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# THE HOPF BIFURCATION THEOREM FOR PARABOLIC EQUATIONS WITH INFINITE DELAY 

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Summary. The existence of the Hopf bifurcation for parabolic functional equations with delays of maximum order in spatial derivatives is proved. An application to an integrodifferential equation with a singular kernel is given.

Keywords: Hopf bifurcation, parabolic functional equation, infinite delay.

AMS Classification: 45 K 05, 35 B 10, 35 B 32.

## 1. INTRODUCTION

This paper is mainly concerned with periodic solutions of the functional differential equation in a Banach space $X$

$$
\dot{u}(t)=A u(t)+L u_{t}+f\left(\mu, u(t), u_{t}\right) .
$$

Here $u_{t}$ denotes the shift of $u$ given by $u_{t}(s)=u(t+s)$ for $s \in \mathbf{R}^{-}, A$ is a generator of an analytic semigroup $e^{A t}$ on $X, L$ is a continuous linear operator from an appropriate function space $Y$ into $X, f \in C^{2}\left([-1,1] \times \mathscr{D}\left(-A^{\alpha}\right) \times Y, X\right)$. The existence of periodic solutions is proved by using classical methods of the Hopf bifurcation. There exists a lot of literature dealing with the Hopf bifurcation problems for ordinary differential equations with finite or infinite delays (see e.g. Hale [5], Cushing [3], Simpson [7], Stech [10], Staffans [9]). Yoshida and Kishimoto [14], [15] have studied partial differential equations with finite time delays. There are only few papers dealing with the infinite dimensional problem with infinite delay. Tesei [11] has considered the special problem

$$
u_{t}=\Delta u+\lambda u-a u \int_{-\infty}^{t} \Theta^{2}(t-s) \mathrm{e}^{-o(t-s)} u(s) \mathrm{d} s
$$

and, after rewriting the equation to the system without delay, he applied the standard theorem [1]. Yamada and Niikura [13] have dealt with the system

$$
\begin{aligned}
& \dot{u}(x, t)=D(\alpha) \Delta u(x, t)+C(\alpha) u(x, t)+ \\
& +\int_{-\infty}^{t} K(t-\tau, \alpha) u(x, \tau) \mathrm{d} \tau+f\left(u_{t}, \alpha\right)(x),
\end{aligned}
$$

$u=\left(u^{\mathbf{1}}, \ldots, u^{N}\right), x \in \Omega \subset \mathbf{R}^{n}$ with Dirichlet or Neumann boundary conditions. Making use of the special type of the system they proceeded similarly as in [1]. Da Prato and Lunardi [4] were concerned with the equation

$$
\dot{u}(t)=f(\lambda, u(t))+\int_{-\infty}^{t} g(\lambda, t-s, u(s)) \mathrm{d} s
$$

where

$$
f:(-1,1) \times D \rightarrow X, g:(-1,1) \times(0, \infty) \times D \rightarrow X
$$

are $C^{\infty}$ functions, $D$ is continuously imbedded in $X$, but there is a mistake in a trans ${ }^{\text { }}$ formation of the equation there.

The present paper generalizes the results [4] [11] [13], needing less restrictions on the delay term $L u_{t}$ and on the smoothness of the data. The operator $L$ and the nonlinearity $f$ can act on the spaces of functions with values in $\mathscr{D}(A)$, and certain singular kernels are also admissible provided $L$ has the integral form $L u_{t}=$ $=\int_{-\infty}^{t} k(t-s) A^{\alpha} u(s) \mathrm{d} s$. In the proof we follow the idea of Crandall and Rabinowitz [1] with help of the Fourier series method which leads directly to the decomposition of the space of periodic functions before an application of the Implicit Function Theorem.

## 2. NOTATION AND ASSUMPTIONS

Let $X$ be a real Banach space and let $A$ be a generator of an analytic semigroup $T(t)$ in $X$.
We shall use the usual complexification of the space and the operators without changing the notation. We shall explain the precise meaning at places, where misunderstanding can occur. Using a shift if necessary, we can define all fractional powers $(-A)^{\alpha}$. We denote by $X^{\alpha}$ the domain of $(-A)^{\alpha}$ endowed with the graph norm $\|\cdot\|_{\alpha}$ $\left(X^{0}=X,\|\cdot\|_{0}=\|\cdot\|\right)$. The operators $(\lambda-A)^{-1}$ then satisfy the estimates (see e.g. [6])

$$
\begin{equation*}
\left\|(\lambda-A)^{-1} x\right\|_{\alpha} \leqq \frac{C(\alpha)}{|\lambda+a|^{1-\alpha}}\|x\|, \quad 0 \leqq \alpha \leqq 1 \tag{2.1}
\end{equation*}
$$

whenever $\lambda$ does not belong to the sector $\{\lambda \in \mathbf{C},|\arg (\lambda+a)| \geqq \omega\}$, which contains the spectrum of $A$. Throughout the paper we shall denote by $C$ any constant.

