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# A NOTE TO THE CONSTRUCTION OF A LINEAR DIFFERENTIAL EQUATION WITH GIVEN SOLUTIONS 

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0. Let be given $n$ functions with continuous $n$-th derivative in the interval $(a, b)$, such that their Wronskian is different from zero in this interval. It is a well known fact that then there exists a homogeneous linear differential equation of the $n$-th order with continuous coefficients in the form

$$
x^{(n)}+a_{1}(t) x^{(n-1)}+\ldots+a_{n-1}(t) x^{\prime}+a_{n}(t) x=0
$$

such that the given functions form its fundamental system of solutions.
We shall show that a similar result holds even when the number of given functions is $k<n$ and if we know only that the $k \times n$-matrix constructed from the given functions and their derivatives in a similar way as the Wronski matrix has the maximum rank, i.e. $k$, at each point of the interval $(a, b)$.

1. Let us denote by $W\left(f_{1}, f_{2}, \ldots, f_{k}\right)(t)$ the value of the Wronskian of functions $f_{1}, f_{2}, \ldots, f_{k}$ at $t$.

Theorem 1. Let $a, b$ be real numbers, $a<b, k$ positive integer. Let functions $x_{1}(t), x_{2}(t), \ldots, x_{k}(t)$ have continuous derivative of the $k$-th order in the interval $(a, b)$ and let the matrix

$$
\left(\begin{array}{cccc}
x_{1}(t), & x_{2}(t), & \ldots, & x_{k}(t) \\
x_{1}^{\prime}(t), & x_{2}^{\prime}(t), & \ldots, & x_{k}^{\prime}(t) \\
\ldots \ldots & \ldots(\ldots & \ldots & \ldots \\
x_{1}^{(k)}(t), & x_{2}^{(k)}(t), & \ldots, & x_{k}^{(k)}(t)
\end{array}\right)
$$

be of the rank $k$ for all $t \in(a, b)$.
Then there exists a function $x_{k+1}(t)$ with continuous $k$-th derivative in $(a, b)$, such that

$$
W\left(x_{1}, x_{2}, \ldots, x_{k}, x_{k+1}\right)(t) \neq 0
$$

for all $t \in(a, b)$.

The assumptions of Theorem 1 obviously do not guarantee that the Wronskian of functions $x_{1}(t), x_{2}(t), \ldots, x_{k}(t)$ is different from zero in $(a, b)$. Nevertheless, the following lemma holds:

Lemma. Let $a, b$ be real numbers, $a<b, k$, $s$ positive integers, $s \geqq k$. Let functions $x_{1}(t), x_{2}(t), \ldots, x_{k}(t)$ have continuous derivative of the $s$-th order and let the matrix

$$
\left(\begin{array}{cccc}
x_{1}(t), & x_{2}(t), & \ldots, & x_{k}^{\prime}(t)  \tag{1}\\
x_{1}^{\prime}(t), & x_{2}^{\prime}(t), & \ldots, & x_{k}^{\prime}(t) \\
\ldots \ldots & \ldots & \ldots & \ldots . \\
x_{1}^{(s)}(t), & x_{2}^{(s)}(t), & \ldots, & x_{k}^{(s)}(t)
\end{array}\right)
$$

be of the rank $k$ for all $t \in(a, b)$.
Then there exists $a$ set of numbers $a_{m}, m=0, \pm 1, \pm 2, \ldots, a<\ldots<a_{-n}<\ldots$ $\ldots<a_{-1}<a_{0}<a_{1}<\ldots<a_{n}<\ldots<b$,

$$
\lim _{n \rightarrow \infty} a_{n}=b, \quad \lim _{n \rightarrow \infty} a_{-n}=a
$$

such that the Wronskian $W\left(x_{1}, x_{2}, \ldots, x_{k}\right)(t) \neq 0$ for all $t \in(a, b), t \neq a_{m}, m$ integer.
Proof of the Lemma follows from Theorem 1 [1]. Denote by $N$ the set of all $t \in(a, b)$ such that $W\left(x_{1}, x_{2}, \ldots, x_{k}\right)(t)=0$ and assume that there is an accumulation point $c$ of the set $N, c \in(a, b)$. The continuity of $W\left(x_{1}, x_{2}, \ldots, x_{k}\right)(t)$ implies $c \in N$ which is a contradiction with Theorem 1 [1].

