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# A $p$-Laplacian system with resonance and nonlinear boundary conditions on an unbounded domain 

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#### Abstract

We study a nonlinear elliptic system with resonance part and nonlinear boundary conditions on an unbounded domain. Our approach is variational and is based on the well known Landesman-Laser type conditions.


Keywords: quasilinear problem, p-Laplacian system, Landesman-Laser condition, resonance
Classification: 35D05, 35J45, 35J50

## 1. Introduction and statement of results

Let $\Omega$ be an unbounded domain in $\mathbb{R}^{N}, N \geq 3$, with a noncompact and smooth boundary $\partial \Omega$. In this paper we consider the following quasilinear elliptic system

$$
\left\{\begin{array}{l}
-\Delta_{p} u=\lambda_{1} a(x)|u|^{p-2} u+\lambda_{1} b(x)|u|^{\alpha}|v|^{\beta} v+g_{1}(x, u)-h_{1}(x), x \in \Omega  \tag{1}\\
-\Delta_{p} v=\lambda_{1} d(x)|v|^{p-2} v+\lambda_{1} b(x)|u|^{\alpha}|v|^{\beta} u+g_{2}(x, u)-h_{2}(x), x \in \Omega
\end{array}\right.
$$

subject to the nonlinear boundary conditions

$$
\begin{cases}|\nabla u|^{p-2} \nabla u \cdot \eta+c_{1}(x)|u|^{p-2} u=0, & x \in \partial \Omega  \tag{2}\\ |\nabla v|^{p-2} \nabla v \cdot \eta+c_{2}(x)|v|^{p-2} v=0, & x \in \partial \Omega\end{cases}
$$

where $\Delta_{p} u=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ and $\eta$ is the unit outward normal vector on $\partial \Omega$. On a single equation level with $\Omega$ bounded and Dirichlet boundary conditions, the problem has been studied by Arcoya and Orsina [1] taking into consideration the well known Landesman-Laser type conditions for the resonance part. The extension to the case of a system, again with $\Omega$ bounded and Dirichlet boundary conditions, was first considered by Zographopoulos in [7].

In order to confront with our problem we need a suitable space setting which we describe next.

For $\xi \in \mathbb{R}$, we set $w_{\xi}(x):=\frac{1}{(1+|x|)^{\xi}}$, and assume that the space $L^{r}\left(w_{\xi}, \Omega\right):=$ $\left\{u: \int_{\Omega} w_{\xi}(x)|u|^{r}<+\infty\right\}, r \geq 1$, is supplied with the norm

$$
\|u\|_{w_{\xi}, r}=\left(\int_{\Omega} w_{\xi}(x)|u|^{r}\right)^{1 / r}
$$

Let $C_{\delta}^{\infty}(\Omega)$ be the space of $C_{0}^{\infty}\left(\mathbb{R}^{N}\right)$-functions restricted on $\Omega$. For $p \in(1,+\infty)$, the weighted Sobolev space $E_{p}$ is the completion of $C_{\delta}^{\infty}(\Omega)$ in the norm

$$
\|u\|_{p}=\left(\int_{\Omega}|\nabla u|^{p}+\int_{\Omega} w_{p}(x)|u|^{p}\right)^{1 / p}
$$

By Lemma 2 in [5], we see that if $c(\cdot)$ is a positive continuous function defined on $\mathbb{R}^{N}$ such that

$$
k w_{p-1}(x) \leq c(x) \leq K w_{p-1}(x)
$$

for some positive constants $k$ and $K$,
then the norm

$$
\|u\|_{1, p}=\left(\int_{\Omega}|\nabla u|^{p}+\int_{\partial \Omega} c(x)|u|^{m}\right)^{1 / p}
$$

is equivalent to $\left|\|\cdot \mid\|_{p}\right.$.
We will consider our system on the space $E=E_{p} \times E_{p}$, supplied with the norm

$$
\|(u, v)\|=\|u\|_{1, p}+\|v\|_{1, p} .
$$

The following lemma is useful for our compactness arguments.
Lemma 1. (i) If

$$
p \leq r \leq \frac{p N}{N-p} \text { and } N>\alpha \geq N-r \frac{N-p}{p}
$$

