# Rosa Maria Bianchini Tiberio; Roberto Conti On local and global controllability

Časopis pro pěstování matematiky, Vol. 111 (1986), No. 1, 54--61

Persistent URL: http://dml.cz/dmlcz/118264

## Terms of use:

© Institute of Mathematics AS CR, 1986

Institute of Mathematics of the Academy of Sciences of the Czech Republic provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This paper has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ*: *The Czech Digital Mathematics Library* http://project.dml.cz

### ON LOCAL AND GLOBAL CONTROLLABILITY

R. M. BIANCHINI TIBERIO, ROBERTO CONTI, Firenze

Dedicated to Professor Jaroslav Kurzweil on the occasion of his sixtieth birthday (Received May 25, 1985)

1.

We consider the control process represented by a family of ordinary differential equations

$$(A, c) dx/dt = Ax + c$$

where x, the state vector, is a function of time  $t \ge 0$  with values  $x(t) \in \mathbb{R}^n$ , A is a real  $n \times n$  matrix, and c, the control parameter, is a function of t with values c(t) in a subset  $\Gamma$  of  $\mathbb{R}^n$ .

We shall denote by  $C_{\Gamma}$  the set of measurable, locally integrable functions of  $t \ge 0$ ,  $c: t \to c(t) \in \Gamma$ .

For each  $c \in C_{\Gamma}$  the solution of (A, c) starting from an initial state  $v \in \mathbb{R}^n$  at time t = 0 is represented, at time t, by

(1.1) 
$$x(t, v, c) = e^{tA}v + \int_0^t e^{(t-s)A} c(s) \, ds \, .$$

In order that c might be considered as a genuine control it must not be constant, so that we shall assume that  $\Gamma$  is not reduced to a single point, or, equivalently, that

rel int co  $\Gamma \neq \emptyset$ 

holds, where co  $\Gamma$  is the convex hull of  $\Gamma$  and rel int co  $\Gamma$  is the interior of co  $\Gamma$  relative to the affine hull of  $\Gamma$ .

A point  $w \in \mathbb{R}^n$  is said to be reachable from the origin O of  $\mathbb{R}^n$  at time t if there exist some  $c \in C_{\Gamma}$  such that x(t, 0, c) = w.

According to (1.1) the set of points reachable from O at time t is

$$W(t, A, \Gamma) = \left\{ \int_0^t e^{(t-s)A} c(s) \, \mathrm{d}s \colon c \in C_\Gamma \right\}.$$

The union of these sets with respect to t > 0,

 $W(A,\Gamma) = \bigcup_{t>0} W(t,A,\Gamma)$ ,

is the set of points reachable from O.

We say that a pair  $(A, \Gamma)$  is O-locally reachable if

 $(\mathbf{R})_{O-\mathrm{loc}} \qquad O \in \mathrm{int} \ W(A, \Gamma)$ 

holds.

We say that  $(A, \Gamma)$  is O-globally reachable if

 $(\mathbf{R})_{o-gl}$ 

,

$$W(A,\Gamma) = \mathbb{R}'$$

holds. Obviously

$$(\mathbf{R})_{\boldsymbol{O}-\mathbf{g}\mathbf{l}} \Rightarrow (\mathbf{R})_{\boldsymbol{O}-\mathbf{loc}}$$

In what follows we shall discuss

**Problem P.** To find a property (x) of the pair  $(A, \Gamma)$  such that

$$(\mathbf{R})_{o-\mathrm{loc}}$$
 plus  $(\mathbf{x}) \Leftrightarrow (\mathbf{R})_{o-\mathrm{gl}}$ .

2.

Before we go further let us recall some known properties of reachable sets (see, for instance, [Q]).

First of all (Cl S = closure of S),

(2.1) 
$$W(t, A, \Gamma) = \operatorname{co} W(t, A, \Gamma), \quad \forall t, A, \Gamma,$$

(2.2) 
$$\operatorname{Cl} W(t, A, \Gamma) = \operatorname{Cl} W(t, A, \operatorname{Cl} \operatorname{co} \Gamma), \quad \forall t, A, \Gamma,$$

(2.3)  $O \in \operatorname{int} W(A, \Gamma) \Leftrightarrow \exists t > 0: O \in \operatorname{int} W(t, A, \Gamma)$ 

hold. Consequently,

(2.4) 
$$O \in \operatorname{int} W(A, \Gamma) \Leftrightarrow O \in \operatorname{int} W(A, \operatorname{Cl} \operatorname{co} \Gamma)$$
.