Let $\alpha \in[0,1]$ be fixed and let $Y^{\alpha}$ be the space of continuous functions defined on $\mathbf{R}^{-}=(-\infty, 0)$ with values in $X^{\alpha}$ and such that

$$
\|u\|_{\mathbf{r}^{\alpha}}=\sup _{t \in \mathbf{R}^{-}}\left\||t-1|^{-1} u(t)\right\|_{\alpha}<\infty
$$

Let
$L$ be a continuous linear operator from $Y^{\alpha}$ into $X$.

For $\lambda \in \mathbf{C}, \operatorname{Re} \lambda \geqq 0$ we denote by $B(\lambda)$ the operator defined by

$$
\mathscr{D}(B(\lambda))=X^{\alpha}, \quad B(\lambda) x=L\left(\tau \rightarrow \mathrm{e}^{\tau \lambda} x\right) .
$$

We shall assume that there are $\beta \geqq 0, \delta>0$ such that $\alpha-\beta<\delta<1$ and
(i) $\|B(\mathrm{i} k) x\| \leqq C k^{-\beta}\|x\|_{\alpha}$ for $x \in X^{\alpha}$,
(ii) for any $u \in C_{2 \pi}^{\delta+\beta-\alpha}\left(X^{\alpha}\right)$ the function $\varphi(t)=L u_{t}$ belongs to $C_{2 \pi}^{\delta}(X)$ $\left(C_{2 \pi}^{k+\delta}\left(X^{\alpha}\right)\right.$ denotes the space of $X^{\alpha}$-valued $2 \pi$-periodic functions with $\delta$-Hölder continuous derivatives of the order $k$ with the usual norm). (H1) and (H3) imply the existence of a constant $N \geqq 0$ such that the operator (ik-A-B(ik)) admits a continuous inverse $D(\mathrm{i} k)$ for $k \in \mathbf{Z},|k|>N$,

$$
\begin{equation*}
D(\mathrm{i} k)=(\mathrm{i} k-A-B(\mathrm{i} k))^{-1}=(\mathrm{i} k-A)^{-1} \sum_{n=0}^{\infty}\left[B(\mathrm{i} k)(\mathrm{i} k-A)^{-1}\right]^{n} \tag{2.2}
\end{equation*}
$$

There is $K>0$ such that

$$
\begin{align*}
& \|D(\mathrm{i} k)\|_{L\left(X, X^{1}\right)} \leqq K \quad \text { whenever } D(\mathrm{i} k) \text { exists in } L\left(X, X^{1}\right)  \tag{2.3}\\
& \text { and } \quad k \in \mathbf{Z}, \quad|k| \leqq N .
\end{align*}
$$

(2.3) together with (2.1), (2.2) yield that there is $C>0$ such that

$$
\begin{equation*}
\|D(\mathrm{i} k) x\|_{v} \leqq C /|k|^{1-v}\|x\|, \quad 0 \leqq v \leqq 1, \quad k \in \mathbf{Z}, \quad k \neq 0 \tag{2.4}
\end{equation*}
$$

whenever $D(\mathrm{i} k)$ exists. It will be shown later that the operator $L$, given by $L \psi=$ $=\int_{0}^{\infty} t^{-\gamma} \mathrm{e}^{-p t} A \psi(-t) \mathrm{d} t$, satisfies the assumption (H3) if $\gamma<\frac{1}{3}, p>0$.

Further hypotheses concern the spectrum of the operators $A+B(\mathrm{i} k)$.
(i) $(\mathrm{i} k-A-B(\mathrm{i} k))^{-1}$ exist in $L\left(X, X^{1}\right)$ for $k \in \mathbf{Z},|k| \neq 1$,
(ii) $i$ is an algebraically simple isolated eigenvalue of $A+B(i)$ with the eigenvector $x_{0}$.
It is easily seen that -i is a simple isolated eigenvalue of $A+B(-\mathrm{i})$ with the eigenvector $\bar{x}_{0}$. There exists a closed subspace of $X^{c}=X \oplus \mathrm{i} X$, denoted by $\tilde{X}$, such that $X^{c}=\tilde{X} \oplus C x_{0}$ and the operators (i-A-B(i)), $(\mathrm{i}+A+B(-\mathrm{i}))$ are invertible on $\tilde{X}$. The last assumption on the operator $L$ will be the following:

$$
\begin{equation*}
\text { If } L\left(\tau \rightarrow \tau \mathrm{e}^{\mathrm{i} \tau} x_{0}\right)=a x_{0}+x_{1} \quad \text { where } \quad x_{1} \in \tilde{X}, \text { then } \operatorname{Re} a \neq 1 \tag{H5}
\end{equation*}
$$

