## Czechoslovak Mathematical Journal

## Ladislav Nebeský

Geodesics and steps in a connected graph

Czechoslovak Mathematical Journal, Vol. 47 (1997), No. 1, 149-161

Persistent URL:
http://dml.cz/dmlcz/127346

## Terms of use:

© Institute of Mathematics AS CR, 1997

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these Terms of use.


This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project DML-CZ: The Czech Digital Mathematics Library http://dml.cz

# GEODESICS AND STEPS IN A CONNECTED GRAPH 

Ladislav Nebeský, Praha

(Received January 4, 1995)

Let $G$ be a connected (finite undirected) graph. By a step in $G$ will mean an ordered triple $(u, v, x)$ of vertices in $G$ with the property that $d(u, v)=1$ and $d(u, x)=d(v, x)+1$, where $d$ denotes the distance function of $G$. The concept of a step is closely related to that of a geodesic (or a shortest path). An axiomatic characterization of the set of all geodesics in a connected graph was given by the present author in [5]. A characterization of the set of all steps in a connected graph will be given here.

The letters $g, h, i, j, k, m$ and $n$ will be reserved for denoting integers.
Let $V$ be a finite nonempty set. We denote by $\Sigma(V)$ the set of all sequences

$$
\begin{equation*}
\left(v_{0}, \ldots, v_{n}\right), \tag{1}
\end{equation*}
$$

where $n \geqslant 0$ and $v_{0}, \ldots, v_{n} \in V$.
By a graph we mean here a finite undirected graph with no loops or multiple edges, i.e. a graph in the sense of [1] or [2], for example. If $G$ is a graph, then $V(G)$ and $E(G)$ denote its vertex set and its edge set, respectively. Let $v_{0}, \ldots, v_{n} \in V(G)$, where $n \geqslant 0$; we say that (1) is a walk in $G$ if $\left\{v_{i}, v_{i+1}\right\} \in E(G)$ for each $i, 0 \leqslant i<n$. Obviously, every walk in $G$ is an element of $\Sigma(V(G))$. By a path in $G$ we mean such a walk (1) in $G$ that the vertices $v_{0}, \ldots, v_{n}$ are mutually distinct.

Let $G$ be a connected graph, and let $d$ denote the distance function of $G$. (Note that in [3] a characterization of the distance function of a connected graph was given.) Obviously, if (1) is a walk in $G$, then $d\left(v_{0}, v_{n}\right) \leqslant n$. By a geodesic (or a shortest path) in $G$ we mean such a walk (1) that $d\left(v_{0}, v_{n}\right)=n$. It is not difficult to see that every geodesic in $G$ is a path. We now introduce the concept of a step in $G$. By a step in $G$ we will mean an ordered triple $(u, v, x)$, where $u, v, x \in V(G)$ and

$$
\begin{equation*}
d(u, v)=1 \text { and } d(u, x)=d(v, x)+1 . \tag{2}
\end{equation*}
$$

Obviously, $(u, v, x)$ is a step in $G$ if and only if there exists a geodesic (1) in $G$ with the properties that $n \geqslant 1, u=v_{0}, v=v_{1}$ and $x=v_{n}$. In the present paper a characterization of the set of all steps in a connected graph will be given.

Let $V$ be a finite nonempty set, and let $T \subseteq V^{3}$. If $u, v, x \in V$, then instead of

$$
(u, v, x) \in T \text { or }(u, v, x) \notin T
$$

we will write

$$
u v \rightarrow_{T} x \text { or } u v \text { non } \rightarrow_{T} x, \text { respectively. }
$$

We denote by $\Gamma(V, T)$ the graph $H$ with $V(H)=V$ and

$$
\begin{aligned}
E(H)=\{ & \{u, v\} ; u, v \in V, u \neq v \text { and there exists } x \in V \\
& \text { such that } \left.u v \rightarrow_{T} x \text { or } v u \rightarrow_{T} x\right\} .
\end{aligned}
$$

Proposition 1. Let $V$ be a finite nonempty set, and let $T \subseteq V^{3}$. Assume that there exists a connected graph $G$ with the properties that $V(G)=V$ and $T$ is the set of all steps in $G$. Then $G=\Gamma(V, T)$.

Proof. Let $d$ denote the distance function of $G$. Since $V(G)=V(\Gamma(V, T))$, we see that $G=\Gamma(V, T)$ if and only if $E(G)=E(\Gamma(V, T))$.

Consider arbitrary $u, v \in V$.
Let $\{u, v\} \in E(G)$. Then $d(u, v)=1$. Since $d(v, v)=0$, we see that $(u, v, v)$ is a step in $G$. This means that $u v \rightarrow_{T} v$. Since $u \neq v$, we have $\{u, v\} \in E(\Gamma(V, T))$.

Conversely, let $\{u, v\} \in E(\Gamma(V, T))$. Then $u \neq v$ and there exists $x \in V$ such that $u v \rightarrow_{T} x$ or $v u \rightarrow_{T} x$. The fact that $(u, v, x)$ or $(v, u, x)$ is a step in $G$ implies that $d(u, v)=1$. Hence $\{u, v\} \in E(G)$.

We have $G=\Gamma(V, T)$, which completes the proof.
Proposition 1 is an introduction to the next theorem, which is the main result of the present paper.

