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# NONISOLATED SINGULARITIES OF SOLUTIONS TO A QUASILINEAR ELLIPTIC SYSTEM 

Jan MALY

Abstract: There is presented an example of a quasilinear elliptic system which has solutions with nonisolated discontinuities.

Key words: Elliptic systems of partial differential equations, weak solutions, regularity.

Classification: 35J60, 35010

1. Introduction. Let $\Omega \subset R^{n}$ be an open set. We consider quasilinear elliptic systems
(1) $D_{\alpha} A_{i j}^{\alpha \beta}(u) D_{\beta} u^{j}=0, i=1, \ldots, m$.
(The summation convention concerning repeated indices is used throughout the paper; $i, j=1, \ldots, m, \alpha, \beta=1, \ldots, n$.) Referring to the system (1) we always assume the coefficients to be bounded uniformly continuous functions on $R^{m}$ satisfying the ellipticity condition
(2) $A_{i j}^{\alpha \beta} \xi_{\alpha}^{i} \xi_{\beta}^{j} \geq|\xi|^{2}$ for each $\xi \in R^{m n}$.

By a (weak) solution of (1) we understand a (vector valued) function $u \in W_{l o c}^{1,2}\left(\Omega, R^{m}\right)$ such that
(3) $D_{\alpha} b_{i}^{\alpha}=0, i=1, \ldots, m$
holds in the sense of distributions for
(4) $b_{i}^{\alpha}=A_{i j}^{\alpha \beta}(u) D_{\beta} u^{j}$.

The counterexample by E. Giusti and M. Miranda [3] shows that for $n \geq 3$ the discontinuous function

$$
u: x \mapsto \frac{x}{|x|}
$$

solves a system of type (1). Thus one cannot expect full regularity results in this general setting. Typical results estimate the Hausdorff dimension of singularities.

Theorem 1. (E. Giusti [2], see also [1].) Let $u$ be a weak solution of (1). Then there is an open set $\Omega_{0} \subset \Omega$ such that $u$ is locally Hölder continuous on $\Omega_{0}$ and the Hausdorff dimension of $\Omega \backslash \Omega_{0}$ is less than n-2.

An easy modification of the above mentioned counterexample shows that for every $n \geq 4$ there is a system of type (1) which has a solution discontinuous at every point of

$$
\left\{x \in R^{n}: x_{1}=x_{2}=x_{3}=0\right\}
$$

Thus, it has been known for a long time that the singular set can be nonisolated if $n \geq 4$. We shall prove the following theorem concerning $n=3$.

Theorem 2. There are a weak solution $s: R^{3} \rightarrow R^{6}$ of a system of type (1) and a sequence $\left\{z_{k}\right\}$ of discontinuity points for $s$ such that $z_{k} \neq 0, z_{k} \rightarrow 0$.
2. Reduction to two singularities. Let $z_{0} \in R^{3}, z_{0} \neq 0$. Let $u_{0}$ be a bounded weak solution of (1). For each $k=0,1, \ldots$ denote

$$
\begin{aligned}
& z_{k}=z_{0} / 2^{k}, \\
& u_{k}(x)=u_{0}\left(2^{k} x\right), \\
& B_{k}=B\left(z_{k},\left|z_{k}\right| / 4\right)
\end{aligned}
$$

( $B(z, r)$ denotes the open ball with center at $z$ and radius $r$ ). By a simple homothety argument we see that $u_{k}$ also solve (1) (the coefficients are fixed!). Now let us assume that

$$
\mathrm{u}_{1}=\mathrm{u}_{\mathrm{o}} \text { outside } \mathrm{B}_{0} \cup \mathrm{~B}_{1} .
$$

Put

$$
s_{1}=\left\{\begin{array}{l}
u_{0} \text { outside } B_{1}, \\
u_{1} \text { on } B_{1} .
\end{array}\right.
$$

Of course, $s_{1}=u_{1}$ outside $B_{0}$. As the concept of weak solution is local, we see that $s_{1}$ solves (1). We define recurrently ( $k=2,3, \ldots$ )

$$
s_{k}= \begin{cases}s_{k-1} & \text { outside } B_{k} \\ u_{k} & \text { on } B_{k}\end{cases}
$$