A function $f=f(\mu, x, p)$ will be supposed to satisfy the following conditions:
(H6) (i) $f \in C^{2}(\Omega, X)$, where $\Omega$ is a neighbourhood of zero in $\mathbf{R} \times X^{\alpha} \times Y^{\alpha}$,
(ii) $f(\mu, 0,0)=0, f_{x}(0,0,0)=0, f_{p}(0,0,0)=0$ if $(\mu, 0,0) \in \Omega$.

The assumptions (H4)(i), (H6) (ii) imply (see [2]) that there are continuously differentiable functions $x(\mu), \lambda(\mu)$ defined for small $\mu$ such that

$$
\begin{align*}
& \left(A+B(\mathrm{i})+f_{x}(\mu, 0,0)\right) x(\mu)+f_{p}(\mu, 0,0) p(\mu)=\lambda(\mu) x(\mu),  \tag{2.5}\\
& x(0)=x_{0}, \quad \lambda(0)=\mathrm{i}, \quad p(\mu)(t)=\mathrm{e}^{\mathrm{i} t} x(\mu) .
\end{align*}
$$

Following Hopf we shall assume

$$
\begin{equation*}
\operatorname{Re} \lambda^{\prime}(0) \neq 0 \tag{H7}
\end{equation*}
$$

Remark. The assumption (H3) is satisfied when $\alpha=0$ (equations in [11], [13]). For $\alpha<1$ only the smoothing property (H3) (ii) is needed $(\beta=0)$. On the other hand, (H3) (ii) is automatically satisfied when $\beta \geqq \alpha$. (H4) (ii) together with (H6) (ii) means that i is a characteristic eigenvalue for the linearized equation. (H5) and the transversality condition (H7) assure the invertibility of the operator $\mathscr{G}$ (see (3.5)), and consequently allow to apply the Implicit Function Theorem.

At the end of this section we collect some properties of Fourier coefficients of $2 \pi$ periodic Hölder continuous functions. A proof of the following lemma can be found e.g. in [12].

Lemma 1. Let $v_{k}=(1 / 2 \pi) \int_{0}^{2 \pi} \mathrm{e}^{-\mathrm{i} k s} v(s) \mathrm{d} s$ be the Fourier coefficients of the function $v$. Then for each $\delta \in(0,1)$ there exists $C(\delta)>0$ such that

$$
\begin{array}{ll}
|k|^{\delta}\left\|v_{k}\right\| \leqq C(\delta)\|v\|_{C^{\delta}(X)} & \text { if } \quad v \in C_{2 \pi}^{\delta}(X)  \tag{2.6}\\
|k|^{1+\delta}\left\|v_{k}\right\| \leqq C(\delta)\|v\|_{C^{1+\delta}(X)} & \text { if } \quad v \in C_{2 \pi}^{1+\delta}(X)
\end{array}
$$

$$
\begin{equation*}
\text { if } v(t)=\sum_{k=-\infty}^{\infty} v_{k} \mathrm{e}^{\mathrm{i} k t} \text { with }\left\|v_{k}\right\| \leqq C|k|^{-(1+\delta)} \text {, then } v \in C_{2 \pi}^{\delta}(X) \tag{2.7}
\end{equation*}
$$

## 3. THE BIFURCATION THEOREM

The assumptions stated above imply that the equation

$$
\begin{equation*}
\dot{u}(t)=A u(t)+L u_{t}+f\left(\mu, u(t), u_{t}\right) \tag{3.1}
\end{equation*}
$$

linearized about $u=0$ for $\mu=0$ has a nontrivial $2 \pi$-periodic solution $u(t)=\mathrm{e}^{\mathrm{it}} x_{0}$. We shall now seek nontrivial $2 \pi \varrho$-periodic solutions of (3.1) with $\varrho$ near 1 and $(\mu, u)$ near $(0,0)$. With the substitution $\tau=\varrho^{-1} t$ the equation (3.1) can be rewritten in the form

$$
\begin{align*}
& \dot{u}(t)=\varrho A u(t)+\varrho L\left(u_{\varrho}\right)_{t}+\varrho f\left(\mu, u(t),\left(u_{\varrho}\right)_{t}\right)  \tag{3.2}\\
& \text { with } \quad u_{\varrho}(s)=u\left(\frac{s}{\varrho}\right)
\end{align*}
$$

