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# Equivalence and zero sets of certain maps in infinite dimensions 

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#### Abstract

Equivalence and zero sets of certain maps on infinite dimensional spaces are studied using an approach similar to the deformation lemma from the singularity theory.


Keywords: singular points, right equivalence, the splitting lemma
Classification: 58F14, 58C27

## 1. Introduction

In this paper we shall use a singularity theory approach to study both right equivalance (see [1, p. 1038]) of certain two maps in Banach spaces, and zero sets of maps near their critical points. The method used in this paper is described in [1], where it was used in a proof of Tromba's Morse lemma. Using this method we obtain both a theorem which is a generalization of Kuiper's theorem [5], [6], and an infinite dimensional version of Theorem 1.3 of [2]. From the theorem in Section 2 it follows the splitting lemma [1].

The plan of the paper is as follows

1. Theorem 2.1 in Section 2 gives conditions under which two functions are related by a homeomorphism in some neighbourhood of a singular point.
2. Section 3 discusses the splitting lemma.
3. Section 4 deals with the infinite dimensional version of the Buchner, Marsden and Schecter theorem [2]. That theorem provides a relation between the zero set of a map near its singular point and the zero set of the first nonzero term of the Taylor expansion of that map at that singular point near that point.

## 2. The generalization of Kuiper's theorem

Theorem 2.1. Let $E$ be a Banach space. Let $Q, P: U \rightarrow \mathbb{R}$ be $C^{1}$-maps defined on a neighbourhood $U$ of $0 \in E$ such that $Q(0)=P(0)=0$ and $D P, D Q$ are Lipschitz. Let $A$ be a vector field defined on $U^{+}=U \backslash\{0\}$ and $f: U \rightarrow \mathbb{R}$. We assume
(1) $A \in C^{1}\left(U^{+}\right),\|A(x)\| \leq 1$ for any $x \in U^{+}$;
(2) $D Q(x) \cdot A(x) \geq c \cdot f(x)$ for some constant $c>0, x \in U^{+}$ and $\lim _{x \rightarrow 0} \frac{|D P(x)|}{f(x)}=0$;
(3) $f \in C^{1}\left(U^{+}\right), f \in C^{0}(U), f(0)=0, f(x)>0$ for $x \neq 0$, $f(t \cdot x) \leq K \cdot f(x)$ for any $0 \leq t \leq 1$ and $x \in U, K>0$ is constant.

Then $Q+P$ is $C^{0}$-right equivalent to $Q$ at 0 .
We say that functions $g, f$ defined on a neighbourhood of 0 with $g(0)=f(0)=0$ are $C^{0}$-right equivalent if there is a homeomorphism $r$ defined on a neighbourhood of 0 with $r(0)=0$ such that $g(x)=h(r(x))$.

Let us consider the initial value problem

$$
\begin{align*}
& y_{t}^{\prime}(x)=-P\left(y_{t}(x)\right) \cdot \bar{A}\left(y_{t}(x)\right) \\
& y_{0}(x)=x \tag{1}
\end{align*}
$$

where $x \in U^{+}, y_{t}^{\prime}(x)=\frac{d}{d t} y_{t}(x), \bar{A}(x)=\frac{A(x)}{f(x)}$. Since $P, \bar{A} \in C^{1}$ there is a unique local solution of (1).

Lemma 2.2. For any $T>0$ there exists an open neighbourhood $V_{T}$ of $0 \in E$ such that for $x \in V_{T} \backslash\{0\}$ the initial value problem (1) has a unique solution on the interval $(-T, T)$.