We see by induction that $s_{k}$ solve (1) and

$$
\left\|s_{k}-s_{k-1}\right\|_{W}^{2} 2_{(\Omega)} \leqslant C(\Omega) 2^{-k}
$$

for every bounded domain $\Omega \subset R^{3}$. Hence the sequence $\left\{s_{k}\right\}$ has a limit $s$ in the sense of (strong) $W_{l o c}^{1,2}$ convergence. By routine arguments we see that $s$ solves (1), too. If $u_{0}$ is discontinuous at $z_{0}$, then $s$ is discontinuous at
all points $z_{k}$ (and at the origin).
Conclusion. Theorem 2 is proved if we construct a system (1) (i.e. coefficients $A_{i j}^{\alpha}(\beta)$ and its bounded weak solution $u$ such that
(5) $u$ is discontinuous at some point $z \in R^{3}, z \neq 0$,
(6) $u(2 x)=u(x)$ for all $x \$ B(z,|z| / 4) \cup B(z / 2,|z| / B)$.
3. Construction. Fix a decreasing function $\varphi \in C^{2}([0,1])$ with

$$
\varphi^{\prime}\left(1 l_{-}\right)=0, \varphi(0)=1, \varphi(1)=0
$$

and denote by $\boldsymbol{\Psi}$ its inverse. Now, prolong the functions $\boldsymbol{\varphi}$ and $\boldsymbol{\Psi}$ to $[0, \infty$ ) putting

$$
\varphi(r)=0, \quad \psi(t)=0 \text { for } r, t \in(1, \infty) .
$$

Fix a point $z \in R^{3},|z|=4$. Denote
$y=x-z$ for every $x \in R^{3}$.
Let c be a fixed constant,
(7) $\mathrm{c} \geq 2 \sup (4+r)\left|\varphi^{\prime}(r)\right|: r \in(0,1)$.

Put
(8) $\quad u^{i}(x)=\left\{\begin{array}{l}c \frac{x_{i-3}}{|x|} \text { if } i=4,5,6, \\ \varphi(|y|) \frac{y_{i}}{|y|} \text { if } i=1,2,3 .\end{array}\right.$

We have
(9) $D_{\alpha} u^{i}=\left\{\begin{array}{l}\frac{c}{|x|}\left(\delta_{i-3}^{\alpha}-\frac{x_{i-3} \alpha_{\alpha}}{|x|^{2}}\right) \text { if } i=4,5,6, \\ \frac{\varphi(|y|)}{|y|}\left(\delta_{i}^{\alpha}-\frac{y_{i} y_{\alpha}}{|y|^{2}}\right)+\varphi^{\prime}(|y|) \frac{y_{i} y_{\alpha}}{|y|^{2}} \text { if } i=1,3,3 .\end{array}\right.$

Denote
(10) $\quad b_{i}^{\alpha}=\left\{\begin{array}{l}\frac{c}{|x|}\left(\delta_{i-3^{+}}^{\alpha}+\frac{x_{i-3} 3^{x} \alpha}{|x|^{2}}\right) \text { if } i=4,5,6, \\ \frac{\varphi(|y|)}{|y|}\left(\delta_{i}^{\alpha}+\frac{y_{i} y_{\alpha}}{|y|^{2}}\right)+\varphi^{\prime}(|y|)\left(\delta_{i}^{\alpha}-\frac{y_{i} y_{\alpha}}{|y|^{2}}\right) \text { if } i=1,2,3 .\end{array}\right.$

By a routine calculation we obtain the validity of (3). Obviously, the function $u$ satisfies (5) and (6). It remains only to find coefficients $A_{i j}^{\alpha<\beta}$ such that (4) holds.
4. Coefficients. In this section we construct coefficients $A_{i j}^{\alpha \beta}(v, w)\left(v, w \in R^{3}\right)$ such that the functions $u^{i}, b_{i}^{\alpha}$ given by (8), (10) satisfy
(11) $b_{i}^{\alpha}=A_{i j}^{\alpha ; \beta}\left(\left(u^{1}, u^{2}, u^{3}\right),\left(u^{4}, u^{5}, u^{6}\right)\right) D_{\beta} u^{j}$.

We follow essentially the method due to J. Souček [6]. Denote
$Y=\boldsymbol{\varphi}(|v|)$,
$X= \begin{cases}\mid z+Y & \left.\frac{v}{|v|} \right\rvert\,, \\ 4, & v \neq 0, \\ 4=0,\end{cases}$
$h=\frac{c Y}{c Y+X \varphi(Y)}$,
$f=\frac{X \varphi(Y)}{c Y+X \varphi(Y)}$,
$g=\frac{X Y \varphi^{\prime}(Y)}{c Y+X \varphi(Y)}$.
Using the conventions

$$
\begin{aligned}
& \frac{v_{i} v_{\alpha}}{|v|^{2}}=0 \text { if } v=0, \frac{w_{i-3} w^{w}}{|w|^{2}}=0 \text { if } w=0, \\
& v_{i}=w_{i}=0 \text { if } i \notin\{1,2,3\}
\end{aligned}
$$

