## Mathematica Bohemica

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Mathematica Bohemica, Vol. 118 (1993), No. 2, 171-174
Persistent URL: http://dml.cz/dmlcz/126048

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# INVARIANT CURVES FROM SYMMETRY 

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(Received December 20, 1991)

Summary. We show that certain symmetries of maps imply the existence of their invariant curves.

Keywords: invariant curves, discrete dynamical systems
AMS classification: 58 F21, 58 F08

## 1. Introduction

In this paper we shall investigate the following problem: Does a symmetry of a continuous map imply the existence of invariant curves? An affirmative answer to a similar question for ordinary differential equations was given in [1].

We study a continuous map $F: \mathbf{R}^{m} \rightarrow \mathbf{R}^{m}, m \geqslant 2$ equivariant under an orthogonal representation of a compact Lie group. Then assuming some other properties of $F$ we show the existence of invariant curves which lie on spheres. The proof of the theorem of this paper is based on results of the paper [1] and features of orthogonal representations.

## 2. Main result

Consider a continuous map $F: \mathbf{R}^{m} \rightarrow \mathbf{R}^{m}, m \geqslant 2$ such that
i) there exist $x_{1}, x_{2}$ satisfying

$$
\left(\left|F\left(x_{1}\right)\right|-\left|x_{1}\right|\right)\left(\left|F\left(x_{2}\right)\right|-\left|x_{2}\right|\right)<0 ;
$$

ii) $F$ is equivariant under a linear othogonal representation $T$ of a compact Lie group $G, T=\left\{T_{g}: g \in G\right\}$, i.e.,

$$
F\left(T_{g} x\right)=T_{g} F(x)
$$

iii) $T$ is transitive on the unit sphere $S^{m-1} \subset \mathbf{R}^{m}$, i.e.,

$$
\left\{T_{g} x: g \in G\right\}=S^{m-1}
$$

for each $x \in S^{m-1}$ (see [1, p. 478]).
Theorem. Under the above assumptions $F$ has an invariant curve.
Proof. Since $F$ is equivariant under $T$ and $T$ is transitive, we have $|F(x)|=$ $\varrho(|x|)$ for a continuous function $\varrho:[0, \infty) \rightarrow[0, \infty)$. We note that the assumption ii) implies $F(0)=0$. The condition i) implies

$$
\left(\varrho\left(\left|x_{1}\right|\right)-\left|x_{1}\right|\right) \cdot\left(\varrho\left(\left|x_{2}\right|\right)-\left|x_{2}\right|\right)<0 .
$$

Hence there is $h>0$ such that $\varrho(h)=h$. Thus the sphere $S_{h}=\{x:|x|=h\}$ is invariant under $F$. Take $x_{0} \in S_{h}$. Then by [1, Lemma 1 and Lemma 2] there is
$K_{0} \in C(T)=\left\{K: K\right.$ is an $m \times m$ matrix, $K T_{g}=T_{g} K$ for each $\left.g \in G\right\}$
such that $F\left(x_{0}\right)=K_{0} x_{0}$.
Further $K_{0} T_{g} x_{0}=T_{g} K_{0} x_{0}=T_{g} F\left(x_{0}\right)=F\left(T_{g} x_{0}\right)$. Thus

$$
\left|K_{0} T_{g} x_{0}\right|=\left|F\left(T_{g} x_{0}\right)\right|=\left|F\left(x_{0}\right)\right|=h .
$$

Since $T$ is transitive and $T_{g} x_{0} \in S_{h}$, we see that $\left|K_{0} x\right|=|x|, \forall x \in S_{h}$. Thus $K_{0}$ is orthogonal. Hence the eigenvalues of $K_{0}$ lie on the unit circle.

We have $K_{0} T_{g} x_{0}=F\left(T_{g} x_{0}\right)$. Since $T$ is transitive we have

$$
K_{0} x=F(x)
$$

for each $x \in S_{h}$. Hence $F / S_{h}=K_{0}$, i.e., the restriction of $F$ on $S_{h}$ is the linear $\operatorname{map} K_{0}$.