Note that the assumptions of Theorem 1 are those of lemma with $s=k$.
Proof of Theorem 1. Let us choose numbers $\alpha_{0}^{i}, i=0,1,2, \ldots, k$ such that

$$
\left|\begin{array}{llll}
x_{1}\left(a_{0}\right), & x_{2}\left(a_{0}\right), & \ldots, & x_{k}\left(a_{0}\right), \\
\alpha_{0}^{0} \\
x_{1}^{\prime}\left(a_{0}\right), & x_{2}^{\prime}\left(a_{0}\right), & \ldots, x_{k}^{\prime}\left(a_{0}\right), & \alpha_{0}^{1} \\
\ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots & \ldots \ldots \\
x_{1}^{(k)}\left(a_{0}\right), & x_{2}^{(k)}\left(a_{0}\right), & \ldots, x_{k}^{(k)}\left(a_{0}\right), & \alpha_{0}^{k}
\end{array}\right| \neq 0
$$

and a function $u(t)$ with continuous $k$-th derivative in $\left(a_{-1}, a_{1}\right), u^{(i)}\left(a_{0}\right)=\alpha_{0}^{i}$ for $i=0,1,2, \ldots, k .^{1}$ ) Evidently there exists $\varepsilon_{0}>0$ such that $W\left(x_{1}, x_{2}, \ldots, x_{k}, u\right)(t) \neq$ $\neq 0$ for $t \in\left\langle a_{0}-\varepsilon_{0}, a_{0}+\varepsilon_{0}\right\rangle$. Put

$$
x_{k+1}(t)=u(t) \quad \text { for } \quad t \in\left\langle a_{0}-\varepsilon_{0}, a_{0}+\varepsilon_{0}\right\rangle
$$

Let us now suppose that the function $x_{k+1}(t)$ has been already defined (and satisfies Theorem 1) on $\left\langle a_{-j}-\varepsilon, a_{j}+\varepsilon\right\rangle, \varepsilon>0, j$ nonnegative integer.

[^0]Let us choose a function $f_{j}(t)$ continuous on $\left\langle a_{j}, a_{j+1}\right\rangle$ and a function $f_{-j}(t)$ continuous on $\left\langle a_{-j-1}, a_{-j}\right\rangle$ such that

$$
f_{j}(t) \neq 0, \quad f_{-j}(t) \neq 0 \quad \text { for } \quad t \in\left\langle a_{j}, a_{j+1}\right\rangle, \quad t \in\left\langle a_{-j-1}, a_{-j}\right\rangle,
$$

respectively. Moreover, let

$$
\begin{align*}
f_{j}\left(a_{j}+\varepsilon\right) & =W\left(x_{1}, x_{2}, \ldots, x_{k}, x_{k+1}\right)\left(a_{j}+\varepsilon\right),  \tag{2}\\
f_{-j}\left(a_{-j}-\varepsilon\right) & =W\left(x_{1}, x_{2}, \ldots, x_{k}, x_{k+1}\right)\left(a_{-j}-\varepsilon\right)
\end{align*}
$$

(Since $x_{k+1}(t)$ is defined and satisfies Theorem 1 on $\left\langle a_{-j}-\varepsilon, a_{j}+\varepsilon\right\rangle$, the values of the Wronskian on the righthand side of the last two equations are nonzero and hence such functions $f_{j}, f_{-j}$ exist.)

Let us consider differential equations

$$
\left|\begin{array}{cccc}
x_{1}(t), & x_{2}(t), & \ldots, & x_{k}(t),  \tag{3}\\
x_{1}^{\prime}(t), & x_{2}^{\prime}(t), & \ldots, & x_{k}^{\prime}(t), \\
y^{\prime}(t) \\
\ldots \ldots \ldots & \ldots & \ldots \ldots \ldots \ldots & \ldots \ldots \\
x_{1}^{(k)}(t), & x_{2}^{(k)}(t), & \ldots, & x_{k}^{(k)}(t), \\
y^{(k)}(t)
\end{array}\right|=f_{J}(t)
$$