Theorem 1. Let $V$ be a finite nonempty set, and let $T \subseteq V^{3}$. Assume that $\Gamma(V, T)$ is connected. Then the following statements (I) and (II) are equivalent:
(I) $T$ is the set of all steps in $\Gamma(V, T)$;
(II) $T$ fulfils Axioms A-H (for arbitrary $u, v, x, y \in V$ ):

A if $u v \rightarrow_{T} x$, then $v u \rightarrow_{T} u$;
B if $u v \rightarrow_{T} x$ and $v u \rightarrow_{T} y$, then $x \neq y$;
C if $u v \rightarrow_{T} x$ and $x y \rightarrow_{T} v$, then $x y \rightarrow_{T} u$;
D if $u v \rightarrow_{T} x$ and $x y \rightarrow_{T} v$, then $u v \rightarrow_{T} y$;
$\mathrm{E} \quad$ if $u v \rightarrow_{T} x$ and $u y \rightarrow_{T} v$, then $y=v$;
$\mathrm{F} \quad$ if $u v \rightarrow_{T} x, v u \rightarrow_{T} y$ and $x y \rightarrow_{T} y$, then $x y \rightarrow_{T} u$;
G if $u v \rightarrow_{T} x$ and $x y \rightarrow_{T} y$, then either $x y \rightarrow_{T} u$ or $y x \rightarrow_{T} v$ or $u v \rightarrow_{T} y$;
$\mathrm{H} \quad$ if $u \neq x$, then there exists $z \in V$ such that $u z \rightarrow_{T} x$.
Combining Theorem 1 with Proposition 1, we get the following result:

Corollary 1. Let $V$ be a finite nonempty set, and let $T \subseteq V^{3}$. Then there exists a connected graph $G$ with the properties that $V(G)=V$ and $T$ is the set of all steps in $G$ if and only if $\Gamma(V, T)$ is connected and $T$ fulfils Axioms A-H (for arbitrary $u, v, x, y \in V)$.

For the proof of Theorem 1 we will need three remarks and three lemmas.
In Remarks 1-3 and Lemmas 1-3 we will assume that $V$ is a finite nonempty set, $T \subseteq V^{3}$ and $T$ fulfils Axioms A, B, C, D and H .

Remark 1. Let $u, v, x \in V$ be such that $u v \rightarrow_{T} x$. Axiom B implies that $u \neq v$, and therefore, $\{u, v\} \in E(\Gamma(V, T))$.

Let $u_{0}, u_{1}, \ldots, u_{n}, w_{1}, \ldots, w_{n} \in V$, where $n \geqslant 1$, and let

$$
u_{0} u_{1} \rightarrow_{T} w_{1}, \ldots, u_{n-1} u_{n} \rightarrow_{T} w_{n}
$$

It is clear that $\left(u_{0}, u_{1}, \ldots, u_{n}\right)$ is a walk in $\Gamma(V, T)$.
Remark 2. Let $u, v, x \in V$ be such that $u v \rightarrow_{T} x$. Combining Axioms A and B we get $u \neq x$.

Lemma 1. Let $u_{0}, u_{1}, v_{1}, \ldots, v_{i+1} \in V$, where $i \geqslant 1$, let

$$
v_{1} v_{2} \rightarrow_{T} u_{0}, \ldots, v_{i} v_{i+1} \rightarrow_{T} u_{0}
$$

and let $u_{1} u_{0} \rightarrow_{T} v_{1}$. Then

$$
v_{g} v_{g+1} \rightarrow_{T} u_{1} \text { and } u_{1} u_{0} \rightarrow_{T} v_{g+1}
$$

for each $g, 1 \leqslant g \leqslant i$.
Proof. We proceed by induction on $g$. First, let $g=1$. Since $v_{1} v_{2} \rightarrow_{T} u_{0}$ and $u_{1} u_{0} \rightarrow_{T} v_{1}$, Axioms C and D imply that $v_{1} v_{2} \rightarrow_{T} u_{1}$ and $u_{1} u_{0} \rightarrow_{T} v_{2}$. If $i=1$, then the proof is complete. Assume that $2 \leqslant g \leqslant i$. According to the induction hypothesis, $u_{1} u_{0} \rightarrow_{T} v_{g}$. Since $v_{g} v_{g+1} \rightarrow_{T} u_{0}$, Axioms C and D imply that $v_{g} v_{g+1} \rightarrow_{T} u_{1}$ and $u_{1} u_{0} \rightarrow_{T} v_{g+1}$, which completes the proof.

Lemma 2. Let $x_{0}, \ldots, x_{j}, y_{1}, \ldots, y_{j+1} \in V$, where $j \geqslant 1$, let

$$
y_{1} y_{2} \rightarrow_{T} x_{0}, \ldots, y_{j} y_{j+1} \rightarrow_{T} x_{0}
$$

and

$$
x_{1} x_{0} \rightarrow_{T} y_{1}, \ldots, x_{j} x_{j-1} \rightarrow_{T} y_{j}
$$

Then

$$
y_{h} y_{h+1} \rightarrow_{T} x_{h}, \ldots, y_{j} y_{j+1} \rightarrow_{T} x_{h}
$$

and

$$
x_{h} x_{h-1} \rightarrow_{T} y_{h}, \ldots, x_{h} x_{h-1} \rightarrow_{T} y_{j+1}
$$

for each $h, 1 \leqslant h \leqslant j$.
Proof. We proceed by induction on $h$. Since $x_{1} x_{0} \rightarrow_{T} y_{1}$, the case when $h=1$ is covered by Lemma 1. If $j=1$, then the proof is complete. Assume that $2 \leqslant h \leqslant j$. The induction hypothesis implies that

$$
y_{h} y_{h+1} \rightarrow_{T} x_{h-1}, \ldots, y_{j} y_{j+1} \rightarrow_{T} x_{h-1}
$$

Recall that $x_{h} x_{h-1} \rightarrow_{T} y_{h}$. Applying Lemma 1, we get the result.