Now we shall look for $2 \pi$-periodic solutions of the equation

$$
\begin{equation*}
F(\varrho, \mu, u)=0 \tag{3.3}
\end{equation*}
$$

where $F(\varrho, \mu, u)(t)=\dot{u}(t)-\varrho A u(t)-\varrho L\left(u_{e}\right)_{t}-\varrho f\left(\mu, u(t),\left(u_{\varrho}\right)_{t}\right)$ is regarded as a mapping of $U \times Z$ into $C_{2 \pi}^{1+\delta}(X)$ where $U$ is a neighbourhood of $(1,0)$ in $\mathbf{R}^{2}$ and $Z=C_{2 \pi}^{2+\delta}(X) \cap C_{2 \pi}^{1+\delta}\left(X^{1}\right)$. Some properties of $F$ are given in

Lemma 2. Let the assumptions $(\mathrm{H} 1),(\mathrm{H} 2),(\mathrm{H} 6)$ be fulfilled. Then $F$ has continuous derivatives $F_{u u}, F_{\boldsymbol{Q u}}, F_{\mu u}$ and

$$
\begin{equation*}
F(\varrho, \mu, 0)=0 \text { for }(\varrho, \mu) \in U \tag{i}
\end{equation*}
$$

$$
\begin{align*}
& F_{u}(\varrho, \mu, 0) v(t)=\dot{v}(t)-\varrho A v(t)-\varrho L\left(v_{e}\right)_{t}-\varrho f_{x}(\mu, 0,0) v(t)-  \tag{ii}\\
& -\varrho f_{p}(\mu, 0,0)\left(v_{e}\right)_{t}
\end{align*}
$$

$$
\begin{equation*}
F_{\varrho u}(1,0,0) v(t)=-A v(t)-L v_{t}+L\left(\mathrm{id} \dot{v}_{t}\right) \tag{iii}
\end{equation*}
$$

(id denotes the identity map $\operatorname{id}(t)=t$ ),

$$
\begin{equation*}
F_{\mu u}(1,0,0) v(t)=-f_{\mu x}(0,0,0) v(t)-f_{\mu p}(0,0,0) v_{t} \tag{iv}
\end{equation*}
$$

Proof. The computation of the derivatives is routine, provided we realize that

$$
\frac{\partial}{\partial \varrho} u_{e}(t)=-\frac{' t}{\varrho^{2}} \dot{u}\left(\frac{t}{\varrho}\right)=-\frac{1}{\varrho}\left[(\mathrm{id} \dot{u})_{e}(t)\right]
$$

Next we examine the operator $F_{u}(1,0,0): Z \rightarrow C_{2 \pi}^{1+\delta}(X), F_{u}(1,0,0) v(t)=\dot{v}(t)-$ $-A v(t)-L v_{t}$. Denote $v_{0}(t)=\operatorname{Re}\left(\mathrm{e}^{\mathrm{it}} x_{0}\right), v_{1}(t)=\operatorname{Im}\left(\mathrm{e}^{\mathrm{it}} x_{0}\right)$ where $x_{0}$ is given by $A x_{0}+B(\mathrm{i}) x_{0}=\mathrm{i} x_{0}, V=\operatorname{lin}\left\{v_{0}, v_{1}\right\}$. Note that $\dot{v}_{0}(t)=-v_{1}(t)$.

Lemma 3. Let (H3), (H4) be satisfied, $\alpha \leqq 1, \alpha-\beta<\delta<1$. Then

$$
\begin{equation*}
\mathscr{N}\left(F_{u}(1,0,0)\right)=V \tag{i}
\end{equation*}
$$

$$
\begin{equation*}
\mathscr{R}\left(F_{u}(1,0,0)\right) \oplus V=C_{2 \pi}^{1+\delta}(X) \tag{ii}
\end{equation*}
$$

Proof. Let $v \in Z$. Then $v(t)=\sum_{k=-\infty}^{\infty} v_{k} \mathrm{e}^{\mathrm{i} k t}, v_{-k}=\bar{v}_{k}$.

$$
F_{u}(1,0,0) v(t)=\sum_{k=-\infty}^{\infty}(\mathrm{i} k-A-B(\mathrm{i} k)) v_{k} \mathrm{e}^{\mathrm{i} k t}
$$