$J= \pm j$. The coefficient at the highest derivative $y^{(k)}(t)$ in these equations is $W\left(x_{1}, x_{2}, \ldots, x_{k}\right)(t)$. Denote by $Y_{+}(t), Y_{-}(t)$ the solution of the equation with $J=j$, $J=-j$ and with the initial condition

$$
\begin{equation*}
Y_{+}^{(i)}\left(a_{j}+\varepsilon\right)=x_{k+1}^{(i)}\left(a_{j}+\varepsilon\right), \quad Y_{-}^{(i)}\left(a_{-j}-\varepsilon\right)=x_{k+1}^{(i)}\left(a_{-j}-\varepsilon\right) \tag{4}
\end{equation*}
$$

respectively, $i=0,1, \ldots, k-1$. Since $W\left(x_{1}, x_{2}, \ldots, x_{k}\right)(t) \neq 0$ for $t \in\left(a_{j}, a_{j+1}\right) \cup$ $\cup\left(a_{-j-1}, a_{-j}\right)$, the functions $Y_{+}(t), Y_{-}(t)$ are continuous and have continuous $k$-th derivative in $\left\langle a_{j}+\varepsilon, a_{j+1}\right),\left(a_{-j-1}, a_{-j}-\varepsilon\right\rangle$, respectively. Moreover, the inequalities

$$
W\left(x_{1}, x_{2}, \ldots, x_{k}, Y_{+}\right)(t) \neq 0, \quad W\left(x_{1}, x_{2}, \ldots, x_{k}, Y_{-}\right)(t) \neq 0
$$

hold in the respective intervals.
Further, let us choose (analogously to the first part of the proof) the numbers $\alpha_{j+1}^{i}, \alpha_{-j-1}^{i}, i=0,1, \ldots, k$ such that the determinant

$$
\left|\begin{array}{cccc}
x_{1}\left(a_{j+1}\right), & x_{2}\left(a_{j+1}\right), & \ldots, x_{k}\left(a_{j+1}\right), & \alpha_{j+1}^{0} \\
x_{1}^{\prime}\left(a_{j+1}\right), & x_{2}^{\prime}\left(a_{j+1}\right), & \ldots, x_{k}^{\prime}\left(a_{j+1}\right), & \alpha_{j+1}^{1} \\
\ldots \ldots \ldots & \ldots \ldots \ldots \ldots \ldots \ldots \ldots & \ldots \ldots & \ldots \ldots \\
x_{1}^{(k)}\left(a_{j+1}\right), & x_{2}^{(k)}\left(a_{j+1}\right), & \ldots, x_{k}^{(k)}\left(a_{j+1}\right), & \alpha_{j+1}^{k}
\end{array}\right|
$$

as well as the determinant obtained by replacing the index $j+1$ by $-j-1$ are different from zero. Let $u_{j+1}(t), u_{-j-1}(t)$ be functions with continuous $k$-th derivative in $\left\langle a_{j}, a_{j+2}\right\rangle,\left\langle a_{-j-2}, a_{-j}\right\rangle$ respectively and $u_{j+1}^{(i)}\left(a_{j+1}\right)=\alpha_{j+1}^{i}, u_{-j-1}^{(i)}\left(a_{-j-1}\right)=$
$=\alpha_{-j-1}^{i}$ for $i=0,1, \ldots, k$. (Such functions obviously exist.) From the continuity of $W\left(x_{1}, x_{2}, \ldots, x_{k}, u_{j+1}\right)(t)$ and $W\left(x_{1}, x_{2}, \ldots, x_{k}, u_{-j-1}\right)(t)$ there follows that

$$
W\left(x_{1}, x_{2}, \ldots, x_{k}, u_{j+1}\right)(t) \neq 0, \quad W\left(x_{1}, x_{2}, \ldots, x_{k}, u_{-j-1}\right)(t) \neq 0
$$

in some interval $\left\langle a_{j+1}-\varepsilon^{\prime}, a_{j+1}+\varepsilon^{\prime}\right\rangle,\left\langle a_{-j-1}-\varepsilon^{\prime}, a_{-j-1}+\varepsilon^{\prime}\right\rangle$ respectively, $\varepsilon^{\prime}>0$.