Lemma 3. Let $\Gamma(V, T)$ be connected, let $x_{0}, \ldots, x_{n}, y_{1} \in V$, where $n \geqslant 2$, let $\left(x_{0}, \ldots, x_{n}\right)$ be a geodesic in $\Gamma(V, T)$, and let $x_{n} y_{1} \rightarrow_{T} x_{0}$. Let $d$ denote the distance function of $\Gamma(V, T)$. Then there exist $k \geqslant 0$ and $x_{n+1}, \ldots, x_{n+k+1} \in V$ such that $x_{n+1}=y_{1}$,

$$
\begin{align*}
& x_{n+g} x_{n+g+1} \rightarrow_{T} x_{0} \text { for each } g, 0 \leqslant g \leqslant k,  \tag{3}\\
& x_{h} x_{h-1} \rightarrow_{T} x_{n+h} \text { for each } h, 1 \leqslant h \leqslant k \tag{4}
\end{align*}
$$

and

$$
\begin{align*}
& \text { either (a) } x_{n} x_{n-1} \rightarrow_{T} x_{0} \text { and } d\left(y_{1}, x_{0}\right)=n-1,  \tag{5}\\
& \text { or (b) } x_{k+1} x_{k} \text { non } \rightarrow_{T} x_{n+k+1} .
\end{align*}
$$

Proof. We distinguish two cases.
Case 1. Assume that there exists an infinite sequence

$$
\left(x_{n+1}, x_{n+2}, x_{n+3}, \ldots\right)
$$

of vertices in $\Gamma(V, T)$ such that $x_{n+1}=y_{1}$ and

$$
x_{n+i} x_{n+i+1} \rightarrow_{T} x_{0} \text { for each } i=0,1,2, \ldots
$$

Let

$$
x_{g} x_{g-1} \rightarrow_{T} x_{n+g} \text { for each } g=1,2,3, \ldots
$$

Lemma 2 implies that

$$
x_{h} x_{h-1} \rightarrow_{T} x_{n+h}, x_{h} x_{h-1} \rightarrow_{T} x_{n+h+1}, x_{h} x_{h-1} \rightarrow_{T} x_{n+h+2}, \ldots
$$

$$
\text { for each } h=1,2,3, \ldots
$$

As follows from Remark 2,

$$
x_{h} \neq x_{n+h}, x_{n+h+1}, x_{n+h+2}, \ldots \quad \text { for each } h=1,2,3, \ldots
$$

This implies that

$$
x_{1}, x_{n+1}, x_{2 n=1}, \ldots
$$

are mutually distinct, which is a contradiction to the fact that $V$ is finite. Therefore, there exists $k \geqslant 0$ such that $x_{k+1} x_{k}$ non $\rightarrow_{T} x_{n+k+1}$. We see that (3), (4) and (5) hold.

Case 2. Let the assumption of Case 1 be not fulfilled. Since $\left(x_{0}, \ldots, x_{n}\right)$ is a geodesic in $\Gamma(V, T)$ and $n \geqslant 2$, we have $y_{1} \neq x_{0}$. It follows from Axiom H that there exist $x_{n+1}, \ldots, x_{n+j+1} \in V$, where $j \geqslant 1$, such that $x_{n+1}=y_{1}, x_{n+j+1}=x_{0}$ and

$$
x_{n} x_{n+1} \rightarrow_{T} x_{0}, \ldots, x_{n+j} x_{n+j+1} \rightarrow_{T} x_{0}
$$

As follows from Remark 1,

$$
\left(x_{n+1}, \ldots, x_{n+j+1}\right)
$$

is a walk in $\Gamma(V, T)$. Thus $d\left(x_{n+1}, x_{0}\right) \leqslant j$. Since $d\left(x_{n}, x_{0}\right)=n$, we have $d\left(x_{n+1}, x_{0}\right) \geqslant n-1$.

First, let

$$
x_{i+1} x_{i} \rightarrow_{T} x_{n+i+1} \text { for each } i, 0 \leqslant i \leqslant j .
$$

Then $x_{j+1} x_{j} \rightarrow_{T} x_{0}$. If $j \geqslant n$, we also have $x_{j} x_{j+1} \rightarrow_{T} x_{0}$, which is a contradiction to Axiom B. Hence $d\left(x_{n+1}, x_{0}\right)=n-1$ and $x_{n} x_{n-1} \rightarrow_{T} x_{0}$. Put $k=j$. Then (3), (4) and (5) hold.

Next, let there exist $k, 0 \leqslant k \leqslant j$, such that

$$
x_{k+1} x_{k} \text { non } \rightarrow_{T} x_{n+k+1}
$$

and (4) holds. We see that (3) and (5) hold, too.
Thus the lemma is proved.

Remark 3. Let $\Gamma(V, T)$ be connected, let $x_{0}, \ldots, r_{n}, y_{1} \in V$, where $n \geqslant 2$, let $\left(x_{0}, \ldots, x_{n}\right)$ be a geodesic in $\Gamma(V, T)$, and let $x_{n} y_{1} \rightarrow \rightarrow_{0}$. Let $d$ denote the distance function of $\Gamma(V, T)$. Lemma 3 implies that there exist $k \geqslant 0$ and $x_{n+1}, \ldots, x_{n+k+1} \in$ $V$ such that $x_{n+1}=y_{1}$ and (3)-(5) hold.

