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A NOTE TO THE CONSTRUCTION OF A LINEAR DIFFERENTIAL EQUATION WITH GIVEN SOLUTIONS

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0. Let be given n functions with continuous n-th derivative in the interval (a, b), such that their Wronskian is different from zero in this interval. It is a well known fact that then there exists a homogeneous linear differential equation of the n-th order with continuous coefficients in the form

$$x^{(n)} + a_1(t) x^{(n-1)} + \ldots + a_{n-1}(t) x' + a_n(t) x = 0$$

such that the given functions form its fundamental system of solutions.

We shall show that a similar result holds even when the number of given functions is k < n and if we know only that the $k \times n$ -matrix constructed from the given functions and their derivatives in a similar way as the Wronski matrix has the maximum rank, i.e. k, at each point of the interval (a, b).

1. Let us denote by $W(f_1, f_2, ..., f_k)(t)$ the value of the Wronskian of functions $f_1, f_2, ..., f_k$ at t.

Theorem 1. Let a, b be real numbers, a < b, k positive integer. Let functions $x_1(t), x_2(t), \ldots, x_k(t)$ have continuous derivative of the k-th order in the interval (a, b) and let the matrix

$\begin{vmatrix} x_1(t), \\ x_1'(t), \end{vmatrix}$	$x_2(t), x_2'(t), x_2'(t),$	••••, ••••,	$\begin{array}{c} x_k(t) \\ x'_k(t) \end{array}$	
$x_1^{(k)}(t),$	$\frac{\ldots}{x_2^{(k)}(t)},$	••••	$\frac{x_k^{(k)}(t)}{x_k^{(k)}(t)}$	

be of the rank k for all $t \in (a, b)$.

Then there exists a function $x_{k+1}(t)$ with continuous k-th derivative in (a, b), such that

$$W(x_1, x_2, ..., x_k, x_{k+1})(t) \neq 0$$

for all $t \in (a, b)$.

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The assumptions of Theorem 1 obviously do not guarantee that the Wronskian of functions $x_1(t), x_2(t), \ldots, x_k(t)$ is different from zero in (a, b). Nevertheless, the following lemma holds:

Lemma. Let a, b be real numbers, a < b, k, s positive integers, $s \ge k$. Let functions $x_1(t), x_2(t), ..., x_k(t)$ have continuous derivative of the s-th order and let the matrix

(1) $\begin{pmatrix} x_1(t), x_2(t), \dots, x_k^{\tilde{k}}(t) \\ x'_1(t), x'_2(t), \dots, x'_k(t) \\ \dots \\ x_1^{(s)}(t), x_2^{(s)}(t), \dots, x_k^{(s)}(t) \end{pmatrix}$

be of the rank k for all $t \in (a, b)$.

Then there exists a set of numbers a_m , $m = 0, \pm 1, \pm 2, ..., a < ... < a_{-n} < ...$ $<math>\ldots < a_{-1} < a_0 < a_1 < ... < a_n < ... < b$,

$$\lim_{n\to\infty}a_n=b\,,\ \lim_{n\to\infty}a_{-n}=a$$

such that the Wronskian $W(x_1, x_2, ..., x_k)(t) \neq 0$ for all $t \in (a, b), t \neq a_m$, m integer.

Proof of the Lemma follows from Theorem 1 [1]. Denote by N the set of all $t \in (a, b)$ such that $W(x_1, x_2, ..., x_k)(t) = 0$ and assume that there is an accumulation point c of the set N, $c \in (a, b)$. The continuity of $W(x_1, x_2, ..., x_k)(t)$ implies $c \in N$ which is a contradiction with Theorem 1 [1].

Note that the assumptions of Theorem 1 are those of lemma with s = k.