In the interval $\left\langle a_{j+1}-\varepsilon^{\prime}, a_{j+1}+\varepsilon^{\prime}\right\rangle$ put

$$
v_{j+1}(t)=\beta_{0} u_{j+1}(t)+\sum_{p=1}^{k} \beta_{p} x_{p}(t)
$$

the constants $\beta_{0}, \beta_{1}, \ldots, \beta_{k}$ being the solution of the linear system

$$
\beta_{0} u_{j+1}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right)+\sum_{p=1}^{k} \beta_{p} x_{p}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right)=Y_{+}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right),
$$

$i=0,1, \ldots, k$. Since from the choice of $u_{j+1}(t)$ and $\varepsilon^{\prime}$ there follows that the determinant of this system is nonzero, there exists a unique solution $\beta_{0}, \beta_{1}, \ldots, \beta_{k}{ }^{2}$ )

Analogously put

$$
v_{-j-1}(t)=\gamma_{0} u_{-j-1}(t)+\sum_{p=1}^{k} \gamma_{p} x_{p}(t)
$$

in $\left\langle a_{-j-1}-\varepsilon^{\prime}, a_{-j-1}+\varepsilon^{\prime}\right\rangle$; we obtain the constants $\gamma_{0}, \gamma_{1}, \ldots, \gamma_{k}$ as the (unique) solution of the system

$$
\gamma_{0} u_{-j-1}^{(i)}\left(a_{-j-1}+\varepsilon^{\prime}\right)+\sum_{p=1}^{k} \gamma_{p} x_{p}^{(i)}\left(a_{-j-1}+\varepsilon^{\prime}\right)=Y_{-}^{(i)}\left(a_{-j-1}+\varepsilon^{\prime}\right)
$$

Let us now define

$$
x_{k+1}(t)=\left\{\begin{array}{lll}
Y_{+}(t) & \text { in the interval } & \left\langle a_{j}+\varepsilon, a_{j+1}-\varepsilon^{\prime}\right\rangle \\
v_{j+1}(t) & \text { in the interval } & \left\langle a_{j+1}-\varepsilon^{\prime}, a_{j+1}+\varepsilon^{\prime}\right\rangle \\
Y_{-}(t) & \text { in the interval } & \left\langle a_{-j-1}+\varepsilon^{\prime}, a_{-j}-\varepsilon\right\rangle \\
v_{-j-1}(t) & \text { in the interval } & \left\langle a_{-j-1}-\varepsilon^{\prime}, a_{-j-1}+\varepsilon^{\prime}\right\rangle
\end{array}\right.
$$

By this way it is evidently possible to define the function $x_{k+1}(t)$ on the whole interval $(a, b)$. It follows from the construction that $x_{k+1}(t)$ has all properties required by the assertion of Theorem 1. It is just necessary to verify that the $k$-th derivative $x_{k+1}^{(k)}(t)$ is continuous at the points $a_{j}+\varepsilon, a_{-j}-\varepsilon$.

There is

$$
\begin{gathered}
W\left(x_{1}, x_{2}, \ldots, x_{k}, Y_{+}\right)\left(a_{j}+\varepsilon\right)=f_{j}\left(a_{j}+\varepsilon\right)= \\
=W\left(x_{1}, x_{2}, \ldots, x_{k}, x_{k+1}\right)\left(a_{j}+\varepsilon\right)
\end{gathered}
$$

according to the choice of $f_{j}(t)$; moreover, $Y_{+}(t)$ fulfils the initial conditions $Y_{+}^{(i)}\left(a_{j}+\right.$

[^1]$+\varepsilon)=x_{k+1}^{(i)}\left(a_{j}+\varepsilon\right)$ for $i=0,1, \ldots, k-1$, which implies immediately
$$
Y_{+}^{(k)}\left(a_{j}+\varepsilon\right)=x_{k+1}^{(k)}\left(a_{j}+\varepsilon\right)
$$
(the derivative of $Y_{+}$being taken from the right, the derivative of $x_{k+1}$ from the left). The continuity of the $k$-th derivative $x_{k+1}^{(k)}(t)$ at $a_{-j}-\varepsilon$ is proved quite analogously.
2. In this article we shall generalize Theorem 1 assuming that the functions $x_{1}, x_{2}, \ldots, x_{k}$ have continuous derivatives of the $s$-th order, $s \geqq k$ and that the matrix from Theorem 1 has $s+1$ rows. (For $s=k$ we get Theorem 1.) We shall prove

Theorem 2. Let $a, b$ be real numbers, $a<b, k$, $s$ positive integers, $s \geqq k$. Let functions $x_{1}(t), x_{2}(t), \ldots, x_{k}(t)$ have continuous derivatives of the s-th order in the interval $(a, b)$ and let the matrix (1) be of the rank $k$ for all $t \in(a, b)$.