It follows from Remark 1 that

$$
\left(x_{0}, x_{1}, \ldots, x_{n}, \ldots, x_{n+k+1}\right)
$$

is a walk in $\Gamma(V, T)$. Axiom A implies that

$$
\begin{equation*}
x_{g} x_{g+1} \rightarrow_{T} x_{g+1} \text { for each } g, 0 \leqslant g \leqslant n+k \tag{6}
\end{equation*}
$$

Combining (3) and (4) with Lemma 2, we see that if $k \geqslant 1$, then

$$
x_{n+h} x_{n+h+1} \rightarrow_{T} x_{h}, \ldots, x_{n+k} x_{n+k+1} \rightarrow_{T} x_{h}
$$

and

$$
x_{h} x_{h-1} \rightarrow_{T} x_{n+h}, \ldots, x_{h} x_{h-1} \rightarrow_{T} x_{n+k+1}
$$

for each $h, 1 \leqslant h \leqslant k$.
Since $x_{n} x_{n+1} \rightarrow_{T} x_{0}$, we have

$$
\begin{equation*}
x_{n+i} x_{n+i+1} \rightarrow_{T} x_{i} \text { for each } i, 0 \leqslant i \leqslant k . \tag{7}
\end{equation*}
$$

Proof of Theorem 1. Denote $G=\Gamma(V, T)$. Recall that $G$ is connected. We denote by $d, D$ and $S$ the distance function of $G$, the diameter of $G$ and the set of all steps in $G$, respectively. Obviously, $S \subseteq V^{3}$.

PART ONE ( $\mathrm{I} \Rightarrow \mathrm{II}$ ). Let $T=S$. Consider arbitrary $u, v, x, y \in V$. It is easy to see that $T$ fulfils Axioms A, B, E and H. We will prove that $T$ fulfils Axioms C. D. F and G.
(Verification of Axioms C and D). Let $u v \rightarrow_{T} x$ and $x y \rightarrow_{T} v$. Then

$$
d(u, v)=1=d(x, y), d(u, x)=d(v, x)+1 \text { and } d(x, v)=d(y, v)+1
$$

We get

$$
d(u, y) \leqslant d(v, y)+1=d(x, v)=d(u, x)-1 \leqslant d(u, y)
$$

Therefore, $d(u, y)=d(v, y)+1=d(u, x)-1$. We see that $x y \rightarrow_{T} u$ and $u v \rightarrow_{T} y$.
(Verification of Axiom F.) Let $u v \rightarrow_{T} x, v u \rightarrow_{T} y$ and $x y \rightarrow_{T} y$. Then

$$
d(u, x)=d(v, x)+1, d(v, y)=d(u, y)+1 \text { and } d(x, y)=1
$$

We get

$$
d(y, u)+1 \geqslant d(x, u)=d(v, x)+1 \geqslant d(v, y)=d(u, y)+1
$$

We see that $x y \rightarrow_{T} u$.
(Verification of Axiom G.) Let $u v \rightarrow_{T} x$ and $x y \rightarrow_{T} y$. Assume that $u v$ non $\rightarrow_{T} y$ and $y x$ non $\rightarrow_{T} v$. Then

$$
d(u, x)=d(v, x)+1, d(x, y)=1, d(v, y) \geqslant d(u, y) \text { and } d(x, v) \geqslant d(y, v)
$$

We get

$$
d(y, u)+1 \geqslant d(x, u)=d(v, x)+1 \geqslant d(y, v)+1 \geqslant d(u, y)+1
$$

We see that $x y \rightarrow_{T} u$.
Thus $T$ fulfils Axioms A-H.
PART TWO ( $\mathrm{II} \Rightarrow \mathrm{I}$ ). Let $T$ fulfil Axioms A -H . We will prove that

$$
\begin{align*}
& \text { if } r s \rightarrow_{S} t \text {, then } r s \rightarrow_{T} t \text { for every } r, s, t \in V  \tag{n}\\
& \text { such that } d(r, t) \leqslant n
\end{align*}
$$

and

$$
\begin{equation*}
\text { if } r s \rightarrow_{T} t \text {, then } r s \rightarrow_{S} t \text { for every } r, s, t \in V \tag{n}
\end{equation*}
$$ such that $d(r, t) \leqslant n$

for each $n, 0 \leqslant n \leqslant D$.
We proceed by induction on $n$. It is obvious that both $\left(8_{0}\right)$ and $\left(9_{0}\right)$ hold. If $D=0$, then the theorem is proved. Assume that $D \geqslant 1$.

Consider arbitrary $r_{1}, r_{2}, r_{3} \in V$ such that $r_{1} r_{2} \rightarrow_{S} r_{3}$ and $d\left(r_{1}, r_{3}\right)=1$. Then $\left\{r_{1}, r_{2}\right\} \in E(G)$ and $r_{2}=r_{3}$. Since $G=\Gamma(V, T)$, there exists $z \in V$ such that $r_{1} r_{2} \rightarrow_{T} z$ or $r_{2} r_{1} \rightarrow_{T} z$. It follows from Axiom A that $r_{1} r_{2} \rightarrow_{T} r_{2}$. Since $r_{2}=r_{3}$, we get $r_{1} r_{2} \rightarrow_{T} r_{3}$. Thus ( $8_{1}$ ) holds.

Consider arbitrary $s_{1}, s_{2}, s_{3} \in V$ such that $s_{1} s_{2} \rightarrow_{T} s_{3}$ and $d\left(s_{1}, s_{3}\right)=1$. Then $s_{1} s_{3} \rightarrow_{S} s_{3}$. According to $\left(8_{1}\right), s_{1} s_{3} \rightarrow_{T} s_{3}$. Since $s_{1} s_{2} \rightarrow_{T} s_{3}$, Axiom E implies that $s_{3}=s_{2}$ and therefore, $s_{1} s_{2} \rightarrow_{S} s_{3}$. Thus ( $9_{1}$ ) holds.

If $D=1$, then the theorem is proved. Let $2 \leqslant n \leqslant D$. The remainder of the proof will be divided into two sections. In Section 1 we will show that $\left(8_{n-1}\right)$ and $\left(9_{n-1}\right)$ imply $\left(8_{n}\right)$. In Section 2 we will show that $\left(8_{n}\right)$ and ( $9_{n-1}$ ) imply ( $9_{n}$ ).

