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# GEOMETRICAL ASPECTS OF THE COVARIANT DYNAMICS OF HIGHER ORDER 

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Abstract. We present some geometrical aspects of a higher-order jet bundle which is considered a suitable framework for the study of higher-order dynamics in continuous media. We generalize some results obtained by A. Vondra, [7]. These results lead to a description of the geometrical dynamics of higher order generated by regular equations.

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## Introduction

The present study is an attempt to emphasize some geometrical aspects of a possible mathematical model for the higher-order dynamics in continuous media as well as for the higher-order field theories.

The mathematicians agree (see [1], [2], [4], etc) that the most suitable framework for this application is a higher-order jet bundle associated to a fibered manifold. A physical field is a section of this "configuration manifold". The partial differential equations describing some higher-order dynamics are the kernels of some operators which appear as sections in a vector bundle of forms over that jet bundle, [1].
A. Vondra initiated such a study for a fibered manifold having the base of dimension 1, [5], [6], [7].

We consider a fibered manifold $\left(E, \pi_{0}, B\right)$, where $B$ is an orientable manifold of dimension $n \geqslant 1$ ("parameter space" containing $n-1$ "spatial variables" and a "time variable"), $E$ is a manifold of dimension $n+m$ and $\pi_{0}$ is a submersion of $E$ on $B$.

In [4] one argues the importance of a covariant approach that is the time variable and the other parameters on the whole.

To start the study it is necessary to define some associated structures and geometrical objects as $f(3,-1)$-structures, contact forms, connection of order $r$, dynamical connections.

Our approach means, in a more general context, to consider the $f(3,-1)$-structure on a jet bundle introduced by Vondra in the case $n=1,[6]$.

The results of $\S 4(r=1)$ generalize those obtained by Vondra in [7]. These results lead to a description of the geometrical dynamics of higher order generated by regular equations.

We shall use the standard multi-index notation. A multi-index is denoted by $I=\left(i_{1}, \ldots, i_{n}\right) \in \mathbb{N}^{n}$. The length of $I$ is $|I|=i_{1}+\ldots+i_{n}$ and its power is $w(I)=|I|!/ I!$ where $I!=i_{1}!\ldots i_{n}!. \quad 0=(0, \ldots, 0)$ is the null multi-index and $1_{i}=(0, \ldots, 1, \ldots 0)$ with 1 at the $i$-th place. For $I=\left(i_{1}, \ldots, i_{n}\right), J=\left(j_{1}, \ldots, j_{n}\right)$ we define the sum $I+J=\left(i_{1}+j_{1}, \ldots, i_{n}+j_{n}\right)$. In particular, $I j=j I=I+1_{j}=$ $\left(i_{1}, \ldots, i_{j-1}, i_{j}+1, i_{j+1}, \ldots, i_{n}\right)$. For a family of objects $A=\left\{a_{i, J},|I|=m,|J|=1\right\}$ with $m, l$ fixed, we may define a new family $\sigma(A)=\left\{\sigma_{L}(A),|L|=m+1\right\}$ by

$$
\sigma_{L}(A)=\frac{1}{w(L)} \sum_{I+J=L} w(I) w(J) a_{I, J}
$$

(the sum is made for all multi-indexes $I, J$ with $I+J=L$ ). The family of objects $A=\left\{a_{I, j},|I|=m\right\}$ is identified with the family $A=\left\{a_{I, 1_{j}},|I|=m\right\}$ for which $\sigma(A)=\left\{\sigma_{L}(A),|L|=m+1\right\}$, where

$$
\sigma_{L}(A)=\frac{1}{w(L)} \sum_{I+J=L} w(I) a_{I, J},|I|=m,|J|=1
$$

All manifolds and mappings are supposed to be smooth and the summation convention is used as far as possible.

## 1. Geometric structures on $J^{p} E$

Let $\left(E, \pi_{0}, B\right)$ be a fibered manifold with $\operatorname{dim} B=n, \operatorname{dim} E=n+m,\left(U, x^{i}\right)$ a local chart on $B$ and $\left(U_{0}=\pi_{0}^{-1}(U), x^{i}, u^{\alpha}\right)$ the local fibered chart on $E$ adapted to $\left(U, x^{i}\right)$. If $\left(\bar{U}_{0}, \bar{x}^{i}, \bar{u}^{\alpha}\right)$ is another chart local fibered charts on $E$ adapted to ( $\bar{U}, \bar{x}^{i}$ ) and $U \cap \bar{U} \neq \emptyset$ then the coordinate transformations are

$$
\begin{align*}
& \bar{x}^{i}=\bar{x}^{i}(x), \operatorname{det}\left\|\bar{B}_{j}^{i}\right\| \neq 0, \bar{B}_{j}^{i}=\frac{\partial \bar{x}^{i}}{\partial x^{j}}  \tag{1.1}\\
& \bar{u}^{\alpha}=\bar{u}^{\alpha}(x, u), \operatorname{det}\left\|\bar{A}_{\beta}^{\alpha}\right\| \neq 0, \bar{A}_{\beta}^{\alpha}=\frac{\partial \bar{u}^{\alpha}}{\partial u^{\beta}}
\end{align*}
$$

Let $\Gamma\left(\pi_{0}\right)$ be the set of the sections of $\pi_{0}$ and for a local section on $U \subset B$, $s \in \Gamma_{U}\left(\pi_{0}\right)$, let us denote

$$
\begin{equation*}
u_{I}^{\alpha}(x)=: u_{i_{1} \ldots i_{n}}^{\alpha}(x):=\frac{\partial^{|I|} s^{\alpha}(x)}{\left(\partial x^{1}\right)^{i_{1}} \ldots\left(\partial x^{n}\right)^{i_{n}}}, \tag{1.2}
\end{equation*}
$$

where $I=\left(i_{1}, \ldots, i_{n}\right)$ is a multi-index with $|I| \leqslant r$. The equivalence relation in $\Gamma_{U}\left(\pi_{0}\right)$ is introduced as follows: $s_{1} \sim s_{2}$ iff ${\underset{1}{I}}_{u_{I}}^{(x)}={\underset{2}{u}}_{\alpha}^{\alpha}(x), 0 \leqslant|I| \leqslant r, x \in U$ and determines the $r$-jets of sections of $\pi_{0}$ in $x$, denoted by $j_{x}^{r} s$. Finally, the set of all such $r$-jets of sections of $\pi_{0}$ is a differentiable manifold denoted by $J^{r} E$;

$$
\begin{align*}
& \left(J^{r} E, \pi_{r}, B\right), \text { where } \\
& \pi_{r}: J^{r} E \rightarrow B, \pi_{r}\left(j_{x}^{r} s\right)=x, \tag{1.3}
\end{align*}
$$

is a fibered manifold; for each pair $(p, r)$ such that $0 \leqslant p \leqslant r-1,\left(J^{r} E, \pi_{p r}, J^{p} E\right)$, where

$$
\begin{equation*}
\pi_{p r}: J^{r} E \rightarrow J^{p} E, \pi_{p r}\left(j_{x}^{r} s\right)=j_{x}^{p} s \tag{1.4}
\end{equation*}
$$

is a fiber bundle. In particular, $J^{r} E$ is an affine bundle over $J^{r-1} E$ and $J^{0} E=$ $E$. The local fibered chart on $J^{r} E$ induced by $\left(U, x^{i}\right)$ is $\left(U_{r}=\pi_{r}^{-1}(U), x^{i}, u_{I}^{\alpha}\right)$, $0<|I|<r$.

For $f \in \mathscr{F}\left(J^{r} E\right)$ the partial derivative of $f$ in direction $x^{i}$ is defined by

$$
\begin{equation*}
\left(j^{r+1} s\right)^{*}\left(d_{i} f\right)=\partial_{i}\left(f \circ j^{r} s\right), \forall s \in \Gamma\left(\pi_{0}\right) \tag{1.5}
\end{equation*}
$$

In the local chart $\left(U_{r}, x^{i}, u_{I}^{\alpha}\right)$ we have

$$
\begin{equation*}
d_{i}^{r} f=\partial_{i} f+\sum_{0 \leqslant|I| \leqslant r} u_{i I}^{\alpha} \partial_{\alpha}^{I} f, \tag{1.6}
\end{equation*}
$$

where $0 \leqslant|I| \leqslant r, \partial_{\alpha}^{I}=: \frac{\partial}{\partial u_{I}^{\alpha}}$ and $i$ is identified with $1_{i},[3],[1]$.
For two local fibered charts on $J^{r} E,\left(\bar{U}_{r}, \bar{x}^{i}, \bar{u}_{I}^{\alpha}\right),\left(U_{r}, x^{i}, u_{J}^{\beta}\right)$ with $\bar{U} \cap U \neq \emptyset$, the coordinate transformations are

$$
\begin{align*}
\bar{x}^{i} & =\bar{x}^{i}(x),  \tag{1.7}\\
\bar{u}^{\alpha} & =\bar{u}^{\alpha}(x, u), \\
\ldots & \ldots \ldots \ldots \\
\bar{u}_{L}^{\alpha} & =\sigma_{L}\left(d_{i}\left(\bar{u}_{I}^{\alpha}\right)\right),
\end{align*}
$$

where $|L|=1+|I|$ and $0 \leqslant|I| \leqslant r-1$. The natural local basis on $J^{r} E$ is $\left\{\partial_{i}, \partial_{\alpha}^{I}\right\}$ and the local co-basis is $\left\{d x^{i}, d u_{I}^{\alpha}\right\}$, where $0 \leqslant|I| \leqslant r$.