then the embedding $E \subseteq L^{r}\left(w_{\alpha}, \Omega\right)$ is continuous. If the upper bound for $r$ in the first inequality and the upper bound for $\alpha$ in the second are strict, then the embedding is compact.
(ii) If

$$
p \leq m \leq \frac{p(N-1)}{N-p} \text { and } N>\beta \geq N-1-m \frac{N-p}{p}
$$

then the trace operator $T: E \rightarrow L^{m}\left(w_{\beta}, \partial \Omega\right)$ is continuous. If the upper bound for $m$ in the first inequality and the lower bound for $\beta$ are strict, then the trace operator is compact.
(iii) If

$$
1 \leq q<p \text { and } \frac{\alpha_{1}-N}{\alpha_{2}-N}>\frac{p}{q}
$$

then the embedding $L^{p}\left(w_{\alpha_{1}}, \Omega\right) \subseteq L^{q}\left(w_{\alpha_{2}}, \Omega\right)$ is continuous.
Proof: The first and second part of the lemma is Theorem 1 in [5], while the third is a consequence of the following inequality

$$
\int_{\Omega} \frac{1}{(1+|x|)^{\alpha_{2}}}|u|^{q} d x \leq\left(\int_{\Omega} \frac{1}{(1+|x|)^{d}} d x\right)^{\frac{p-q}{p}}\left(\int_{\Omega} \frac{1}{(1+|x|)^{\alpha_{1}}}|u|^{p} d x\right)^{\frac{q}{p}}
$$

where $d=\frac{\alpha_{2} p-\alpha_{1} q}{p-q}$. Note that the integral $\int_{\Omega} \frac{1}{(1+|x|)^{d}} d x$ converges since $d>N$.

We study (1)-(2) in connection with the eigenvalue problem

$$
\left\{\begin{array}{l}
-\Delta_{p} u=\lambda_{1} a(x)|u|^{p-2} u+\lambda_{1} b(x)|u|^{\alpha}|v|^{\beta} v  \tag{3}\\
-\Delta_{p} v=\lambda_{1} d(x)|v|^{p-2} v+\lambda_{1} b(x)|u|^{\alpha}|v|^{\beta} u
\end{array}\right.
$$

subject to the boundary conditions (2), which was considered in [4] under the following set of assumptions, also needed for the present problem:
(H1) $2<p<N, \alpha, \beta \geq 0$ with $\alpha+\beta=p-2$ and $\alpha+1, \beta+1 \leq \frac{p p^{*}}{N}$, where $p^{*}=\frac{N p}{N-p}$.
(H2) (i) There exist positive constants $\alpha_{1}, A$ with $\alpha_{1} \in\left(p+\frac{(\beta+1)(N-p)}{p^{*}}, N\right)$ such that $0<a(x) \leq A w_{\alpha_{1}}(x)$ a.e. in $\Omega$.
(ii) There exist positive constants $\alpha_{2}, D$ with $\alpha_{2} \in\left(p+\frac{(\alpha+1)(N-p)}{p^{*}}, N\right)$ such that

$$
0<d(x) \leq D w_{\alpha_{2}}(x) \text { a.e. in } \Omega .
$$

(iii) $m\{x \in \Omega: b(x)>0\}>0$ and

$$
0 \leq b(x) \leq B w_{s}(x) \text { a.e. in } \Omega
$$

where $B>0$ and $s \in(p, N)$.
$(\mathrm{H} 3) c_{1}(\cdot)$ and $c_{2}(\cdot)$ are positive continuous functions defined on $R^{N}$ with

$$
k w_{p-1}(x) \leq c_{1}(x), c_{2}(x) \leq K w_{p-1}(x)
$$

for some positive constants $k$ and $K$.
Let
$I(u, v)=\frac{\alpha+1}{p} \int_{\Omega}|\nabla u|^{p}+\frac{\alpha+1}{p} \int_{\partial \Omega} c_{1}(x)|u|^{p}+\frac{\beta+1}{p} \int_{\Omega}|\nabla v|^{p}+\frac{\beta+1}{p} \int_{\partial \Omega} c_{2}(x)|v|^{p}$
and

$$
J(u, v)=\frac{\alpha+1}{p} \int_{\Omega} a(x)|u|^{p}+\frac{\beta+1}{p} \int_{\Omega} d(x)|v|^{p}+\int_{\Omega} b(x)|u|^{\alpha}|v|^{\beta} u v .
$$

