}.$$

We follow essentially the method due to J. Souček [6]. Denote

$$Y = \Psi(|v|),$$

$$X = \begin{cases} |z+Y| \frac{v}{|v|}|, v \neq 0, \\ 4, v=0, \end{cases}$$

$$h = \frac{cY}{cY+X\varphi(Y)},$$

$$f = \frac{X\varphi(Y)}{cY+X\varphi(Y)},$$

$$g = \frac{XY\varphi'(Y)}{cY+X\varphi(Y)}.$$

Using the conventions

$$\begin{array}{l} \frac{v_{1}v_{oc}}{|v|^{2}} = 0 \ \text{if } v=0, \ \frac{w_{1-3}w_{oc}}{|w|^{2}} = 0 \ \text{if } w=0, \\ v_{1}=w_{1}=0 \ \text{if } i \notin \{1,2,3\}, \end{array}$$

we define

$$B_{i}^{\alpha c} = h(\sigma_{i-3}^{\alpha c} + \frac{w_{i-3}w_{\alpha c}}{|w|^{2}}) + f(\sigma_{i}^{\alpha c} + \frac{v_{i}v_{\alpha c}}{|v|^{2}}) + g(\sigma_{i}^{\alpha c} - \frac{v_{i}v_{\alpha c}}{|v|^{2}}),$$

$$T_{i}^{\alpha c} = h(\sigma_{i-3}^{\alpha c} - \frac{w_{i-3}w_{\alpha c}}{|w|^{2}}) + f(\sigma_{i}^{\alpha c} - \frac{v_{i}v_{\alpha c}}{|v|^{2}}) + g\frac{v_{i}v_{\alpha c}}{|v|^{2}}$$

(i=1,...,6; **%**=1,2,3). Finally we put

$$\begin{aligned} & \mathbb{Q}=\min(1,|w|) (3B_{i}\mathsf{T}_{i}-\mathsf{T}_{i}\mathsf{T}_{i})^{-1}, \\ & \mathbb{A}_{ij}=\boldsymbol{\sigma}_{i}^{j}\boldsymbol{\sigma}_{\boldsymbol{\omega}}^{\boldsymbol{\beta}} + \mathbb{Q}(3B_{i}^{\boldsymbol{\omega}}-\mathsf{T}_{i}^{\boldsymbol{\omega}})(3B_{j}^{\boldsymbol{\beta}}-\mathsf{T}_{j}^{\boldsymbol{\beta}}) \end{aligned}$$

(i,j=1,...,6; \propto , β =1,2,3). By (7) we verify that Q is a nonnegative bounded function on $R^3 \ll R^3$. Indeed, we have

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$${}^{3B_{i}T_{i}-T_{i}T_{i}} = \frac{\frac{3}{4}c^{2}Y^{2}+X^{2}\varphi^{2}(Y)+3(X\varphi(Y)+2XY\varphi'(Y))^{2}+\frac{13}{4}Y^{2}(c^{2}-4X^{2}(\varphi'(Y))^{2})}{(cY+X\varphi(Y))^{2}} \cdot$$

The coefficients are continuous: discontinuities $\frac{v_i v_{ec}}{|v|^2}$, $\frac{w_{i-3} w_{ec}}{|w|^2}$, X are always

neutralized being multiplied by vanishing continuous functions. We observe that the supremum of $|A_{ij}^{\checkmark\beta}|$ as well as the modulus of continuity of $A_{ij}^{\checkmark\beta}$ are estimated by the same quantities on $\{v: |v| \neq l\} \times \{w: |w| \neq l\}$. Hence the coefficients are bounded and uniformly continuous. By a direct calculation we see that (11) is satisfied.

5. Some remarks. A) If we admit discontinuous coefficients (Borel measurable only) then Theorem 1 does not hold.

Let $a_{i,j}^{\boldsymbol{\mathcal{L}},\boldsymbol{\beta}}$ be bounded Borel measurable functions on \textbf{R}^3 satisfying

$$a_{ij}^{\alpha\beta} \xi_{\alpha}^{i} \xi_{\beta}^{j} \ge |\xi|^{2}$$
 for each $\xi \in \mathbb{R}^{9}$.

Let v be a weak solution to the linear system

(12)
$$D_{ac} a_{ij}^{ac} (x) D_{\beta} v^{j} = 0.$$

Then the function u defined by

$$u^{1}=v^{1}$$
, $i=1,2,3$, $u^{1}=x_{i-3}$, $i=4,5,6$

solves the quasilinear system

where

$$A_{ij}^{\boldsymbol{\omega},\boldsymbol{\beta}}(\mathbf{u}) = \begin{cases} a_{ij}^{\boldsymbol{\omega},\boldsymbol{\beta}}(\mathbf{u}^{4},\mathbf{u}^{5},\mathbf{u}^{6}) \text{ if } i,j \in \{1,2,3\} \\ \sigma_{i}^{j} \sigma_{\boldsymbol{\omega}}^{\boldsymbol{\beta}} \text{ otherwise.} \end{cases}$$

However, solutions of (12) can be everywhere discontinuous (see [4]).

B) Our example does not fill the gap between the estimate of Hausdorff dimension of singular sets given in Theorem 1 and n-3-dimensionality of singular sets in the known counterexamples. It is not even clear whether the singular set for n=3 can be uncountable.

C) It would be nice to have counterexamples (or further positive regularity results) in case when the quasilinear system (1) is obtained as a system in variation. The only known counterexamples (see e.g. J. Nečas [5]) have one singular point.

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