The canonical projection (1.4), $\pi_{p r}:\left(x^{i}, u_{I}^{\alpha}\right) \in J^{r} E \mapsto\left(x^{i}, u_{J}^{\alpha}\right) \in J^{p} E$, with $0 \leqslant$ $|I| \leqslant r, 0 \leqslant|J| \leqslant p$, leads to the vector subbundles $V_{p r}=\operatorname{Ker}\left(\pi_{p r}\right)_{*}, 0 \leqslant p \leqslant r-1$, of the tangent bundle $T\left(J^{r} E\right)$. The local fiberes of $V_{p r}$ determine regular differential systems

$$
\begin{equation*}
V_{p r}: z \in J^{r} E \mapsto V_{p r}(z) \subset T_{z}\left(J^{r} E\right) \tag{1.8}
\end{equation*}
$$

on $J^{r} E$ having the property

$$
\begin{equation*}
V_{r-1 r}(z) \subset V_{r-2 r}(z) \subset \ldots \subset V_{o r}(z) \tag{1.9}
\end{equation*}
$$

These differential systems are generated by the vector fields $\left\{\partial_{\alpha}^{I}\right\}, 0 \leqslant|I| \leqslant r$.
We call the contact form $\stackrel{p}{\theta}, 1 \leqslant p \leqslant r-1$, the $V\left(J^{p} E\right)$-valued 1-form on $J^{r} E$ such that

$$
\begin{align*}
& \stackrel{p}{\theta\left(\left(j^{r} s\right)_{*} \nu\right)}=0, \forall s \in \Gamma_{U}\left(\pi_{0}\right), \quad \forall \nu \in T B,  \tag{1.10}\\
& p \\
& \theta(\xi)=\left(\pi_{p r}\right)_{*} \xi, \forall \xi \in V\left(J^{r} E\right),[3] .
\end{align*}
$$

By using the canonical local basis and co-basis we obtain

$$
\begin{equation*}
\stackrel{p}{\theta}=\sum_{|I|=p-1} \stackrel{p}{\theta_{I}^{\alpha}} \otimes \partial_{\alpha}^{I} \tag{1.11}
\end{equation*}
$$

where

$$
\begin{equation*}
\stackrel{p}{\theta_{I}^{\alpha}}=d u_{I}^{\alpha}-u_{I, i}^{\alpha} d x^{i}, \quad|I|=p-1 . \tag{1.12}
\end{equation*}
$$

We can define a $V\left(J^{r} E\right)$-valued contact form $\theta_{2}$ on $J^{r} E$ by

$$
\begin{equation*}
\theta_{2}=\sum_{p=1}^{r-1}{ }^{p}=\sum_{p=1}^{r-1} \sum_{|I|=p} \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I} \tag{1.13}
\end{equation*}
$$

Finally, we consider a contact map on $J^{r} E$ which is a $\pi_{r}^{*}\left(T^{*} B\right) \otimes T\left(J^{r-1} E\right)$-valued 1-form $\theta_{1}$ locally given by

$$
\begin{equation*}
\theta_{1}=d x^{i} \otimes d_{i}^{r}, \quad \text { where } d_{i}^{r}=\partial_{i}+\sum_{0 \leqslant|I| \leqslant r} u_{i I}^{\alpha} \partial_{\alpha}^{I} . \tag{1.14}
\end{equation*}
$$

We can also introduce some 1 -forms $\stackrel{p}{J}, 1 \leqslant p \leqslant r-1$, on $J^{r} E$, which are $T\left(J^{p} E\right) \otimes$ $T\left(J^{p+1} E\right)$-valued and defined by

$$
\begin{equation*}
J^{p}=\sum_{|I|=p-1} \stackrel{p}{\theta_{I}^{\alpha}} \otimes \partial_{\alpha}^{I i} \otimes d_{i}^{p+1} \tag{1.15}
\end{equation*}
$$

where

$$
\begin{equation*}
d_{i}^{p+1}=\partial_{i}+\sum_{0 \leqslant|I| \leqslant p+1} u_{i I}^{\alpha} \partial_{\alpha}^{I} \tag{1.16}
\end{equation*}
$$

For each $i \in\{1, \ldots, n\}$, let us define a $T\left(J^{p+1} E\right)$-valued 1-form on $J^{r} E$ by

$$
\begin{equation*}
\stackrel{p}{J^{i}}=\sum_{|I|=p-1} \stackrel{p}{\theta_{I}^{\alpha}} \otimes \partial_{\alpha}^{I i} \tag{1.17}
\end{equation*}
$$

It follows from (1.17) that

$$
\begin{equation*}
\left.\stackrel{p}{J^{i} \circ \stackrel{p}{J^{j}}=0 ;} \stackrel{p}{J^{i}}, \stackrel{p}{J^{j}}\right]_{F N}=0, \tag{1.18}
\end{equation*}
$$

where $[,]_{F N}$ is the Frölicher-Nijenhuis bracket defined for the vector valued forms. Consequently, the 1-form $J^{i}$ is an almost tangent structure called the almost tangent structure in direction $x^{i}$.

## 2. Connection of order $r$. Dynamical connection of order $r$

A connection of order $r$ on $\left(E, \pi_{0}, B\right)$ is a section $\Lambda: J^{r-1} E \rightarrow J^{r} E$ of the bundle $\left(J^{r} E, \pi_{r-1 r}, J^{r-1} E\right)$. Any such connection is locally given by

$$
\Lambda:\left(x^{i}, u_{I}^{\alpha}\right) \in J^{r-1} E \mapsto\left(x^{i}, u_{I}^{\alpha}, \Lambda_{J}^{\alpha}\right) \in J^{r} E, 0 \leqslant|I| \leqslant r-1,|J|=r,
$$

where

$$
\Lambda_{J}^{\alpha}=\Lambda_{J}^{\alpha}\left(x^{i}, u_{I}^{\alpha}\right) .
$$

The horizontal form $h^{r}$ of $\Lambda$ and the vertical form $v^{r}$ are given by

$$
\begin{align*}
& h^{r}=\theta_{1} \circ \Lambda=d x^{i} \otimes\left(\partial_{i}+\sum_{0 \leqslant|I| \leqslant r-2} u_{i I}^{\alpha} \partial_{\alpha}^{I}+\sum_{|J|=r-1} \Lambda_{i J}^{\alpha} \partial_{\alpha}^{J}\right),  \tag{2.1}\\
& v^{r}=\theta_{2} \circ \Lambda=\sum_{0 \leqslant|I| \leqslant r-1} \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I}+\sum_{|J|=r-1}\left(d u_{J}^{\alpha}-\Lambda_{i J}^{\alpha} d x^{i}\right) \partial_{\alpha}^{J} .
\end{align*}
$$

The $\pi_{r-1 r}$-horizontal distribution $\operatorname{Im} h^{r}$ is called the semispray distribution $\Delta_{r}^{r-1}(\Lambda)$ and it is locally generated on $J^{r-1} E$ by the vector fields

$$
\begin{equation*}
\Gamma_{i}=\partial_{i}+\sum_{0 \leqslant|I| \leqslant r-2} u_{i I}^{\alpha} \partial_{\alpha}^{I}+\sum_{|J|=r-1} \Lambda_{i J}^{\alpha} \partial_{\alpha}^{J} \tag{2.2}
\end{equation*}
$$

The forms associated to $\Delta_{r}^{r-1}(\Lambda)$ are given by

$$
\begin{equation*}
\theta_{I}^{\alpha}=d u_{I}^{\alpha}-u_{i I}^{\alpha} d x^{i}, \Psi_{J}^{\alpha}=d u_{J}^{\alpha}-\Lambda_{i J}^{\alpha} d x^{i} \tag{2.3}
\end{equation*}
$$

$0 \leqslant|I| \leqslant r-2,|J|=r-2$. The connection $\Lambda$ of order $r$ determines the direct sum decomposition

$$
\begin{equation*}
T J^{r-1} E=\Delta_{r}^{r-1}(\Lambda) \oplus V\left(J^{r-1} E\right) \tag{2.4}
\end{equation*}
$$

A section $s \in \Gamma_{U}\left(\pi_{0}\right)$ is called an integral section of $\Lambda$ if

$$
j^{r} s=\Lambda \circ j^{r-1} s
$$

on $U$. The condition of integrability is locally given by the relations

$$
\begin{equation*}
s_{J}^{\alpha}\left(x, s_{I}^{\beta}(x)\right)=\Lambda_{J}^{\alpha}\left(x, s_{I}^{\beta}(x)\right),|J|=r, 0 \leqslant|I| \leqslant r-1 . \tag{2.5}
\end{equation*}
$$

From (2.2) and (2.5) it results that $s$ is an integral section if and only if $j^{r-1} s$ is an integral map of $\Delta_{r}^{r-1}(\Lambda)$.