Proof of Lemma 2.2: In the standard arguments we obtain

$$
\begin{aligned}
& |P(x)| \leq \int_{0}^{1}|D P(t \cdot x) \cdot x| d t \leq\|x\| \cdot \int_{0}^{1}|D P(t \cdot x)| d t \\
& \leq \int_{0}^{1} M_{1} \cdot f(t \cdot x) \cdot\|x\| d t \leq M_{1} \int_{0}^{1} K \cdot f(x) \cdot\|x\| d t \leq M_{2} \cdot f(x) \cdot\|x\|
\end{aligned}
$$

where $M_{2}=K \cdot M_{1}, M_{1}$ follows from the condition 2 . Thus for a sufficiently small $x$ we have

$$
\begin{equation*}
|P(x)| \leq M_{2} \cdot\|x\| \cdot f(x) \tag{2}
\end{equation*}
$$

where $M_{2}$ is a positive constant. Hence from the assumption 1 and (2) we have for $x \neq 0$

$$
\begin{aligned}
& \left\|y_{t}(x)\right\| \leq \int_{0}^{t}\left\|y_{t}^{\prime}(x)\right\| d s+\|x\| \\
& \leq\|x\|+\int_{0}^{t} \frac{\left\|P\left(y_{s}(x)\right) \cdot A\left(y_{s}(x)\right)\right\|}{f\left(y_{s}(x)\right)} \leq\|x\|+\int_{0}^{t} M_{2} \cdot\left\|y_{s}(x)\right\| d s
\end{aligned}
$$

Using the Gronwall's lemma we have

$$
\left\|y_{t}(x)\right\| \leq\|x\| \cdot e^{M_{2} \cdot t} \leq\|x\| \cdot e^{M_{2} \cdot T} \leq\|x\| \cdot M_{4}
$$

By (2) it follows

$$
\begin{aligned}
& \|x\|-\left\|y_{s}(x)\right\| \leq\left\|y_{s}(x)-x\right\| \leq\left\|y_{r}^{\prime}(x)\right\| \cdot|s| \\
& \leq T \cdot \frac{\left\|P\left(y_{r}(x)\right) \cdot A\left(y_{r}(x)\right)\right\|}{f\left(y_{r}(x)\right)} \leq T \cdot\left\|y_{r}(x)\right\| \cdot M_{2}
\end{aligned}
$$

for some $r \in(-T, T)$, and we obtain

$$
\|x\| \leq\left\|y_{s}(x)\right\|+T \cdot\left\|y_{r}(x)\right\| \cdot M_{2} \leq\left\|y_{s}(x)\right\|+M_{2} \cdot T \cdot e^{M_{2} \cdot T} \cdot\|x\|
$$

For a sufficiently small $x$ we can find a small $M_{2}$ as well. Hence

$$
\|x\| \leq \tilde{c} \cdot\left\|y_{s}(x)\right\|
$$

for a constant $\tilde{c}>0$. This finishes the proof, since

$$
\|x\| / \tilde{c} \leq\left\|y_{t}(x)\right\| \leq M_{4} \cdot\|x\|, \forall x \neq 0 \text { small, } t \in[-T, T]
$$

Proof of Theorem 2.1: Consider the initial value problem

$$
\begin{align*}
& \left(D Q\left(y_{t}(x)\right)+h(t, x) \cdot D P\left(y_{t}(x)\right)\right) \cdot \bar{A}\left(y_{t}(x)\right)=h^{\prime}(t, x) \\
& h(0, x)=0, x \neq 0  \tag{4}\\
& y_{t}(x) \text { is the solution of }(1)
\end{align*}
$$

where $x \in V_{T}$ and $T>3 / c$ is sufficiently large. Let us choose a small neighbourhood $V_{1}$ of 0 such that $V_{1} \subset U$ and for $0 \neq x \in V_{1}$

$$
\left\|D P\left(y_{t}(x)\right) \cdot \bar{A}\left(y_{t}(x)\right)\right\|<c / 4
$$

Since $\lim _{x \rightarrow 0} \frac{\|D P(x)\|}{f(x)}=0$ and $\left\|y_{t}(x)\right\| \leq M_{4} \cdot\|x\|$ we can find such $V_{1}$. If $|h(t, x)|<2$ for $t \in[0, T]$ then

$$
\begin{aligned}
h^{\prime}(t, x) & =\left(D P\left(y_{t}(x)\right) \cdot h(t, x)+D Q\left(y_{t}(x)\right)\right) \cdot \bar{A}\left(y_{t}(x)\right) \\
& \geq-2 \cdot c / 4+c \geq c / 2
\end{aligned}
$$