Section 1. Consider arbitrary $x_{0}, x, y \in V$ such that $x_{0} x \rightarrow_{S} y$ and $d\left(x_{0}, y\right)=n$. Clearly, there exist $x_{1}, \ldots, x_{n} \in V$ such that $x_{1}=x, x_{n}=y$ and $\left(x_{0}, x_{1}, \ldots, x_{n}\right)$ is a
geodesic in $G$. We have $x_{0} x_{1} \rightarrow_{S} x_{n}$. We want to prove that $x_{0} x_{1} \rightarrow_{T} x_{n}$. Suppose, to the contrary, that $x_{0} x_{1}$ non $\rightarrow_{T} x_{n}$.

First, let $x_{n} x_{n-1} \rightarrow_{T} x_{0}$. Clearly, $x_{0} x_{1} \rightarrow_{S} x_{n-1}$. Since $d\left(x_{0}, x_{n-1}\right)=n-1$, it follows from $\left(8_{n-1}\right)$ that $x_{0} x_{1} \rightarrow_{T} x_{n-1}$. According to Axiom $\mathrm{C}, x_{0} x_{1} \rightarrow_{T} x_{n}$, which is a contradiction.

We get $x_{n} x_{n-1}$ non $\rightarrow_{T} x_{0}$. According to Axiom $H$, there exists $y_{1} \in V$ such that $x_{n} y_{1} \rightarrow_{T} x_{0}$. As follows from Lemma 3, there exist $k \geqslant 0$ and $x_{n+1}, \ldots, x_{n+k+1} \in V$ such that $x_{n+1}=y_{1}, x_{k+1} x_{k}$ non $\rightarrow_{T} x_{n+k+1}$, and (3) and (4) hold. Recall that $x_{0} x_{1}$ non $\rightarrow_{T} x_{n}$ and $d\left(x_{0}, x_{n}\right)=n$. There exists $m, 0 \leqslant m \leqslant k$, such that

$$
\begin{align*}
& x_{m} x_{m+1} \text { non } \rightarrow_{T} x_{n+m} \text { and }  \tag{10}\\
& d\left(x_{n}, x_{n+m}\right)=n
\end{align*}
$$

and

$$
\begin{align*}
& \text { either } x_{m+1} x_{m} \text { non } \rightarrow_{T} x_{n+m+1} \text { or } x_{m+1} x_{m+2} \rightarrow_{T} x_{n+m+1}  \tag{11}\\
& \text { or } d\left(x_{m+1}, x_{n+m+1}\right)<n .
\end{align*}
$$

According to (6), $x_{m} x_{m+1} \rightarrow_{T} x_{m+1}$. As follows from (7), $x_{n+m} x_{n+m+1} \rightarrow_{T} x_{m}$.
We distinguish Cases 1.1 and 1.2.
Case 1.1. Let $x_{m+1} x_{m} \rightarrow_{T} x_{n+m+1}$.
Assume that $d\left(x_{m+1}, x_{n+m+1}\right)<n$. According to $\left(9_{n-1}\right)$ we have $x_{m+1} x_{m} \rightarrow_{S}$ $x_{n+m+1}$, and thus $d\left(x_{m}, x_{n+m+1}\right)=d\left(x_{m+1}, x_{n+m+1}\right)-1<n-1$. This implies that $d\left(x_{m}, x_{n+m}\right)<n$, which contradicts (10). Thus $d\left(x_{m+1}, x_{n+m+1}\right)=n$. This means that

$$
\left(x_{n+m+1}, \ldots, x_{m+2}, x_{m+1}\right)
$$

is a geodesic in $G$. We have $d\left(x_{n+m+1}, x_{m+2}\right)=n-1$ and $d\left(x_{n+m}, x_{m+2}\right)=n-2$. Therefore, $x_{n+m+1} x_{n+m} \rightarrow_{S} x_{m+2}$. It follows from ( $8_{n-1}$ ) that $x_{n+m+1} x_{n+m} \rightarrow_{T}$ $x_{m+2}$.

Let $x_{m+1} x_{m+2} \rightarrow_{T} x_{n+m+1}$. Axiom C implies that $x_{n+m+1} x_{n+m} \rightarrow_{T} x_{m+1}$. We have seen that $x_{n+m} x_{n+m+1} \rightarrow_{T} x_{m}$. Since $x_{m} \cdot x_{m+1} \rightarrow_{T} x_{m+1}$, it follows from Axiom F that $x_{m} x_{m+1} \rightarrow_{T} x_{n+m}$, which is a contradiction to (10). Thus $x_{m+1} x_{m+2}$ non $\rightarrow_{T} x_{n+m+1}$. Since $x_{m+1} \cdot x_{m} \rightarrow_{T} x_{n+m+1}$ and $d\left(x_{m+1}, x_{n+m+1}\right)=n$, we get a contradiction to (11).