Then there exists a function $x_{k+1}(t)$ with continuous $s$-th derivative in $(a, b)$ such that the matrix
is of the rank $k+1$ for all $t \in(a, b)$.
Proof will follow the same lines as that of Theorem 1. If $a_{m}, m=0, \pm 1, \pm 2, \ldots$ are the points from Lemma ${ }^{3}$ ) then again $W\left(x_{1}, x_{2}, \ldots, x_{k}\right)(t) \neq 0$ for all $t \in(a, b)$, $t \neq a_{m}, m=0, \pm 1, \pm 2, \ldots$. We start constructing $x_{k+1}(t)$ at $a_{0}$ again, choosing numbers $\alpha_{0}^{i}, i=0,1,2, \ldots, s$, a function $u(t)$ and $\varepsilon_{0}>0$ so that
(i) the matrix

$$
\left(\begin{array}{ccccc}
x_{1}\left(a_{0}\right), & x_{2}\left(a_{0}\right), & \ldots, & x_{k}\left(a_{0}\right), & \alpha_{0}^{0} \\
x_{1}^{\prime}\left(a_{0}\right), & x_{2}^{\prime}\left(a_{0}\right), & \ldots, & x_{k}^{\prime}\left(a_{0}\right), & \alpha_{0}^{1} \\
\ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots & \ldots \\
x_{1}^{(s)}\left(a_{0}\right), & x_{2}^{(s)}\left(a_{0}\right), & \ldots, & x_{k}^{(s)}\left(a_{0}\right), & \alpha_{0}^{s}
\end{array}\right)
$$

has the rank $k+1$;
(ii) $u(t)$ has continuous $s$-th derivative;
(iii) $u^{(i)}\left(a_{0}\right)=\alpha_{0}^{i}, i=0,1,2, \ldots, s$;
(iv) the matrix

$$
\left(\begin{array}{ccccc}
x_{1}(t), & x_{2}(t), & \ldots, & x_{k}(t), & u(t) \\
x_{1}^{\prime}(t), & x_{2}^{\prime}(t), & \ldots, & x_{k}^{\prime}(t), & u^{\prime}(t) \\
\ldots \ldots & \ldots \ldots \ldots \ldots \ldots \ldots & \ldots & \ldots & \ldots \\
x_{1}^{(s)}(t), & x_{2}^{(s)}(t), & \ldots, & x_{k}^{(s)}(t), & u^{(s)}(t)
\end{array}\right)
$$

has the rank $k+1$ for all $t \in\left\langle a_{0}-\varepsilon_{0}, a_{0}+\varepsilon_{0}\right\rangle$.

[^2]The functions $x_{1}(t), x_{2}(t), \ldots, x_{k}(t), u(t)$ satisfy the assumptions of Lemma on $\left(a_{0}-\varepsilon_{0}, a_{0}+\varepsilon_{0}\right)$. Hence there is $\varepsilon>0$ such that $W\left(x_{1}, x_{2}, \ldots, x_{k}, u\right)(t) \neq 0$ for all $t \neq a_{0}, t \in\left\langle a_{0}-\varepsilon, a_{0}+\varepsilon\right\rangle^{4}$ ); for $t=a_{0}$ we have (iv).

Put $x_{k+1}(t)=u(t)$ for $t \in\left\langle a_{0}-\varepsilon, a_{0}+\varepsilon\right\rangle$. If $x_{k+1}(t)$ is defined (and satisfies Theorem 2) for all $t \in\left\langle a_{-j}-\varepsilon, a_{j}+\varepsilon\right\rangle$,

$$
W\left(x_{1}, x_{2}, \ldots, x_{k}, x_{k+1}\right)(t) \neq 0
$$

for $t \neq a_{m}, m=0, \pm 1, \pm 2, \ldots, \pm j$, let us consider again equation (3) where the function $f_{J}(t), J= \pm j$ is defined in the following manner:
(i') $f_{J}$ is defined and has continuous $s$-th derivative in the intervals $\left\langle a_{j}, a_{j+1}\right\rangle$, $\left\langle a_{-j-1}, a_{-j}\right\rangle$ respectively;
(ii') $f_{J}(t) \neq 0$ in its interval of definition;
(iii') the values $f_{j}^{(i)}\left(a_{j}+\varepsilon\right), f_{-j}^{(i)}\left(a_{-j}-\varepsilon\right)$ are given so as to satisfy equations

$$
\begin{gathered}
\frac{\mathrm{d}^{i}}{\mathrm{~d} t^{i}} W\left(x_{1}, x_{2}, \ldots, x_{k}, x_{k+1}\right)\left(a_{j}+\varepsilon\right)=f_{j}^{(i)}\left(a_{j}+\varepsilon\right) \\
\frac{\mathrm{d}^{i}}{\mathrm{~d} t^{i}} W\left(x_{1}, x_{2}, \ldots, x_{k}, x_{k+1}\right)\left(a_{-j}-\varepsilon\right)=f_{-j}^{(i)}\left(a_{-j}-\varepsilon\right), \\
i=0,1, \ldots, s-k\left(\text { for } i=0, \text { this equations are equivalent to (2)). }{ }^{5}\right)
\end{gathered}
$$