for $x \in\left(V_{T} \backslash\{0\}\right) \cap V_{1}=V_{T}^{+}$, and hence

$$
h(T, x) \geq T \cdot c / 2>(3 / c) \cdot c / 2=3 / 2
$$

Since $h(0, x)=0$ we obtain a $C^{0}-$ map $t(x): V_{T}^{+} \rightarrow \mathbb{R}$ such that

$$
\begin{equation*}
h(t(x), x)=1 \tag{+}
\end{equation*}
$$

We put

$$
H(x)=y_{t(x)}(x)
$$

for any $x \in V_{T}^{+}$and $H(0)=0$. Since it holds

$$
\left\|y_{t}(x)\right\| \leq M_{4} \cdot\|x\| \forall x \neq 0 \text { small, } t \in(-T, T)
$$

from the proof of Lemma 2.2, the map $H$ is continuous.
By the equations (4) and (1) we have

$$
\frac{d}{d t}\left(Q\left(y_{t}(x)\right)+h(t, x) \cdot P\left(y_{t}(x)\right)\right)=0
$$

and using $(+)$ we obtain

$$
\begin{align*}
Q(x) & =Q\left(y_{t(x)}(x)\right)+h(t(x), x) \cdot P\left(y_{t(x)}(x)\right) \\
& =Q\left(y_{t(x)}(x)\right)+P\left(y_{t(x)}(x)\right) . \tag{5}
\end{align*}
$$

Lastly we show that $H$ is a local homeomorphism. If we put

$$
Q_{1}(x)=Q(x)+P(x) \text { and } P_{1}(x)=-P(x)
$$

then similarly as above we obtain maps $y_{t}^{1}(x)=y_{-t}(x)$ and $t^{+}(x)$. Hence $\left(Q_{1}+\right.$ $\left.P_{1}\right)\left(y_{-t^{+}(z)}(z)\right)=Q_{1}(z)$. We have

$$
\begin{aligned}
& Q\left(y_{-t^{+}(z)+t(x)}(x)\right)=Q\left(y_{-t^{+}(z)}\left(y_{t(x)}(x)\right)\right)=\left(Q_{1}+P_{1}\right)\left(y_{-t^{+}(z)}(z)\right)= \\
& Q_{1}(z)=(Q+P)\left(y_{t(x)}(x)\right)=Q(x)
\end{aligned}
$$

where $z=y_{t(x)}(x)$. We have used the "flow" property of $y_{t}(x)$ at $t$ in the previous equality. But

$$
\frac{d}{d t} Q\left(y_{t}(x)\right)=-P\left(y_{t}(x)\right) \cdot D Q \cdot \bar{A}\left(y_{t}(x)\right)
$$

According to the assumptions of Theorem 2.1, the map $w(t)=Q\left(y_{t}(x)\right)$ is monotone, and thus $t^{+}(z)=t(x)$ for $z=H(x)$. Hence

$$
y_{-t^{+}(z)}(z)=y_{-t^{+}(z)}\left(y_{t(x)}(x)\right)=y_{-t^{+}(z)+t(x)}(x)=y_{0}(x)=x
$$

This implies $H^{-1}(x)=y_{-t^{+}(x)}(x)$. We obtain the conclusion of the proof.
Remark 2.3. If $E$ is a Hilbert space and $f(x)=\|x\|^{k}$ where $k$ is a natural number $(k \geq 2)$ then we have the Kuiper's theorem [5], [6].

Moreover, let $Q: U \rightarrow \mathbb{R}$ be a $C^{2}$-map defined on a neighbourhood $U$ of $0 \in E$ such that $Q(0)=0$. Assume

$$
\begin{aligned}
& Q(t \cdot x)=t^{\alpha} \cdot Q(x) \quad \forall x \in E, t \geq 0 \\
& \|\operatorname{grad} Q(x)\|>c>0 \quad \forall x,\|x\|=1
\end{aligned}
$$

for constants $\alpha>1, c$. Then $Q+P$ is $C^{0}$-right equivalent to $Q$ at 0 for any $C^{2}$-map $P: U \rightarrow \mathbb{R}$ such that $\lim _{x \rightarrow o} \frac{|D P(x)|}{\|x\|^{\alpha-1}}$. Indeed, we take

$$
A(x)=\operatorname{grad} Q(x) /\|\operatorname{grad} Q(x)\|, \quad f(x)=\|x\|^{\alpha-1}
$$

