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# A REMARK ON CONFLUENT CAUCHY AND CONFLUENT LOEWNER MATRICES 

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## 1. Introduction

Cauchy matrices are matrices (rectangular in general) with elements $1 /\left(y_{i}-z_{j}\right)$, corresponding to two sequences of interpolation nodes

$$
\begin{equation*}
y^{S}=\left(y_{0}, \ldots, y_{n_{1}-1}\right), \quad z^{S}=\left(z_{0}, \ldots, z_{n_{2}-1}\right) \tag{1}
\end{equation*}
$$

( $y_{i}, z_{j}$ are $n_{1}+n_{2}$ mutually distinct nodes, complex in general). For a given function $\varphi$ defined at least at the points $y_{i}, z_{j}$ we denote by $L_{\varphi} \in \mathcal{L}\left(y^{S}, z^{S}\right)$ the $n_{1}$-by- $n_{2}$ Loewner matrix with elements $\left(\varphi\left(y_{i}\right)-\varphi\left(z_{j}\right)\right) /\left(y_{i}-z_{j}\right)$ (where $\mathcal{L}\left(y^{S}, z^{S}\right)$ is the class of all such matrices for fixed sequences $y^{S}$ and $\left.z^{S}\right)$. Then the Cauchy matrix is a special case of Loewner matrices, obtained for $\varphi\left(y_{i}\right)=1 \forall i$ and $\varphi\left(z_{j}\right)=0 \forall j$. Evidently the rational function

$$
\begin{equation*}
\varphi(x)=\frac{b^{S}(x)}{a^{S}(x)+b^{S}(x)} \tag{2}
\end{equation*}
$$

where

$$
\begin{equation*}
b^{S}(x)=\prod\left(x-z_{j}\right), a^{S}(x)=\prod\left(x-y_{i}\right) \tag{3}
\end{equation*}
$$

serves as an example. Denoting the Cauchy matrix by $C_{y^{s}, z^{s}}$ we obtain

$$
C_{y^{s}, z^{s}}=L_{\frac{1, s}{a^{s}+1^{S}}} \in \mathcal{L}\left(y^{S}, z^{S}\right)
$$

(Let us remark that the existence of a rational function $\varphi$ of Mac-Millan degree ${ }^{1} n$ for the conditions $\varphi\left(y_{i}\right)=1, \varphi\left(z_{j}\right)=0$ follows from the fact that $C_{y^{s}, z^{s}}$ is nonsingular and by Loewner's theory connecting Loewner matrices with interpolation.)
${ }^{1}$ The Mac-Millan degree of a rational function is the maximum of the degrees of its nu-
merator and denominator.

The present note solves the problem whether the confluent Cauchy matrix, introduced in [5] (see Definition 1 below) has the analogous property of being a special case of confluent Loewner matrices. Theorem 5 in Section 3 proves the validity of the formally identical equality

$$
C_{y, z}=L_{\frac{b}{a+b}} \in \mathcal{L}(y, z)
$$

## 2. Notation and preliminaries

Besides the sequences of simple interpolation nodes 1 , we introduce the multiplenodes sequences

$$
\begin{gather*}
y=\left(\left[y_{0}, \varrho_{0}\right], \ldots,\left[y_{r-1}, \varrho_{r-1}\right]\right)  \tag{4}\\
y_{i} \neq y_{i^{\prime}} \quad \text { if } i \neq i^{\prime}, \quad \sum_{i=0}^{r-1} \varrho_{i}=n_{1}
\end{gather*}
$$

$$
\begin{gather*}
z=\left(\left[z_{0}, \sigma_{0}\right], \ldots,\left[z_{s-1}, \sigma_{s-1}\right]\right)  \tag{5}\\
z_{j} \neq z_{j^{\prime}} \quad \text { if } j \neg j^{\prime}, \quad \sum_{j=0}^{s-1} \sigma_{j}=n_{2}
\end{gather*}
$$

( $\varrho_{i}, \sigma_{j}$ are positive integers-multiplicities). We introduce also the corresponding polynomials

$$
\begin{equation*}
a(x)=\prod_{i=0}^{r-1}\left(x-y_{i}\right)^{\varrho_{i}}, \quad b(x)=\prod_{j=0}^{s-1}\left(x-z_{j}\right)^{\sigma_{j}} \tag{6}
\end{equation*}
$$

Definition 1. If $y_{i} \neq z_{j} \forall i=0, \ldots, r-1$ and $\forall j=0, \ldots, s-1$ then we introduce the confluent Cauchy matrix $C_{y, z}$ (of dimension $n_{1}$-by- $n_{2}$ ) [5]:

$$
\begin{equation*}
C_{y, z}=\left(C_{i, j}\right)_{\substack{i=0, \ldots, r-1 \\ j=0, \ldots, s-1}} \tag{7}
\end{equation*}
$$

$$
\begin{align*}
C_{i j} & =\left(\binom{k+l}{k} \frac{(-1)^{k}}{\left(y_{i}-z_{j}\right)^{k+l+1}}\right)_{\substack{k=0, \ldots, e_{i}-1 \\
l=0, \ldots, \sigma_{j}-1}}  \tag{8}\\
& =\left(\frac{\partial^{k+l}}{k!l!\partial \eta^{k} \zeta^{l}}\left[\frac{1}{\eta-\zeta}\right]_{\substack{\eta=y_{i} \\
\zeta=z_{j}}}\right),
\end{align*}
$$

Remark 2. G. Heinig in his paper [3] introduced another generalization of Cauchy matrices, of the form

$$
\left(\frac{c_{i}^{T} d_{j}}{y_{i}-z_{j}}\right)
$$

where $c_{i}, d_{j}$ are $k$-term vectors $(k \ll n)$. Such matrices have connections with vector interpolation.