The solutions $Y_{+}, Y_{-}$with the corresponding initial condition (4) have then continuous $s$-th derivative (since the same holds for $x_{1}, x_{2}, \ldots, x_{k}, f_{J}$ ) and, moreover,

$$
Y_{+}^{(i)}\left(a_{j}+\varepsilon\right)=x_{k+1}^{(i)}\left(a_{j}+\varepsilon\right), \quad Y_{-}^{(i)}\left(a_{-j}-\varepsilon\right)=\dot{x}_{k+1}^{(i)}\left(a_{-j}-\varepsilon\right)
$$

for $i=0,1,2, \ldots, s$. In fact, for $i=0,1, \ldots, k-1$ these relations coincide with the initial conditions; for $i=k, k+1, \ldots, s$ we get them successively from (iii').

Let us now choose numbers ${ }_{p} \alpha_{j+1}^{i},{ }_{p} \alpha_{-j-1}^{i}, i=0,1,2, \ldots, s, p=k+1, k+2, \ldots$ $\ldots, s+1$ so that

$$
\left.\left|\begin{array}{llll}
x_{1}\left(a_{j+1}\right), & \ldots, x_{k}\left(a_{j+1}\right), & { }_{k+1} \alpha_{j+1}^{0}, \ldots,{ }_{s+1} \alpha_{j+1}^{0}  \tag{5}\\
x_{1}^{\prime}\left(a_{j+1}\right), & \ldots, x_{k}^{\prime}\left(a_{j+1}\right), & k+1 \alpha_{j+1}^{1}, \ldots,{ }_{s+1} \alpha_{j+1}^{1} \\
\ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \ldots \\
x_{1}^{(s)}\left(a_{j+1}\right), \ldots, x_{k}^{(s)}\left(a_{j+1}\right), & { }_{k+1} \alpha_{j+1}^{s}, \ldots, s+1 \alpha_{j+1}^{s}
\end{array}\right| \neq 0{ }^{6}\right)
$$

and similarly for $a_{-j-1}$. Let ${ }_{p} u_{j+1}(t), p=k+1, k+2, \ldots, s+1$ be functions that fulfil:
( $\mathrm{i}^{\prime \prime}$ ) they have continuous $s$-th derivative in $\left\langle a_{j}, a_{j+2}\right\rangle,\left\langle a_{-j-2}, a_{-j}\right\rangle$ respectively;

[^3](ii") ${ }_{p} u_{j+1}^{(i)}\left(a_{j+1}\right)={ }_{p} \alpha_{j+1}^{i},{ }_{p} u_{-j-1}^{(i)}\left(a_{-j-1}\right)={ }_{p} \alpha_{-j-1}^{i}$ for $i=0,1,2, \ldots, s, p=k+$ $+1, k+2, \ldots, s+1$.
Again there exists $\varepsilon^{\prime}>0$ such that
\[

$$
\begin{align*}
& W\left(x_{1}, x_{2}, \ldots, x_{k}, k_{k+1} u_{j+1}, \ldots, s+1 u_{j+1}\right)(t) \neq 0  \tag{6}\\
& W\left(x_{1}, x_{2}, \ldots, x_{k}, k_{k+1} u_{-j-1}, \ldots,{ }_{s+1} u_{-j-1}\right)(t) \neq 0
\end{align*}
$$
\]

holds for all $t$ from the interval $\left\langle a_{j+1}-\varepsilon^{\prime}, a_{j+1}+\varepsilon^{\prime}\right\rangle,\left\langle a_{-j-1}-\varepsilon^{\prime}, a_{-j-1}+\varepsilon^{\prime}\right\rangle$, respectively.