Let $\widetilde{\pi}_{1, r-1}: J^{1}\left(J^{r-1} E\right) \rightarrow J^{r-1} E$ be the 1-jet bundle of sections of the bundle $\pi_{r-2 r-1}: J^{r-1} E \rightarrow J^{r-2} E$. If $\left(U_{r-1}, x^{i}, u_{I}^{\alpha}\right), 0 \leqslant|I| \leqslant r-2$, is a local chart on $J^{r-2} E$ and $s\left(x^{i}, u_{I}^{\alpha}\right)=\left(x^{i}, u_{I}^{\alpha}, s_{J}^{\alpha}\left(x, u_{I}^{\alpha}\right)\right), 0 \leqslant|I| \leqslant r-2,|J|=r-1$, is a section of $\pi_{r-2 r-1}$, then

$$
\begin{align*}
j_{(x, u)}^{1} s & =\left(x^{i}, u_{I}^{\alpha}, s_{J}^{\alpha}, s_{J i}^{\alpha}, s_{J \beta}^{\alpha I}\right), \text { where }  \tag{2.6}\\
s_{J i}^{\alpha} & =\frac{\partial s_{J}^{\alpha}}{\partial x^{i}}, s_{J \beta}^{\alpha I}=\frac{\partial s_{J}^{\alpha}}{\partial u_{I}^{\beta}} .
\end{align*}
$$

A canonical chart on $J^{1}\left(J^{r-1} E\right)$ is given by $\left(\widetilde{U}_{1 r-1}=\widetilde{\pi}_{1 r-1}\left(U_{r-1}\right), x^{i}, u_{I}^{\alpha}\right.$, $\left.u_{J}^{\alpha}, u_{L}^{\alpha}, u_{J \beta}^{\alpha I}\right), 0 \leqslant|I| \leqslant r-2,|J|=r-1,|L|=r$. The contact map on $J^{1}\left(J^{r-1} E\right)$ is

$$
\begin{equation*}
\tilde{\theta}_{1}=d x^{i} \otimes\left(\partial_{i}+\sum_{0 \leqslant|I| \leqslant r-1} u_{i I}^{\alpha} \partial_{\alpha}^{I}\right)+\sum_{0 \leqslant|I| \leqslant r-2} d u_{I}^{\alpha} \otimes\left(\partial_{\alpha}^{I}+\sum_{|J|=r-1} u_{J \alpha}^{\beta I} \partial_{\beta}^{J}\right) \tag{2.7}
\end{equation*}
$$

and the contact form is

$$
\begin{equation*}
\widetilde{\theta}_{2}=\sum_{|J|=r-1}\left(d u_{J}^{\alpha}-d u_{i J}^{\alpha} d x^{i}-\sum_{0 \leqslant|I| \leqslant r-2} u_{J \beta}^{\alpha I} d u_{I}^{\beta}\right) \otimes \partial_{\alpha}^{J} . \tag{2.8}
\end{equation*}
$$

A dynamical connection on $J^{r-1} E$ is a section $F_{d}: J^{r-1} E \rightarrow J^{1}\left(J^{r-1} E\right)$ of $\widetilde{\pi}_{1, r-1}$. Locally, such a connection is given by

$$
F_{d}:\left(x^{i}, u_{I}^{\alpha}\right) \in J^{r-1} E \mapsto\left(x^{i}, u_{I}^{\alpha}, u_{J}^{\alpha}, F_{L}^{\alpha}, F_{J \beta}^{\alpha I}\right) \in J^{1}\left(J^{r-1} E\right),
$$

where

$$
F_{L}^{\alpha}=F_{L}^{\alpha}\left(x^{i}, u_{I}^{\beta}\right), F_{J \beta}^{\alpha I}=F_{J \beta}^{\alpha I}\left(x^{i}, u_{I}^{\gamma}\right), 0 \leqslant|I| \leqslant r-2,|J|=r-1,|L|=r .
$$

The horizontal form $h_{F_{d}}$ of $F_{d}$ and the vertical form $v_{F_{d}}$ are given by

$$
\begin{align*}
h_{F_{d}}= & \tilde{\theta}_{1} \circ F_{d}=d x^{i} \otimes\left(\partial_{i}+\sum_{0 \leqslant|I| \leqslant r-2} u_{i I}^{\alpha} \partial_{\alpha}^{I}+\sum_{|J|=r-1} F_{i J}^{\alpha} \partial_{\alpha}^{J}\right)  \tag{2.9}\\
& +\sum_{0 \leqslant|I| \leqslant r-2} d u_{I}^{\alpha} \otimes\left(\partial_{\alpha}^{I}+\sum_{|J|=r-1} F_{J \alpha}^{\beta I} \partial_{\beta}^{J}\right), \\
v_{F_{d}} & =\widetilde{\theta}_{2} \circ F_{d}=\sum_{|J|=r-1}\left(d u_{J}^{\alpha}-F_{i J}^{\alpha} d x^{i}-\sum_{0 \leqslant|I| \leqslant r-2} F_{J \beta}^{\alpha I} d u_{I}^{\beta}\right) \otimes \partial_{\alpha}^{I} .
\end{align*}
$$

The horizontal distribution $\operatorname{Im} F_{d}$ on $J^{r-1} E$ is locally generated by the vector fields

$$
\begin{gather*}
\widetilde{\Gamma}_{i}=\partial_{i}+\sum_{0 \leqslant|I| \leqslant r-2} u_{i I}^{\alpha} \partial_{\alpha}^{I}+\sum_{|J|=r-1} F_{i J}^{\alpha} \partial_{\alpha}^{J},  \tag{2.10}\\
\widetilde{H}_{\alpha}^{I}=\partial_{\alpha}^{I}+\sum_{|J|=r-1} F_{J \alpha}^{\beta I} \partial_{\beta}^{J}, \quad 0 \leqslant|I| \leqslant r-2,
\end{gather*}
$$

or equivalently by the forms
(2.11) $\widetilde{\Psi}_{J}^{\alpha}=d u_{J}^{\alpha}-\left(F_{i J}^{\alpha}-\sum_{0 \leqslant I \leqslant r-2} u_{i I}^{\beta} F_{J \beta}^{\alpha I}\right) d x^{i}-\sum_{0 \leqslant|I| \leqslant r-2} F_{J \beta}^{\alpha I} d u_{I}^{\beta}, \quad|J|=r-1$.

## 3. $f(3,-1)$-STRUCTURE ON $J^{r-1} E$

Theorem 3.1. A tensor field $H$ of type $(1,1)$ on $J^{r-1} E$ which satisfies the relations

$$
\begin{equation*}
\theta_{1} \circ H=0, \quad \theta_{2} \circ H=\theta_{2}, \quad H_{\left.\right|_{V\left(J^{r-1} E\right)}}=-1_{V\left(J^{r-1} E\right)} \tag{3.1}
\end{equation*}
$$

is a $f(3,-1)$-structure on $J^{r-1} E$.
Proof. The endomorphism $H: T\left(J^{r-1} E\right) \rightarrow T\left(J^{r-1} E\right)$ in the local chart $\left(U_{r-1}, x^{i}, u_{I}^{\alpha}\right), 0 \leqslant|I| \leqslant r-1$, has the expression

$$
\begin{align*}
H= & \left(H_{j}^{i} d x^{j}+\sum_{0 \leqslant|I| \leqslant r-2} H_{\alpha}^{i, I} \theta_{I}^{\alpha}+\sum_{|J|=r-1} H^{i, J} d u_{J}^{\alpha}\right) \otimes \partial_{i}  \tag{3.2}\\
& +\sum_{0 \leqslant|I| \leqslant r-2}\left(H_{I, j}^{\beta} d x^{j}+\sum_{0 \leqslant|L| \leqslant r-2} H_{I \alpha}^{\beta L} \theta_{L}^{\alpha}+\sum_{|J|=r-1} H_{I \alpha}^{\beta J} d u_{J}^{\alpha}\right) \partial_{\beta}^{I} \\
& +\sum_{|J|=r-1}\left(H_{J, j}^{\beta} d x^{j}+\sum_{0 \leqslant|I| \leqslant r-2} H_{J \alpha}^{\beta I} \theta_{I}^{\alpha}+\sum_{|K|=r-1} H_{J \alpha}^{\beta K} d u_{K}^{\alpha}\right) \otimes \partial_{\beta}^{J} .
\end{align*}
$$