Proof of Theorem 1. Let us choose numbers α_0^i , i = 0, 1, 2, ..., k such that

$x_1(a_0), x_1'(a_0),$	$x_2(a_0), x'_2(a_0),$	$\ldots, x_k(a_0), \\ \ldots, x'_k(a_0),$	α_0^0 α_0^1	+ 0
$\Big \begin{array}{c} \dots \\ x_1^{(k)}(a_0), \end{array} \Big $	$x_{2}^{(k)}(a_{0}),$	$\ldots, x_k^{(k)}(a_0),$	α_0^k	

and a function u(t) with continuous k-th derivative in $(a_{-1}, a_1), u^{(i)}(a_0) = \alpha_0^i$ for i = 0, 1, 2, ..., k.¹) Evidently there exists $\varepsilon_0 > 0$ such that $W(x_1, x_2, ..., x_k, u)(t) \neq 0$ for $t \in \langle a_0 - \varepsilon_0, a_0 + \varepsilon_0 \rangle$. Put

$$x_{k+1}(t) = u(t)$$
 for $t \in \langle a_0 - \varepsilon_0, a_0 + \varepsilon_0 \rangle$.

Let us now suppose that the function $x_{k+1}(t)$ has been already defined (and satisfies Theorem 1) on $\langle a_{-i} - \varepsilon, a_i + \varepsilon \rangle$, $\varepsilon > 0$, *j* nonnegative integer.

¹) We denote $u^{(0)}(t) = u(t)$.

Let us choose a function $f_j(t)$ continuous on $\langle a_j, a_{j+1} \rangle$ and a function $f_{-j}(t)$ continuous on $\langle a_{-j-1}, a_{-j} \rangle$ such that

$$f_j(t) \neq 0$$
, $f_{-j}(t) \neq 0$ for $t \in \langle a_j, a_{j+1} \rangle$, $t \in \langle a_{-j-1}, a_{-j} \rangle$,

respectively. Moreover, let

(2)
$$f_j(a_j + \varepsilon) = W(x_1, x_2, \dots, x_k, x_{k+1}) (a_j + \varepsilon),$$
$$f_{-j}(a_{-j} - \varepsilon) = W(x_1, x_2, \dots, x_k, x_{k+1}) (a_{-j} - \varepsilon).$$

(Since $x_{k+1}(t)$ is defined and satisfies Theorem 1 on $\langle a_{-j} - \varepsilon, a_j + \varepsilon \rangle$, the values of the Wronskian on the righthand side of the last two equations are nonzero and hence such functions f_j , f_{-j} exist.)

Let us consider differential equations

(3)
$$\begin{vmatrix} x_1(t), & x_2(t), & \dots, & x_k(t), & y(t) \\ x'_1(t), & x'_2(t), & \dots, & x'_k(t), & y'(t) \\ \dots & \dots & \dots & \dots \\ x_1^{(k)}(t), & x_2^{(k)}(t), & \dots, & x_k^{(k)}(t), & y^{(k)}(t) \end{vmatrix} = f_J(t) ,$$

 $J = \pm j$. The coefficient at the highest derivative $y^{(k)}(t)$ in these equations is $W(x_1, x_2, ..., x_k)(t)$. Denote by $Y_+(t)$, $Y_-(t)$ the solution of the equation with J = j, J = -j and with the initial condition

(4)
$$Y_{+}^{(i)}(a_j + \varepsilon) = x_{k+1}^{(i)}(a_j + \varepsilon), \quad Y_{-}^{(i)}(a_{-j} - \varepsilon) = x_{k+1}^{(i)}(a_{-j} - \varepsilon)$$

respectively, i = 0, 1, ..., k - 1. Since $W(x_1, x_2, ..., x_k)(t) \neq 0$ for $t \in (a_j, a_{j+1}) \cup (a_{-j-1}, a_{-j})$, the functions $Y_+(t), Y_-(t)$ are continuous and have continuous k-th derivative in $\langle a_j + \varepsilon, a_{j+1} \rangle$, $(a_{-j-1}, a_{-j} - \varepsilon \rangle$, respectively. Moreover, the inequalities

$$W(x_1, x_2, ..., x_k, Y_+)(t) \neq 0, \quad W(x_1, x_2, ..., x_k, Y_-)(t) \neq 0$$

hold in the respective intervals.