Now put

$$
v_{j+1}(t)=\sum_{p=1}^{k} \beta_{p} x_{p}(t)+\sum_{p=k+1}^{s+1} \beta_{p} u_{j+1}(t)
$$

the constants $\beta_{p}, p=1,2, \ldots, s+1$ being the solution of the system

$$
\sum_{p=1}^{k} \beta_{p} x_{p}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right)+\sum_{p=k+1}^{s+1} \beta_{p p} u_{j+1}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right)=Y_{+}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right),
$$

$i=0,1, \ldots, s^{7}$ ) Since the determinant of the system is nonzero according to (6) there exists a unique solution $\beta_{1}, \beta_{2}, \ldots, \beta_{s+1}$. The constants $\beta_{k+1}, \ldots, \beta_{s+1}$ are not simultaneously equal to zero. In fact, if

$$
v_{j+1}(t)=\sum_{p=1}^{k} \beta_{p} x_{p}(t)
$$

then also

$$
Y_{+}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right)=\sum_{p=1}^{k} \beta_{p} x_{p}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right)
$$

$i=0,1,2, \ldots, s$. However, this means that

$$
W\left(x_{1}, x_{2}, \ldots, x_{k}, Y_{+}\right)\left(a_{j+1}-\varepsilon^{\prime}\right)=0
$$

which is not possible according to the construction of $Y_{+}$.
Further, the definition of $\beta_{p}$ implies that

$$
Y_{+}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right)=v_{j+1}^{(i)}\left(a_{j+1}-\varepsilon^{\prime}\right),
$$

$i=0,1,2, \ldots, s$.
Analogously we define the function $v_{-j-1}(t)$ in the interval $\left\langle a_{-j-1}-\varepsilon^{\prime}, a_{-j-1}+\right.$ $\left.+\varepsilon^{\prime}\right\rangle$. (It may be necessary to make $\varepsilon^{\prime}$ smaller.)

[^4]
## Let us now put

$$
x_{k+1}(t)=\left\{\begin{array}{lll}
Y_{+}(t) & \text { in the interval } & \left\langle a_{j}+\varepsilon, a_{j+1}-\varepsilon^{\prime}\right\rangle \\
v_{j+1}(t) & \text { in the interval } & \left\langle a_{j+1}-\varepsilon^{\prime}, a_{j+1}+\varepsilon^{\prime}\right\rangle \\
Y_{-}(t) & \text { in the interval } & \left\langle a_{-j-1}+\varepsilon^{\prime}, a_{-j}-\varepsilon\right\rangle \\
v_{-j-1}(t) \text { in the interval } & \left\langle a_{-j-1}-\varepsilon^{\prime}, a_{-j-1}+\varepsilon^{\prime}\right\rangle .
\end{array}\right.
$$

Continuing like that we can define $x_{k+1}(t)$ for all $t \in(a, b)$. It is evident that all assertions of Theorem 2 hold, in particular the continuity of the $s$-th derivative of $x_{k+1}(t)$. Moreover, it is evident that even

$$
W\left(x_{1}, x_{2}, \ldots, x_{k+1}\right)(t) \neq 0
$$

for all $t \in(a, b), t \neq a_{m}, m=0, \pm 1, \pm 2, \ldots$
3. From the both Theorems there follows

Corollary. Let be given functions $x_{1}(t), x_{2}(t), \ldots, x_{k}(t)$ with continuous derivative of $n$-th order in $(a, b), k<n$. Let the matrix

$$
\left(\begin{array}{lll}
x_{1}(t), & x_{2}(t), & \ldots, x_{k}(t) \\
x_{1}^{\prime}(t), & x_{2}^{\prime}(t), & \ldots, x_{k}^{\prime}(t) \\
\ldots \ldots \ldots \ldots \ldots & \ldots \ldots & \ldots, \ldots \\
x_{1}^{(n-1)}(t), & x_{2}^{(n-1)}(t), & \ldots, x_{k}^{(n-1)}(t)
\end{array}\right)
$$

have the rank $k$ for all $t \in(a, b)$.
Then there exists a differential equation

$$
x^{(n)}+a_{1}(t) x^{(n-1)}+\ldots+a_{n-1}(t) x^{\prime}+a_{n}(t) x=0
$$

with continuous coefficients $a_{i}(t), i=1,2, \ldots, n$ such that the functions $x_{1}(t), x_{2}(t), \ldots$ $\ldots, x_{k}(t)$ are its solutions on $(a, b)$.