Case 1.2. Let $x_{m+1} x_{m}$ non $\rightarrow_{T} x_{n+m+1}$. Recall that $x_{n+m} x_{n+m+1} \rightarrow_{T} x_{m}$. According to (10), $x_{m} x_{m+1}$ non $\rightarrow_{T} x_{n+m}$. Since $x_{m} x_{m+1} \rightarrow_{T} x_{m+1}$, Axiom G implies that

$$
x_{n+m} x_{n+m+1} \rightarrow_{T} x_{m+1}
$$

Since $d\left(x_{m}, x_{n+m}\right)=n, d\left(x_{m+1}, x_{n+m}\right)=n-1$. According to $\left(9_{n-1}\right), x_{n+m} x_{n+m+1}$ $\rightarrow_{S} x_{m+1}$. Hence $d\left(x_{m+1}, x_{n+m+1}\right)=n-2$. Since $x_{m} x_{m+1} \rightarrow_{S} x_{n+m}$, we get $x_{m} x_{m+1} \rightarrow_{S} x_{n+m+1}$. Clearly, $d\left(x_{m}, x_{n+m+1}\right)=n-1$. According to ( $8_{n-1}$ ), $x_{m} x_{m+1} \rightarrow_{T} x_{n+m+1}$. Recall that $x_{n+m} x_{n+m+1} \rightarrow_{T} x_{m}$. Axiom C implies that $x_{m} x_{m+1} \rightarrow_{T} x_{n+m}$, which contradicts (10).

We proved that $x_{0} x_{1} \rightarrow_{T} x_{n}$. Hence ( $8_{n}$ ) holds.
Section 2. Consider arbitrary $y, y_{1}, x_{0} \in V$ such that $y y_{1} \rightarrow_{T} x_{0}$ and $d\left(y, x_{0}\right)=n$. Clearly, there exist $x_{1}, \ldots, x_{n} \in V$ such that $x_{n}=y$, and $\left(x_{0}, x_{1}, \ldots, x_{n}\right)$ is a geodesic in $G$. We have $x_{n} y_{1} \rightarrow_{T} x_{0}$. Obviously, $d\left(y_{1}, x_{0}\right) \geqslant n-1$. We want to prove that $x_{n} y_{1} \rightarrow_{S} x_{0}$. We see that $x_{n} y_{1} \rightarrow_{S} x_{0}$ if and only if $d\left(y_{1}, x_{0}\right)=n-1$. Suppose, to the contrary, that $d\left(y_{1}, x_{0}\right) \geqslant n$.

As follows from Lemma 3 , there exist $k \geqslant 0$ and $x_{n+1}, \ldots, x_{n+k+1} \in V$ such that $x_{n+1}=y_{1}, x_{k+1} x_{k} n o n \rightarrow_{T} x_{n+k+1}$, and (3) and (4) hold. Recall that $d\left(x_{0}, x_{n}\right)=n$. There exists $m, 0 \leqslant m \leqslant k$, such that

$$
\begin{equation*}
d\left(x_{m}, x_{n+m}\right)=n \tag{12}
\end{equation*}
$$

and
either $x_{m+1} x_{m}$ non $\rightarrow_{T} x_{n+m+1}$ or $d\left(x_{m+1}, x_{n+m+1}\right)<n$.
According to (6), $x_{m} x_{m+1} \rightarrow_{T} x_{m+1}$. Axiom A implies that $x_{m+1} x_{m} \rightarrow_{T} x_{m}$. As follows from (7), $x_{n+m} x_{n+m+1} \rightarrow_{T} x_{m}$.

We distinguish Cases 2.1 and 2.2.
Case 2.1. Let $d\left(x_{m+1}, x_{n+m+1}\right)=n$. Then

$$
\left(x_{n+m+1}, x_{n+m}, \ldots, x_{m+1}\right)
$$

is a geodesic in $G$. Hence $x_{n+m+1} x_{n+m} \rightarrow_{S} x_{m+1}$. It follows from ( $8_{n}$ ) that $x_{n+m+1} x_{n+m} \rightarrow_{T} x_{m+1}$. Recall that $x_{n+m} x_{n+m+1} \rightarrow_{T} x_{m}$. Since $x_{m+1} x_{m} \rightarrow_{T} x_{m}$, Axiom F implies that $x_{m+1} x_{m} \rightarrow_{T} x_{n+m+1}$, which contradicts (13).

Case 2.2. Let $d\left(x_{m+1}, x_{n+m+1}\right)<n$.
Assume that $d\left(x_{m}, x_{n+m+1}\right)=n$. Then $d\left(x_{m+1}, x_{n+m+1}\right)=n-1$. Therefore, $x_{m} x_{m+1} \rightarrow_{S} x_{n+m+1}$. According to $\left(8_{n}\right), x_{m} x_{m+1} \rightarrow_{T} x_{n+m+1}$. Since $x_{n+m} x_{n+m+1} \rightarrow_{T} x_{m}$, Axiom D implies that $x_{n+m} x_{n+m+1} \rightarrow_{T} x_{m+1}$. Since $d\left(x_{m+1}, x_{n+m}\right)=n-1$, it follows from $\left(9_{n-1}\right)$ that $x_{n+m} x_{n+m+1} \rightarrow_{S} x_{m+1}$. Therefore, $d\left(x_{m+1}, x_{n+m+1}\right)=n-2$, which is a contradiction.

Thus $d\left(x_{m}, x_{n+m+1}\right)<n$. It follows from (12) that

$$
d\left(x_{m}, x_{n+m+1}\right)=n-1 .
$$

Recall that $x_{n+1}=y_{1}$. If $m=0$, then $d\left(x_{0}, x_{n+1}\right)=n-1$, which is a contradiction. Let $m \geqslant 1$. Since $m \leqslant k$, Remark 3 implies that

$$
x_{1} x_{0} \rightarrow_{T} x_{n+m+1}, \ldots, x_{m} x_{m-1} \rightarrow_{T} x_{n+m+1} .
$$