Theorem 2 ([4]). Let $\Omega$ be an unbounded domain in $R^{N}, N \geq 2$, with a noncompact and smooth boundary $\partial \Omega$. Assume that hypotheses (H1), (H2) and (H3) hold. Then
(a) the system (3) admits a positive principal eigenvalue $\lambda_{1}$ given by

$$
\lambda_{1}=\inf \{I(u, v): J(u, v)=1\}
$$

Each component of the associated normalized eigenfunction $\left(u_{1}, v_{1}\right)$ is positive on $\bar{\Omega}$ and of class $C_{\text {loc }}^{1, \delta}(\Omega)$ for some $\delta \in(0,1)$.
(b) the set of eigenfunctions corresponding to $\lambda_{1}$ forms a one dimensional manifold $X \subseteq E$ defined by

$$
X=\left\{c\left(u_{1}, v_{1}\right) ; c \in \mathbb{R} \backslash\{0\}\right\}
$$

(c) $\lambda_{1}$ is isolated, in the sense that there exists $\eta>0$ such that the interval $\left(0, \lambda_{1}+\eta\right)$ does not contain any other eigenvalue than $\lambda_{1}$.

We make the following assumptions concerning the resonance part:
(H4) (i) $g_{1}(\cdot, \cdot), g_{2}(\cdot, \cdot)$ are Caratheodory functions such that
$\left|g_{1}(x, s)\right| \leq \frac{C_{1}}{(1+|x|)^{\alpha_{3}}}$ and $\left|g_{2}(x, s)\right| \leq \frac{C_{2}}{(1+|x|)^{\alpha_{4}}}$, where
$\alpha_{3}>N-\frac{N-\alpha_{1}}{p}, \alpha_{4}>N-\frac{N-\alpha_{2}}{p}, C_{1}, C_{2}$ are positive constants, and the limits

$$
\lim _{s \rightarrow \pm \infty} g_{i}(x, s)=g_{i}^{ \pm}(x), \quad i=1,2
$$

exist for almost every $x \in \Omega$.
(ii) $\left|h_{1}(x)\right| \leq \frac{H_{1}}{(1+|x|)^{\alpha_{3}}}$ and $\left|h_{2}(x)\right| \leq \frac{H_{2}}{(1+|x|)^{\alpha_{4}}}$ for some positive constants $H_{1}, H_{2}$.
Furthermore, we will need the following inequalities

$$
\begin{align*}
& L^{+}<(\alpha+1) \int_{\Omega} h_{1}(x) u_{1}+(\beta+1) \int_{\Omega} h_{2}(x) v_{1}<L^{-}  \tag{4}\\
& L^{-}<(\alpha+1) \int_{\Omega} h_{1}(x) u_{1}+(\beta+1) \int_{\Omega} h_{2}(x) v_{1}<L^{+} \tag{5}
\end{align*}
$$

where $\left(u_{1}, v_{1}\right)$ is the normalized eigenfunction of $(3)-(2)$ with positive components and

$$
\begin{aligned}
& L^{+}=(\alpha+1) \int_{\Omega} g_{1}^{+}(x) u_{1}+(\beta+1) \int_{\Omega} g_{2}^{+}(x) v_{1} \\
& L^{-}=(\alpha+1) \int_{\Omega} g_{1}^{-}(x) u_{1}+(\beta+1) \int_{\Omega} g_{2}^{-}(x) v_{1}
\end{aligned}
$$

Inequalities (4) and (5) are the adaptation to the case of systems of the Landes-man-Laser type conditions for scalar equations.

The energy functional of the problem (1)-(2) is

$$
\begin{aligned}
\Phi(u, v)= & \frac{\alpha+1}{p} \int_{\Omega}|\nabla u|^{p}+\frac{\alpha+1}{p} \int_{\partial \Omega} c_{1}(x)|u|^{p}-\lambda_{1} \frac{\alpha+1}{p} \int_{\Omega} a(x)|u|^{p} \\
& -(\alpha+1) \int_{\Omega} G_{1}(x, u)+(\alpha+1) \int_{\Omega} h_{1}(x) u \\
& +\frac{\beta+1}{p} \int_{\Omega}|\nabla v|^{p}+\frac{\beta+1}{p} \int_{\partial \Omega} c_{2}(x)|v|^{p}-\lambda_{1} \frac{\beta+1}{p} \int_{\Omega} d(x)|v|^{p} \\
& -(\beta+1) \int_{\Omega} G_{2}(x, v)+(\beta+1) \int_{\Omega} h_{2}(x) v-\lambda_{1} \int_{\Omega} b(x)|u|^{\alpha}|v|^{\beta} u v,
\end{aligned}
$$