Further, let us choose (analogously to the first part of the proof) the numbers $\alpha_{i+1}^i, \alpha_{-i-1}^i, i = 0, 1, ..., k$ such that the determinant

$\begin{vmatrix} x_1(a_{j+1}), \\ x'_1(a_{j+1}), \end{vmatrix}$	$x_2(a_{j+1}), x'_2(a_{j+1}),$	$\ldots, x_k(a)$ $\ldots, x'_k(a)$	$(i_{j+1}), i_{j+1}),$	$\alpha_{j+1}^0 \\ \alpha_{j+1}^1$
$\Big \begin{array}{c} \dots \\ x_1^{(k)}(a_{j+1}), \end{array} \Big $	$x_{2}^{(k)}(a_{j+1}),$	$\ldots, x_k^{(k)}$	$(a_{j+1}),$	α_{j+1}^k

as well as the determinant obtained by replacing the index j + 1 by -j - 1 are different from zero. Let $u_{j+1}(t)$, $u_{-j-1}(t)$ be functions with continuous k-th derivative in $\langle a_j, a_{j+2} \rangle$, $\langle a_{-j-2}, a_{-j} \rangle$ respectively and $u_{j+1}^{(i)}(a_{j+1}) = \alpha_{j+1}^i, u_{-j-1}^{(i)}(a_{-j-1}) =$

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= α_{-j-1}^{i} for i = 0, 1, ..., k. (Such functions obviously exist.) From the continuity of $W(x_1, x_2, ..., x_k, u_{j+1})(t)$ and $W(x_1, x_2, ..., x_k, u_{-j-1})(t)$ there follows that

$$W(x_1, x_2, ..., x_k, u_{j+1})(t) \neq 0, \quad W(x_1, x_2, ..., x_k, u_{-j-1})(t) \neq 0$$

in some interval $\langle a_{j+1} - \varepsilon', a_{j+1} + \varepsilon' \rangle$, $\langle a_{-j-1} - \varepsilon', a_{-j-1} + \varepsilon' \rangle$ respectively, $\varepsilon' > 0$.

In the interval $\langle a_{j+1} - \varepsilon', a_{j+1} + \varepsilon' \rangle$ put

$$v_{j+1}(t) = \beta_0 u_{j+1}(t) + \sum_{p=1}^{k} \beta_p x_p(t) ,$$

the constants $\beta_0, \beta_1, \ldots, \beta_k$ being the solution of the linear system

$$\beta_0 u_{j+1}^{(i)}(a_{j+1} - \varepsilon') + \sum_{p=1}^k \beta_p x_p^{(i)}(a_{j+1} - \varepsilon') = Y_+^{(i)}(a_{j+1} - \varepsilon'),$$

i = 0, 1, ..., k. Since from the choice of $u_{j+1}(t)$ and ε' there follows that the determinant of this system is nonzero, there exists a unique solution $\beta_0, \beta_1, ..., \beta_k$.²)

Analogously put

$$v_{-j-1}(t) = \gamma_0 u_{-j-1}(t) + \sum_{p=1}^k \gamma_p x_p(t)$$

in $\langle a_{-j-1} - \varepsilon', a_{-j-1} + \varepsilon' \rangle$; we obtain the constants $\gamma_0, \gamma_1, ..., \gamma_k$ as the (unique) solution of the system

$$\gamma_0 u_{-j-1}^{(i)} (a_{-j-1} + \varepsilon') + \sum_{p=1}^k \gamma_p x_p^{(i)} (a_{-j-1} + \varepsilon') = Y_-^{(i)} (a_{-j-1} + \varepsilon') \,.$$

Let us now define

$$x_{k+1}(t) = \begin{cases} Y_+(t) & \text{in the interval } \langle a_j + \varepsilon, a_{j+1} - \varepsilon' \rangle \\ v_{j+1}(t) & \text{in the interval } \langle a_{j+1} - \varepsilon', a_{j+1} + \varepsilon' \rangle \\ Y_-(t) & \text{in the interval } \langle a_{-j-1} + \varepsilon', a_{-j} - \varepsilon \rangle \\ v_{-j-1}(t) & \text{in the interval } \langle a_{-j-1} - \varepsilon', a_{-j-1} + \varepsilon' \rangle. \end{cases}$$

By this way it is evidently possible to define the function $x_{k+1}(t)$ on the whole interval (a, b). It follows from the construction that $x_{k+1}(t)$ has all properties required by the assertion of Theorem 1. It is just necessary to verify that the k-th derivative $x_{k+1}^{(k)}(t)$ is continuous at the points $a_j + \varepsilon$, $a_{-j} - \varepsilon$.