The assumptions (H4)(i), (ii) imply that the complex null space $\mathscr{N}^{c}\left(F_{u}(1,0,0)\right)=$ $=\operatorname{lin}\left\{x_{0} \mathrm{e}^{\mathrm{it}}, \bar{x}_{0} \mathrm{e}^{-\mathrm{it} t}\right\}$ and hence the real null space $\mathscr{N}\left(F_{u}(1,0,0)\right)=V$. To prove (ii), let $y \in C_{2 \pi}^{1+\delta}(X), y(t)=\sum_{k=-\infty}^{\infty} y_{k} \mathrm{e}^{\mathrm{i} k t}$. We can decompose $y_{1}=\tilde{y}_{1}+a x_{0}$ where $\tilde{y}_{1} \in \tilde{X}$, $a \in \mathbf{C}$. Then $y(t)=\tilde{y}(t)+a x_{0} \mathrm{e}^{\mathrm{i} t}+\bar{a} \bar{x}_{0} \mathrm{e}^{-\mathrm{i} t}=\tilde{y}(t)+a_{1} v_{0}(t)-a_{2} v_{1}(t)$ with $a_{1}=$ $=2 \operatorname{Re} a, a_{2}=2 \operatorname{Im} a$. We prove that $\tilde{y} \in \mathscr{R}\left(F_{u}(1,0,0)\right)$. Set $v_{k}=D(\mathrm{i} k) y_{k}=$ $=(\mathrm{i} k-A-B(\mathrm{i} k))^{-1} y_{k}$ for $k \neq \pm 1, v_{1}=D(\mathrm{i}) \tilde{y}_{1}, v_{-1}=\bar{v}_{1}$. By virtue of (2.4) and (2.6) we get $\left\|v_{k}\right\|_{v} \leqq C|k|^{v-1}\left\|y_{k}\right\| \leqq C|k|^{-(2+\delta-v)}$. If we take $v=1$ and $v=0$, we obtain the estimates $\left\|v_{k}\right\|_{1} \leqq C|k|^{-(1+\delta)},\left\|i k v_{k}\right\| \leqq C|k|^{-(1+\delta)}$. Now (2.7) implies that $v=\sum_{k=-\infty}^{\infty} v_{k} \mathrm{e}^{\mathrm{i} k t} \in C_{2 \pi}^{\delta}\left(X^{1}\right) \cap C_{2 \pi}^{1+\delta}(X)$ and $\dot{v}(t)-A v(t)-L v_{t}=\tilde{y}(t)$. To prove
the regularity of $v$, set $u(t)=\dot{v}(t), z(t)=\sum_{k=-\infty}^{\infty} \mathrm{i} k B(\mathrm{i} k) v_{k} \mathrm{e}^{\mathrm{i} k t}$. Then (H3) (i) and (2.4) with $v=\alpha$ imply that $\| i k B(i k))^{\prime} v_{k} \| \leqq C|k|^{-(\beta+\delta+1-\alpha)}$ and, consequently, $z \in C_{2 \pi}^{\beta+\delta-\alpha}(X)$. Owing to the equality $B(\mathrm{i} k) D(\mathrm{i} k)=-I+(\mathrm{i} k-A) D(\mathrm{i} k)$, the function $u, u(t)=$ $=\sum_{k=-\infty}^{\infty} \mathrm{i} k v_{k} \mathrm{e}^{\mathrm{i} k t}$ satisfies the equation

$$
\begin{equation*}
u(t)=\mathrm{e}^{A t} u(0)+\int_{0}^{t} \mathrm{e}^{A(t-s)}(z(s)+\dot{y}(s)) \mathrm{d} s \tag{3.4}
\end{equation*}
$$

With help of regularity theorems which state that a solution of (3.4) belongs to the space $C^{1+\delta}((\varepsilon, T), X) \cap C^{\delta}\left((\varepsilon, T), X^{1}\right)$ whenever $z+\dot{y} \in C^{\delta}((0, T), X)$ (see e.g. [8]) we get $u \in C^{\delta+\beta-\alpha}\left([2 \pi, 4 \pi], X^{1}\right)$ and, owing to the periodicity, $u \in C_{2 \pi}^{\delta+\beta-\alpha}\left(X^{1}\right)$. It is easily seen that $z(t)=L u_{t}$, and (H3) (ii) yields $z \in C_{2 \pi}^{\delta}(X)$. Again, the periodicity and the regularity of solutions of (3.4) imply $u \in C_{2 \pi}^{1+\delta}(X) \cap C_{2 \pi}^{\delta}\left(X^{1}\right)$ and, consequently, $v \in Z, F_{u}(1,0,0) v=\tilde{y}$.