## 3. The splitting lemma

We now briefly discuss the splitting lemma of Gromoll and Meyer [1].
Theorem 3.1. Let $E$ be a Banach space possessing a splitting $E=Y \oplus Z$, where $Y, Z$ are Banach spaces. Let $P, Q$ be $C^{0}$-smooth with a Lipschitz partial derivatives $D_{y}^{1} P, D_{y}^{1} Q$, defined on a neighbourhood $U$ of $(0,0)$. Let $A(y, z)$ be a $C^{0}$-vector field on $U^{+}=U \backslash\{(y, z) \mid y=0\}$ and let $f: U \cap Y \rightarrow \mathbb{R}$ be a $C^{0}$-map such that
(1) $A: U^{+} \rightarrow Y,|A(y, z)| \leq 1, A$ is $C^{1}$-smooth by $y$;
(2) $D_{y} Q(y, z) A(y, z) \geq c \cdot f(y)$ for $(y, z) \in U^{+}$, where $c>0$ and $\lim _{x \rightarrow 0} \frac{\left|D_{y} P(y, z)\right|}{f(y)}=0$ uniformly with respect to a small $z$;
(3) $f \in C^{1}\left(U^{+} \cap Y\right), f(0)=0, f(y)>0$ if $y \neq 0$ and $f(t \cdot y) \leq K \cdot f(y)$ for any $t \in[0,1]$, where $K$ is a positive constant.
Then the function $Q(y, z)+P(0, z)$ is $C^{0}$-right equivalent to $Q(y, z)+P(y, z)$ at $(0,0)$ by a homeomorphism $H(y, z)=(h(y, z), z)$.
Proof: Applying Theorem 2.1 for the functions $Q_{1}(y, z)=Q(y, z)-Q(0, z)$, $P_{1}(y, z)=P(y, z)-P(0, z)$ uniformly with respect to a small $z$ we obtain our result.
Splitting lemma. Let $H$ be a Hilbert space and $h: U \rightarrow \mathbb{R}$ a $C^{1}$-map, where $U$ is a neighbourhood of 0 . We assume that $h(0)=D h(0)=0, D^{2} h(0)$ exists and $D^{2} h(0)=\left\langle B w_{1}, w_{2}\right\rangle$, where $B$ is a Fredholm operator. Moreover we assume that $h$ has a continuous partial derivative $D_{y}^{2} h$ for $y \in Y \cap U$, where $H=Y \oplus Z, Y=\operatorname{im} B$, $Z=\operatorname{ker} B$.

Then there is a homeomorphism $H(y, z)=(\bar{h}(y, z), z)$ such that

$$
h(H(y, z))=\frac{1}{2} \cdot\langle B y, y\rangle+\tilde{h}(z)
$$

where $(y, z) \in Y \oplus Z$ is small, $\tilde{h}$ is continuous, $\tilde{h}(0)=0$.
Proof: We consider the equation $\nabla_{y} h(y, z)=0$, where $\nabla_{y}$ is the partial gradient. The implicit function theorem guarantees that this equation uniquely defines a $C^{0}$ map $y(z)$ such that $\nabla_{y} h(y(z), z)=0$. Let us put

$$
\begin{aligned}
& h_{1}(y, z)=h(y+y(z), z) \text { and } P(y, z)=h_{1}(y, z)-\frac{1}{2}\langle B y, y\rangle \\
& Q(y, z)=\frac{1}{2}\langle B y, y\rangle, A(y, z)=B y /\|B y\|, f(y)=\|y\|
\end{aligned}
$$

Since $B$ is invertible on $Y$ we obtain

$$
D_{y} Q(y, z) \cdot \frac{B y}{\|B y\|}=\|B y\| \geq c \cdot\|y\|
$$

for some $c>0$. Moreover

$$
\left|D_{y} P(y, z)\right| \leq \int_{0}^{1}\left\|D_{y}^{2} P(t \cdot y, z)\right\| \cdot\|y\| d t
$$

and from this we have

$$
\lim _{y \rightarrow 0, z \rightarrow 0} \frac{\left|D_{y} P(y, z)\right|}{\|y\|}=0
$$

Theorem 3.1 implies the assertion of the lemma.