where

$$
G_{i}(x, s)=\int_{0}^{s} g_{i}(x, t) d t, \quad i=1,2
$$

In view of (H1)-(H3), the functional $\Phi$ is well defined and continuously differentiable on $E$. By a weak solution of (1)-(2) we mean an element of $E$ which is a critical point of $\Phi$.

The main result of this work is the following theorem:
Theorem 3. (i) Assume that hypotheses (H1)-(H3) and inequality (4) or (5) hold. Then the system (1)-(2) admits a weak solution.

## 2. The main result

In view of Theorem $2(\mathrm{a})$, it is clear that $\lambda_{1} \leq \min \left\{\lambda_{u}, \lambda_{v}\right\}$, where $\lambda_{u}, \lambda_{v}$ are the first eigenvalues of the problems $-\Delta_{p} u=\lambda a(x)|u|^{p-2} u$ and $-\Delta_{p} v=$ $\lambda d(x)|v|^{p-2} v$, with the boundary conditions (2), respectively. The following lemma shows that this inequality is actually strict.

Lemma 4. $\lambda_{1}<\min \left\{\lambda_{u}, \lambda_{v}\right\}$.
Proof: Let $u_{0}>0$ be an eigenfunction corresponding to $\lambda_{u}$ and $v_{0}>0$ an eigenfunction corresponding to $\lambda_{v}$. If $\lambda_{u}=\lambda_{v}$, then

$$
\lambda_{1} \leq \frac{I\left(u_{0}, v_{0}\right)}{J\left(u_{0}, v_{0}\right)}<\lambda_{u}
$$

so without loss of generality we may assume that $\lambda_{u}<\lambda_{v}$. Let $t>0$ be such that

$$
\begin{equation*}
\frac{\beta+1}{p} \int_{\Omega} d(x)\left|v_{0}\right|^{p}<\frac{\lambda_{u}}{\lambda_{v}-\lambda_{u}} \int_{\Omega} b(x)\left|t u_{0}\right|^{\alpha}\left|v_{0}\right|^{\beta} t u_{0} v_{0} \tag{6}
\end{equation*}
$$

Then, in view of (6),

$$
\lambda_{1} \leq \frac{I\left(t u_{0}, v_{0}\right)}{J\left(t u_{0}, v_{0}\right)}<\lambda_{u}=\min \left\{\lambda_{u}, \lambda_{v}\right\}
$$

Note that due to assumptions $\mathrm{H}(1)-\mathrm{H}(4)$, the operators $A, N, B, C: E \rightarrow E^{*}$ given by

$$
\begin{aligned}
\langle A(u, v),(\varphi, \psi)\rangle:= & \int_{\Omega}|\nabla u|^{p-2} u \nabla \varphi+\int_{\Omega}|\nabla v|^{p-2} \nabla v \nabla \psi \\
\langle N(u, v),(\varphi, \psi)\rangle:= & \int_{\Omega} a(x)|u|^{p-2} u \varphi-\int_{\partial \Omega} c_{1}(x)|u|^{p-2} u \varphi \\
& +\int_{\Omega} d(x)|v|^{p-2} v \psi-\int_{\partial \Omega} c_{2}(x)|v|^{p-2} v \psi \\
\langle B(u, v),(\varphi, \psi)\rangle:= & \int_{\Omega} b(x)|u|^{\alpha}|v|^{\beta} v \varphi+\int_{\Omega} b(x)|u|^{\alpha}|v|^{\beta} u \psi \\
\langle C(u, v),(\varphi, \psi)\rangle:= & \int_{\Omega}\left(g_{1}(x, u)-h_{1}(x)\right) \varphi+\int_{\Omega}\left(g_{2}(x, v)-h_{2}(x)\right) \psi
\end{aligned}
$$

are well defined. Following standard arguments based on the embeddings given in Lemma 1, we have:

Lemma 5. The operators $A, N, B$ and $C$ are continuous. Moreover, $N, B$ and $C$ are compact.