Consider an arbitrary $i, 1 \leqslant i \leqslant m$. If $d\left(x_{i}, x_{n+i+1}\right)<n$, then $\left(9_{n-1}\right)$ implies that $x_{i} x_{i-1} \rightarrow_{S} x_{n+m+1}$, and therefore, $d\left(x_{i-1}, x_{n+m+1}\right)=d\left(x_{i}, x_{n+m+1}\right)-1$. Since $d\left(x_{m}, x_{n+m+1}\right)=n-1$, we get

$$
d\left(x_{0}, x_{n+m+1}\right)=n-m-1 .
$$

This means that $m \leqslant n-1$. As follows from Remark 3,

$$
\left(x_{n+1}, \ldots, x_{n+m+1}\right)
$$

is a walk in $G$. Thus $d\left(x_{n+1}, x_{n+m+1}\right) \leqslant m$. This means that

$$
d\left(x_{0}, x_{n+1}\right) \leqslant d\left(x_{0}, x_{n+m+1}\right)+d\left(x_{n+m+1}, x_{n+1}\right) \leqslant n-1,
$$

which is a contradiction.
We have proved that $x_{n} y_{1} \rightarrow_{S} x_{0}$. Hence $\left(9_{n}\right)$ holds.
Thus $T=S$, which completes the proof of Theorem 1 .
Remark 4. Let $V$ be a finite nonempty set, and let $T \subseteq V^{3}$. As we will show, the fact that $T$ fulfils Axioms A-H does not imply that $\Gamma(V, T)$ is connected.

Assume that $V=\left\{r_{1}, \ldots, r_{n}, s_{1}, \ldots, s_{n}\right\}$, where $n \geqslant 3$ and $|V|=2 n$. Put $r_{n+1}=$ $r_{1}$ and $s_{n+1}=s_{1}$. Assume that $T$ is the subset of $V^{3}$ with the property that $u v \rightarrow_{T} x$ if and only if one of the following cases a) and b) holds:
a) there exist distinct $g$ and $h, 1 \leqslant g \leqslant n$ and $1 \leqslant h \leqslant n$, such that

$$
\begin{aligned}
& \text { either }\left(u=r_{g}, v=r_{h} \text { and } x=r_{h}\right) \\
& \text { or }\left(u=s_{g}, v=s_{h}, x=s_{h}\right)
\end{aligned}
$$

b) there exist $i$ and $j, 1 \leqslant i \leqslant n$ and $1 \leqslant i \leqslant n$, such that

$$
\begin{aligned}
& \text { either }\left(u=r_{i}, v=r_{i+1} \text { and } x=s_{j}\right) \\
& \text { or }\left(u=s_{i}, v=s_{i+1} \text { and } x=r_{j}\right)
\end{aligned}
$$

It is not difficult to see that $T$ fulfils Axioms $\mathrm{A}-\mathrm{H}$ and that $\Gamma(V, T)$ has exactly two components.

Let $V$ be a finite nonempty set, and let $R \subseteq \Sigma(V)$. We denote by $[R]$ the subset $T$ of $V^{3}$ defined as follows:

$$
\begin{aligned}
& u v \rightarrow_{T} x \text { if and only if there exist } n \geqslant 1 \text { and } u_{0}, u_{1}, \\
& \ldots, u_{n} \in V \text { such that }\left(u_{0}, u_{1}, \ldots, u_{n}\right) \in R, u=u_{0}, \\
& v=u_{1} \text { and } x=u_{n}
\end{aligned}
$$

for any $u, v, x \in V$.
Proposition 2. Let $V$ be a finite nonempty set, and let $R \subseteq \Sigma(V)$. Put $T=[R]$. Assume that there exists a connected graph $G$ with the properties that $V(G)=V$ and $R$ is the set of all geodesics in $G$. Then $G=\Gamma(V, T)$.

Proof. Since $V(G)=V(\Gamma(V, T))$, we see that $G=\Gamma(V, T)$ if and only if $E(G)=E(\Gamma(V, T))$.

Consider arbitrary $u, v \in V$.
Let $\{u, v\} \in E(G)$. Then $(u, v)$ is a geodesic in $G$. Thus $(u, v) \in R$. Clearly, $u v \rightarrow_{T} v$. Since $u \neq v$, we see that $\{u, v\} \in E(\Gamma(V, T))$.

Conversely, let $\{u, v\} \in E(\Gamma(V, T))$. Then $u \neq v$ and there exists $x \in V$ such that $u v \rightarrow_{T} x$ or $v u \rightarrow_{T} x$. Since $T=[R]$, there exist $n \geqslant 1$ and $u_{0}, u_{1}, \ldots, u_{n} \in V$ such that $\left(u_{0}, u_{1}, \ldots, u_{n}\right) \in R, x=u_{n}$ and either (i) $u=u_{0}$ and $v=u_{1}$ or (ii) $u=u_{1}$ and $v=u_{0}$. The fact that $\left(u_{0}, u_{1}, \ldots, u_{n}\right)$ is a geodesic in $G$ implies that $\{u, v\} \in E(G)$.

We have $G=\Gamma(V, T)$, which completes the proof.
Theorem 2. Let $V$ be a finite nonempty set, and let $R \subseteq \Sigma(V)$. Put $T=[R]$. Assume that $\Gamma(V, T)$ is connected. Then the following statements (III) and (IV) are equivalent:
(III) $R$ is the set of all geodesics in $\Gamma(V, T)$;
(IV) $T$ fulfils Axioms A-H (for arbitrary ( $u, v, x, y \in V$ ) and moreover, $R$ fulfils the following Axioms X, Y and Z (for arbitrary $m, n \geqslant 1$ and $u, u_{0}, \ldots, u_{m}$, $\left.w_{0}, \ldots, w_{n} \in V\right):$
$\mathrm{X}(u) \in R$;
Y if $\left(u, u_{m}, \ldots, u_{0}\right) \in R$, then $\left(u_{m}, \ldots, u_{0}\right) \in R$;
Z if $\left(u, u_{m}, \ldots, u_{0}\right),\left(w_{n}, \ldots, w_{0}\right) \in R, w_{0}=u_{0}$ and $w_{n}=u_{m}$, then $\left(u, w_{n}, \ldots, w_{0}\right) \in R$.