From (2.2) we have also

$$\operatorname{Cl} W(A, \Gamma) = \operatorname{Cl} W(A, \operatorname{Cl} \operatorname{co} \Gamma), \quad \forall A, \Gamma$$

and since

(2.5) 
$$\operatorname{Cl} W(A, \Gamma) = \mathbb{R}^n \Leftrightarrow W(A, \Gamma) = \mathbb{R}^n,$$

we obtain

(2.6) 
$$W(A, \Gamma) = \mathbb{R}^n \Leftrightarrow W(A, \operatorname{Cl} \operatorname{co} \Gamma) = \mathbb{R}^n.$$

From (2.4), (2.6) we conclude that, in dealing with Problem P, it is not restrictive to assume

$$\Gamma = \operatorname{Cl} \operatorname{co} \Gamma$$

as we shall do from now on.

55

112.4

One further remark:  $(R)_{o-gl}$  does not imply that

(h)  $O \in \Gamma$ ,

hence the same applies to  $(\mathbf{R})_{o-loc}$ . Therefore, also the condition (x) we are looking for must be independent of assumption (h).

3.

Let us now review what is known about Problem P. Notice that the results we are going to review are originally stated in terms of the pair  $(-A, -\Gamma)$  rather than  $(A, \Gamma)$ .

The first contribution to Problem P is contained in a wellknown paper of J. P. LaSalle [1] who proved the following.

Let  $\Gamma = BU^m$  where  $U^m$  is a cube, namely

$$U^{m} = \{ u \in \mathbb{R}^{m} : |u_{i}| \leq 1, i = 1, 2, ..., m \},\$$

and B is a real  $n \times m$  matrix. Then  $(R)_{o-gl}$  is equivalent to  $(R)_{o-loc}$  plus

(c<sup>i</sup>) 
$$z \neq 0$$
,  $z^*A = \lambda z^* \Rightarrow \operatorname{Re} \lambda \ge 0$ .

The same result was obtained independently and almost simultaneously by J. Kurzweil and Z. Vorel [2] by means of an entirely different proof.

Other cases where  $\Gamma = B\Omega$ ,  $\Omega$  a bounded subset of  $\mathbb{R}^m$ , were considered by E. B. Lee - L. Markus ([3], p. 96), A. M. Formal'skii [4], R. F. Brammer ([5], Th. 3.5), S. H. Saperstone ([6], Cor. 5.2); V. I. Korobov - A. P. Marinic - E. N. Podol'skii ([7], Cor. p. 1978), L. A. Kun - Yu. F. Pronosin [8].

All these results were finally extended by L. A. Kun [9] who proved that

$$(3.2) (R)_{O^{-}loc} plus (c^{i}) \Rightarrow (R)_{O-gl}$$

holds with no supplementary assumptions on  $\Gamma$ , and that if

( $H_0$ )  $\Gamma$  is a bounded set

then the converse

(3.3) (R)<sub> $o-loc</sub> plus (c<sup>i</sup>) <math>\leftarrow$  (R)<sub>o-gl</sub></sub></sub>

is also true.

In other words,

$$(\mathbf{x}) \Leftrightarrow (\mathbf{c}^{\mathbf{i}})$$

provided that  $(H_0)$  holds.

Assumption  $(H_0)$  is quite a reasonable one for applications, but unsatisfactory from a theoretical viewpoint. So we must try to get rid of it.

Taking for instance  $\Gamma = \mathbb{R}^n$  it is obvious that  $(\mathbb{R})_{o-gl}$  holds for every A, so that  $(c^i)$  is no longer necessary and (3.3) is no longer valid.

In other words  $(c^i)$  is stronger than the condition (x) we are after.