We can now proceed with the proof of the main result:
Proof of Theorem 3: We assume first that (4) holds. We claim that $\Phi$ satisfies the PS-condition. Indeed, let $\left\{\left(u_{n}, v_{n}\right)\right\}_{n \in N}$ be a PS-sequence in $E$. Then

$$
\begin{equation*}
-c \leq \Phi\left(u_{n}, v_{n}\right) \leq c \tag{7}
\end{equation*}
$$

for some $c>0$, and there exists a sequence $\left\{\varepsilon_{n}\right\}_{n \in N}$ converging to $0^{+}$, such that

$$
\begin{equation*}
-\varepsilon_{n}\|(u, v)\| \leq \Phi^{\prime}\left(u_{n}, v_{n}\right)(u, v) \leq \varepsilon_{n}\|(u, v)\| \text { for every }(u, v) \in E \tag{8}
\end{equation*}
$$

We will show that the sequence $\left\{\left(u_{n}, v_{n}\right)\right\}_{n \in N}$ is bounded in $E$. Assume the contrary, that is $\left\|\left(u_{n}, v_{n}\right)\right\| \rightarrow+\infty$. Let

$$
\begin{equation*}
\widehat{u}_{n}:=\frac{u_{n}}{\left\|\left(u_{n}, v_{n}\right)\right\|}, \quad \widehat{v}_{n}:=\frac{v_{n}}{\left\|\left(u_{n}, v_{n}\right)\right\|} \tag{9}
\end{equation*}
$$

Since $\left\|\widehat{u}_{n}\right\|_{E_{p}} \leq 1$ and $\left\|\widehat{v}_{n}\right\|_{E_{p}} \leq 1$, by passing to subsequences if necessary, we may assume that $\widehat{u}_{n} \rightarrow \widehat{u}$ and $\widehat{v}_{n} \rightarrow \widehat{v}$ weakly in $E_{p}$. Due to our hypotheses on $h_{1}$ and $g_{1}$ we obtain

$$
\begin{equation*}
\lim _{n \rightarrow+\infty} \int_{\Omega} \frac{G_{1}\left(x, u_{n}\right)}{\left\|\left(u_{n}, v_{n}\right)\right\|^{p}}=\lim _{n \rightarrow+\infty} \int_{\Omega} \frac{h_{1} u_{n}}{\left\|\left(u_{n}, v_{n}\right)\right\|^{p}}=0 \tag{10}
\end{equation*}
$$

and similarly for $G_{2}(\cdot, \cdot)$ and $h_{2}(\cdot)$. Dividing (7) by $\left\|\left(u_{n}, v_{n}\right)\right\|^{p}$ and using (10), we arrive at

$$
\begin{aligned}
& \limsup _{n \rightarrow+\infty}\left[\frac{\alpha+1}{p}\left\{\int_{\Omega}\left|\nabla \widehat{u}_{n}\right|^{p}+\int_{\partial \Omega} c_{1}(x)\left|\widehat{u}_{n}\right|^{p}-\lambda_{1} \int_{\Omega} a(x)\left|\widehat{u}_{n}\right|^{p}\right\}\right. \\
& \quad+\frac{\beta+1}{p}\left\{\int_{\Omega}\left|\nabla \widehat{v}_{n}\right|^{p}+\int_{\partial \Omega} c_{2}(x)\left|\widehat{v}_{n}\right|^{p}-\lambda_{1} \int_{\Omega} d(x)\left|\widehat{v}_{n}\right|^{p}\right\} \\
& \left.\quad-\lambda_{1} \int_{\Omega} b(x)\left|\widehat{u}_{n}\right|^{\alpha}\left|\widehat{v}_{n}\right|^{\beta} \widehat{u}_{n} \widehat{v}_{n}\right] \leq 0
\end{aligned}
$$

