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## SOLVABILITY OF INFINITE SYSTEMS OF LINEAR EQUATIONS

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Let  $S$  be a finite or infinite system of polynomial equations over a field  $F$ . It is not true in general that if every proper subsystem of  $S$  has a solution in  $F$  then  $S$  has a solution in  $F$ . For instance, the system  $S$  of polynomial equations

$$(1) \quad (a - x)y_a - 1 = 0 \quad \text{with } a \in F$$

is such that every proper subsystem of it has a solution in  $F$ , however, the entire system has no solution in  $F$ . Indeed, if  $P$  is a proper subsystem of (1) such that, say, the equation  $(b - x)y_b - 1 = 0$  does not appear in  $P$ , then a solution of  $P$  is given by  $x = b$  and  $y_a = (a - b)^{-1}$  which exists since  $a \neq b$ . Nevertheless, the entire system (1) has no solution in  $F$  since if (1) had a solution in  $F$  with, say,  $x = r$ , then the equation  $(r - x)y_r - 1 = 0$  would have no solution in  $F$ .

In sharp contrast to the above is the case of a system of linear equations over a field. As shown below any system (finite or infinite)  $L$  of linear equations over a field  $F$  has a solution in  $F$  under a weaker assumption; namely, the assumption that every finite subsystem of  $L$  has a solution in  $F$ .

**Theorem.** *Let  $(L_i = 0)_{i \in E}$  be a (not necessarily finite) system of linear equations  $L_i = 0$  over a field  $F$ . Then the system  $(L_i = 0)_{i \in E}$  has a solution in  $F$  if and only if every finite subsystem of it has a solution in  $F$ .*

**Proof.** Clearly, if the entire system has a solution in  $F$  then every finite subsystem of it has a solution in  $F$ .

Thus, in what follows we suppose that every finite subsystem of  $(L_i = 0)_{i \in E}$  has a solution in  $F$  and we prove that the entire system has a solution in  $F$ .

Let  $(x_i)_{i \in U}$  be the set of all the variables appearing in the system  $(L_i = 0)_{i \in E}$ . Moreover, let  $(L_i)_{i \in V}$  be the set of all linear polynomials in variables  $(x_i)_{i \in U}$  with coefficients in  $F$ , including the constant polynomials, i.e.,  $F \subseteq (L_i)_{i \in V}$ .

Next, let  $(L_i)_{i \in Q}$  be the subspace of  $(L_i)_{i \in V}$  generated by the set of vectors  $(L_i)_{i \in E}$ . We prove that:

$$(1) \quad r \notin (L_i)_{i \in Q} \quad \text{for every nonzero element } r \text{ of } F$$

Assume on the contrary that  $r \in (L_i)_{i \in Q}$ . Hence,  $r$  is equal to a finite linear combination of vectors belonging to  $(L_i)_{i \in E}$ , i.e.

$$(2) \quad 0 \neq r = \sum_{i \in N} r_i L_i \quad \text{for a finite subset } N \text{ of } E$$

where  $r_i \in F$  for every  $i \in N$ . However, by our supposition, the finite system  $(L_i = 0)_{i \in N}$  has a solution in  $F$ . Thus, there exists a substitution by elements of  $F$  of the variables appearing in  $(L_i)_{i \in N}$  such that the right-hand side of the equality in (2) is equal to zero. But this contradicts (2). Hence, our assumption is false and (1) is established.

Now, let  $(L_i)_{i \in B}$  be a basis for the subspace  $(L_i)_{i \in Q}$  and let 1 be the multiplicative unit of  $F$ . From (1) and the axiom of choice it follows that  $\{1\} \cup (L_i)_{i \in B}$  can be enlarged to a basis, say,

$$(3) \quad \{1\} \cup (L_i)_{i \in B} \cup (L_i)_{i \in D}.$$

for the entire vector space  $(L_i)_{i \in V}$ .

Finally, based on (3), we consider the linear mapping  $f$  from  $(L_i)_{i \in V}$  onto  $F$  defined by:

$$(4) \quad f(1) = 1 \quad \text{and} \quad f(L_i) = 0 \quad \text{for every} \quad i \in (B \cup D)$$

Since  $(L_i)_{i \in B}$  is a basis for  $(L_i)_{i \in Q}$ , we see that  $f(L_i) = 0$  for every  $i \in E$ . But then from the linear additivity of  $f$ , it follows that  $r_i = f(x_i)$  for every  $i \in U$  gives a solution (in  $F$ ) of the entire system  $(L_i = 0)_{i \in E}$ , as desired.

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