## 4. The infinite dimensional version of the Buchner, Marsden and Schecter theorem

We need the following definition.
Definition. We say that an open set $S \subset H$ ( $H$ is a Hilbert space) has the property $\mathcal{B}$ if there exists a function $h: H \rightarrow \mathbb{R}$ such that
(i) $h$ is a $C^{1}$-map, $0 \leq h \leq 1$;
(ii) $\operatorname{supp} h \subset S$, $\operatorname{supp} h \subset B_{\bar{R}}$ for some $\bar{R}>0(\operatorname{supp} h$ is the support of $h)$, and $B_{\bar{R}}$ is the ball with the radius $\bar{R}$ at 0 ;
(iii) $\|\operatorname{grad} h\| \leq \bar{R}$.

Theorem 4.1. Let $g$ be a $C^{k}$-map $g: H \rightarrow \mathbb{R},(k \geq 3)$, $g(0)=D g(0)=\cdots=$ $D^{i-1} g(0)=0(2 \leq i<k)$ and $Q$ be the $i$-form

$$
Q(x)=\frac{1}{i!} \cdot D^{i} g(0)(x \cdots x)
$$

We assume that there exist an open set $S$ and a number $r_{0}>0$ such that
(i) $S$ has the property $\mathcal{B}$ with a function $h$;
(ii) $P=\{x \mid \quad\|x\|=1, Q(x)=0\} \subset \operatorname{Int}\{x \mid h(x)=1\}=V$
$\operatorname{dist}(\bar{V} \backslash V, P) \geq r_{0}$;
(iii) $\|\operatorname{grad} Q(x)\|>r_{0}, \quad \forall x \in S$.

Then there are neighbourhoods $U_{1}, U_{2}$ of the point 0 and a $C^{1}$-diffeomorphism $\tilde{F}$ such that
(a) $\tilde{F}\left(Q^{-1}(0) \cap U_{1}\right) \subset g^{-1}(0) \cap U_{2}$;
(b) $\tilde{F}(0)=0, D \tilde{F}(0)=I$.

Moreover if we assume the condition
(C)

$$
\begin{aligned}
& Q\left(y_{n}\right) \rightarrow 0 \text { implies } \operatorname{dist}\left(y_{n}, P\right) \rightarrow 0 \\
& \text { for }\left\|y_{n}\right\|=1 \text { and } n \rightarrow \infty
\end{aligned}
$$

then in (a) we have the equality.
Here Int $A$ is the interior of the set $A$; dist $(A, B)$ is the distance of the sets $A, B$. Proof of Theorem 4.1: Let us put $N(x)=\frac{\operatorname{grad} Q(x)}{\|\operatorname{grad} Q(x)\|^{2}} \cdot h(x)$. By the assumptions of the theorem we have

$$
N(x) \text { is a } C^{1}-\operatorname{map},\|N(x)\| \leq M,\left\|D_{x} N(x)\right\| \leq M
$$

$$
\begin{equation*}
\text { for some } M>0 \text { and any } x \in H \tag{6}
\end{equation*}
$$

We consider the following initial value problem

$$
\begin{align*}
& Y_{t}^{\prime}(x, r)=\frac{d}{d t} Y_{t}(x, r)=h(x, r) \cdot N\left(Y_{t}(x, r)\right)  \tag{I}\\
& Y_{0}(x, r)=x, r>0
\end{align*}
$$

where $h(x, r)=\bar{h}(x \cdot r)(r \cdot x, \cdots, r \cdot x) / r^{i}$, and $\bar{h}(x)(x, \cdots, x)$ we obtain by the Taylor's theorem

$$
g(x)=Q(x)+\bar{h}(x)(x, \cdots, x)
$$

where $\bar{h}$ is an $i$-linear $C^{k-1}$-map, $\bar{h}(0)=0$.
Then there exist $\bar{M}, \tilde{r}_{0}>0$ such that