The condition $\theta_{1} \circ H=0$ yields $H_{j}^{i}=H_{j}^{i, I}=H_{\alpha}^{i, J}=0 ; \theta_{2} \circ H=\theta_{2}$ implies $H_{I, j}^{\beta}=H_{I \alpha}^{\beta J}=0, H_{I \alpha}^{\beta L}=\delta_{\alpha}^{\beta} \delta_{I}^{L}, 0 \leqslant|I| \leqslant r-2,0 \leqslant|L| \leqslant r-2,|J|=r-1$, where

$$
\delta_{I}^{L}=\delta_{i_{1}}^{1_{1}} \ldots \delta_{i_{n}}^{1_{n}}, \quad \text { for } I=\left(i_{1}, \ldots, i_{n}\right), L=\left(l_{1}, \ldots, l_{n}\right)
$$

From the third condition (3.1) we obtain $H_{J \alpha}^{\beta K}=-\delta_{\alpha}^{\beta} \delta_{J}^{K},|K|=|J|=r-1$, and consequently,

$$
\begin{equation*}
H=\sum_{0 \leqslant|I| \leqslant r-2} \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I}+\sum_{|J|=r-1}\left(H_{J, i}^{\beta} d x^{i}+\sum_{0 \leqslant|I| \leqslant r-2} H_{J \alpha}^{\beta I} \theta_{I}^{\alpha}-d u_{J}^{\beta}\right) \otimes \partial_{\beta}^{J} \tag{3.3}
\end{equation*}
$$

In particular, we have

$$
\begin{align*}
& H\left(\partial_{i}\right)=-\sum_{0 \leqslant|I| \leqslant r-2} u_{i I}^{\alpha} \partial_{\alpha}^{I}+\sum_{|J|=r-1} H_{J, i}^{\beta} \partial_{\beta}^{J} ;  \tag{3.4}\\
& H\left(\partial_{\alpha}^{I}\right)=\partial_{\alpha}^{I}+\sum_{|J|=r-1} H_{J \alpha}^{\beta I} \partial_{\beta}^{J}, \quad 0 \leqslant|I| \leqslant r-2 ; \\
& H\left(\partial_{\alpha}^{J}\right)=-\partial_{\alpha}^{J} ; \quad|J|=r-1 .
\end{align*}
$$

From (3.4) we obtain

$$
\begin{aligned}
H^{2}\left(\partial_{i}\right) & =-\sum_{0 \leqslant|I| \leqslant r-2} u_{i I}^{\alpha} \partial_{\alpha}^{I}-\sum_{|J|=r-1}\left(\sum_{0 \leqslant|I| \leqslant r-2} u_{i I}^{\alpha} H_{J \alpha}^{\beta I}+H_{J, i}^{\beta}\right) \partial_{\beta}^{J} \\
H^{2}\left(\partial_{\alpha}^{I}\right) & =\partial_{\alpha}^{I}, \quad 0 \leqslant|I| \leqslant r-2 \\
H^{2}\left(\partial_{\alpha}^{J}\right) & =\partial_{\alpha}^{J},|J|=r-1
\end{aligned}
$$

Thus $H^{3}\left(\partial_{i}\right)=\partial_{i}, H^{3}\left(\partial_{\alpha}^{I}\right)=\partial_{\alpha}^{I}, H^{3}\left(\partial_{\alpha}^{J}\right)=\partial_{\alpha}^{J}$ and $H$ defines a $f(3,-1)$-structure on $J^{r-1} E$.

Corollary 3.2. The eigenspace of $H$ corresponding to the eigenvalue 1 is $\operatorname{Im}\left(H^{2}-\right.$ $H)=V_{\tilde{\pi}_{1, r-1}}\left(J^{r-1} E\right)$. The eigenspace of $H$ corresponding to the eigenvalue 0 is $\operatorname{Im}\left(H^{2}-I\right)$. The eigenspace of $H$ corresponding to the eigenvalue $(-1)$ is $\operatorname{Im}\left(H^{2}+H\right)$.

The subbundle

$$
\begin{equation*}
H^{\prime}\left(J^{r-1} E\right)=\operatorname{Im}\left(H^{2}+H\right) \oplus \operatorname{Im}\left(H^{2}-I\right) \tag{3.5}
\end{equation*}
$$

is called the weak horizontal subbundle associated to $H$. His generators and the vector fields

$$
\begin{align*}
\bar{\Gamma}_{i} & =\partial_{i}+\sum_{0 \leqslant|I| \leqslant r-2} u_{i I}^{\alpha} \partial_{\alpha}^{I}+\sum_{|J|=r-1}\left(H_{J, i}^{\beta}+\frac{1}{2} \sum_{0 \leqslant|I| \leqslant r-2} u_{i J}^{\alpha} H_{J \alpha}^{\beta I}\right) \partial_{\beta}^{J},  \tag{3.6}\\
\bar{H}_{\alpha}^{I} & =\partial_{\alpha}^{I}+\frac{1}{2} \sum_{|J|=r-1} H_{J \alpha}^{\beta I} \partial_{\beta}^{J}, \quad 0 \leqslant|I| \leqslant r-2
\end{align*}
$$

Also we have

$$
\begin{equation*}
T\left(J^{r-1} E\right)=H^{\prime}\left(J^{r-1} E\right) \oplus V\left(J^{r-1} E\right) \tag{3.7}
\end{equation*}
$$

Theorem 3.3. Each $f(3,-1)$-structure $H$ on $J^{r-1} E$ defined in Theorem 3.1 induces a canonical dynamical connection $F_{d}$ on $J^{r-1} E$ by

$$
\begin{equation*}
\operatorname{Im} h_{F_{d}}=H^{\prime}\left(J^{r-1} E\right) \tag{3.8}
\end{equation*}
$$

Locally, $F_{d}$ is given by

$$
\begin{align*}
F_{L}^{\alpha} & =\sigma_{L}\left(H_{J, i}^{\beta}\right)+\frac{1}{2} \sum_{0 \leqslant|I| \leqslant r-2} \sigma_{L}\left(U_{i I}^{\alpha} H_{J \alpha}^{\beta I}\right), \quad|L|=1+|J|,  \tag{3.9}\\
F_{J \alpha}^{\beta I} & =\frac{1}{2} H_{J \alpha}^{\beta I} ; \quad 0 \leqslant|I| \leqslant r-2,|J|=r-1 .
\end{align*}
$$

Proof. The relation (3.9) follows from (3.6) and (2.10).

An $f(3,-1)$-structure $H$ on $J^{r-1} E$ defined by (3.1) is called symmetric if

$$
\sigma_{L}\left(H_{J, i}^{\beta}\right)=H_{J i}^{\beta}, \quad \forall L \text { with }|L|=r,|J|=r-1
$$

Theorem 3.4. The set of the dynamical connections on $J^{r-1} E$ and the set of the symmetric $f(3,-1)$-structures defined by (3.1) have the same cardinality.

Proof. A bijection is given by

$$
\begin{align*}
F_{L}^{\alpha} & =H_{L}^{\beta}+\frac{1}{2} \sum_{0 \leqslant|I| \leqslant r-2} \sigma_{L}\left(u_{i I}^{\alpha} H_{J \alpha}^{\beta I}\right), \quad|L|=1+|J|,|J|=r-1,  \tag{3.10}\\
F_{J \alpha}^{\beta I} & =\frac{1}{2} H_{J \alpha}^{\beta I}, \quad 0 \leqslant|I| \leqslant r-2,|J|=r-1,
\end{align*}
$$

or

$$
\begin{align*}
H_{L}^{\beta} & =F_{L}^{\beta}-\sum_{0 \leqslant|I| \leqslant r-2} \sigma_{L}\left(u_{i I}^{\alpha} F_{J \alpha}^{\beta I}\right), \quad|L|=1+|J|,|J|=r-1,  \tag{3.11}\\
H_{J \alpha}^{\beta I} & =2 F_{J \alpha}^{\beta I}, \quad 0 \leqslant|I| \leqslant r-2,|J|=r-1 .
\end{align*}
$$

Theorem 3.5. Each connection of order $r$ defines a symmetric $f(3,-1)$-structure.
Proof. Let $h=\theta_{1} \circ \Lambda=d x^{i} \otimes \Gamma_{i}$, where $\Gamma_{i}$ is given by (2.2), be the horizontal 1-form of a connection $\Lambda$ of order $r$. Consider the tensor field

$$
\begin{equation*}
A=\sum_{p=1}^{r-1}\left[h, \stackrel{p}{J}^{i}\right]_{F N} \otimes d_{i}^{p+1} \tag{3.12}
\end{equation*}
$$

where $\stackrel{p}{J}{ }^{i}$ is given by (1.17) and $d_{i}^{p+1}$ is given by (1.16). Using the definition of the bracket $[,]_{F N}$ we deduce

$$
A=\sum_{p=1}^{r-1} d x^{k} \wedge \mathscr{L}_{\Gamma_{k}} \stackrel{p}{J}^{i} \otimes d_{i}^{p+1}
$$