and Lemma 1 gives

$$
\begin{aligned}
& \limsup _{n \rightarrow+\infty}\left[\frac{\alpha+1}{p}\left\{\int_{\Omega}\left|\nabla \widehat{u}_{n}\right|^{p}+\int_{\partial \Omega} c_{1}(x)\left|\widehat{u}_{n}\right|^{p}\right\}\right. \\
& \left.\quad+\frac{\beta+1}{p}\left\{\int_{\Omega}\left|\nabla \widehat{v}_{n}\right|^{p}+\int_{\partial \Omega} c_{2}(x)\left|\widehat{v}_{n}\right|^{p}\right\}\right] \\
& \leq \lambda_{1}\left(\frac{\alpha+1}{p} \int_{\Omega} a(x)|\widehat{u}|^{p}+\frac{\beta+1}{p} \int_{\Omega} d(x)|\widehat{v}|^{p}+\int_{\Omega} b(x)|\widehat{u}|^{\alpha}|\widehat{v}|^{\beta} \widehat{u} \widehat{v}\right) .
\end{aligned}
$$

The reverse inequality (with the limsup replaced by liminf) also holds due to the lower semicontinuity of the norms. Thus $(\widehat{u}, \widehat{v})$ is a nonzero solution of (3) with $\|(\widehat{u}, \widehat{v})\|=1$. In view of Lemma $4, \widehat{u} \neq 0$ and $\widehat{v} \neq 0$. By Theorem $2, \widehat{u}$ and $\widehat{v}$ have the same sign. Suppose that both $\widehat{u}$ and $\widehat{v}$ are positive, the other case can be treated similarly. Thus $\widehat{u}=u_{1}$ and $\widehat{v}=v_{1}$. If we replace $(u, v)$ by ( $u_{n}, v_{n}$ ) in (8), write the relation for $-\Phi^{\prime}$, multiply the members of (7) by $p$, add memberwise the resulting inequalities, and divide by $\left\|\left(u_{n}, v_{n}\right)\right\|$, we obtain

$$
\begin{gathered}
\mid(\alpha+1)(p-1) \int_{\Omega} h_{1}(x) \widehat{u}_{n}+(\beta+1)(p-1) \int_{\Omega} h_{2}(x) \widehat{v}_{n} \\
-(\alpha+1) p \int_{\Omega} \widehat{g}_{1}\left(x, u_{n}\right) \widehat{u}_{n}+(\alpha+1) \int_{\Omega} g_{1}\left(x, u_{n}\right) \widehat{u}_{n}-(\beta+1) p \int_{\Omega} \widehat{g}_{2}\left(x, v_{n}\right) \widehat{v}_{n} \\
+(\beta+1) \int_{\Omega} g_{2}\left(x, v_{n}\right) \widehat{v}_{n} \left\lvert\, \leq \frac{c}{\left\|\left(u_{n}, v_{n}\right)\right\|}+\varepsilon_{n}\right.,
\end{gathered}
$$

where

$$
\widehat{g}_{i}(x, s):=\left\{\begin{array}{ll}
\frac{G_{i}(x, s)}{s} & \text { if } s \neq 0, \\
g_{i}(x, 0) & \text { if } s=0
\end{array} \quad i=1,2\right.
$$

By letting $n \rightarrow+\infty$, we get

$$
\begin{align*}
& \lim _{n \rightarrow+\infty}\left\{(\alpha+1) \int_{\Omega}\left[g_{1}\left(x, u_{n}\right) \widehat{u}_{n}-p \widehat{g}_{1}\left(x, u_{n}\right) \widehat{u}_{n}\right]\right. \\
& \left.\quad+(\beta+1) \int_{\Omega}\left[g_{2}\left(x, v_{n}\right) \widehat{v}_{n}-p \widehat{g}_{2}\left(x, v_{n}\right) \widehat{v}_{n}\right]\right\}  \tag{11}\\
& = \\
& (\alpha+1)(1-p) \int_{\Omega} h_{1}(x) \widehat{u}+(\beta+1)(1-p) \int_{\Omega} h_{2}(x) \widehat{v} .
\end{align*}
$$

By $(9), u_{n}(x)$ and $v_{n}(x)$ tend to $+\infty$, so

$$
g_{1}\left(x, u_{n}\right) \rightarrow g_{1}^{+}(x) \text { and } g_{2}\left(x, v_{n}\right) \rightarrow g_{2}^{+}(x) \text { a.e. in } \Omega .
$$