A weaker condition than  $(c^i)$ , reducing to  $(c^i)$  when  $(H_0)$  holds, is represented by ([7], Theorem 2):

(c<sup>ii</sup>) 
$$z \neq 0$$
,  $z^*A = \lambda z^*$ , Re  $\lambda < 0 \Rightarrow \{z^*\gamma \colon \gamma \in \Gamma\}$  unbounded,

and it is easy to show that

(4.1) 
$$(\mathbf{R})_{\boldsymbol{\theta}-\mathbf{g}\mathbf{i}} \Rightarrow (\mathbf{c}^{\mathbf{i}\mathbf{i}}) \,.$$

In fact,  $w \in W(A, \Gamma)$  if and only if  $w = \int_0^t e^{sA}c(t-s) ds$  for some t > 0 and  $c \in C_{\Gamma}$ . Let there exist  $z \neq 0$  and  $\varrho > 0$  such that  $z^*A = \lambda z^*$ , Re  $\lambda < 0$ ,  $|z^*\gamma| \leq \varrho$  for  $\gamma \in \Gamma$ . Then

$$z^*w = \int_0^t e^{\lambda s} z^* c(t-s) \, \mathrm{d}s \, ,$$

hence

$$|z^*w| \leq \int_0^t e^{\operatorname{Re}\lambda s} |z^*c(t-s)| \, \mathrm{d}s \leq -\varrho/\operatorname{Re}\lambda$$

so that  $(\mathbf{R})_{o-g1}$  cannot hold.

On the other hand,

$$(\mathbf{R})_{O-loc}$$
 plus  $(\mathbf{c}^{ii}) \Rightarrow (\mathbf{R})_{O-g}$ 

is not true, as is shown, for instance, by

Example 4.1. Let n = 2 and

$$A = \begin{pmatrix} -1 & 0 \\ -1 & -1 \end{pmatrix}, \quad \Gamma = \{(\gamma_1, \gamma_2): \gamma_1 \in \mathbb{R}, \gamma_2 \ge \gamma_1^2\}$$

It can be shown (see [Q]) that

$$W(A, \Gamma) = \{ (w_1, w_2) : (w_1 - 1/2)^2 < w_2 + 1/2 \}$$

so that  $(R)_{o-loc}$  holds, but  $(R)_{o-g1}$  does not.

On the other hand, it is easily seen that  $(c^{ii})$  holds.

From the preceding we have

(4.2) 
$$(c^i) \Rightarrow (x) \Rightarrow (c^{ii}).$$

5.

Let us now consider the condition

(c<sup>iii</sup>) 
$$y \neq 0$$
,  $y^*A = \lambda y^*$ ,  $\lambda < 0 \Rightarrow$   
 $\Rightarrow \exists \{\gamma^k\}$  in  $\Gamma$  such that  $|\gamma^k| \to +\infty$  and  $y^*\gamma^k \ge \delta |\gamma^k|$  for some  $\delta > 0$ ;

 $z \neq 0$ ,  $z^*A = \lambda z^*$ ,  $\operatorname{Re} \lambda < 0$ ,  $\operatorname{Im} \lambda \neq 0 \Rightarrow$ 

 $\Rightarrow \exists \{\gamma^k\} \text{ in } \Gamma \text{ such that } |\gamma^k| \to +\infty \text{ and } |z^*\gamma^k| \ge \delta |\gamma^k| \text{ for some } \delta > 0.$ 

Obviously,  $(c^i) \Rightarrow (c^{iii})$ .

It was proved in [7] (Theorem 2), under the additional assumption (h), that

(5.1) 
$$(\mathbf{R})_{O-loc} \quad \text{plus} \quad (\mathbf{c}^{iii}) \Rightarrow (\mathbf{R})_{O-gl}$$

holds. The proof, entirely analytic, makes use of the properties of almost periodic functions.  $\hfill \Box$ 

#### 6.

Recall that (see T. R. Rockafellar: Convex Analysis, Princeton, 1970) the recession cone of a non empty convex set  $S \subset \mathbb{R}^n$  is defined as the set  $O^+S = \{x: S + x \subset S\}$ .

Then let us consider the condition

(c<sup>iv</sup>)  $O^+\Gamma$  is not supported by any y,  $y^*A = \lambda y^*$ ,  $\lambda < 0$ ;

 $O^+\Gamma$  is not orthogonal to any  $z, z^*A = \lambda z^*$ , Re  $\lambda < 0$ , Im  $\lambda \neq 0$ .