For the Lie derivation $\mathscr{L}_{\Gamma_{k}}$ we have

$$
\begin{aligned}
& \mathscr{L}_{\Gamma_{k}} J^{i}=\sum_{|I|=p-1}\left(\mathscr{L}_{\Gamma_{k}} \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I i}+\theta_{I}^{\alpha} \otimes \mathscr{L}_{\Gamma_{k}} \partial_{\alpha}^{I i}\right), 1 \leqslant p \leqslant r-1 ; \\
& \mathscr{L}_{\Gamma_{k}} \theta_{I}^{\alpha}=\theta_{I k}^{\alpha}, 0 \leqslant|I| \leqslant r-2 ; \mathscr{L}_{\Gamma_{k}} \theta_{I}^{\alpha}=d u_{I k}^{\alpha}-\Lambda_{I k h}^{\alpha} d x^{h},|I|=r-2 ; \\
& \mathscr{L}_{\Gamma_{k}} \partial_{\alpha}^{I i}=\left[\Gamma_{k}, \partial_{\alpha}^{I i}\right]=-\delta_{k}^{i} \partial_{\alpha}^{I}-\sum_{|J|=r-1} \partial_{\alpha}^{I i}\left(\Lambda_{k J}^{\beta}\right) \partial_{\beta}^{J}, 0 \leqslant|I| \leqslant r-2 .
\end{aligned}
$$

Then we can write

$$
\begin{aligned}
A= & \sum_{p=1}^{r-1} \sum_{|I|=p-1} d x^{k} \wedge\left(\mathscr{L}_{\Gamma_{k}} \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I i}+\theta_{I}^{\alpha} \otimes \mathscr{L}_{\Gamma_{k}} \partial_{\alpha}^{I i}\right) \otimes d_{i}^{p+1} \\
= & \sum_{0 \leqslant|I|<r-2} d x^{k} \wedge\left(\theta_{I k}^{\alpha} \otimes \partial_{\alpha}^{I i}-\delta_{k}^{i} \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I}\right) \otimes d_{i}^{r} \\
& \left.+\sum_{|I|=r-2}\left[\left(d u_{I k}^{\alpha}-\Lambda_{I k h}^{\alpha} d x^{h}\right) \otimes \partial_{\alpha}^{I i}-\delta_{k}^{i} \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I}\right)\right] \otimes d_{i}^{r} \\
& -\sum_{0 \leqslant|I| \leqslant r-2} \sum_{|J|=r-1} \partial_{\alpha}^{I i}\left(\Lambda_{k J}^{\beta}\right) d x^{k} \wedge \theta_{I}^{\alpha} \otimes \partial_{\beta}^{J} \otimes d_{i}^{r} .
\end{aligned}
$$

Let $\operatorname{tr} A=\sum_{p=1}^{r-1} \mathscr{L}_{\Gamma_{k}} \stackrel{p}{J}^{i} d x^{k}\left(d_{i}^{p+1}\right)=\sum_{p=1}^{r-1} \mathscr{L}_{\Gamma_{k}}{ }^{p}{ }^{k}$. Then

$$
\begin{aligned}
\operatorname{tr} A= & \sum_{0 \leqslant|I|<r-2}\left(\theta_{I k}^{\alpha} \otimes \partial^{I k}-n \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I}\right) \\
& +\sum_{|I|=r-2}\left[\left(d u_{I k}^{\alpha}-\Lambda_{I k h}^{\alpha} d x^{h}\right) \otimes \partial_{\alpha}^{I k}-n \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I}\right] \\
& -\sum_{0 \leqslant|I| \leqslant r-2} \sum_{|J|=r-1} \partial_{\alpha}^{I i}\left(\Lambda_{i J}^{\beta}\right) \theta_{I}^{\alpha} \otimes \partial_{\beta}^{J} \\
= & \sum_{0 \leqslant|I| \leqslant r-2} \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I}-n \sum_{0 \leqslant|I| \leqslant r-2} \theta_{I}^{\alpha} \otimes \partial_{\alpha}^{I} \\
& +\sum_{|J|=r-1} d u_{J}^{\alpha} \otimes \partial_{\alpha}^{J}-\sum_{|J|=r-1} \Lambda_{J h} d x^{h} \otimes \partial_{\alpha}^{J}-\sum_{|J|=r-1} \sum_{0 \leqslant|I| \leqslant r-2} \partial_{\beta}^{I i}\left(\Lambda_{i J}^{\alpha}\right) \theta_{I}^{\beta} \otimes \partial_{\alpha}^{J} \\
= & (1-n) \theta_{2}+\sum_{|J|=r-1}\left(d u_{J}^{\alpha}-\Lambda_{J h}^{\alpha} d x^{h}-\sum_{0 \leqslant|I| \leqslant r-2} \partial_{\beta}^{I i}\left(\Lambda_{i J}^{\alpha}\right) \theta_{I}^{\beta}\right) \otimes \partial_{\alpha}^{J} .
\end{aligned}
$$

Now we put

$$
\begin{align*}
H & =-(n-2) \theta_{2}-\operatorname{tr} A, \text { i.e. }  \tag{3.13}\\
H & =\theta_{2}+\sum_{|J|=r-1}\left(\Lambda_{J i}^{\alpha} d x^{i}+\sum_{0 \leqslant|I| \leqslant r-2} \partial_{\beta}^{I i}\left(\Lambda_{i J}^{\alpha}\right) \theta_{I}^{\beta}-d u_{J}^{\alpha}\right) \otimes \partial_{\alpha}^{I} .
\end{align*}
$$

$H$ is a symmetric $f(3,-1)$-structure on $J^{r-1} E$, satisfying the condition (3.1).
It is easy to establish the following theorems.

Theorem 3.6. Each connection of order $r$ defines a dynamical connection. Conversely, each dynamical connection determines a connection of order $r$.

If $\Lambda$ is a connection of order $r$ then the associated dynamical connection $F_{d}$ is given by

$$
\begin{align*}
F_{L}^{\alpha} & =\Lambda_{L}^{\alpha}+\frac{1}{2} \sum_{0 \leqslant|I| \leqslant r-2} \sigma_{L}\left(u_{i I}^{\beta} \partial_{\beta}^{I k}\left(\Lambda_{k J}^{\alpha}\right)\right), \quad|L|=1+|J|,|J|=r-1 ;  \tag{3.14}\\
F_{J \alpha}^{\beta I} & =\frac{1}{2} \partial_{\alpha}^{I i}\left(\Lambda_{i J}^{\beta}\right), \quad 0 \leqslant|I| \leqslant r-2,|J|=r-1 .
\end{align*}
$$

A dynamical connection $F_{d}$ determines a connection of order $r$ given by

$$
\begin{equation*}
\Lambda_{L}^{\alpha}=F_{L}^{\alpha}-\sum_{0 \leqslant|I| \leqslant r-2} \sigma_{L}\left(u_{i I}^{\beta} F_{J \beta}^{\alpha I}\right),|L|=1+|J|,|J|=r-1 . \tag{3.15}
\end{equation*}
$$

Theorem 3.7. Let $\omega: J^{1}\left(J^{r-1} E\right) \rightarrow J^{r} E$ be the bundle morphism

$$
\omega:\left(x^{i}, u_{I}^{\alpha}, u_{J}^{\alpha}, u_{L}^{\alpha}, u_{J \beta}^{\alpha I}\right) \mapsto\left(x^{i}, u_{I}^{\alpha}, \widetilde{u}_{L}^{\alpha}\right), 0 \leqslant|I| \leqslant r-2,|J|=r-2,|L|=r,
$$

where

$$
\widetilde{u}_{L}^{\alpha}=u_{L}^{\alpha}-\sum_{0 \leqslant|I| \leqslant r-2} \sigma_{L}\left(u_{i I}^{\beta} u_{J \beta}^{\alpha I}\right),|L|=1+|J|,
$$

and $F_{d}$ is a dynamical connection on $J^{r-1} E$. The associated connection of order $r$ is given by

$$
\begin{equation*}
\Lambda=\omega \circ F_{d} . \tag{3.16}
\end{equation*}
$$

## 4. A GEOMETRIC STUDY OF SYSTEMS OF PARTIAL DIFFERENTIAL EQUATIONS OF SECOND ORDER

A dynamical connection $F_{d}$ on $J^{1} E$ is locally characterized by the vector fields $\left\{\Gamma_{i}, H_{\alpha}, V_{\alpha}^{i}\right\}$, where

$$
\begin{equation*}
\Gamma_{i}=\partial_{i}+u_{i}^{\alpha} \partial_{\alpha}+F_{i j}^{\alpha} V_{\alpha}^{j}, H_{\alpha}=\partial_{\alpha}+F_{i \alpha}^{\beta} V_{\beta}^{i}, \quad V_{\alpha}^{i}=\partial_{\alpha}^{i}, \tag{4.1}
\end{equation*}
$$

with $F_{i j}^{\alpha}=F_{j i}^{\alpha}$. The 1-forms associated with (4.1) are $\left\{d x^{i}, \theta^{\alpha}, \Psi_{i}^{\alpha}\right\}$, where

$$
\begin{align*}
\theta^{\alpha} & =d u^{\alpha}-u_{i}^{\alpha} d x^{i} ;  \tag{4.2}\\
\Psi_{i}^{\alpha} & =d u_{i}^{\alpha}-F_{i \beta}^{\alpha} d u^{\beta}-\left(F_{i j}^{\alpha}+u_{i}^{\beta} F_{j \beta}^{\alpha}\right) d x^{j}=d u_{i}^{\alpha}-F_{i \beta}^{\alpha} \theta^{\beta}-F_{i \beta}^{\beta} d x^{j} .
\end{align*}
$$