Proof. Completing the system of functions $x_{1}(t), x_{2}(t), \ldots, x_{k}(t)$ according to Theorem $2(n-k)$-times we get a system $x_{1}(t), x_{2}(t), \ldots, x_{n}(t)$ with the Wronskian different from zero for all $t \in(a, b)$. The functions $x_{k+1}(t), \ldots, x_{n}(t)$ have continuous derivatives of the $(n-1)$-st order.
To be able to write the required differential equation, it is sufficient to use Lemma 6 [ $2, \mathrm{p} .76$ ]. According to this Lemma, to any function $x(t)$ with continuous $k$-th derivative in $(a, b)$ and to an arbitrary sequence of numbers $\varepsilon_{p}>0, p=0,1, \ldots$, $\lim _{p \rightarrow \infty} \varepsilon_{p}=0$, there exists a function $\xi(t)$ analytic in $(a, b)$ and such that for the difference

$$
\Delta^{(i)}(t)=\left|x^{(i)}(t)-\xi^{(i)}(t)\right|
$$

there is $\Delta^{(i)}(t)<\varepsilon_{p}, i=0,1, \therefore, k$ for $t \in\left(a, a_{-p}\right\rangle \cup\left\langle a_{p}, b\right)$. It is evident that by a proper choice of numbers $\varepsilon_{p}$ it is possible to keep - after replacing $x_{k+q}(t)$ by
$\xi_{k+q}(t), q=1,2, \ldots, n-q-$ the inequality for the Wronskian, viz. $W\left(x_{1}, x_{2}, \ldots\right.$ $\left.\ldots, x_{k}, \xi_{k+1}, \ldots, \xi_{n}\right)(t) \neq 0$. Now the required equation can be written in the form

$$
W\left(x_{1}, x_{2}, \ldots, x_{k}, \xi_{k+1}, \ldots, \xi_{n}, x\right)(t)=0
$$

whose all coefficients are continuous in $(a, b)$ and the coefficient at $x^{(n)}$ is different from zero since it is equal to $W\left(x_{1}, x_{2}, \ldots, x_{k}, \xi_{k+1}, \ldots, \xi_{n}\right)(t)$.

Author's Note. The paper being already in print, the author's attention was drawn to the paper by Ascoli, G.: Sulla decomposizione degli operatori differenziali lineari. Revista (Univ. Nac. Tucuman), Ser. A, 1 (1940), pp. 189-215, where (p. 210) a theorem identical to Corollary of the present paper is proved. However, the method of Ascoli yields just one equation (uniquely determined by the given functions) which has the required properties.

## References

[1] Jarnik V.: Linear Dependence of Functions of One Real Variable. Čas. pěst. mat. 80 (1955), pp. 32-43 (Czech; French and Russian Summaries).
[2] Whitney H.: Analytic Extensions of Differentiable Functions Defined in Closed Sets. TAMS 36 (1934), pp. 63-89.

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[^0]:    ${ }^{1}$ ) We denote $u^{(0)}(t)=u(t)$.

[^1]:    ${ }^{2}$ ) Moreover, $\beta_{0} \neq 0$ since otherwise $W\left(x_{1}, x_{2}, \ldots, x_{k}, Y_{+}\right)\left(a_{j+1}-\varepsilon^{\prime}\right)=0$; hence $W\left(x_{1}, x_{2}, \ldots, x_{k}, v_{j+1}\right)(t) \neq 0$ implies $W\left(x_{1}, x_{2}, \ldots, x_{k}, u_{j+1}\right)(t) \neq 0$ and conversely.

[^2]:    ${ }^{3}$ ) Actually, the assumptions of Lemma are the same as those of Theorem 2.

[^3]:    ${ }^{4}$ ) Otherwise $a_{0}$ would be an accumulation point of the zero points of the Wronskian which contradicts Lemma.
    ${ }^{5}$ ) This does not contradict (ii') since in particular $W\left(x_{1}, x_{2}, \ldots, x_{k+1}\right)\left(a_{j}+\varepsilon\right) \neq 0 \neq$ $\neq W\left(x_{1}, x_{2}, \ldots, x_{k+1}\right)\left(a_{-j}-\varepsilon\right)$.
    ${ }^{6}$ ) This is possible since the rank of (1) for $t=a_{j+1}$ is $k$.

[^4]:    ${ }^{7}$ ) We have here the derivatives from the left and from the right analogously to the proof of Theorem 1.