Recently Nguyen Khoa Son [10] proved, under the additional assumption (h), that

(6.1) 
$$(\mathbf{R})_{O-loc} \quad \text{plus} \quad (\mathbf{c}^{iv}) \Rightarrow (\mathbf{R})_{O-gl}$$

holds. However we can see that

(6.2) 
$$(\mathbf{c}^{\mathbf{i}\mathbf{v}}) \Leftrightarrow (\mathbf{c}^{\mathbf{i}\mathbf{i}\mathbf{i}}).$$

Proof. Assume first that  $(c^{iii})$  does not hold. This gives two possibilities, namely a) there exist  $y, y^*A = \lambda y^*, \lambda < 0$ , such that for any sequence  $\gamma^k \in \Gamma$ ,  $\lim |\gamma^k| = +\infty$ , we have

$$\limsup \frac{y^* \gamma^k}{|\gamma^k|} \leq 0 ;$$

b) there exist  $z, z^*A = \lambda z^*$ , Re  $\lambda < 0$ , Im  $\lambda \neq 0$ , such that for any sequence  $\gamma^k \in \Gamma$ ,  $\lim |\gamma^k| = +\infty$ , we have

$$\limsup \frac{|z^*\gamma^k|}{|\gamma^k|} = 0.$$

Let us fix  $\gamma_0 \in \Gamma$ . Then for any non-zero  $\gamma \in O^+\Gamma$  we have  $\gamma^k \triangleq \gamma_0 + k\gamma \in \Gamma$ (k = 0, 1, ...),  $\lim |\gamma^k| = +\infty$  and

$$\lim \frac{k}{|\gamma^{k}|} = \lim k(|\gamma_{0}|^{2} + 2k\gamma_{0}^{*}\gamma + k^{2}|\gamma|^{2})^{-1/2} = \frac{1}{|\gamma|}$$

In case a) we have

$$\limsup \frac{y^* \gamma^k}{|\gamma^k|} = \lim \left\{ \frac{y^* \gamma_0}{|\gamma^k|} + \frac{k}{|\gamma^k|} y^* \gamma \right\} = \frac{y^* \gamma}{|\gamma|} \le 0$$

or  $y^* \gamma \leq 0$ , i.e.,  $O^+ \Gamma$  is supported by y.

The proof in case b) is analogous.

So we have  $(c^{i\nu}) \Rightarrow (c^{iii})$ . Let us now prove  $(c^{i\nu}) \leftarrow (c^{iii})$ .

Let  $\gamma^k \in \Gamma$  be such that  $\lim |\gamma^k| = +\infty$ . We can assume that  $\gamma^k/|\gamma^k| \to \gamma_{\infty}, |\gamma_{\infty}| = 1$ . Let  $\gamma \in \Gamma$  and  $\vartheta \ge 0$ . Then

$$\gamma + \vartheta \gamma_{\infty} = \lim \left\{ \frac{\vartheta}{|\gamma^k|} \gamma^k + \left(1 - \frac{\vartheta}{|\gamma^k|}\right) \gamma \right\}.$$

Since  $\gamma^k$ ,  $\gamma \in \Gamma$  and  $\vartheta/|\gamma^k| \in [0, 1]$  if k is sufficiently large, we have

$$\frac{\vartheta}{|\gamma^k|}\,\gamma^k\,+\left(1\,-\frac{\vartheta}{|\gamma^k|}\right)\gamma\in\Gamma\,,$$

hence  $\gamma + \vartheta \gamma_{\infty} \in \Gamma = \operatorname{Cl} \operatorname{co} \Gamma$ , so that  $\gamma_{\infty} \in O^{+} \Gamma$ .

If  $(\mathbf{c}^{iii})$  holds, then  $y^*\gamma_{\infty} \geq \delta > 0$  for every  $y, y^*A = \lambda y^*, \lambda < 0$ , and  $|z^*\gamma_{\infty}| \geq \delta > 0$  for every  $z, z^*A = \lambda z^*$ , Re  $\lambda < 0$ , Im  $\lambda \neq 0$ , so that neither  $O^+\Gamma$  is supported by y, nor  $O^+\Gamma$  is orthogonal to z, i.e.,  $(\mathbf{c}^{iv})$  holds.

From (6.2) we conclude that (5.1) and (6.1) are equivalent results. It should be noticed, however, that, unlike the proof of (5.1) in [7], the proof of (6.1) in [10] is entirely geometric and makes use of Schauder fixed point theorem.  $\Box$ 

7.

We shall now show that assumption (h) can be omitted to obtain (5.1), i.e., (6.1). To see this let

(7.1) 
$$W(A, \Gamma, x) = W(A, \Gamma + Ax) + x$$

denote the set of points which can be reached from a given  $x \in \mathbb{R}^n$ : in particular,  $W(A, \Gamma, 0) = W(A, \Gamma)$ .