For the vector fields (4.1) the following relations are satisfied:

$$
\begin{align*}
{\left[\Gamma_{i}, \Gamma_{j}\right] } & =T_{i j k}^{\alpha} V_{\alpha}^{k}, T_{i j k}^{\alpha}=\Gamma_{i}\left(F_{j k}^{\alpha}\right)-\Gamma_{j}\left(F_{i k}^{\alpha}\right)  \tag{4.3}\\
{\left[\Gamma_{i}, H_{\alpha}\right] } & =-F_{i \alpha}^{\beta} H_{\beta}+T_{i k \alpha}^{\gamma} V_{\gamma}^{k}, T_{i k \alpha}^{\gamma}=\Gamma_{i}\left(F_{k \alpha}^{\gamma}\right)+F_{i \alpha}^{\beta} F_{k \beta}^{\gamma}-H_{\alpha}\left(F_{i k}^{\gamma}\right) \\
{\left[\Gamma_{i}, V_{\alpha}^{j}\right] } & =-\delta_{i}^{j} H_{\alpha}+T_{i k \alpha}^{j \gamma} V_{\gamma}^{k}, T_{i k \alpha}^{j \gamma}=\delta_{i}^{j} F_{k \alpha}^{\gamma}-\partial_{\alpha}^{j}\left(F_{i k}^{\gamma}\right), \\
{\left[H_{\alpha}, H_{\beta}\right] } & =T_{\alpha \beta k}^{\gamma} V_{\gamma}^{k}, T_{\alpha \beta k}^{\gamma}=H_{\alpha}\left(F_{k \beta}^{\gamma}\right)-H_{\beta}\left(F_{k \alpha}^{\gamma}\right), \\
{\left[V_{\alpha}^{i}, V_{\beta}^{j}\right] } & =0 .
\end{align*}
$$

For the forms (4.2) we have

$$
\begin{aligned}
d \theta^{\alpha}= & -\Psi_{i}^{\alpha} \wedge d x^{i}-F_{i \beta}^{\alpha} \theta^{\beta} \wedge d x^{i} \\
d \Psi_{i}^{\alpha}= & \frac{1}{2} T_{j k i}^{\alpha} d x^{j} \wedge d x^{k}+T_{k i \beta}^{\alpha} \theta^{\beta} \wedge d x^{k}-\frac{1}{2} T_{\beta \gamma i}^{\alpha} \theta^{\beta} \wedge \theta^{\gamma} \\
& -\partial_{\gamma}^{k}\left(F_{i \beta}^{\alpha}\right) \Psi_{k}^{\gamma} \wedge \theta^{\beta}+T_{j i \beta}^{k \alpha} \Psi_{k}^{\beta} \wedge d x^{j} .
\end{aligned}
$$

The tensor field of type $(1,1)$ associated with $F_{d}$ (see 3.11 ) is given by

$$
\begin{equation*}
H=\theta^{\alpha} \otimes \partial_{\alpha}+\left(H_{i j}^{\alpha} d x^{j}+H_{i \beta}^{\alpha} d u^{\beta}-d u_{i}^{\alpha}\right) \otimes V_{\alpha}^{i} \tag{4.5}
\end{equation*}
$$

where

$$
\begin{equation*}
H_{i j}^{\alpha}=F_{i j}^{\alpha}-\left(u_{i}^{\beta} F_{j \beta}^{\alpha}+u_{j}^{\beta} F_{i \beta}^{\alpha}\right), H_{i \beta}^{\alpha}=2 F_{i \beta}^{\alpha} \tag{4.6}
\end{equation*}
$$

With respect to the basis $\left\{\Gamma_{i}, H_{\alpha}, V_{\alpha}^{i}\right\}$ and the co-basis $\left\{d x^{i}, \theta^{\alpha}, \Psi_{i}^{\alpha}\right\}$ the tensor field $H$ has the form

$$
\begin{equation*}
H=\theta^{\alpha} \otimes \partial_{\alpha}+\left[\left(F_{i \beta}^{\alpha} u_{j}^{\beta}-F_{j \beta}^{\alpha} u_{i}^{\beta}\right) d x^{j}+F_{i \beta}^{\alpha} \theta^{\beta}-\Psi_{i}^{\alpha}\right] \otimes V_{\alpha}^{i} \tag{4.7}
\end{equation*}
$$

From (4.7) we obtain

$$
\begin{equation*}
H\left(\Gamma_{i}\right)=\left(F_{i \beta}^{\alpha} u_{j}^{\beta}-F_{j \beta}^{\alpha} u_{i}^{\beta}\right) V_{\alpha}^{i}, H\left(H_{\alpha}\right)=H_{\alpha}+F_{i \alpha}^{\beta} V_{\beta}^{i}, H\left(V_{\alpha}^{i}\right)=-V_{\alpha}^{i} \tag{4.8}
\end{equation*}
$$

and

$$
\begin{align*}
& { }^{t} H\left(d x^{i}\right)=d x^{i}(H)=0, t_{H}\left(\theta^{\alpha}\right)=\theta^{\alpha}(H)=\theta^{\alpha}  \tag{4.9}\\
& { }^{t} H\left(\Psi_{i}^{\alpha}\right)=-\Psi_{i}^{\alpha}+\left(F_{i \beta}^{\alpha} u_{j}^{\beta}-F_{j \beta}^{\alpha} u_{i}^{\beta}\right) d x^{j}+F_{i \beta}^{\alpha} \theta^{\beta} .
\end{align*}
$$

Let now $\omega=f(x) d x^{1} \wedge \ldots \wedge d x^{n}$ be a volume form on $B$ and $\omega_{i}=\iota_{\partial_{i}} \omega$ (the interior product with respect to $\partial_{i}$ ). Then

$$
d \omega_{i}=f^{-1}\left(\partial_{i} f\right) \omega, d x^{j} \wedge \omega_{i}=\delta_{i}^{j} \omega
$$

Consider $\widetilde{J}: J^{1} E \rightarrow T^{*}\left(J^{1} E\right) \wedge \Lambda^{n-1}(B) \otimes V T\left(J^{1} E\right)$ defined by

$$
\begin{equation*}
\widetilde{J}=\theta^{\alpha} \wedge \omega_{i} \otimes V_{\alpha}^{i} \tag{4.10}
\end{equation*}
$$

then

$$
\operatorname{Im} \widetilde{J}=\Lambda^{n-1}(B) \otimes V T\left(J^{1} E\right), \widetilde{J} \circ \widetilde{J}=0
$$

We call the Poincaré-Cartan form of a function $L \in \mathscr{F}\left(J^{1} E\right)$ the $n$-form $\theta_{L}$ defined by

$$
\begin{equation*}
\theta_{L}=\widetilde{J}(L)+L \omega \tag{4.11}
\end{equation*}
$$

where $\widetilde{J}(L)+{ }^{t} \widetilde{J}(d L)=d L(\widetilde{J})$. In a local fibered chart we have

$$
\begin{equation*}
\theta_{L}=\partial_{\alpha}^{i}(L) \theta^{\alpha} \wedge \omega_{i}+L \omega \tag{4.12}
\end{equation*}
$$