$$
\begin{equation*}
|h(x, r)| \leq \bar{M} \cdot|r| \tag{7}
\end{equation*}
$$

for $|r| \leq \tilde{r}_{0}$ and $\|x\| \leq \bar{R}$. We can consider $\bar{R} \geq 3$.
Lemma 4.2. There exist constants $M_{2}, r_{1}>0$ such that

$$
Y_{t}(x, r) \in B_{\bar{R}},\left\|Y_{t}(x, r)-x\right\| \leq M_{2} \cdot|r|
$$

for $\|x\| \leq \bar{R} / 2,|r|<r_{1}$ and $|t|<2$.
Proof of Lemma 4.2: The assertion is a consequence of (6), (7).
We put

$$
V_{1}=\left\{x \in V \mid \operatorname{dist}(x, P)<r_{0} / 2\right\} .
$$

Then $V_{1}$ is open and $P \subset V_{1}$.
Proposition 4.3. If $x \notin V_{1},\|x\|=1$ then dist $\left(x, Q^{-1}(0)\right)>r_{0} / 4$.
Proof of Proposition 4.3: Let $y \in P$. We can assume that $\langle x, y\rangle \geq 0$, since $\pm y \in P$. Then we have for any $t \in \mathbb{R}$

$$
\begin{aligned}
& \|x-t \cdot y\|^{2}=t^{2}-2 t\langle x, y\rangle+1 \geq 1-\langle x, y\rangle^{2} \\
& =(1+\langle x, y\rangle) \cdot(1-\langle x, y\rangle) \geq 1-\langle x, y\rangle \\
& =\|x-y\|^{2} / 2 \geq r_{0}^{2} / 8>r_{0}^{2} / 16
\end{aligned}
$$

This completes the proof.
As a consequence of Lemma 4.2 and Proposition 4.3 we obtain
Lemma 4.4. There exists $\bar{r}>0\left(\bar{r}<r_{1}, r_{0}\right)$ such that if $x \in V_{1} \cap \partial B_{1}$ then $Y_{t}(x, r) \in V$, and if $x \notin V_{1}, x \in \partial B_{1}$ then $Y_{t}(x, r) \notin Q^{-1}(0)$ for any $t,|t|<2$ and $r,|r|<\bar{r}$.

We put

$$
F(x)=\|x\| \cdot Y_{1}(x /\|x\|,\|x\|)
$$

for $x \neq 0$ and $F(0)=0$. By Lemma 4.2 we have

$$
\begin{equation*}
D F(0)=I,(I=\text { Identity }) \tag{8}
\end{equation*}
$$

From the equation (I) we obtain

$$
\begin{aligned}
& X_{t}^{\prime}(x, r)=D_{x} h(x, r) \cdot N\left(Y_{t}(x, r)\right)+h(x, r) \cdot D_{x} N\left(Y_{t}(x, r)\right) \cdot X_{t}(x, r) \\
& X_{0}(x, r)=I
\end{aligned}
$$

where $X_{t}(x, r)=D_{x} Y_{t}(x, r)$. Since $N$ satisfies (6) and $D_{x} h(x, r) \rightarrow 0$ uniformly with respect to $x,\|x\| \leq 2$ if $r \rightarrow 0$, applying the Gronwall's lemma we obtain

$$
\begin{equation*}
\left(X_{1}(x, r)-I\right) \rightarrow 0 \tag{9}
\end{equation*}
$$

uniformly with respect to $x,\|x\| \leq 2$ if $r \rightarrow 0$.
We put

$$
e(z, r)=Y_{1}(z, r)-z
$$

Then we have

$$
F(x)=x+\|x\| \cdot e(x /\|x\|,\|x\|)
$$

Hence

$$
\begin{aligned}
& D_{x} F(x) v=v+\langle x /\|x\|, v\rangle \cdot e(x /\|x\|,\|x\|)+ \\
& +\frac{d}{d z} e(x /\|x\|,\|x\|) \cdot(v-\langle x /\|x\|, v\rangle \cdot x /\|x\|)+ \\
& +\langle x, v\rangle \cdot \frac{d}{d r} e(x /\|x\|,\|x\|)
\end{aligned}
$$