Therefore

$$
\begin{equation*}
\lim _{n \rightarrow+\infty} \int_{\Omega}\left[g_{1}\left(x, u_{n}\right) \widehat{u}_{n}-p \widehat{g}_{1}\left(x, u_{n}\right) \widehat{u}_{n}\right]=(1-p) \int_{\Omega} g_{1}^{+}(x) \widehat{u} \tag{12}
\end{equation*}
$$

with a similar relation holding for $g_{2}(\cdot, \cdot)$ as well. In view of (11) and (12), we have
$(\alpha+1) \int_{\Omega} g_{1}^{+}(x) u_{1}+(\beta+1) \int_{\Omega} g_{2}^{+}(x) v_{1}=(\alpha+1) \int_{\Omega} h_{1}(x) u_{1}+(\beta+1) \int_{\Omega} h_{2}(x) v_{1}$,
contradicting (4). Thus $\left\{\left(u_{n}, v_{n}\right)\right\}_{n \in N}$ is bounded. Therefore, up to subsequences, $u_{n} \rightarrow u_{0}$ and $v_{n} \rightarrow v_{0}$ weakly in $E_{p}$ and strongly in $L^{p}\left(w_{\alpha_{1}}, \Omega\right)$ and $L^{p}\left(w_{\alpha_{2}}, \Omega\right)$, respectively. By taking $(u, v)=\left(u_{n}, v_{n}\right)-\left(u_{0}, v_{0}\right)$ in (8), and using Lemma 1, we derive that

$$
\begin{aligned}
& (\alpha+1)\left\{\int_{\Omega}\left(\left|\nabla u_{n}\right|^{p-2} \nabla u_{n}-\left|\nabla u_{0}\right|^{p-2} \nabla u_{0}\right)\left(\nabla u_{n}-\nabla u_{0}\right)\right. \\
& \left.\quad+\int_{\partial \Omega} c_{1}\left(\left|u_{n}\right|^{p-2} u_{n}-\left|u_{0}\right|^{p-2} u_{0}\right)\left(u_{n}-u_{0}\right)\right\} \\
& \quad+(\beta+1)\left\{\int_{\Omega}\left(\left|\nabla v_{n}\right|^{p-2} \nabla v_{n}-\left|\nabla v_{0}\right|^{p-2} \nabla v_{0}\right)\left(\nabla v_{n}-\nabla v_{0}\right)\right. \\
& \left.\quad+\int_{\partial \Omega} c_{1}\left(\left|v_{n}\right|^{p-2} v_{n}-\left|v_{0}\right|^{p-2} v_{0}\right)\left(v_{n}-v_{0}\right)\right\} \rightarrow 0
\end{aligned}
$$

which, in view of inequality 2.5 in [2], implies that $\left(u_{n}, v_{n}\right) \rightarrow\left(u_{0}, v_{0}\right)$ in $E$.
We show next that $\Phi$ is coercive. Indeed, if this were not the case, there would exist a sequence $\left\{\left(u_{n}, v_{n}\right)\right\}_{n \in N}$ with $\left\|\left(u_{n}, v_{n}\right)\right\| \rightarrow+\infty$ and

$$
\begin{equation*}
\left|\Phi\left(u_{n}, v_{n}\right)\right| \leq M, \text { for some } M>0 \tag{13}
\end{equation*}
$$

Working as before, we get that

$$
\begin{aligned}
& \lim _{n \rightarrow+\infty}\left[\frac{\alpha+1}{p}\left\{\int_{\Omega}\left|\nabla \widehat{u}_{n}\right|^{p}+\int_{\partial \Omega} c_{1}(x)\left|\widehat{u}_{n}\right|^{p}-\lambda_{1} \int_{\Omega} a(x)\left|\widehat{u}_{n}\right|^{p}\right\}\right. \\
& \quad+\frac{\beta+1}{p}\left\{\int_{\Omega}\left|\nabla \widehat{v}_{n}\right|^{p}+\int_{\partial \Omega} c_{2}(x)\left|\widehat{v}_{n}\right|^{p}-\lambda_{1} \int_{\Omega} d(x)\left|\widehat{v}_{n}\right|^{p}\right\} \\
& \left.\quad-\lambda_{1} \int_{\Omega} b(x)\left|\widehat{u}_{n}\right|^{\alpha}\left|\widehat{v}_{n}\right|^{\beta} \widehat{u}_{n} \widehat{v}_{n}\right]=0
\end{aligned}
$$