Now we define the map $G$ :

$$
G(s, \varrho, \mu, v)= \begin{cases}s^{-1} F\left(\varrho, \mu, s\left(v_{0}+v\right)\right) & \text { for } \quad s \neq 0 \\ F_{u}(\varrho, \mu, 0)\left(v_{0}+v\right) & \text { for } \quad s=0\end{cases}
$$

By Lemma 2, $G$ is a mapping of class $C^{1}$ from a neighbourhood of $(0,1,0,0)$ in $\mathbf{R}^{3} \times Z_{1}$, where $Z_{1}=\mathscr{R}\left(F_{u}(1,0,0)\right)$, to $C_{2 \pi}^{1+\delta}(X)$. Obviously $G(0,1,0,0)=0$ and the Frèchet derivative of the map $(\varrho, \mu, v) \rightarrow G(s, \varrho, \mu, v)$ at $(0,1,0,0)$ is the linear map

$$
\begin{align*}
& \mathscr{G}(\hat{\varrho}, \hat{\mu}, \hat{v})(t)=\hat{v}^{\prime}(t)-A \hat{v}(t)-L \hat{v}_{t}-\hat{\varrho}\left(A v_{0}(t)+\right.  \tag{3.5}\\
& \left.+L v_{0 t}-L\left(\operatorname{id} \dot{v}_{0 t}\right)\right)-\hat{\mu}\left(f_{\mu x}(0,0,0) v_{0}(t)+f_{\mu p}(0,0,0) v_{0 t}\right)
\end{align*}
$$

We claim that $\mathscr{G}$ is an isomorphism. Once this is shown, the fact that $G(0,1,0,0)=$ $=0$ and the Implicit Function Theorem imply that the solutions ( $s, \varrho, \mu, v$ ) of $G=0$ near $(0,1,0,0)$ are given by continuously differentiable functions $\varrho(s), \mu(s)$, $v(s)$. Then setting $u(s)(t)=s\left(\left(v_{0}+v(s)\right)(t)\right)$ we see that $(\varrho(s), \mu(s), u(s))$ is the desired curve of solutions of $F=0$.

We shall discuss each part of $\mathscr{G}$ separately.

$$
\begin{aligned}
& \dot{\hat{v}}(t)-A \hat{v}(t)-L \hat{v}_{t}=F_{u}(1,0,0) \hat{v}(t) \\
& \hat{\varrho}\left(A v_{0}(t)+L v_{0 t}-L\left(\mathrm{id} \dot{v}_{0 t}\right)\right)=\hat{\varrho}\left(\dot{v}_{0}(t)-L\left(\mathrm{id} \dot{v}_{0 t}\right)\right)= \\
& =\hat{\varrho}\left(-v_{1}(t)+L\left(\operatorname{id} v_{1 t}\right)\right)=\hat{\varrho}\left(-v_{1}(t)+\operatorname{Im}\left(\mathrm{e}^{\mathrm{i} t} L\left(\tau \rightarrow \tau \mathrm{e}^{\mathrm{i} \tau} x_{0}\right)\right)\right)= \\
& =\hat{\varrho}\left(-v_{1}(t)+\operatorname{Im}\left(\mathrm{e}^{\mathrm{i} t}\left(a x_{0}+x_{1}\right)\right)=\hat{\varrho}\left(-v_{1}(t)+a_{1} v_{1}(t)+a_{2} v_{0}(t)+\right.\right. \\
& \left.+\operatorname{Im} \mathrm{e}^{\mathrm{i} t} x_{1}\right)=\hat{\varrho}\left(\left(a_{1}-1\right) v_{1}(t)+a_{2} v_{0}(t)+F_{u}(1,0,0) \varphi(t)\right)
\end{aligned}
$$

where

$$
\varphi(t)=F_{u}(1,0,0)^{-1}\left(\operatorname{Im} \mathrm{e}^{\mathrm{it}} x_{1}\right)
$$

We have used here the notation from (H5) with $a_{1}=\operatorname{Re} a, a_{2}=\operatorname{Im} a$.