There is

$$W(x_1, x_2, \dots, x_k, Y_+) (a_j + \varepsilon) = f_j(a_j + \varepsilon) =$$

= $W(x_1, x_2, \dots, x_k, x_{k+1}) (a_j + \varepsilon)$

according to the choice of $f_i(t)$; moreover, $Y_+(t)$ fulfils the initial conditions $Y_+^{(i)}(a_j + t)$

²) Moreover, $\beta_0 \neq 0$ since otherwise $W(x_1, x_2, ..., x_k, Y_+) (a_{j+1} - \varepsilon') = 0$; hence $W(x_1, x_2, ..., x_k, v_{j+1}) (t) \neq 0$ implies $W(x_1, x_2, ..., x_k, u_{j+1}) (t) \neq 0$ and conversely.

 $(+ \varepsilon) = x_{k+1}^{(i)}(a_i + \varepsilon)$ for i = 0, 1, ..., k - 1, which implies immediately

$$Y_{+}^{(k)}(a_{j}+\varepsilon) = x_{k+1}^{(k)}(a_{j}+\varepsilon)$$

(the derivative of Y_+ being taken from the right, the derivative of x_{k+1} from the left). The continuity of the k-th derivative $x_{k+1}^{(k)}(t)$ at $a_{-i} - \varepsilon$ is proved quite analogously.

2. In this article we shall generalize Theorem 1 assuming that the functions $x_1, x_2, ..., x_k$ have continuous derivatives of the s-th order, $s \ge k$ and that the matrix from Theorem 1 has s + 1 rows. (For s = k we get Theorem 1.) We shall prove

Theorem 2. Let a, b be real numbers, a < b, k, s positive integers, $s \ge k$. Let functions $x_1(t), x_2(t), \ldots, x_k(t)$ have continuous derivatives of the s-th order in the interval (a, b) and let the matrix (1) be of the rank k for all $t \in (a, b)$.

Then there exists a function $x_{k+1}(t)$ with continuous s-th derivative in (a, b) such that the matrix

$$\begin{pmatrix} x_1(t), x_2(t), \dots, x_k(t), x_{k+1}(t) \\ x'_1(t), x'_2(t), \dots, x'_k(t), x'_{k+1}(t) \\ \dots \\ x_1^{(s)}(t), x_2^{(s)}(t), \dots, x_k^{(s)}(t), x_{k+1}^{(s)}(t) \end{pmatrix}$$

is of the rank k + 1 for all $t \in (a, b)$.

Proof will follow the same lines as that of Theorem 1. If a_m , $m = 0, \pm 1, \pm 2, ...$ are the points from Lemma³) then again $W(x_1, x_2, ..., x_k)(t) \neq 0$ for all $t \in (a, b)$, $t \neq a_m$, $m = 0, \pm 1, \pm 2, ...$ We start constructing $x_{k+1}(t)$ at a_0 again, choosing numbers α_0^i , i = 0, 1, 2, ..., s, a function u(t) and $\varepsilon_0 > 0$ so that

(i) the matrix

$$\begin{pmatrix} x_1(a_0), & x_2(a_0), & \dots, & x_k(a_0), & \alpha_0^0 \\ x_1'(a_0), & x_2'(a_0), & \dots, & x_k'(a_0), & \alpha_0^1 \\ \dots & \dots & \dots \\ x_1^{(s)}(a_0), & x_2^{(s)}(a_0), & \dots, & x_k^{(s)}(a_0), & \alpha_0^s \end{pmatrix}$$

has the rank k + 1;

(ii) u(t) has continuous s-th derivative; (iii) $u^{(i)}(a_0) = \alpha_0^i$, i = 0, 1, 2, ..., s; (iv) the matrix

$$\begin{pmatrix} x_1(t), x_2(t), \dots, x_k(t), u(t) \\ x'_1(t), x'_2(t), \dots, x'_k(t), u'(t) \\ \dots \\ x_1^{(s)}(t), x_2^{(s)}(t), \dots, x_k^{(s)}(t), u^{(s)}(t) \end{pmatrix}$$

has the rank k + 1 for all $t \in \langle a_0 - \varepsilon_0, a_0 + \varepsilon_0 \rangle$.