Now we consider the $(n+1)$-form

$$
\begin{equation*}
\Omega_{L}=d \theta_{L} \tag{4.13}
\end{equation*}
$$

Using a dynamical connection $F_{d}$ on $J^{1} E$, the relations (4.4) and the fact that

$$
d f=\Gamma_{i}(f) d x^{i}+H_{\alpha}(f) \theta^{\alpha}+\partial_{\alpha}^{i}(f) \Psi_{i}^{\alpha}, \forall f \in \mathscr{F}\left(J^{1} E\right)
$$

we obtain

$$
\begin{align*}
\Omega_{L} & =\partial_{\beta}^{j}\left(\partial_{\alpha}^{i} L\right) \Psi_{j}^{\beta} \wedge \theta^{\alpha} \wedge \omega_{i}-\frac{1}{2}\left[H_{\beta}\left(\partial_{\alpha}^{i} L\right)\right.  \tag{4.14}\\
& \left.-H_{\alpha}\left(\partial_{\beta}^{i} L\right)\right] \theta^{\alpha} \wedge \theta^{\beta} \wedge \omega_{i}-\left[\Gamma_{k}\left(\partial_{\alpha}^{k} L\right)-\partial_{\alpha} L-f^{-1}\left(\partial_{i} f\right) \delta_{\alpha}^{i} L\right] \theta^{\alpha} \wedge \omega
\end{align*}
$$

Denoting $A_{\alpha \beta}^{i j}=\partial_{\alpha}^{i}\left(\partial_{\beta}^{j} L\right)$ we have the relations

$$
\begin{equation*}
A_{\alpha \beta}^{i j}=A_{\alpha \beta}^{j i}=A_{\beta \alpha}^{i j} . \tag{4.15}
\end{equation*}
$$

We now make a general remark.
Remark. Let $T$ be a tensor field of type $(1,1)$ on a differential manifold $M$ and let $\Omega$ be a 3-form on $M$. We can define in terms of $T$ the following 3-forms on $M$ :

$$
\begin{align*}
& \left(T^{(1)} \Omega\right)(X, Y, Z)=\Omega(T X, Y, Z)+\Omega(X, T Y, Z)+\Omega(X, Y T Z)  \tag{4.16}\\
& \left(T^{(2)} \Omega\right)(X, Y, Z)=\Omega(T X, T Y, Z)+\Omega(T X, Y, T Z)+\Omega(X, T Y, T Z)
\end{align*}
$$

On the other hand, we can associate with $T$ an antiderivation $\delta_{T}$ of degree zero on the algebra of forms on $M . \delta_{T}$ is uniquely determined by the conditions

$$
\delta_{T} f=0, \forall f \in \mathscr{F}(M) ; \quad \delta_{T} \theta={ }^{t} T \theta, \forall \theta \in \Lambda^{1}(M) .
$$

For a $k$-form $\omega \in \Lambda^{k}(M)$ we have

$$
\begin{equation*}
\left(\delta_{T} \omega\right)\left(X_{1}, \ldots, X_{k}\right)=\left(T^{(1)} \omega\right)\left(X_{1}, \ldots, X_{k}\right) \tag{4.17}
\end{equation*}
$$

If we consider the operator $d_{T}$ given by

$$
\begin{equation*}
d_{T}=\delta_{T} \circ d-d \circ \delta_{T} \tag{4.18}
\end{equation*}
$$

then we have

$$
\begin{gather*}
d \circ d_{T}=-d_{T} \circ d, d_{T}^{2} \circ d=d \circ d_{T}^{2},  \tag{4.19}\\
\iota_{X} \circ d_{T}+d_{T} \circ \iota_{X}=\mathscr{L}_{T X}+\left[\delta_{T}, \mathscr{L}_{X}\right] .
\end{gather*}
$$

Theorem 4.1. The $(n+1)$-form $\Omega_{L}$ from (4.13) has the decomposition

$$
\begin{equation*}
\Omega_{L}=\Omega_{L}^{c}+H^{(2)} \Omega_{L}-H^{(1)} \Omega_{L} \tag{4.20}
\end{equation*}
$$

where

$$
\begin{align*}
\Omega_{L}^{c}= & A_{\alpha \beta}^{i j} \Psi_{i}^{\alpha} \wedge \theta^{\beta} \wedge \omega_{j},  \tag{4.21}\\
H^{(1)} \Omega_{L}= & -A_{\alpha \beta}^{i j} F_{i \gamma}^{\alpha} \theta^{\gamma} \wedge \theta^{\beta} \wedge \omega_{j}-\left[H_{\beta}\left(\partial_{\alpha}^{i} L\right)-H_{\alpha}\left(\partial_{\beta}^{i} L\right)\right] \theta^{\alpha} \wedge \theta^{\beta} \wedge \omega_{i} \\
& -\left[\Gamma_{k}\left(\partial_{\alpha}^{k} L\right)-\partial_{\alpha} L-f^{-1}\left(\partial_{k} f\right) \partial_{\alpha}^{k} L\right] \theta^{\alpha} \wedge \omega, \\
H^{(2)} \Omega_{L}= & -A_{\alpha \beta}^{i j} F_{i \gamma}^{\alpha} \theta^{\gamma} \wedge \theta^{\beta} \wedge \omega_{j}-\frac{1}{2}\left[H_{\beta}\left(\partial_{\alpha}^{i} L\right)-H_{\alpha}\left(\partial_{\beta}^{i} L\right)\right] \theta^{\alpha} \wedge \theta^{\beta} \wedge \omega_{i} . \tag{4.23}
\end{align*}
$$

Proof. By using the above remark and (4.9) we have

$$
\begin{aligned}
H^{(1)} \Omega_{L}= & \left.A_{\alpha \beta}^{i j}{ }^{t} H\left(\Psi_{i}^{\alpha}\right) \wedge \theta^{\beta} \wedge \omega_{j}+\Psi_{i}^{\alpha} \wedge^{t} H\left(\theta^{\beta}\right) \wedge \omega_{j}+\Psi_{i}^{\alpha} \wedge \theta^{\beta} \wedge H^{(1)}\left(\omega_{j}\right)\right] \\
& \left.-\frac{1}{2}\left[H_{\beta}\left(\partial_{\alpha}^{i} L\right)-H_{\alpha}\left(\partial_{\beta}^{i} L\right)\right]\right]^{t} H\left(\theta^{\alpha}\right) \wedge \theta^{\beta} \wedge \omega_{i}+\theta^{\alpha} \wedge^{t} H\left(\theta^{\beta}\right) \wedge \omega_{i} \\
& \left.+\theta^{\alpha} \wedge \theta^{\beta} \wedge H^{(1)}\left(\omega_{i}\right)\right]-\left[\Gamma_{k}\left(\partial_{\alpha}^{k} L\right)-\partial_{\alpha} L-f^{-1}\left(\partial_{k} f\right) \partial_{\alpha}^{k}\right]{ }^{t} H\left(\theta^{\alpha}\right) \wedge \omega \\
& \left.+\theta^{\alpha} \wedge H^{(1)}(\omega)\right] \\
= & A_{\alpha \beta}^{i j}\left[-\Psi_{i}^{\alpha}+\left(F_{i \gamma}^{\alpha} u_{k}^{\gamma}-F_{k \gamma}^{\alpha} u_{k}^{\gamma}\right) d x^{k}+F_{i \gamma}^{\alpha} \theta^{\gamma}+\Psi_{i}^{\alpha}\right] \wedge \theta^{\beta} \wedge \omega_{j} \\
& -\frac{1}{2}\left[H_{\beta}\left(\partial_{\alpha}^{i} L\right)-H_{\alpha}\left(\partial_{\beta}^{i} L\right)\right]\left(\theta^{\alpha} \wedge \theta^{\beta} \wedge \omega_{i}+\theta^{\alpha} \wedge \theta^{\beta} \wedge \omega_{i}\right) \\
& -\left[\Gamma_{k}\left(\partial_{\alpha}^{k} L\right)-\partial_{\alpha} L-f^{-1}\left(\partial_{k} f\right) \partial_{\alpha}^{k}\right] \wedge \theta^{\alpha} \wedge \omega \\
= & -\left(A_{\alpha \beta}^{i j} F_{i \gamma}^{\alpha} u_{j}^{\gamma}-A_{\alpha \beta}^{i j} F_{i \gamma}^{\alpha} u_{j}^{\gamma}\right) \theta^{\beta} \wedge \omega_{j}-A_{\alpha \beta}^{i j} F_{i \gamma}^{\alpha} \theta^{\gamma} \wedge \theta^{\beta} \wedge \omega_{j} \\
& -\left[H_{\beta}\left(\partial_{\alpha}^{i} L\right)-H_{\alpha}\left(\partial_{\beta}^{i} L\right)\right] \theta^{\alpha} \wedge \theta^{\beta} \wedge \omega_{i}-\left[\Gamma_{k}\left(\partial_{\alpha}^{k} L\right)-\partial_{\alpha} L\right. \\
& \left.-f^{-1}\left(\partial_{k} f\right) \partial_{\alpha}^{k} L\right] \theta^{\alpha} \wedge \omega .
\end{aligned}
$$