By differentiating (2.5) at $\mu=0$, multiplying by $e^{i t}$ and computing the real part we obtain

$$
\begin{aligned}
& \hat{\mu}\left(f_{\mu x}(0,0,0) v_{0}(t)+f_{\mu p}(0,0,0) v_{0 t}\right)= \\
& =-\hat{\mu}\left(\operatorname{Re} \mathrm{e}^{\mathrm{i} t}(A+B(\mathrm{i})-\mathrm{i}) x^{\prime}(0)-\operatorname{Re} \lambda^{\prime}(0) v_{0}(t)\right)= \\
& =\hat{\mu} F_{u}(1,0,0) \psi(t)+\hat{\mu} \operatorname{Re} \lambda^{\prime}(0) v_{0}(t)
\end{aligned}
$$

where $\psi(t)=-\operatorname{Re}\left(\mathrm{e}^{\mathrm{it}} x^{\prime}(0)\right)$. Now we can write the operator $\mathscr{G}$ as follows:

$$
\begin{aligned}
& \mathscr{G}(\hat{\varrho}, \hat{\mu}, \hat{v})(t)=F_{u}(1,0,0)(\hat{v}-\hat{\varrho} \varphi-\hat{\mu} \psi)(t)+ \\
& +v_{1}(t)\left(1-a_{1}\right) \hat{\varrho}+v_{0}(t)\left(-\hat{\mu} \operatorname{Re} \lambda^{\prime}(0)-\hat{\varrho} a_{2}\right) .
\end{aligned}
$$

From this expression, Lemma 3, (H5) and (H7) it is easily seen that $\mathscr{G}$ is a one to one mapping from $\mathbf{R}^{2} \times \mathscr{R}\left(F_{u}(1,0,0)\right)$ onto $C_{2 \pi}^{1+\delta}(X)$.

The local uniqueness given by the Implicit Function Theorem together with the fact that $u_{\theta}: u_{\theta}(t)=u(t+\theta)$ is a solution of (3.1) iff $u$ is a solution ensures the uniqueness assertion in the following theorem:

Theorem. Let the assumptions $(\mathrm{H} 1)-(\mathrm{H} 7)$ be fulfilled. Then there are $\varepsilon>0$, $\eta>0,0<\delta<1$ nad continuously differentiable functions $(\varrho, \mu, u):(-\eta, \eta) \rightarrow$ $\rightarrow \mathbf{R} \times \mathbf{R} \times\left(C_{2 \pi}^{2+\delta}(X) \cap C_{2 \pi}^{1+\delta}\left(X^{1}\right)\right)$ with the following properties:
(a) $F(\varrho(s), \mu(s), u(s))=0$ for $|s|<\eta$,
(b) $\mu(0)=0, u(0)=0, \varrho(0)=1$ and $u(s) \neq 0$ if $0<|s|<\eta$.
(c) If $\left(\mu_{1}, u_{1}\right) \in \mathbf{R} \times Z$ is a solution of (3.1) of period $2 \pi \varrho_{1}$, where $\left|\varrho_{1}-1\right|<\varepsilon$, $\left|\mu_{1}\right|<\varepsilon$ and $\left|u_{1}\right|_{z}<\varepsilon$, then there exist numbers $s \in\langle 0, \eta)$ and $\theta \in\langle 0,2 \pi)$ such that $u_{1}\left(\varrho_{1} \tau\right)=u(s)(\tau+\theta)$ for $\tau \in \mathbf{R}$.

## 4. AN EXAMPLE

We shall give here examples of memory operators $L$ with singular kernels satisfying the conditions $(\mathrm{H} 2),(\mathrm{H} 3)$, and an application of the previous results to the problem

$$
\begin{align*}
& u_{t}=a u_{x x}+b u+c \int_{-\infty}^{t} k(t-s) u_{x x}(s) \mathrm{d} s+  \tag{4.1}\\
& +\int_{-\infty}^{t} k_{1}(t-s)\left(g\left(\mu, u(s)_{x}\right)_{x}\right) \mathrm{d} s \\
& u(t, 0)=u(t, \pi)=0, \quad x \in\langle 0, \pi\rangle, \quad t \in \mathbf{R}
\end{align*}
$$

Lemma 4. Let $k(t)=t^{-\gamma} e^{-p t}$ with $\gamma<(2-\alpha) / 3, p>0$. Then the operator $L: Y^{\alpha} \rightarrow X, L \varphi=\int_{0}^{\infty} k(s) A^{\alpha} \varphi(-s) \mathrm{d} s$ satisfies (H2), (H3).