³) Actually, the assumptions of Lemma are the same as those of Theorem 2.

The functions $x_1(t), x_2(t), ..., x_k(t), u(t)$ satisfy the assumptions of Lemma on $(a_0 - \varepsilon_0, a_0 + \varepsilon_0)$. Hence there is $\varepsilon > 0$ such that $W(x_1, x_2, ..., x_k, u)(t) \neq 0$ for all $t \neq a_0, t \in \langle a_0 - \varepsilon, a_0 + \varepsilon \rangle^4$; for $t = a_0$ we have (iv).

Put $x_{k+1}(t) = u(t)$ for $t \in \langle a_0 - \varepsilon, a_0 + \varepsilon \rangle$. If $x_{k+1}(t)$ is defined (and satisfies Theorem 2) for all $t \in \langle a_{-j} - \varepsilon, a_j + \varepsilon \rangle$,

$$W(x_1, x_2, ..., x_k, x_{k+1})(t) \neq 0$$

for $t \neq a_m$, $m = 0, \pm 1, \pm 2, ..., \pm j$, let us consider again equation (3) where the function $f_j(t)$, $J = \pm j$ is defined in the following manner:

- (i') f_j is defined and has continuous s-th derivative in the intervals $\langle a_j, a_{j+1} \rangle$, $\langle a_{-j-1}, a_{-j} \rangle$ respectively;
- (ii') $f_J(t) \neq 0$ in its interval of definition;
- (iii') the values $f_j^{(i)}(a_j + \varepsilon)$, $f_{-j}^{(i)}(a_{-j} \varepsilon)$ are given so as to satisfy equations

$$\frac{\mathrm{d}^{i}}{\mathrm{d}t^{i}} W(x_{1}, x_{2}, \dots, x_{k}, x_{k+1}) (a_{j} + \varepsilon) = f_{j}^{(i)}(a_{j} + \varepsilon)$$

$$\frac{\mathrm{d}^{i}}{\mathrm{d}t^{i}} W(x_{1}, x_{2}, \dots, x_{k}, x_{k+1}) (a_{-j} - \varepsilon) = f_{-j}^{(i)}(a_{-j} - \varepsilon) ,$$

i = 0, 1, ..., s - k (for i = 0, this equations are equivalent to (2)).⁵)

The solutions Y_+ , Y_- with the corresponding initial condition (4) have then continuous s-th derivative (since the same holds for $x_1, x_2, ..., x_k, f_J$) and, moreover,

$$Y_{+}^{(i)}(a_{j} + \varepsilon) = x_{k+1}^{(i)}(a_{j} + \varepsilon), \quad Y_{-}^{(i)}(a_{-j} - \varepsilon) = x_{k+1}^{(i)}(a_{-j} - \varepsilon)$$

for i = 0, 1, 2, ..., s. In fact, for i = 0, 1, ..., k - 1 these relations coincide with the initial conditions; for i = k, k + 1, ..., s we get them successively from (iii').

Let us now choose numbers $_{p}\alpha_{j+1}^{i}$, $_{p}\alpha_{-j-1}^{i}$, i = 0, 1, 2, ..., s, p = k + 1, k + 2,, s + 1 so that

(5)
$$\begin{vmatrix} x_1(a_{j+1}), & \dots, & x_k(a_{j+1}), & {}_{k+1}\alpha_{j+1}^0, & \dots, & {}_{s+1}\alpha_{j+1}^0 \\ x_1'(a_{j+1}), & \dots, & x_k'(a_{j+1}), & {}_{k+1}\alpha_{j+1}^1, & \dots, & {}_{s+1}\alpha_{j+1}^1 \\ \dots & \dots & \dots & \dots \\ x_1^{(s)}(a_{j+1}), & \dots, & x_k^{(s)}(a_{j+1}), & {}_{k+1}\alpha_{j+1}^s, & \dots, & {}_{s+1}\alpha_{j+1}^s \end{vmatrix} \neq 0^{-6} \end{vmatrix}$$

and similarly for a_{-j-1} . Let $_{p}u_{j+1}(t)$, p = k + 1, k + 2, ..., s + 1 be functions that fulfil:

(i") they have continuous s-th derivative in $\langle a_j, a_{j+2} \rangle$, $\langle a_{-j-2}, a_{-j} \rangle$ respectively;

⁴) Otherwise a_0 would be an accumulation point of the zero points of the Wronskian which contradicts Lemma.