By (8), (9) it follows

$$
v-D_{x} F(x) v \rightarrow 0
$$

uniformly with respect to $v$ as $x \rightarrow 0$. Hence $F$ is a local diffeomorphism at 0 .
By Lemma 4.4 we have

$$
\frac{d}{d t}\left(Q(x)+t \cdot h(x, r)-Q\left(Y_{t}(x, r)\right)\right)=h(x, r)-h(x, r)=0
$$

for $x \in V_{1} \cap \partial B_{1}, r<\bar{r}$.
Hence for $x$ such that $x /\|x\| \in V_{1}$ and $\|x\|<\bar{r}$, we have

$$
g(x)=Q(F(x))
$$

On the other hand, Lemma 4.4 also implies

$$
F(x) \notin Q^{-1}(0)
$$

if $x /\|x\| \notin V_{1},\|x\|<\bar{r}$.
Concerning the map $F^{-1}=\tilde{F}$ we obtain immediately the first assertion of the theorem.

To prove the last part of the theorem, assume $x \in g^{-1}(0) \cap U_{2}$ and $x \notin \tilde{F}\left(Q^{-1} \cap\right.$ $\left.U_{1}\right)$. Then $g(x)=0, F(x) \notin Q^{-1}(0)$. This implies $x /\|x\| \notin V_{1}$. On the other hand, $0=g(x)=Q(x)+\bar{h}(x)(x, \cdots, x)$. Hence $0=Q(x /\|x\|)+O(\|x\|)$. By (C) we have $|Q(y)|>\bar{c}>0 \forall y \notin V_{1}, y \in \partial B_{1}$. We arrive at the contradiction for $U_{2}$ small.

Remark 4.5. 1. If $\|\operatorname{grad} Q(x)\|>c>0$ for any $x,\|x\|=1$ then we obtain again the Kuiper's lemma (see the assertion 2 of Theorem 4.6).
2. If $H$ is a finite dimensional space then we have Theorem 1.3 from [2] for functions (see Remark 4.9).

Now we consider a map $g(x)=Q(x)+\tilde{h}(x)$, where $g: H_{1} \rightarrow H_{2}$ is a map which has the same properties as in Theorem 4.1 where we considered the case $H_{2}=\mathbb{R}$; $H_{1}, H_{2}$ are Hilbert spaces. But instead of the assumption (iii) of Theorem 4.1 we assume

$$
\begin{align*}
& D Q(x) \text { is surjective and }\|D Q(x) v\|>r_{0} \text { for any } \\
& x \in S \text { and } v \text { such that }  \tag{10}\\
& \|v\|=1 \text { and } v \perp \text { ker } D Q(x)
\end{align*}
$$

By using (10) there exists $c>0$ such that we can find for any $y \in S$ the linear mapping $B(y): H_{2} \rightarrow H_{1}$ satisfying $D Q(y) \cdot B(y)=I$ and $\|B(y)\| \leq c$, im $B(y)=$ $(\operatorname{ker} D Q(y))^{\perp},\left\|D_{y} B(y)\right\| \leq c$.

We put $N(x, r)=B(x) \cdot h(x, r) \cdot h(x)$, where $h(x, r)$ is defined as in the proof of Theorem 4.1. Then $D Q(x) \cdot N(x, r)=h(x, r) \cdot h(x)$ and we see that for the map $g: H_{1} \rightarrow H_{2}$ possessing the above properties we obtain a similar theorem as Theorem 4.1. Indeed, we consider instead of (I) the following equation

$$
\begin{aligned}
& Y_{t}^{\prime}(x, r)=N(x, r) \\
& Y_{0}(x, r)=x, r>0
\end{aligned}
$$

and we can repeat the above proof. We summarize our results in the following theorem.