we define

$$
\begin{aligned}
& B_{i}^{\alpha}=h\left(\delta_{i-3}^{\alpha}+\frac{w_{i-3}{ }^{w} \alpha}{|w|^{2}}\right)+f\left(\delta_{i}^{\alpha}+\frac{v_{i} v_{\alpha}}{|v|^{2}}\right)+g\left(\delta_{i}^{\alpha}-\frac{v_{i} v^{\alpha}}{|v|^{2}}\right), \\
& T_{i}^{\alpha}=h\left(\delta_{i-3}^{\alpha}-\frac{w_{i-3}{ }^{w} \alpha}{|w|^{2}}\right)+f\left(\delta_{i}^{\alpha}-\frac{v_{i} v_{\alpha}}{|v|^{2}}\right)+g \frac{v_{i} v_{\alpha}}{|v|^{2}} \\
& (i=1, \ldots, 6 ; \alpha=1,2,3) . \text { Finally we put }
\end{aligned}
$$

$Q=\min (1,|w|)\left(3 B_{i} T_{i}-T_{i} T_{i}\right)^{-1}$,

$$
A_{i j}=\delta j_{i}^{j} \delta_{\alpha}^{\beta}+Q\left(3 B_{i}^{\alpha}-T_{i}^{\alpha}\right)\left(3 B_{j}^{\beta}-T_{j}^{\beta}\right)
$$

( $i, j=1, \ldots, 6 ; \alpha, \beta=1,2,3$ ). By (7) we verify that $Q$ is a nonnegative bounded function on $R^{3} \times R^{3}$. Indeed, we have
$3 B_{i} T_{i}-T_{i} T_{i}=\frac{\frac{3}{4} c^{2} Y^{2}+X^{2} \varphi^{2}(Y)+3\left(X \boldsymbol{\varphi}(Y)+2 X Y \varphi^{\prime}(Y)\right)^{2}+\frac{13}{4} Y^{2}\left(c^{2}-4 X^{2}\left(\boldsymbol{\varphi}^{\prime}(Y)\right)^{2}\right)}{(c Y+X \varphi(Y))^{2}}$.
The coefficients are continuous: discontinuities $\frac{v_{i} v_{\alpha}}{|v|^{2}}, \frac{w_{i-3}{ }^{W} \propto}{|w|^{2}}, X$ are always
neutralized being multiplied by vanishing continuous functions. We observe that the supremum of $\left|A_{i j}^{\alpha / \beta}\right|$ as well as the modulus of continuity of $A_{i j}^{\alpha / \beta}$ are estimated by the same quantities on $\{v:|v| \leq 1\} \times\{w:|w| \leq 1\}$. Hence the coefficients are bounded and uniformly continuous. By a direct calculation we see that (11) is satisfied.
5. Some remarks. A) If we admit discontinuous coefficients (Borel measurable only) then Theorem 1 does not hold.

Let $a_{i j}^{\alpha \beta}$ be bounded Borel measurable functions on $R^{3}$ satisfying
$a_{i j}^{\alpha \beta} \xi_{\alpha}^{i} \xi_{\beta}^{j} \geq|\xi|^{2}$ for each $\xi \in R^{9}$.
Let $v$ be a weak solution to the linear system
(12) $D_{\alpha} a_{i j}^{\alpha / \beta}(x) D_{\beta} v^{j}=0$.

Then the function $u$ defined by

$$
u^{i}=v^{i}, \quad i=1,2,3, \quad u^{i}=x_{i-3}, \quad i=4,5,6
$$

solves the quasilinear system

$$
D_{\alpha} A_{i j}^{\alpha \beta}(u) D_{\beta} u^{j}=0
$$

where

$$
A_{i j}^{\alpha \beta}(u)= \begin{cases}a_{i j}^{\infty \beta}\left(u^{4}, u^{5}, u^{6}\right) & \text { if } i, j \in\{1,2,3\}, \\ \sigma_{i}^{j} \delta_{\alpha}^{\infty} & \text { otherwise. }\end{cases}
$$

However, solutions of (12) can be everywhere discontinuous (see [4]).
B) Our example does not fill the gap between the estimate of Hausdorff dimension of singular sets given in Theorem 1 and n-3-dimensionality of singular sets in the known counterexamples. It is not even clear whether the singular set for $n=3$ can be uncountable.
C) It would be nice to have counterexamples (or further positive regularity results) in case when the quasilinear system (1) is obtained as a system in variation. The only known counterexamples (see e.g. J. Nečas [5]) have one singular point.

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Matematicko-fyzikální fakulta, Univerzita Karlova, Sokolovská 83, 18600
Praha 8, Czechoslovakia
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