⁵) This does not contradict (ii') since in particular $W(x_1, x_2, ..., x_{k+1}) (a_j + \varepsilon) \neq 0 \neq W(x_1, x_2, ..., x_{k+1}) (a_{-j} - \varepsilon).$

⁶) This is possible since the rank of (1) for $t = a_{j+1}$ is k.

(ii")
$$_{p}u_{j+1}^{(i)}(a_{j+1}) = _{p}\alpha_{j+1}^{i}, _{p}u_{-j-1}^{(i)}(a_{-j-1}) = _{p}\alpha_{-j-1}^{i}$$
 for $i = 0, 1, 2, ..., s, p = k + 1, k + 2, ..., s + 1$.

Again there exists $\varepsilon' > 0$ such that

(6)
$$W(x_1, x_2, ..., x_k, {}_{k+1}u_{j+1}, ..., {}_{s+1}u_{j+1})(t) \neq 0,$$
$$W(x_1, x_2, ..., x_k, {}_{k+1}u_{-j-1}, ..., {}_{s+1}u_{-j-1})(t) \neq 0$$

holds for all t from the interval $\langle a_{j+1} - \varepsilon', a_{j+1} + \varepsilon' \rangle$, $\langle a_{-j-1} - \varepsilon', a_{-j-1} + \varepsilon' \rangle$, respectively.

Now put

$$v_{j+1}(t) = \sum_{p=1}^{k} \beta_p x_p(t) + \sum_{p=k+1}^{s+1} \beta_{p p} u_{j+1}(t)$$

the constants β_p , p = 1, 2, ..., s + 1 being the solution of the system

$$\sum_{p=1}^{k} \beta_{p} x_{p}^{(i)}(a_{j+1} - \varepsilon') + \sum_{p=k+1}^{s+1} \beta_{p} y_{j+1}^{(i)}(a_{j+1} - \varepsilon') = Y_{+}^{(i)}(a_{j+1} - \varepsilon'),$$

 $i = 0, 1, ..., s.^7$) Since the determinant of the system is nonzero according to (6) there exists a unique solution $\beta_1, \beta_2, ..., \beta_{s+1}$. The constants $\beta_{k+1}, ..., \beta_{s+1}$ are not simultaneously equal to zero. In fact, if

$$v_{j+1}(t) = \sum_{p=1}^{k} \beta_p x_p(t)$$

then also

$$Y_{+}^{(i)}(a_{j+1} - \varepsilon') = \sum_{p=1}^{k} \beta_{p} x_{p}^{(i)}(a_{j+1} - \varepsilon')$$

 $i = 0, 1, 2, \dots, s$. However, this means that

$$W(x_1, x_2, ..., x_k, Y_+)(a_{j+1} - \varepsilon') = 0$$

which is not possible according to the construction of Y_+ .

Further, the definition of β_p implies that

$$Y^{(i)}_{+}(a_{j+1} - \varepsilon') = v^{(i)}_{j+1}(a_{j+1} - \varepsilon'),$$

 $i = 0, 1, 2, \dots, s.$

Analogously we define the function $v_{-j-1}(t)$ in the interval $\langle a_{-j-1} - \varepsilon', a_{-j-1} + \varepsilon' \rangle$. (It may be necessary to make ε' smaller.)

 $[\]overline{}^{7}$) We have here the derivatives from the left and from the right analogously to the proof of Theorem 1.