Definition 3. If $\varphi(x)$ is a function such that the values $\varphi^{(k)}\left(y_{i}\right), i=0, \ldots, r-1$, $k=0, \ldots, \varrho_{i}-1$ and $\varphi^{(l)}\left(z_{j}\right), j=0, \ldots, s-1, l=0, \ldots, \sigma_{j}-1$, exist then we introduce the confluent Loewner matrix $L_{\varphi} \in \mathcal{L}(y, z)$ (of dimension $n_{1}$-by- $n_{2}$ ) (see (he "generalized Loewner matrix" in [4]) by

$$
\begin{equation*}
L_{\varphi}=\left(L_{i j}\right)_{\substack{i=0, \ldots, r-1 \\ j=0, \ldots, s-1}}, \tag{9}
\end{equation*}
$$

$$
\begin{equation*}
L_{i j}=([\underbrace{y_{i}, \ldots, y_{i}}_{(k+1) \text { times }}, \underbrace{z_{j}, \ldots, z_{j}}_{(l+1) \text { times }}]_{\varphi})_{\substack{k=0, \ldots, \varrho_{i}-1 \\ l=0, \ldots, \sigma_{i}-1}} \tag{10}
\end{equation*}
$$

Here $[\ldots]_{\varphi}$ denotes the divided difference-see e.g. [2]. We admit $y_{i}=z_{j}$ for some $i$ and $j$. If, however, $y_{i} \neq z_{j}$ then

$$
\begin{equation*}
\left[y_{i}, \ldots, y_{i}, z_{j}, \ldots, z_{j}\right]_{\varphi}=\frac{\partial^{k+l}}{k!l!\partial \eta^{k} \partial \zeta^{l}}\left[\frac{\varphi(\eta)-\varphi(\zeta)}{\eta-\zeta}\right]_{\substack{\eta=y_{i} \\ \zeta=z_{j}}} \tag{11}
\end{equation*}
$$

Remark 4. 1. The same definition was introduced one year before [4] in [1], up to the constants $1 / k!l!$.
2. The author decided here to change the name from "generalized" to "confluent" Locwner matrices since this corresponds better to the interpolation connections.

## 3. The result

Theorem 5. If the sequences of interpolation nodes fulfil the condition

$$
\begin{equation*}
y_{i} \neq z_{j}, \quad i=0, \ldots, r-1, j=0, \ldots, s-1 \tag{12}
\end{equation*}
$$

then the confluent Loewner matrix

$$
L_{\frac{b}{a+b}} \in \mathcal{L}(y, z)
$$

is defined and equals the confluent Cauchy matrix $C_{y, z}$.
The proof will be very casy if we use the following lemma:

Lemma 6. Let $k$ and $l$ be positive integers and let the function $\varphi$ have derivatives up to orders $k, l$ at the points $\eta_{0}$, $\zeta_{0}$ respectively $\left(\eta_{0} \neq \zeta_{0}\right)$. Then the partial derivative

$$
\frac{\partial^{k+l}}{\partial \eta^{k} \partial \zeta^{l}}\left[\frac{\varphi(\eta)-\varphi(\zeta)}{\eta-\zeta}\right]_{\substack{\eta=\eta_{0} \\ \zeta=\zeta_{0}}}
$$

exists and can be expressed in the form

$$
\begin{aligned}
& \frac{1}{\left(\eta_{0}-\zeta_{0}\right)^{k+l+1}}\left[\sum_{\kappa=1}^{k} \varphi^{(\kappa)}\left(\eta_{0}\right) p_{k, l, \kappa}\left(\eta_{0}, \zeta_{0}\right)\right. \\
+ & \left.\sum_{\lambda=1}^{l} \varphi^{(\lambda)}\left(\zeta_{0}\right) q_{k, l, \lambda}\left(\eta_{0}, \zeta_{0}\right)+(-1)^{k}(k+l)!\left(\varphi\left(\eta_{0}\right)-\varphi\left(\zeta_{0}\right)\right)\right]
\end{aligned}
$$

where $p_{k, l, \kappa}, q_{k, l, \lambda}$ are polynomials in two variables.
The proof is easy by induction.
Now we shall return to the proof of Theorem :
Proof. Let us denote

$$
\varphi(x)=\frac{b(x)}{a(x)+b(x)} .
$$

Then

$$
\varphi^{\prime}(x)=\frac{a(x) b^{\prime}(x)-a^{\prime}(x) b(x)}{(a(x)+b(x))^{2}}
$$

This shows that $\varphi^{\prime}(x)$ is divisible by $\left(x-y_{i}\right)^{\varrho_{i}-1}$ and by $\left(x-z_{j}\right)^{\sigma_{j}-1}$. As an easy consequence we get that

$$
\begin{gathered}
\varphi\left(y_{i}\right)=1, \quad \varphi^{(\kappa)}\left(y_{i}\right)=0, \quad \kappa=1, \ldots, \varrho_{i}-1 \\
\varphi^{(\lambda)}\left(z_{j}\right)=0, \quad \lambda=0, \ldots, \sigma_{j}-1
\end{gathered}
$$

This together with Lemma 6 proves Theorem 5.

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