Proof. The continuity of $L$ is obvious.

$$
\|B(\mathrm{i} k) x\|=\left\|\int_{0}^{\infty} s^{-\gamma} \mathrm{e}^{-(p+\mathrm{i} k) s} A^{\alpha} x \mathrm{~d} s\right\|=\left|\frac{\Gamma(1-\gamma)}{(p+\mathrm{i} k)^{1-\gamma}}\right|\|x\|_{\alpha} \leqq \frac{C}{|k|^{1-\gamma}}\|x\|_{\alpha}
$$

so the condition (H3) (i) holds with $\beta=1-\gamma$. To prove (H3) (ii), let $u \in C_{2 \pi}^{\delta+\beta-\alpha}\left(X^{\alpha}\right)$, and write $L u_{t}-L u_{s}$ as follows:

$$
\begin{aligned}
& L u_{t}-L u_{s}=\int_{-\infty}^{t}(t-\tau)^{-\gamma} \mathrm{e}^{-p(t-\tau)} A^{\alpha} u(\tau) \mathrm{d} \tau- \\
& -\int_{-\infty}^{s}(s-\tau)^{-\gamma} \mathrm{e}^{-p(s-\tau)} A^{\alpha} u(\tau) \mathrm{d} \tau= \\
& =\int_{-\infty}^{s}\left[(t-\tau)^{-\gamma} \mathrm{e}^{-p(-\tau)}-(s-\tau)^{-\gamma} \mathrm{e}^{-p(s-\tau)}\right] A^{\alpha}(u(\tau)-u(s)) \mathrm{d} s+ \\
& +A^{\alpha} u(s) \int_{-\infty}^{s}\left[(t-\tau)^{-\gamma} \mathrm{e}^{-p(t-\tau)}-(s-\tau)^{-\gamma} \mathrm{e}^{-p(s-\tau)}\right] \mathrm{d} \tau+ \\
& +\int_{s}^{t}(t-\tau)^{-\gamma} \mathrm{e}^{-p(t-\tau)} A^{\alpha} u(\tau) \mathrm{d} \tau .
\end{aligned}
$$

If we choose $\delta \in(2 \gamma+\alpha-1,1-\gamma)$, we can estimate the first integral with help
 equal to

$$
\int_{t-s}^{\infty} \mathrm{e}^{-p \sigma} \sigma^{-\gamma} \mathrm{d} \sigma-\int_{0}^{\infty} \mathrm{e}^{-p \sigma} \sigma^{-\gamma} \mathrm{d} \sigma=-\int_{0}^{t-s} \mathrm{e}^{-p \sigma} \sigma^{-\gamma} \mathrm{d} \sigma,
$$

so that the second term as well as the third are estimated by $C(t-s)^{1-\gamma}\|u\|_{C_{2 \pi}\left(X^{\alpha}\right)}$, which implies that $L u_{t} \in C_{2 \pi}^{\delta}(X)$.

Now, we turn our attention to the equation (4.1). We take $X=L^{2}(0, \pi), \mathscr{D}(A)=$ $=W^{2,2}(0, \pi) \cap W^{2,1}(0, \pi), \alpha=1,0<\gamma<\frac{1}{3}$.

$$
A x=a x^{\prime \prime}+b x, \quad L \varphi=c \int_{0}^{\infty} s^{-\gamma} \mathrm{e}^{-p s} \mathrm{D}_{2}^{2} \varphi(-s, \cdot) \mathrm{d} s
$$

Then (H1)-(H3) are satisfied and

$$
A x+B(\mathrm{i} k) x=\left(a+\frac{c \Gamma(1-\gamma)}{(p+\mathrm{i} k)^{1-\gamma}}\right) x^{\prime \prime}+b x
$$

The eigenvalues of $A$ are the numbers $b-a n^{2}, n=1,2, \ldots$, and it is easily seen that there are no eigenvalues of $A+B(\mathrm{i} k)$ with nonnegative real parts when $b \leqq 0$. In that case the zero solution is asymptotically stable. On the other hand, we can choose constants $a, b, c$ such that (H4), (H5) are fulfilled. $g$ is supposed to be smooth
with $g_{u}(0,0)=0, k_{1} \in L^{1}$. If $\operatorname{Re} g_{\mu u}(0,0) \hat{k}_{1}(i) \neq 0$, then the transversality condition (H7) holds, so all assumptions of Theorem 1 are fulfilled and consequently there exists a nontrivial branch of periodic solutions of (4.1).
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## Souhrn

## HOPFOVA BIFURKACE PRO PARABOLICKÉ ROVNICE S NEKONEČNÝM ZPOŽDĚNIM

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V práci je dokázána existence Hopfovy bifurkace pro funkcionální diferenciálni rovnice parabolického typu $u(t)=A u(t)+L u_{t}+f\left(\mu, u(t), u_{t}\right)$, kde $u_{t}(s)=u(t+s), s \in \mathbf{R}^{-}$, priXemž operátory $L$ a $f$ jsou definovány na prostorech funkcí s hodnotami $v \mathscr{D}(A)$. Výsledek je aplikován na integrodiferenciální rovnici se singulárním jádrem.

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