Let us now put

$$x_{k+1}(t) = \begin{cases} Y_{+}(t) & \text{in the interval} \quad \langle a_{j} + \varepsilon, a_{j+1} - \varepsilon' \rangle \\ v_{j+1}(t) & \text{in the interval} \quad \langle a_{j+1} - \varepsilon', a_{j+1} + \varepsilon' \rangle \\ Y_{-}(t) & \text{in the interval} \quad \langle a_{-j-1} + \varepsilon', a_{-j} - \varepsilon \rangle \\ v_{-j-1}(t) & \text{in the interval} \quad \langle a_{-j-1} - \varepsilon', a_{-j-1} + \varepsilon' \rangle. \end{cases}$$

Continuing like that we can define $x_{k+1}(t)$ for all $t \in (a, b)$. It is evident that all assertions of Theorem 2 hold, in particular the continuity of the s-th derivative of $x_{k+1}(t)$. Moreover, it is evident that even

$$W(x_1, x_2, ..., x_{k+1})(t) \neq 0$$

for all $t \in (a, b)$, $t \neq a_m$, $m = 0, \pm 1, \pm 2, ...$

3. From the both Theorems there follows

Corollary. Let be given functions $x_1(t), x_2(t), ..., x_k(t)$ with continuous derivative of n-th order in (a, b), k < n. Let the matrix

 $\begin{pmatrix} x_1(t), & x_2(t), & \dots, & x_k(t) \\ x'_1(t), & x'_2(t), & \dots, & x'_k(t) \\ \dots & \dots & \dots \\ x_1^{(n-1)}(t), & x_2^{(n-1)}(t), & \dots, & x_k^{(n-1)}(t) \end{pmatrix}$

have the rank k for all $t \in (a, b)$.

Then there exists a differential equation

$$x^{(n)} + a_1(t) x^{(n-1)} + \ldots + a_{n-1}(t) x' + a_n(t) x = 0$$

with continuous coefficients $a_i(t)$, i = 1, 2, ..., n such that the functions $x_1(t), x_2(t), ..., x_k(t)$ are its solutions on (a, b).

Proof. Completing the system of functions $x_1(t), x_2(t), ..., x_k(t)$ according to Theorem 2 (n - k)-times we get a system $x_1(t), x_2(t), ..., x_n(t)$ with the Wronskian different from zero for all $t \in (a, b)$. The functions $x_{k+1}(t), ..., x_n(t)$ have continuous derivatives of the (n - 1)-st order.

To be able to write the required differential equation, it is sufficient to use Lemma 6 [2, p. 76]. According to this Lemma, to any function x(t) with continuous k-th derivative in (a, b) and to an arbitrary sequence of numbers $\varepsilon_p > 0$, $p = 0, 1, ..., \lim_{p \to \infty} \varepsilon_p = 0$, there exists a function $\xi(t)$ analytic in (a, b) and such that for the difference

$$\Delta^{(i)}(t) = |x^{(i)}(t) - \xi^{(i)}(t)|$$

there is $\Delta^{(i)}(t) < \varepsilon_p$, i = 0, 1, ..., k for $t \in (a, a_{-p}) \cup \langle a_p, b \rangle$. It is evident that by a proper choice of numbers ε_p it is possible to keep – after replacing $x_{k+q}(t)$ by

 $\xi_{k+q}(t), q = 1, 2, ..., n - q$ — the inequality for the Wronskian, viz. $W(x_1, x_2, ..., x_k, \xi_{k+1}, ..., \xi_n)(t) \neq 0$. Now the required equation can be written in the form

 $W(x_1, x_2, ..., x_k, \xi_{k+1}, ..., \xi_n, x)(t) = 0$

whose all coefficients are continuous in (a, b) and the coefficient at $x^{(n)}$ is different from zero since it is equal to $W(x_1, x_2, ..., x_k, \xi_{k+1}, ..., \xi_n)(t)$.

Author's Note. The paper being already in print, the author's attention was drawn to the paper by Ascoli, G.: Sulla decomposizione degli operatori differenziali lineari. Revista (Univ. Nac. Tucuman), Ser. A, 1 (1940), pp. 189–215, where (p. 210) a theorem identical to Corollary of the present paper is proved. However, the method of Ascoli yields just one equation (uniquely determined by the given functions) which has the required properties.

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