Let also define the set

$$Q = \{x: -Ax \in \operatorname{rel} \operatorname{int} \operatorname{co} \Gamma\}.$$

Then it can be shown [11] that  $(\mathbf{R})_{O-loc}$  implies  $Q \neq \emptyset$  and

(7.2)  $x \in \operatorname{int} W(A, \Gamma, x), \quad x \in Q,$ 

hence, by (7.1),

$$O \in \operatorname{int} W(A, \Gamma + Ax), \quad x \in Q$$

Since  $x \in Q$  implies  $0 \in \Gamma + Ax$  we can use condition (c<sup>iii</sup>) or (c<sup>iv</sup>), i.e., (5.1) or (6.1), to obtain

$$W(A, \Gamma + Ax) = \mathbb{R}^n, x \in Q.$$

Hence

(7.3) 
$$W(A, \Gamma, x) = \mathbb{R}^n, \quad x \in Q.$$

On the other hand, it can also be shown ([11]) that if  $x \in \operatorname{int} W(A, \Gamma, x)$ ,  $y \in \epsilon$  int  $W(A, \Gamma, y)$ , then  $W(A, \Gamma, x) = W(A, \Gamma, y)$ , so that  $(R)_{o-loc}$ , due to (7.2), yields

$$W(A, \Gamma) = W(A, \Gamma, x), \quad x \in Q$$

and from (7.3) we have  $W(A, \Gamma) = \mathbb{R}^n$ , i.e.,  $(\mathbb{R})_{O-gl}$ .

8.

The following example shows that condition  $(c^{iii}) = (c^{iv})$  is not necessary for  $(R)_{o-g1}$  to hold.

Example 8.1. Let A be the same as in Example 4.1 but let, instead,  $\Gamma$  be the union of the cone  $\Gamma' = \{(\gamma_1, \gamma_2): \gamma_1 \leq 0, \gamma_2 \geq 0\}$  and the closed region  $\Gamma'' = \{(\gamma_1, \gamma_2): \gamma_1 \geq 0, \gamma_2 \geq \varphi(\gamma_1)\}$ , where  $\varphi(\gamma) = (|\gamma| + 1) \log (|\gamma| + 1) - |\gamma|$ .

Since  $O^+\Gamma = \Gamma'$  we see that  $(c^{iv})$  does not hold.

Obviously  $\Gamma = \Gamma' + \Gamma''$ , so that  $W(t, A, \Gamma) = W(t, A, \Gamma') + W(t, A, \Gamma'')$ ,  $\forall t > 0$ . It is readily seen that Cl  $W(t, A, \Gamma') = \Gamma'$ : namely,  $W(t, A, \Gamma')$  is  $\Gamma'$  without the points  $w_1 < 0$ ,  $w_2 = 0$ .

Taking  $\gamma_1(t-s) = e^s - 1$ ,  $\gamma_2(t-s) = \varphi(\gamma_1(t-s)) = e^s s - e^s + 1$  we obtain the point

$$P_t = (t - 1 + e^{-t}, -t + 2 - 2e^{-t} - te^{-t}) \in W(t, A, \Gamma'')$$

so that Cl  $W(t, A, \Gamma) \supset \Gamma' + P_t$ .

As t goes from 0 to  $+\infty$ ,  $P_t$  describes a curve in the region  $w_1 > 0$ ,  $w_2 < 0$  going from the origin to the asymptote  $w_1 + w_2 = 1$ , and it follows that  $W(A, \Gamma) = \mathbb{R}^2$ .

Summing up, (4.2) can be replaced by the stronger implication

(8.1) 
$$(\mathbf{c}^{\mathrm{i}\mathrm{i}\mathrm{i}}) \Leftrightarrow (\mathbf{c}^{\mathrm{i}\mathrm{v}}) \Rightarrow (\mathbf{x}) \Rightarrow (\mathbf{c}^{\mathrm{i}\mathrm{i}})$$

and the arrows are not invertible.