where $\widehat{u}_{n}$ and $\widehat{v}_{n}$ are defined in (9). Thus $\left(\widehat{u}_{n}, \widehat{v}_{n}\right) \rightarrow\left(u_{1}, v_{1}\right)$ or $\left(\widehat{u}_{n}, \widehat{v}_{n}\right) \rightarrow$ $-\left(u_{1}, v_{1}\right)$ in $E$. If $\left(\widehat{u}_{n}, \widehat{v}_{n}\right) \rightarrow\left(u_{1}, v_{1}\right)$, by (13) and the variational characterization of $\lambda_{1}$, we obtain
$(\alpha+1) \int_{\Omega} g_{1}^{+}(x) u_{1}+(\beta+1) \int_{\Omega} g_{2}^{+}(x) v_{1} \geq(\alpha+1) \int_{\Omega} h_{1}(x) u_{1}+(\beta+1) \int_{\Omega} h_{2}(x) v_{1}$, while if $\left(\widehat{u}_{n}, \widehat{v}_{n}\right) \rightarrow-\left(u_{1}, v_{1}\right)$, we get $(\alpha+1) \int_{\Omega} g_{1}^{-}(x) u_{1}+(\beta+1) \int_{\Omega} g_{2}^{-}(x) v_{1} \leq(\alpha+1) \int_{\Omega} h_{1}(x) u_{1}+(\beta+1) \int_{\Omega} h_{2}(x) v_{1}$, contradicting (4). We can now use Theorem 4.7 in [3] to get a weak solution of (1)-(2).

Assume next that (5) holds. We split $E$ as the direct sum of the eigenspace $X$ and $Y=\left\{(u, v) \in E: \int_{\Omega} u u_{1}^{p-1}+\int_{\Omega} v v_{1}^{p-1}=0\right\}$. Then $\Phi$ has a saddle point geometry, i.e.,
(i) $\Phi\left(t\left(u_{1}, v_{1}\right)\right) \rightarrow-\infty$ if $|t| \rightarrow+\infty$, and
(ii) $\Phi$ is bounded from below on $Y$.

Indeed, since

$$
\begin{aligned}
\Phi\left(t\left(u_{1}, v_{1}\right)\right)= & (\alpha+1)\left[\int_{\Omega} h_{1}(x) t u_{1}-\int_{\Omega} G_{1}\left(x, t u_{1}\right)\right] \\
& +(\beta+1)\left[\int_{\Omega} h_{2}(x) t v_{1}-\int_{\Omega} G_{2}\left(x, t v_{1}\right)\right] \\
= & (\alpha+1) t\left[\int_{\Omega} h_{1}(x) u_{1}-\int_{\Omega} \frac{G_{1}\left(x, t u_{1}\right)}{t u_{1}} u_{1}\right] \\
& +(\beta+1) t\left[\int_{\Omega} h_{2}(x) v_{1}-\int_{\Omega} \frac{G_{2}\left(x, t v_{1}\right)}{t v_{1}} v_{1}\right]
\end{aligned}
$$

by taking the limit as $|t| \rightarrow \infty$ and working as in the first part of the proof, we can use (5) to get (i). To prove (ii) we exploit the isolation of $\lambda_{1}$, see Theorem 2, to derive that there exists $\widehat{\lambda}>\lambda_{1}$ such that

$$
\widehat{\lambda}<\frac{I(u, v)}{J(u, v)}
$$

for every $(u, v) \in Y$. If $(u, v) \in Y$, in view of Lemma 1 ,

$$
\begin{aligned}
\Phi(u, v)= & I(u, v)-\lambda_{1} J(u, v)+(\alpha+1)\left[\int_{\Omega} h_{1}(x) u-\int_{\Omega} G_{1}(x, u)\right] \\
& +(\beta+1)\left[\int_{\Omega} h_{2}(x) v-\int_{\Omega} G_{2}(x, v)\right] \\
> & \left(1-\frac{\lambda_{1}}{\hat{\lambda}}\right) I(u, v)-(\alpha+1) c_{1}\|u\|_{1, p}-(\beta+1) c_{2}\|v\|_{1, p}
\end{aligned}
$$

for some $c_{1}, c_{2}>0$. Consequently, $\Phi$ is bounded from below on $Y$. An application of the saddle point theorem, see [6], provides a weak solution of (1)-(2).
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