Since $T$ is transitive, $T$ is irreducible. Hence the minimal polynomial of $K_{0}$ is irreducible as well. Indeed, let the minimal polynomial $p$ be expressed as $p=p_{1} p_{2}$ for $p_{1}, p_{2}$ nonconstant polynomials. Then $\exists \alpha \in \mathbf{R}^{m}$ such that $\beta=p_{2}\left(K_{0}\right) \alpha \neq 0$. Consider $Y=\operatorname{ker} p_{1}\left(K_{0}\right)$. Then $\beta \in Y$, since $p_{1}\left(K_{0}\right) \beta=p_{1}\left(K_{0}\right) \cdot p_{2}\left(K_{0}\right) \alpha=$
$p\left(K_{0}\right) \alpha=0$. Hence $Y \neq\{0\}$. Using the property $K_{0} T_{g}=T_{g} K_{0}, \forall g \in G$, we have $p_{1}\left(K_{0}\right) T_{g}=T_{g} p_{1}\left(K_{0}\right), \forall g \in G$. This implies that $Y$ is invariant under $T_{g}$, $\forall g \in G$. But $T$ is irreducible, hence $Y=\mathbf{R}^{m}$ and $p_{2}$ has to be constant. This is a contradiction. Thus $K_{0}$ satisfies either an equation $K_{0}=d \cdot I, d \in \mathbf{R}$ or

$$
\begin{equation*}
K_{0}^{2}=b \cdot K_{0}+c \cdot I \tag{1}
\end{equation*}
$$

for $b, c \in \mathbf{R}$ and $I=$ Identity.
Let the minimal polynomial of $K_{0}$ be $y-d$, i.e., $K_{0}=d \cdot I$. Since $K_{0}$ is orthogonal we have $d= \pm 1$ and the existence of an invariant curve is trivial.

Let $y^{2}-b y-c$ be the minimal polynomial. Since $K_{0}$ has only eigenvalues on the unit circle,

$$
y^{2}=b y+c
$$

has only roots with absolute values 1 . We have applied the Cayley-Hamilton theorem [2]. This implies

$$
|b| \leqslant 2, \quad c= \pm 1
$$

From (1) and $K_{0}^{\top}=K_{0}^{-1}$ we have

$$
\begin{align*}
& K_{0}=b \cdot I \pm K_{0}^{-1}=b \cdot I \pm K_{0}^{\top} \\
& K_{0} \mp K_{0}^{\top}=b \cdot I \tag{2}
\end{align*}
$$

First, we consider

$$
\begin{equation*}
K_{0}-K_{0}^{\top}=b \cdot I \tag{3}
\end{equation*}
$$

Then $b=0, K_{0}=K_{0}^{\top}$. In this case the polynomial $y^{2}-1$ is not irreducible. Thus it is not minimal and we arrive at the first case.

Now we consider the second version of (2),

$$
K_{0}+K_{0}^{\top}=b \cdot I
$$

Let us take $B=K_{0}-\frac{b}{2} \cdot I$. Then $K_{0}=\frac{b}{2} \cdot I+B$ and $B^{\top}=-B$. By $K_{0} K_{0}^{\top}=I$ we have

$$
\begin{align*}
I & =\left(\frac{b}{2} \cdot I+B\right)\left(\frac{b}{2} \cdot I-B\right) \\
& =\frac{b^{2}}{4} \cdot I-B^{2}, \\
B^{2} & =\left(\frac{b^{2}}{4}-1\right) \cdot I . \tag{4}
\end{align*}
$$

Let $|b|<2$. Then $B$ is invertible. Consider

$$
A=\{c \cdot x+d \cdot B x: c, d \in \mathbf{R}\}, \quad x \neq 0
$$

Note that $B^{\top}=-B$ implies $x \perp B x$. Then by (4) $K_{0} A=A$ and easy computation shows that the matrix $K_{0} / A=E$ under the basis $B x, x$ has the form

$$
E=\left(\begin{array}{cc}
\frac{b}{2} & \frac{b^{2}}{4}-1 \\
1 & \frac{b}{2}
\end{array}\right)
$$

$E$ has eigenvalues $\frac{1}{2}\left(b \pm \sqrt{b^{2}-4}\right)$. Hence $E$ is equivalent to a rotation. This implies that $C=A \cap S_{h}$ is an invariant circle of $F$ and $F / C$ is equivalent to a rotation.

Finally, let $b= \pm 2$. Then the polynomial $y^{2} \mp 2 y+1=(y \mp 1)^{2}$ is not irreducible. Thus we have again arrived at the first case.

Corollary. The dynamics of $F$ on an invariant curve predicted by Theorem is equivalent to a rotation.

Proof. The statement follows immediately from the above proof.

## References

[1] G. Cicogna, G. Gaeta: Periodic solutions from symmetry, Nonlinear Analysis T.M.A. 13 (1989), 475-488.
[2] G. Birkhoff, S. Mac Lane: A Survey of Modern Algebra, The Macmillan Company, New York, 1965.

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