### 9.

Let us recall that the barrier cone  $K_s$  of a convex non empty set  $S \subset \mathbb{R}^n$  is the convex cone with vertex at 0 defined by

$$K_{\mathcal{S}} = \left\{ y \in \mathbb{R}^n \colon \sup_{x \in S} y^* x < +\infty \right\}.$$

 $K_S$  is not necessarily closed even if S is closed. Also,  $K_S = \mathbb{R}^n$  if S is bounded. Therefore the assumption  $(H_0)$  is stronger than the assumption

(H<sub>1</sub>) the barrier cone of  $\Gamma$  is closed.

Nguyen Khoa Son [10] noted that if  $(H_1)$  holds then

 $(c^{iv}) \leftarrow (R)_{o-gl}$ .

In fact, if  $(c^{iv})$  does not hold there are two possibilities:

a) there exist  $y \neq 0$ ,  $y^*A = \lambda^* y$ ,  $\lambda < 0$ , such that  $y^*x \leq 0$ ,  $\forall x \in O^+\Gamma$ , which means  $y \in (O^+\Gamma)^0$ , the polar cone of  $O^+\Gamma$ . But (cf. T. R. Rockafellar, loc. cit. p. 123) we have  $O^+\Gamma = (K_{\Gamma})^0$ , hence  $(O^+\Gamma)^0 = (K_{\Gamma})^{00} = \operatorname{Cl} K_{\Gamma}$ . Therefore if  $\operatorname{Cl} K_{\Gamma} = K_{\Gamma}$  we have  $y \in K_{\Gamma}$ , against condition (c<sup>ii</sup>);

b) there exist  $z \neq 0$ ,  $z^*A = \lambda z^*$ , Re  $\lambda < 0$ , Im  $\lambda \neq 0$ , such that  $z^*x = 0$ ,  $x \in O^+\Gamma$ , so that Re z, Im  $z \in (O^+\Gamma)^0$ , hence Re z, Im  $z \in K_{\Gamma}$ , against (c<sup>ii</sup>) again.

Therefore, in our notation

 $(\mathbf{x}) \Leftrightarrow (\mathbf{c}^{i\mathbf{v}}) \Leftrightarrow (\mathbf{c}^{iii})$ 

provided  $(H_1)$  holds, i.e., Problem P is solved under the additional assumption  $(H_1)$ . 'As far as we know, the solution is still unknown when  $(H_1)$  does not hold.

#### Bibliography

- J. P. LaSalle: The time optimal control problem. Contributions to the Theory of Nonlinear Oscillations, 5 (1960), 1-24.
- [2] J. Kurzweil, Z. Vorel: On linear control systems. Bul. Inst. Pol. Iasi, s.n., t. VI (X) (1960), 13-20 (MR 25 1357, J. P. LaSalle).
- [3] E. B. Lee, L. Markus: Foundations of Optimal Control Theory. J. Wiley & Sons, 1964.
- [4] A. M. Formal'skii: Determination of the control region for an unstable linear system (Russian). Izv. AN SSSR, Teor. Kib. 5 (1965), 129-136.
- [5] R. F. Brammer: Controllability in linear autonomous systems with positive controllers. SIAM J. Control, 10 (1972), 339-353.
- [6] S. H. Saperstone: Global controllability of linear systems with positive controls. SIAM J. Control 11 (1973), 417-423.
- [7] V. I. Korobov, A. P. Marinic, E. N. Podol'skii: Controllability of a linear autonomous system with constraints on the control (Russian). Diff. Uravn. 11 (1975), 1967-1979.
- [8] L. A. Kun, Yu. F. Pronosin: Global controllability of linear systems (Russian). Avt. i Telem. 3 (1972), 155-156; Engl. transl.: Autom. Remote Control 33 (1972), 456-457.
- [9] L. A. Kun: Connection between local and global controllability (Russian). Avt. i Telem. 10 (1977), 12-15; Engl. transl.: Autom. Remote Control 38 (1977), 1437-1439.
- [10] Nguyen Khoa Son: Global controllability of linear autonomous systems: geometric consideration. Systems and Control Letters, 6 (1985), 207-212.
- [11] R. M. Bianchini Tiberio: Local controllability, rest states and cyclic points. SIAM J. C. O. 21 (1983), 714-720.
- [Q] R. Conti: Processi di controllo lineari in R<sup>n</sup>, "Quaderni dell'Unione Matematica Italiana"
  30, Pitagora Ed., Bologna, 1985.

Authors' address: Instituto Matematico "Ulisse Dini", Viale Morgagni 67/A, 50134 Firenze, Italy.