Proof. Denote $G=\Gamma(V, T)$. Recall that $G$ is connected. We denote by $d$ the distance function of $G$.

PART ONE (III $\Rightarrow$ IV). Let III hold. It is easy to see that $R$ fulfils Axioms X, Y and Z. Since $T=[R]$, we see that $T$ is the set of all steps in $G$. According to Theorem 1, $T$ fulfils Axioms A-H. Hence IV holds.

PART TWO (IV $\Rightarrow$ III). Let IV hold. Consider arbitrary $v_{0}, \ldots, v_{n} \in V$, where $n \geqslant 0$. We will prove that

$$
\begin{equation*}
\left(v_{n}, \ldots, v_{0}\right) \in R \text { if and only if }\left(v_{n}, \ldots, v_{0}\right) \text { is a geodesic in } G . \tag{n}
\end{equation*}
$$

We proceed by induction on $n$. Let first $n=0$. It is obvious that ( $v_{0}$ ) is a geodesic. According to Axiom $\mathrm{X},\left(v_{0}\right) \in R$. Thus $\left(14_{0}\right)$ holds. We now assume that $n \geqslant 1$.

Let $\left(v_{n}, v_{n-1}, \ldots, v_{0}\right) \in R$. Since $T=[R], v_{n} v_{n-1} \rightarrow_{T} v_{0}$. Theorem 1 implies that $\left(v_{n}, v_{n-1}, v_{0}\right)$ is a step in $G$. Hence

$$
\begin{equation*}
d\left(v_{n}, v_{n-1}\right)=1 \text { and } d\left(v_{n}, v_{0}\right)=d\left(v_{n-1}, v_{0}\right)+1 \tag{15}
\end{equation*}
$$

As follows from Axiom $Y,\left(v_{n-1}, \ldots, v_{0}\right) \in R$. According to $\left(14_{n-1}\right),\left(v_{n-1}, \ldots, v_{0}\right)$ is a geodesic in $G$. It follows from (15) that $\left(v_{n}, v_{n-1}, \ldots, v_{0}\right)$ is a geodesic in $G$.

Conversely, let $\left(v_{n}, v_{n-1}, \ldots, v_{0}\right)$ be a geodesic in $G$. Then (15) holds. Hence $\left(v_{n}, v_{n-1}, v_{0}\right)$ is a step in $G$. According to Theorem $1, v_{n} v_{n-1} \rightarrow_{T} v_{0}$. Recall that $T=[R]$. It follows from the definition of $[R]$ that there exist $m \geqslant 0, u_{0}, \ldots, u_{m} \in V$ such that $\left(v_{n}, u_{m}, \ldots, u_{0}\right) \in R, u_{0}=v_{0}$ and $u_{m}=v_{n-1}$. Since $\left(v_{n}, v_{n-1}, \ldots, v_{0}\right)$ is a geodesic, $\left(v_{n-1}, \ldots, v_{0}\right)$ is also a geodesic. According to $\left(14_{n-1}\right),\left(v_{n-1}, \ldots, v_{0}\right) \in R$. Axiom Z implies that $\left(v_{n}, v_{n-1}, \ldots, v_{0}\right) \in R$.

Thus ( $14_{n}$ ) holds. The proof of the theorem is complete.
Combining Theorem 2 with Proposition 2 we get the following characterization of the set of all geodesics in a connected graph.

Corollary 2. Let $V$ be a finite nonempty set, and let $R \subseteq \Sigma(V)$. Put $T=[R]$. Then there exists a connected graph $G$ with the properties that $V(G)=V$ and $R$ is the set of all geodesics in $G$ if and only if $\Gamma(V, T)$ is connected, $T$ fulfils Axioms A-H (for arbitrary $u, v, x, y \in V$ ) and moreover, $R$ fulfils Axioms $\mathrm{X}, \mathrm{Y}$ and Z (for arbitrary $m, n \geqslant 1$ and $\left.u, u_{0}, \ldots, u_{m}, w_{0}, \ldots, w_{n} \in V\right)$.

Another characterization of the set of all geodesics in a connected graph can be found in [5] (cf. also [7] or [8]).

Remark 5. The concept of the set of all geodesics in a connected graph is closely connected to that of the interval function (in the sense of [4]) of a connected graph. A characterization of the interval function of a connected graph was given in [6].

## References

[1] M. Behzad, G. Chartrand and L. Lesniak-Foster: Graphs \& Digraphs. Prindle, Weber \& Schmidt, Boston 1979.
[2] F. Harary: Graph Theory. Addison-Wesley, Reading (Mass.) 1969.
[3] D. C. Kay and G. Chartrand: A characterization of certain ptolemaic graphs. Canad. J. Math. 17 (1965), 342-346.
[4] H. M. Mulder: The Interval Function of a Graph. Mathematisch Centrum. Amsterdam 1980.
[5] L. Nebesky: A characterization of the set of all shortest paths in a connected graph. Mathematica Bohemica 119 (1994), 15-20.
[6] L. Nebeský: A characterization of the interval function of a connected graph. Czechoslovak Math. J. 44 (119) (1994), 173-178.
[7] L. Nebeský: Visibilities and sets of shortest paths in a connected graph. Czechoslovak Math. J. 45(120) (1995), 563-570.
[8] L. Nebesky: On the set of all shortest paths of a given length in a connected graph. Czechoslovak Math. J. 46(121) (1996), 155-160.

Author's address: Filozofická fakulta Univerzity Karlovy, nám. J. Palacha 2, 11638 Praha 1, Czech Republic.