Similarly,

$$
\begin{aligned}
H^{(2)} \Omega_{L} & =A_{\alpha \beta}^{i j}{ }^{t} H\left(\Psi_{i}^{\alpha}\right) \wedge^{t} H\left(\theta^{\beta}\right) \wedge \omega_{j}-\frac{1}{2}\left[H_{\beta}\left(\partial_{\alpha}^{i} L\right)-H_{\alpha}\left(\partial_{\beta}^{i} L\right)\right] \theta^{\alpha} \wedge \theta^{\beta} \wedge \omega_{i} \\
& =-A_{\alpha \beta}^{i j} F_{i \gamma}^{\alpha} \theta^{\gamma} \wedge \theta^{\beta} \wedge \omega_{j}-\frac{1}{2}\left[H_{\beta}\left(\partial_{\alpha}^{i} L\right)-H_{\alpha}\left(\partial_{\beta}^{i} L\right)\right] \theta^{\alpha} \wedge \theta^{\beta} \wedge \omega_{i}
\end{aligned}
$$

Then

$$
\begin{aligned}
H^{(2)} \Omega_{L}-H^{(1)} \Omega_{L}= & \frac{1}{2}\left[H_{\beta}\left(\partial_{\alpha}^{i} L\right)-H_{\alpha}\left(\partial_{\beta}^{i} L\right)\right] \theta^{\alpha} \wedge \theta^{\beta} \wedge \omega_{i} \\
& +\left[\Gamma_{K}\left(\partial_{\alpha}^{k} L\right)-\partial_{\alpha} L-f^{-1}\left(\partial_{k} f\right) \partial_{\alpha}^{k} L\right] \theta^{\alpha} \wedge \omega
\end{aligned}
$$

If $\Omega_{L}^{c}$ is given by (4.21) then (4.20) is verified.
The above theorem suggests the following definition:
A dynamical connection $F_{d}$ is said to be compatible with $L$ if $H^{(1)} \Omega_{L}=H^{(2)} \Omega_{L}$.

Theorem 4.2. A dynamical connection $F_{d}$ is compatible with $L$ iff the following conditions are satisfied:

$$
\begin{equation*}
A_{\alpha \beta}^{i j} F_{i j}^{\alpha}+B_{\beta}=0, A_{\alpha \beta}^{i j} F_{j \gamma}^{\alpha}=\frac{1}{2} \partial_{\beta}^{i} B_{\gamma}+R_{\beta \gamma}^{i}, \tag{4.24}
\end{equation*}
$$

where

$$
\begin{equation*}
B_{\alpha}=\partial_{k} \partial_{\alpha}^{k} L+u_{k}^{\beta} \partial_{\beta} u_{\alpha}^{k} L-\partial_{\alpha} L+f^{-1}\left(\partial_{k} f\right) \partial_{\alpha}^{k} L \tag{4.25}
\end{equation*}
$$

and

$$
R_{\beta \gamma}^{i}=R_{\gamma \beta}^{i} .
$$

Proof. The definition yields

$$
\begin{align*}
\partial_{k}\left(\partial_{\alpha}^{k} L\right)+u_{k}^{\beta} \partial_{\beta} \partial_{\alpha}^{k} L-\partial_{\alpha} L+f^{-1}\left(\partial_{k} f\right) \partial_{\alpha}^{k} L+A_{\alpha \beta}^{i j} F_{i j}^{\beta} & =0,  \tag{4.26}\\
\partial_{\beta} \partial_{\alpha}^{i} L-\partial_{\alpha} \partial_{\beta}^{i} s L+F_{k \beta}^{\gamma} A_{\gamma \alpha}^{k i}-F_{k \alpha}^{\gamma} A_{\gamma \beta}^{k i} & =0 ;
\end{align*}
$$

by (4.25) we obtain

$$
A_{\alpha \beta}^{i j} F_{i j}^{\alpha}+B_{\beta}=0
$$

and

$$
\begin{equation*}
\partial_{\beta}^{i} B_{\alpha}=\partial_{k} A_{\beta \alpha}^{i k}+\partial_{\beta} \partial_{\alpha}^{i} L-\partial_{\alpha} \partial_{\beta}^{i} L+u_{k}^{\gamma} \partial_{\gamma} A_{\beta \alpha}^{i k}+f^{-1}\left(\partial_{k} f\right) A_{\beta \alpha}^{i k} . \tag{4.27}
\end{equation*}
$$

From (4.27) we obtain

$$
\begin{aligned}
\partial_{\beta} \partial_{\alpha}^{i} L-\partial_{\alpha} \partial_{\beta}^{i} L & =\partial_{\beta}^{i} B_{\alpha}-\partial_{k} A_{\alpha \beta}^{i k}-u_{k}^{\gamma} \partial_{\gamma} A_{\alpha \beta}^{i k}+f^{-1}\left(\partial_{k} f\right) A_{\alpha \beta}^{i k}, \\
\partial_{\alpha} \partial_{\beta}^{i} L-\partial_{\beta} \partial_{\alpha}^{i} L & =\partial_{\alpha}^{i} B_{\beta}-\partial_{k} A_{\alpha \beta}^{i k}-u_{k}^{\gamma} \partial_{\gamma} A_{\alpha \beta}^{i k}+f^{-1}\left(\partial_{k} f\right) A_{\alpha \beta}^{i k}
\end{aligned}
$$

and

$$
\begin{equation*}
\partial_{\beta} \partial_{\alpha}^{i} L-\partial_{\alpha} \partial_{\beta}^{i} L=\frac{1}{2}\left(\partial_{\beta}^{i} B_{\alpha}-\partial_{\alpha}^{i} B_{\beta}\right) \tag{4.28}
\end{equation*}
$$

(4.26) and (4.28) imply

$$
\frac{1}{2}\left(\partial_{\beta}^{i} B_{\alpha}-\partial_{\alpha}^{i} B_{\beta}\right)+A_{\gamma \alpha}^{k i} F_{k \beta}^{\gamma}-A_{\gamma \beta}^{k i} F_{k \alpha}^{\gamma}=0
$$

or

$$
\left(\frac{1}{2} \partial_{\beta}^{i} B_{\alpha}-A_{\gamma \beta}^{k i} F_{k \alpha}^{\gamma}\right)-\left(\frac{1}{2} \partial_{\beta}^{i} B_{\alpha}-A_{\gamma \alpha}^{k i} F_{k \beta}^{\gamma}\right)=0 .
$$

Therefore

$$
A_{\alpha \beta}^{i j} F_{j \gamma}^{\alpha}=\frac{1}{2} \partial_{\beta}^{i} B_{\alpha}+R_{\beta \gamma}^{i}, R_{\beta \gamma}^{i}=R_{\gamma \beta}^{i} .
$$

A function $L \in \mathscr{F}\left(J^{1} E\right)$ is called regular is $\operatorname{det}\left\|A_{\alpha \beta}^{i j}\right\| \neq 0$. Let us note that $\left\|\widetilde{A}_{i j}^{\alpha \beta}\right\|=\left\|A_{\alpha \beta}^{i j}\right\|^{-1}$.

Theorem 4.3. If $L$ is regular then the connections $F_{d}$ compatible with $L$ are given by

$$
\begin{align*}
F_{i j}^{\alpha} & =\widetilde{A}_{i h}^{\alpha \beta}\left(P_{\beta j}^{h}-\frac{1}{n} \delta_{j}^{h} B_{\beta}\right),  \tag{4.29}\\
F_{i \beta}^{\alpha} & =\widetilde{A}_{i j}^{\alpha \gamma}\left(R_{\gamma \beta}^{j}+\frac{1}{2} \partial_{\gamma}^{j} B_{\beta}\right),
\end{align*}
$$

where $P\left(P_{\beta j}^{h}\right)$ is a tensor field of type (1,2) with Trace $P_{\alpha}=0$ and $\left(\delta_{k}^{h} \delta_{i}^{j}-\delta_{i}^{h} \delta_{k}^{j}\right) P_{\alpha j}^{l}=$ $0 ; R=\left(R_{\alpha \beta}^{i}\right)$ is a symmetric tensor field of type $(1,2)$.

Proof. We consider the system of linear equations

$$
\begin{equation*}
A_{\alpha \beta}^{i j} F_{i k}^{\alpha}+\frac{1}{n} \delta_{k}^{j} B_{\beta}=P_{\beta k}^{j} . \tag{4.30}
\end{equation*}
$$

Setting $j=k$ and summing one obtains the first relation (4.24) if Trace $P_{\alpha}=0$. From (4.30) we deduce the first relation (4.29). The symmetry of $F_{i j}$ implies

$$
\widetilde{A}_{i j}^{\alpha \beta}\left(P_{\beta k}^{j}-\frac{1}{n} \delta_{k}^{j} B_{\beta}\right)=\widetilde{A}_{k j}^{\alpha \beta}\left(P_{\beta i}^{j}-\frac{1}{n} \delta_{i}^{j} B_{\beta}\right),
$$

which leads to $\left(\delta_{k}^{h} \delta_{i}^{j}-\delta_{i}^{h} \delta_{k}^{j}\right) P_{\alpha j}^{l}=0$. The second relation (4.29) results from (4.24).
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