Theorem 4.6. Let $H_{1}, H_{2}$ be Hilbert spaces. Consider $g: H_{1} \rightarrow H_{2}$ a $C^{k}$-map, $k \geq 3$ and $g(0)=D g(0)=\cdots=D^{i-1} g(0)=0,2 \leq i<k$. Let $Q$ be the $i$-form

$$
Q(x)=\frac{1}{i!} \cdot D^{i} g(0)(x, \cdots, x)
$$

We assume that there exist an open set $S$ and a number $r_{0}>0$ such that
(i) $S$ has the property $\mathcal{B}$ with a function $h$;
(ii) $P=\{x \mid \quad\|x\|=1, Q(x)=0\} \subset \operatorname{Int}\{x \mid h(x)=1\}=V$ $\operatorname{dist}(\bar{V} \backslash V, P) \geq r_{0}$;
(iii) $\|D Q(x) v\|>r_{0}, D Q(x)$ is surjective for any $x \in S$ and $v,\|v\|=1, v \perp \operatorname{ker} D Q(x)$.
Then

1. There are neighbourhoods $U_{1}, U_{2}$ of the point 0 and a $C^{1}$-diffeomorphism $F$ such that
(a) $F\left(Q^{-1}(0) \cap U_{1}\right) \subset g^{-1}(0) \cap U_{2}$;
(b) $F(0)=0, D F(0)=I$.

Moreover if we assume the condition

$$
\begin{align*}
& Q\left(y_{n}\right) \rightarrow 0 \text { implies dist }\left(y_{n}, P\right) \rightarrow 0 \\
& \text { for any }\left\|y_{n}\right\|=1 \text { and } n \rightarrow \infty . \tag{C}
\end{align*}
$$

Then in (a) we have the equality.
2. If the assumption (iii) is satisfied for any $x,\|x\|=1$, i.e. $\partial B_{1} \subset S$ in (iii). Then $g(F(x))=Q(x)$ for any $x \in U_{1}$. For this case we do not assume the conditions (i), (ii).

Proof: It remains to prove the statement 2. Since $Q(t \cdot y)=t^{i} \cdot Q(y)$ we have $D Q(t \cdot y)=t^{i-1} \cdot D Q(y)$. Thus we establish the assumptions (i), (ii) by taking

$$
\begin{aligned}
& S=\{t \cdot x \mid \quad\|x\|=1, t \in(1 / 2,2)\} \\
& h(x)=f\left(\|x\|^{2}\right)
\end{aligned}
$$

where $f: \mathbb{R} \rightarrow[0,1]$ is $C^{\infty}$-smooth, $\operatorname{supp} f \subset(1 / 4,4)$ and

$$
f(z)=1 \forall z \in[9 / 16,16 / 9] .
$$

Corollary 4.7. Let $g: H \rightarrow \mathbb{R}^{k}$ be a $C^{3}$-map and $g(0)=D g(0)=0$. Let

$$
D^{2} g(0)(u, v)=\left(\left(A_{1} u, v\right),\left(A_{2} u, v\right), \cdots,\left(A_{k} u, v\right)\right)
$$

where $A_{i}: H \rightarrow H$ are continuous linear maps. If there exists $r_{0}>0$ such that

$$
\left|\operatorname{det}\left(A_{i} u, A_{j} u\right)\right|>r_{0}
$$

for any $u \in H$ such that $\|u\|=1$. Then $g$ is $C^{1}$-right equivalent to the map

$$
f(x)=\frac{1}{2}\left(\left(A_{1} x, x\right),\left(A_{2} x, x\right), \cdots,\left(A_{k} x, x\right)\right)
$$

Remark 4.8. This corollary generalizes the Morse-Palais lemma [1].
Remark 4.9. The condition (C) of Theorems 4.1-2 is always satisfied for finite dimensional cases. The assumptions (i), (ii) of Theorems 4.1-2 are satisfied for finite dimensional cases provided $P \subset S$. Indeed, by using the partion of unity theorem [4, p. 377], we can construct such a function $h$. On the other hand, the assumptions of these theorems implies $P \subset S$. For infinite dimensional cases, the last assumption of the definition of the property $\mathcal{B}$ is problematic by using the partion of unity theorem. The author does not know whether the condition

$$
P \subset S, \operatorname{dist}(\bar{S} \backslash S, P)>c_{0}>0
$$

will already imply the existence of such a function $h$. These conditions remind the well-known (P.S.) condition for variational problems [3].
Maps in infinite dimensions

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